Assume: $\log = \ln$, 4 d.p.

Taylor Polynomial

The **Taylor polynomial** of degree n of f, centred at x_0 is defined by

$$P_n(x) = \sum_{k=0}^{n} \frac{f^{(k)}(x_0)}{k!}(x - x_0)^k.$$

Error (Approximating x with $\tilde{x}$)

$$\text{absolute error} = |\tilde{x} - x|$$
$$\text{relative error} = \frac{|\tilde{x} - x|}{|x|}.$$

Floating Point Number Systems

$\mathbb{F}(\beta, k, m, M)$ is a *finite subset* of the real number system. For $f \in \mathbb{F}$:

$$f = \pm (d_1 \,.\, d_2 d_3 \dots d_k)_\beta \times \beta^e$$

- $\beta \in \mathbb{N}$: the base
- $d_1.d_2 d_3 \dots d_k$: the significand
- $k \in \mathbb{N}$: #digits in the significand
- $e \in \mathbb{Z}$: the exponent, $m \leq e \leq M$

d_i are base-β digits with $d_1 \neq 0$ unless $f = 0$. For $x \in \mathbb{R}$ and $f > 0$:

$$f_{\min} = \min_{f \in \mathbb{F}} |f| = \beta^m$$
$$f_{\max} = \max_{f \in \mathbb{F}} |f| = (1 - \beta^{-k})\,\beta^{M+1}.$$

Underflow: $x < f_{\min}$ (replaced by 0).
Overflow: $x > f_{\max}$ (replaced by ∞).
For $\mathbb{F}^+ = \{f \in \mathbb{F} : f > 0\}$:

$$|\mathbb{F}^+| = (M - m + 1)(\beta - 1)\,\beta^{k-1}.$$

Representing Real Numbers

If $x \notin \mathbb{F}$, x is rounded to the nearest representable number with $fl : \mathbb{R} \to \mathbb{F}$. To determine $fl(x)$:

1. Express x in base-β.
2. Express x in scientific form.
3. Verify that $m \leq e \leq M$:
   - if $e > M$, then $x = \infty$.
   - if $e < m$, then $x = 0$.
   - else, round to k digits.

$$\frac{|fl(x) - x|}{|x|} \leq u = \frac{1}{2}\beta^{1-k}.$$

where u is the **unit roundoff** of $\mathbb{F}$.

Catastrophic Cancellation

The error when subtracting similar floating point numbers, where at least one is not exactly representable.

Taylor Polynomials

The nth degree **Taylor polynomial** of f approximates f for x near x_0:

$$P_n(x) = \sum_{k=0}^{n} \frac{f^{(k)}(x_0)}{k!}(x - x_0)^k.$$

If f is $n+1$ times differentiable on $[a, b]$ containing x_0, then for all $x \in [a, b]$, there exists a value $x_0 < c < x$ such that

$$f(x) = P_n(x) + R_n(x)$$

where

$$R_n(x) = \frac{f^{(n+1)}(c)}{(n+1)!}(x - x_0)^{n+1}$$

is the **remainder (error) term** for P_n. The maximum value of $|R_n(x)|$ on $[a, b]$ bounds the maximum absolute error of the approximation:

$$|f(x) - P_n(x)| = |R_n(x)|.$$

Ordinary Differential Equations

$\frac{\mathrm{d}y}{\mathrm{d}t} = f(t, y)$ with $y(a) = \alpha$ on $a \leq t \leq b$. Divide $[a, b]$ into n subintervals of width $h = (b - a)/n$. Let $t_i = a + ih$ for $i = 0, 1, \dots, n$. Then $y_i = y(t_i)$ approximates y at $t = t_i$, with $y_0 = \alpha$.

Euler's Method (First Order Taylor)

$$y(t) = P_1(t) + R_1(t)$$
$$y(t) = y(t_i) + y'(t_i)(t - t_i) + \mathcal{O}(t^2)$$
$$y(t_{i+n}) = y(t_i) + y'(t_i)(t_{i+n} - t_i) + \mathcal{O}(t^2)$$
$$y(t_{i+n} - t_i + t_i) = y(t_i) + y'(t_i)(t_{i+n} - t_i) + \mathcal{O}(t^2)$$
$$y(t_i + h) = y(t_i) + hy'(t_i) + \mathcal{O}(h^2).$$

where the error is proportional to h^2.

$$y_{i+1} = y_i + hf(t_i, y_i).$$

Local and Global Error

Assuming the solution was correct at the previous step:
Local: error after 1 **step** — $\mathcal{O}(h^{p+1})$.
Global: error after i **steps** — $\mathcal{O}(h^p)$.
The **order** of a method is its global error.

Second Order Taylor Method

$$y_{i+1} = y_i + hf(t_i, y_i) + \frac{h^2}{2} f'(t_i, y_i).$$

Modified Euler Method

To avoid computing $f'(t, y)$ use,

$$\frac{f(t_{i+1}, y_{i+1}) - f(t_i, y_i)}{h} + \mathcal{O}(h).$$
$$y_{i+1} = y_i + \frac{1}{2}(k_1 + k_2)$$
$$k_1 = hf(t_i, y_i)$$
$$k_2 = hf(t_i + h, y_i + k_1)$$

Runge-Kutta Method (Fourth Order)

$$y_{i+1} = y_i + \frac{1}{6}(k_1 + 2k_2 + 2k_3 + k_4)$$
$$k_1 = hf(t_i, y_i)$$
$$k_2 = hf\left(t_i + \frac{h}{2}, y_i + \frac{k_1}{2}\right)$$
$$k_3 = hf\left(t_i + \frac{h}{2}, y_i + \frac{k_2}{2}\right)$$
$$k_4 = hf(t_i + h, y_i + k_3)$$

$i = 0, 1, \dots, n-1$ for all four methods.

Interpolation

$$P_n(x) = a_0 + a_1 x + \dots + a_n x^n.$$

Lagrange Form

Solve for a_i then factor $P_n(x_i)$ for y_i:

$$P_n(x) = \sum_{i=0}^{n} L_{n,i}(x)\, y_i$$

$$L_{n,i}(x) = \prod_{\substack{j=0 \\ j \neq i}}^{n} \frac{x - x_j}{x_i - x_j}, L_{n,i}(x_j) = \delta_{ij}$$

For distinct increasing x_i on $[a, b]$ there exists $c \in [a, b]$ such that

$$f(x) = P_n(x) + \frac{f^{(n+1)}(c)}{(n+1)!} \prod_{i=0}^{n}(x - x_i).$$

Newton's Divided Difference Form

$$\begin{aligned} P_n(x) &= a_0 + a_1(x - x_0) \\ &\quad + a_2(x - x_0)(x - x_1) + \cdots \\ &\quad + a_n(x - x_0)\cdots(x - x_{n-1}) \\ &= \sum_{k=0}^{n} f[x_0, x_1, \dots, x_k] \prod_{i=0}^{k-1}(x - x_i) \end{aligned}$$

Solve $P_n(x_i) = y_i$ for $a_0, a_1, \dots, a_n$:

$$a_0 = y_0, \quad a_1 = \frac{y_1 - y_0}{x_1 - x_0}$$
$$a_2 = \frac{\frac{y_2 - y_1}{x_2 - x_1} - \frac{y_1 - y_0}{x_1 - x_0}}{x_2 - x_0}$$

Divided Differences (Simplify a_i)

$f[x_i] = y_i$ (Zeroth divided difference)

$$f[x_i, x_{i+1}, \dots, x_{i+k}] = \frac{f[x_{i+1}, \dots, x_{i+k}] - f[x_i, \dots, x_{i+k-1}]}{x_{i+k} - x_i}$$

$$f[x_0, x_1] = \frac{f[x_1] - f[x_0]}{x_1 - x_0} = \frac{y_1 - y_0}{x_1 - x_0}$$
$$f[x_1, x_2] = \frac{f[x_2] - f[x_1]}{x_2 - x_1} = \frac{y_2 - y_1}{x_2 - x_1}$$
$$f[x_0, x_1, x_2] = \frac{f[x_1, x_2] - f[x_0, x_1]}{x_2 - x_0}$$

Newton's Forward Difference Form

Equally spaced abscissas: $h = x_{i+1} - x_i$.

Forward Difference Operator

$$\Delta y_i = y_{i+1} - y_i, \quad \Delta^{k+1} y_i = \Delta(\Delta^k y_i)$$
$$\Delta^2 y_i = y_{i+2} - 2y_{i+1} + y_i$$
$$\Delta^3 y_i = y_{i+3} - 3y_{i+2} + 3y_{i+1} - y_i$$
$$f[x_0, x_1, \dots, x_k] = \frac{\Delta^k y_0}{k! h^k}$$

Substitute $x = x_0 + sh$ ($x_i = x_0 + ih$), with $s = \frac{x - x_0}{h}$ into the divided difference form:

$$P_n(x) = \sum_{k=0}^{n} \frac{\Delta^k y_0}{k!} \prod_{i=0}^{k-1}(s - i)$$

Difference Tables

x_i	y_i		
$\div$	$f[x_i]$	$f[x_i, x_i + 1]$	$f[x_i, x_{i+1}, x_{i+2}]$
Δ	y_i	Δy_i	$\Delta^2 y_i$

Root Finding ($f(x) = 0$)

Intermediate Value Theorem

For continuous f on $[a, b]$ with $f(a) \leq k \leq f(b)$, $\exists c_1 \in [a, b] : f(c_1) = k$. If $f(a)f(b) < 0$ ($f(a)$ and $f(b)$ have opposite signs), $\exists c_2 \in [a, b] : f(c_2) = 0$.

Bisection Method

1. Find $[a, b]$ such that $f(a)f(b) < 0$.
2. For $p = \frac{a+b}{2}$, evaluate $f(p)$.
   - If $f(p) = 0$, then p is a root of f.
   - If $f(a)f(p) < 0$, then p becomes the new b and the root lies in $[a, p]$.
   - If $f(p)f(b) < 0$, then p becomes

the new a and the root lies in $[p, b]$.

3. Go to step 2.

Fixed-Point Iteration

Rewrite $f(x) = 0$ as $x = g(x)$. Solve by finding a fixed-point p s.t. $g(p) = p$.

$$x_{n+1} = g(x_n) \quad (n \geq 0).$$

Newton's Method

Find the root of the tangent line at each iterate x_n using the first degree Taylor polynomial and solving for x:

$$f(x) \approx f(x_n) + f'(x_n)(x - x_n) \stackrel{\text{set}}{=} 0$$

$$x = x_{n+1} = x_n - \frac{f(x_n)}{f'(x_n)} \quad (n \geq 0)$$

Secant Method

Approximate $f'(x_n)$ with the secant between x_{n-1} and x_n:

$$f'(x_n) \approx \frac{f(x_n) - f(x_{n-1})}{x_n - x_{n-1}}$$

with two initial values for $n \geq 1$.

Convergence of Rootfinding Methods

A convergent $\{x_n\}$ satisfies (for large n)

$$|x_{n+1} - p| \approx \lambda |x_n - p|^r$$

Fixed-point iteration ($r = 1$)

p is a fixed-point and $0 < \lambda < 1$.

Newton's method ($r = 2$)

p is a root and $\lambda > 0$.

Secant method ($r = \frac{1+\sqrt{5}}{2} \approx 1.618$)

p is a root and $\lambda > 0$.

Numerical Differentiation

Forward ($h = x - x_0$, $c \in [x_0, x_0 + h]$)

$$f'(x_0) = \frac{f(x_0 + h) - f(x_0)}{h} - \frac{h}{2} f''(c)$$

Backward ($-h = x - x_0$, $c \in [x_0 - h, x_0]$)

$$f'(x_0) = \frac{f(x_0) - f(x_0 - h)}{h} + \frac{h}{2} f''(c)$$

Central Difference (Second Order)

Derive using $f(x_0 + h) - f(x_0 - h)$:

$$f'(x_0) = \frac{f(x_0 + h) - f(x_0 - h)}{2h} - \frac{h^2}{6} f^{(3)}(c)$$

$f^{(3)}(c) = \frac{f^{(3)}(c_1) + f^{(3)}(c_2)}{2}$ and $c \in [c_1, c_2]$, with $c_1 \in [x_0 - h, x_0]$ and $c_2 \in [x_0, x_0 + h]$.

Second Derivative (Third Order)

Derive using $f(x_0 + h) + f(x_0 - h)$:

$$f''(x_0) = -\frac{h^2}{12} f^{(4)}(c) + \frac{f(x_0 + h) - 2f(x_0) + f(x_0 - h)}{h^2}$$

$f^{(4)}(c) = \frac{f^{(4)}(c_1) + f^{(4)}(c_2)}{2}$ and $c \in [c_1, c_2]$, with $c_1 \in [x_0 - h, x_0]$ and $c_2 \in [x_0, x_0 + h]$.

Brouwer's Fixed-Point Theorem

For g continuous on $[a, b]$, and differentiable on (a, b), with $g(x) \in [a, b] : \forall x \in [a, b]$, let a positive constant $k < 1$ exist such that $|g'(x)| \leq k \; \forall x \in (a, b)$. Then, g has a unique fixed-point p in $[a, b]$, and $x_{n+1} = g(x_n)$ will converge to p for all x_0 in $[a, b]$.

Numerical Integration (Quadrature)

$$I = \int_a^b f(x) \, \mathrm{d}x \approx \sum_{i=0}^{n} w_i f(x_i)$$

for weights w_i and abscissas x_i.
Divide $[a, b]$ into n subintervals of width $h = (b - a)/n$. Let $x_i = a + ih$ for $i = 0, 1, \ldots, n$, so that $x_0 = a$ and $x_n = b$.

Trapezoidal Rule (Second Order)

Approximate $f(x)$ over each subinterval $[x_{i-1}, x_i]$ with a degree 1 interpolant:

$$P_{1,i}(x) = y_{i-1} + s\Delta y_{i-1} = y_{i-1} + s(y_i - y_{i-1})$$

and integrate w.r.t. s: $x = x_{i-1} + sh$, $\mathrm{d}x = h\,\mathrm{d}s$, with limits $s \in [0, 1]$:

$$\int_{x_{i-1}}^{x_i} f(x) \, \mathrm{d}x \approx \int_0^1 P_{1,i}(x) \, h \, \mathrm{d}s = \frac{h}{2}(y_{i-1} + y_i) \quad (i = 1, 2, \ldots, n).$$

$$I = \sum_{i=1}^{n} \int_{x_{i-1}}^{x_i} f(x) \, \mathrm{d}x \approx \sum_{i=1}^{n} \frac{h}{2} [f(x_{i-1}) + f(x_i)]$$

$$= \frac{h}{2} \left[f(x_0) + 2 \sum_{i=1}^{n-1} f(x_i) + f(x_n) \right] - \frac{(b-a) h^2}{12} f''(c)$$

Simpson's Rule (Fourth Order)

Approximate $f(x)$ over each subinterval $[x_{2i-2}, x_{2i}]$ with a degree 2 interpolant:

$$P_{2,i}(x) = y_{2i-2} + s\Delta y_{2i-2} + \frac{s(s-1)}{2} \Delta^2 y_{2i-2}$$

$$= y_{2i-2} + s(y_{2i} - y_{2i-1}) + \frac{s(s-1)}{2} (y_{2i} - 2y_{2i-1} + y_{2i-2})$$

and integrate w.r.t. s: $x = x_{2i-2} + sh$, $\mathrm{d}x = h\,\mathrm{d}s$, with limits $s \in [0, 2]$:

$$\int_{x_{2i-2}}^{x_{2i}} f(x) \, \mathrm{d}x \approx \int_0^2 P_{2,i}(x) \, h \, \mathrm{d}s = \frac{h}{3}(y_{2i-2} + 4y_{2i-1} + y_{2i}) \quad (i = 1, 2, \ldots, n/2).$$

$$I = \sum_{i=2}^{n/2} \int_{x_{2i-2}}^{x_{2i}} f(x) \, \mathrm{d}x \approx \sum_{i=2}^{n/2} \frac{h}{3} [f(x_{2i-2}) + 4f(x_{2i-1}) + f(x_{2i})]$$

$$= \frac{h}{3} \left[f(x_0) + 4 \sum_{i=1}^{n/2} f(x_{2i-1}) + 2 \sum_{i=1}^{n/2-1} f(x_{2i}) + f(x_n) \right] - \frac{(b-a) h^4}{180} f^{(4)}(c)$$

Linear Systems ($\mathbf{A}\boldsymbol{x} = \boldsymbol{b}$)

LU Decomposition ($\mathbf{A} = \mathbf{LU} \implies \mathbf{L}\boldsymbol{z} = \boldsymbol{b}$, $\mathbf{U}\boldsymbol{x} = \boldsymbol{z}$)

$$\mathbf{LU} = \begin{bmatrix} 1 & 0 & 0 \\ \frac{a_{21}}{u_{11}} & 1 & 0 \\ \frac{a_{31}}{u_{11}} & \frac{a_{32} - \ell_{31} u_{12}}{u_{22}} & 1 \end{bmatrix} \begin{bmatrix} a_{11} & a_{12} & a_{13} \\ 0 & a_{22} - \ell_{21} u_{12} & a_{23} - \ell_{21} u_{13} \\ 0 & 0 & a_{33} - \ell_{31} u_{13} - \ell_{32} u_{23} \end{bmatrix}$$

$$= \begin{bmatrix} u_{11} & u_{12} & u_{13} \\ \ell_{21} u_{11} & \ell_{21} u_{12} + u_{22} & \ell_{21} u_{13} + u_{23} \\ \ell_{31} u_{11} & \ell_{31} u_{12} + \ell_{32} u_{22} & \ell_{31} u_{13} + \ell_{32} u_{23} + u_{33} \end{bmatrix}$$

Symmetric Positive Definite: $\boldsymbol{x}^\top \mathbf{A} \boldsymbol{x} > 0 : \forall \boldsymbol{x} \in \mathbb{R}^n$.

Cholesky Decomposition ($\mathbf{A} = \mathbf{LL}^\top \implies \mathbf{L}\boldsymbol{z} = \boldsymbol{b}$, $\mathbf{L}^\top \boldsymbol{x} = \boldsymbol{z}$)

$$\mathbf{L} = \begin{bmatrix} \sqrt{a_{11}} & 0 & 0 \\ \frac{a_{21}}{\ell_{11}} & \sqrt{a_{22} - \ell_{21}^2} & 0 \\ \frac{a_{31}}{\ell_{11}} & \frac{a_{32} - \ell_{21} \ell_{31}}{\ell_{22}} & \sqrt{a_{33} - \ell_{31}^2 - \ell_{32}^2} \end{bmatrix}$$

$$\mathbf{LL}^\top = \begin{bmatrix} \ell_{11}^2 & \ell_{11} \ell_{21} & \ell_{11} \ell_{31} \\ \ell_{11} \ell_{21} & \ell_{21}^2 + \ell_{22}^2 & \ell_{21} \ell_{31} + \ell_{22} \ell_{32} \\ \ell_{11} \ell_{31} & \ell_{21} \ell_{31} + \ell_{22} \ell_{32} & \ell_{31}^2 + \ell_{32}^2 + \ell_{33}^2 \end{bmatrix}$$