



For spring/damper fitting, we use the following:  $q = \begin{bmatrix} q_1 \\ q_2 \\ q_3 \end{bmatrix}$   $v = \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix}$   $v = \dot{q}$

We want to fit a linear model:

$$T = Kq + Cv$$

$$\begin{bmatrix} T_1 \\ T_2 \\ T_3 \end{bmatrix} = \begin{bmatrix} k_{11} & k_{12} & k_{13} \\ k_{21} & k_{22} & k_{23} \\ k_{31} & k_{32} & k_{33} \end{bmatrix} \begin{bmatrix} q_1 \\ q_2 \\ q_3 \end{bmatrix} + \begin{bmatrix} c_{11} & c_{12} & c_{13} \\ c_{21} & c_{22} & c_{23} \\ c_{31} & c_{32} & c_{33} \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix}$$

$$= \begin{bmatrix} q_1 & 0 & 0 & q_2 & 0 & 0 & q_3 & 0 & 0 & v_1 & 0 & 0 & 0 & 0 \\ 0 & q_1 & 0 & 0 & q_2 & 0 & 0 & q_3 & 0 & 0 & v_1 & \dots & v_3 & 0 \\ 0 & 0 & q_1 & 0 & 0 & q_2 & 0 & 0 & q_3 & 0 & 0 & 0 & 0 & v_3 \end{bmatrix} \begin{bmatrix} k_{11} \\ k_{21} \\ \vdots \\ k_{32} \\ c_{11} \\ \vdots \\ c_{23} \\ c_{33} \end{bmatrix}$$

$$= ([q_1 \ q_2 \ q_3 \ v_1 \ v_2 \ v_3] \otimes I) \begin{bmatrix} \text{vec}(K) \\ \text{vec}(C) \end{bmatrix}$$

Stack  $K$  time steps:

$$\begin{bmatrix} T_1^{(1)} \\ T_2^{(1)} \\ \vdots \\ T_2^{(K)} \\ T_3^{(K)} \end{bmatrix} = \begin{bmatrix} q_1^{(1)} & q_2^{(1)} & q_3^{(1)} & v_1^{(1)} & v_2^{(1)} & v_3^{(1)} \\ \vdots & \vdots & \vdots & \vdots & \vdots & \vdots \\ q_1^{(K)} & q_2^{(K)} & q_3^{(K)} & v_1^{(K)} & v_2^{(K)} & v_3^{(K)} \end{bmatrix} \otimes I \begin{bmatrix} \text{vec}(K) \\ \text{vec}(C) \end{bmatrix}$$

Define:  $F = \begin{bmatrix} | & & | \\ T^{(1)} & \dots & T^{(K)} \\ | & & | \end{bmatrix}$   $Q = \begin{bmatrix} | & & | \\ q^{(1)} & \dots & q^{(K)} \\ | & & | \end{bmatrix}$   $V = \begin{bmatrix} | & & | \\ v^{(1)} & \dots & v^{(K)} \\ | & & | \end{bmatrix}$

Rewrite stacked setup:

$$\text{vec}(F) = ([Q^T \ V^T] \otimes I) \begin{bmatrix} \text{vec}(K) \\ \text{vec}(C) \end{bmatrix}$$

$$y = Ax$$

Standard least squares: minimize  $\|y - Ax\|^2$

Regularized least squares: minimize  $\|y - Ax\|^2 + x^T W x$

PSD constraint: minimize  $\|y - Ax\|^2 + x^T W x$

subject to  $x = \begin{bmatrix} \text{vec}(K) \\ \text{vec}(C) \end{bmatrix}$

$$K \succeq 0 \text{ and } C \succeq 0$$