

MATH 131—HOMEWORK 7

Ricardo J. Acuña

(862079740)

**Q1** Suppose  $U, V$  and  $W$  are finite-dimensional vector spaces and  $S \in \mathcal{L}(V, W)$  and  $T \in \mathcal{L}(U, V)$ . Prove that

$$\dim(\text{range } ST) \leq \min\{\dim(\text{range } S), \dim(\text{range } T)\}$$

Pf.

Let  $U, V$  and  $W$  be finite-dimensional vector spaces and  $S \in \mathcal{L}(V, W)$  and  $T \in \mathcal{L}(U, V)$ .

$ST : U \rightarrow W$  defined by  $ST(u) = S(T(u))$ ,  $u \in U$

$$\text{range } ST = ST(U) = S(T(U)) = S(\text{range } T)$$

$$\Rightarrow \text{range } ST = \{w \in W \mid \exists v \in \text{range } T : w = S(v)\}$$

$$\Rightarrow \text{range } ST \subseteq \text{range } S \Rightarrow \dim(\text{range } ST) \leq \dim(\text{range } S) \quad (1)$$

Let  $B_{T(U)} = \{v_i\}_{i=1}^n$  be a basis for  $\text{range } T$ ,

then  $B_{S(T(U))} = \{S(v_i)\}_{i=1}^n$  spans  $\text{range } ST$  (by Q2 HW6)

If  $T$  is surjective, then  $\text{range } T = V$ ,

$$\text{so } \text{range } ST = S(V) = \text{range } S$$

If  $T$  is not surjective, then either  $B_{S(T(U))}$  is linearly independent or not.

If  $B_{S(T(U))}$  is linearly independent, then  $\dim(\text{range } ST) = n = \dim(\text{range } T)$

If  $B_{S(T(U))}$  is not linearly independent, then we can reduce it to a basis of  $\text{range } ST$ ,

$$\text{accordingly } \dim(\text{range } ST) < n = \dim(\text{range } T)$$

$$\text{In both cases, } \dim(\text{range } ST) \leq \dim(\text{range } T) \quad (2)$$

If  $\dim(\text{range } S) < \dim(\text{range } T)$ , then  $\dim(\text{range } ST) \leq \dim(\text{range } S)$ , which is always true by (1).

If  $\dim(\text{range } T) \leq \dim(\text{range } S)$ , then  $\dim(\text{range } ST) \leq \dim(\text{range } T)$ , by (2).

So,  $\dim(\text{range } ST) \leq \min\{\dim(\text{range } T), \dim(\text{range } S)\}$ .

■

**Q2** Suppose that  $V$  is finite-dimensional and  $T \in \mathcal{L}(V, W)$ . Prove that  $T$  is injective if and only if there exists  $S \in \mathcal{L}(W, V)$  such that  $ST$  is the identity map on  $V$ .

Pf.

$$\forall V, W : \dim(V) \in \mathbb{N} : T \in \mathcal{L}(V, W)$$

( $\Rightarrow$ ) Assume  $T$  is injective

$$\Rightarrow \text{null } T = \{0\}$$

$$\Rightarrow \dim(V) = \dim(\text{null } T) + \dim(\text{range } T)$$

$$= \dim(\{0\}) + \dim(\text{range } T)$$

$$= 0 + \dim(\text{range } T) = \dim(\text{range } T)$$

$$\Rightarrow \dim(V) = m = \dim(\text{range } T) \quad (0)$$

Let  $B_0 = \{v_i\}_{i=1}^m$ , be a basis for  $V$ ,

then  $B = \{T(v_i) = w_i\}_{i=1}^m$ , is a basis for  $\text{range } T$  (by 0)

One can extend  $B$  to a basis  $B' = \{w_i\}_{i=1}^n$ ,  $m \leq n$

Define,  $S : W \rightarrow V$  by 
$$\begin{cases} S(w_i) = v_i, 1 \leq i \leq m \\ S(w_i) = 0, m < i \leq n \end{cases}$$

$$ST(v_i) = S(T(v_i)) = S(w_i) = v_i = id_V(v_i), 1 \leq i \leq m$$

$$\Rightarrow \exists S \in \mathcal{L}(W, V) : ST = id_V$$

( $\Leftarrow$ ) Assume  $\exists S \in \mathcal{L}(W, V) : ST = id_V$

$$\forall v_x, v_y \in V : T(v_x) = T(v_y)$$

$$\Rightarrow S(T(v_x)) = S(T(v_y))$$

$$\Rightarrow ST(v_x) = ST(v_y)$$

$$\Rightarrow id_V(v_x) = id_V(v_y)$$

$$\Rightarrow v_x = v_y$$

$\Rightarrow T$  is injective

So,

$$T \text{ is injective} \Leftrightarrow \exists S \in \mathcal{L}(W, V) : ST = id_V$$

■

**Q3** Suppose  $T \in L(P_2(\mathbb{R}), P_4(\mathbb{R}))$  is the linear map defined by

$$Tp = x^2p.$$

(1) Find the matrix of  $T$  with respect to the standard basis.

$$\mathcal{E} = \{1, x, x^2\}$$

$$\mathcal{F} = \{1, x, x^2, x^3, x^4\}$$

$$T1 = x^21 = x^2 = \begin{bmatrix} 0 \\ 0 \\ 1 \\ 0 \\ 0 \end{bmatrix}_{\mathcal{F}} \quad Tx = x^2x = x^3 = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 1 \\ 0 \end{bmatrix}_{\mathcal{F}} \quad Tx^2 = x^2x^2 = x^4 = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \\ 1 \end{bmatrix}_{\mathcal{F}}$$

$$\Rightarrow [T]_{\mathcal{F} \leftarrow \mathcal{E}} = \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

(2) Verify the fundamental theorem of linear maps.

$$\text{range } T = \text{span} \{x^2, x^3, x^4\}$$

$$\text{null } T = \text{span} \{0\}, \text{ since } x^2p = 0, \text{ has only solution } p = 0, \forall x$$

$$\dim P_2(\mathbb{R}) = |\mathcal{E}| = 3 = 0 + 3 = \dim \{0\} + \dim \{x^2, x^3, x^4\} \checkmark$$

**Q4** Let  $S, T \in \mathcal{L}(V, W)$  and  $\lambda \in F$ . Let  $\mathcal{E} = \{e_1, \dots, e_n\}$  be a basis of  $V$ , and  $\mathcal{F} = \{f_1, \dots, f_m\}$  be a basis of  $W$ . Show that there are identities of matrices as following:

$$[S + T]_{\mathcal{F} \leftarrow \mathcal{E}} = [S]_{\mathcal{F} \leftarrow \mathcal{E}} + [T]_{\mathcal{F} \leftarrow \mathcal{E}},$$

and

$$[\lambda S]_{\mathcal{F} \leftarrow \mathcal{E}} = \lambda [S]_{\mathcal{F} \leftarrow \mathcal{E}}.$$

Pf.

Let  $S, T \in \mathcal{L}(V, W)$  and  $\lambda \in F$ . Let  $\mathcal{E} = \{e_1, \dots, e_n\}$  be a basis of  $V$ , and  $\mathcal{F} = \{f_1, \dots, f_m\}$  be a basis of  $W$ .

$$\exists a_{ji} \in F : S(e_i) = \sum_{j=1}^m a_{ji} f_j \Rightarrow [S]_{\mathcal{F} \leftarrow \mathcal{E}} = \begin{bmatrix} a_{11} & \cdots & a_{1n} \\ \vdots & \ddots & \vdots \\ a_{m1} & \cdots & a_{mn} \end{bmatrix}$$

and

$$\exists b_{ji} \in F : T(e_i) = \sum_{j=1}^m b_{ji} f_j \Rightarrow [T]_{\mathcal{F} \leftarrow \mathcal{E}} = \begin{bmatrix} b_{11} & \cdots & b_{1n} \\ \vdots & \ddots & \vdots \\ b_{m1} & \cdots & b_{mn} \end{bmatrix}$$

$$\Rightarrow [S]_{\mathcal{F} \leftarrow \mathcal{E}} + [T]_{\mathcal{F} \leftarrow \mathcal{E}} = \begin{bmatrix} a_{11} & \cdots & a_{1n} \\ \vdots & \ddots & \vdots \\ a_{m1} & \cdots & a_{mn} \end{bmatrix} + \begin{bmatrix} b_{11} & \cdots & b_{1n} \\ \vdots & \ddots & \vdots \\ b_{m1} & \cdots & b_{mn} \end{bmatrix} = \begin{bmatrix} a_{11} + b_{11} & \cdots & a_{1n} + b_{1n} \\ \vdots & \ddots & \vdots \\ a_{m1} + b_{m1} & \cdots & a_{mn} + b_{mn} \end{bmatrix}$$

$$(S + T)(e_i) := S(e_i) + T(e_i) = \sum_{j=1}^m a_{ji} f_j + \sum_{j=1}^m b_{ji} f_j = \sum_{j=1}^m (a_{ji} + b_{ji}) f_j$$

$$\Rightarrow [S + T]_{\mathcal{F} \leftarrow \mathcal{E}} = \begin{bmatrix} a_{11} + b_{11} & \cdots & a_{1n} + b_{1n} \\ \vdots & \ddots & \vdots \\ a_{m1} + b_{m1} & \cdots & a_{mn} + b_{mn} \end{bmatrix}$$

$$\Rightarrow [S + T]_{\mathcal{F} \leftarrow \mathcal{E}} = [S]_{\mathcal{F} \leftarrow \mathcal{E}} + [T]_{\mathcal{F} \leftarrow \mathcal{E}}$$

$$\lambda S(e_i) = \lambda \sum_{j=1}^m a_{ji} f_j = \sum_{j=1}^m \lambda a_{ji} f_j$$

Also,

$$\Rightarrow [S]_{\mathcal{F} \leftarrow \mathcal{E}} = \begin{bmatrix} \lambda a_{11} & \cdots & \lambda a_{1n} \\ \vdots & \ddots & \vdots \\ \lambda a_{m1} & \cdots & \lambda a_{mn} \end{bmatrix}$$

and

$$[S]_{\mathcal{F} \leftarrow \mathcal{E}} = \begin{bmatrix} a_{11} & \cdots & a_{1n} \\ \vdots & \ddots & \vdots \\ a_{m1} & \cdots & a_{mn} \end{bmatrix} \Rightarrow \lambda [S]_{\mathcal{F} \leftarrow \mathcal{E}} = \lambda \begin{bmatrix} a_{11} & \cdots & a_{1n} \\ \vdots & \ddots & \vdots \\ a_{m1} & \cdots & a_{mn} \end{bmatrix} = \begin{bmatrix} \lambda a_{11} & \cdots & \lambda a_{1n} \\ \vdots & \ddots & \vdots \\ \lambda a_{m1} & \cdots & \lambda a_{mn} \end{bmatrix}$$

$$\Rightarrow [\lambda S]_{\mathcal{F} \leftarrow \mathcal{E}} = \lambda [S]_{\mathcal{F} \leftarrow \mathcal{E}}$$

■

**Q5** Suppose  $D \in \mathcal{L}(P_3(\mathbb{R}), P_2(\mathbb{R}))$  is the differential map defined by

$$Dp = p'$$

Find a basis  $\mathcal{E}$  of  $P_3(\mathbb{R})$  and a basis  $\mathcal{F}$  of  $P_2(\mathbb{R})$  such that the matrix of  $D$  with respect to these bases is

$$[D]_{\mathcal{F} \leftarrow \mathcal{E}} = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \end{pmatrix}$$

$$Dx = 1, D\frac{1}{2}x^2 = x, D\frac{1}{3}x^3 = x^2, D1 = 0$$

So,  $\mathcal{E} = \{x, \frac{1}{2}x^2, \frac{1}{3}x^3, 1\}$ , and  $\mathcal{F} = \{1, x, x^2\}$ , or  $\mathcal{E} = \{x, x^2, x^3, 1\}$ , and  $\mathcal{F} = \{1, 2x, 3x^2\}$ ,

or  $\mathcal{E} = \{2000 + x, 2000 + x^2, 2000 + x^3, 5\}$ , and  $\mathcal{F} = \{1, 2x, 3x^2\}$

Really, bunch, infinitely many.

**Q6** Find linear maps  $S, T \in \mathcal{L}(\mathbb{R}^2)$  such that  $ST \neq TS$ .

$S, T \in \mathcal{L}(\mathbb{R}^2) : \{e_1, e_2\}$  is the standard basis for  $\mathbb{R}^2$

$S : \mathbb{R}^2 \rightarrow \mathbb{R}^2$  defined by

$$S(e_1) = e_1$$

$$S(e_2) = 2e_2$$

$T : \mathbb{R}^2 \rightarrow \mathbb{R}^2$  defined by

$$T(e_1) = e_2$$

$$T(e_2) = 2e_1$$

$$\Rightarrow ST(e_1) = S(T(e_1)) = S(e_2) = 2e_2 \text{ and } ST(e_2) = S(T(e_2)) = S(2e_1) = 2S(e_1) = 2e_1$$

$$\Rightarrow TS(e_1) = T(S(e_1)) = T(e_1) = e_2 \text{ and } TS(e_2) = T(S(e_2)) = T(2e_2) = 2T(e_2) = 2(2e_1) = 4e_1$$

$$\Rightarrow ST \neq TS$$