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Part C

```
robot_coin_collector;

A = [    0.5 0 0 0 0 0
        2 0 0 0 0 0;
        4 0.5 0 0 0 0;
        6 2 0 0 0 0;
        8 4 0.5 0 0 0;
        10 6 2 0 0 0;
        12 8 4 0.5 0 0;
        14 10 6 2 0 0;
        16 12 8 4 0.5 0;
        18 14 10 6 2 0;
        20 16 12 8 4 0.5;
        22 18 14 10 6 2];

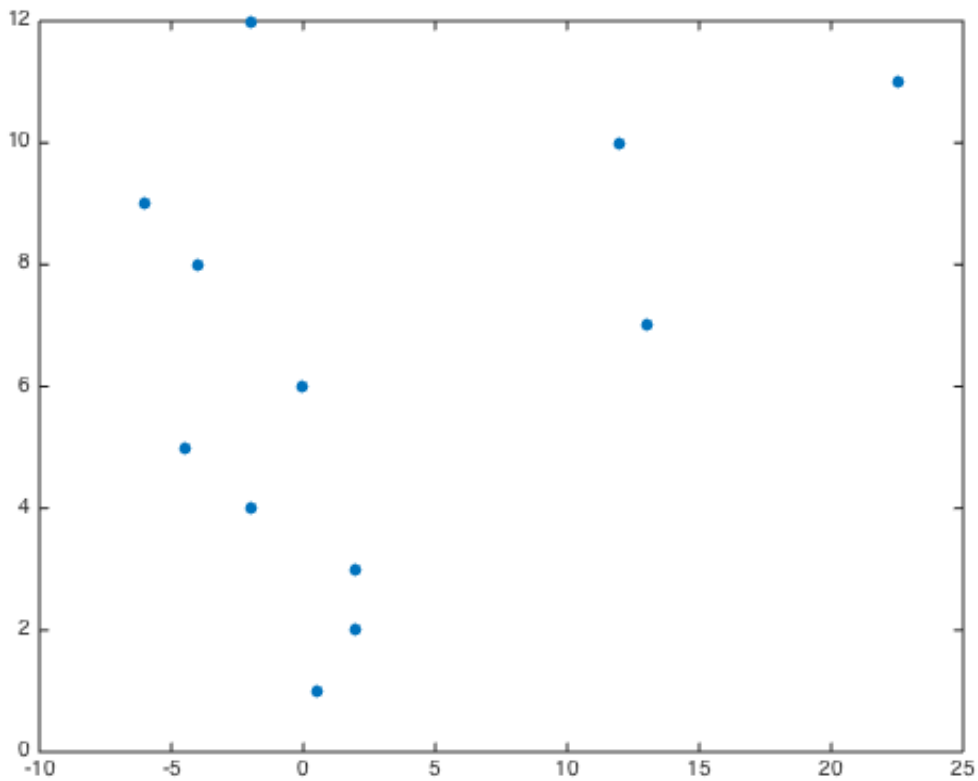
fEst = (A'*A)\A'*x;

res = norm(A*fEst - x)^2;

if( res > 0.0001)
    ['The robot is not able to collect all of the coins. The residual is ' num2str(res)]
else
    'The robot is able to collect all coins because J = 0'
end
```

ans =

The robot is not able to collect all of the coins. The residual is 37.992



Part E

```

for i = 1:2*n
    if i == 1
        A = 0.5;
        continue;
    elseif i == 2
        A = [0.5;2];
        continue;
    %even rows
    elseif mod(i,2) == 0
        %new row will be of length i/2
        arow = zeros(1, i/2);
        arow(end) = 2;
        for j = 1:length(arow)-1
            arow(j) = 2*(i-1) - 4*(j-1);
        end
    %odd rows
    else
        arow = zeros(1, (i+1)/2);
        arow(end) = 0.5;
        for j = 1:length(arow)-1
            arow(j) = 2*(i-1) - 4*(j-1);
        end
    end
end

if( mod(i,2) ~= 0)
    A = [A zeros(i-1,1)];
end

```

```

end
A = [ A ; arow];

% Test for which coin cannot be reached
%Least squares to get forces
if mod(i,2) ~= 0
    rows = 1:2:i;
    f = (A(rows,:)'*A(rows,:))\A(rows,:)'*x(rows);%x(1:i);
end
res = norm(A*f - x(1:i))^2;
if res > 0.0001
    ['The residual is non-zero and therefore coin ' num2str(i) ' cannot be reached']
    %break;
end
end

xpositions = A*forces;
forces

figure; hold;
plot(x,1:2*n, '.', 'MarkerSize',20);
plot(xpositions, 1:2*n, '*');

```

ans =

The residual is non-zero and therefore coin 8 cannot be reached

ans =

The residual is non-zero and therefore coin 9 cannot be reached

ans =

The residual is non-zero and therefore coin 10 cannot be reached

ans =

The residual is non-zero and therefore coin 11 cannot be reached

ans =

The residual is non-zero and therefore coin 12 cannot be reached

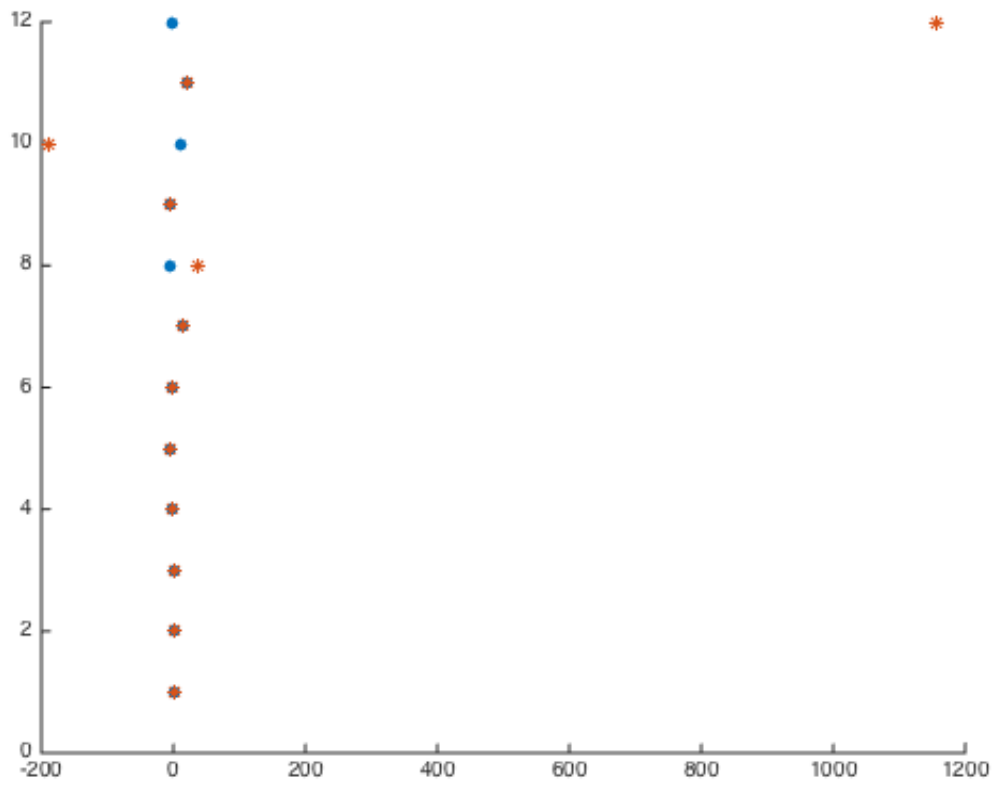
forces =

```

    1.0000
   -4.0000
    7.0000
   10.0000
  -140.0000
   925.0000

```

Current plot held



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