

Simulink Desktop Real-Time for Lab 1

1. Chose a directory where you want to work. Then start Matlab and change to that directory in Matlab. Type *simulink* at the Matlab prompt. On the next screen that pops up, click on the “Blank Model” tab.
2. Create and run an m-file to assign values to all of the variables that will be used in the Simulink model, including the sampling interval, T.
3. In the Simulink window, click on the red, white, and blue icon to bring up the Simulink Library Browser. Click and drag the following components to the Simulink workspace: Two *Step* blocks (found in *Sources*), an *Add* block and a *Gain* block (found in *Math Operations*), *Derivative* block (found in *Continuous*), a *Scope* (found in *Sinks*), *Encoder Input* and *Analog Output* (D/A) blocks (found in *Simulink Desktop Real-Time*).
4. At the top of the Simulink model, change the time from 10.0 to however many seconds you want the system to run (for Lab 1 use 1 sec.).
5. Connect the blocks together and set the parameters of each block. Set the sample times of all the digital blocks to T.
6. Configure the Scopes to send their data to the Matlab workspace as an array using simple variable names like **u** and **v**. Give the scope blocks in the Simulink diagram a name (e.g. Motor Velocity, Plant input).
7. Double click on the Analog Output and Encoder Input Blocks. If you see **<no board selected>** click on **Install New Board** and select **Humusoft MF634**. Click **Okay** in the window that pops up. Configure these blocks **using the information at the bottom of this page**.
8. At the top of the Simulink model click the *Modeling* tab and click *Model Settings*:
 - (a) Click on **Solver**. Change *Type* to **Fixed Step**. Click on *Solver Details*. In the *Fixed Step Size* box type in T.
 - (b) Click on **Data Import/Export**. Uncheck the *Single Simulation Output* box.
 - (c) Click on **Code Generation**. Browse for the *System Target File*. Choose *sldrt.tlc* (*Simulink Desktop Real-Time*).
9. Click on **Desktop Real-Time** tab. In the upper left, click the black arrow below *Simulation*, make sure the *Mode* is **Run Model in Kernel Mode**. Also, to the left of *Stop Time* click on black arrow. Then click on **Control Panel** icon. Select *Signal & Trigger* and set the duration to 100000.
10. Click on the black arrow below *Run in Real Time*. The sequence is (*black arrow*)**Build**, (*black arrow*)**Connect**. Once the green **Start** arrow is visible and you can click it to run the hardware. If the *Build* icon is visible, you can click on *Connect*.

Analog Output

| | |
|----------------|----------------|
| Board Select | MF634 |
| Sample Time | T |
| Output Channel | Get from cable |
| Output Range | -10 to 10 |
| Initial Value | 0 |
| Final Value | 0 |

Encoder Input

| | |
|----------------------|-------------------|
| Board Select | MF634 |
| Sample Time | T |
| Input Channel | Get from cable |
| Quadrature Mode | Quadruple |
| Reset Input Function | Rising edge index |