COMSC-200
Lab 7

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1 Search Tree

```
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#include<iostream>

using namespace std;

class Node {
private:
    Node * left;
    Node * right;
    int val;
public:
    Node(int);
    Node * search(int);
    Node * insert(int);
    void setLeft(Node *);
    void setRight(Node *);
    int getVal();
};

Node::Node(int val) {
    this->left = nullptr;
    this->right = nullptr;
    this->val = val;
}

Node * Node::search(int val) {
    if(this->val == val) return this;
    if(this->val > val) return this->left->search(val);
    return this->right->search(val);
}

Node * Node::insert(int val) {
    if(val < this->val) {
        if(this->left == nullptr){
            this->left == new Node(val);
            return this->left;
        }
        this->left->insert(val);
    }
    else if(val > this->val) {
```

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42          if(this->right == nullptr){
43              this->right == new Node(val);
44              return this->right;
45          }
46          this->right->insert(val);
47      }
48
49      return this;
50  }
51
52  void Node::setLeft(Node * n) {
53      this->left = n;
54  }
55
56  void Node::setRight(Node * n) {
57      this->right = n;
58  }
59
60  int Node::getVal() {
61      return val;
62  }
63
64  int main() {
65      Node head = Node(50);
66      head.insert(30);
67      head.insert(80);
68      head.insert(10);
69      head.insert(60);
70      head.insert(70);
71
72      cout << head.search(70)->getVal();
73      return 0;
74  }
```

Listing 1: main.cpp