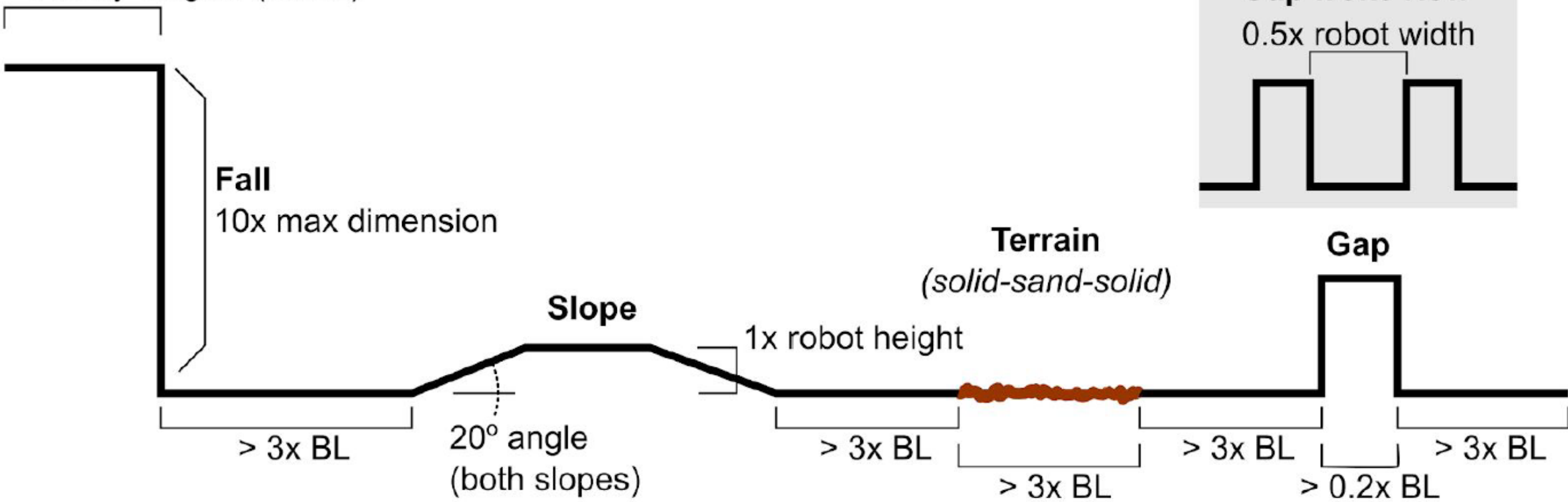


# Obstacle course side view

> 3 body lengths (3x BL)



## Gap front view

$0.5 \times \text{robot width}$

