

nanort::IntersectRayAABB  
< double >

nanort::IntersectRayAABB  
< float >

nanort::safemax

```
graph LR; A[nanort::IntersectRayAABB< double >] --> C[nanort::safemax]; B[nanort::IntersectRayAABB< float >] --> C;
```

The diagram illustrates a common variable, `nanort::safemax`, which is referenced by two different function templates. The first template, `nanort::IntersectRayAABB< double >`, is shown in a white box with a black border. The second template, `nanort::IntersectRayAABB< float >`, is also in a white box with a black border. Both templates have a blue arrow pointing to the `nanort::safemax` variable, which is contained within a gray box with a black border. This suggests that `safemax` is a shared resource or a common state that both functions rely on.