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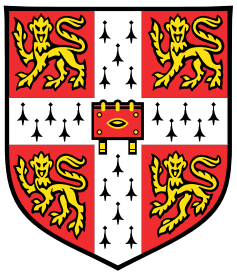

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This dissertation is submitted for the degree of
Master of Engineering

Robinson College May 2022

Declaration

I hereby declare that except where specific reference is made to the work of others, the contents of this dissertation are original and have not been submitted in whole or in part for consideration for any other degree or qualification in this, or any other university. This dissertation is my own work and contains nothing which is the outcome of work done in collaboration with others, except as specified in the text and Acknowledgements. This dissertation contains fewer than 10,000 words including appendices, bibliography, footnotes, tables and equations and has fewer than 40 pages.

Ross Brown
May 2022

Acknowledgements

And I would like to acknowledge ...

Abstract

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Nomenclature

Chapter 3

X_{test}	Datasets used to provide a score for the algorithms
X_{train}	Datasets used for training the algorithms
x_{known}	Data points where the true label is available to the algorithms used
x_{unknown}	Data points where the true label is not available to the algorithms used
y_{known}	True labels available to the algorithms used
y_{unknown}	True labels unavailable to the algorithms used

Chapter 1

Introduction

In 2019, human civilisation was on the precipice of a natural disaster: SARS-CoV-2 (COVID-19). First reported to the WHO on December 31st, it became officially recognised as a pandemic on March 11th 2020. As of the writing of this passage, 515 million cases and 6.24 million death have been recorded. This, however, is not the first time a pandemic has occurred, with the Black Death infamously killing a third of Europe's population and the Spanish Flu causing mass death throughout the world. Likewise, it is unlikely to be the last.

When such a disaster does strike, it is important to react quickly. Vaccinations are allowed accelerated timelines in development cutting development from years to month, and trials into potential treatments are encouraged with haste. Within the first stages of the pandemic, drugs such as hydroxychloroquine and bleach were amongst several that were promoted by the President of the United States of America demonstrating the desperation in finding therapeutic drugs against the virus.

In order to facilitate a more robust approach to finding treatments, the FDA instigated the Coronavirus Treatment Acceleration Program (CTAP) [Cen22]. Here, over 690 drugs are in the development stage with over 450 clinical trials underway to investigate the effectiveness, with 15 drugs currently authorised for emergency use and only one drug, remdesivir, with approval for use against COVID-19 [Cen22]. Indeed, remdesivir is an important case. This drug was developed initially for hepatitis-c before being used for several other conditions until finally being used for COVID-19 [Par+20]. This demonstrates how a discovered drug can be repurposed for new diseases providing a cheap means of drug "redevelopment".

Investigations into pre-existing drugs, however, were slow and largely carried out through labour intensive mechanisms without a rational methodical testing regime. This added time to finding treatments to COVID-19. Time many did not have. A hopeful fulfilment of this problem is the "Robot Scientist"; a fully automated combination of software and hardware aimed at achieving this problem.

Chapter 2

Previous Work

Scores displayed in examples have been based on the entire data set. Although this usually leads to data leakage within machine learning, this is not a concern here as the true comparison comes from testing *intelligent* vs *dumb* learning methods. In both of these cases, the model is kept identical, but the selection process in not. The baseline simply takes the first n entries from the data set, with the *intelligent* method described where required. A simple function has been used to present data as a means of demonstrating these models, with x having two dimensions. The function for y is shown in 2.1 and displayed graphically in Figure 2.1.

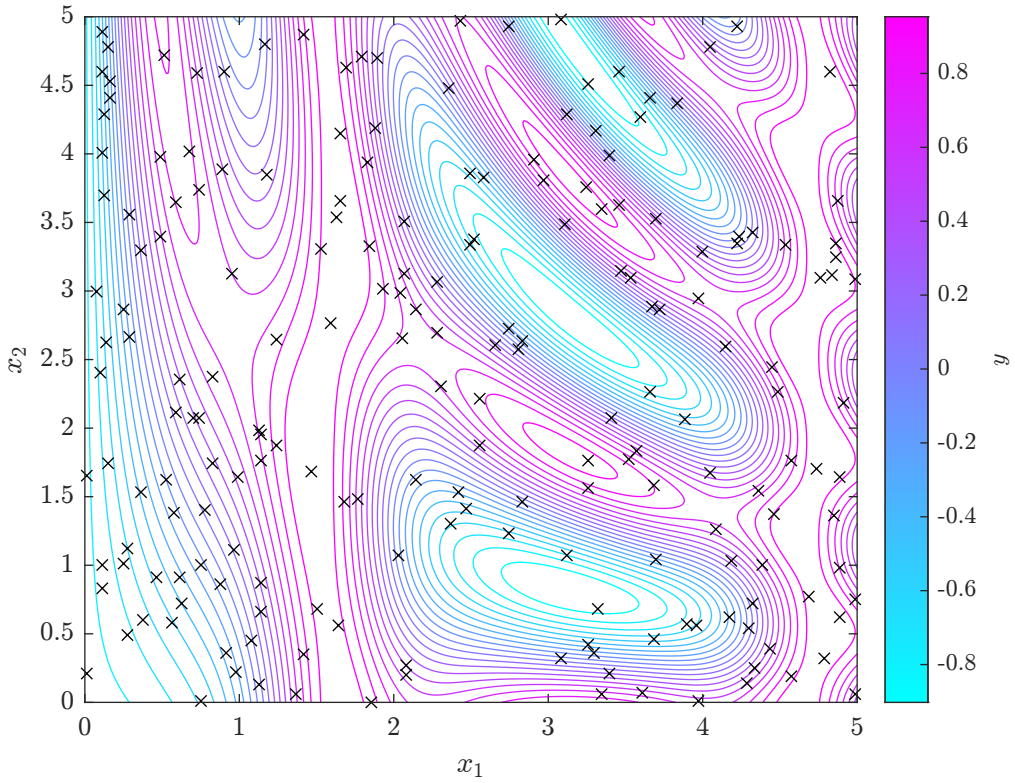


Fig. 2.1 Contour plot of the function used to demonstrate the algorithms presented in previous work. The crosses have been used to show the location of the 200 test data points used within this example.

$$y = \sin(x_1)^{10} + \cos(10 + x_1 x_2)\cos(x_1) \tag{2.1}$$

2.1 Active Learning

There are several schools of thought regarding active learning. These can be separated into two distinct categories: current data and future predictions. The former of these is computationally cheaper, as will be apparent on description.

2.1.1 Current Data

Uncertainty Sampling and Regions of Disagreements

The simplest is applicable to cases in which a certainty is provided with each prediction. Settles [Set09] suggests selecting the data point with the largest uncertainty according to the

current model. Using the dataset ”, this is demonstrated in Figure 2.2 with the algorithm for deciding the next sample point given in Algorithm 1.

Algorithm 1: Uncertainty Sampling Selection

Data: X_{known}, Y_{known}, X_{unknown}

Result: Next X to label

model = BayesianRidge();

model.fit(X_{known}, Y_{known});

standard_deviation = model.standard_deviation(X_{unknown});

return *max(standard_deviation)*

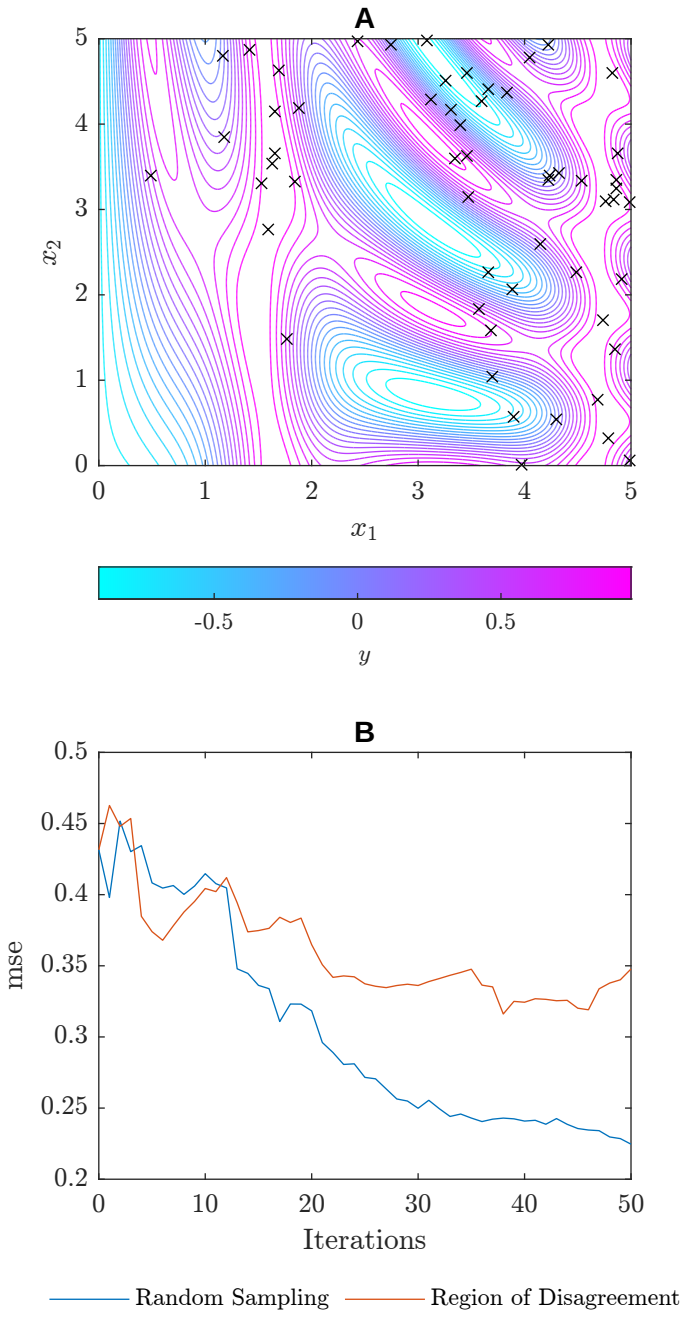


Fig. 2.2 The outcome of the investigating the areas of the highest uncertainty. A) Demonstrates the final set of points tested by the algorithm and B) shows the change in the mean squared error for the algorithm after each iteration.

Interestingly, Figure 2.2B shows how the mean squared error for the random sampling method performed to worse within the iterations tested. This is likely due to a bias in the use of linear models in fitting leading to large uncertainties surrounding areas with high

curvature. Evidence to this is provided in 2.2A with a large proportion of the sampled points at areas of high curvature.

As addressed by Settles [Set09], this can be extended to any probabilistic model through 2.2. Settles [Set09] also notes the use of information theory for probabilistic models(2.3), where y_i refers to all possible categorisations for x. This derives from the principle that the greatest entropy requires the most information to encode, and thus the least certain. However, Settles [Set09] fails to address non-probabilistic models in this instance, instead converting such models into probabilistic ones.

$$x_{\text{next}} = \underset{X}{\operatorname{argmax}} \left[s_{g(X)} \right] \tag{2.2}$$

In order to adapt non-probabilistic models into probabilistic ones, composite models may be used. These are an amalgamation of other models where the standard deviation of the individual models can be taken as the degree of certainty for a given point. Many authors have called this as minimising the region of disagreement as it attempts to produce a coherent hypothesis space. By minimising the region of disagreement between various models, a finer fit may be achieved. Indeed, this was the method used in Figure 2.2.

One way of achieving this, especially in a regression model where boundaries are not quite so distinct, is to declare n models $M = \{m_1, \ldots, m_n\}$. Combining these allow for a model $\hat{m}$ to be defined with prediction $\hat{y}$, being the mean prediction of M, $\frac{1}{n}\sum y_i$ and a sample standard deviation $\hat{s}$ defined as the sample standard deviation of y_i. This standard deviation can be used as a measure of the disagreement between the models. Thus, using a method as in Section 2.1.1.

$$x_{\text{next}} = \underset{x}{\operatorname{argmax}} \left[-\sum_i P(y_i|x) \ln P(y_i|x) \right] \tag{2.3}$$

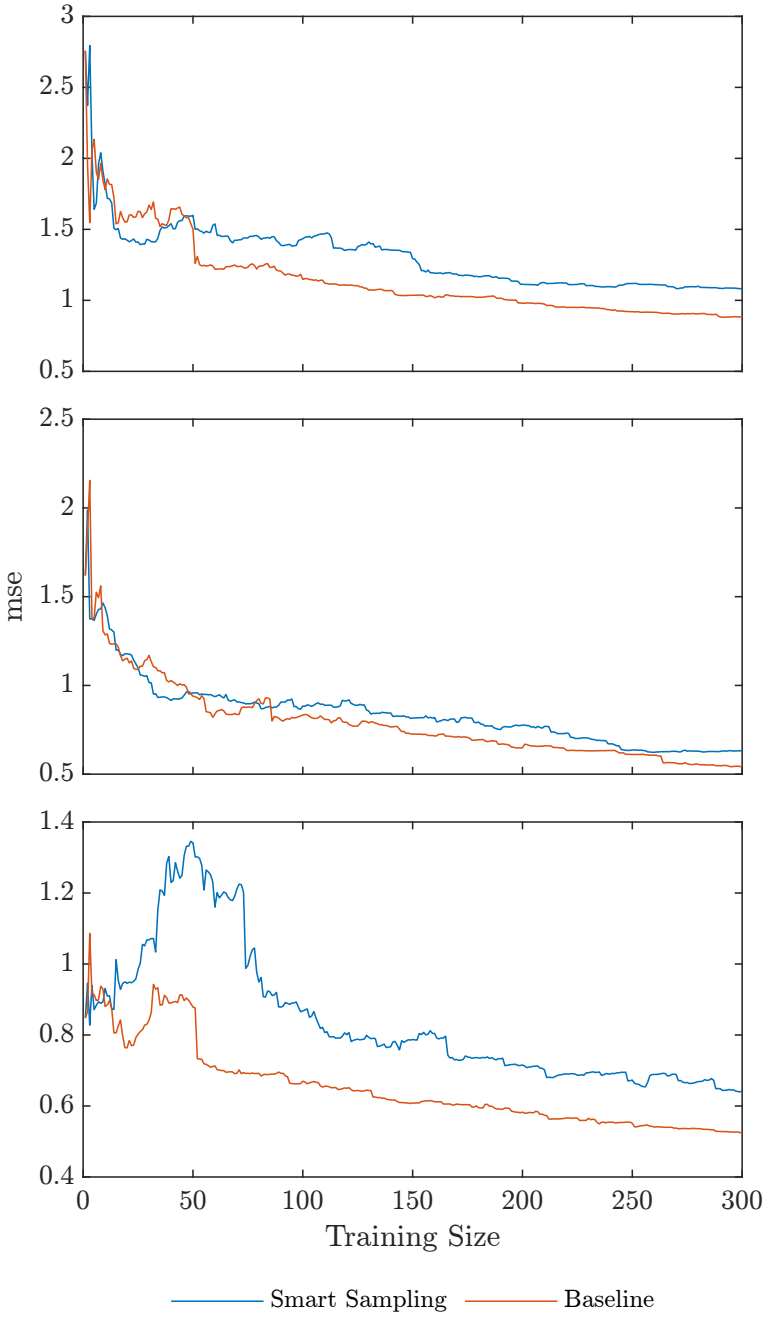
Broad Knowledge Base

A second form stems from information theory. Here, the aim is to produce an evenly dispersed x allowing a well-informed knowledge base. This prevents poor model choice from influencing the algorithm as was seen in 2.2. There are two paths to proceed: density and nearest neighbours.

The former of these requires a definition of density in a sparsely populated space. As an analogy, although the density of a gas appears well-defined, it becomes non-smooth once the volume defined over is comparable to the distance between particles. Thus, a new definition is required.

Alternatively, nearest neighbour requires little explanation. x_{next} is the unlabelled data point furthest from any labelled data point.

$$x_{\text{next}} = \underset{x}{\text{argmax}} \left(\sum \frac{1}{\text{sim}(x, x_i)} \right) \tag{2.4}$$



Density Hotspots

Conversely, a density weighted model has been suggested, as it escapes the introduction of error from outlier (i.e. data points far away from alternative data points). Settles and Craven [SC08] suggest (2.5) which can be broken down into two parts: a function for selection, ϕ_A, and a function for similarity, sim. The former arises from another method described in this section. The latter requires a function to describe the similarity between data points.

$$x_{\text{next}} = \underset{x}{\text{argmax}} \left[\phi_A(x) \times \left(\frac{1}{U} \sum \text{sim}(x, x_i) \right)^{\beta} \right] \tag{2.5}$$

Settles and Craven [SC08] admits that sim is open for interpretation. For simplicity, the average distance

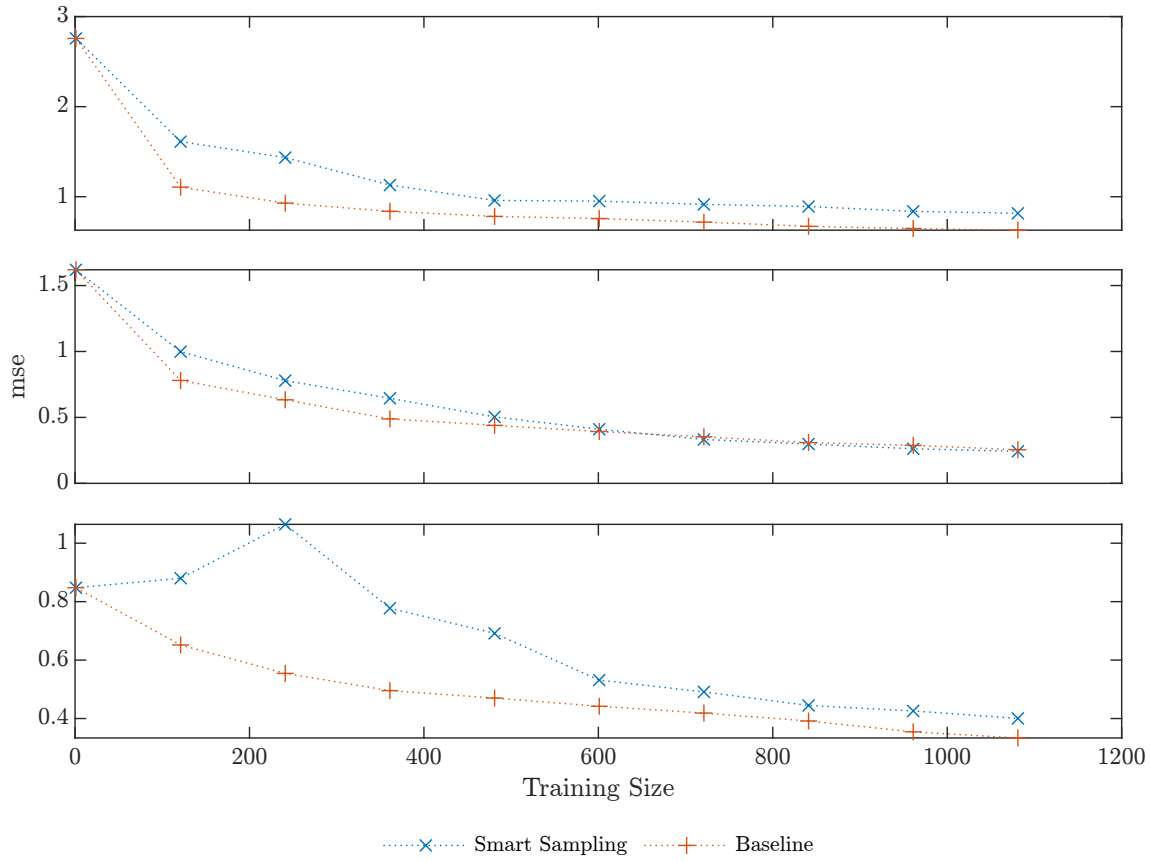
2.1.2 Estimated Future

These methods attempt to minimise a future attribute of the model. This works by predicting changes given with the inclusion of more data.

Expected Model Change

2.2 Batch Active Learning

Several naive methods are available here. Firstly, getting the top N data points from a model described in Section. However, this method does not take into account the equivalence of the data points. This is extremely clear using the highest uncertainty method. Each method in Section[] has been modified to demonstrate this weakness.


3
2
1
1.5
1
0.5
0
mse
1
0.8
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0.4
0
200
400
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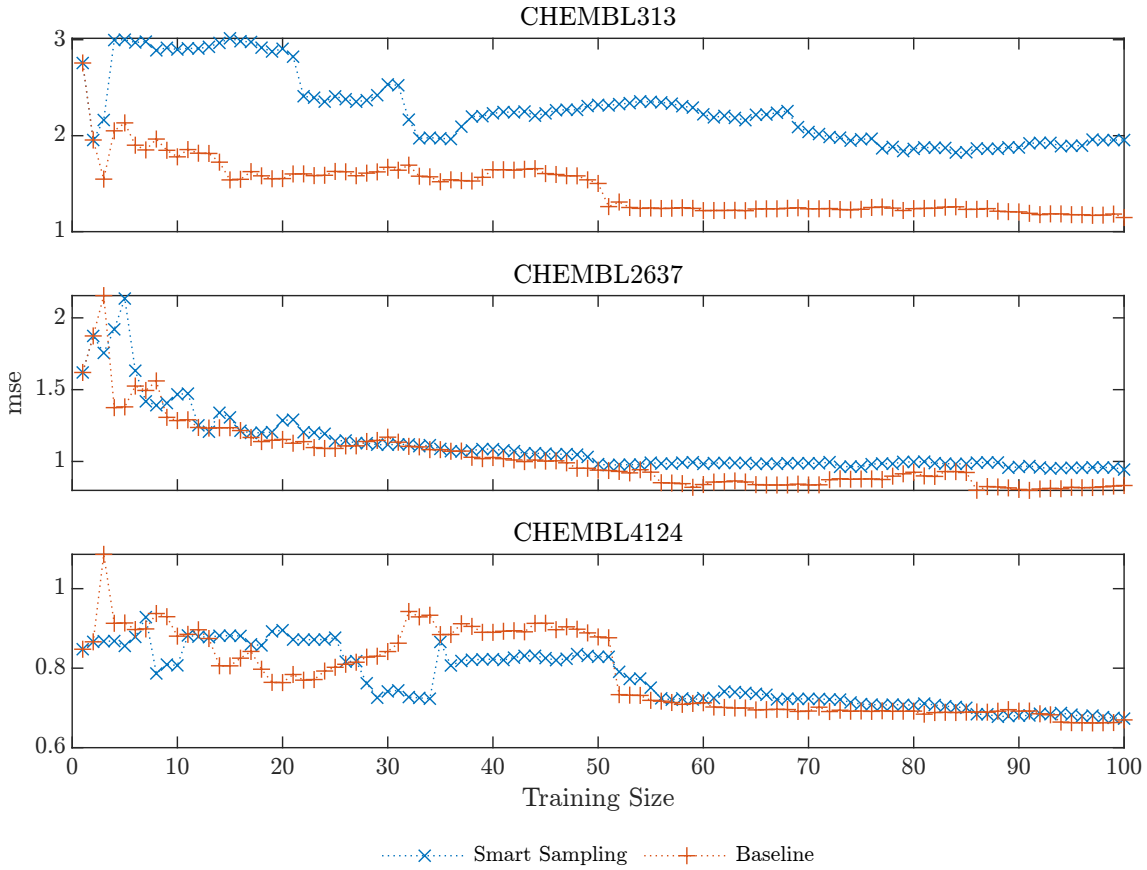
1200
Training Size
Smart Sampling
Baseline



It stands to reason that the area which has the highest uncertainty will see this for the data points nearest neighbours. Thus, this singular data point suffers the potential of being surrounded by $N-1$ other data points. The benefit this provides in fitting the model is thus extremely limited, and only slightly greater than if one data point had been chosen. A simple fix would be to simulate the model after 1 iteration, and select the next point from here. By doing this $N-1$ times, a better solution may be found, although this may prove to be computationally very expensive.

2.3 Drug Data

There are numerous data categories that can be used to represent a chemical in a suitable form for machine learning. Each of these methods have various strengths and weaknesses. Some are directly based upon the chemical structure.

2.4 Physical Properties

A selection of physical properties from chemicals are known, from melting points to solubility. Many of these provide important aspects for consideration and allow human scientists to predict interactions, especially when determining new drugs. These data are often reported in tables within textbooks such as Perry's [] or provided through software [chembl ...]. Several of these data can be predicted through theoretical models, although the difficulty increases for larger molecules. For example, Lorem ipsum dolor sit amet, consectetuer adipiscing elit. Etiam lobortis facilisis sem. Nullam nec mi et neque pharetra sollicitudin. Praesent imperdiet mi nec ante. Donec ullamcorper, felis non sodales commodo, lectus velit ultrices augue, a dignissim nibh lectus placerat pede. Vivamus nunc nunc, molestie ut, ultricies vel, semper in, velit. Ut porttitor. Praesent in sapien. Lorem ipsum dolor sit amet, consectetuer adipiscing elit. Duis fringilla tristique neque. Sed interdum libero ut metus. Pellentesque placerat. Nam rutrum augue a leo. Morbi sed elit sit amet ante lobortis sollicitudin. Praesent blandit blandit mauris. Praesent lectus tellus, aliquet aliquam, luctus a, egestas a, turpis. Mauris lacinia lorem sit amet ipsum. Nunc quis urna dictum turpis accumsan semper.

2.5 Fingerprints

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2.6 Combining Drug Data with Active Learning

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Chapter 3

Methodology

3.1 Outline

The methodology presents a novel means of assessing different parametrised active learning methods on existing data sets, allowing for a robust answer into the use of active learning in drug rediscovery. Results can thus be given with a given belief. This approach has taken principles commonly used in machine learning and applied it to more traditional algorithmic methods.

Firstly, a collection of pre-existing data sets, X, are used. X is then split into two sub sets: X_{train} and X_{test}. Similarly to machine learning, the former of these subsets is used in fitting the parameters of the equation, and the latter is used to provide a result without the risk of data leakage into the training set. This is represented in []. Parallelisation is used to efficiently train the algorithms allowing the time for training to be $\sim \mathcal{O}(c)$.

Examining the smaller details, each algorithm is provided with the sets x_{known}, y_{known}, and x_{unknown}. Various algorithms are given these sets and allowed to generate a subset of x_{unknown} to be added into x_{known} alongside corresponding y_{known}. This can then repeat until a predefined stopping point is reached. Scores are reported using a weighted mean squared error [] based upon y_{predict} for all x. This is similar to a standard machine learning methodology with a couple of differences. Firstly, no distinction is made between the training and testing set within a dataset contrary to standard practice. This is due to two reasons. Firstly, the datasets are not large enough for an accurate representation of the data within the testing set, and secondly, the scoring to each dataset is not used within the machine learning algorithms to fit parameters as is usually the case. All algorithms used rely upon a simple custom composite model to allow for flexibility and consistency.

In Section [], it was discussed that there are various methodologies of representing chemicals and drugs. ... (if time)

3.2 Proof

In order to demonstrate the effectiveness, a few data sets are used instead, and the program is executed function by function. To start with, the underlying custom functions will be demonstrated, followed by the algorithms and then finally the training framework.

3.2.1 Custom Base Functions

Split

The split function allows for each dataset to be split into x_{known}, y_{known}, x_{unknown}, and y_{unknown}, as demonstrated in Figure 3.1. This is required as a fundamental step for the algorithmic testing. To demonstrate the validity of this function, ...

Repartition

Upon each iteration, the sets provided to the algorithms need to be repartitioned to allow for the continual operation of the algorithm. This consists of two parts: expanding the known sets and removing entries from the unknown sets.

Model

The machine learning model is the only custom class used. Here, a similar structure is used when compared with sci-kit's [] machine learning. To manage this, it has four methods: __init__ , fit , predict , and predict_error . The last of these is not seen in all sci-kit's machine learning models and is reserved for those which can report a certainty of prediction. Here, this was achieved by taking a standard deviation of the models.

Validate

This is a simple method with greater potential than has been explored. By providing this as a separate method, a more computationally intensive validation model could be used without interference as parallelisation could be exploited. However, as it currently stands, it returns the weighted mean squared error using the standard method provided by [].

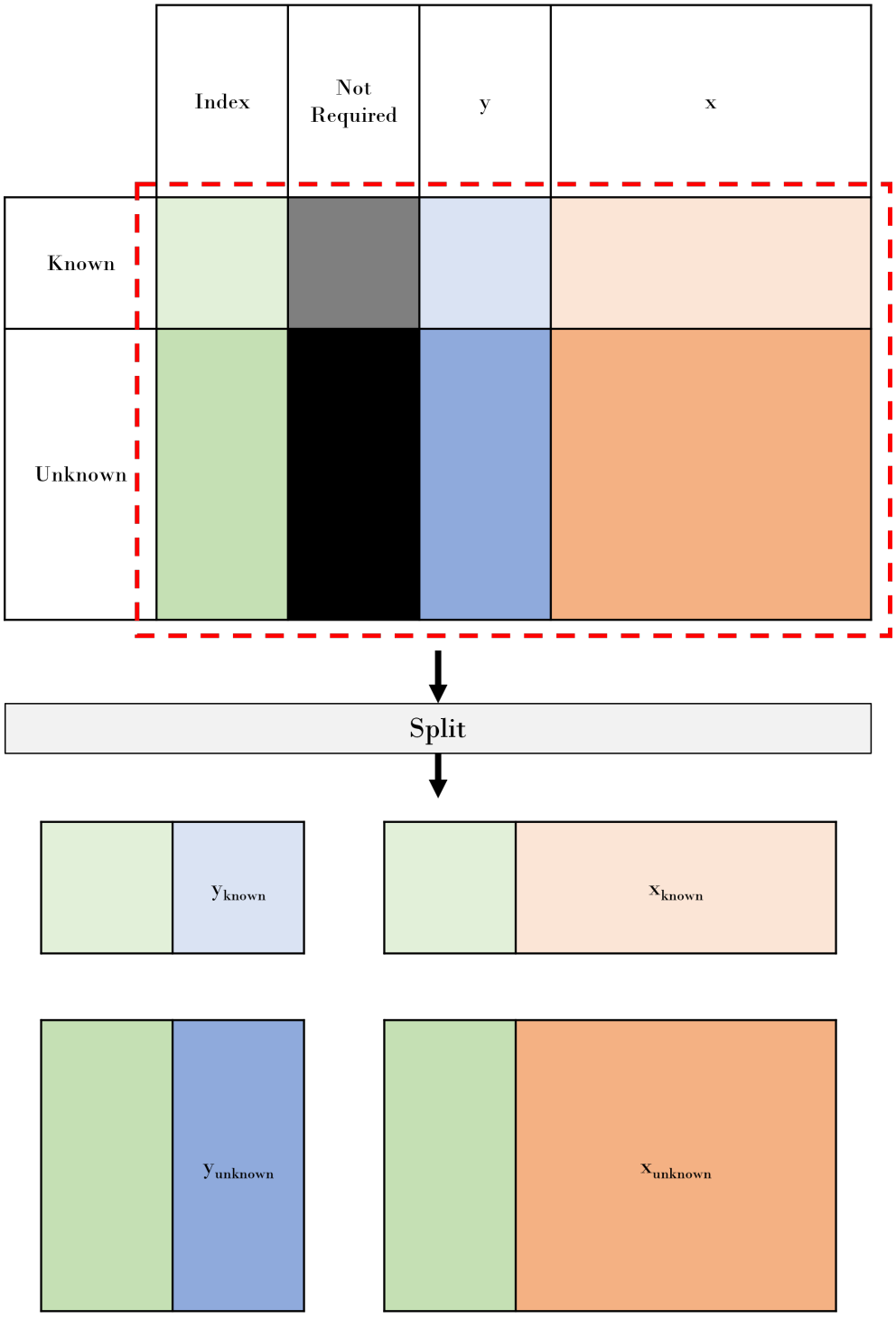

Fig. 3.1 Graphical representation of the split function. The red dashed boundary represents the input (additional colour coding has been performed to assist the reader in understanding the transposition of the base components).

3.2.2 Active Learning Algorithms

Dumb

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The Greatest Uncertainty

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Region of Disagreement

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3.2.3 Training Framework

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Parallelisation

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Minimisation

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Chapter 4

Results

4.1 Overview

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4.2 Second Part

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4.3 Special Case: COVID-19

Chapter 5

Discussion

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Chapter 6

Conclusion

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