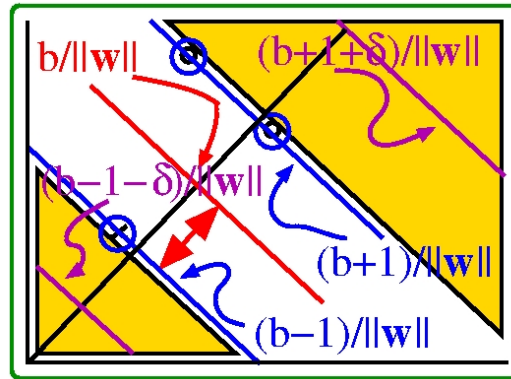


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- We want the golden regions: 2-class data, well-separated
- Consider a magenta line to the right of the blue 'far' line
- Consider 4 dists from origin
- $\frac{b-1}{\|w\|}$ ,  $\frac{b}{\|w\|}$ ,  $\frac{b+1}{\|w\|}$ ,  $\frac{b+1+\delta}{\|w\|}$  Last line:  $w^T x + b = -(1 + \delta)$
- Hence for this region  $w^T x + b < -1$  ||ly the other
- 2 regions:  $w^T x + b < -1$  &  $w^T x + b > +1$  ( $t_i = \mp 1$ )
- $t_i = -1 : w^T x + b < -1$  &  $t_i = +1 : w^T x + b > +1$
- Generalised Canonical Rep<sup>n</sup>:  $t_i [w^T \phi(x) + b] > +1$
- Recap:  $\phi(x)$  is a feature space xform/kernel fn, for a linear decision boundary in xform space
- SVs: closest to d'boundary vis-a-vis margin
- Optimal margin: linear combo of SVs

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- **Max margin:**  $\arg \max_{\mathbf{w}, b} \left\{ \frac{1}{\|\mathbf{w}\|} \min_i \{t_i [\mathbf{w}^T \boldsymbol{\phi}(\mathbf{x}_i) + b]\} \right\}$
- $\min_i \{t_i [\mathbf{w}^T \boldsymbol{\phi}(\mathbf{x}_i) + b]\}$ : margin. So opt:  $\max \frac{1}{\|\mathbf{w}\|}$
- $\max \frac{1}{\|\mathbf{w}\|} \equiv \min \|\mathbf{w}\| \equiv \min \frac{1}{2} \|\mathbf{w}\|^2$ .  $\frac{1}{2}$ : convenience in derivative, square: gets rid of the root in  $\|\mathbf{w}\|$
- $\arg \min_{\mathbf{w}, b} \frac{1}{2} \|\mathbf{w}\|^2$  **subject to**  $t_i [\mathbf{w}^T \boldsymbol{\phi}(\mathbf{x}_i) + b] > 1, \forall \mathbf{x}_i$
- Quad prog, subject to linear ineq constr.s:  $\mathcal{O}(M^3)$
- $L(\mathbf{w}, b, \mathbf{a}) \triangleq \frac{1}{2} \|\mathbf{w}\|^2 - \sum_{i=1}^N a_i \{t_i [\mathbf{w}^T \boldsymbol{\phi}(\mathbf{x}_i) + b] - 1\}$
- $\frac{1}{2} \|\mathbf{w}\|^2$ : to min,  $t_i [\mathbf{w}^T \boldsymbol{\phi}(\mathbf{x}_i) + b] - 1 > 0$ : sep to max
- $\min(L)$ :  $\|\mathbf{w}\| \geq 0$ ; take max terms neg; constr  $\geq 0$ ; in combo coeffs  $a_i \geq 0$ : L'mults;  $\mathbf{a} = [a_1 \dots a_N]^T$
- **Lagrange multipliers:** ONE function to max/min, subject to a set of equality/inequality constraints
- $\frac{\partial L}{\partial \mathbf{w}^T} = \mathbf{0}, \frac{\partial L}{\partial b} = 0$



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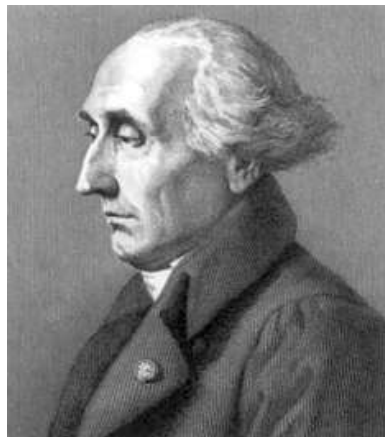
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# Intertwined Histories



J.-L. Lagrange  
[1736-1813]

[https://upload.wikimedia.org/wikipedia/commons/1/19/Lagrange\\_portrait.jpg](https://upload.wikimedia.org/wikipedia/commons/1/19/Lagrange_portrait.jpg)



A. Lavoisier  
[1743-1794]

<https://upload.wikimedia.org/wikipedia/commons/4/44/Lavoisier-statue.jpg>



J.-B. J. Fourier  
[1768-1830]

<https://upload.wikimedia.org/wikipedia/commons/a/aa/Fourier2.jpg>

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- $\frac{\partial L}{\partial \mathbf{w}^T} = \frac{1}{2}2\mathbf{w} - \sum_{i=1}^N a_i t_i \boldsymbol{\phi}(\mathbf{x}_i) = 0$ :  $\mathbf{w} = \sum_{i=1}^N a_i t_i \boldsymbol{\phi}(\mathbf{x}_i)$

- $\frac{\partial L}{\partial b} = 0$ :  $\sum_{i=1}^N a_i t_i = 0$

- Under these constraints, what is  $L(\mathbf{w}, b, \mathbf{a})$ ?

- $= \frac{1}{2}\mathbf{w}^T \mathbf{w} - \sum_{i=1}^N a_i t_i \mathbf{w}^T \boldsymbol{\phi}(\mathbf{x}_i) - \sum_{i=1}^N a_i t_i b + \sum_{i=1}^N a_i$

- 1st term  $= \frac{1}{2}\mathbf{w}^T \mathbf{w} = \frac{1}{2}(\sum_{i=1}^N a_i t_i \boldsymbol{\phi}^T(\mathbf{x}_i))(\sum_{j=1}^N a_j t_j \boldsymbol{\phi}(\mathbf{x}_j))$

- $= \frac{1}{2} \sum_{i=1}^N \sum_{j=1}^N a_i a_j t_i t_j \boldsymbol{\phi}^T(\mathbf{x}_i) \boldsymbol{\phi}(\mathbf{x}_j)$

- $k(\mathbf{x}_i, \mathbf{x}_j) \triangleq \boldsymbol{\phi}^T(\mathbf{x}_i) \boldsymbol{\phi}(\mathbf{x}_j) = \boldsymbol{\phi}^T(\mathbf{x}_j) \boldsymbol{\phi}(\mathbf{x}_i)$

- 1st term  $= \frac{1}{2} \sum_{i=1}^N \sum_{j=1}^N a_i a_j t_i t_j k(\mathbf{x}_i, \mathbf{x}_j)$

- 2nd term  $= \sum_{i=1}^N a_i t_i (\sum_{j=1}^N a_j t_j \boldsymbol{\phi}^T(\mathbf{x}_j)) \boldsymbol{\phi}(\mathbf{x}_i)$

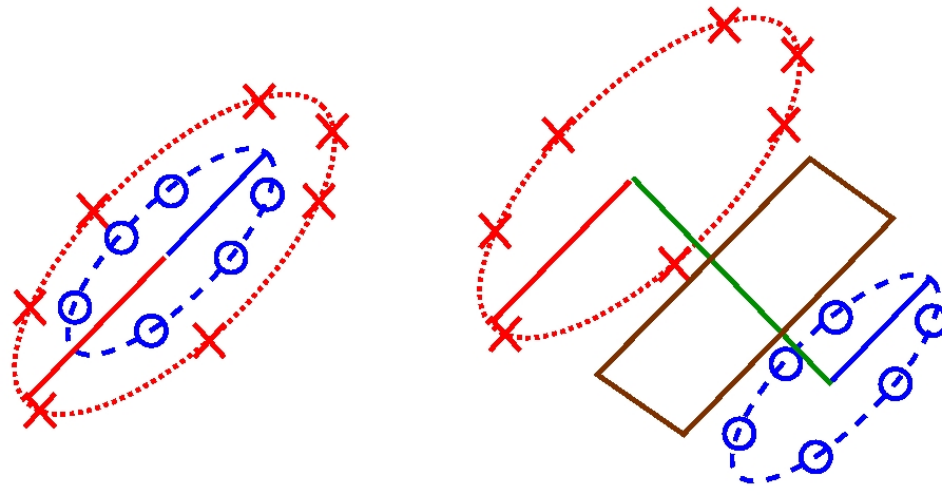
- $= \sum_{i=1}^N \sum_{j=1}^N a_i a_j t_i t_j k(\mathbf{x}_i, \mathbf{x}_j)$

- 3rd term  $= b \sum_{i=1}^N a_i t_i = 0$

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$$L(\mathbf{w}, b, \mathbf{a}) = \tilde{L}(\mathbf{a}) = \sum_{i=1}^N a_i - \frac{1}{2} \sum_{i=1}^N \sum_{j=1}^N a_i a_j t_i t_j k(\mathbf{x}_i, \mathbf{x}_j)$$

- subject to  $a_i \geq 0$  (Lagrange multipliers) &  $\sum_{i=1}^N a_i t_i = 0$ : **Dual Formulation**: no  $\mathbf{w}, b$ : at opt
- constrained  $L(\mathbf{w}, b, \mathbf{a}) \rightarrow$  constrained  $\tilde{L}(\mathbf{a})$  **Dual**
- **Weird?** **Original**  $\arg \min_{\mathbf{w}, b} \frac{1}{2} \mathbf{w}^T \mathbf{w}$ :  $M$ -dim,  $\mathcal{O}(M^3)$
- **Dual**  $\arg \min_{\mathbf{a}} \sum_{i=1}^N a_i - \frac{1}{2} \sum_{i=1}^N \sum_{j=1}^N a_i a_j t_i t_j k(\mathbf{x}_i, \mathbf{x}_j)$ :  $N$ -dim problem
- $D = (M - 1)$ -dim formulation:  $y(\mathbf{x}) = \mathbf{w}^T \boldsymbol{\phi}(\mathbf{x}) + b$
- $D = 2$ :  $y(x_2, x_1) = [w_2 \ w_1] \begin{bmatrix} \phi_2(x_2, x_1) \\ \phi_1(x_2, x_1) \end{bmatrix} + b$
- $y(\mathbf{x}) = [w_2 \ w_1] \begin{bmatrix} \phi_2(\mathbf{x}) \\ \phi_1(\mathbf{x}) \end{bmatrix} + b = w_2 x_2 + w_1 x_1 + b$  (omit  $\boldsymbol{\phi}$ )
- 2-D line: coeffs 0 ( $w_0 = b$ ) to  $M - 1$ , 2-D weights  $\mathbf{w}$  & one  $b$ :  $M = D + 1$  params typically  $< N$  (# points)
- **Kernel: transform data to a higher dim space**

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- The 2 classes (left) have the same centre in 2-D
- Separable by a circle, not a lin decision boundary
- Transform it to 3-D, the third coord = radius
- $[x, y, r]$ : larger circle floats up, separating plane
- Kernel function: to higher dim, hope: lin boundary
- Kernel trick: May not need to transform
- Comps in inner product space  $\phi^T(\mathbf{x})\phi(\mathbf{x}) = \mathbf{x}^T\mathbf{x}$
- Philosophically: like energy in Parseval's theorem