Obstacle course side view > 3 body lengths (3x BL) Gap front view 0.5x robot width Fall 10x max dimension Terrain Gap (solid-sand-solid) Slope 1x robot height 20° angle > 3x BL > 3x BL > 3x BL > 3x BL

> 3x BL

> 0.2x BL

(both slopes)