

Contents

1	Point Estimation	2
1.1	Method of Moments	2
2	Maximum Likelihood	4

1 Point Estimation

Definition: A point estimator is any scalar (or vector) -valued function of the sample. $(x_1, \dots, x_n) \sim f(x|\theta)$

A point estimator for $\tau(\theta)$ is a statistic $T(x)$ with the purpose of approximating $\tau(\theta)$

1.1 Method of Moments

The k-th moment of a r.v. X is $\mu_k(\theta) = \mathbb{E}_\theta(X^k) = \int_{\mathbb{X}} x^k f(x|\theta) dx$

Given an iid sample $x_1, \dots, x_n \stackrel{\text{iid}}{\sim} f(x|\theta)$ we have sample moments: $\hat{\mu}_k = \frac{1}{n} \sum_{i=1}^n x_i^k$

Suppose $\theta \in \Theta \in \mathbb{R}^P$, and that $\mu_k(\theta)$ exists and is finite for $k = 1, \dots, p$.

Definition: The method of moments estimator of θ is the solution to the system of equations:

$$\mu_1(\theta) = \hat{\mu}_1 \quad (1)$$

$$\cdot \quad (2)$$

$$\cdot \quad (3)$$

$$\mu_p(\theta) = \hat{\mu}_p \quad (4)$$

We call it $\hat{\theta}_{MM}$

Example: $X_i \stackrel{\text{iid}}{\sim} \text{Beta}(\alpha, \beta), \theta = (\alpha, \beta)$

$$\mu_1(\theta) = \frac{\alpha}{\alpha + \beta}$$

$$\mu_2(\theta) = \text{Var}_\theta(x_1) + \left(\frac{\alpha}{\alpha + \beta}\right)^2 = \frac{\alpha\beta}{(\alpha + \beta)^2(\alpha + \beta + 1)} + \frac{\alpha^2}{(\alpha + \beta)^2}$$

$$\frac{\alpha}{\alpha + \beta} = \hat{\mu}_1, \frac{\alpha\beta}{(\alpha + \beta)^2(\alpha + \beta + 1)} + \frac{\alpha^2}{(\alpha + \beta)^2} = \hat{\mu}_2$$

$\beta = \left(\frac{1 - \hat{\mu}_1}{\hat{\mu}_1}\right) \alpha$ from the first equation. Plug this into the second expression and solve:

$$\hat{\alpha}_{MM} = \hat{\mu}_1 \left[\frac{\hat{\mu}_1(1 - \hat{\mu}_1)}{\hat{\mu}_2 - \hat{\mu}_1^2} - 1 \right]$$

$$\implies \hat{\beta}_{MM} = \frac{(1 - \hat{\mu}_1)}{\hat{\mu}_1} \hat{\alpha}_{MM}$$

Example: $x_i \stackrel{\text{iid}}{\sim} N(\mu, \sigma^2)$

$$\mu_1(\theta) = \hat{\mu}_1, \mu_1(\theta) = \mu, \implies \hat{\mu}_{MM} = \mu$$

$$\mu_2(\theta) = \text{Var}_\theta(x_1) + \mu_1^2 = \sigma^2 + \mu^2 = \hat{\mu}_2$$

$$\sigma_{MM}^2 = \hat{\mu}_2 - \hat{\mu}_1^2 = \frac{n-1}{n} s^2$$

Note: If μ, σ^2 are the mean/variance of any family, their MM estimators are $\overline{X}, \frac{n-1}{n} s^2$.

For families where parameters are not just the mean and variance, you can find it via two ways: use mean/variance in MM, then calculate parameters, or use parameters in MM then calculate mean/variance. Both yield same results.

Fact: MM estimators are invariant of re-parameterizations.

Let $\eta = \eta(\theta)$ be a 1:1 mapping (invertible). Then, $\hat{\eta}_{MM} = \eta(\hat{\theta}_{MM})$

Let's say $x_i \stackrel{\text{iid}}{\sim} N(\mu, \sigma^2)$ and we want to estimate $\tau(\theta) = \frac{\mu}{\sigma}$. This isn't 1:1. What can we do? We can do the 'Transformations' method and create a second value τ_2 , etc. We can also just plug in the estimators.

Definition: The MM estimator for a parametric function $\tau(\theta)$ is just $\hat{\tau}_{MM}(\theta) = \tau(\hat{\theta}_{MM})$

Properties:

- MM equations may have a unique solution, no solution, or many solutions
- Often, MM estimators are used as initial values for another estimation technique (ie. a root finding method)
- Why should it work? Let's say θ^* is the true value of θ . Then Law of Large Numbers says: $\hat{\mu}_k \xrightarrow{P} \mu_k(\theta^*)$. Then we are solving $\mu_k(\theta) = \hat{\mu}_k \approx \mu_k(\theta^*)$

Example: $X_i \stackrel{\text{iid}}{\sim} \text{Bin}(m, \theta), i = 1, \dots, n$ (m is known)

Find the MM estimator of $\tau(\theta) = \ln \frac{\theta}{1-\theta}$

1. Find MM for θ ($\hat{\theta}_{MM}$)
2. Plug in ($\hat{\tau}_{MM}(\theta) = \tau(\hat{\theta}_{MM})$)
3. $\hat{\tau}_{MM}(\theta) = \ln \frac{\bar{X}/m}{1-\bar{X}/m}$

2 Maximum Likelihood

$X = (X_1, \dots, X_n) \sim f(x|\theta), \theta \in \Theta \subset \mathbb{R}^k$

Notation: $f(x; \theta)$: function of x indexed at θ . Basically, given some set value of the θ .

Likelihood Function: The likelihood function is: $L(\theta; x) = f(x|\theta)$

Notes:

- L is a function of θ for each $x \in \mathbb{X}$ (in sample space)
- Plugging in X for x gives $L(\theta; X)$, a stochastic process (ie. plug in a random X makes this a random function for θ)
- The log-likelihood function is $l(\theta; x) = \ln[L(\theta; x)]$
- If $x_i \stackrel{\text{iid}}{\sim} f(x_i|\theta)$ (f is marginal dist.), then $l(\theta; x) = \sum_{i=1}^n \ln[f(x_i|\theta)]$ (because $x_i \stackrel{\text{iid}}{\sim}$, the sum is just a transformation and we can apply LLN, CLT, etc.)

Maximum Likelihood Estimate: If $x \in \mathbb{X}$ is observed, a maximum likelihood estimate of $\theta, \hat{\theta}(x)$, is any value $\theta \in \Theta$ that maximizes $L(\theta|x)$.

$$\hat{\theta}(x) = \underset{\theta \in \Theta}{\operatorname{argmax}} [L(\theta|x)]$$

This is a function of observed data (an estimate, not an estimator).

Maximum Likelihood Estimator: A maximum likelihood estimator (MLE) is $\hat{\theta} = \hat{\theta}(X)$

If an ML estimate exists, then $\hat{\theta}(x) = \underset{\theta \in \Theta}{\operatorname{argmax}} [l(\theta; x)]$. This is because $\ln(x)$ is a strictly increasing function.

Why does maximum likelihood work? Can we show that $\hat{\theta} \approx \theta_0$ (true parameter)?

Assume $X_1, \dots, X_n \stackrel{\text{iid}}{\sim} f(x_i|\theta)$. $l(\theta|x) = \sum_{i=1}^n \ln[f(x_i|\theta)]$

$$\frac{1}{n} l(\theta|x) = \frac{1}{n} \sum_{i=1}^n \ln[f(x_i|\theta)] \xrightarrow{P} \mathbb{E}_{\theta_0}(\ln[f(x|\theta)]) = \int_{\mathbb{X}} \ln[f(x|\theta)] f(x|\theta_0) dx$$

It would make sense that $\hat{\theta}(x) = \underset{\theta \in \Theta}{\operatorname{argmax}} [l(X|\theta)] \approx \underset{\theta \in \Theta}{\operatorname{argmax}} \mathbb{E}_{\theta_0}(\ln[f(X|\theta)])$ which we hope $= \theta_0$.

Define $D(\theta; \theta_0) = \mathbb{E}_{\theta_0}(\ln[f(X|\theta)])$. We will show that $D(\theta_0; \theta_0) - D(\theta; \theta_0) \geq 0 \forall \theta$.

Kullback-Liebler Divergence: Let f_0 and f_1 be any two PDFs/PMFs. The Kullback-Liebler divergence from f_0 to f_1 is $K(f_0, f_1) = -\mathbb{E}_{f_0}[\ln \frac{f_1(x)}{f_0(x)}]$

$$D(\theta_0; \theta_0) - D(\theta; \theta_0) = \mathbb{E}_{\theta_0}[\ln(f(X|\theta_0)) - \ln(f(X|\theta))] = -\mathbb{E}_{\theta_0}[\ln \frac{f(X|\theta)}{f(X|\theta_0)}].$$

Lemma: For any two PDFs/PMFs f_0, f_1 , $K(f_0, f_1) \geq 0$, with equality iff $f_0 \equiv f_1$.

Remember Jensen's Inequality: When $g(x)$ is convex (happy), $\mathbb{E}[g(x)] \geq g(\mathbb{E}[x])$.

Proof (Discrete Case): Suppose $X \sim f_0$ and set $Z = \frac{f_1(x)}{f_0(x)}$. Let $S_j = \{x : f_j(x) > 0\}$

Since $g(z) = -\ln(z)$ is convex and $\mathbb{E}_{f_0}(z) = \sum_{x \in S_0} \frac{f_1(x)}{f_0(x)} f_0(x) = \sum_{x \in S_0} f_1(x) \leq 1$.

By Jensen's Inequality: $K(f_0, f_1) = -\mathbb{E}_{f_0}[\ln(Z)] = \mathbb{E}_{f_0}[g(z)] \underset{1}{\geq} g(\mathbb{E}_{f_0}(z)) \underset{2}{\geq} 0$.

This is only 'equal' when g is linear. Since $g(z)$ is not linear, equality in 1 only happens iff $Z = \frac{f_1(x)}{f_0} = c \neq 0, \forall x \in S_0, [S_0 \subset S_1]$. Equality in 2 only happens iff $\sum_{x \in S_0} f_1(x) = 1, [S_1 \subset S_0]$.

Suppose 1 and 2 are equalities. $1 = \sum_{x \in S_1} f_1(x) = \sum_{x \in S_1} c f_0(x) = c \sum_{x \in S_1} f_0(x) = c \sum_{x \in S_0} f_0(x) = c$