

Pneumatic Flow Rate Regulation System

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Client: Dr. Peter Galie

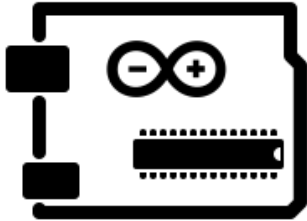
December 10, 2018



Overview

Scope and Motivation

Project Constraints and Requirements



Budget and Resources

System Design

System Operation

Future Work

Conclusions



Scope and Motivation

Started with a Previously Broken Project

Original open-source code converted for Dr. Galie's use but broken in the process

Create GUI in Python for User Controls

Allows user to adjust output waveforms

Code Firmware on Arduino for System Control

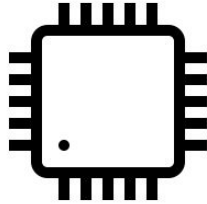
Takes user input data and adjusts signals on system

System Controls Air Flow Rate from Lab Benches

Enables more controlled lab experiments



Project Constraints and Requirements



Had to abide by Arduino
and other hardware
restrictions



Very user friendly setup
and usage



System was already
bought, did not want to
make too many changes
to components needed



Budget and Resources

Base System Components Already Bought

All components from open-source bill of materials

Had to Replace Industruino

Did so with Arduino UNO

Simple Circuit to Increase Arduino Output

Because transducer input requirements previously met by Industruino specs

Appended Original Bill of Materials

All original components already bought, new required hardware recorded



System Design

Create Easy-to-Use GUI

With Python 3 which sends data via serial port to Arduino

Communication via Serial Port

Python writes to Arduino read buffer and vice versa

Utilize an Arduino to Control Pump

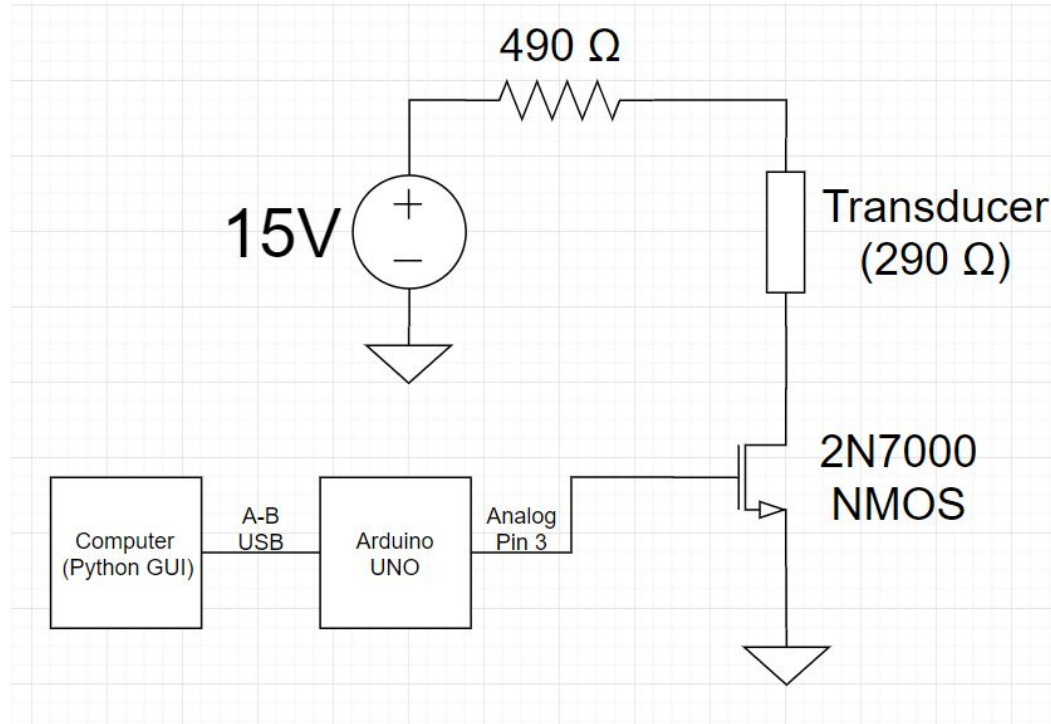
Arduino takes python data, and produces a pressure via the transducer

Amplification of Voltage

MOSFET low-side switch design to step up voltage



System Design



System Operation

Multiple Output States

Can create constant (DC), pulse (50% PWM) and ramp waveforms

High and Low DAC Outputs

8-bit DAC (0 - 255 on GUI) mapped to 4mA - 20mA output

Variable Output Period

For pulse and ramp outputs, period can be changed from 0s - 1s



System Operation

First-Time and One-Time Configuration Setup

User is prompted to input serial COM port Arduino is found at

GUI Pops Up in Default State

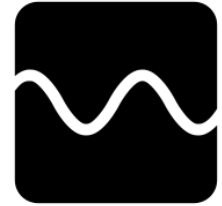
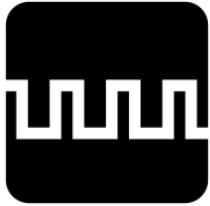
Default state is constant output set to 0V DAC

User Modifies Output with Slider Bars

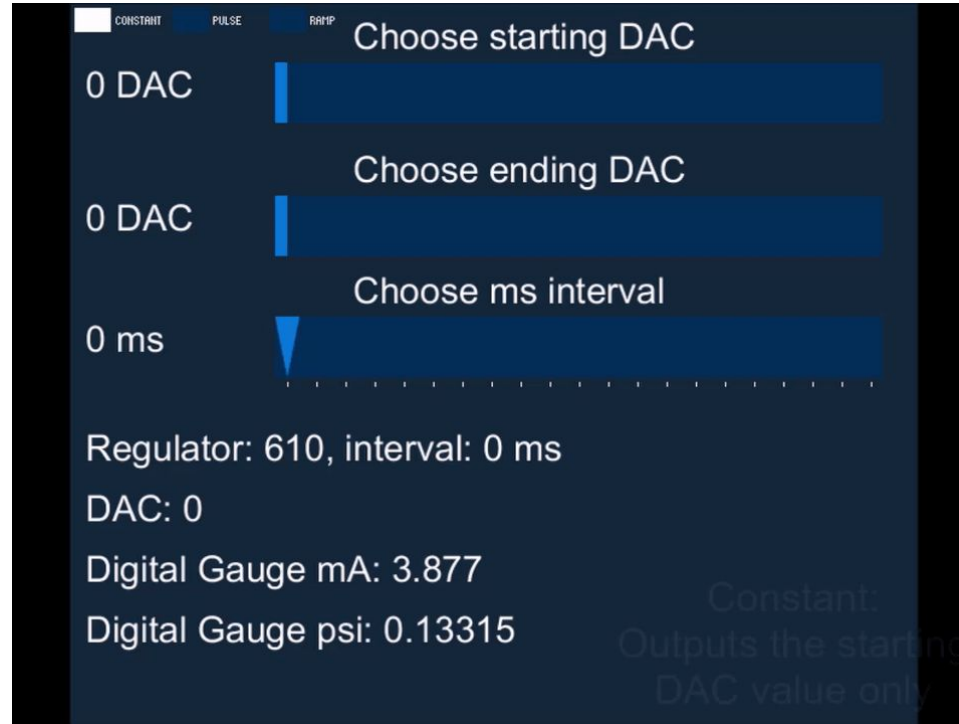
Python read/writes serial port at rate of 10Hz

Output Feedback to User

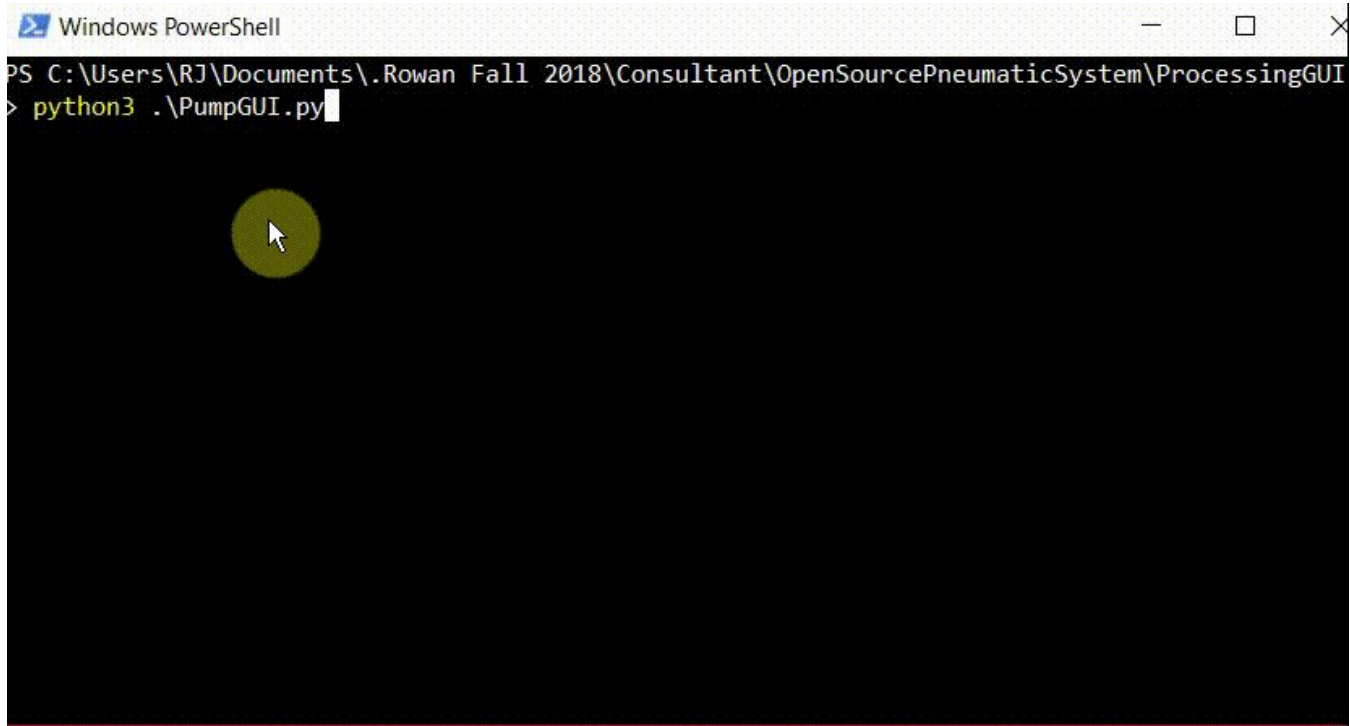
Arduino reads digital gauge and writes data to serial port



Old GUI Operation



New GUI Operation



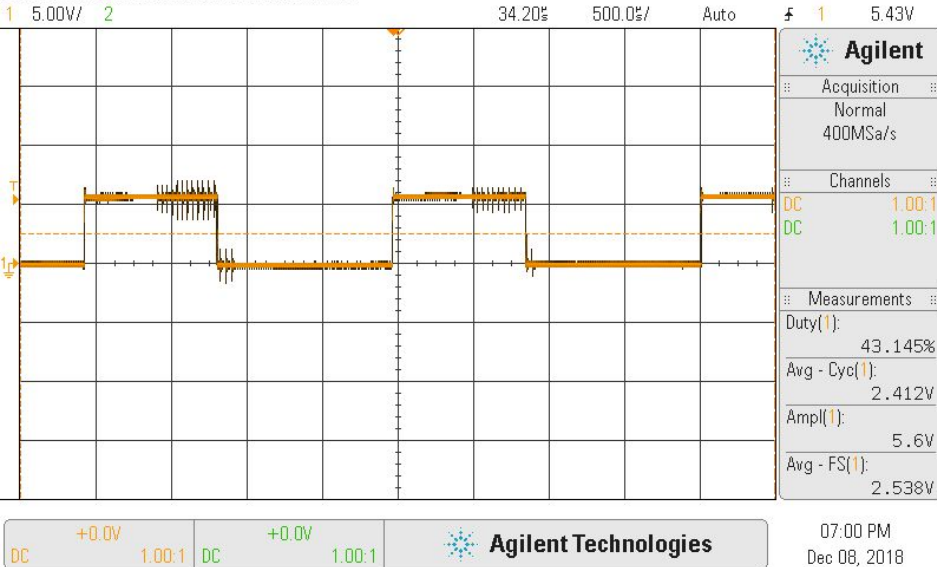
A screenshot of a Windows PowerShell terminal window. The title bar at the top reads "Windows PowerShell" and includes standard window controls (minimize, maximize, close). The command prompt shows the current directory as "C:\Users\RJ\Documents\.Rowan Fall 2018\Consultant\OpenSourcePneumaticSystem\ProcessingGUI". The user has entered the command "python3 .\PumpGUI.py" and is waiting for the program to execute. A mouse cursor is visible over a small green circular icon in the terminal area.

```
PS C:\Users\RJ\Documents\.Rowan Fall 2018\Consultant\OpenSourcePneumaticSystem\ProcessingGUI
> python3 .\PumpGUI.py
```



System Operation

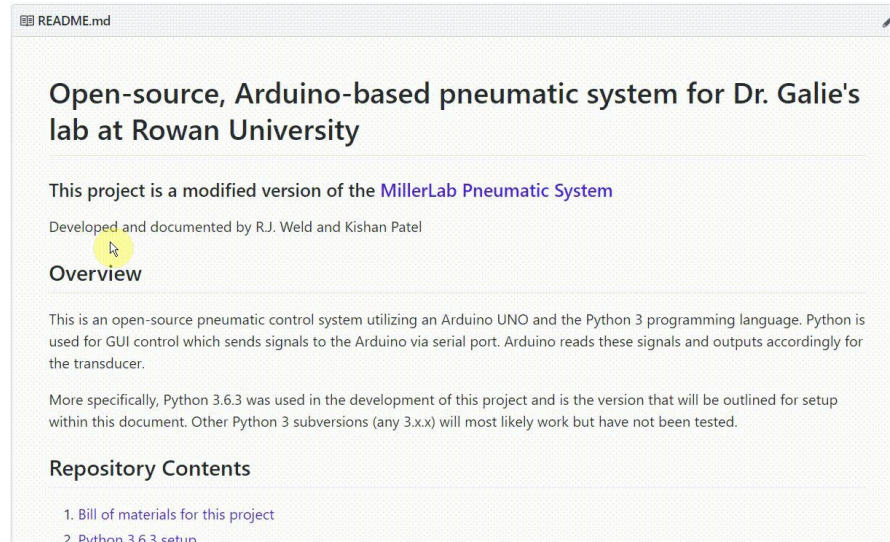
MSO-X 3012A, MY54230242: Sat Dec 08 19:00:37 2018



System Documentation

README Files Accessible on GitHub

Thorough documentation for easy setup, usage and troubleshooting



Future Work

Feedback Signals and Control System

Utilize a closed loop system for better control output and user feedback

Embed circuit onto PCB

Increases circuit stability and durability

3-D Printed Enclosure

Enclose circuit in 3-D printed box to better protect it and its users



Conclusions

Avoid tunnel visioning

Always try to have a backup plan

Efficient Planning is Key

Having a plan of attack, and setting deadlines helps



More Work Needed to Create Optimal Functionality

Implement PID controller on Arduino with feedback signals



Questions?

