

CreatePath



```
graph LR; A[CreatePath] --> B[HF::Pathfinding::FindPath]
```

The diagram consists of two rectangular boxes connected by a blue arrow pointing from left to right. The left box is white with a black border and contains the text 'CreatePath'. The right box is gray with a black border and contains the text 'HF::Pathfinding::FindPath'.

HF::Pathfinding::FindPath