

# Introduction to Recurrent Neural Networks

Vanilla RNN / Long-Short Term Memory / Gated Recurrent Unit

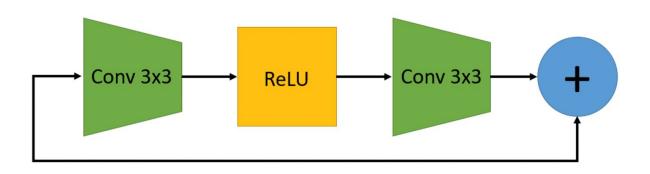
Dr. Risman Adnan Mattororang Telkom University

### Outline

- Why not feed-forward neural networks
- What is recurrent neural networks
  - Issue with recurrent neural networks
  - Vanishing and exploding gradient
- Introduction to long-short term memory
- Gated Recurrent Unit

Standard Neural Networks are DAGs (Directed Acyclic Graphs). That means they have a topological ordering.

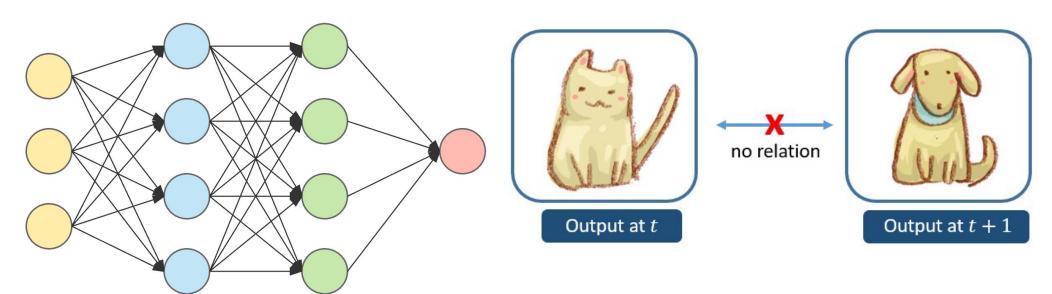
## Feed-forward Structure



"They process one input instance at a time."

### Why not feed-forward neural networks

Feed forward tidak bisa mengatasi sequential problem. Feed forward NN tidak punya aspek waktu. Tidak bisa mengingat waktu (secara urutan/order)

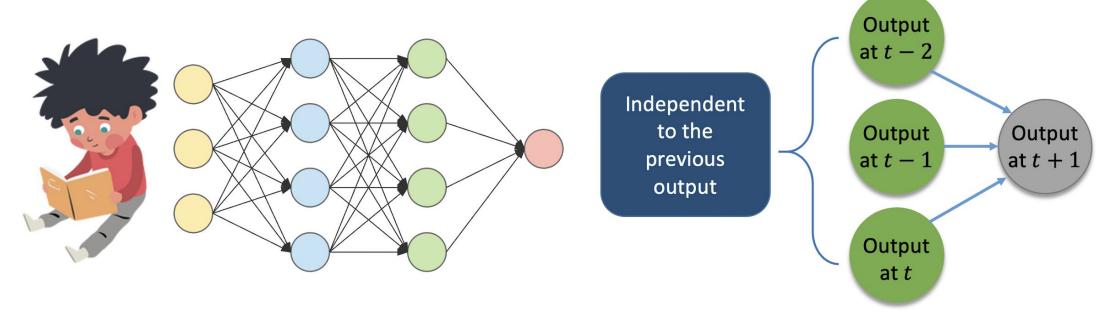


A Trained feed-forward can be access to any random collection of data (images) and the image at t exposed is not necessarily alter how the image at t+1 is predicted

### Why not feed-forward neural networks

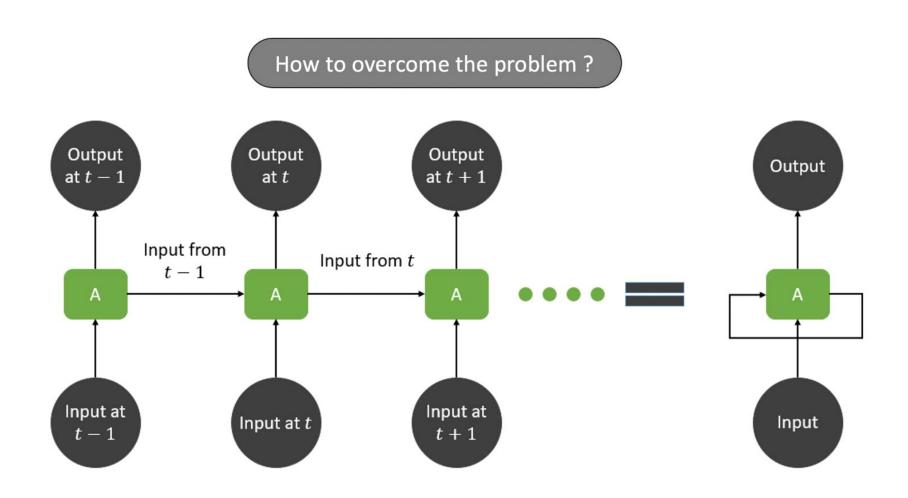
Kita paham konten buku terhadap kata-kata sebelumnya.

When we read book, we understand the content based on our understanding from previous content / words



Sehingga kita gabisa pakai CNN tapi RNN.

### Why not feed-forward neural networks

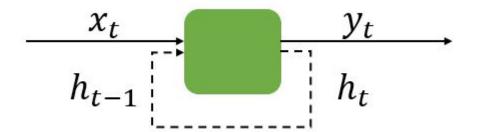


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Dengan looping, maka network bisa mengingat pola-pola sebelumnya.

- produce sequences of outputs  $y_1, y_2, ..., y_n$
- Examples of sequence data in real-world, genomes, handwriting, the spoken word, numerical time series data (such as sensors), etc.



# What is Recurrent Neural Network



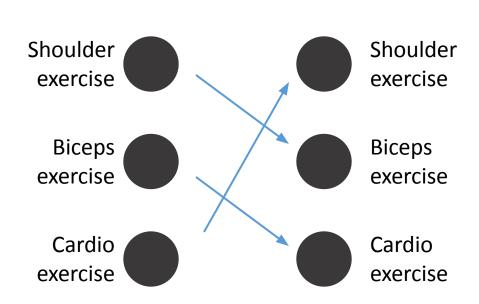


### Suppose:

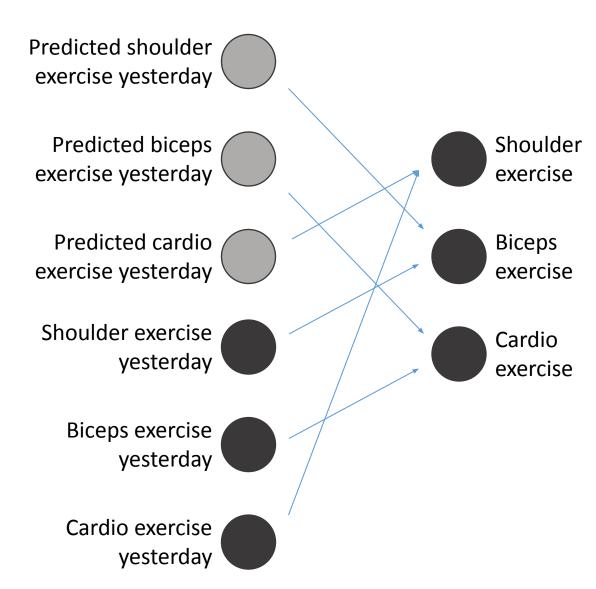
A doctor physiotherapy made a schedule to patient and the exercise schedule are repeated every third day.

- · First day, shoulder exercise
- · Second day, biceps exercise
- Third day, cardio exercise

"An analogy and real-world use case"



Predicting type of exercise



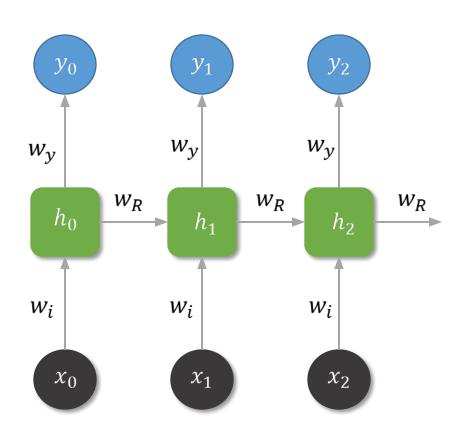
 $\begin{array}{c} \text{Information from} \\ \text{prediction at time } t-1 \end{array}$ 

Prediction at time t

New Information (at time t)

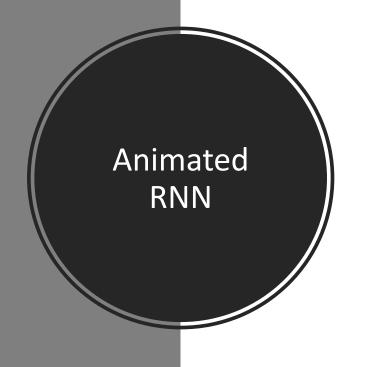
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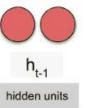
Predicting type of exercise

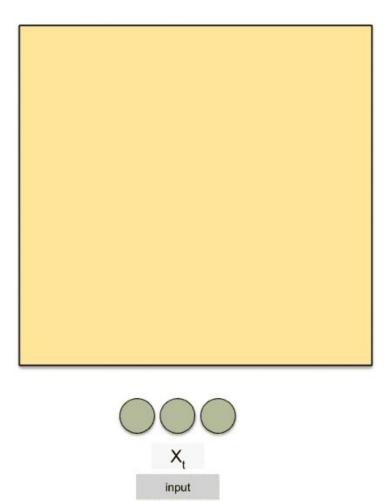


$$h_{(t)} = g_h(w_i x_t + w_R h_{(t-1)}^{\text{hidden state}} + b_h)$$
 $y_{(t)} = g_y(w_y h_{(t)} + b_y)$ 
g adalah aktivasi

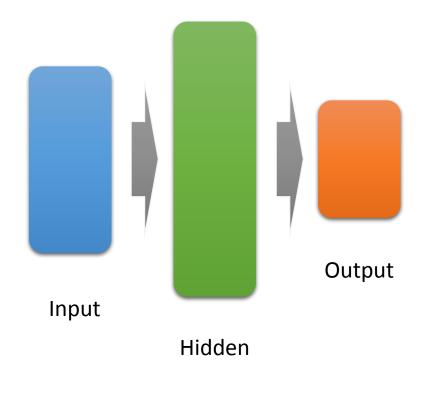
Kalau dihilangkan t-nya mirip forward neural network.

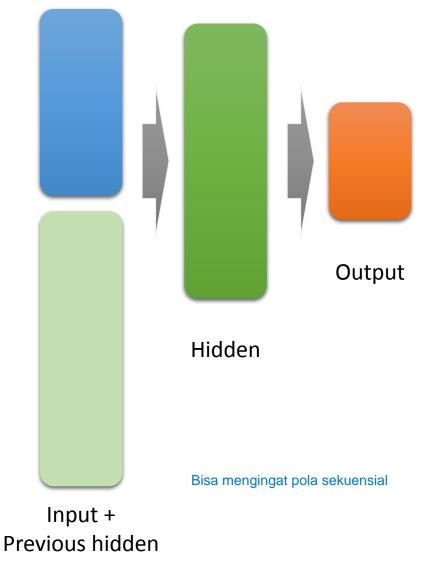






### (Recall) Feedforward NN Vs Recurrent NN





# Recurrent Neural Networks

Why?

 $[input + previous\ hidden] \rightarrow Hidden \rightarrow Output$ 

And why **not** 

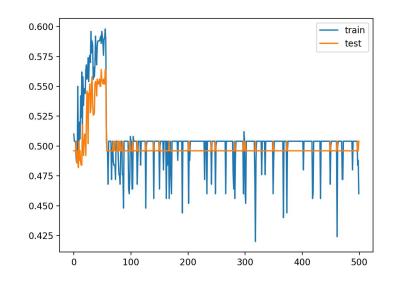
 $[input + previous\ input] \rightarrow Hidden \rightarrow Output$ 

pada kondisi t, RNN memorizing hidden state.



### Training a recurrent neural networks

Recurrent neural networks uses backpropagation algorithm, however this algorithm applied for every timestamp. It is known as backpropagation through time (BTT)



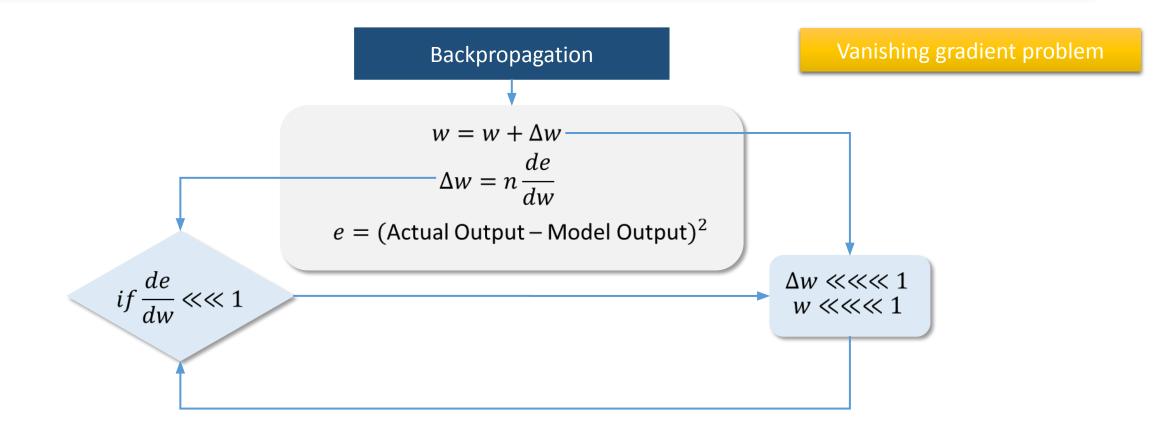
Vanishing gradient problem



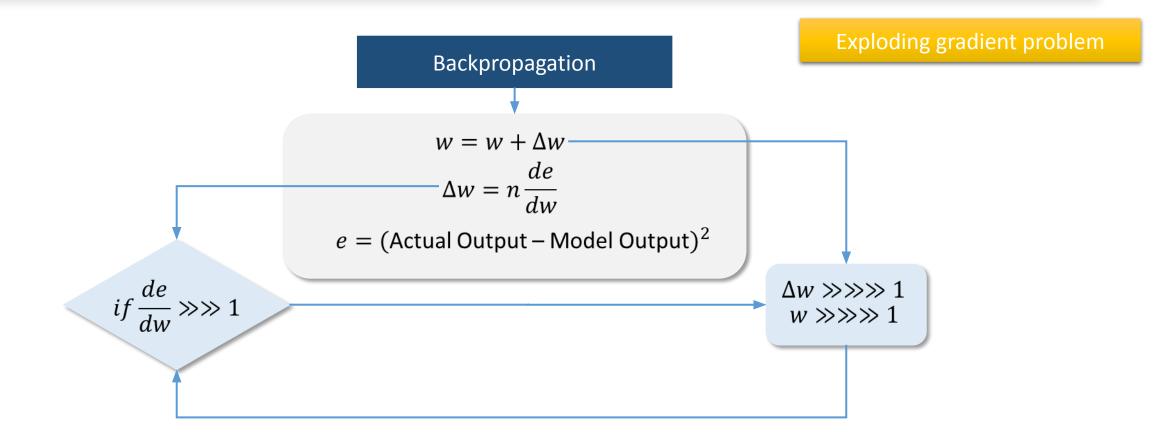
Exploding gradient problem

gradien terlalu besar/terlalu kecil, jadi masalah. over flow(?)

### Problem with RNN



### Problem with RNN



### How to overcome RNN Challenges?

### Vanishing Gradient Problem

- ReLU activation function
   we can use activation like ReLU, which
   gives us output 1 while calculating
   gradient
- Clipping regularisasi, nilai dari gradien kita klip.
   Clip the gradient value when it goes lower than threshold
- LSTM / GRUs GRU cukup, LSTM lebih baik
   Different network architecture that has been designed to overcome this problem

### **Exploding Gradient Problem**

- Truncated BTT
  - Instead of we start backpropagation at the last timestamp, we choose smaller timestamp such as 10 (we will lose temporal context after 10 timestamp)
- Clipping
   Clip the gradient value when it goes
   bigger than threshold
- RSMProp
   Using RMSProp to adjust learning rate

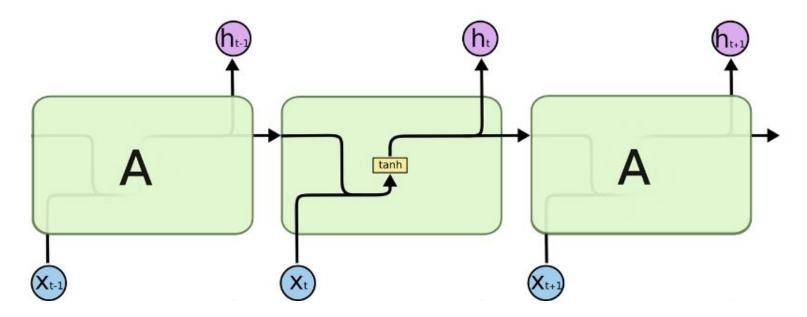
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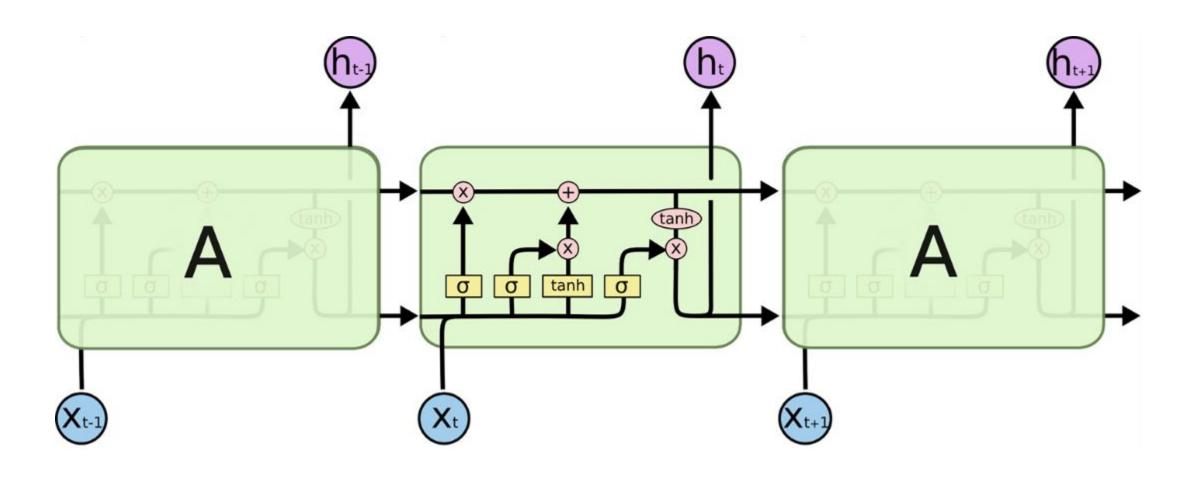


RNN yang bisa memorize pola yang long term

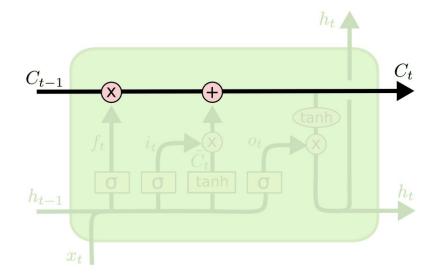
- Long short term memory usually called LSTM, are special kind of RNN
- Capable of long-term dependencies



A repeating module in standard RNN



- Cell state is the key of LSTM
- It runs straight down the entire chain, with only some minor linear interactions
- Information can be added or deleted from this state vector via the forget and input gates.





### LSTM Cell State

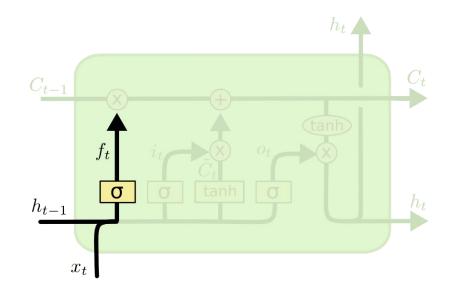
### Illustration

- Want to remember person & phone number
- Forget gate will remove existing information of a prior subject when a new one is encountered.
- Input gate "adds" in the information for the new subject.



### Step-1

Identify the information that and it will be thrown from the cell state. This decision is made by sigmoid layer called as **forget gate** layer



$$f_t = \sigma\left(W_f \cdot [h_{t-1}, x_t] + b_f\right)$$

$$W_f = Weight$$

 $h_{t-1} = \text{Output from the previous timestamp}$ 

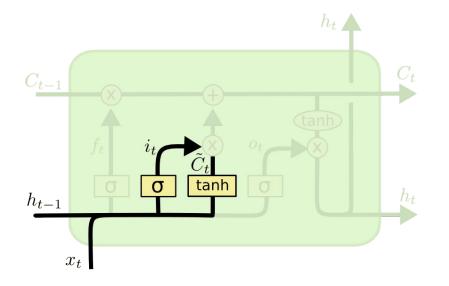
$$x_t = \text{New input}$$

$$b_f = Bias$$



### Step - 2

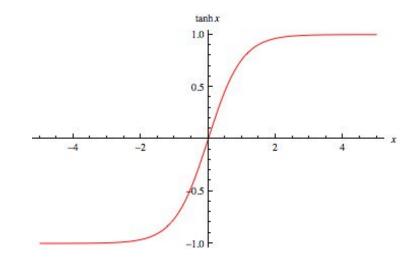
Decide what is new information we are going to store in cell state. This whole process comprises of the following steps. A sigmoid layer called the input gate layer, decide which values will be updated. Next a tanh layer create a vector of a new candidate values, that could be added to the state



### sigmoid mahal, diganti dengan ReLU

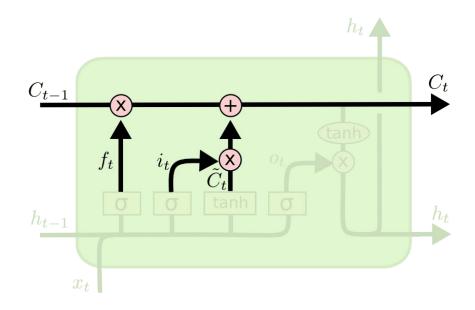
$$i_t = \sigma\left(W_i \cdot [h_{t-1}, x_t] + b_i\right)$$

$$\tilde{C}_t = \tanh(W_C \cdot [h_{t-1}, x_t] + b_C)$$



### Step-3

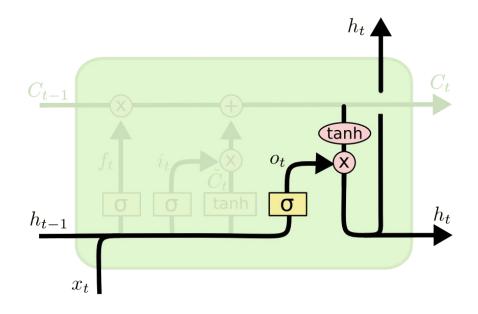
Update the old state  $C_{t-1}$ , into the new cell state  $C_t$ . First, we multiply the old state  $(c_{t-1})$  by  $f_t$ , forgetting the things we forget earlier. Then we add  $i_t * \tilde{C}_t$ . This is a new candidate values, scaled by how much we decide to update each state value.



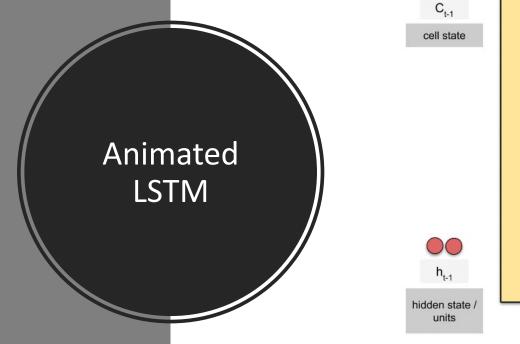
$$C_t = f_t * C_{t-1} + i_t * \tilde{C}_t$$

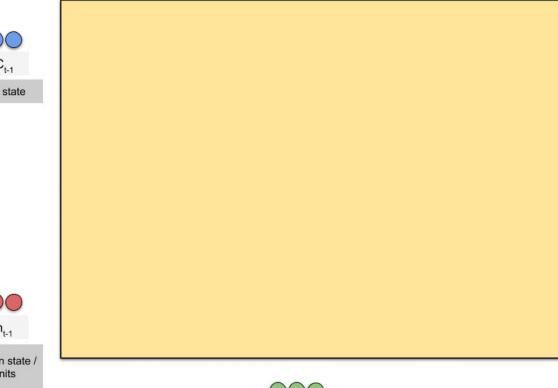
### Step-4

Run sigmoid layer which decide what part of the cell state we are going to output. Then we put the cell state through tanh (push value between -1 and 1) and then multiply it by the output of the sigmoid gate, so that we only output the part we decide.



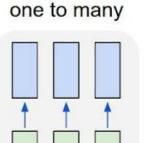
$$o_t = \sigma (W_o [h_{t-1}, x_t] + b_o)$$
$$h_t = o_t * \tanh (C_t)$$

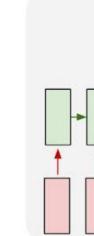


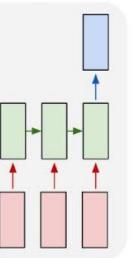




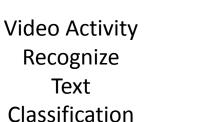
# Summary of LSTM Application Arch.

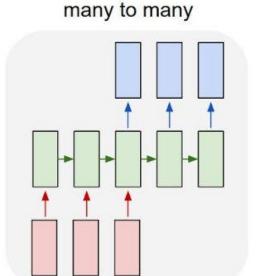




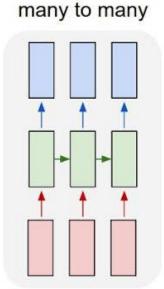


many to one





**Video Captioning** Machine Translation



**POS Tagging** Language Modeling

**Image Captioning** 

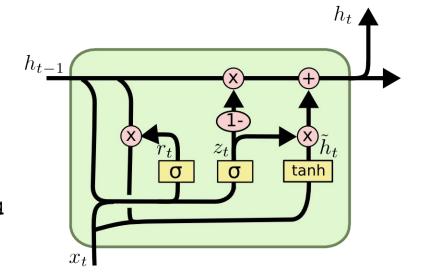
masukin image, akan keluar kata2.

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## Gated Recurrent Unit (GRU)

- A very simplified version of the LSTM
  - Merge forget & input gate into single "update" gate
  - Merge cell and hidden state
- Has fewer parameters than LSTM & has been shown to outperform LSTM on some tasks.



Learning Phrase Representations using RNN Encoder-Decoder for Statistical Machine Translation, Cho et al., 2014

$$z_t = \sigma\left(W_z \cdot [h_{t-1}, x_t]\right)$$

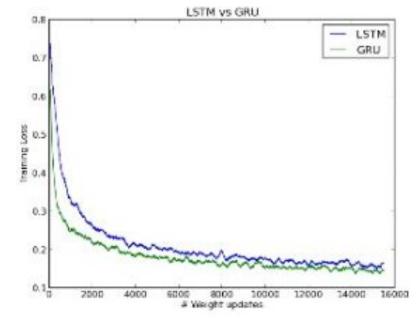
$$r_t = \sigma\left(W_r \cdot [h_{t-1}, x_t]\right)$$

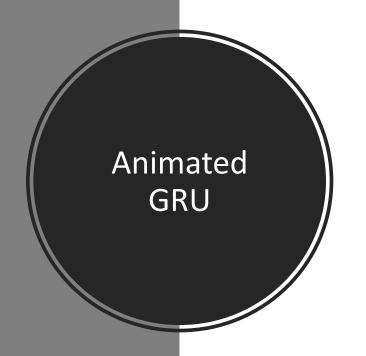
$$\tilde{h}_t = \tanh\left(W \cdot [r_t * h_{t-1}, x_t]\right)$$

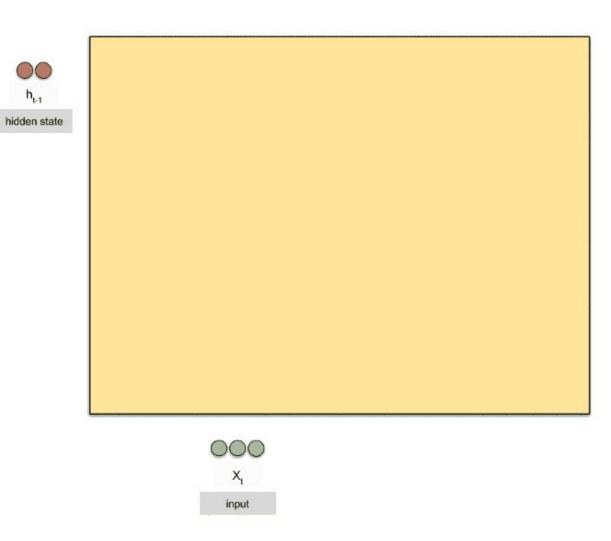
$$h_t = (1 - z_t) * h_{t-1} + z_t * \tilde{h}_t$$

### **GRU vs LSTM**

- GRU has significantly fewer parameters and trains faster.
- Experimental results comparing the two are still inconclusive, many problems they perform the same, some better than the other on some tasks.

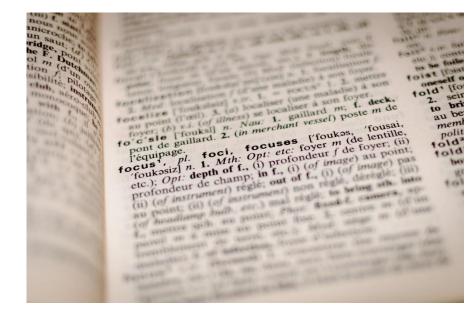






### Attention Layer (Advanced Topic)

- For many applications, it helps to add "attention" to RNNs.
- The Attention mechanism in Deep Learning is based off this concept of directing your focus, and it pays greater attention to certain factors when processing the data
- Allows network to learn to attend to different parts of the input at different time steps, shifting its attention to focus on different aspects during its processing.















# Thank You