Cb AST Validation

1 Naming Rules

- No duplicate names amongst globals, externs, and functions.
- No duplicate names amongst struct types, and for a given struct type no duplicate names amongst its
 fields.
- For a given function, no duplicate names amongst its parameters and no duplicate names amongst its locals.

2 Miscellaneous Rules

- There exists a function called main and its type is () \rightarrow int.
- For every function, all paths from that function's entry reach a Return statement.

3 Type Checking

3.1 Types

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\tau \in Type ::= int \mid struct_{Id} \mid \&\tau \mid (\vec{\tau}) \rightarrow \tau^?
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A type τ is either the integer type, a struct type (qualified by the name of the struct), a pointer type (qualified by the type being pointed to), or a function type (qualified by the types of the parameters and an optional return type). Examples:

- An integer value has type int.
- A struct named foo has type struct_{foo} .
- A pointer to an int has type &int.
- A function taking an int and a pointer to an int and returning an int has type (int, &int) → int.
- A function taking an int and a pointer to an int and not returning anything has type (int, &int) \rightarrow ...

3.2 Type Evironment

Let $\Gamma: Id \to Type$ be a map from identifiers (variable and function names) to types.

Let $\Delta: Id \to (Id \to Type)$ be a map from identifiers (struct names) to a map from identifiers (field names) to types.

We initialize Γ_0 and Δ from the the AST Program node's globals, structs, externs, and functions fields. Note that for a function inside externs the function name is mapped to its function type, while for a function inside functions the function name is mapped to a *pointer* to the function type. Also, we don't include the main function in Γ_0 . At this point, Γ_0 has all the type information for global variables, extern declared functions, and internal defined functions (except main) and Δ has the typing information for all struct declarations.

 Δ will stay constant throughout the type checking process. Γ_0 will be augmented when type checking each function's body to contain that function's parameters and locals.

3.3 Exp and Lval Typing Rules

Typing judgements for Exp and Lval nodes in the AST are of the form $\Gamma, \Delta \vdash e : \tau$, stating that given the type environment consisting of Γ and Δ , the AST node has type τ .

$$\overline{\Gamma, \Delta \vdash \mathtt{Num}(\mathtt{n}) : \mathtt{int}}^{\ \ \mathrm{NUM}}$$

$$\frac{\Gamma(\mathtt{name}) = \tau}{\Gamma, \Delta \vdash \mathtt{Id}(\mathtt{name}) : \tau} \text{ ID}$$

$$\overline{\Gamma,\Delta \vdash \mathtt{Nil} : \&_{-}}$$
 NIL

We're using a convenient ad-hoc notation for the NIL rule expressing that a Nil expression is a pointer, but it can be treated as a pointer to any type. When comparing two types to see whether they are equal, Nil's type should be considered equal to any other pointer type.

$$\frac{\Gamma, \Delta \vdash \mathtt{e} : \mathtt{int}}{\Gamma, \Delta \vdash \mathtt{Unop}(\mathtt{Neg}, \mathtt{e}) : \mathtt{int}} \ ^{\mathrm{NEG}}$$

$$\frac{\Gamma, \Delta \vdash \texttt{e} : \& \tau}{\Gamma, \Delta \vdash \texttt{Unop}(\texttt{Deref}, \texttt{e}) : \tau} \text{ DEREF}$$

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\frac{\texttt{op} \not\in \{\texttt{Equal}, \texttt{NotEq}\} \qquad \Gamma, \Delta \vdash \texttt{left} : \texttt{int} \qquad \Gamma, \Delta \vdash \texttt{right} : \texttt{int}}{\Gamma, \Delta \vdash \texttt{Binop}(\texttt{op}, \texttt{left}, \texttt{right}) : \texttt{int}} \text{ BINOP-REST}
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$$\frac{\Gamma, \Delta \vdash \mathtt{ptr} : \& \tau \qquad \Gamma, \Delta \vdash \mathtt{idx} : \mathtt{int}}{\Gamma, \Delta \vdash \mathtt{ArrayAccess}(\mathtt{ptr}, \mathtt{idx}) : \tau} \text{ } \mathsf{ARRAY}$$

$$\frac{\Gamma, \Delta \vdash \mathtt{ptr} : \&\mathtt{struct}_{id} \qquad \Delta(id)(\mathtt{fld}) = \tau}{\Gamma, \Delta \vdash \mathtt{FieldAccess}(\mathtt{ptr}, \mathtt{fld}) : \tau} \text{ }_{\mathrm{FIELD}}$$

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\frac{\texttt{callee} \neq \texttt{main} \qquad \Gamma, \Delta \vdash \texttt{callee} : \&(\vec{\tau}) \rightarrow \tau_r \qquad \forall (\texttt{e}, \tau) \in (\texttt{args}, \vec{\tau}) \,. \, [\Gamma, \Delta \vdash \texttt{e} : \tau]}{\Gamma, \Delta \vdash \texttt{Call}(\texttt{callee}, \texttt{args}) : \tau_r} \\ \qquad \qquad \qquad \texttt{ECALL-INTERNAL}
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\frac{\Gamma, \Delta \vdash \mathsf{callee} : (\vec{\tau}) \to \tau_r \qquad \forall (\mathsf{e}, \tau) \in (\mathsf{args}, \vec{\tau}) \,.\, [\Gamma, \Delta \vdash \mathsf{e} : \tau]}{\Gamma, \Delta \vdash \mathsf{Call}(\mathsf{callee}, \mathsf{args}) : \tau_r} \;\; \text{\tiny ECALL-EXTERN}
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We need two different call rules because internally defined functions are present in Γ as pointer types (in order to allow for function pointers and indirect calls) while externally defined functions are present in Γ as function types (because we can't call them indirectly via pointers).

3.4 Statement Typing Rules

Typing judgements for statement nodes in the AST are of the form $\Gamma, \Delta, \tau_r^2, \mathbf{loop} \vdash \mathbf{stmt} : \mathbf{ok}$, where τ_r^2 is the (optional) return type of the function containing \mathbf{stmt} and \mathbf{loop} is a boolean indicating whether \mathbf{stmt} is contained inside a while loop.

$$\frac{\mathbf{loop} = \mathbf{true}}{\Gamma, \Delta, \tau_r^?, \mathbf{loop} \vdash \mathtt{Break} : \mathbf{ok}} \ \mathtt{BREAK}$$

$$\frac{\mathbf{loop} = \mathbf{true}}{\Gamma, \Delta, \tau_r^?, \mathbf{loop} \vdash \mathtt{Continue} : \mathbf{ok}} \ \ ^{\mathtt{CONTINUE}}$$

$$\frac{\tau_r^? = \mathbf{none}}{\Gamma, \Delta, \tau_r^?, \mathbf{loop} \vdash \mathtt{Return}(\mathbf{none}) : \mathbf{ok}} \text{ RETURN-1}$$

$$\frac{\Gamma, \Delta \vdash \mathbf{e} : \tau \qquad \tau_r^? = \tau}{\Gamma, \Delta, \tau_r^?, \mathbf{loop} \vdash \mathtt{Return}(\mathbf{e}) : \mathbf{ok}} \text{ RETURN-2}$$

$$\frac{\Gamma, \Delta \vdash \mathtt{lhs} : \tau \qquad \Gamma, \Delta \vdash \mathtt{e} : \tau \qquad \tau \not\in \{\mathtt{struct}_{id}, (\vec{\tau}) \to \tau_r\}}{\Gamma, \Delta, \tau_r^?, \mathbf{loop} \vdash \mathtt{Assign}(\mathtt{lhs}, \mathtt{e}) : \mathbf{ok}} \quad \text{\tiny ASSIGN-EXP}$$

$$\frac{\Gamma, \Delta \vdash \mathbf{lhs} : \& \tau \qquad \Gamma, \Delta \vdash \mathbf{e} : \mathbf{int} \qquad \tau \neq (\vec{\tau}) \to \tau_r}{\Gamma, \Delta, \tau_r^?, \mathbf{loop} \vdash \mathbf{Assign}(\mathbf{lhs}, \mathbf{New}(\tau, \mathbf{e})) : \mathbf{ok}} \quad \text{Assign-New}$$

$$\frac{\Gamma, \Delta \vdash \mathtt{callee} : (\vec{\tau}) \rightarrow \tau_1^? \qquad \forall (\mathtt{e}, \tau) \in (\mathtt{args}, \vec{\tau}) \,.\, [\Gamma, \Delta \vdash \mathtt{e} : \tau]}{\Gamma, \Delta, \tau_r^?, \mathbf{loop} \vdash \mathtt{Call}(\mathtt{callee}, \mathtt{args}) : \mathbf{ok}} \;\; \mathtt{SCALL\text{-}EXTERN}$$

$$\frac{\Gamma, \Delta \vdash \mathbf{e} : \mathtt{int} \qquad \forall s \in \mathtt{tt} \,. \, [\Gamma, \Delta, \tau_r^?, \mathbf{loop} \vdash s : \mathbf{ok}] \qquad \forall s \in \mathtt{ff} \,. \, [\Gamma, \Delta, \tau_r^?, \mathbf{loop} \vdash s : \mathbf{ok}]}{\Gamma, \Delta, \tau_r^?, \mathbf{loop} \vdash \mathtt{If}(\mathbf{e}, \mathtt{tt}, \mathtt{ff}) : \mathbf{ok}} \ _{\mathrm{IF}}$$

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\frac{\Gamma, \Delta \vdash \mathbf{e} : \mathtt{int} \qquad \forall s \in \mathtt{body} \,.\, [\Gamma, \Delta, \tau_r^?, \mathbf{true} \vdash s : \mathbf{ok}]}{\Gamma, \Delta, \tau_r^?, \mathbf{loop} \vdash \mathtt{While}(\mathbf{e}, \mathtt{body}) : \mathbf{ok}} \quad \text{WHILE}
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3.5 Program Typing Rules

Typing judgements for the Program node and its children in the AST are of the form $\Gamma, \Delta \vdash \text{node} : \text{ok}$.

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 \frac{\forall g \in \mathtt{globs} \,.\, [\Gamma_0, \Delta \vdash g : \mathbf{ok}] \qquad \forall s \in \mathtt{structs} \,.\, [\Gamma_0, \Delta \vdash s : \mathbf{ok}] \qquad \forall f \in \mathtt{funcs} \,.\, [\Gamma_0, \Delta \vdash f : \mathbf{ok}]}{\Gamma_0, \Delta \vdash \mathtt{Program}(\mathtt{globs}, \mathtt{structs}, \mathtt{externs}, \mathtt{funcs}) : \mathbf{ok}} \ _{\mathtt{PROGRAM}}
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The PROGRAM rule is the entry point for the type checker; it kicks everything off by calling all the other rules directly or transitively. Note that it explicitly uses Γ_0 , the initial type environment, whereas all other rules use whatever type environment is passed to them.

$$\frac{\tau \not \in \{\mathtt{struct}_{id}, (\vec{\tau}) \to \tau_r\}}{\Gamma, \Delta \vdash \mathtt{Decl}(\mathtt{name}, \tau) : \mathbf{ok}} \text{ GLOBAL}$$

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\frac{\forall \mathtt{Decl}(\mathtt{name},\tau) \in \mathtt{flds} \, . \, [\tau \not\in \{\mathtt{struct}_{id},(\vec{\tau}) \to \tau_r\}]}{\Gamma, \Delta \vdash \mathtt{Struct}(\mathtt{name},\mathtt{flds}) : \mathbf{ok}} \,\, \mathtt{STRUCT}
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 \begin{array}{|c|c|c|c|}\hline & \Gamma' = \texttt{prms} \sqcup \texttt{locals.decls} & \forall \texttt{Decl}(\texttt{name}, \tau) \in \Gamma' . \left[\tau \not\in \{\texttt{struct}_{id}, (\vec{\tau}) \to \tau_r\}\right] & \Gamma'' = \Gamma \sqcup \Gamma' \\ & \forall (\texttt{Decl}(\texttt{name}, \tau), \texttt{e}) \in \texttt{locals} . \left[\Gamma'', \Delta \vdash \texttt{e} : \tau\right] & \forall s \in \texttt{stmts} . \left[\Gamma'', \Delta, \tau_r^?, \texttt{false} \vdash s : \texttt{ok}\right] \\ & & \Gamma, \Delta \vdash \texttt{Function}(\texttt{name}, \texttt{prms}, \tau_r^?, \texttt{locals}, \texttt{stmts}) : \texttt{ok} \\ \hline \end{array}
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The notation $\Gamma' = \text{prms} \sqcup \text{locals.decls}$ means to turn the parameter and local declarations (ignoring any optional local initializations) into a type environment, i.e., a map from names to types, allowing any entries from the right-hand side to override entries with the same name on the left-hand side. In other words, a local declaration overrides a parameter declaration with the same name. Similarly for $\Gamma'' = \Gamma \sqcup \Gamma'$ any entry from Γ' overrides an entry with the same name in Γ .