Concrete Semantics with Isabelle/HOL

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Part II

Semantics

Chapter 7

IMP:

A Simple Imperative Language

1 IMP Commands

2 Big-Step Semantics

3 Small-Step Semantics

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2 Big-Step Semantics

3 Small-Step Semantics

Statement: declaration of fact or claim

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Semantics is easy.

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Command: order to do something

Statement: declaration of fact or claim

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Command: order to do something

Study the book until you have understood it.

Statement: declaration of fact or claim

Semantics is easy.

Command: order to do something

Study the book until you have understood it.

Expressions are evaluated, commands are executed

Commands

Concrete syntax:

7

Commands

Abstract syntax:

```
\begin{array}{lll} \textbf{datatype} \ com & = & SKIP \\ & | & Assign \ string \ aexp \\ & | & Seq \ com \ com \\ & | & If \ bexp \ com \ com \\ & | & While \ bexp \ com \end{array}
```

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Com.thy

1 IMP Commands

2 Big-Step Semantics

3 Small-Step Semantics

Concrete syntax:

 $(com, initial\text{-}state) \Rightarrow final\text{-}state$

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Intended meaning of $(c, s) \Rightarrow t$:

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Command c started in state s terminates in state t

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Intended meaning of $(c, s) \Rightarrow t$:

Command c started in state s terminates in state t

"⇒" here not type!

$$(SKIP, s) \Rightarrow s$$

$$(SKIP, s) \Rightarrow s$$

$$(x := a, s) \Rightarrow s(x = aval \ a \ s)$$

$$(SKIP, s) \Rightarrow s$$

$$(x ::= a, s) \Rightarrow s(x := aval \ a \ s)$$

$$\frac{(c_1, s_1) \Rightarrow s_2 \quad (c_2, s_2) \Rightarrow s_3}{(c_1;; c_2, s_1) \Rightarrow s_3}$$

$$\frac{bval\ b\ s}{(IF\ b\ THEN\ c_1\ ELSE\ c_2,\ s) \Rightarrow t}$$

$$\frac{bval\ b\ s}{(IF\ b\ THEN\ c_1\ ELSE\ c_2,\ s) \Rightarrow t}$$

$$\frac{\neg\ bval\ b\ s}{(IF\ b\ THEN\ c_1\ ELSE\ c_2,\ s) \Rightarrow t}$$

$$\frac{\neg \ bval \ b \ s}{(WHILE \ b \ DO \ c, \ s) \Rightarrow s}$$

$$\frac{\neg bval \ b \ s}{(WHILE \ b \ DO \ c, \ s) \Rightarrow s}$$

$$\frac{bval \ b \ s_1}{(C, \ s_1) \Rightarrow s_2 \qquad (WHILE \ b \ DO \ c, \ s_2) \Rightarrow s_3}{(WHILE \ b \ DO \ c, \ s_1) \Rightarrow s_3}$$

Examples: derivation trees

```
\frac{\vdots}{("x" ::= N 5;; "y" ::= V "x", s) \Rightarrow ?}
```

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```
\frac{\vdots}{("x" ::= N 5;; "y" ::= V "x", s) \Rightarrow ?} \qquad \frac{\vdots}{(w, s_i) \Rightarrow ?}
where w = WHILE \ b \ DO \ c
         b = NotEq (V''x'') (N 2)
         c = "x" ::= Plus (V "x") (N 1)
         s_i = s("x" := i)
NotEq \ a_1 \ a_2 =
Not(And\ (Not(Less\ a_1\ a_2))\ (Not(Less\ a_2\ a_1)))
```

Logically speaking

$$(c, s) \Rightarrow t$$

is just infix syntax for

$$big_step~(c,s)~t$$

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$$(c, s) \Rightarrow t$$

is just infix syntax for

$$big_step\ (c,s)\ t$$

where

$$big_step :: com \times state \Rightarrow state \Rightarrow bool$$

is an inductively defined predicate.

Big_Step.thy

Semantics

What can we deduce from

• $(SKIP, s) \Rightarrow t$?

What can we deduce from

• $(SKIP, s) \Rightarrow t$? t = s

What can we deduce from

- $(SKIP, s) \Rightarrow t$? t = s
- $(x := a, s) \Rightarrow t$?

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- $(SKIP, s) \Rightarrow t$? t = s
- $(x := a, s) \Rightarrow t$? $t = s(x := aval \ a \ s)$
- $(c_1;; c_2, s_1) \Rightarrow s_3$?

- $(SKIP, s) \Rightarrow t$? t = s
- $(x := a, s) \Rightarrow t$? $t = s(x := aval \ a \ s)$
- $(c_1;; c_2, s_1) \Rightarrow s_3$? $\exists s_2. (c_1, s_1) \Rightarrow s_2 \land (c_2, s_2) \Rightarrow s_3$

- $(SKIP, s) \Rightarrow t$? t = s
- $(x := a, s) \Rightarrow t$? $t = s(x := aval \ a \ s)$
- $(c_1;; c_2, s_1) \Rightarrow s_3$? $\exists s_2. (c_1, s_1) \Rightarrow s_2 \land (c_2, s_2) \Rightarrow s_3$
- (IF b THEN c_1 ELSE c_2 , s) $\Rightarrow t$?

- $(SKIP, s) \Rightarrow t$? t = s
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- $(c_1;; c_2, s_1) \Rightarrow s_3$? $\exists s_2. (c_1, s_1) \Rightarrow s_2 \land (c_2, s_2) \Rightarrow s_3$
- (IF b THEN c_1 ELSE c_2 , s) $\Rightarrow t$? bval b $s \land (c_1, s) \Rightarrow t \lor$ $\neg bval b s \land (c_2, s) \Rightarrow t$

- $(SKIP, s) \Rightarrow t$? t = s
- $(x := a, s) \Rightarrow t$? $t = s(x := aval \ a \ s)$
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- $(w, s) \Rightarrow t$ where $w = WHILE \ b \ DO \ c$? $\neg bval \ b \ s \land t = s \lor$ $bval \ b \ s \land (\exists \ s'. \ (c, s) \Rightarrow s' \land (w, s') \Rightarrow t)$

Automating rule inversion

Isabelle command **inductive_cases** produces theorems that perform rule inversions automatically.

$$\frac{(c_1;; c_2, s_1) \Rightarrow s_3}{\exists s_2. (c_1, s_1) \Rightarrow s_2 \land (c_2, s_2) \Rightarrow s_3}$$

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is logically equivalent to

$$\underbrace{\bigwedge s_2. \ \llbracket (c_1, s_1) \Rightarrow s_2; \ (c_2, s_2) \Rightarrow s_3 \rrbracket \Longrightarrow P}_{P}$$

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is logically equivalent to

$$\underbrace{\bigwedge s_2. \ \llbracket (c_1, s_1) \Rightarrow s_2; \ (c_2, s_2) \Rightarrow s_3 \rrbracket \Longrightarrow P}_{P}$$

Replaces assm $(c_1;; c_2, s_1) \Rightarrow s_3$ by two assms $(c_1, s_1) \Rightarrow s_2$ and $(c_2, s_2) \Rightarrow s_3$

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Replaces assm
$$(c_1;; c_2, s_1) \Rightarrow s_3$$
 by two assms $(c_1, s_1) \Rightarrow s_2$ and $(c_2, s_2) \Rightarrow s_3$ (with a new fixed s_2).

$$\frac{(c_1;; c_2, s_1) \Rightarrow s_3}{\exists s_2. (c_1, s_1) \Rightarrow s_2 \land (c_2, s_2) \Rightarrow s_3}$$

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Replaces assm $(c_1;; c_2, s_1) \Rightarrow s_3$ by two assms $(c_1, s_1) \Rightarrow s_2$ and $(c_2, s_2) \Rightarrow s_3$ (with a new fixed s_2). No \exists and \land !

$$\underbrace{asm \quad asm_1 \Longrightarrow P \quad \dots \quad asm_n \Longrightarrow P}_{P}$$

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(possibly with $\Lambda \overline{x}$ in front of the $asm_i \Longrightarrow P$)

$$\frac{asm \quad asm_1 \Longrightarrow P \quad \dots \quad asm_n \Longrightarrow P}{P}$$

(possibly with $\Lambda \overline{x}$ in front of the $asm_i \Longrightarrow P$)

Reading:

To prove a goal P with assumption asm, prove all $asm_i \Longrightarrow P$

$$\underbrace{asm \quad asm_1 \Longrightarrow P \quad \dots \quad asm_n \Longrightarrow P}_{P}$$

(possibly with $\Lambda \overline{x}$ in front of the $asm_i \Longrightarrow P$)

Reading:

To prove a goal P with assumption asm, prove all $asm_i \Longrightarrow P$

Example:

$$F \lor G \quad F \Longrightarrow P \quad G \Longrightarrow P$$

elim attribute

 Theorems with elim attribute are used automatically by blast, fastforce and auto

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- Can also be added locally, eg (blast elim: . . .)

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- Theorems with elim attribute are used automatically by blast, fastforce and auto
- Can also be added locally, eg (blast elim: . . .)
- Variant: *elim!* applies elim-rules eagerly.

Big_Step.thy

Rule inversion

Command equivalence

Two commands have the same input/output behaviour:

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Example

$$w \sim w'$$

where
$$w = WHILE \ b \ DO \ c$$

 $w' = IF \ b \ THEN \ c;; \ w \ ELSE \ SKIP$

$$(w, s) \Rightarrow t$$

$$(w, s) \Rightarrow t$$

$$\longleftrightarrow$$

$$bval \ b \ s \land (\exists s'. \ (c, s) \Rightarrow s' \land (w, s') \Rightarrow t)$$

$$\lor \qquad \qquad \lor$$

$$\lnot \ bval \ b \ s \land t = s$$

$$(w, s) \Rightarrow t$$

$$\longleftrightarrow$$

$$bval \ b \ s \land (\exists s'. \ (c, s) \Rightarrow s' \land (w, s') \Rightarrow t)$$

$$\lor \qquad \qquad \lor$$

$$\neg \ bval \ b \ s \land t = s$$

$$\longleftrightarrow$$

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$$\lor \qquad \qquad \lor$$

$$\neg \ bval \ b \ s \land t = s$$

$$\longleftrightarrow$$

$$(w', s) \Rightarrow t$$

Using the rules and rule inversions for \Rightarrow .

Big_Step.thy

Command equivalence

Execution is deterministic

Any two executions of the same command in the same start state lead to the same final state:

$$(c, s) \Rightarrow t \implies (c, s) \Rightarrow t' \implies t = t'$$

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Proof by rule induction, for arbitrary t'.

Big_Step.thy

Execution is deterministic

We cannot observe intermediate states/steps

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Example problem:

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(c,s) does not terminate iff $\nexists t$. $(c, s) \Rightarrow t$?

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Needs a formal notion of nontermination to prove it.

We cannot observe intermediate states/steps

Example problem:

(c,s) does not terminate iff $\nexists t$. $(c, s) \Rightarrow t$?

Needs a formal notion of nontermination to prove it. Could be wrong if we have forgotten $a \Rightarrow rule$.

Big-step semantics cannot directly describe

• nonterminating computations,

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- nonterminating computations,
- parallel computations.

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- nonterminating computations,
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We need a finer grained semantics!

1 IMP Commands

② Big-Step Semantics

3 Small-Step Semantics

Concrete syntax:

```
(com, state) \rightarrow (com, state)
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Intended meaning of $(c, s) \rightarrow (c', s')$:

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$$(com, state) \rightarrow (com, state)$$

Intended meaning of $(c, s) \rightarrow (c', s')$:

The first step in the execution of c in state s leaves a "remainder" command c' to be executed in state s'.

Concrete syntax:

$$(com, state) \rightarrow (com, state)$$

Intended meaning of $(c, s) \rightarrow (c', s')$:

The first step in the execution of c in state s leaves a "remainder" command c' to be executed in state s'.

Execution as finite or infinite reduction:

$$(c_1,s_1) \to (c_2,s_2) \to (c_3,s_3) \to \dots$$

Terminology

• A pair (c,s) is called a *configuration*.

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- If $cs \rightarrow cs'$ we say that cs reduces to cs'.

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- A pair (c,s) is called a *configuration*.
- If $cs \rightarrow cs'$ we say that cs reduces to cs'.
- A configuration cs is *final* iff $\nexists cs'$. $cs \rightarrow cs'$

The intention:

(SKIP, s) is final

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(SKIP, s) is final

Why?

SKIP is the empty program.

The intention:

(SKIP, s) is final

Why?

SKIP is the empty program. Nothing more to be done.

$$(x:=a, s) \rightarrow$$

$$(x:=a, s) \rightarrow (SKIP, s(x:=aval \ a \ s))$$

$$(x:=a, s) \rightarrow (SKIP, s(x:=aval\ a\ s))$$

 $(SKIP;; c, s) \rightarrow$

$$(x:=a, s) \rightarrow (SKIP, s(x:=aval \ a \ s))$$

 $(SKIP;; c, s) \rightarrow (c, s)$

$$(x:=a, s) \rightarrow (SKIP, s(x := aval \ a \ s))$$

$$(SKIP;; c, s) \rightarrow (c, s)$$

$$\frac{(c_1, s) \rightarrow (c'_1, s')}{(c_1;; c_2, s) \rightarrow}$$

$$(x:=a, s) \to (SKIP, s(x := aval \ a \ s))$$

$$(SKIP;; c, s) \to (c, s)$$

$$\frac{(c_1, s) \to (c'_1, s')}{(c_1;; c_2, s) \to (c'_1;; c_2, s')}$$

$$\frac{\textit{bval b s}}{(\textit{IF b THEN } c_1 \textit{ ELSE } c_2, s) \ \rightarrow}$$

$$\frac{bval\ b\ s}{(IF\ b\ THEN\ c_1\ ELSE\ c_2,s)\ \rightarrow\ (c_1,s)}$$

$$\frac{bval\ b\ s}{(IF\ b\ THEN\ c_1\ ELSE\ c_2, s)\ \rightarrow\ (c_1, s)} \\
\neg\ bval\ b\ s} \\
\overline{(IF\ b\ THEN\ c_1\ ELSE\ c_2, s)\ \rightarrow\ (c_2, s)}$$

$$\frac{bval\ b\ s}{(IF\ b\ THEN\ c_1\ ELSE\ c_2,s)\ \rightarrow\ (c_1,s)} \\ \frac{\neg\ bval\ b\ s}{(IF\ b\ THEN\ c_1\ ELSE\ c_2,s)\ \rightarrow\ (c_2,s)} \\ (WHILE\ b\ DO\ c,\ s)\ \rightarrow$$

$$\frac{bval\ b\ s}{(IF\ b\ THEN\ c_1\ ELSE\ c_2,s)\ \to\ (c_1,s)} \\
\neg\ bval\ b\ s} \\
\overline{(IF\ b\ THEN\ c_1\ ELSE\ c_2,s)\ \to\ (c_2,s)}$$

$$(WHILE\ b\ DO\ c,\ s) \rightarrow (IF\ b\ THEN\ c;;\ WHILE\ b\ DO\ c\ ELSE\ SKIP,\ s)$$

$$\frac{bval\ b\ s}{(IF\ b\ THEN\ c_1\ ELSE\ c_2,s)\ \rightarrow\ (c_1,s)} \\ \neg\ bval\ b\ s} \\ \overline{(IF\ b\ THEN\ c_1\ ELSE\ c_2,s)\ \rightarrow\ (c_2,s)}$$

$$(\textit{WHILE b DO } c, \textit{s}) \rightarrow \\ (\textit{IF b THEN } c;; \textit{WHILE b DO } c \textit{ ELSE SKIP}, \textit{s})$$

Fact (SKIP, s) is a final configuration.

Small-step examples

```
("z" ::= V "x";; "x" ::= V "y";; "y" ::= V "z", s) \rightarrow \cdots
```

where $s = \langle "x" := 3, "y" := 7, "z" := 5 \rangle$.

Small-step examples

$$("z" ::= V "x";; "x" ::= V "y";; "y" ::= V "z", s) \rightarrow \dots$$

where $s = \langle "x" := 3, "y" := 7, "z" := 5 \rangle$.

$$(w, s_0) \rightarrow \dots$$

where
$$w = WHILE \ b \ DO \ c$$

 $b = Less \ (V "x") \ (N \ 1)$
 $c = "x" ::= Plus \ (V "x") \ (N \ 1)$
 $s_n = <"x" := n>$

Small_Step.thy

Semantics

Are big and small-step semantics equivalent?

Theorem $cs \Rightarrow t \implies cs \rightarrow * (SKIP, t)$

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Proof by rule induction

Theorem $cs \Rightarrow t \implies cs \rightarrow * (SKIP, t)$

Proof by rule induction (of course on $cs \Rightarrow t$)

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Proof by rule induction (of course on $cs \Rightarrow t$) In two cases a lemma is needed:

Theorem
$$cs \Rightarrow t \implies cs \rightarrow * (SKIP, t)$$

Proof by rule induction (of course on $cs \Rightarrow t$) In two cases a lemma is needed:

Lemma

$$(c_1, s) \rightarrow * (c_1', s') \Longrightarrow (c_1;; c_2, s) \rightarrow * (c_1';; c_2, s')$$

Theorem
$$cs \Rightarrow t \implies cs \rightarrow * (SKIP, t)$$

Proof by rule induction (of course on $cs \Rightarrow t$) In two cases a lemma is needed:

Lemma

$$(c_1, s) \rightarrow * (c_1', s') \Longrightarrow (c_1;; c_2, s) \rightarrow * (c_1';; c_2, s')$$

Proof by rule induction.

Theorem $cs \rightarrow * (SKIP, t) \implies cs \Rightarrow t$

Theorem $cs \to * (SKIP, t) \implies cs \Rightarrow t$ Proof by rule induction on $cs \to * (SKIP, t)$.

Theorem $cs \to *(SKIP, t) \Longrightarrow cs \Rightarrow t$ Proof by rule induction on $cs \to *(SKIP, t)$. In the induction step a lemma is needed:

Theorem $cs \rightarrow * (SKIP, t) \implies cs \Rightarrow t$

Proof by rule induction on $cs \rightarrow * (SKIP, t)$. In the induction step a lemma is needed:

Lemma $cs \rightarrow cs' \implies cs' \Rightarrow t \implies cs \Rightarrow t$

Theorem $cs \rightarrow * (SKIP, t) \implies cs \Rightarrow t$

Proof by rule induction on $cs \rightarrow * (SKIP, t)$. In the induction step a lemma is needed:

Lemma $cs \rightarrow cs' \implies cs' \Rightarrow t \implies cs \Rightarrow t$

Proof by rule induction on $cs \rightarrow cs'$.

Equivalence

Corollary
$$cs \Rightarrow t \longleftrightarrow cs \rightarrow *(SKIP, t)$$

Small_Step.thy

Equivalence of big and small

That is, are there any final configs except (SKIP,s)?

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Lemma final
$$(c, s) \Longrightarrow c = SKIP$$

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Lemma final
$$(c, s) \Longrightarrow c = SKIP$$

We prove the contrapositive

$$c \neq SKIP \Longrightarrow \neg final(c,s)$$

That is, are there any final configs except (SKIP,s) ?

Lemma
$$final(c, s) \Longrightarrow c = SKIP$$

We prove the contrapositive

$$c \neq SKIP \Longrightarrow \neg final(c,s)$$

by induction on c.

• Case c_1 ;; c_2 : by case distinction:

That is, are there any final configs except (SKIP,s) ?

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We prove the contrapositive

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- Case c_1 ;; c_2 : by case distinction:
 - $c_1 = SKIP$

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Lemma final
$$(c, s) \Longrightarrow c = SKIP$$

We prove the contrapositive

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- Case c_1 ;; c_2 : by case distinction:
 - $c_1 = SKIP \Longrightarrow \neg final(c_1;; c_2, s)$

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- Case c_1 ;; c_2 : by case distinction:
 - $c_1 = SKIP \Longrightarrow \neg final(c_1;; c_2, s)$
 - $c_1 \neq SKIP$

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We prove the contrapositive

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- Case c_1 ;; c_2 : by case distinction:
 - $c_1 = SKIP \Longrightarrow \neg final(c_1;; c_2, s)$
 - $c_1 \neq SKIP \Longrightarrow \neg final(c_1, s)$ (by IH)

That is, are there any final configs except (SKIP,s) ?

Lemma
$$final(c, s) \Longrightarrow c = SKIP$$

We prove the contrapositive

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That is, are there any final configs except (SKIP,s) ?

Lemma final
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We prove the contrapositive

$$c \neq SKIP \Longrightarrow \neg final(c,s)$$

- Case c_1 ;; c_2 : by case distinction:
 - $c_1 = SKIP \Longrightarrow \neg final(c_1;; c_2, s)$
 - $c_1 \neq SKIP \Longrightarrow \neg final (c_1, s)$ (by IH) $\Longrightarrow \neg final (c_1;; c_2, s)$
- Remaining cases: trivial or easy

By rule inversion: $(SKIP, s) \rightarrow ct \Longrightarrow False$

By rule inversion: $(SKIP, s) \rightarrow ct \Longrightarrow False$

Together:

Corollary final(c, s) = (c = SKIP)

Lemma
$$(\exists t. cs \Rightarrow t) = (\exists cs'. cs \rightarrow * cs' \land final cs')$$

Lemma
$$(\exists t. cs \Rightarrow t) = (\exists cs'. cs \rightarrow * cs' \land final cs')$$

Proof: $(\exists t. cs \Rightarrow t)$

Lemma
$$(\exists t. cs \Rightarrow t) = (\exists cs'. cs \rightarrow * cs' \land final cs')$$

Proof: $(\exists t. cs \Rightarrow t)$
 $= (\exists t. cs \rightarrow * (SKIP, t))$

```
Lemma (\exists t. cs \Rightarrow t) = (\exists cs'. cs \rightarrow * cs' \land final cs')

Proof: (\exists t. cs \Rightarrow t)

= (\exists t. cs \rightarrow * (SKIP, t))

(by big = small)
```

```
Lemma (\exists t. cs \Rightarrow t) = (\exists cs'. cs \rightarrow * cs' \land final cs')

Proof: (\exists t. cs \Rightarrow t)

= (\exists t. cs \rightarrow * (SKIP, t))

(\text{by big} = \text{small})

= (\exists cs'. cs \rightarrow * cs' \land final cs')
```

```
Lemma (\exists t. cs \Rightarrow t) = (\exists cs'. cs \rightarrow * cs' \land final cs')

Proof: (\exists t. cs \Rightarrow t)

= (\exists t. cs \rightarrow * (SKIP, t))

(\text{by big} = \text{small})

= (\exists cs'. cs \rightarrow * cs' \land final cs')

(\text{by final} = SKIP)
```

 \Rightarrow yields final state $\mbox{ iff } \rightarrow \mbox{ terminates}$

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Lemma (\exists t. cs \Rightarrow t) = (\exists cs'. cs \rightarrow * cs' \land final cs')

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(\text{by final} = SKIP)
```

Equivalent:

 \Rightarrow does not yield final state iff \rightarrow does not terminate

Lemma
$$cs \rightarrow cs' \implies cs \rightarrow cs'' \implies cs'' = cs'$$

Lemma
$$cs \to cs' \implies cs \to cs'' \implies cs'' = cs'$$
 (Proof by rule induction)

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```
Therefore: no difference between may terminate (there is a terminating \rightarrow path) must terminate (all \rightarrow paths terminate)
```

 \rightarrow is deterministic:

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Lemma cs \to cs' \implies cs \to cs'' \implies cs'' = cs' (Proof by rule induction)
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Therefore: no difference between $\begin{array}{c} \text{may terminate (there is a terminating} \rightarrow \text{path)} \\ \text{must terminate (all} \rightarrow \text{paths terminate)} \end{array}$

Therefore: \Rightarrow correctly reflects termination behaviour.

 \rightarrow is deterministic:

Lemma
$$cs \to cs' \implies cs \to cs'' \implies cs'' = cs'$$
 (Proof by rule induction)

Therefore: no difference between

may terminate (there is a terminating \rightarrow path)

must terminate (all \rightarrow paths terminate)

Therefore: \Rightarrow correctly reflects termination behaviour.

With nondeterminism: may have both $cs \Rightarrow t$ and a nonterminating reduction $cs \rightarrow cs' \rightarrow \dots$

Chapter 8

Hoare Logic

4 Weakest Preconditions

5 Towards Simpler Verification of Programs

6 Example Verifications

7 Advanced Verification

4 Weakest Preconditions

5 Towards Simpler Verification of Programs

6 Example Verifications

Advanced Verification

4 Weakest Preconditions Introduction

We have proved functional programs correct

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We have modeled semantics of imperative languages

We have proved functional programs correct

We have modeled semantics of imperative languages

But how do we prove imperative programs correct?

```
program exp {
a := 1
while (0 < n) do {
a := a + a;
n := n - 1
}
```

```
program exp \ \{ a := 1 \\ while \ (0 < n) \ do \ \{ \\ a := a + a; \\ n := n - 1 \\ \}
```

At the end of the execution, variable a should contain 2^n ,

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At the end of the execution, variable a should contain 2^n , where n is the original value of variable n!

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program exp \ \{ a := 1 \\ while \ (0 < n) \ do \ \{ \\ a := a + a; \\ n := n - 1 \\ \}
```

At the end of the execution, variable a should contain 2^n , where n is the original value of variable n! and $0 \le n!$

Formally

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$$P s \Longrightarrow \exists t. (c, s) \Rightarrow t \land Q t$$

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The RHS of this implication is called *weakest precondition*

$$wp \ c \ Q \ s \equiv \exists \ t. \ (c, \ s) \Rightarrow t \land Q \ t$$

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The RHS of this implication is called *weakest precondition*

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Weakest condition on state, such that program c will satisfy postcondition Q.

Some obvious facts:

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Consequence rule:

 $\llbracket wp \ c \ P \ s; \bigwedge s. \ P \ s \Longrightarrow Q \ s \rrbracket \Longrightarrow wp \ c \ Q \ s$

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Consequence rule:

$$\llbracket wp\ c\ P\ s;\ \bigwedge s.\ P\ s \Longrightarrow \ Q\ s \rrbracket \implies wp\ c\ Q\ s$$

wp of equivalent programs is equal

$$c \sim c' \Longrightarrow wp \ c = wp \ c'$$

Correctness of $\ensuremath{\mathit{exp}}$

$$0 \le s "n" \Longrightarrow wp \ exp \ (\lambda s'. \ s' "a" = 2^{\operatorname{nat} \ (s "n")}) \ s$$

$$0 \le s "n" \Longrightarrow wp \ exp \ (\lambda s'. \ s' "a" = 2^{nat \ (s "n")}) \ s$$

 $nat::int \Rightarrow nat \text{ required b/c } (\hat{\ })::'a \Rightarrow nat \Rightarrow 'a \text{ only defined on } nat.$

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 $nat::int \Rightarrow nat \text{ required b/c (^)}::'a \Rightarrow nat \Rightarrow 'a \text{ only defined on } nat.$

In general: $P s \Longrightarrow wp \ c \ Q \ s$

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wp SKIP Q s =

 $P s \Longrightarrow wp \ c \ Q \ s$

 $wp \ \mathit{SKIP} \ \mathit{Q} \ \mathit{s} = \ \mathit{Q} \ \mathit{s}$

$$P s \Longrightarrow wp \ c \ Q \ s$$

$$wp SKIP Q s = Q s$$

$$wp (x ::= a) Q s =$$

$$P s \Longrightarrow wp \ c \ Q \ s$$

$$wp SKIP Q s = Q s$$

$$wp (x := a) Q s = Q (s(x := aval a s))$$

$$P s \Longrightarrow wp \ c \ Q \ s$$

$$wp \ SKIP \ Q \ s = Q \ s$$

 $wp \ (x := a) \ Q \ s = Q \ (s(x := aval \ a \ s))$
 $wp \ (c_1;; c_2) \ Q \ s =$

$$P s \Longrightarrow wp \ c \ Q \ s$$

$$wp \ SKIP \ Q \ s = Q \ s$$

 $wp \ (x := a) \ Q \ s = Q \ (s(x := aval \ a \ s))$
 $wp \ (c_1;; c_2) \ Q \ s = wp \ c_1 \ (wp \ c_2 \ Q) \ s$

 $P s \Longrightarrow wp \ c \ Q \ s$

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Reasoning along syntax of program!

That was easy!

 $wp (WHILE \ b \ DO \ c) \ Q \ s$

```
wp \ (WHILE \ b \ DO \ c) \ Q \ s = if bval \ b \ s then wp \ c \ (wp \ (WHILE \ b \ DO \ c) \ Q) \ s else Q \ s
```

```
wp\ (WHILE\ b\ DO\ c)\ Q\ s =if bval\ b\ s then wp\ c\ (wp\ (WHILE\ b\ DO\ c)\ Q)\ s else Q\ s
```

Unfolding will continue forever!

```
wp\ (WHILE\ b\ DO\ c)\ Q\ s =if bval\ b\ s then wp\ c\ (wp\ (WHILE\ b\ DO\ c)\ Q)\ s else Q\ s
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Unfolding will continue forever!

Obviously, need some inductive argument!

```
wp \ (WHILE \ b \ DO \ c) \ Q \ s =if bval \ b \ s then wp \ c \ (wp \ (WHILE \ b \ DO \ c) \ Q) \ s else Q \ s
```

Unfolding will continue forever!

Obviously, need some inductive argument!

But, let's get less ambitious (for first)

Weakest liberal precondition

 $wlp \ c \ Q \ s \equiv \forall \ t. \ (c, \ s) \Rightarrow t \longrightarrow Q \ t$

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Weakest liberal precondition

$$wlp \ c \ Q \ s \equiv \forall \ t. \ (c, \ s) \Rightarrow t \longrightarrow Q \ t$$

If c terminates on s, then new state satisfies Q

Cannot reason about termination. This is called *partial correctness*.

Some obvious facts:

$$c \sim c' \Longrightarrow wlp \ c = wlp \ c'$$
 $\llbracket wlp \ c \ P \ s; \ \bigwedge s. \ P \ s \Longrightarrow Q \ s \rrbracket \Longrightarrow wlp \ c \ Q \ s$

Some obvious facts:

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Relation between wp and wlp

$$wp \ c \ Q \ s \Longrightarrow wlp \ c \ Q \ s$$

$$wlp \ c \ Q \ s \land (c, s) \Rightarrow t \Longrightarrow wp \ c \ Q \ s$$

Some obvious facts:

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Relation between wp and wlp

$$wp \ c \ Q \ s \Longrightarrow wlp \ c \ Q \ s$$

$$wlp \ c \ Q \ s \land (c, s) \Rightarrow t \Longrightarrow wp \ c \ Q \ s$$

Unfold rules still hold:

 $wlp \ (\textit{WHILE b DO c}) \ \textit{Q s} = \\ (\textit{if bval b s then } wlp \ c \ (wlp \ (\textit{WHILE b DO c}) \ \textit{Q}) \ s \ \textit{else} \\ \textit{Q s})$

 $wlp\ (WHILE\ b\ DO\ c)\ Q\ s =$ (if $bval\ b\ s$ then $wlp\ c\ (wlp\ (WHILE\ b\ DO\ c)\ Q)\ s$ else $Q\ s$)

Let's try to find predicate *I*, such that

 $\bigwedge s. \ I \ s \Longrightarrow \text{ if } bval \ b \ s \ \text{then } wp \ c \ I \ s \ \text{else } Q \ s$

 $wlp \ (\textit{WHILE b DO c}) \ \textit{Q s} = \\ (\textit{if bval b s then } wlp \ c \ (wlp \ (\textit{WHILE b DO c}) \ \textit{Q}) \ \textit{s else} \\ \textit{Q s})$

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and I holds for start state.

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Intuition: I holds initially, is preserved by iteration, and implies Q at end of loop.

 $wlp\ (WHILE\ b\ DO\ c)\ Q\ s =$ (if $bval\ b\ s$ then $wlp\ c\ (wlp\ (WHILE\ b\ DO\ c)\ Q)\ s$ else $Q\ s$)

Let's try to find predicate *I*, such that

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and *I* holds for start state.

Intuition: I holds initially, is preserved by iteration, and implies Q at end of loop. I is called *loop invariant*

While-rule for partial correctness

 $\llbracket I \ s_0; \bigwedge s. \ I \ s \Longrightarrow \text{if } bval \ b \ s \text{ then } wlp \ c \ I \ s \text{ else } Q \ s
rbracket{}$ $\Longrightarrow wlp \ (WHILE \ b \ DO \ c) \ Q \ s_0$

Wp_Demo.thy

Weakest Precondition

 $P s \Longrightarrow wlp \ c \ Q \ s$

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If $c = \mathit{WHILE} \ _ \mathit{DO} \ _$, provide invariant and apply while rule

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Otherwise, use unfold rules.

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If $c = \mathit{WHILE} \ _ \mathit{DO} \ _$, provide invariant and apply while rule

Otherwise, use unfold rules.

Iterate, until all wlps gone!

 wlp_if_eq and wlp_whileI' produce if_then_else

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Combine rule with splitting!

Wp_Demo.thy

Proving Partial Correctness

An (ordering) relation < is *well-founded*, iff every non-empty set has a minimal element.

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Well-foundedness implies induction principle

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Equivalently: No infinite sequence with $x_1 > x_2 > \dots$

Well-foundedness implies induction principle

$$\frac{wf \ r \qquad \bigwedge x. \ \frac{\forall \ y. \ (y, \ x) \in r \longrightarrow P \ y}{P \ x}}{P \ a}$$

Wellfounded_Demo.thy

For while loop: Find wf relation < such that state decreases in each iteration

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 $\bigwedge s. \ I \ s \Longrightarrow \text{if } bval \ b \ s \text{ then } wp \ c \ (\lambda s'. \ I \ s' \land s' < s) \ s \text{ else } Q \ s$

For while loop: Find $\it wf$ relation $\it <$ such that state decreases in each iteration

 $\bigwedge s. \ I \ s \Longrightarrow \text{if } bval \ b \ s \ \text{then } wp \ c \ (\lambda s'. \ I \ s' \land s' < s) \ s$ else $Q \ s$

Then use wf-induction to prove:

```
\llbracket wf \ R; \ I \ s_0;

\bigwedge s. \ I \ s \Longrightarrow \text{ if } bval \ b \ s \ \text{then } wp \ c \ (\lambda s'. \ I \ s' \land (s', \ s) \in R) \ s \ \text{else} \ Q \ s \rrbracket

\Longrightarrow wp \ (WHILE \ b \ DO \ c) \ Q \ s_0
```

Or, equivalently

```
assumes WF: wf R assumes INIT: I s_0 assumes STEP: \bigwedge s. \ \llbracket \ I \ s; \ bval \ b \ s \ \rrbracket \implies wp \ c \ (\lambda s'. \ I \ s' \land (s',s) \in R) \ s assumes FINAL: \bigwedge s. \ \llbracket \ I \ s; \ \neg bval \ b \ s \ \rrbracket \implies Q \ s shows wp \ (WHILE \ b \ DO \ c) \ Q \ s_0
```

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```

Now we can prove total correctness ...

Wp_Demo.thy

Total Correctness

lemma $ASSUME \Theta$ alt:

ASSUME_ Θ π f_0 s_0 R Θ = $(\forall (f,(P,c,Q)) \in \Theta$. HT' π $(\lambda s. (f s, f_0 s_0) \in R \land P s) c Q)$

unfolding $ASSUME_\Theta_def\ HT'set_r_def$..

4 Weakest Preconditions

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- **6** Example Verifications
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Add standard arithmetic operators to IMP

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Add nice syntax for programs
Make VCs more readable
Simplify specification of pre/postcondition, and invariants

$$Unop::(int \Rightarrow int) \Rightarrow aexp \Rightarrow aexp$$

```
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Binop::(int \Rightarrow int \Rightarrow int) \Rightarrow aexp \Rightarrow aexp \Rightarrow aexp
```

```
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Binop::(int \Rightarrow int \Rightarrow int) \Rightarrow aexp \Rightarrow aexp \Rightarrow aexp

Cmpop::(int \Rightarrow int \Rightarrow bool) \Rightarrow aexp \Rightarrow aexp \Rightarrow bexp
```

```
Unop::(int \Rightarrow int) \Rightarrow aexp \Rightarrow aexp

Binop::(int \Rightarrow int \Rightarrow int) \Rightarrow aexp \Rightarrow aexp \Rightarrow aexp

Cmpop::(int \Rightarrow int \Rightarrow bool) \Rightarrow aexp \Rightarrow aexp \Rightarrow bexp

BBinop::(bool \Rightarrow bool \Rightarrow bool) \Rightarrow bexp \Rightarrow bexp
```

We add generic syntax for any unary/binary operator

```
\begin{array}{l} \textit{Unop::}(\textit{int} \Rightarrow \textit{int}) \Rightarrow \textit{aexp} \Rightarrow \textit{aexp} \\ \textit{Binop::}(\textit{int} \Rightarrow \textit{int} \Rightarrow \textit{int}) \Rightarrow \textit{aexp} \Rightarrow \textit{aexp} \Rightarrow \textit{aexp} \\ \textit{Cmpop::}(\textit{int} \Rightarrow \textit{int} \Rightarrow \textit{bool}) \Rightarrow \textit{aexp} \Rightarrow \textit{aexp} \Rightarrow \textit{bexp} \\ \textit{BBinop::}(\textit{bool} \Rightarrow \textit{bool} \Rightarrow \textit{bool}) \Rightarrow \textit{bexp} \Rightarrow \textit{bexp} \Rightarrow \textit{bexp} \end{array}
```

For example:

$$Cmpop (\leq) (Binop (+) (Unop uminus (V "x")) (N 42)) (N 50)$$

IMP2/Introduction.thy

Adding more Operators

Operators

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Arith: +,-,*,/ with usual binding

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Boolean: \neg, \land, \lor and $=, \neq, \leq, <, >, \geq$

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skip, v = aexp, \{c\}, c_1; c_2 if bexp then c_1 [else c_2]
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```
skip, v = aexp, \{c\}, c_1; c_2 if bexp then <math>c_1 [else \ c_2] else part is optional
```

Operators

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```
skip, v = aexp, \{c\}, c_1; c_2

if\ bexp\ then\ c_1\ [else\ c_2] else part is optional

while\ (bexp)\ c
```

IMP2/Introduction.thy

Program Syntax

More Readable VCs

Idea: Replace s "x" by (Isabelle) variable x.

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Similar: s_0 "x" by x_0 .

More Readable VCs

Idea: Replace s''x'' by (Isabelle) variable x.

Similar: s_0 "x" by x_0 .

If subgoal can still be proved for arbitrary (Isabelle) variable x, it can, in particular, be proved for s "x".

$$(\bigwedge x. \ P \ x) \Longrightarrow P \ (s \ ''x'')$$

IMP2/Introduction.thy

More Readable VCs

Can we do similar trick for pre/postconditions and invariants?

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E.g. write
$$c \le n_0 \land a = c * c$$
 for $s "c" \le s_0 "n" \land s "a" = s "c" * s "c"$

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Which variables to interpret?

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All variables that occur in the program!

More Readable Annotations

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$$c \le n_0 \land a = c * c$$
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Which variables to interpret? over which states?

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Precondition: x interpreted as s "x"

More Readable Annotations

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 for $s "c" \le s_0 "n" \land s "a" = s "c" * s "c"$

Which variables to interpret? over which states?

All variables that occur in the program!

Precondition: x interpreted as s "x"

Postcondition/Invariant: x as s "x", x_0 as s_0 "x"

IMP2/Introduction.thy

More Readable Annotations

4 Weakest Preconditions

- **5** Towards Simpler Verification of Programs
- **6** Example Verifications

Advanced Verification

6 Example Verifications Loop Patterns Euclid's Algorithm

```
a=1; c=0; while (c< n) \{a=2*a; c=c+1\} Compute operation by iterating weaker operation
```

```
a=1; c=0; while (c< n) \{a=2*a; c=c+1\}
Compute operation by iterating weaker operation e.g. 2^n = 2*...*2
```

We've seen a few loop's already:

```
a=1; c=0; while (c< n) \{a=2*a; c=c+1\}
Compute operation by iterating weaker operation e.g. 2^n=2*\ldots*2
```

Use accumulator a and increment counter (count-up)

```
a=1;\ c=0;\ while\ (c< n)\ \{a=2*a;\ c=c+1\} Compute operation by iterating weaker operation e.g. 2^n=2*\ldots*2 Use accumulator a and increment counter (count-up) Or decrement counter (e.g. n) (count down)
```

```
a=1; c=0; while (c< n) \{a=2*a; c=c+1\}
Compute operation by iterating weaker operation
e.g. 2^n=2*\ldots*2
Use accumulator a and increment counter (count-up)
Or decrement counter (e.g. n) (count down)
Invariant: a=2\hat{\ }c\wedge\ldots (accumulator = f(iterations))
```

```
a=1;\ c=0;\ while\ (c< n)\ \{a=2*a;\ c=c+1\} Compute operation by iterating weaker operation e.g. 2^n=2*\ldots*2 Use accumulator a and increment counter (count-up) Or decrement counter (e.g. n) (count down) Invariant: a=2\hat{\ }c\wedge\ldots (accumulator = f(iterations)) Applications: * by +, exp, Fibonacchi, factorial, ...
```

IMP2/Examples.thy

Count-up, Count-Down

Invert monotonic function, by naively trying all values:

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$$r=1; while (r*r \le n) \{r=r+1\}; r=r-1$$

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Invert monotonic function, by naively trying all values: r=1; $while\ (r*r\leq n)\ \{r=r+1\};\ r=r-1$ What does this compute?

Invert monotonic function, by naively trying all values: r=1; while $(r*r \le n)$ $\{r=r+1\}$; r=r-1

What does this compute?square root, rounded down!

Invert monotonic function, by naively trying all values: r=1; $while\ (r*r\leq n)\ \{r=r+1\};\ r=r-1$ What does this compute?square root, rounded down! Idea: Iterate until we overshoot by one. Then decrement.

Invert monotonic function, by naively trying all values:

$$r=1; while (r*r \le n) \{r=r+1\}; r=r-1$$

What does this compute?square root, rounded down!

Idea: Iterate until we overshoot by one. Then decrement

Invariant:

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Invariant: ?

Invert monotonic function, by naively trying all values:

$$r=1; while (r*r \le n) \{r=r+1\}; r=r-1$$

What does this compute?square root, rounded down!

Idea: Iterate until we overshoot by one. Then decrement.

Invariant: ? $(r-1)^2 \le n \land \dots (r-1 \text{ below or equal result})$

Invert monotonic function, by naively trying all values:

$$r=1; while (r*r \le n) \{r=r+1\}; r=r-1$$

What does this compute?square root, rounded down!

Idea: Iterate until we overshoot by one. Then decrement.

Invariant: ? $(r-1)^2 \le n \land \dots (r-1 \text{ below or equal result})$

Applications: sqrt, log, ...

IMP2/Examples.thy

Approximate from Below

We can compute sqrt more efficiently.

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```
 black length 1 length 2 len
```

We can compute sqrt more efficiently.

```
 \begin{array}{l} l{=}0;\; h{=}n{+}1;\\ while\; (l{+}1< h)\\ m=(l+h)\;/\; 2;\\ \text{if } m^*m\leq n \; \text{then } l{=}m \; \text{else } h{=}m\\ ;\\ r{=}l \end{array}
```

Idea: Half range in each step

We can compute sqrt more efficiently.

```
 \begin{array}{l} l{=}0;\; h{=}n{+}1;\\ while\; (l{+}1< h)\\ m=(l+h)\;/\; 2;\\ if\; m^*m\leq n\; then\; l{=}m\; else\; h{=}m\\ ;\\ r{=}l \end{array}
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Idea: Half range in each step Invariant

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 \begin{array}{l} l{=}0;\; h{=}n{+}1;\\ while\; (l{+}1< h)\\ m=(l+h)\;/\; 2;\\ \text{if } m^*m\leq n \; \text{then } l{=}m \; \text{else } h{=}m\\ ;\\ r{=}l \end{array}
```

Idea: Half range in each step Invariant?

We can compute sqrt more efficiently.

```
l=0: h=n+1;
while (l+1 < h)
 m = (1 + h) / 2;
 if m*m < n then l=m else h=m
r=1
```

Idea: Half range in each step

Invariant? $l^2 \le n < h^2 \land \dots$ (range contains solution)

We can compute sqrt more efficiently.

```
 \begin{array}{l} l{=}0;\;h{=}n{+}1;\\ while\;(l{+}1< h)\\ m=(l+h)\;/\;2;\\ if\;m^*m\leq n\;then\;l{=}m\;else\;h{=}m\\ ;\\ r{=}l \end{array}
```

Idea: Half range in each step Invariant? $l^2 \le n < h^2 \land \dots$ (range contains solution) This program is actually tricky to get right!

IMP2/Examples.thy

Bisection

6 Example Verifications
Loop Patterns
Euclid's Algorithm

Euclid Intro

Compute gcd of positive numbers a, b

Euclid Intro

Compute gcd of positive numbers a, b

```
Reminder: Divides: (b\ dvd\ a) = (\exists\ k.\ a = b*k)
Greatest Common Divisor: gcd::int\Rightarrow int\Rightarrow int such that gcd\ a\ b\ dvd\ a and gcd\ a\ b\ dvd\ b and [a\neq 0;\ b\neq 0;\ c\ dvd\ a;\ c\ dvd\ b] \implies c < qcd\ a\ b
```

Euclid Variants

By subtraction. Using $\gcd\left(m-n\right) \ n = \gcd \ m \ n$

Euclid Variants

By subtraction. Using gcd (m - n) n = gcd m n

By modulo. Using: $gcd \ x \ y = gcd \ y \ (x \ mod \ y)$

IMP2/Examples.thy

Euclid

4 Weakest Preconditions

5 Towards Simpler Verification of Programs

6 Example Verifications

Advanced Verification

Program: $a=1; i=0; while (i< n) \{ a=a*2; i=i+1 \}$

Pre: $n \ge 0$ Post: $a = 2 \hat{n}_0$

Program: $a=1; i=0; while (i< n) \{ a=a*2; i=i+1 \}$

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Only a,i changed: $\forall x. \ x \notin \{"a", "i"\} \longrightarrow s \ x = s' \ x$

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modifies vars $s_1 \ s_2 = (\forall x. \ x \notin vars \longrightarrow s_1 \ x = s_2 \ x)$

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Program modifies at most variables it assigns to

 $\pi: (c, s) \Rightarrow t \Longrightarrow modifies (lhsv \pi c) t s$

We can strengthen correctness statement (automatically)

$$wp \ \pi \ c \ Q \ s \Longrightarrow wp \ \pi \ c \ (\lambda s'. \ Q \ s' \land modifies \ (lhsv \ \pi \ c)$$

 $s' \ s) \ s$

We can strengthen correctness statement (automatically)

$$wp \ \pi \ c \ Q \ s \Longrightarrow wp \ \pi \ c \ (\lambda s'. \ Q \ s' \land \ modifies \ (lhsv \ \pi \ c) \ s' \ s) \ s$$

For while-rule, we get

```
lemma wp\_whileI\_modset:

fixes c

defines [simp]: modset \equiv lhsv c

assumes WF: wf R

assumes INIT: I \mathfrak{s}_0

assumes STEP: \bigwedge \mathfrak{s}. \llbracket modifies modset \mathfrak{s} \mathfrak{s}_0; I \mathfrak{s}; bval b \mathfrak{s} \rrbracket

\Longrightarrow wp c (\lambda \mathfrak{s}'. I \mathfrak{s}' \wedge (\mathfrak{s}',\mathfrak{s}) \in R) \mathfrak{s}

assumes FINAL: \bigwedge \mathfrak{s}. \llbracket modifies modset \mathfrak{s} \mathfrak{s}_0; I \mathfrak{s}; \neg bval b \mathfrak{s} \rrbracket

\Longrightarrow Q \mathfrak{s}

shows vvv (WHIIF b, DO, c) O \mathfrak{s}_0
```

The VCG will automatically rewrite with rule

$$[\![modifies\ vs\ s\ s';\ x\notin vs]\!] \Longrightarrow s\ x=s'\ x$$

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program_spec computes *lhs*-variables:

 $HT_mods \pi \ mods \ P \ c \ Q \equiv HT \pi \ P \ c \ (\lambda s_0 \ s. \ modifies \ mods \ s \ s_0 \land Q \ s_0 \ s)$

IMP2/Examples.thy

Euclid – show modified sets

Consider program

```
 a=1; \\ while (m>0) \{ \\ n=a; a=1; \\ while (n>0) \{ \\ a=2*a; n=n-1 \\ \}; \\ m=m-1 \} \}
```

What does this compute

Consider program

```
 a = 1; \\ while (m>0) \{ \\ n = a; a = 1; \\ while (n>0) \{ \\ a = 2*a; n = n-1 \\ \}; \\ m = m-1 \}
```

What does this compute?

Consider program

```
 \begin{array}{l} a{=}1;\\ while\;(m{>}0)\;\{\\ n{=}a;\;a=1;\\ while\;(n{>}0)\;\{\\ a{=}2{*}a;\;n{=}n{-}1\\ \};\\ m{=}m{-}1\\ \} \end{array}
```

What does this compute?

Power-tower function: $2^{2^{\cdot \cdot \cdot \cdot 2}}$ (m times)

Inner loop invariant: Would like to refer to n right before loop!

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In our simple VCG, we can't!

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Still, we already have verified inner loop!

Inner loop invariant: Would like to refer to $\,n$ right before loop!

In our simple VCG, we can't!

Still, we already have verified inner loop!

Idea: Split and verify separately!

```
 \begin{array}{l} a{=}1;\\ while \ (m{>}0) \ \{\\ n{=}a;\\ inline \ exp\_count\_down;\\ m{=}m{-}1\\ \} \end{array}
```

```
 \begin{array}{l} a{=}1;\\ while \ (m{>}0) \ \{\\ n{=}a;\\ inline \ exp\_count\_down;\\ m{=}m{-}1\\ \} \end{array}
```

Reuse existing proof of exp-count-down program!

Re-using proofs:

Re-using proofs:

$$\begin{bmatrix} HT \pi & P & c & Q; \land s. & P' & s \Longrightarrow P & s; \land s_0 & s. & \llbracket P & s_0; & P' & s_0; & Q \\ s_0 & s \rrbracket & \Longrightarrow Q' & s_0 & s \rrbracket \\ & \Longrightarrow HT \pi & P' & c & Q'
 \end{bmatrix}$$

Re-using proofs:

```
    \begin{bmatrix} HT \pi & P & c & Q; \ \land s. & P' & s \Longrightarrow P & s; \ \land s_0 & s. & \llbracket P & s_0; & P' & s_0; & Q \\ s_0 & s \rrbracket & \Longrightarrow & Q' & s_0 & s \rrbracket \\ & \Longrightarrow & HT \pi & P' & c & Q' 
    \end{bmatrix}
```

with modified sets:

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VCG will automatically use this rule.

Re-using proofs:

```
    \begin{bmatrix} HT \pi & P & c & Q; \ \land s. & P' & s \Longrightarrow P & s; \ \land s_0 & s. & \llbracket P & s_0; & P' & s_0; & Q \\ s_0 & s \rrbracket & \Longrightarrow & Q' & s_0 & s \rrbracket \\ & \Longrightarrow & HT \pi & P' & c & Q' 
    \end{bmatrix}
```

with modified sets:

VCG will automatically use this rule.

If inlined program has been proved with **program_spec**

IMP2/Examples.thy

Power-Tower

7 Advanced Verification Arrays

Data Refinement Local Variables Recursion

Every variable is of type $int \Rightarrow int$.

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aval (Vidx x i) s = s x (aval i s)

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Arithmetic Expressions:

```
Vidx::char\ list \Rightarrow aexp \Rightarrow aexp

aval\ (Vidx\ x\ i)\ s = s\ x\ (aval\ i\ s)
```

Commands:

```
AssignIdx::char list \Rightarrow aexp \Rightarrow aexp \Rightarrow com

\pi: (x[i] ::= a, s) \Rightarrow s(x := (s x)(aval i s := aval a s))
```

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Vidx::char\ list \Rightarrow aexp \Rightarrow aexp aval (Vidx\ x\ i) s=s\ x\ (aval\ i\ s)
```

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AssignIdx::char list \Rightarrow aexp \Rightarrow aexp \Rightarrow com

\pi: (x[i] ::= a, s) \Rightarrow s(x := (s x)(aval \ i \ s := aval \ a \ s))

ArrayCpy::char list \Rightarrow char list \Rightarrow com

\pi: (x[] ::= y, s) \Rightarrow s(x := s y)
```

Every variable is of type $int \Rightarrow int$.

Arithmetic Expressions:

```
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```

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AssignIdx::char list \Rightarrow aexp \Rightarrow aexp \Rightarrow com

\pi: (x[i] ::= a, s) \Rightarrow s(x := (s x)(aval i s := aval a s))
```

$$ArrayCpy::char\ list \Rightarrow char\ list \Rightarrow com$$

 $\pi: (x[] ::= y, s) \Rightarrow s(x := s y)$

ArrayClear::char list \Rightarrow com π : (CLEAR x[], s) \Rightarrow $s(x := \lambda_{-}, 0)$

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By default, we use index 0.

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Abbreviations:

$$V x = Vidx x (N 0)$$

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Only with index 0: Bind VAR (s "x" 0) (λx)

By default, we use index 0.

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Otherwise: Bind VAR (s "x") (λx)

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IMP2/Examples.thy

Array-Sum

Usually, use function $int \Rightarrow int$ directly.

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Set interval notation:

$${l..h}, {l..< h}, {l<...h}, {l<...< h}$$

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Examples:

$$\forall i \in \{0...<42\}. \ a \ i > 0$$

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Elements 0 to 41 are positive

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Examples:

 $\forall i \in \{0...<42\}. \ a \ i > 0 \text{ means?}$

Elements 0 to 41 are positive

$$\forall i \in \{l.. < h\}. \ \forall j \in \{l.. < h\}. \ i \leq j \longrightarrow a \ i \leq a \ j$$

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Examples:

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Theory $IMP2/IMP2_Aux_Lemmas$ provides useful lemmas and definitions

IMP2/Examples.thy

Sortedness Check

Find element in sorted array. In time $O(\log n)$.

Find element in sorted array. In time $O(\log n)$. Idea: Halve interval in each step.

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This algorithm is tricky to implement correctly!

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Although the basic idea of binary search is comparatively straightforward, the details can be surprisingly tricky ...

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Although the basic idea of binary search is comparatively straightforward, the details can be surprisingly tricky ...

— Donald Knuth

Only 5 out of 20 surveyed textbooks had correct implementations

— Richard E. Pattis, 1988

```
while (I < h) { m = (I + h) / 2; if (a[m] < x) I = m + 1 else h = m }
```

```
while ( | < h )  { m = ( | + h ) / 2; if ( a [m] < x ) | = m + 1 else h = m }
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while (| < h) { m = (| + h|) / 2; if (a[m] < x) | = m + 1 else h = m }
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if (a[m] < x) | = m + 1

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```

```
while (| < h) {
    m = (| + h) / 2;
    if (a[m] < x) | = m + 1
    else h = m
}</pre>
```

Returns smallest i with $x \le a[i]$

Notes on Binary Search

```
while (| < h) {
    m = (| + h) / 2;
    if (a[m] < x) | = m + 1
    else | h = m
}</pre>
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Note: Our language has arbitrary large integers.

Notes on Binary Search

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}</pre>
```

Note: Our language has arbitrary large integers.

Otherwise, m = (l + h)/2 may overflow!

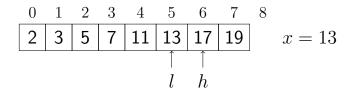
Notes on Binary Search

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```

Note: Our language has arbitrary large integers.

Otherwise, m = (l + h)/2 may overflow!

Bug in Java Standard Library for > 9 years!



Invariant:

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• $i < l \implies a[i] < x$ (strictly smaller than x)

Invariant:

- $i < l \implies a[i] < x$ (strictly smaller than x)
- $i \ge h \Longrightarrow x \le a[i]$ (greater or equal to x)

Invariant:

- $i < l \implies a[i] < x$ (strictly smaller than x)
- $i \ge h \implies x \le a[i]$ (greater or equal to x)
- and the usual bounds

IMP2/Examples.thy

Binary Search

Insertion Sort

```
i = 1 + 1;
while (i < h) {
  key = a[i];
  i = i - 1:
  while (i>=| \&\& a[i]>key) {
    a[i+1] = a[i];
    i=i-1
  a[i+1] = key
  i=i+1
```

Idea: Build sorted array from start. In each iteration, move next element to its position

Precondition: $l \le h$

Precondition: $l \le h$

Precondition: $l \le h$

Postcondition:

Array is sorted

Precondition: $l \le h$

Postcondition:

Array is sorted ran_sorted a l h

Precondition: $l \le h$

- Array is sorted ran_sorted a l h
- Array contains same elements

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Precondition: $l \le h$

Postcondition:

- Array is sorted $ran_sorted\ a\ l\ h$
- Array contains same elements $mset_ran \ a \{l...< h\} = mset_ran \ a_0 \{l...< h\}$

where

```
ran\_sorted\ a\ l\ h \equiv \forall\ i \in \{l... < h\}.\ \forall\ j \in \{l... < h\}.\ i \leq j \longrightarrow a\ i \leq a\ j mset\_ran\ a\ r = (\sum i \in r.\ \{\#a\ i\#\})
```

imports HOL-Library.Multiset

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'a multiset: Finite multiset

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Some functions and syntax:

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\{\#a, b, c, c\#\} — Syntax for add\_mset and \{\#\}
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Multiset of elements at indexes in finite set r

```
j = l + 1;
while (j<h) {
   inline inner_loop;
   j=j+1
}</pre>
```

Separate proof for inner loop!

```
j = | + 1;
while (j<h) {
   inline inner_loop;
   j=j+1
}</pre>
```

Specification of inner loop:

Separate proof for inner loop!

```
j = | + 1;
while (j<h) {
   inline inner_loop;
   j=j+1
}</pre>
```

Specification of inner loop: ?

```
j = I + 1;
while (j<h) {
  inline inner_loop;
  j=j+1
}
Specification of inner loop: ?
  assumes ran_sorted a l j</pre>
```

```
\begin{array}{l} \textbf{j} = \textbf{l} + \textbf{1}; \\ \textbf{while} \ (\textbf{j} < \textbf{h}) \ \{ \\ & \texttt{inline} \ \texttt{inner\_loop}; \\ & \texttt{j} = \textbf{j} + 1 \\ \} \\ \\ \textbf{Specification of inner loop: ?} \\ & \textbf{assumes} \ ran\_sorted \ a \ l \ j \\ & \textbf{ensures} \ ran\_sorted \ a \ l \ (j+1) \end{array}
```

```
\begin{array}{l} {\rm j = l + 1;} \\ {\rm while \ (j < h) \ \{} \\ {\rm inline \ inner\_loop;} \\ {\rm j = j + 1} \\ {\rm \}} \\ \\ {\rm Specification \ of \ inner \ loop:} \ ?} \\ {\rm assumes \ } ran\_sorted \ a \ l \ j \\ {\rm ensures \ } ran\_sorted \ a \ l \ (j + 1) \ {\rm and} \end{array}
```

```
i = 1 + 1;
while (j < h) {
   inline inner_loop;
  i=i+1
Specification of inner loop: ?
 assumes ran_sorted a l j
  ensures ran\_sorted \ a \ l \ (j + 1) and
  ensures mset\_ran \ a \{l..j\} = mset\_ran \ a_0 \{l..j\}
```

Separate proof for inner loop!

```
i = 1 + 1;
while (j < h) {
   inline inner_loop;
  i=i+1
Specification of inner loop: ?
 assumes ran_sorted a l j
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Invariant of outer loop:
```

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```
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Specification of inner loop: ?
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  ensures ran\_sorted \ a \ l \ (j + 1) and
  ensures mset\_ran \ a \{l..j\} = mset\_ran \ a_0 \{l..j\}
Invariant of outer loop:
ran_sorted a l j
\land mset\_ran \ a \{l.. < h\} = mset\_ran \ a_0 \{l.. < h\}
```

```
\label{eq:key} \begin{array}{l} \text{key} = \text{a[j];} \\ \text{i} = \text{j}-1; \\ \text{while (i>=| &\& a[i]>key) } \\ \text{a[i+1]} = \text{a[i];} \\ \text{i=i}-1 \\ \text{}; \\ \text{a[i+1]} = \text{key} \end{array}
```

```
 \begin{array}{l} \text{key} &=& \text{a[j];} \\ \text{i} &=& \text{j}-1; \\ \text{while} & \text{(i>=| \&\& a[i]>key)} \end{array} \} \\ &=& \text{a[i+1]} =& \text{a[i];} \\ &=& \text{i=i-1} \\ \}; \\ &=& \text{a[i+1]} =& \text{key} \\ \end{array}
```

Intuition:

```
key = a[j];
i = j-1;
while (i>=| && a[i]>key) {
   a[i+1] = a[i];
   i=i-1
};
a[i+1] = key
Intuition: ?
```

```
key = a[j];
i = i - 1;
while (i \ge 1 \&\& a[i] > key) {
  a[i+1] = a[i];
  i=i-1
a[i+1] = key
Intuition: ?
a[j] is moved backwards
```

```
key = a[i];
i = i - 1;
while (i \ge 1 \&\& a[i] > key) {
  a[i+1] = a[i];
  i=i-1
a[i+1] = key
Intuition: ?
a[j] is moved backwards until
```

```
key = a[j];
i = i - 1:
while (i \ge 1 \&\& a[i] > key) {
  a[i+1] = a[i];
  i=i-1
a[i+1] = key
Intuition: ?
a|j| is moved backwards until
previous element is \leq a[j]
```

```
key = a[j];
i = i - 1:
while (i \ge 1 \&\& a[i] > key) {
  a[i+1] = a[i];
  i=i-1
a[i+1] = key
Intuition: ?
a|j| is moved backwards until
previous element is \leq a[j] or
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```
key = a[j];
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  a[i+1] = a[i];
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a[i+1] = key
Intuition: ?
a|j| is moved backwards until
previous element is \leq a[j] or
begin of array is reached
```

```
\label{eq:key} \begin{array}{l} \text{key} &=& \text{a[j];} \\ \text{i} &=& \text{j}-1; \\ \text{while } (\text{i}>=\text{I \&\& a[i]}>\text{key}) \ \{ \\ \text{a[i+1]} &=& \text{a[i];} \\ \text{i}=\text{i}-1 \\ \}; \\ \text{a[i+1]} &=& \text{key} \end{array}
```

Intuition: ? a[j] is moved backwards until previous element is $\leq a[j]$ or begin of array is reached

Move a[j] backwards over greater elements.

Let's specify this intuition!

Move a[j] backwards over greater elements. Let's specify this intuition! It implies sortedness and mset-preservation

Move a[j] backwards over greater elements. Let's specify this intuition! It implies sortedness and mset-preservation But is closer to what algorithm does

Move a[j] backwards over greater elements. Let's specify this intuition! It implies sortedness and mset-preservation But is closer to what algorithm does Invariants easier to find!

Move a[j] backwards over greater elements.

assumes l < j, let $key = a_0 j$

```
assumes l < j, let key = a_0 j
ensures i \in \{l - 1... < j\}
```

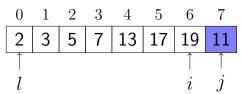
```
assumes l < j, let \ key = a_0 \ j ensures i \in \{l-1...< j\} ensures \forall \ k \in \{l..i\}. a \ k = a_0 \ k and
```

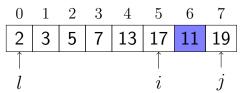
```
assumes l < j, let \ key = a_0 \ j ensures i \in \{l-1...< j\} ensures \forall \ k \in \{l..i\}. a \ k = a_0 \ k and a \ (i+1) = key and
```

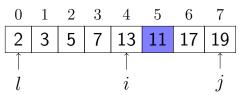
```
assumes l < j, let \ key = a_0 \ j ensures i \in \{l-1...< j\} ensures \forall \ k \in \{l..i\}. a \ k = a_0 \ k and a \ (i+1) = key and \forall \ k \in \{i+2..j\}. a \ k = a_0 \ (k-1)
```

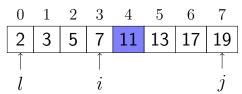
```
assumes l < j, let \ key = a_0 \ j ensures i \in \{l-1...< j\} ensures \forall \ k \in \{l..i\}. a \ k = a_0 \ k and a \ (i+1) = key and \forall \ k \in \{i+2..j\}. a \ k = a_0 \ (k-1) ensures l \le i \longrightarrow a \ i \le key and
```

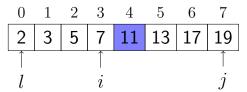
```
assumes l < j, let \ key = a_0 \ j ensures i \in \{l-1...< j\} ensures \forall \ k \in \{l..i\}. a \ k = a_0 \ k and a \ (i+1) = key and \forall \ k \in \{i+2..j\}. a \ k = a_0 \ (k-1) ensures l \le i \longrightarrow a \ i \le key and \forall \ k \in \{i+2..j\}. key < a \ k
```

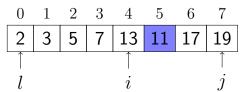


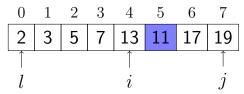












Consider intermediate situation

• indexes $\leq i$ unchanged: $\forall k \in \{l..i\}$. $a k = a_0 k$

- indexes $\leq i$ unchanged: $\forall k \in \{l..i\}$. $a k = a_0 k$
- indexes $\geq i+2$ correctly shifted $\forall k \in \{i+2...j\}$. $a \ k = a_0 \ (k-1)$

- indexes $\leq i$ unchanged: $\forall k \in \{l..i\}$. $a k = a_0 k$
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- indexes $\leq i$ unchanged: $\forall k \in \{l..i\}$. $a k = a_0 k$
- indexes $\geq i+2$ correctly shifted $\forall k \in \{i+2...j\}$. $a \ k = a_0 \ (k-1)$
- and elements greater than key $\forall k \in \{i + 2...j\}$. $key < a \ k$
- + the usual bounds: $l-1 \le i \land i < j$

IMP2/Examples.thy

Insertion Sort

Summary so Far

Understand what program does!

Summary so Far

Understand what program does! Split program into handy parts

Summary so Far

Understand what program does!

Split program into handy parts

Specify what parts do (independently of users)

Summary so Far

Understand what program does!

Split program into handy parts

Specify what parts do (independently of users)

Prove that this implies expectations of users

Summary so Far

Understand what program does!

Split program into handy parts

Specify what parts do (independently of users)

Prove that this implies expectations of users

Prove parts separately and assemble to bigger parts

7 Advanced Verification

Arrays

Data Refinement

Local Variables
Recursion

Model $int \Rightarrow int$ not always appropriate

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E.g., list: Understand a [l.. < h] as int list

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Idea: Do proof at level of understanding first

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Instead of one proof, get two

Model $int \Rightarrow int$ not always appropriate

E.g., list: Understand a [l.. < h] as int list

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Instead of one proof, get two ???

Model $int \Rightarrow int$ not always appropriate E.g., list: Understand a [l..<h] as int list Idea: Do proof at level of understanding first then show that implementation is correct! Instead of one complex proof, get two simple proofs!

IMP2/Examples.thy

Filter, Merge, dedup

Advanced Verification

Arrays
Data Refinement
Local Variables

Recursion

Introduce local variables

Introduce local variables

Why?

Introduce local variables

Why? Better modularity.

Introduce local variables

Why? Better modularity.

Don't worry about name-clashes with subroutine's auxiliary variables

Partition variable names into local and global names

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is_qlobal — Variable name starts with "G"

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is_global — Variable name starts with "G"

```
fun is\_global :: vname \Rightarrow bool where is\_global [] \longleftrightarrow True | is\_global (CHR "G"\#\_) \longleftrightarrow True | is\_global \_ \longleftrightarrow False
```

Partition variable names into local and global names

is_global — Variable name starts with "G"

```
fun is\_global :: vname \Rightarrow bool where is\_global [] \longleftrightarrow True | is\_global (CHR "G"#\_) \longleftrightarrow True | is\_global \_ \longleftrightarrow False
```

$$is_local \ a = \neg is_global \ a$$

$$\langle s|t \rangle$$
 $n=(if\ is_local\ n\ then\ s\ n\ else\ t\ n)$

 $<\!s_1|s_2\!>$ – State with locals from s_1 , globals from s_2

$$\langle s|t \rangle$$
 $n=(if\ is_local\ n\ then\ s\ n\ else\ t\ n)$

Some rules: $\langle s|s \rangle = s$

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 $\langle s|\langle s'|t \rangle \rangle$

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Some rules:
$$\langle s|s \rangle = s$$

 $\langle s|\langle s'|t \rangle \rangle =$

$$<\!\!s|t\!\!> n=$$
 (if $is_local\ n$ then $s\ n$ else $t\ n$)

Some rules:
$$< s | s > = s$$

 $< s | < s' | t > > = < s | t >$
 $< < s | t' > | t > = < s | t >$

$$\langle s|t \rangle$$
 $n=(if\ is_local\ n\ then\ s\ n\ else\ t\ n)$

Some rules:
$$\langle s|s \rangle = s$$

 $\langle s|\langle s'|t \rangle \rangle = \langle s|t \rangle$
 $\langle \langle s|t' \rangle|t \rangle = \langle s|t \rangle$
 $is_local\ x \Longrightarrow \langle s|t \rangle\ x =$

 $< s_1 | s_2 >$ – State with locals from s_1 , globals from s_2 $< s | t > n = (if is_local n then s n else t n)$

Some rules:
$$\langle s|s \rangle = s$$

 $\langle s|\langle s'|t \rangle \rangle = \langle s|t \rangle$
 $\langle \langle s|t' \rangle|t \rangle = \langle s|t \rangle$
 $is_local\ x \Longrightarrow \langle s|t \rangle\ x = s\ x$
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 $is_local\ x \Longrightarrow \langle s|t \rangle\ x = s\ x$
 $is_global\ x \Longrightarrow \langle s|t \rangle\ x = t\ x$
 $is_local\ x \Longrightarrow \langle s|t \rangle(x := v) =$

$$<\!\!s|t\!\!> n=(if\ is_local\ n\ then\ s\ n\ else\ t\ n)$$

Some rules:
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 $is_local\ x \Longrightarrow \langle s|t \rangle\ x = s\ x$
 $is_global\ x \Longrightarrow \langle s|t \rangle\ x = t\ x$
 $is_local\ x \Longrightarrow \langle s|t \rangle(x := v) = \langle s(x := v)|t \rangle$

 $<\!s_1|s_2\!>$ – State with locals from s_1 , globals from s_2

 $\langle s|t \rangle n = (if is_local \ n \ then \ s \ n \ else \ t \ n)$

Some rules:
$$\langle s|s \rangle = s$$

 $\langle s|\langle s'|t \rangle \rangle = \langle s|t \rangle$
 $\langle \langle s|t' \rangle|t \rangle = \langle s|t \rangle$
 $is_local\ x \Longrightarrow \langle s|t \rangle\ x = s\ x$
 $is_global\ x \Longrightarrow \langle s|t \rangle\ x = t\ x$
 $is_local\ x \Longrightarrow \langle s|t \rangle\ (x := v) = \langle s(x := v)|t \rangle$
 $is_global\ x \Longrightarrow \langle s|t \rangle\ (x := v) = \langle s|t(x := v) \rangle$

 $SCOPE\ c$ — Execute c with fresh set of local variables. Restore original local variables afterwards

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$$\pi: (c, <<>|s>) \Rightarrow s' \Longrightarrow \pi: (SCOPE \ c, \ s) \Rightarrow$$

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$$\pi: (c, <<>|s>) \Rightarrow s' \Longrightarrow \pi: (SCOPE \ c, s) \Rightarrow$$

Unfold rule:
$$wp \pi (SCOPE c) Q s$$

 $SCOPE\ c$ — Execute c with fresh set of local variables. Restore original local variables afterwards

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= ?

 $SCOPE\ c$ — Execute c with fresh set of local variables. Restore original local variables afterwards

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Unfold rule:
$$wp \pi (SCOPE c) Q s$$

Scope Command

 $SCOPE\ c$ — Execute c with fresh set of local variables. Restore original local variables afterwards

Semantics:

$$\pi: (c, <<>|s>) \Rightarrow s' \Longrightarrow \pi: (SCOPE \ c, s) \Rightarrow$$

Unfold rule:
$$wp \pi (SCOPE c) Q s$$

= $wp \pi c (\lambda s'. Q < s|s'>) <<>|s>$

Pass information over scope boundaries by globals

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Non-recursive procedure call: $r = f(a_1, \ldots, a_n)$

Pass information over scope boundaries by globals

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$$r = f(a_1, ..., a_n)$$

 $G_1 = a_1; ...; G_n = a_n; inline f; r = G$

Pass information over scope boundaries by globals

```
Non-recursive procedure call: r = f(a_1, ..., a_n)

G_1 = a_1; ...; G_n = a_n; inline f; r = G
```

Procedure: $f(p_1, \ldots, p_n) \{ body; return x \}$

Pass information over scope boundaries by globals

```
Non-recursive procedure call: r = f(a_1, ..., a_n)

G_1 = a_1; ...; G_n = a_n; inline f; r=G

Procedure: f(p_1, ..., p_n) \{ body; return x \}

scope \{ p_1 = G_1; ...; p_n = G_n; body; G=x \}
```

Given specification of body: $HT\ P\ body\ Q$ and parameters $p_1,...,p_n$ and return variable x

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How to derive specification for procedure? HT $P'(scope \{ p_1 = G_1; ...; p_n = G_n; body; G=x \})$ Q'

Given specification of body: $HT\ P\ body\ Q$ and parameters $p_1,...,p_n$ and return variable x

How to derive specification for procedure? HT $P'(scope \{ p_1 = G_1; ...; p_n = G_n; body; G=x \})$ Q'

Recall:

$$HT \pi P c Q \equiv \forall s_0. P s_0 \longrightarrow wp \pi c (Q s_0) s_0$$

Prologue

```
HT \pi \ P \ body \ Q \Longrightarrow

HT \pi \ (wp \pi \ prologue \ P) \ (prologue;; \ body)

(\lambda s_0 \ s. \ wp \pi \ prologue \ (\lambda s_0. \ Q \ s_0 \ s) \ s_0)
```

Intuition: Weakest precondition to enforce ${\cal P}$ after prologue

Epilogue

 $\llbracket HT \ \pi \ P \ body \ Q; \ \forall \ s. \ \exists \ t. \ \pi: \ (epilogue, \ s) \Rightarrow t \rrbracket$ $\Longrightarrow HT \ \pi \ P \ (body; \ epilogue) \ (\lambda s_0. \ sp \ \pi \ (Q \ s_0) \ epilogue)$

Intuition: Strongest postcondition we get from ${\it Q}$ after epilogue

 $sp \pi P c t \equiv \exists s. P s \land \pi : (c, s) \Rightarrow t$

$$sp \pi P c t \equiv \exists s. P s \land \pi : (c, s) \Rightarrow t$$

$$sp \pi P(x[] := y) t$$

$$sp \pi P c t \equiv \exists s. P s \land \pi : (c, s) \Rightarrow t$$

$$sp \pi P(x[] ::= y) t \longleftrightarrow$$

$$sp \pi P c t \equiv \exists s. P s \land \pi : (c, s) \Rightarrow t$$

$$sp \pi P(x[] := y) t \longleftrightarrow \exists vx. let s = t(x := vx) in t x = s y \land P s$$

$$sp \pi P c t \equiv \exists s. P s \land \pi : (c, s) \Rightarrow t$$

$$sp \pi P(x[] ::= y) \ t \longleftrightarrow \exists vx. \ \textit{let} \ s = t(x := vx) \ \textit{in} \ t \ x = s \ y \land P \ s$$
 $sp \pi P(x[] ::= y) \ t$

$$sp \pi P c t \equiv \exists s. P s \land \pi : (c, s) \Rightarrow t$$

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$$sp \ \pi \ P \ (x[] ::= y) \ t \longleftrightarrow t \ x = t \ y \land (\exists \ vx. \ P \ (t(x := vx, \ y := t \ x)))$$

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 $sp \ \pi \ P \ (x[] ::= y) \ t \longleftrightarrow t \ x = t \ y \land (\exists \ vx. \ P \ (t(x := vx, \ y := t \ x)))$
 $sp \ \pi \ P \ (c_1;; \ c_2) \ t$

$$sp \pi P c t \equiv \exists s. P s \land \pi: (c, s) \Rightarrow t$$

$$sp \pi P(x[] ::= y) t \longleftrightarrow \exists vx. \ \textit{let} \ s = t(x := vx) \ \textit{in} \ t \ x = s \ y \land P \ s$$
 $sp \pi P(x[] ::= y) t \longleftrightarrow t \ x = t \ y \land (\exists vx. \ P(t(x := vx, y := t \ x)))$
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$$sp \pi P c t \equiv \exists s. P s \land \pi: (c, s) \Rightarrow t$$

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 $sp \pi P(x[] ::= y) t \longleftrightarrow t \ x = t \ y \land (\exists vx. \ P(t(x := vx, y := t \ x)))$
 $sp \pi P(c_1;; c_2) t \longleftrightarrow sp \pi (sp \pi P c_1) c_2 t$

$$HT \ P' \ (scope \ \{ \ p_1 = G_1; \ldots; \ p_n = G_n; \ body; \ G=x \ \}) \ Q'$$

HT P' (scope {
$$p_1 = G_1; \ldots; p_n = G_n; body; G=x$$
 }) Q'

Derive specification for

```
HT\ P'\ (scope\ \{\ p_1=G_1;\ldots;\ p_n=G_n;\ body;\ G=x\ \})\ Q'
```

Derive specification for

```
Parameter assignments: HT \pi P c Q \Longrightarrow HT \pi (\lambda s. P (s(x := s y))) (x[] ::= y;; c) (\lambda s_0. Q (s_0(x := s_0 y)))
```

```
HT P' (scope \{ p_1 = G_1; ...; p_n = G_n; body; G=x \}) Q'
```

Derive specification for

Parameter assignments: $HT \pi P c Q \Longrightarrow HT \pi (\lambda s. P(s(x := s y))) (x[] ::= y;; c) (\lambda s_0. Q(s_0(x := s_0 y)))$

Return value assignment: $HT \pi P c Q \Longrightarrow$

 $HT \pi P(c;; x[] ::= y) (\lambda s_0 \ s. \ \exists \ vx. \ Q \ s_0 \ (s(x := vx, \ y := s \ x)))$

$$HT P' (scope \{ p_1 = G_1; \ldots; p_n = G_n; body; G=x \}) Q'$$

Derive specification for

Parameter assignments:
$$HT \pi \ P \ c \ Q \Longrightarrow HT \pi \ (\lambda s. \ P \ (s(x:=s \ y))) \ (x[] ::= y;; \ c) \ (\lambda s_0. \ Q \ (s_0(x:=s_0 \ y)))$$
 Return value assignment: $HT \pi \ P \ c \ Q \Longrightarrow$

HT
$$\pi$$
 P $(c;; x[] ::= y)$ $(\lambda s_0 \ s. \ \exists \ vx. \ Q \ s_0 \ (s(x := vx, \ y := s \ x)))$

Scope:
$$HT \pi P c Q \Longrightarrow HT \pi (\lambda s. P <<>|s>) (SCOPE c) (\lambda s_0 s. \exists l. Q <<>|s>) < l|s>)$$

IMP2/Examples.thy

Merge as Procedure

Advanced Verification

Arrays
Data Refinement
Local Variables

Recursion

Program is map pname
ightharpoonup com

Program is map $pname \rightarrow com$

Procedure call command $PCall::char\ list \Rightarrow com$

Program is map pname
ightharpoonup com

Procedure call command $PCall::char \ list \Rightarrow \ com$

Big-Step semantics: π : $(c, s) \Rightarrow t$

parameterized with program π

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 $\mathsf{Big}\text{-}\mathsf{Step}\ \mathsf{semantics}\text{:}\ \pi\text{:}\ (\mathit{c},\ \mathit{s})\ \Rightarrow\ \mathit{t}$

parameterized with program π

$$\llbracket \pi \ p = Some \ c; \ \pi \colon (c, \ s) \Rightarrow t \rrbracket \Longrightarrow \pi \colon (PCall \ p, \ s) \Rightarrow t$$

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Note: Gets stuck if procedure does not exist! No problem when proving total correctness

Proof Rules for Recursion

Unfolding: π $p = Some \ c \Longrightarrow wp \ \pi \ (PCall \ p) \ Q \ s = wp \ \pi \ c \ Q \ s$

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Idea: Well-Founded induction on state

```
assumes wf\ R \bigwedge s.\ \llbracket HT\ \pi\ (\lambda s'.\ (s',s)\in R\ \wedge\ P\ s')\ (PCall\ p)\ \ Q;\ P\ s\ \rrbracket \Longrightarrow wp\ \pi\ (PCall\ p)\ (Q\ s)\ s shows HT\ \pi\ P\ (PCall\ p)\ \ Q
```

Proof Rules for Recursion

Unfolding: π $p = Some \ c \Longrightarrow wp \ \pi \ (PCall \ p) \ Q \ s = wp \ \pi \ c \ Q \ s$

Idea: Well-Founded induction on state

Show specification for state s, assuming it holds for smaller states s'.

Same idea, but for sets of specifications.

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 $HT'set \pi \Theta \equiv \forall (n, P, c, Q) \in \Theta. \ HT' \pi P c Q$ All Hoare-Triples in Θ valid. Annotation n ignored!

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 $\begin{array}{l} ASSUME_\Theta \ \pi \ f_0 \ s_0 \ R \ \Theta = \\ (\forall \ (f,\ P,\ c,\ Q) \in \Theta.\ HT' \ \pi \ (\lambda s.\ (f\ s,\ f_0\ s_0) \in R \ \wedge \ P\ s)\ c\ Q) \\ \text{Hoare-triples valid for states less than} \ f_0 \ s_0.\ \text{Annotation is variant}. \end{array}$

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$$PROVE_\Theta$$
 π f_0 s_0 Θ \equiv \forall P c Q . $(f_0, P, c, Q) \in \Theta \land P$ $s_0 \longrightarrow wp$ π $(c$ $s_0)$ $(Q$ $s_0)$ s_0 Hoare-triples valid for fixed variant f_0 and state s_0 .

```
lemma vcg\_HT'setI: assumes wf\ R assumes RL: \bigwedge f_0\ s_0. \llbracket \ ASSUME\_\Theta\ \pi\ f_0\ s_0\ R\ \Theta\ \rrbracket \Longrightarrow PROVE\_\Theta\ \pi\ f_0\ s_0\ \Theta shows HT'set\ \pi\ \Theta
```

Fix variant and state, assume that Hoare-triples hold for smaller states prove that Hoare-triples hold for this state.

```
lemma vcg\_HT'setI: assumes wf R assumes RL: \bigwedge f_0 s_0. \llbracket ASSUME\_\Theta \ \pi \ f_0 \ s_0 \ R \ \Theta \ \rrbracket \Longrightarrow PROVE\_\Theta \ \pi \ f_0 \ s_0 \ \Theta shows HT'set \ \pi \ \Theta
```

Fix variant and state, assume that Hoare-triples hold for smaller states prove that Hoare-triples hold for this state.

 $\llbracket \pi \ p = Some \ c; \ HT_mods \ \pi \ mods \ P \ c \ Q \rrbracket \Longrightarrow HT_mods \ \pi \ mods \ P \ (PCall \ p) \ Q$

Maps Hoare-Triples to procedure calls

Idea: Recursive procedure names only valid locally!

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: $(c, s) \Rightarrow t \Longrightarrow \pi$: $(PScope \pi' c, s) \Rightarrow t$

Call procedure with local procedure environment

Idea: Recursive procedure names only valid locally! No need to worry about name clashes!

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: $(c, s) \Rightarrow t \Longrightarrow \pi$: $(PScope \pi' c, s) \Rightarrow t$

Call procedure with local procedure environment

$$HT_mods \ \pi \ mods \ P \ (PCall \ p) \ Q \Longrightarrow HT_mods \ \pi' \ mods \ P \ (PScope \ \pi \ (PCall \ p)) \ Q$$

Wrap current procedure environment

The IMP2 tools take care of

• wf-relation. Default less_than

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- wf-relation. Default less_than
- parameters and return values.
- variants: expression over parameters.
- localization of procedure environment.

IMP2/Examples.thy

Ackermann, Odd/Even, Merge Sort

Completeness

Consider program with $HT \pi P c Q$

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Can we always find annotations to get provable VCs?

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Consider program with $HT \pi P c Q$

Can we always find annotations to get provable VCs?

Only consider while-rule here

Partial Correctness

Partial Correctness

 $\llbracket I \ s_0; \bigwedge s. \ I \ s \Longrightarrow \text{if } bval \ b \ s \text{ then } wlp \ \pi \ c \ I \ s \text{ else } Q \ s \rrbracket \Longrightarrow wlp \ \pi \ (WHILE \ b \ DO \ c) \ Q \ s_0$

What invariant shall we use?

Partial Correctness

What invariant shall we use?

 $wlp \pi c Q!$

Total Correctness

```
\llbracket wf \ R; \ I \ s_0;

\bigwedge s. \ I \ s \Longrightarrow \text{if } bval \ b \ s \ \text{then } wp \ \pi \ c \ (\lambda s'. \ I \ s' \land (s', \ s)

\in R) \ s \ \text{else} \ Q \ s \rrbracket

\Longrightarrow wp \ \pi \ (WHILE \ b \ DO \ c) \ Q \ s_0

Invariant: wp \ \pi \ c \ Q
```

Total Correctness

```
\llbracket wf \ R; \ I \ s_0;

\bigwedge s. \ I \ s \Longrightarrow if \ bval \ b \ s \ then \ wp \ \pi \ c \ (\lambda s'. \ I \ s' \land (s', \ s)

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\Longrightarrow \ wp \ \pi \ (WHILE \ b \ DO \ c) \ Q \ s_0

Invariant: \ wp \ \pi \ c \ Q
```

Variant?

Total Correctness

```
[wf R; I s_0;

\bigwedge s. I s \Longrightarrow if bval \ b \ s then wp \ \pi \ c \ (\lambda s'. \ I \ s' \land \ (s', \ s)

\in R) \ s else Q \ s]

\Longrightarrow wp \ \pi \ (WHILE \ b \ DO \ c) \ Q \ s_0

Invariant: wp \ \pi \ c \ Q
```

Variant?

Number of iterations until termination!

IMP2/Examples.thy

Completeness of While-Rule

Conclusions

IMP2: Verification of simple programs in Isabelle/HOL while-language, arrays, local-vars, recursive procedures Tools: concrete syntax for programs and specs, VCG

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Conclusions

IMP2: Verification of simple programs in Isabelle/HOL while-language, arrays, local-vars, recursive procedures Tools: concrete syntax for programs and specs, VCG

Not supported:

types (char, float, records), pointers, concurrency, ... Tools: ghost variables, compiler, ...

Caveats:

Procedures+Recursion tools not well-tested VCG is slow for many procedures/inlines

Chapter 9

Compiler

9 Compiler

Compiler

Instructions:

```
\begin{array}{ll} \textbf{datatype} \ instr = \\ LOADI \ int \\ \mid LOAD \ vname \\ \mid ADD \end{array} \qquad \begin{array}{ll} \text{load value} \\ \text{add top of stack} \end{array}
```

Instructions:

```
\begin{array}{lll} \textbf{datatype} & instr = \\ & LOADI & int & | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, | \  \, |
```

Instructions:

Stack Machine

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```
\begin{array}{lll} \textbf{datatype} \ instr = \\ LOADI \ int & | \ load \ value \\ | \ LOAD \ vname & | \ load \ var \\ | \ ADD & | \ add \ top \ of \ stack \\ | \ STORE \ vname & | \ store \ var \\ | \ JMP \ int & | \ jump \\ | \ JMPLESS \ int & | \ jump \ if < \end{array}
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Stack Machine

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```
\begin{array}{lll} \textbf{datatype} \ instr = \\ LOADI \ int & | \ load \ value \\ | \ LOAD \ vname & | \ load \ var \\ | \ ADD & | \ add \ top \ of \ stack \\ | \ STORE \ vname & | \ store \ var \\ | \ JMP \ int & | \ jump \ | f < \\ | \ JMPGE \ int & | \ jump \ if > \\ \end{array}
```

Semantics

Type synonyms:

```
\begin{array}{lll} stack & = & int \; list \\ config & = & int \times state \times stack \end{array}
```

Semantics

Type synonyms:

```
stack = int \ list

config = int \times state \times stack
```



Execution of 1 instruction:

 $iexec :: instr \Rightarrow config \Rightarrow config$

Instruction execution

```
iexec\ instr\ (i,\ s,\ stk) =
(case instr of LOADI n \Rightarrow (i + 1, s, n \# stk)
  LOAD x \Rightarrow (i + 1, s, s x \# stk)
  ADD \Rightarrow (i + 1, s, (hd2 \ stk + hd \ stk) \# tl2 \ stk)
  STORE \ x \Rightarrow (i + 1, s(x := hd \ stk), tl \ stk)
 | JMP \ n \Rightarrow (i + 1 + n, s, stk)
  JMPLESS \ n \Rightarrow
    (if hd2 stk < hd stk then i + 1 + n else i + 1,
     s, tl2 stk
 | JMPGE n \Rightarrow
    (if hd \ stk \le hd2 \ stk then i + 1 + n else i + 1,
     s, tl2 stk)
```

Programs are instruction lists.

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Executing one program step:

 $instr\ list \vdash config \rightarrow config$

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$$P \vdash c \rightarrow c' = (\exists i \ s \ stk.$$

$$c = (i, \ s, \ stk) \land$$

$$c' = iexec \ (P !! \ i) \ (i, \ s, \ stk) \land$$

$$0 \le i \land i < size \ P)$$

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c' = iexec \ (P !! \ i) \ (i, s, stk) \land
0 \le i \land i < size \ P)
```



where $'a \ list !! \ int = \text{nth instruction of list}$ $size :: 'a \ list \Rightarrow int = \text{list size as integer}$

Defined in the usual manner:

$$P \vdash (pc, s, stk) \rightarrow * (pc', s', stk')$$

Compiler.thy

Stack Machine



Stack Machine

Ompiler

Same as before:

```
acomp\ (N\ n) = [LOADI\ n]

acomp\ (V\ x) = [LOAD\ x]

acomp\ (Plus\ a_1\ a_2) = acomp\ a_1\ @\ acomp\ a_2\ @\ [ADD]
```

Same as before:

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Correctness theorem:

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Correctness theorem:

```
acomp \ a
 \vdash (0, s, stk) \rightarrow * (size (acomp \ a), s, aval \ a \ s \# \ stk)
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Proof by induction on a (with arbitrary stk).

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Correctness theorem:

$$acomp\ a$$
 $\vdash (0, s, stk) \rightarrow * (size\ (acomp\ a), s, aval\ a\ s \#\ stk)$

Proof by induction on a (with arbitrary stk).

Needs lemmas!

 $P \vdash c \to \ast \ c' \Longrightarrow P @ P' \vdash c \to \ast \ c'$

$$P \vdash c \rightarrow * c' \Longrightarrow P @ P' \vdash c \rightarrow * c'$$

$$P \vdash (i, s, stk) \rightarrow * (i', s', stk') \Longrightarrow$$

 $P' @ P \vdash (size P' + i, s, stk) \rightarrow * (size P' + i', s', stk')$

$$P \vdash c \rightarrow * c' \Longrightarrow P @ P' \vdash c \rightarrow * c'$$

 $P \vdash (i, s, stk) \rightarrow * (i', s', stk') \Longrightarrow$
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Proofs by rule induction on $\rightarrow *$,

$$P \vdash c \rightarrow * c' \Longrightarrow P @ P' \vdash c \rightarrow * c'$$

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$$P \vdash (i, s, stk) \rightarrow (i', s', stk') \Longrightarrow P' @ P \vdash (size P' + i, s, stk) \rightarrow (size P' + i', s', stk')$$

Proofs by cases.

Let ins be the compilation of b:

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Do not put value of b on the stack

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Do not put value of b on the stack but let value of b determine where execution of ins ends.

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Principle:



- Either execution leads to the end of ins
- or it jumps to offset +n beyond ins.

Parameters: when to jump (if b is True or False) where to jump to (n)

 $bcomp :: bexp \Rightarrow bool \Rightarrow int \Rightarrow instr \ list$

Example

Let
$$b = And \quad (Less \ (V "x") \ (V "y"))$$

 $(Not \ (Less \ (V "z") \ (V "a"))).$

Example

$$\begin{array}{ll} \mathsf{Let}\ b = \mathit{And}\ \ (\mathit{Less}\ (\mathit{V}\ ''x'')\ (\mathit{V}\ ''y'')) \\ & (\mathit{Not}\ (\mathit{Less}\ (\mathit{V}\ ''z'')\ (\mathit{V}\ ''a''))). \\ b\mathit{comp}\ b\ \mathit{False}\ 3 = \end{array}$$

Let
$$b = And$$
 $(Less (V "x") (V "y"))$
 $(Not (Less (V "z") (V "a"))).$
 $bcomp \ b \ False \ 3 =$
 $[LOAD "x",$

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```

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bcomp \ b \ False \ 3 =
[LOAD "x",
LOAD "y"
LOAD "z"
```

```
Let b = And (Less (V''x'') (V''y''))
               (Not (Less (V "z") (V "a"))).
bcomp \ b \ False \ 3 =
[LOAD "x"]
LOAD "y"
LOAD "z".
LOAD "a".
```

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Let b = And (Less (V''x'') (V''y''))
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bcomp \ b \ False \ 3 =
[LOAD "x"]
LOAD "y"
LOAD "z".
LOAD''a''
```

```
Let b = And (Less (V''x'') (V''y''))
               (Not (Less (V''z'') (V''a''))).
bcomp \ b \ False \ 3 =
[LOAD "x"]
LOAD "y"
JMPGE 6.
LOAD "z".
LOAD''a''
```

```
Let b = And (Less (V''x'') (V''y''))
              (Not (Less (V "z") (V "a"))).
bcomp \ b \ False \ 3 =
[LOAD "x"]
LOAD "y"
LOAD "z",
JMPGE 6,
LOAD "a".
JMPLESS 3
```

 $bcomp\ (Bc\ v)\ f\ n=(if\ v=f\ then\ [JMP\ n]\ else\ [])$

$$bcomp\ (Bc\ v)\ f\ n = (if\ v = f\ then\ [JMP\ n]\ else\ [])$$
 $bcomp\ (Not\ b)\ f\ n = bcomp\ b\ (\neg f)\ n$

$$bcomp \ (Bc \ v) \ f \ n = (if \ v = f \ then \ [JMP \ n] \ else \ [])$$
 $bcomp \ (Not \ b) \ f \ n = bcomp \ b \ (\neg f) \ n$
 $bcomp \ (Less \ a_1 \ a_2) \ f \ n =$

bcomp (Bc v) f $n = (if \ v = f \ then \ [JMP \ n] \ else \ [])$ bcomp (Not b) f $n = bcomp \ b \ (\neg f) \ n$ bcomp (Less $a_1 \ a_2$) f n =acomp $a_1 \ @$ acomp $a_2 \ @$ (if f then $[JMPLESS \ n] \ else \ [JMPGE \ n]$)

bcomp (Bc v) f n = (if v = f then [JMP n] else [])bcomp (Not b) f $n = bcomp b (\neg f) n$ bcomp (Less a_1 a_2) f n =acomp a_1 @ acomp a_2 @ (if f then [JMPLESS n] else [JMPGE n]) bcomp (And b_1 b_2) f n =

 $bcomp\ (Bc\ v)\ f\ n=(\mathit{if}\ v=f\ \mathit{then}\ [\mathit{JMP}\ n]\ \mathit{else}\ [])$



 $bcomp (Less a_1 a_2) f n =$

 $acomp \ a_1 \ @$

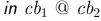
 $acomp \ a_2 \ @ \ (\textit{if} \ f \ \textit{then} \ [\textit{JMPLESS} \ n] \ \textit{else} \ [\textit{JMPGE} \ n])$

 $bcomp (And b_1 b_2) f n =$

 $let cb_2 = bcomp \ b_2 \ f \ n;$

 $m = if f then size cb_2 else size cb_2 + n;$

 $cb_1 = bcomp \ b_1 \ False \ m$







Correctness of bcomp

Correctness of *bcomp*

```
0 \le n \Longrightarrow
bcomp \ b \ f \ n
\vdash (0, \ s, \ stk) \longrightarrow *
(size \ (bcomp \ b \ f \ n) + (if \ f = bval \ b \ s \ then \ n \ else \ 0),
s, \ stk)
```



 $ccomp :: com \Rightarrow instr \ list$

```
ccomp :: com \Rightarrow instr \ list
ccomp \ SKIP = []
```

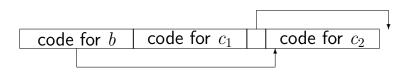
```
ccomp :: com \Rightarrow instr \ list
ccomp \ SKIP = []
```

 $ccomp (x := a) = acomp \ a @ [STORE x]$

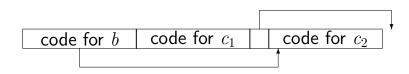
```
ccomp :: com \Rightarrow instr \ list
ccomp \ SKIP = []
ccomp \ (x ::= a) = acomp \ a @ [STORE \ x]
ccomp \ (c_1;; c_2) = ccomp \ c_1 @ ccomp \ c_2
```

 $ccomp (IF \ b \ THEN \ c_1 \ ELSE \ c_2) =$

$ccomp (IF b THEN c_1 ELSE c_2) =$

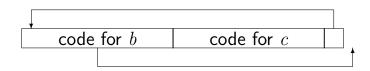


```
ccomp \ (IF \ b \ THEN \ c_1 \ ELSE \ c_2) =
let \ cc_1 = ccomp \ c_1; \ cc_2 = ccomp \ c_2;
cb = bcomp \ b \ False \ (size \ cc_1 + 1)
in \ cb \ @ \ cc_1 \ @ \ JMP \ (size \ cc_2) \ \# \ cc_2
```

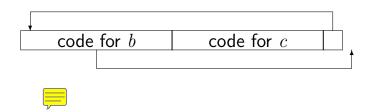


 $ccomp (WHILE \ b \ DO \ c) =$

$ccomp (WHILE \ b \ DO \ c) =$



 $ccomp \ (WHILE \ b \ DO \ c) =$ $let \ cc = ccomp \ c; \ cb = bcomp \ b \ False \ (size \ cc + 1)$ $in \ cb \ @ \ cc \ @ \ [JMP \ (- \ (size \ cb + size \ cc + 1))]$



Correctness of *ccomp*

If the source code produces a certain result, so should the compiled code:

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$$(c, s) \Rightarrow t \Longrightarrow ccomp \ c \vdash (0, s, stk) \rightarrow * (size (ccomp \ c), t, stk)$$

Correctness of *ccomp*

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$$(c, s) \Rightarrow t \Longrightarrow ccomp \ c \vdash (0, s, stk) \rightarrow * (size (ccomp \ c), t, stk)$$

Proof by rule induction.

We have only shown " \Longrightarrow ": compiled code simulates source code.

We have only shown "⇒":

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How about "←":

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If $ccomp\ c$ with start state s produces result t, and if(!) $(c, s) \Rightarrow t'$,

We have only shown "⇒":

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How about "←":

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If $ccomp\ c$ with start state s produces result t, and if(!) $(c,\ s)\Rightarrow t'$, then " \Longrightarrow " implies that $ccomp\ c$ with start state s must also produce t'

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If $ccomp\ c$ with start state s produces result t, and if(!) $(c, s) \Rightarrow t'$, then " \Longrightarrow " implies that $ccomp\ c$ with start state s must also produce t' and thus t' = t (why?).

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If $ccomp\ c$ with start state s produces result t, and if(!) $(c, s) \Rightarrow t'$, then " \Longrightarrow " implies that $ccomp\ c$ with start state s must also produce t' and thus t' = t (why?).

But we have *not* ruled out this potential error:

c does not terminate but ccomp c does.

Two approaches:

In the absence of nondeterminism:
 Prove that ccomp preserves nontermination.

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 Prove that ccomp preserves nontermination.
 A nice proof of this fact requires coinduction.
 Isabelle supports coinduction, this course avoids it.
- A direct proof: theory <u>Compiler2</u>

$$ccomp \ c \vdash (0, s, stk) \rightarrow * (size \ (ccomp \ c), t, stk') \Longrightarrow (c, s) \Rightarrow t$$

Chapter 10

Types

A Typed Version of IMP

A Typed Version of IMP



A Typed Version of IMP Remarks on Type Systems

> Typed IMP: Semantics Typed IMP: Type System Type Safety of Typed IMP

Why Types?

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To prevent mistakes, dummy!

The Good Static types that *guarantee* absence of certain runtime faults.

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Example: no memory access errors in Java.

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Example: C, C++

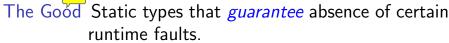
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The Ugly Dynamic types that detect errors when it can be too late.

our focus



Example: no memory access errors in Java.

The Bad Static types that have mostly decorative value but do not guarantee anything at runtime. Example: C. C++

The Ugly Dynamic types that detect errors when it can be too late.

Example: "TypeError: ..." in Python.

The ideal

Well-typed programs cannot go wrong.

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Robin Milner, A Theory of Type Polymorphism in Programming, 1978.

The ideal

Well-typed programs cannot go wrong.

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The most influential slogan and one of the most influential papers in programming language theory.

Corruption of data

- Corruption of data
- Null pointer exception

- Corruption of data
- Null pointer exception
- Nontermination

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- 4 Run out of memory

- Corruption of data
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- and many more . . .

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There are type systems for everything (and more)

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- Null pointer exception
- Nontermination
- 4 Run out of memory
- Secret leaked
- and many more . . .

There are type systems for *everything* (and more) but in practice (Java, C#) only 1 is covered.

Type safety

A programming language is *type safe* if the execution of a well-typed program cannot lead to certain errors.

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Java and the JVM have been *proved* to be type safe. (Note: Java exceptions are not errors!)

Type soundness means that the type system is *sound/correct* w.r.t. the semantics:

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How about completeness?

Correctness and completeness

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How about completeness? Remember Rice:

Nontrivial semantic properties of programs (e.g. termination) are undecidable.

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How about completeness? Remember Rice:

Nontrivial semantic properties of programs (e.g. termination) are undecidable.

Hence there is no (decidable) type system that accepts *all* programs that have a certain semantic property.

Automatic analysis of semantic program properties is necessarily incomplete.

A Typed Version of IMP

Remarks on Type Systems

Typed IMP: Semantics

Typed IMP: Type System
Type Safety of Typed IMP

Arithmetic

Values:

datatype $val = Iv int \mid Rv real$

Arithmetic

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datatype $val = Iv int \mid Rv real$

The state:

 $state = vname \Rightarrow val$

Arithmetic

```
Values:
```

```
datatype val = Iv int \mid Rv real
```

The state:



```
state = vname \Rightarrow val
```

Arithmetic expresssions:

```
\begin{array}{l} \textbf{datatype} \ \ aexp = \\ Ic \ int \mid Rc \ real \mid V \ vname \mid Plus \ aexp \ aexp \end{array}
```

Because we want to detect if things "go wrong".

Because we want to detect if things "go wrong". What can go wrong?

Because we want to detect if things "go wrong". What can go wrong? Adding integer and real!

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Tags are only used to detect certain errors

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No! Compilers compile only well-typed programs, and well-typed programs do not need tags.

Tags are only used to detect certain errors and to prove that the type system avoids those errors.

$$taval :: aexp \Rightarrow state \Rightarrow val \Rightarrow bool$$

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 $taval (Ic i) s (Iv i)$

$$taval :: aexp \Rightarrow state \Rightarrow val \Rightarrow bool$$

 $taval (Ic \ i) \ s \ (Iv \ i)$
 $taval \ (Rc \ r) \ s \ (Rv \ r)$

$$taval :: aexp \Rightarrow state \Rightarrow val \Rightarrow bool$$

$$taval (Ic i) s (Iv i)$$

$$taval (Rc r) s (Rv r)$$

$$taval (V x) s (s x)$$

$$taval :: aexp \Rightarrow state \Rightarrow val \Rightarrow bool$$

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$$taval (V x) s (s x)$$

$$taval a_1 s (Iv i_1) taval a_2 s (Iv i_2)$$

$$taval (Plus a_1 a_2) s (Iv (i_1 + i_2))$$

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$$taval a_1 s (Rv r_1) taval a_2 s (Rv r_2)$$

$$taval (Plus a_1 a_2) s (Rv (r_1 + r_2))$$

Example: evaluation of Plus (V "x") (Ic 1)

If s''x'' = Iv i:

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taval (Plus (V''x'') (Ic 1)) s

If s''x'' = Iv i:

taval (V''x'') s

taval (Plus (V "x") (Ic 1)) s

```
If s "x" = Iv i:

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```

taval (Plus (V''x'') (Ic 1)) s

```
Example: evaluation of Plus (V''x'') (Ic 1)

If s''x'' = Iv i:

\frac{taval (V''x'') s (Iv i)}{taval (Plus (V''x'') (Ic 1)) s}
```

```
Example: evaluation of Plus (V "x") (Ic 1)

If s "x" = Iv i:
\frac{taval (V "x") s (Iv i) taval (Ic 1) s (Iv 1)}{taval (Plus (V "x") (Ic 1)) s}
```

```
Example: evaluation of Plus(V''x'')(Ic\ 1)

If s''x'' = Iv\ i:
\frac{taval(V''x'')s(Iv\ i)}{taval(Plus(V''x'')(Ic\ 1))s(Iv(i+1))}
```

```
Example: evaluation of Plus\ (V\ ''x'')\ (Ic\ 1)

If s\ ''x''=Iv\ i:
\frac{taval\ (V\ ''x'')\ s\ (Iv\ i)\quad taval\ (Ic\ 1)\ s\ (Iv\ 1)}{taval\ (Plus\ (V\ ''x'')\ (Ic\ 1))\ s\ (Iv(i+1))}

If s\ ''x''=Rv\ r:
```



If
$$s''x'' = Iv i$$
:

$$\frac{taval \left(V "x"\right) \ s \ (Iv \ i)}{taval \left(Plus \left(V "x"\right) \ (Ic \ 1)\right) \ s \ (Iv \ i + 1))}$$

If s "x" = Rv r: then there is *no* value v such that $taval\ (Plus\ (V$ "x") $(Ic\ 1))$ s v.

The functional alternative

 $taval :: aexp \Rightarrow state \Rightarrow val \ option$

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 $taval :: aexp \Rightarrow state \Rightarrow val \ option$

Exercise!

Boolean expressions

Syntax as before. Semantics:

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$$tbval (Bc v) s v \qquad \frac{tbval \ b \ s \ bv}{tbval \ (Not \ b) \ s \ (\neg \ bv)}$$

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$$\frac{taval \ a_1 \ s \ (Iv \ i_1) \quad taval \ a_2 \ s \ (Iv \ i_2)}{tbval \ (Less \ a_1 \ a_2) \ s \ (i_1 < i_2)}$$

$$tbval :: bexp \Rightarrow state \Rightarrow bool \Rightarrow bool$$

$$tbval (Bc v) s v \qquad \frac{tbval b s bv}{tbval (Not b) s (\neg bv)}$$

$$\frac{tbval b_1 s bv_1}{tbval (And b_1 b_2) s (bv_1 \land bv_2)}$$

$$\frac{taval a_1 s (Iv i_1)}{tbval (Less a_1 a_2) s (i_1 < i_2)}$$

$$\frac{taval a_1 s (Rv r_1)}{tbval (Less a_1 a_2) s (r_1 < r_2)}$$

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Big step semantics:
 Cannot model error by absence of final state.

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 Could introduce an extra error-element, e.g.
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 Cannot model error by absence of final state.
 Would confuse error and nontermination.
 Could introduce an extra error-element, e.g.
 big_step :: com × state ⇒ state option ⇒ bool
 Complicates formalization.

We need to detect if things "go wrong".

- Big step semantics:
 Cannot model error by absence of final state.
 Would confuse type
 Firor and nontermination.
 Could introduce an extra error-element, e.g.
 big_step :: com × state ⇒ state option ⇒ bool
 Complicates formalization.
- Small step semantics:
 error = semantics gets stuck

$$\frac{taval\ a\ s\ v}{(x::=\ a,\ s)\ \rightarrow\ (\mathit{SKIP},\ s(x:=\ v))}$$

$$\frac{taval\ a\ s\ v}{(x::=\ a,\ s)\ \rightarrow\ (SKIP,\ s(x:=\ v))}$$

tbval b s True

(IF b THEN c_1 ELSE c_2 , s) \rightarrow (c_1 , s)

$$\frac{taval\ a\ s\ v}{(x::=\ a,\ s)\ \rightarrow\ (SKIP,\ s(x:=\ v))}$$

$$\frac{tbval\ b\ s\ True}{(IF\ b\ THEN\ c_1\ ELSE\ c_2,\ s) \to (c_1,\ s)}$$

$$\frac{tbval\ b\ s\ False}{(IF\ b\ THEN\ c_1\ ELSE\ c_2,\ s)\ \rightarrow\ (c_2,\ s)}$$

$$\frac{taval\ a\ s\ v}{(x:=a,\ s)\rightarrow (SKIP,\ s(x:=v))}$$

$$\frac{tbval\ b\ s\ True}{(IF\ b\ THEN\ c_1\ ELSE\ c_2,\ s)\rightarrow (c_1,\ s)}$$

$$\frac{tbval\ b\ s\ False}{(IF\ b\ THEN\ c_1\ ELSE\ c_2,\ s) \to (c_2,\ s)}$$

The other rules remain unchanged.



Let
$$c = ("x" ::= Plus (V "x") (Ic 1)).$$

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• If
$$s$$
 " x " = $Iv i$:
 $(c, s) \rightarrow (SKIP, s("x" := Iv (i + 1)))$

Let
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- If s "x" = Iv i: $(c, s) \to (SKIP, s("x" := Iv (i + 1)))$
- If s''x'' = Rv r:

```
Let c = ("x" ::= Plus (V "x") (Ic 1)).
```

- If s "x" = Iv i: $(c, s) \to (SKIP, s("x" := Iv (i + 1)))$
- If s "x" = Rv r: $(c, s) \not\rightarrow$

A Typed Version of IMP

Remarks on Type Systems Typed IMP: Semantics Typed IMP: Type System Type Safety of Typed IMP

There are two types:

datatype $ty = Ity \mid Rty$

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```
\mathbf{datatype} \ ty = Ity \mid Rty
```

What is the type of Plus(V''x'')(V''y'')?

There are two types:

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datatype ty = Ity \mid Rty
What is the type of Plus (V "x") (V "y")?
Depends on the type of "x" and "y"!
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A *type environment* maps variable names to their types: $tyenv = vname \Rightarrow ty$

There are two types:

datatype
$$ty = Ity \mid Rty$$

What is the type of Plus (V''x'') (V''y'') ?

Depends on the type of "x" and "y"!

A type environment maps variable names to their types:

$$tyenv = vname \Rightarrow ty$$

The type of an expression is always relative to a type environment Γ . Standard notation:

$$\Gamma \vdash e : \tau$$

Read: In the context of Γ , e has type τ



$$\Gamma \vdash a : \tau$$

 $\Gamma \vdash a : \tau$ $tyenv \vdash aexp : ty$

$$\Gamma \vdash a : \tau$$
$$tyenv \vdash aexp : ty$$

$$\Gamma \vdash \mathit{Ic}\ i : \mathit{Ity}$$

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$$tyenv \vdash aexp : ty$$

$$\Gamma \vdash \mathit{Ic}\ i : \mathit{Ity}$$

$$\Gamma \vdash Rc \ r : Rty$$

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$$\Gamma \vdash Ic \ i : Ity$$
$$\Gamma \vdash Rc \ r : Rty$$
$$\Gamma \vdash V \ x : \Gamma \ x$$



$$\Gamma \vdash a : \tau$$
$$tyenv \vdash aexp : ty$$

$$\Gamma \vdash Ic \ i : Ity$$

$$\Gamma \vdash Rc \ r : Rty$$

$$\Gamma \vdash V \ x : \Gamma \ x$$

$$\frac{\Gamma \vdash a_1 : \tau \qquad \Gamma \vdash a_2 : \tau}{\Gamma \vdash Plus \ a_1 \ a_2 : \tau}$$

 $\frac{\vdots}{\Gamma \vdash Plus\;(V\;''x'')\;(Plus\;(V\;''x'')\;(Ic\;0))\;:\;?}$ where $\Gamma\;''x''=\mathit{Ity}.$

Well-typed bexp

Notation:

$$\Gamma \vdash b$$

Well-typed bexp

Notation:

$$\begin{array}{c} \Gamma \vdash b \\ tyenv \vdash bexp \end{array}$$

Well-typed bexp

Notation:

$$\begin{array}{c} \Gamma \vdash b \\ tyenv \vdash bexp \end{array}$$

Read: In context Γ , b is well-typed.

$$\Gamma \vdash Bc \ v$$

$$\frac{\Gamma \vdash Bc \ v}{\Gamma \vdash Not \ b}$$

$$\Gamma \vdash Bc \ v$$

$$\frac{\Gamma \vdash b}{\Gamma \vdash Not \ b}$$

$$\frac{\Gamma \vdash b_1 \qquad \Gamma \vdash b_2}{\Gamma \vdash And \ b_1 \ b_2}$$

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$$\frac{\Gamma \vdash b_1 \quad \Gamma \vdash b_2}{\Gamma \vdash And \ b_1 \ b_2}$$

$$\frac{\Gamma \vdash a_1 : \tau \quad \Gamma \vdash a_2 : \tau}{\Gamma \vdash Less \ a_1 \ a_2}$$

$$\Gamma \vdash Bc \ v$$

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$$\frac{\Gamma \vdash a_1 : \tau \quad \Gamma \vdash a_2 : \tau}{\Gamma \vdash Less \ a_1 \ a_2}$$

 $\Gamma \vdash Less \ a_1 \ a_2$

Example: $\Gamma \vdash Less (Ic \ i) (Rc \ r)$ does not hold.

Well-typed commands

Notation:

$$\Gamma \vdash c$$

Well-typed commands

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$$\begin{array}{c} \Gamma \vdash c \\ tyenv \vdash com \end{array}$$

Well-typed commands

Notation:

$$\Gamma \vdash c$$
$$tyenv \vdash com$$

Read: In context Γ , c is well-typed.

 $\Gamma \vdash SKIP$

$$\Gamma \vdash SKIP \qquad \frac{\Gamma \vdash a : \Gamma x}{\Gamma \vdash x ::= a}$$

$$\Gamma \vdash SKIP \qquad \frac{\Gamma \vdash a : \Gamma x}{\Gamma \vdash x ::= a}$$

$$\frac{\Gamma \vdash c_1 \qquad \Gamma \vdash c_2}{\Gamma \vdash c_1 :; c_2}$$

$$\Gamma \vdash SKIP \qquad \frac{\Gamma \vdash a : \Gamma x}{\Gamma \vdash x ::= a}$$

$$\frac{\Gamma \vdash c_1 \qquad \Gamma \vdash c_2}{\Gamma \vdash c_1 :; c_2}$$

$$\frac{\Gamma \vdash b \qquad \Gamma \vdash c_1 \qquad \Gamma \vdash c_2}{\Gamma \vdash IF \ b \ THEN \ c_1 \ ELSE \ c_2}$$

$$\Gamma \vdash SKIP$$

$$\frac{\Gamma \vdash a : \Gamma x}{\Gamma \vdash x ::= a}$$

$$\frac{\Gamma \vdash c_1 \qquad \Gamma \vdash c_2}{\Gamma \vdash c_1;; \ c_2}$$



$$\frac{\Gamma \vdash b \qquad \Gamma \vdash c_1 \qquad \Gamma \vdash c_2}{\Gamma \vdash \mathit{IF} \ b \ \mathit{THEN} \ c_1 \ \mathit{ELSE} \ c_2}$$

$$\frac{\Gamma \vdash b \qquad \Gamma \vdash c}{\Gamma \vdash WHILE \ b \ DO \ c}$$

All three sets of typing rules are *syntax-directed*:

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• There is exactly one rule for each syntactic construct (*SKIP*, ::=, ...).

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All three sets of typing rules are *syntax-directed*:

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A syntax-directed set of rules

is executable by backchaining without backtracking

All three sets of typing rules are *syntax-directed*:

- There is exactly one rule for each syntactic construct (*SKIP*, ::=, ...).
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A syntax-directed set of rules

- is executable by backchaining without backtracking and
- backchaining terminates d requires at most as many steps as the size of the term.

The big-step semantics is not syntax-directed:

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The big-step semantics is not syntax-directed:

- more than one rule per construct and
- the execution of WHILE depends on the execution of WHILE.

A Typed Version of IMP



Remarks on Type Systems Typed IMP: Semantics Typed IMP: Type System Type Safety of Typed IMP



Even well-typed programs can get stuck ...

```
Even well-typed programs can get stuck ... if they start in an unsuitable state.
```

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Remember:
If s "x" = Rv \ r
then ("x" ::= Plus \ (V "x") \ (Ic \ 1), \ s) \not\rightarrow
```

```
Even well-typed programs can get stuck ... ... if they start in an unsuitable state.
```

Remember:

```
If s "x" = Rv r
then ("x" ::= Plus (V "x") (Ic 1), s) \nrightarrow
```

The state must be well-typed w.r.t. Γ .

The type of a value:

$$type (Iv i) = Ity$$

 $type (Rv r) = Rty$

The type of a value:

$$type (Iv i) = Ity$$
$$type (Rv r) = Rty$$

Well-typed state:

$$\Gamma \vdash s \longleftrightarrow (\forall x. \ type \ (s \ x) = \Gamma \ x)$$

Reduction cannot get stuck:

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If everything is ok ($\Gamma \vdash s$, $\Gamma \vdash c$),

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If everything is ok ($\Gamma \vdash s$, $\Gamma \vdash c$), and you take a finite number of steps,

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If everything is ok ($\Gamma \vdash s$, $\Gamma \vdash c$), and you take a finite number of steps, and you have not reached SKIP,

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If everything is ok ($\Gamma \vdash s$, $\Gamma \vdash c$), and you take a finite number of steps, and you have not reached SKIP, then you can take one more step.

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Follows from *progress*:

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If everything is ok ($\Gamma \vdash s$, $\Gamma \vdash c$), and you take a finite number of steps, and you have not reached SKIP, then you can take one more step.

Follows from *progress*:

If everything is ok and you have not reached SKIP, then you can take one more step.

Reduction cannot get stuck:

If everything is ok ($\Gamma \vdash s$, $\Gamma \vdash c$), and you take a finite number of steps, and you have not reached SKIP, then you can take one more step.

Follows from *progress*:

If everything is ok and you have not reached SKIP, then you can take one more step.

and *preservation*:

Reduction cannot get stuck:

If everything is ok ($\Gamma \vdash s$, $\Gamma \vdash c$), and you take a finite number of steps, and you have not reached SKIP, then you can take one more step.

Follows from *progress*:

If everything is ok and you have not reached SKIP, then you can take one more step.

and preservation:

If everything is ok and you take a step, then everything is ok again.

Progress \land Preservation \Longrightarrow Type safety

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Progress Well-typed programs do not get stuck.

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Preservation Well-typedness is preserved by reduction.

Progress \land Preservation \Longrightarrow Type safety

Progress Well-typed programs do not get stuck.

Preservation Well-typedness is preserved by reduction.

Preservation: Well-typedness is an *invariant*.

com

Progress:

$$\llbracket \Gamma \vdash c; \ \Gamma \vdash s; \ c \neq \mathit{SKIP} \rrbracket \Longrightarrow \exists \ \mathit{cs'}. \ (c, \ s) \rightarrow \mathit{cs'}$$

Progress:

$$\llbracket \Gamma \vdash c; \Gamma \vdash s; c \neq SKIP \rrbracket \Longrightarrow \exists cs'. (c, s) \rightarrow cs'$$

Preservation:

$$\llbracket (c, s) \to (c', s'); \Gamma \vdash c; \Gamma \vdash s \rrbracket \Longrightarrow \Gamma \vdash s'$$

$$\llbracket (c, s) \rightarrow (c', s'); \Gamma \vdash c \rrbracket \Longrightarrow \Gamma \vdash c'$$

Progress:

$$\llbracket \Gamma \vdash c; \Gamma \vdash s; c \neq SKIP \rrbracket \Longrightarrow \exists cs'. (c, s) \rightarrow cs'$$

Preservation:

$$\llbracket (c, s) \to (c', s'); \Gamma \vdash c; \Gamma \vdash s \rrbracket \Longrightarrow \Gamma \vdash s'$$

$$\llbracket (c, s) \to (c', s'); \Gamma \vdash c \rrbracket \Longrightarrow \Gamma \vdash c'$$

Type soundness:

$$[(c, s) \to * (c', s'); \Gamma \vdash c; \Gamma \vdash s; c' \neq SKIP]]$$

$$\Longrightarrow \exists cs''. (c', s') \to cs''$$

bexp

Progress:

$$\llbracket \Gamma \vdash b; \ \Gamma \vdash s \rrbracket \Longrightarrow \exists \ v. \ tbval \ b \ s \ v$$

aexp

Progress:

$$\llbracket \Gamma \vdash a : \tau; \Gamma \vdash s \rrbracket \Longrightarrow \exists v. \ taval \ a \ s \ v$$

Preservation:

$$\llbracket \Gamma \vdash a : \tau; \ taval \ a \ s \ v; \ \Gamma \vdash s \rrbracket \implies type \ v = \tau$$

All proofs by rule induction.



Types.thy

The mantra

Type systems have a purpose:

The static analysis of programs in order to predict their runtime behaviour.

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Type systems have a purpose:

The static analysis of programs in order to predict their runtime behaviour.

The correctness of the prediction must be provable.

Chapter 11

Data-Flow Analyses and Optimization

① Definite Initialization Analysis

Live Variable Analysis

① Definite Initialization Analysis

Live Variable Analysis

Each local variable must have a definitely assigned value when any access of its value occurs. A compiler must carry out a specific conservative flow analysis to make sure that, for every access of a local variable x, x is definitely assigned before the access; otherwise a compile-time error must occur.

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Java Language Specification

Each local variable must have a definitely assigned value when any access of its value occurs. A compiler must carry out a specific conservative flow analysis to make sure that, for every access of a local variable x, x is definitely assigned before the access; otherwise a compile-time error must occur.

Java Language Specification

Java was the first language to force programmers to initialize their variables.

Assume x is initialized:

```
IF x < 1 THEN y := x ELSE y := x + 1; y := y + 1
```

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```
IF x < 1 THEN y := x ELSE y := x + 1;
y := y + 1
IF x < x THEN y := y + 1 ELSE y := x
```



Assume x is initialized:

IF
$$x < 1$$
 THEN $y := x$ ELSE $y := x + 1$; $y := y + 1$

IF
$$x < x$$
 THEN $y := y + 1$ ELSE $y := x$

Assume x and y are initialized:

WHILE
$$x < y DO z := x; z := z + 1$$

Simplifying principle

We do not analyze boolean expressions to determine program execution.

Definite Initialization Analysis
 Prelude: Variables in Expressions
 Definite Initialization Analysis
 Initialization Sensitive Semantics

 $vars :: aexp \Rightarrow vname \ set$

```
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vars \ (N \ n) = \{\}

vars \ (V \ x) = \{x\}

vars \ (Plus \ a_1 \ a_2) = vars \ a_1 \cup vars \ a_2
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vars(N n) = \{\}
vars (V x) = \{x\}
vars (Plus \ a_1 \ a_2) = vars \ a_1 \cup vars \ a_2
vars :: bexp \Rightarrow vname set
vars (Bc \ v) = \{\}
vars (Not b) = vars b
vars (And b_1 b_2) = vars b_1 \cup vars b_2
vars (Less a_1 a_2) = vars a_1 \cup vars a_2
```

Vars.thy



Definite Initialization Analysis
 Prelude: Variables in Expressions
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Modified example from the JLS:

Variable x is definitely initialized after SKIP iff x is definitely initialized before SKIP.

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Variable x is definitely initialized after SKIP iff x is definitely initialized before SKIP.



Similar statements for each language construct.

 $D:: vname \ set \Rightarrow com \Rightarrow vname \ set \Rightarrow bool$

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D A c A' should imply:

 $D:: vname \ set \Rightarrow com \Rightarrow vname \ set \Rightarrow bool$

D A c A' should imply:

If all variables in A are initialized before c is executed,

 $D:: vname \ set \Rightarrow com \Rightarrow vname \ set \Rightarrow bool$

D A c A' should imply:

If all variables in A are initialized before c is executed, then no uninitialized variable is accessed during execution,

 $D:: vname \ set \Rightarrow com \Rightarrow vname \ set \Rightarrow bool$

D A c A' should imply:

If all variables in A are initialized before c is executed, then no uninitialized variable is accessed during execution, and all variables in A' are initialized afterwards.

D A SKIP A

D A SKIP A

 $vars \ a \subseteq A$

D A (x := a) (insert x A)

$D \ A \ SKIP \ A$ $vars \ a \subseteq A$ $\overline{D \ A \ (x ::= a) \ (insert \ x \ A)}$ $\underline{D \ A_1 \ c_1 \ A_2 \quad D \ A_2 \ c_2 \ A_3}$ $\overline{D \ A_1 \ (c_1;; \ c_2) \ A_3}$

$$\begin{array}{c} D \ A \ SKIP \ A \\ \hline vars \ a \subseteq A \\ \hline D \ A \ (x ::= a) \ (insert \ x \ A) \\ \hline \underline{D \ A_1 \ c_1 \ A_2 \quad D \ A_2 \ c_2 \ A_3} \\ \hline D \ A_1 \ (c_1;; \ c_2) \ A_3 \\ \hline \hline vars \ b \subseteq A \quad D \ A \ c_1 \ A_1 \quad D \ A \ c_2 \ A_2 \\ \hline D \ A \ (IF \ b \ THEN \ c_1 \ ELSE \ c_2) \ (A_1 \ \cap A_2) \end{array}$$



D A SKIP A

$$vars \ a \subseteq A$$

$$\overline{D \ A \ (x ::= a) \ (insert \ x \ A)}$$

$$\underline{D \ A_1 \ c_1 \ A_2 \quad D \ A_2 \ c_2 \ A_3}$$

$$\overline{D \ A_1 \ (c_1;; \ c_2) \ A_3}$$

$$\underline{vars \ b \subseteq A \quad D \ A \ c_1 \ A_1 \quad D \ A \ c_2 \ A_2}$$

$$\overline{D \ A \ (IF \ b \ THEN \ c_1 \ ELSE \ c_2) \ (A_1 \cap A_2)}$$

$$\underline{vars \ b \subseteq A \quad D \ A \ c \ A'}$$

$$\overline{D \ A \ (WHILE \ b \ DO \ c) \ A}$$

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- Things can go wrong: execution may access uninitialized variable.
 - ⇒ We need a new, finer-grained semantics.
- Big step semantics: semantics longer, correctness proof shorter
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For variety's sake, we choose a big step semantics.

Definite Initialization Analysis
 Prelude: Variables in Expres

Prelude: Variables in Expressions
Definite Initialization Analysis
Initialization Sensitive Semantics

where

 $\textbf{datatype} \ 'a \ option = None \mid Some \ 'a$

where

datatype $'a \ option = None \mid Some \ 'a$

Notation: $s(x \mapsto y)$ means s(x := Some y)

where

datatype 'a
$$option = None \mid Some 'a$$

Notation: $s(x \mapsto y)$ means s(x := Some y)



Definition: $dom \ s = \{a. \ s \ a \neq None\}$

 $aval :: aexp \Rightarrow state \Rightarrow val \ option$

```
aval :: aexp \Rightarrow state \Rightarrow val \ option
aval \ (N \ i) \ s = Some \ i
```

```
aval :: aexp \Rightarrow state \Rightarrow val \ option

aval \ (N \ i) \ s = Some \ i

aval \ (V \ x) \ s = s \ x
```



```
aval :: aexp \Rightarrow state \Rightarrow val \ option
aval(N i) s = Some i
aval(Vx)s = sx
aval (Plus \ a_1 \ a_2) \ s =
(case (aval a_1 s, aval a_2 s) of
   (Some \ i_1, Some \ i_2) \Rightarrow Some(i_1+i_2)
 | \  \Rightarrow None \rangle
```

 $bval :: bexp \Rightarrow state \Rightarrow bool \ option$

$bval :: bexp \Rightarrow state \Rightarrow bool \ option$ $bval \ (Bc \ v) \ s = Some \ v$

```
bval :: bexp \Rightarrow state \Rightarrow bool \ option

bval \ (Bc \ v) \ s = Some \ v

bval \ (Not \ b) \ s =

(case \ bval \ b \ s \ of \ None \Rightarrow None

| \ Some \ bv \Rightarrow Some \ (\neg \ bv))
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bval :: bexp \Rightarrow state \Rightarrow bool option
bval(Bc\ v)\ s = Some\ v
bval (Not b) s =
(case bval\ b\ s\ of\ None \Rightarrow None
 | Some \ bv \Rightarrow Some \ (\neg \ bv))
bval (And b_1 b_2) s =
(case (bval b_1 s, bval b_2 s) of
   (Some \ bv_1, Some \ bv_2) \Rightarrow Some(bv_1 \land bv_2)
 | \  \Rightarrow None \rangle
```

$bval :: bexp \Rightarrow state \Rightarrow bool \ option$ $bval \ (Bc \ v) \ s = Some \ v$



bval (Not b) s = $(case \ bval \ b \ s \ of \ None \Rightarrow None$ $| \ Some \ bv \Rightarrow Some \ (\neg \ bv))$

 $bval\ (And\ b_1\ b_2)\ s =$ $(case\ (bval\ b_1\ s,\ bval\ b_2\ s)\ of$ $(Some\ bv_1,\ Some\ bv_2) \Rightarrow Some(bv_1\ \land\ bv_2)$ $|\ _- \Rightarrow None)$

 $bval\ (Less\ a_1\ a_2)\ s =$ $(case\ (aval\ a_1\ s,\ aval\ a_2\ s)\ of$ $(Some\ i_1,\ Some\ i_2) \Rightarrow Some(i_1 < i_2)$ $|\ _ \Rightarrow None)$

 $(com, state) \Rightarrow state option$

$$(com, state) \Rightarrow state option$$

A small complication:

$$\frac{(c_1, s_1) \Rightarrow Some \ s_2 \quad (c_2, s_2) \Rightarrow s}{(c_1;; c_2, s_1) \Rightarrow s}$$

$$(com, state) \Rightarrow state option$$

A small complication:

$$\frac{(c_1, s_1) \Rightarrow Some \ s_2 \quad (c_2, s_2) \Rightarrow s}{(c_1;; c_2, s_1) \Rightarrow s}$$

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$$\frac{(c_1, s_1) \Rightarrow None}{(c_1;; c_2, s_1) \Rightarrow None}$$

More convenient, because compositional:

 $(com, state option) \Rightarrow state option$



 $(c, None) \Rightarrow None$

$$(c, None) \Rightarrow None$$

$$(SKIP, s) \Rightarrow s$$

$$(c, None) \Rightarrow None$$

$$(SKIP, s) \Rightarrow s$$

$$aval \ a \ s = Some \ i$$

$$(x := a, Some \ s) \Rightarrow Some \ (s(x \mapsto i))$$

$$(c, None) \Rightarrow None$$

$$(SKIP, s) \Rightarrow s$$

$$aval \ a \ s = Some \ i$$

$$(x ::= a, Some \ s) \Rightarrow Some \ (s(x \mapsto i))$$

$$aval \ a \ s = None$$

$$(x ::= a, Some \ s) \Rightarrow None$$

$$(c, None) \Rightarrow None$$

$$(SKIP, s) \Rightarrow s$$

$$\frac{aval\ a\ s = Some\ i}{(x ::= a,\ Some\ s) \Rightarrow Some\ (s(x \mapsto i))}$$

$$\frac{aval\ a\ s = None}{(x ::= a,\ Some\ s) \Rightarrow None}$$

$$\frac{(c_1, s_1) \Rightarrow s_2 \quad (c_2, s_2) \Rightarrow s_3}{(c_1;; c_2, s_1) \Rightarrow s_3}$$



$\frac{bval\ b\ s = Some\ True \quad (c_1,\ Some\ s) \Rightarrow s'}{(IF\ b\ THEN\ c_1\ ELSE\ c_2,\ Some\ s) \Rightarrow s'}$

$$\frac{bval\ b\ s = Some\ True \qquad (c_1,\ Some\ s) \Rightarrow s'}{(IF\ b\ THEN\ c_1\ ELSE\ c_2,\ Some\ s) \Rightarrow s'}$$

$$\frac{bval\ b\ s = Some\ False}{(IF\ b\ THEN\ c_1\ ELSE\ c_2,\ Some\ s) \Rightarrow s'}$$

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$$\frac{bval\ b\ s = Some\ False \qquad (c_2,\ Some\ s) \Rightarrow s'}{(IF\ b\ THEN\ c_1\ ELSE\ c_2,\ Some\ s) \Rightarrow s'}$$

$$\frac{bval\ b\ s = None}{(IF\ b\ THEN\ c_1\ ELSE\ c_2,\ Some\ s) \Rightarrow None}$$

$\frac{\textit{bval b } s = \textit{Some False}}{\textit{(WHILE b DO c, Some s)} \Rightarrow \textit{Some s}}$

$\frac{\textit{bval b s} = \textit{Some False}}{(\textit{WHILE b DO c, Some s}) \Rightarrow \textit{Some s}}$

$$bval \ b \ s = Some \ True$$

$$(c, Some \ s) \Rightarrow s' \quad (WHILE \ b \ DO \ c, \ s') \Rightarrow s''$$

$$(WHILE \ b \ DO \ c, Some \ s) \Rightarrow s''$$

$$\frac{bval\ b\ s = Some\ False}{(\textit{WHILE}\ b\ DO\ c,\ Some\ s) \Rightarrow Some\ s}$$

$$bval \ b \ s = Some \ True$$

$$(c, Some \ s) \Rightarrow s' \quad (WHILE \ b \ DO \ c, \ s') \Rightarrow s''$$

$$(WHILE \ b \ DO \ c, Some \ s) \Rightarrow s''$$

$$\frac{\textit{bval b } s = \textit{None}}{(\textit{WHILE b DO c, Some s}) \Rightarrow \textit{None}}$$

We want in the end:

Well-initialized programs cannot go wrong.

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If D (dom s) c A' and $(c, Some s) \Rightarrow s'$ then $s' \neq None$.

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If D (dom s) c A' and $(c, Some s) \Rightarrow s'$ then $s' \neq None$.

We need to prove a generalized statement:

If $(c, Some \ s) \Rightarrow s'$ and $D \ A \ c \ A'$ and $A \subseteq dom \ s$ then $\exists \ t. \ s' = Some \ t \land A' \subseteq dom \ t.$

We want in the end:

Well-initialized programs cannot go wrong.

If
$$D$$
 (dom s) c A' and $(c, Some s) \Rightarrow s'$ then $s' \neq None$.

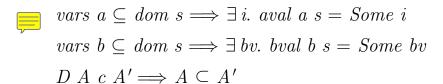
We need to prove a generalized statement:

If
$$(c, Some \ s) \Rightarrow s'$$
 and $D \ A \ c \ A'$ and $A \subseteq dom \ s$ then $\exists \ t. \ s' = Some \ t \land A' \subseteq dom \ t.$



By rule induction on $(c, Some \ s) \Rightarrow s'$.

Proof needs some easy lemmas:



Definite Initialization Analysis

Live Variable Analysis

Consider the following program:

```
x := y + 1;

y := y + 2;

x := y + 3
```

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```
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y := y + 2;

x := y + 3
```

Consider the following program:

```
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y := y + 2;

x := y + 3
```

The first assignment is redundant and can be removed

Consider the following program:

```
x := y + 1;

y := y + 2;

x := y + 3
```

The first assignment is redundant and can be removed because x is dead at that point.

A weaker but easier to check condition:

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We call x *live* before c if there is some potential execution of c where x is read before it can be overwritten.

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We call x *live* before c if there is some potential execution of c where x is read before it can be overwritten. Implicitly, every variable is read at the end of c.

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Examples: Is x initially dead or live?

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We call x *live* before c if there is some potential execution of c where x is read before it can be overwritten. Implicitly, every variable is read at the end of c.

Examples: Is x initially dead or live? x := 0

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We call x *live* before c if there is some potential execution of c where x is read before it can be overwritten. Implicitly, every variable is read at the end of c.

Examples: Is x initially dead or live?

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We call x *live* before c if there is some potential execution of c where x is read before it can be overwritten. Implicitly, every variable is read at the end of c.

Examples: Is x initially dead or live?

$$x := 0$$

$$y := x; y := 0; x := 0$$



A weaker but easier to check condition:

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```
Examples: Is x initially dead or live?

x := 0 \\y := x; y := 0; x := 0 \\width WHILE b DO y := x; x := 1
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We call x *live* before c if there is some potential execution of c where x is read before it can be overwritten. Implicitly, every variable is read at the end of c.



Examples: Is x initially dead or live?

WHILE b DO
$$y := x; x := 1$$



At the end of a command, we may be interested in the value of *only some of the variables*,

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At the end of a command, we may be interested in the value of *only some of the variables*, e.g. *only the global variables* at the end of a procedure.

Then we say that x is live before c relative to the set of variables X.



 $L:: com \Rightarrow vname \ set \Rightarrow vname \ set$

 $L:: com \Rightarrow vname \ set \Rightarrow vname \ set$

 $L \ c \ X =$ live before c relative to X



 $L:: com \Rightarrow vname \ set \Rightarrow vname \ set$ $L \ c \ X \ = \ \mbox{live before} \ c \ \mbox{relative to} \ X$ $L \ SKIP \ X \ = \ \mbox{live before} \ c \ \mbox{relative} \ \mbox{to} \ X$

 $L:: com \Rightarrow vname \ set \Rightarrow vname \ set$ $L \ c \ X \ = \ \mbox{live before} \ c \ \mbox{relative to} \ X$ $L \ SKIP \ X \ = \ X$

 $L:: com \Rightarrow vname \ set \Rightarrow vname \ set$

 $L \ c \ X =$ live before c relative to X

$$L SKIP X = X$$

$$L (x := a) X =$$

$$L:: com \Rightarrow vname \ set \Rightarrow vname \ set$$

$$L \ c \ X =$$
 live before c relative to X

$$L SKIP X = X$$

$$L (x := a) X = vars a \cup (X - \{x\})$$



 $L:: com \Rightarrow vname \ set \Rightarrow vname \ set$

 $L \ c \ X =$ live before c relative to X

$$L SKIP X = X$$

$$L (x := a) X = vars a \cup (X - \{x\})$$

$$L (c_1;; c_2) X =$$

 $L:: com \Rightarrow vname \ set \Rightarrow vname \ set$

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 $L \ (c_1;; c_2) \ X = L \ c_1 \ (L \ c_2 \ X)$

 $L::com \Rightarrow vname\ set \Rightarrow vname\ set$

 $L \ c \ X =$ live before c relative to X

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 $L \ (x := a) \ X = vars \ a \cup (X - \{x\})$
 $L \ (c_1;; c_2) \ X = L \ c_1 \ (L \ c_2 \ X)$
 $L \ (IF \ b \ THEN \ c_1 \ ELSE \ c_2) \ X =$

 $L:: com \Rightarrow vname \ set \Rightarrow vname \ set$ $L \ c \ X =$ live before c relative to XL SKIP X = X $L (x := a) X = vars a \cup (X - \{x\})$ $L(c_1;; c_2) X = L c_1 (L c_2 X)$ $L (IF b THEN c_1 ELSE c_2) X =$ vars $b \cup L c_1 X \cup L c_2 X$

 $L:: com \Rightarrow vname \ set \Rightarrow vname \ set$

 $L \ c \ X =$ live before c relative to X

$$L \ SKIP \ X = X$$

 $L \ (x := a) \ X = vars \ a \cup (X - \{x\})$
 $L \ (c_1;; c_2) \ X = L \ c_1 \ (L \ c_2 \ X)$
 $L \ (IF \ b \ THEN \ c_1 \ ELSE \ c_2) \ X = vars \ b \cup L \ c_1 \ X \cup L \ c_2 \ X$

Example:

$$L ("y" ::= V "z";; "x" ::= Plus (V "y") (V "z"))$$

 $\{"x"\} =$

 $L:: com \Rightarrow vname \ set \Rightarrow vname \ set$

$$L \ c \ X =$$
 live before c relative to X

$$L \ SKIP \ X = X$$

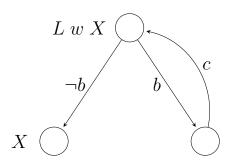
 $L \ (x := a) \ X = vars \ a \cup (X - \{x\})$
 $L \ (c_1;; c_2) \ X = L \ c_1 \ (L \ c_2 \ X)$
 $L \ (IF \ b \ THEN \ c_1 \ ELSE \ c_2) \ X = vars \ b \cup L \ c_1 \ X \cup L \ c_2 \ X$

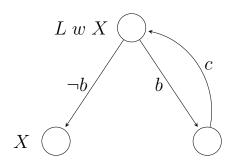


Example:

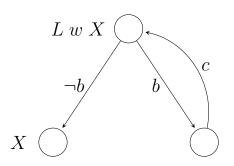
$$L ("y" ::= V "z"; "x" ::= Plus (V "y") (V "z"))$$

 $\{"x"\} = \{"z"\}$

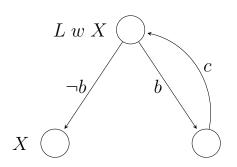




 $L \ w \ X$ must satisfy



 $L \ w \ X$ must satisfy $vars \ b \subseteq L \ w \ X$ (evaluation of b)



L w X must satisfy

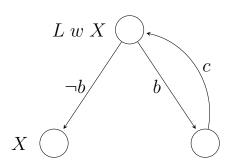
vars b

 $\subseteq L w X$ (evaluation of b)

X

 $\subseteq L w X \text{ (exit)}$

$WHILE \ b \ DO \ c$



L w X must satisfy

 $vars b \subseteq L w X$ (evaluation of b) $\subseteq L w X$ (exit)

 $L \ c \ (L \ w \ X) \subseteq L \ w \ X$ (execution of c)







We define

$$L (WHILE \ b \ DO \ c) \ X = vars \ b \cup X \cup L \ c \ X$$



We define

$$L (WHILE \ b \ DO \ c) \ X = vars \ b \cup X \cup L \ c \ X$$

$$\Longrightarrow vars \ b \subseteq L \ w \ X X \subseteq L \ w \ X$$

We define

$$L (WHILE \ b \ DO \ c) \ X = vars \ b \cup X \cup L \ c \ X$$

$$\Rightarrow vars \ b \subseteq L \ w \ X$$

$$X \subseteq L \ w \ X$$

$$L \ c \ (L \ w \ X) \subseteq L \ w \ X$$
?



Example:

$$L (WHILE Less (V "x") (V "x") DO "y" ::= V "z")$$
$$\{"x"\} =$$

Example:

$$L (WHILE Less (V "x") (V "x") DO "y" ::= V "z")$$

 $\{"x"\} = \{"x","z"\}$

A data-flow analysis $A::com \Rightarrow \tau \ set \Rightarrow \tau \ set$ is called gen/kill analysis

A data-flow analysis $A::com \Rightarrow \tau \ set \Rightarrow \tau \ set$ is called gen/kill analysis if there are functions gen and kill such that

$$A \ c \ X = X - kill \ c \cup gen \ c$$

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Gen/kill analyses are extremely well-behaved, e.g.

$$X_1 \subseteq X_2 \Longrightarrow A \ c \ X_1 \subseteq A \ c \ X_2$$

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Many standard data-flow analyses are gen/kill.

A data-flow analysis $A::com \Rightarrow \tau \ set \Rightarrow \tau \ set$ is called gen/kill analysis if there are functions gen and kill such that

$$A \ c \ X = (X - kill \ c) \cup gen \ c$$

Gen/kill analyses are extremely well-behaved, e.g.

$$X_1 \subseteq X_2 \Longrightarrow A \ c \ X_1 \subseteq A \ c \ X_2$$

 $A \ c \ (X_1 \cap X_2) = A \ c \ X_1 \cap A \ c \ X_2$

Many standard data-flow analyses are gen/kill. In particular liveness analysis.

 $kill :: com \Rightarrow vname set$

```
kill :: com \Rightarrow vname \ set
kill \ SKIP =
```

```
kill :: com \Rightarrow vname \ set
kill \ SKIP = \{\}
```

```
kill :: com \Rightarrow vname \ set
kill \ SKIP = \{\}
kill \ (x ::= a) = \{\}
```

```
\begin{array}{lll} \textit{kill} :: \textit{com} \Rightarrow \textit{vname set} \\ \textit{kill SKIP} & = \{\} \\ \textit{kill } (x ::= a) & = \{x\} \end{array}
```

```
kill :: com \Rightarrow vname \ set
kill \ SKIP = \{\}
kill \ (x ::= a) = \{x\}
kill \ (c_1;; c_2) =
```

```
kill :: com \Rightarrow vname \ set
kill \ SKIP = \{\}
kill \ (x ::= a) = \{x\}
kill \ (c_1;; c_2) = kill \ c_1 \cup kill \ c_2
```

```
\begin{array}{lll} \textit{kill} :: \textit{com} \Rightarrow \textit{vname set} \\ \textit{kill SKIP} & = \{ \} \\ \textit{kill } (x ::= a) & = \{ x \} \\ \textit{kill } (c_1;; c_2) & = \textit{kill } c_1 \cup \textit{kill } c_2 \\ \textit{kill } (\textit{IF b THEN } c_1 \textit{ ELSE } c_2) & = \end{array}
```

```
\begin{array}{lll} \textit{kill} :: \textit{com} \Rightarrow \textit{vname set} \\ \textit{kill SKIP} & = \{ \} \\ \textit{kill } (x ::= a) & = \{ x \} \\ \textit{kill } (c_1;; c_2) & = \textit{kill } c_1 \cup \textit{kill } c_2 \\ \textit{kill } (\textit{IF b THEN } c_1 \textit{ ELSE } c_2) & = \textit{kill } c_1 \cap \textit{kill } c_2 \end{array}
```

```
\begin{array}{lll} \textit{kill} :: \textit{com} \Rightarrow \textit{vname set} \\ \textit{kill SKIP} & = \left\{\right\} \\ \textit{kill } (x ::= a) & = \left\{x\right\} \\ \textit{kill } (c_1;; c_2) & = \textit{kill } c_1 \cup \textit{kill } c_2 \\ \textit{kill } (\textit{IF b THEN } c_1 \textit{ ELSE } c_2) & = \textit{kill } c_1 \cap \textit{kill } c_2 \\ \textit{kill } (\textit{WHILE b DO c}) & = \end{array}
```



```
\begin{array}{lll} \textit{kill} :: \textit{com} \Rightarrow \textit{vname set} \\ \textit{kill SKIP} & = \left\{\right\} \\ \textit{kill } (x ::= a) & = \left\{x\right\} \\ \textit{kill } (c_1;; c_2) & = \textit{kill } c_1 \cup \textit{kill } c_2 \\ \textit{kill } (\textit{IF b THEN } c_1 \textit{ ELSE } c_2) & = \textit{kill } c_1 \cap \textit{kill } c_2 \\ \textit{kill } (\textit{WHILE b DO c}) & = \left\{\right\} \end{array}
```

 $gen :: com \Rightarrow vname \ set$

```
gen :: com \Rightarrow vname \ set
gen \ SKIP =
```

```
gen :: com \Rightarrow vname \ set
gen \ SKIP = \{\}
```

```
gen :: com \Rightarrow vname \ set
gen \ SKIP = \{\}
gen \ (x ::= a) =
```

```
gen :: com \Rightarrow vname \ set
gen \ SKIP = \{\}
gen \ (x ::= a) = vars \ a
```

```
gen :: com \Rightarrow vname \ set

gen \ SKIP = \{\}

gen \ (x ::= a) = vars \ a

gen \ (c_1;; c_2) =
```

```
gen :: com \Rightarrow vname \ set
gen \ SKIP = \{\}
gen \ (x ::= a) = vars \ a
gen \ (c_1;; c_2) = gen \ c_1 \cup (gen \ c_2 - kill \ c_1)
```

```
gen :: com \Rightarrow vname \ set
gen \ SKIP = \{\}
gen \ (x ::= a) = vars \ a
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```

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gen \ (WHILE \ b \ DO \ c) =
```

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gen :: com \Rightarrow vname \ set
gen \ SKIP = \{\}
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gen \ (c_1;; c_2) = gen \ c_1 \cup (gen \ c_2 - kill \ c_1)
gen \ (IF \ b \ THEN \ c_1 \ ELSE \ c_2) = vars \ b \cup gen \ c_1 \cup gen \ c_2
gen \ (WHILE \ b \ DO \ c) = vars \ b \cup gen \ c
```

 $L \ c \ X = gen \ c \cup (X - kill \ c)$

$$L \ c \ X = gen \ c \cup (X - kill \ c)$$

Proof by induction on c.

$$L \ c \ X = gen \ c \cup (X - kill \ c)$$

Proof by induction on c.

$$\Longrightarrow$$

$$L c (L w X) \subseteq L w X$$



 $A \ c \ X$: the set of variables initialized after c if X was initialized before c

 $A \ c \ X$: the set of variables initialized after c if X was initialized before c

 $A\ c\ X$: the set of variables initialized after c if X was initialized before c How to obtain $A\ c\ X = X - kill\ c \cup gen\ c$: $gen\ SKIP =$

A c X: the set of variables initialized after c if X was initialized before c How to obtain A c X = X - kill $c \cup gen$ c:

 $gen SKIP = \{\}$

 $A \ c \ X$: the set of variables initialized after c if X was initialized before c

$$\begin{array}{rcl}
gen SKIP & = \{\}\\
gen (x ::= a) & =
\end{array}$$

 $A \ c \ X$: the set of variables initialized after c if X was initialized before c

$$gen SKIP = \{\}$$

$$gen (x ::= a) = \{x\}$$

 $A \ c \ X$: the set of variables initialized after c if X was initialized before c

```
gen SKIP = \{ \}
gen (x ::= a) = \{x\}
gen (c_1;; c_2) =
```

 $A \ c \ X$: the set of variables initialized after c if X was initialized before c

```
\begin{array}{lll} \textit{gen SKIP} & = & \{\} \\ \textit{gen } (x ::= a) & = & \{x\} \\ \textit{gen } (c_1;; c_2) & = & \textit{gen } c_1 \cup \textit{gen } c_2 \end{array}
```

 $A\ c\ X$: the set of variables initialized after c if X was initialized before c

```
\begin{array}{lll} \textit{gen SKIP} & = & \{\} \\ \textit{gen } (x ::= a) & = & \{x\} \\ \textit{gen } (c_1;; c_2) & = & \textit{gen } c_1 \cup \textit{gen } c_2 \\ \textit{gen } (\textit{IF b THEN } c_1 \textit{ ELSE } c_2) & = & \end{array}
```

 $A \ c \ X$: the set of variables initialized after c if X was initialized before c

```
\begin{array}{lll} \textit{gen SKIP} & = & \{\} \\ \textit{gen } (x ::= a) & = & \{x\} \\ \textit{gen } (c_1;; c_2) & = & \textit{gen } c_1 \cup \textit{gen } c_2 \\ \textit{gen } (\textit{IF b THEN } c_1 \textit{ ELSE } c_2) & = & \textit{gen } c_1 \cap \textit{gen } c_2 \end{array}
```

 $A \ c \ X$: the set of variables initialized after c if X was initialized before c

```
gen SKIP = \{\}
gen (x ::= a) = \{x\}
gen (c_1;; c_2) = gen c_1 \cup gen c_2
gen (IF b THEN c_1 ELSE c_2) = gen c_1 \cap gen c_2
gen (WHILE b DO c) =
```

 $A \ c \ X$: the set of variables initialized after c if X was initialized before c

```
\begin{array}{lll} gen \ SKIP & = & \{\} \\ gen \ (x ::= a) & = & \{x\} \\ gen \ (c_1 ;; \ c_2) & = & gen \ c_1 \cup gen \ c_2 \\ gen \ (IF \ b \ THEN \ c_1 \ ELSE \ c_2) & = & gen \ c_1 \cap gen \ c_2 \\ gen \ (WHILE \ b \ DO \ c) & = & \{\} \end{array}
```

 $A \ c \ X$: the set of variables initialized after c if X was initialized before c

How to obtain $A \ c \ X = X - kill \ c \cup gen \ c$:

```
\begin{array}{lll} gen \ SKIP & = & \{\} \\ gen \ (x ::= a) & = & \{x\} \\ gen \ (c_1 ;; \ c_2) & = & gen \ c_1 \cup gen \ c_2 \\ gen \ (IF \ b \ THEN \ c_1 \ ELSE \ c_2) & = & gen \ c_1 \cap gen \ c_2 \\ gen \ (WHILE \ b \ DO \ c) & = & \{\} \end{array}
```

 $kill \ c =$

 $A \ c \ X$: the set of variables initialized after c if X was initialized before c

How to obtain $A \ c \ X = X - kill \ c \cup gen \ c$:

```
\begin{array}{lll} gen \ SKIP & = & \{\} \\ gen \ (x ::= a) & = & \{x\} \\ gen \ (c_1;; \ c_2) & = & gen \ c_1 \cup gen \ c_2 \\ gen \ (IF \ b \ THEN \ c_1 \ ELSE \ c_2) & = & gen \ c_1 \cap gen \ c_2 \\ gen \ (WHILE \ b \ DO \ c) & = & \{\} \end{array}
```

 $kill\ c = \{\}$



Live Variable Analysis Correctness of L

Dead Variable Elimination True Liveness Comparisons $(.,.) \Rightarrow$ and L should roughly be related like this:

The value of the final state on X only depends on the value of the initial state on $L \ c \ X$.

 $(.,.) \Rightarrow$ and L should roughly be related like this:

The value of the final state on X only depends on the value of the initial state on L c X.

Put differently:

If two initial states agree on L c X then the corresponding final states agree on X.



Equality on

An abbreviation:

$$f = g \text{ on } X \equiv \forall x \in X. f x = g x$$

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Two easy theorems (in theory Vars):

$$s_1 = s_2$$
 on vars $a \Longrightarrow aval \ a \ s_1 = aval \ a \ s_2$

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Two easy theorems (in theory Vars):

$$s_1 = s_2$$
 on vars $a \Longrightarrow aval \ a \ s_1 = aval \ a \ s_2$
 $s_1 = s_2$ on vars $b \Longrightarrow bval \ b \ s_1 = bval \ b \ s_2$

Correctness of L

If
$$(c, s) \Rightarrow s'$$
 and $s = t$ on L c X then $\exists t'$. $(c, t) \Rightarrow t' \land s' = t'$ on X .

Correctness of L

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Proof by rule induction.

Correctness of L

If
$$(c, s) \Rightarrow s'$$
 and $s = t$ on L c X then $\exists t'. (c, t) \Rightarrow t' \land s' = t'$ on X .

Proof by rule induction.



For the two $W\!HILE$ cases we do not need the definition of L w but only the characteristic property

$$vars \ b \cup X \cup L \ c \ (L \ w \ X) \subseteq L \ w \ X$$



Optimality of $L\ w$

The result of ${\cal L}$ should be as small as possible: the more dead variables, the better

Optimality of L w

The result of L should be as small as possible: the more dead variables, the better (for program optimization).

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 $L \ w \ X$ should be the least set such that $vars \ b \cup X \cup L \ c \ (L \ w \ X) \subseteq L \ w \ X.$

Optimality of L w

The result of L should be as small as possible: the more dead variables, the better (for program optimization).

 $L \ w \ X$ should be the least set such that $vars \ b \cup X \cup L \ c \ (L \ w \ X) \subseteq L \ w \ X.$

Follows easily from $L \ c \ X = gen \ c \cup (X - kill \ c)$:

$$vars \ b \cup X \cup L \ c \ P \subseteq P \Longrightarrow L \ (WHILE \ b \ DO \ c) \ X \subseteq P$$



Live Variable Analysis

Correctness of L

Dead Variable Elimination

True Liveness Comparisons

 $bury :: com \Rightarrow vname \ set \Rightarrow com$

$$bury :: com \Rightarrow vname \ set \Rightarrow com$$
 $bury \ SKIP \ X =$

```
bury :: com \Rightarrow vname \ set \Rightarrow com
bury \ SKIP \ X = SKIP
```

```
bury :: com \Rightarrow vname \ set \Rightarrow com
bury \ SKIP \ X = SKIP
bury \ (x ::= a) \ X =
```

```
bury :: com \Rightarrow vname \ set \Rightarrow com
```

```
\begin{array}{lcl} \textit{bury SKIP } X & = & \textit{SKIP} \\ \textit{bury } (x ::= a) \ X & = & \textit{if } x \in X \textit{ then } x ::= a \textit{ else SKIP} \end{array}
```

 $bury :: com \Rightarrow vname \ set \Rightarrow com$

```
\begin{array}{lcl} \textit{bury SKIP } X & = & \textit{SKIP} \\ \textit{bury } (x ::= a) \ X & = & \textit{if } x \in X \textit{ then } x ::= a \textit{ else SKIP} \\ \textit{bury } (c_1;; c_2) \ X & = & \end{array}
```

```
bury :: com \Rightarrow vname \ set \Rightarrow com
```

```
\begin{array}{lll} \textit{bury SKIP } X & = & \textit{SKIP} \\ \textit{bury } (x ::= a) \ X & = & \textit{if } x \in X \textit{ then } x ::= a \textit{ else SKIP} \\ \textit{bury } (c_1;; c_2) \ X & = & \textit{bury } c_1 \ (L \ c_2 \ X);; \textit{bury } c_2 \ X \end{array}
```

```
bury :: com \Rightarrow vname \ set \Rightarrow com
```

```
bury SKIP \ X = SKIP

bury (x := a) \ X = \text{if } x \in X \text{ then } x := a \text{ else } SKIP

bury (c_1;; c_2) \ X = \text{bury } c_1 \ (L \ c_2 \ X);; \text{bury } c_2 \ X

bury (IF \ b \ THEN \ c_1 \ ELSE \ c_2) \ X =
```

 $bury :: com \Rightarrow vname \ set \Rightarrow com$

```
bury SKIP \ X = SKIP

bury (x := a) \ X = \text{if } x \in X \text{ then } x := a \text{ else } SKIP

bury (c_1;; c_2) \ X = \text{bury } c_1 \ (L \ c_2 \ X);; \text{ bury } c_2 \ X

bury (IF \ b \ THEN \ c_1 \ ELSE \ c_2) \ X = IF \ b \ THEN \ bury \ c_1 \ X \ ELSE \ bury \ c_2 \ X
```

 $bury :: com \Rightarrow vname \ set \Rightarrow com$

```
\begin{array}{lll} \textit{bury SKIP } X & = & \textit{SKIP} \\ \textit{bury } (x ::= a) \ X & = & \textit{if } x \in X \textit{ then } x ::= a \textit{ else SKIP} \\ \textit{bury } (c_1 ;; c_2) \ X & = & \textit{bury } c_1 \ (L \ c_2 \ X) ;; \textit{bury } c_2 \ X \\ \textit{bury } (\textit{IF b THEN } c_1 \ \textit{ELSE } c_2) \ X & = \\ & \textit{IF b THEN bury } c_1 \ X \ \textit{ELSE bury } c_2 \ X \\ \textit{bury } (\textit{WHILE b DO c}) \ X & = \\ \end{array}
```

```
bury :: com \Rightarrow vname \ set \Rightarrow com
```

```
bury SKIP \ X = SKIP

bury (x := a) \ X = if \ x \in X \ then \ x := a \ else \ SKIP

bury (c_1;; c_2) \ X = bury \ c_1 \ (L \ c_2 \ X);; \ bury \ c_2 \ X

bury (IF \ b \ THEN \ c_1 \ ELSE \ c_2) \ X = IF \ b \ THEN \ bury \ c_1 \ X \ ELSE \ bury \ c_2 \ X

bury (WHILE \ b \ DO \ c) \ X = WHILE \ b \ DO \ bury \ c \ (L \ (WHILE \ b \ DO \ c) \ X)
```

Correctness of bury

Correctness of bury

bury c $UNIV \sim c$

where UNIV is the set of all variables.

Correctness of bury



bury c $UNIV \sim c$

where *UNIV* is the set of all variables.

The two directions need to be proved separately.

 $(c, s) \Rightarrow s' \Longrightarrow (bury \ c \ UNIV, s) \Rightarrow s'$

$$(c, s) \Rightarrow s' \Longrightarrow (bury \ c \ UNIV, s) \Rightarrow s'$$

If
$$(c, s) \Rightarrow s'$$
 and $s = t$ on L c X then $\exists t'$. $(bury c X, t) \Rightarrow t' \land s' = t'$ on X .

$$(c, s) \Rightarrow s' \Longrightarrow (bury \ c \ UNIV, s) \Rightarrow s'$$

If
$$(c, s) \Rightarrow s'$$
 and $s = t$ on L c X then $\exists t'. (bury c $X, t) \Rightarrow t' \land s' = t'$ on X .$

Proof by rule induction, like for correctness of L.

 $(bury\ c\ UNIV,\ s) \Rightarrow s' \Longrightarrow (c,\ s) \Rightarrow s'$

$$(bury\ c\ UNIV,\ s) \Rightarrow s' \Longrightarrow (c,\ s) \Rightarrow s'$$

If $(bury\ c\ X,\ s) \Rightarrow s'$ and $s=t\ on\ L\ c\ X$ then $\exists\ t'.\ (c,\ t) \Rightarrow t'\wedge s'=t'\ on\ X$.

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Proof very similar to other direction, but needs inversion lemmas for bury for every kind of command, e.g.

$$(bc_1;; bc_2 = bury \ c \ X) =$$

 $(\exists c_1 \ c_2.$
 $c = c_1;; c_2 \land$
 $bc_2 = bury \ c_2 \ X \land bc_1 = bury \ c_1 \ (L \ c_2 \ X))$

Live Variable Analysis

True Liveness

Comparisons

Let $f :: \tau \Rightarrow \tau$ and $x :: \tau$.

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If $f x \leq x$ then x is a *pre-fixpoint* (*pfp*) of f.

If $x \leq y \Longrightarrow f \ x \leq f \ y$ for all x,y, then f is monotone.

Application to L w

Remember the specification of L w:

$$vars \ b \cup X \cup L \ c \ (L \ w \ X) \subseteq L \ w \ X$$

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and in particular of L c.

True liveness

$$L("x" ::= V"y") \{\} = \{"y"\}$$

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But then

$$L (WHILE \ b \ DO \ c) \ X = vars \ b \cup X \cup L \ c \ X$$

is not correct anymore.

L (x := a) X =(if $x \in X$ then $vars \ a \cup (X - \{x\})$ else X) $L (WHILE \ b \ DO \ c) \ X = vars \ b \cup X \cup L \ c \ X$

$$L \ (x ::= a) \ X = \\ (\textit{if } x \in X \textit{ then } vars \ a \cup (X - \{x\}) \textit{ else } X) \\ L \ (\textit{WHILE } b \textit{ DO } c) \ X = vars \ b \cup X \cup L \ c \ X \\ \text{Let } w = \textit{WHILE } b \textit{ DO } c \\ \text{where } b = \textit{Less } (N \ 0) \ (V \ y) \\ \text{and } c = y ::= V \ x;; \ x ::= V \ z \\ \text{and } \textit{distinct } [x, \ y, \ z]$$

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```

```
b = Less (N 0) (V y)

c = y ::= V x;; x ::= V z
```

 $L \ w \ \{y\} = \{x, \ y\}$ is not a pfp of $L \ c$:

```
\begin{array}{lll} b &=& Less \; (N \; 0) \; (V \; y) \\ c &=& y ::= \; V \; x;; \; x ::= \; V \; z \\ \\ L \; w \; \{y\} &=& \{x, \; y\} \; \text{is not a pfp of } L \; c: \\ &y ::= \; V \; x \qquad \qquad x ::= \; V \; z \; \; \{x, \; y\} \end{array}
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b = Less (N 0) (V y)
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L w \{y\} = \{x, y\} \text{ is not a pfp of } L c:
\{x, z\} y ::= V x \{y, z\} x ::= V z \{x, y\}
L c \{x, y\} = \{x, z\} \not\subseteq \{x, y\}
```

L w for true liveness

Define L w X as the least pfp of λP . vars $b \cup X \cup L$ c P

Existence of least fixpoints

Theorem (Knaster-Tarski) Let $f :: \tau \ set \Rightarrow \tau \ set$.

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Theorem (Knaster-Tarski) Let $f :: \tau \ set \Rightarrow \tau \ set$. If f is monotone $(X \subseteq Y \Longrightarrow f(X) \subseteq f(Y))$ then

$$lfp(f) := \bigcap \{P \mid f(P) \subseteq P\}$$

is the least pre-fixpoint and least fixpoint of f.

Theorem If $f :: \tau \ set \Rightarrow \tau \ set$ is monotone then $lfp(f) := \bigcap \{P \mid f(P) \subseteq P\}$ is the least pre-fixpoint.

Theorem If $f:: \tau \ set \Rightarrow \tau \ set$ is monotone then $lfp(f):=\bigcap\{P\mid f(P)\subseteq P\}$ is the least pre-fixpoint. **Proof** $\bullet \ f(lfp\ f)\subseteq lfp\ f$

Theorem If $f:: \tau \ set \Rightarrow \tau \ set$ is monotone then $lfp(f):=\bigcap\{P\mid f(P)\subseteq P\}$ is the least pre-fixpoint.

Proof • $f(lfp f) \subseteq lfp f$

• *lfp f* is the least pre-fixpoint of *f*

Theorem If $f :: \tau \ set \Rightarrow \tau \ set$ is monotone then $lfp(f) := \bigcap \{P \mid f(P) \subseteq P\}$ is the least pre-fixpoint.

- **Proof** \bullet $f(lfp f) \subseteq lfp f$
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Lemma Let f be a monotone function on a partial order \leq . Then a least pre-fixpoint of f is also a least fixpoint.

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 f $p \leq p \Longrightarrow f$ $p = p$

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$$\begin{array}{l} L\ (x ::= a)\ X = \\ (\textit{if}\ x \in X\ \textit{then}\ vars\ a \cup (X - \{x\})\ \textit{else}\ X) \end{array}$$

$$L (WHILE \ b \ DO \ c) \ X = lfp \ f_w$$

where $f_w = (\lambda P. \ vars \ b \cup X \cup L \ c \ P)$

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Proof by induction on c using that lfp is monotone: $lfp \ f \subseteq lfp \ g$ if for all X, $f \ X \subseteq g \ X$

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Corollary f_w is monotone.

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then $lfp(f) = f^k(\{\}).$

Proof Show $f^i(\{\}) \subseteq p$ for any pfp p of f (by induction on i).

Computation of $lfp f_w$

$$f_w = (\lambda P. \ vars \ b \cup X \cup L \ c \ P)$$

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The chain $\{\} \subseteq f_w \{\} \subseteq f_w^2 \{\} \subseteq \dots$ must stabilize:

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Corollary $P \subseteq V_w \Longrightarrow f_w \ P \subseteq V_w$

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The chain $\{\} \subseteq f_w \{\} \subseteq f_w^2 \{\} \subseteq \dots$ must stabilize:

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More precisely: $k \leq |vars| c + 1$

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The chain $\{\} \subseteq f_w \{\} \subseteq f_w^2 \{\} \subseteq \dots$ must stabilize:

Let vars c be the variables in c.

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Hence f_w^k {} stabilizes for some $k \leq |V_w|$.

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because f_w {} $\supseteq vars \ b \cup X$.

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\begin{array}{lll} \text{Let } w = \textit{WHILE b DO c} \\ \text{where } b = \textit{Less } (\textit{N 0}) \; (\textit{V y}) \\ \text{and } c = \textit{y} ::= \textit{V x};; \; \textit{x} ::= \textit{V z} \end{array}
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Let w = WHILE \ b \ DO \ c
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To compute $L \ w \ \{y\}$ we iterate $f_w \ P = \{y\} \cup L \ c \ P$:

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while ::
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then $lfp\ f = while\ (\lambda X.\ f\ X \neq X)\ f\ \{\}$

Fix some small k (eg 2)

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$$Lb \ w \ X = \left\{ \begin{array}{c} g_w^i \ \{\} & \text{if} \ g_w^{i+1} \ \{\} = g_w^i \ \{\} \ \text{for some} \ i < k \\ & \text{otherwise} \end{array} \right.$$

where $g_w P = vars \ b \cup X \cup Lb \ c P$

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If $Lb \ w \ X = V_w$: $L \ w \ X \subseteq V_w$ (by Lemma)

Live Variable Analysis

Comparisons

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- Live variable analysis is a backward may analysis:
 - it analyses the executions ending in some point,
 - live variables *may* be used (on some program path) before they are assigned.

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