

CreatePath



```
graph LR; A[CreatePath] --> B[HF::Pathfinding::FindPath]
```

The diagram consists of two rectangular boxes connected by a blue arrow. The left box is white with a black border and contains the text 'CreatePath'. The right box is gray with a black border and contains the text 'HF::Pathfinding::FindPath'. A blue arrow points from the right side of the first box to the left side of the second box.

HF::Pathfinding::FindPath