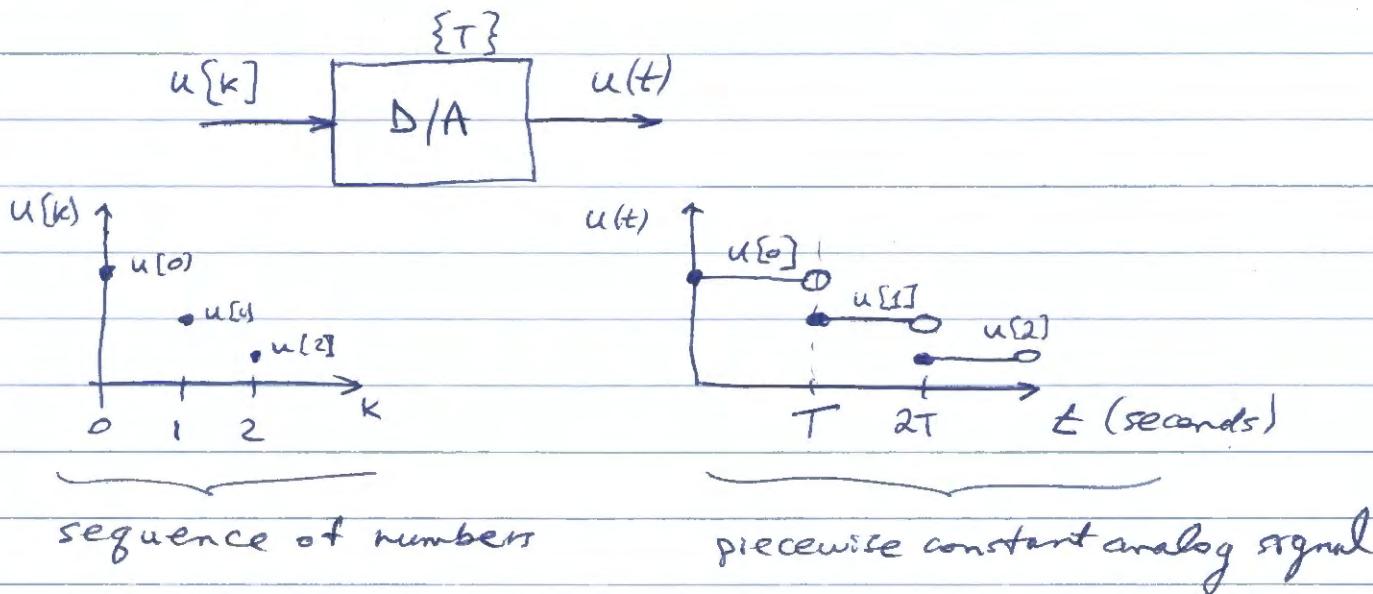


To do digital control we will need digital to analog (D/A) converters, and analog to digital (A/D) converters.

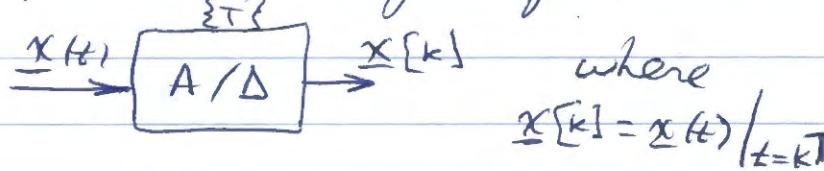
Consider a **D/A converter** with sampling interval T seconds

(Read Section 4.1)

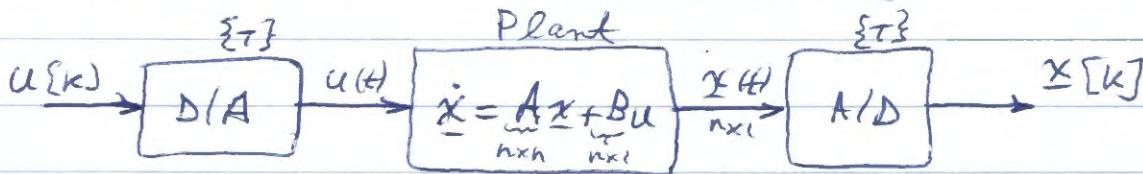


At each sampling instant $t = k \cdot T$ seconds, the D/A converter outputs $u[k]$ volts and holds that voltage constant for T seconds, until $t = kT + T$, when the next sample is sent to the D/A. A constant value may be thought of as a polynomial of degree zero, and this type of D/A converter is referred to as a zero-order hold or ZOH.

An **A/D converter** samples an analog signal every T seconds.



Digital Control with all Plant State Variables Measured



$$\text{plant poles: } s_i = \text{eig}(A), i=1,\dots,n$$

The cascade connection of D/A, plant, A/D is exactly represented by the following (zero-order hold) ZOH plant equivalent:

$$x[k+1] = \underbrace{\Phi}_{nxn} \underbrace{x[k]}_{nx1} + \underbrace{u[k]}_{nx1} \rightarrow x[k]$$

$$\text{poles } z_i = \text{eig}(\Phi), i=1,\dots,n$$

How are the poles of the plant ($\text{eig}(A)$) related to the poles of the ZOH plant equivalent ($\text{eig}(\Phi)$)?

Recall the eigenvalue decomposition of A :

$$A = U \Lambda U^{-1}$$

diagonal matrix.

the columns of U are the eigenvectors of A

and the diagonal elements of Λ are the eigenvalues of A . Previously we have called these numbers λ_i . On this page we have called those numbers s_i .

Note: Any time you decompose a matrix into the product of three matrices where the third is the inverse of the first and the middle matrix is diagonal, that is an eigenvalue decom-

It can be shown (Chapter 4) that the plant ZOH matrices are obtained from the following formulas:

$$\Phi = e^{A \cdot T}, \quad \Gamma = \int_0^T e^{A \cdot t} B dt$$

where (A, B) is the state-space model of the plant and T is the sampling interval for the D/A and A/D converters.

Recall that the matrix exponential can be written in terms of the eigenvalue decomposition

of A :

$$\Lambda = \begin{bmatrix} s_1 & & \\ & \ddots & \\ & & s_n \end{bmatrix}, \quad \Phi = e^{AT} = U e^{\Lambda \cdot T} U^{-1}, \quad \Lambda = \text{diag}(s_i)$$

$$A \cdot T = U (\Lambda \cdot T) U^{-1} = U \underbrace{\begin{bmatrix} e^{s_1 T} & & & \\ & e^{s_2 T} & 0 & \\ & & \ddots & \\ & & & e^{s_n T} \end{bmatrix}}_{\text{scalar sampling interval}} U^{-1}$$

The eigenvalues of Φ are $(z_i = \text{eig}(\Phi))$ this is an eigenvalue decomposition of Φ

$$z_i = e^{s_i T}, \quad i=1, \dots, n$$

This is called the ZOH pole-mapping formula, and it maps the plant poles to the corresponding poles of the ZOH plant equivalent.