

Deep learning

UNIT - I

- 1) Biological neuron
- 2) Artificial neuron
- 3) Different hyper Parameters
- 4) Limits of Traditional Computer Program.
- 5) Feed-forward neural network
- 6) Different Activation functions : Sigmoid, Tanh, ReLU
- 7) Perception \rightarrow Working. \rightarrow curve / logic example.
- 8) Linear Perception as Neurons. & limitation.
- 9) Back Propagation algorithm, in Reducing Error.
- 10) Gradient descent with Sigmoid Neuron
 \hookrightarrow Derivation
- 11) delta rule for training linear neurons.
- 12) Preventing Overfitting, in D2 methods & Demonstration.
- 13) Stochastic & minibatch Gradient.
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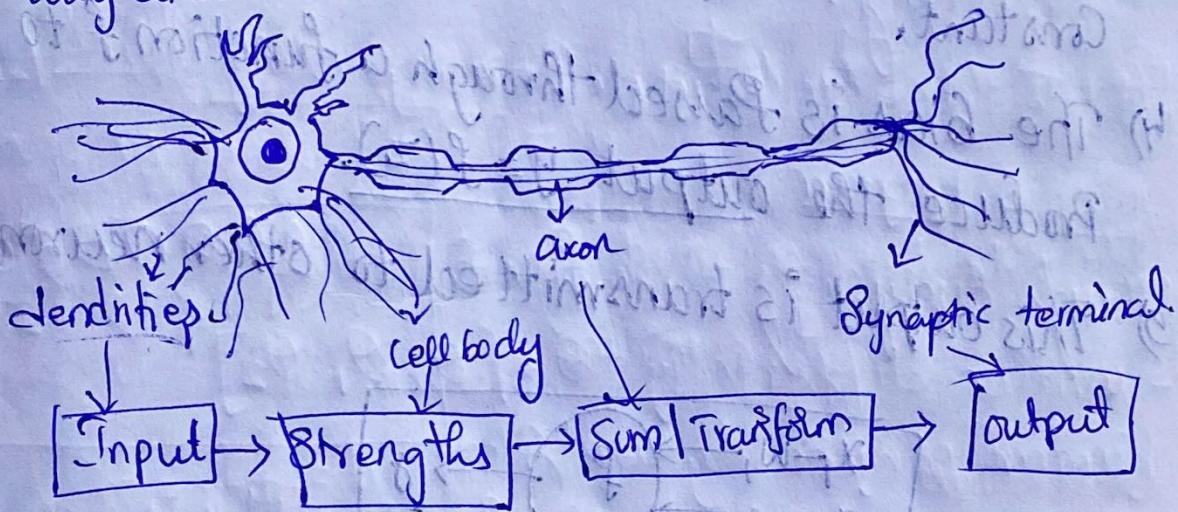
Companion
- 14) Mechanics of ML.

UNIT 1 Chapter 1

(Q1, 2, 4, 5, 6, 7, 8,
9, 15).

1) Biological Neurons

- 1) The foundational unit of human brain is the neuron.
- * It is the massive biological network that enables us to experience outside world.
- * As its core, the neuron is optimized to receive info from other neuron / process the info in a unique way and send its results to other cell.



→ Explain Process :-

1) The neuron receives input along dendrites.

2) Each of incoming connection is dynamically strengthened or weakened based on how it is used.

3) After being weighted by the strength of their respective connection, the input goes to cell body.

4) This sum is then transformed into a new signal that's propagated along the cell axon's & sent off to other neuron.

~~artificial neural network~~

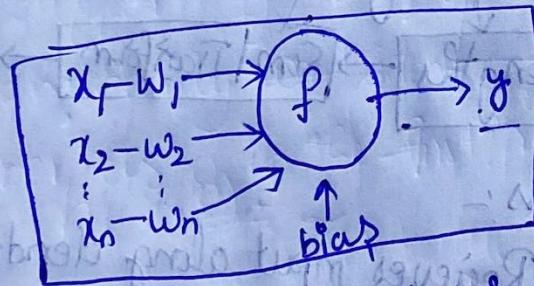
~~neural network~~

② Artificial neuron:

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$\frac{2}{3}$
 $\frac{3}{5}$

- 1) Such as Biological neuron the (a.N) takes in some no of inputs x_1, x_2, \dots, x_n each of which is multiplied by weight, $w_1, w_2, w_3, \dots, w_n$.
- 2) These weighted inputs are, as before, summed together to produce the logit of the neuron, $z = \sum_{i=0}^n w_i x_i$.
- 3) The logit is also called as bias which is constant.
- 4) The bias is passed through a function f to produce the output $y = f(z)$.
- 5) This output is transmitted to other neurons.



We can express this in Vector form

input Vector $\mathbf{x} = [x_1, x_2, \dots, x_n]$

weight vector $\mathbf{w} = [w_1, w_2, \dots, w_n]$

Expression: $y = f(\mathbf{x} \cdot \mathbf{w} + b)$ where b is bias term

3)

Artificial Neuron

- 1) It is a mathematical model which is mainly inspired by the biological neuron system in the human brain.
- 2) Its Processing was Sequential and centralized.
- 3) Small in size
- 4) It process the info at a faster Speed
- 5) Cannot perform Complex Pattern Recognition
- 6) It doesn't provide any feedback
- 7) No fault tolerance
- 8) Operating Environment is well defined and well-constrained
- 9) Reliability : It is very Vulnerable
- 10) Response time is measured in milliseconds.
- 11) It has very accurate structure

Biological Neuron

- It is also composed of several Processing pieces known as Neurons.
- It Process the info in a Parallel and distributive manner.
- large in size.
- It process the Info at a slow speed.
- Perform Complicated tasks.
- It Provides feedback.
- Fault tolerance is their
- Operating Environment is poorly defined and unconstrained.
- It is robust.
- It's Response time is measured in nanoseconds
- They are tolerant & ambiguity.

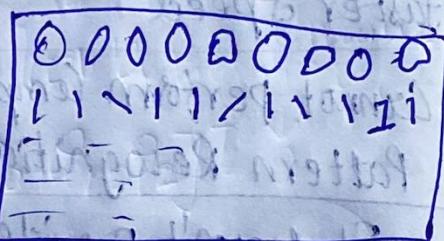
③) Limits of Traditional Computer Programs.

- * Traditional Computer programs are designed to be very good at two things
 - 1) Performing arithmetic really fast.
 - 2) Explicitly following a list of instructions;
- * The T.C.P are good at heavy financial number crunching.

Let us take an example: Recognizing hand written digits Program

although Every digit in the figure is written differently the

human can easily identify



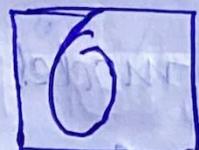
the number as 0 in the first row, 1 in second row etc.,

But if we are said to write Program to automatically read some one's handwriting, it will be very difficult.

If we might state that we have a "Zero", if our image only has a single, closed loop.

but this isn't really a sufficient condition what if someone write a messy zero, it will be a very difficult task to identify it.

like the fig 2 describes



It can't always identify it as 0 or 6 in this case if we even keep the distance between them in the loop.

④ Mechanics of Machine Learning

- To tackle the above Handwritten problem we have to use different kind of approach.
- From childhood to adulthood we often learn things and we learn what is wrong and we will learn from it and train from it.
- We learn how to multiply numbers, solve Equations, take derivatives by set of instructions.
- We learned to recognize a dog by being shown multiple examples and being corrected when we made the wrong guess. If our parents say we are wrong we will modify our model to incorporate this new information.
- Deep Learning is a subset of a more general field of AI called ML. which is predicted on this idea of learning.
- We give model to train and learn instead of set of large instructions.

Let's define our model to be a function $h(x, \theta)$.

The Input(x) is an example Expressed in Vector form.

$\theta \rightarrow$ vector of the parameter that model use.

Let's take an Example: Sleep Predict Exam Performance on Sleep no of hours of Sleep.

We collected a lot of data for each dataset.

Point $x = [x_1 \ x_2]^T$, $x_1 \rightarrow$ no of hours of sleep.

$x_2 \rightarrow$ no of hours we spent studying.

Our goal, the model $h(x, \theta)$ with Parameters Vector $\theta = [\theta_0, \theta_1, \theta_2]^T$

Such that:

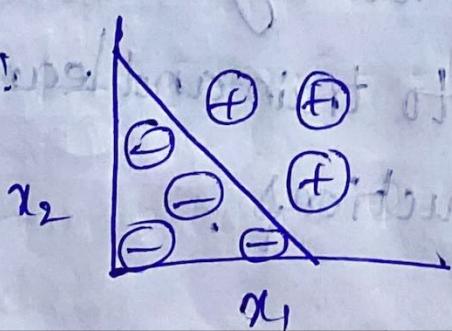
$$h(x, \theta) = \begin{cases} -1 & \text{if } x^T \cdot \begin{bmatrix} \theta_1 \\ \theta_2 \end{bmatrix} + \theta_0 < 0 \\ 1 & \text{if } x^T \cdot \begin{bmatrix} \theta_1 \\ \theta_2 \end{bmatrix} + \theta_0 \geq 0. \end{cases}$$

-1: below average

1: Otherwise.

This model is called linear Perceptron.

Sample Data:

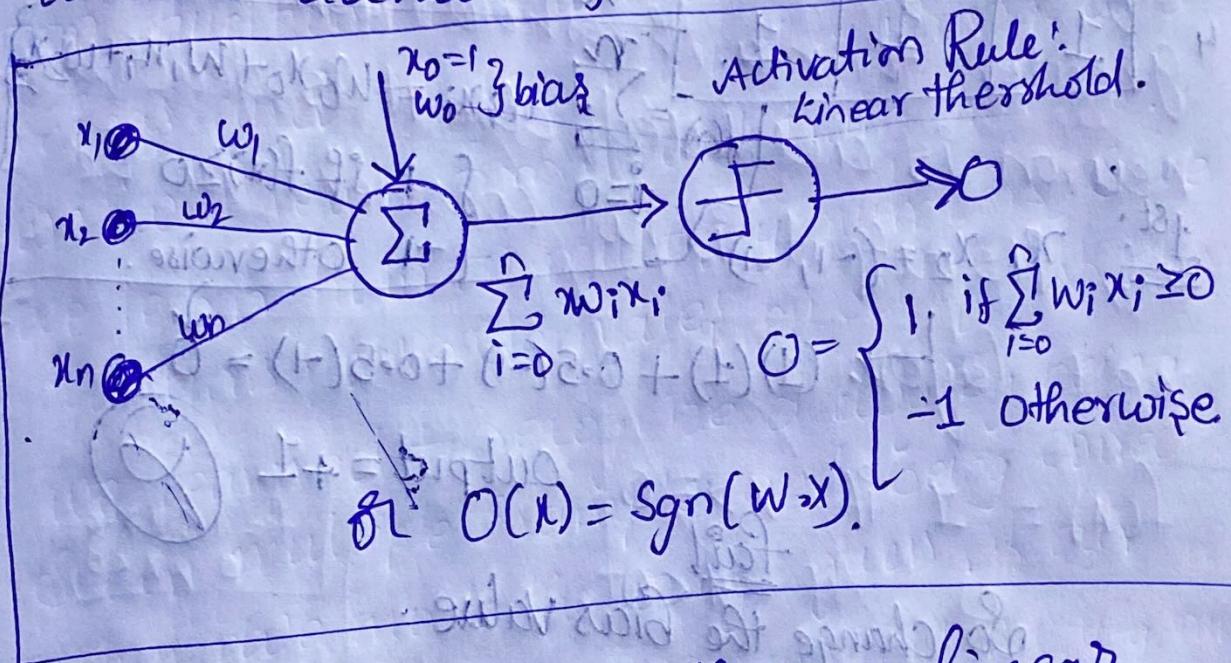


② Linear Perception as Neurons &

limitations:

A linear perception or perceptron is a ML algorithm for supervised learning of various binary classification tasks.

The single layer neural network has four parameters: input values, weights, bias term and an activation function.



It is very easy to show that our linear perception & the neuronal model are perfectly equivalent. And it is quite simple to show that singular neurons are strictly more expressive as linear perception.

$$O = \text{Sgn}(w \cdot x) \quad O = 0 = 2 \cdot 0 + 2 \cdot 0 + 1 \cdot 1 - (1 \cdot 1) \cdot 1$$

Trying the Linear Perceptron by using
and gate:

	x_1	x_2	y
1	-1	-1	-1
2	1	-1	-1
3	-1	1	-1
4	1	1	1

Let us take

$$w_0 = 1 \text{ (bias)} \quad x_0 = 1$$

$$w_1, w_2 = 0.5 \text{ (assum)}$$

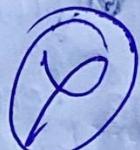
We know formula

$$f(x) = \sum_{i=0}^n w_i x_i = w_0 x_0 + w_1 x_1 + w_2 x_2$$

Ex: $x_1, x_2 = (-1, -1)$

$$\hookrightarrow (-1)(1) + 0.5(-1) + 0.5(-1) = 0$$

Output = +1



So change the bias value.

$$w_0 = -1$$

$$w_1, w_2 = 0.5$$

$$x_0 = 1$$

$$P(-1, -1) \rightarrow -1 + 0.5 - 0.5 = -1 < 0 \quad \boxed{\text{Output} = -1}$$

$$P(1, -1) \rightarrow -1 + 0.5 - 0.5 = -1 < 0 \quad \boxed{\text{Output} = -1}$$

$$P(-1, 1) \rightarrow -1 - 0.5 + 0.5 = -1 < 0 \quad \boxed{\text{Output} = -1}$$

$$P(1, 1) \rightarrow -1 + 0.5 + 0.5 = 0 = 0 \quad \boxed{\text{Output} = 1}$$

Limitations :-

- 1) Lack of complexity: They are incapable of handling complex patterns.
- 2) Limited Expressiveness:
- 3) No feature hierarchy: due to linear nature they cannot form such hierarchies.
(Simple to Complex)
- 4) Inadequate for Complex tasks:
- 5) Overfitting to linear Assumptions.

Activation functions

The Activation function is one that outputs a smaller value for tiny inputs and a higher value if its inputs are greater than their threshold.

There are two types of activation functions:

- 1) linear Activation function.
- 2) Non-linear Activation function.

Linear Activation Function

The function is linear.

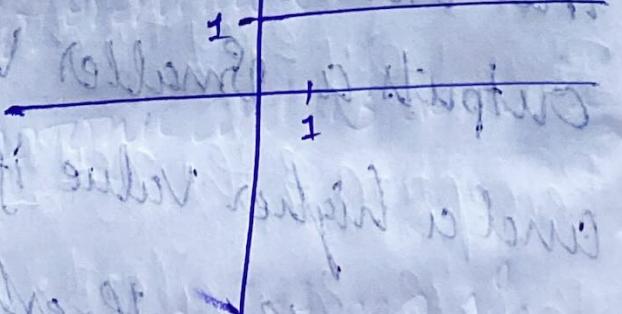
* Binary Step Function

If the input to the activation function is greater than a threshold then the neuron is activated, else it is deactivated. i.e., its output is not considered for the next layer.

$$f(x) = 1 \text{ if } x >= 0$$

$$0 \text{ if } x < 0.$$

$$\begin{cases} 1, & x >= 0 \\ 0, & x < 0. \end{cases}$$



drawbacks

- It can be only used while creating a binary classifier.

* This function is not useful when there are multiple classes in the target variable.

* Non Linear Activation functions:

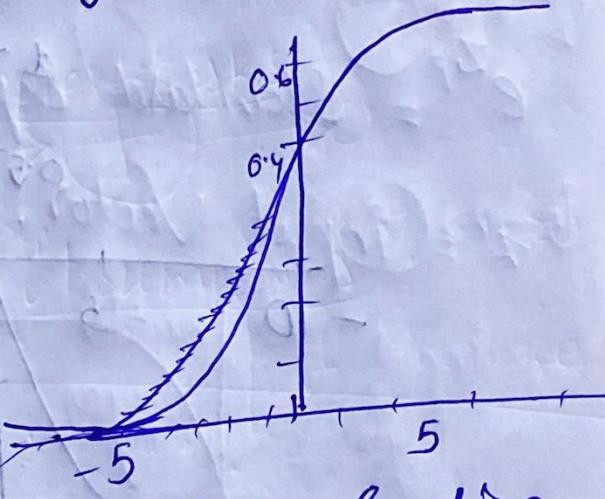
~~The input of the function will be non linear~~

1) Sigmoid :-

A Sigmoid function is graphed in "S" shape.

It uses the function:

$$f(z) = \frac{1}{1+e^{-z}}$$



* When the logit is very small, the output of a logistic function is very close to "0".

* When the logit is very large, the output of the logistic function is close to "1".

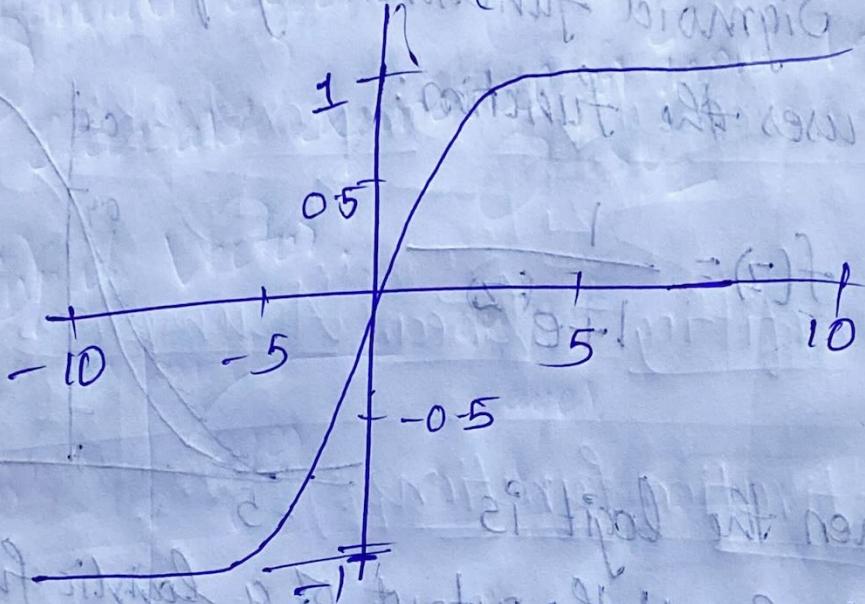
* In b/w them, the function assumes an S-shape.

② Tanh function:

The Tanh function has a similar kind of S-shaped non-linearity, but instead ranging from 0 to 1, the output of tanh function ranges from -1 to 1.

It uses:

$$f(z) = \tanh(z) = \frac{e^z}{(1 + e^{2z})}$$

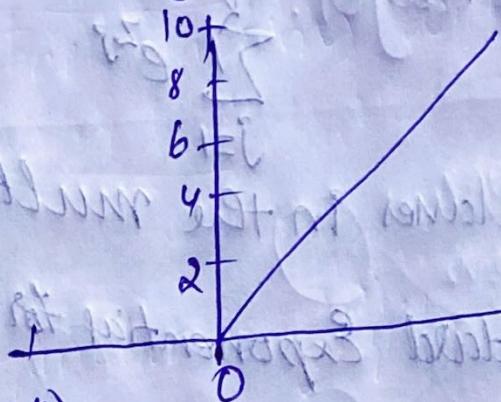


- The function is differentiable.
- The function is monotonic and its derivative is not.
- It is mainly used in between layer and class of.

3) RELU activation function

It is Rectified Linear Unit

It uses the function $f(z) = \max(0, z)$, resulting in a characteristic hockey-stick-shaped response.



It ranges from 0 to ∞ .

The function is monotonic.

4) Softmax Function:

- The Softmax Function can be used for multiclass classification problems,
- It is described as combination of multiple Sigmoids.
- Sigmoid returns values b/w 0 and 1, which can be treated as probabilities of a data point belonging to a particular class.

This function returns the probability for a data point belonging to each individual class.

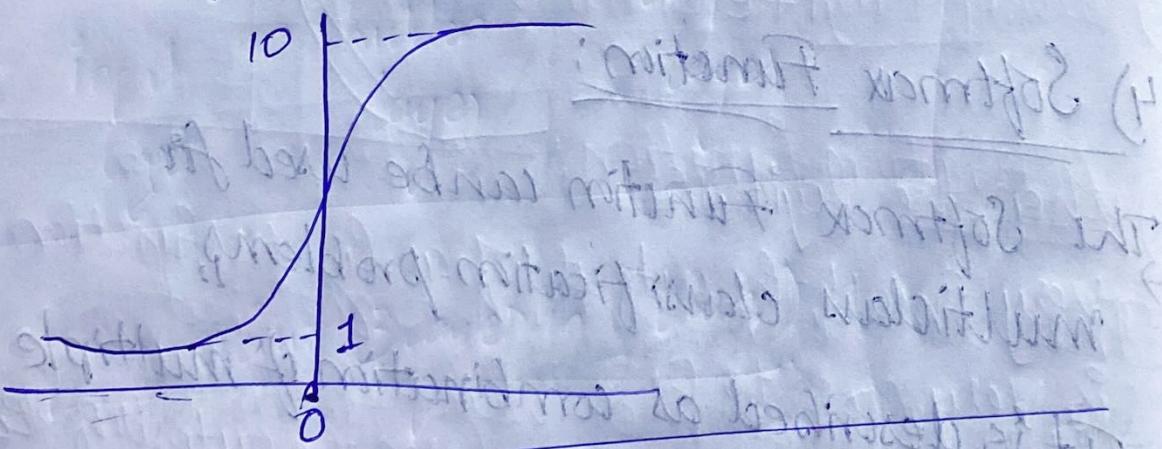
$$\sigma(\vec{z}) = \frac{e^{z_i}}{\sum_{j=1}^k e^{z_j}}$$

k = no of classes in the multiclass classifier

e^{z_j} = Standard Exponential for output vector

e^{z_p} = Standard Exponential for input vector

\vec{z} = Input Vector



Hyperparameters: (not important)

- 1) The k in KNN
- 2) Learning rate for training a neural Network
- 3) Train-test split ratio
- 4) Batch size
- 5) Number of Epochs
- 6) Branches in Decision Tree
- 7) Number of clusters in clustering algorithms

Feed-forward Neural Network:

The process of receiving an input to produce some kind of output to make some kind of prediction is known as feed forward. The feed-forward neural network is the core of many other complex neural networks such as convolution neural network.

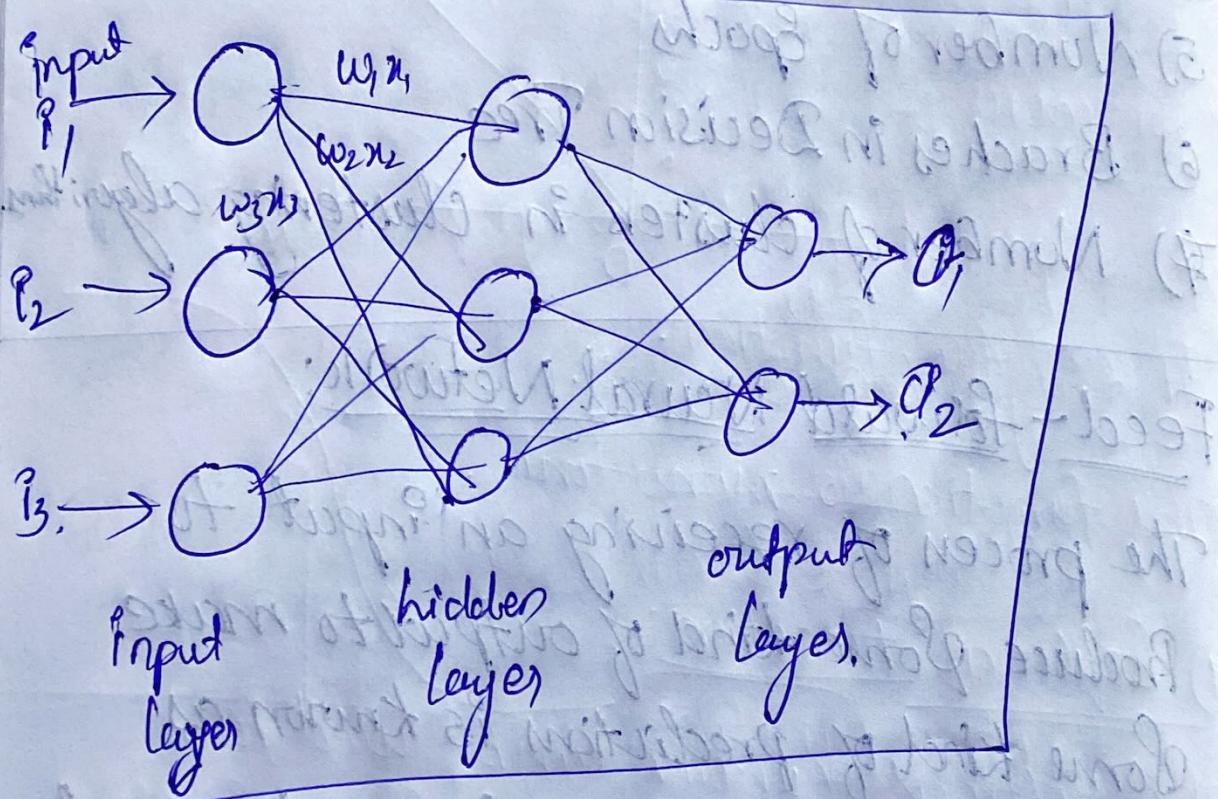
In the feed-forward neural network, there are not only any feedback loops or connections in the network. Here is an

there are 3 layers:

1) Input layer

2) Hidden layer

3) Output layer.



(Explain about 3 layer in own.)