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## Regularised Least Squares

- Why? An otherwise nice model with nice properties, but gives infinite/trivial solutions.
- To control overfitting
- Start:  $\mathbf{E}_D(\mathbf{w}) \stackrel{\triangle}{=} \sum_{i=1}^N \{t_i \mathbf{w}^T \boldsymbol{\phi}(\mathbf{x}_i)\}^2$  (data fidelity)
- To minimise  $E_D(\mathbf{w}) + \lambda E_w(\mathbf{w})$  Fidelity, weights param  $\lambda : E_w(\mathbf{w}) = 0$ .  $E_w(\mathbf{w}) = \frac{1}{2}\mathbf{w}^T\mathbf{w} = \frac{1}{2}\sum_{i=0}^{M-1}w_j^2$
- Advantage: Quadratic in w: tlosed-form solution
- (ML): weight decay': weights ↓ 0 unless supported by the data. (Stat): param shrinkage'

$$\bullet E \stackrel{\triangle}{=} \sum_{i=1}^{N} \{t_i - \mathbf{w}^T \boldsymbol{\phi}(\mathbf{x}_i)\}^2 + \lambda \frac{1}{2} \mathbf{w}^T \mathbf{w}. \quad \stackrel{\partial E}{\partial \mathbf{w}} = 0 \implies \\
\bullet E \stackrel{\triangle}{=} \sum_{i=1}^{N} \{t_i - \mathbf{w}^T \boldsymbol{\phi}(\mathbf{x}_i)\} \boldsymbol{\phi}^T(\mathbf{x}_i) + \frac{2\lambda}{2} \mathbf{w}^T = 0 \implies \\
\bullet E \stackrel{\triangle}{=} \sum_{i=1}^{N} \{t_i - \mathbf{w}^T \boldsymbol{\phi}(\mathbf{x}_i)\} \boldsymbol{\phi}^T(\mathbf{x}_i) + \frac{2\lambda}{2} \mathbf{w}^T = 0 \implies \\
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\bullet E \stackrel{\triangle}{=} \sum_{i=1}^{N} \{t_i - \mathbf{w}^T \boldsymbol{\phi}(\mathbf{x}_i)\} \boldsymbol{\phi}^T(\mathbf{x}_i) + \frac{2\lambda}{2} \mathbf{w}^T \boldsymbol{\phi}(\mathbf{x}_i) \boldsymbol{\phi}^T(\mathbf{x}_i) + \frac{2\lambda}{2} \mathbf{w}^T \boldsymbol{$$



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$$\bullet \sum_{i=1}^{N} t_{i} \boldsymbol{\phi}^{T}(\mathbf{x}_{i}) = \mathbf{w}^{T} (\sum_{i=1}^{N} \boldsymbol{\phi}(\mathbf{x}_{i}) \boldsymbol{\phi}^{T}(\mathbf{x}_{i}) + \lambda \mathbf{I}) \Longrightarrow \mathbf{I}$$

$$\mathbf{t}^{T} \boldsymbol{\Phi} = (\boldsymbol{\Phi}^{T} \boldsymbol{\Phi} + \lambda \mathbf{I})^{T} \mathbf{w} = (\boldsymbol{\Phi}^{T} \boldsymbol{\Phi} + \lambda \mathbf{I}) \mathbf{w} \Longrightarrow \mathbf{I}$$

$$\bullet \mathbf{w} = (\mathbf{\Phi}^T \mathbf{\Phi} + \lambda \mathbf{I})^{-1} \mathbf{\Phi}^T \mathbf{t}$$

• Note about the  $||\mathbf{w}^T\mathbf{w}||$ : May actually be implemented numerically as  $||\mathbf{w}^T\mathbf{w}|| - c$ , small c



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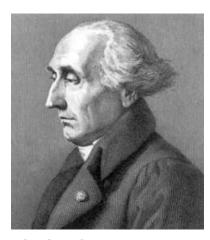
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## Intertwined Histories



J.-L. Lagrange [1736-1813]



A. Lavoisier



J.-B. J. Fourier [1768-1830]

https://upload.wikimedia.org/wikipedia/commons/4/44/Lavoisier-statue.jpg

https://upload.wikimedia.org/wikipedia/commons/a/aa/Fourier2.jpg



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# **Classification**

- $\mathbf{x} \rightarrow [Classifier] \mapsto \mathscr{C}_{j}$
- Three approaches to Classification:
  - 1. Simplest: Discriminant Functions:

    Functions which directly assign a class to x.

    Linear Discriminant: the discriminant fns are lines/linear/hyperplanes
  - 2. Model them directly: Le.g., Mixture of Gaussians. Represent as parametric models, optimise params using a training set
  - 3. Toughest: Generative Approach: Find  $P(\mathscr{C}_j|\mathbf{x})$  Find  $P(\mathscr{C}_j|\mathbf{x})$  using the Bayes' Theorem:  $P(\mathscr{C}_j|\mathbf{x}) = P(\mathbf{x}|\mathscr{C}_j)P(\mathscr{C}_j)/P(\mathbf{x})$ . Models for:  $P(\mathbf{x}|\mathscr{C}_j)$ : class cond densities;  $P(\mathscr{C}_j)$ : priors



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#### Men of God...







[1882-1884]



M. Mitra [1968-]

https://upload.wikimedia.org/wikipedia/commons/d/d4/Thomas\_Bayes.gif

https://upload.wikimedia.org/wikipedia/commons/3/3d/Gregor\_Mendel\_oval.jpg

http://iseeindia.com/wordpress/wp-content/uploads/2011/11/Ramkrishna\_Miss11736-290x290.jpg

Mahan Maharaj/Swami Vidyanathananda 2011 Shanti Swarup Bhatnagar Award in Math Sciences Infosys Prize 2015 for Mathematical Sciences



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### **Useful Generalisations of Linearity**

- Linearity: Written equivalently in two ways:  $y(\mathbf{x}, \mathbf{w}) = \mathbf{w}^T \mathbf{x}$ , for  $(D+1) = M \dim \operatorname{data}$ ,  $x_0 = 1$ , or  $y(\mathbf{x}, \mathbf{w}) = \mathbf{w}^T \mathbf{x} + w_0$ , for  $D = (M-1) \dim \operatorname{data}$
- $y(\mathbf{x}, \mathbf{w}) = \mathbf{w}_0 x_0 + \dots + \mathbf{w}_{M-1} x_{M-1} = \sum_{j=0}^{M-1} w_j x_j$
- Model useful for Regression: linear comb of basis fns (lin/non-lin)  $\mathbf{v}(\mathbf{x}, \mathbf{w}) = \mathbf{w}^T \boldsymbol{\phi}(\mathbf{x})$
- Generalising lin to scalar basis functions  $\phi_i(\mathbf{x})$ :

• 
$$y(\mathbf{x}, \mathbf{w}) = \sum_{j=0}^{M-1} w_j \phi_j(\mathbf{x}) = w_o \phi_0(\mathbf{x}) + \dots w_{M-1} \phi_{M-1}(\mathbf{x})$$

- Model useful for Classification: Ins (lin/non-lin) of the linear  $\mathbf{w}^T \mathbf{x}$  (or  $\mathbf{w}^T \boldsymbol{\phi}(\mathbf{x})$ ) If  $y(\mathbf{x}, \mathbf{w}) = f(\mathbf{w}^T \mathbf{x})$
- Examples: Linear Regression, Neural Networks



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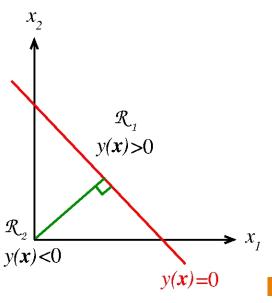
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#### **Discriminant Functions: 2 Classes**



- $\bullet \ y(\mathbf{x}) = \mathbf{w}^T \mathbf{x} + w_0$
- 2-D implicit from of eqn of a line is ax + by + c = 0. Here,  $y(\mathbf{x}, \mathbf{w}) = w_2x_2 + w_1x_1 + w_0 = 0$
- y(x) = 0: 1-D h'plane in 2-D
- Relative location of  $\mathcal{R}_1$ ,  $\mathcal{R}_2$  is immaterial: which is above/below/to the left/to the right
- Physical Significance of  $w_0$ : Impeasure of the dist from the origin IWhy? For ax + by + c = 0, perp distance of  $(x_1, y_1)$  from the line is  $\frac{|ax_1 + by_1 + c|}{\sqrt{a^2 + b^2}}$  Perp dist of  $y(\mathbf{x}) = 0$  from the origin =  $\frac{|w_2(0) + w_1(0) + w_0|}{\sqrt{w_2^2 + w_1^2}} \blacktriangleright \frac{|w_0|}{||\mathbf{w}||}, ||\mathbf{w}||^2 = \mathbf{w}^T \mathbf{w} = \sum w_j^2$



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## Some more Physical Significance

• For two points  $\mathbf{x}_A$  and  $\mathbf{x}_B$  on the line  $y(\mathbf{x}) = 0$ :

$$y(\mathbf{x}_A) = 0 \implies \mathbf{w}^T \mathbf{x}_A + w_0 = 0$$

$$y(\mathbf{x}_B) = 0 \implies \mathbf{w}^T \mathbf{x}_B + w_0 = 0$$

$$\implies \mathbf{w}^T (\mathbf{x}_A - \mathbf{x}_B) = 0$$

$$\implies \mathbf{w}^\perp (\mathbf{x}_A - \mathbf{x}_B) = 0$$

$$\implies \mathbf{w}^\perp (\mathbf{x}_A - \mathbf{x}_B) = 0$$

Phy Significance of perp dist of a point from a line.

$$\bullet \mathbf{x} = \mathbf{x}_{\perp} + r \; \hat{\mathbf{w}} \Vdash \mathbf{x}_{\perp} + r \; \frac{\mathbf{w}}{||\mathbf{w}||}$$

• Pre-multiply by  $\mathbf{w}^T$  & add  $w_0$ :

$$\bullet \mathbf{w}^T \mathbf{x} + w_0 = \mathbf{w}^T (\mathbf{x}_\perp + r_{\frac{\mathbf{w}}{||\mathbf{w}||}}) + w_0$$

$$\mathbf{y}(\mathbf{x}) = (\mathbf{w}^T \mathbf{x}_{\perp} + w_0) + r \frac{||\mathbf{w}||^2}{||\mathbf{w}||}$$

$$\bullet \implies r = \frac{y(\mathbf{x})}{||\mathbf{w}||}$$

→  $x_i$  • Consistent with perp distance of  $(x_1, y_1)$  from line:  $\frac{ax_1 + by_1 + c}{\sqrt{a^2 + b^2}}$ 

y(x)=0



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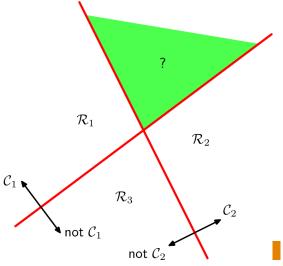
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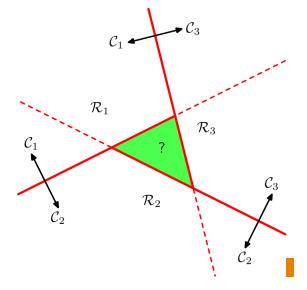
#### Discriminant Functions: K Classes

Building a K − Classifier from 2-class ones

[C. M. Bishop, Pattern Recognition and Machine Learning. Springer, 2006. Fig. 4.2, p. 183]



- One-versus-Rest
- -K-1 classifiers, each of which solves the 2-class  $\mathcal{C}_i$  vs. not  $\mathcal{C}_i$



- One-versus-One
- <sup>K</sup>C<sub>2</sub> 2-class classifiers
- Ambiguity here also!

• e.g., Tree-SVM? Explicitly define the hierarchy!