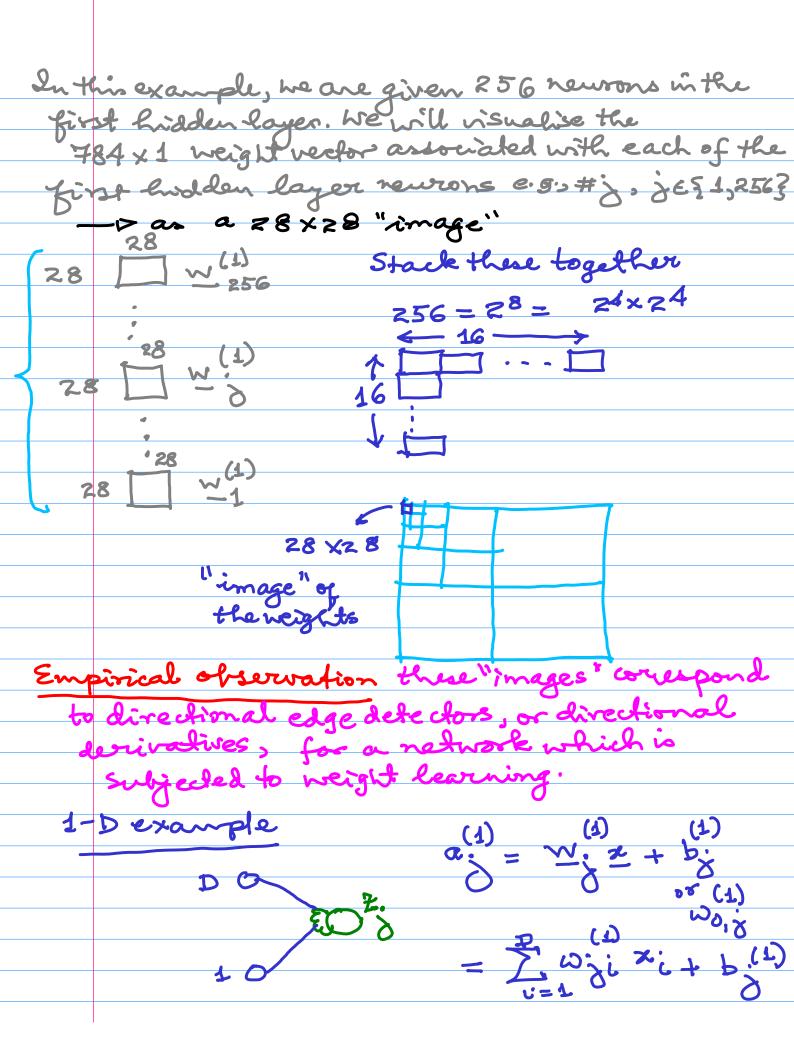
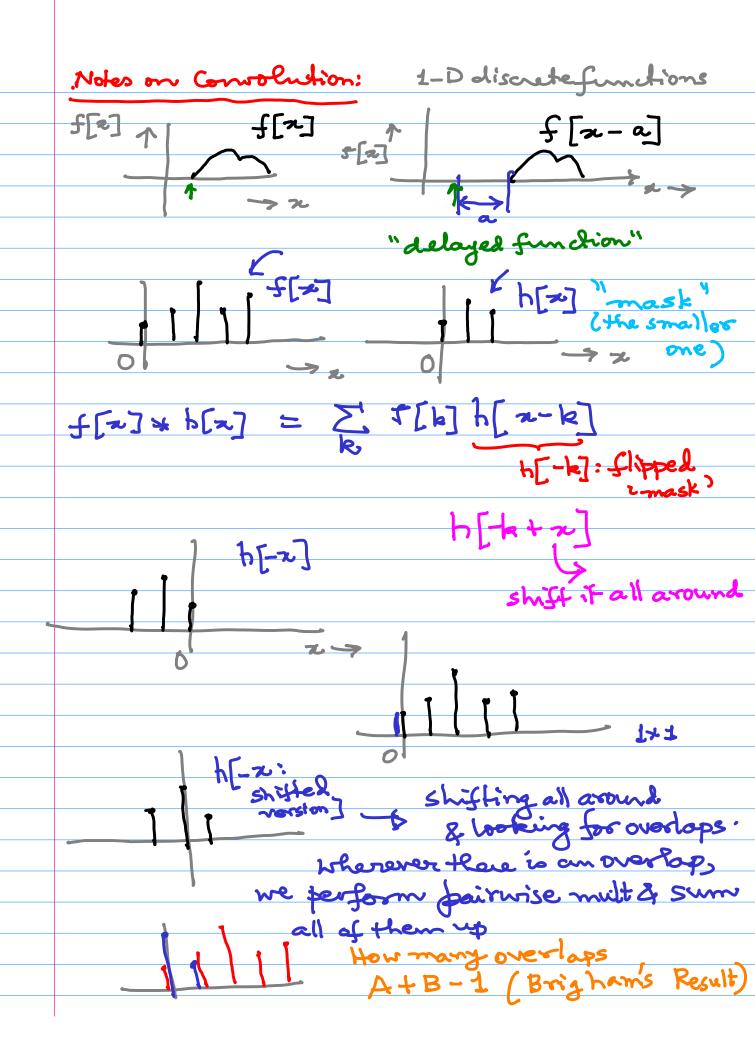
Building Block (Input: 2-D: Image) MNIST Numeral database: 28×28 images Cgrayscale: not binary (not Dand 255, 08 normalised 0 and -> shades of grey as well, though most of the image is black or white. (0) (255, or 1, normalies) Images of the 10 numerals, 0 to 9 -> of specific interest is the first layer 1-D input will ETR, a real number image 428-> of of weights 784×1

Take-home point: The inget is not an ordinary 1-D rector, but a E-D image I we can risualise the weights not as an ordinary 1-D vector, but a 2-Dimage with a similar spatial configuration/ arrangement as the input itself. L) Original Control 1st layer
of connections
(fully connected) (to visualise)



Empirical observation - most of the learnt weights are zers, except for a select few Close to Othe newton in question e.g., $a.(1) = \omega_{2}^{(1)} \times 2 + \omega_{2}^{(1)} \times 2 + 1$ and the other with one of zero and will = 1, wix, 2+1 = -1 $\Rightarrow \alpha_{\ell}^{(1)} = \alpha_{\ell} - \alpha_{\ell+1}$ difference my = f(2) $\frac{05}{0x} = \lim_{6x \to 0} \frac{f(x+8x) - f(x)}{(x+8x) - (x)} = \lim_{6x \to 0} \frac{f(x+8x)}{-f(x)}$ discrete case Sx: 1 sampling point denivate -> f[x+1] - f[x] discrete approximation of the derivative: in 1-D. The first layer: computes a "local" deritative.
(Empirical observation)

CONVOLUTION Newal Network &
Adivation a= w x + b
sum of pairwise products
[Discrete domain: easier to understand]
Formula for Convolution:
2[n] * p[u] € ∑ ×[k] p[u-k]
mask or
input system response
flipped and then
Lrh7 shifted around
10 E
J
knt



	Esticient manner using arrays
	Efficient marmer: Using arrays
	- Conv
(Correlation: Jonask"
	no flipping!