



# **Measuring the Muon Neutrino Magnetic Moment in the NOvA Near Detector**

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*A thesis submitted in fulfilment of the requirements for the degree of  
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I hereby declare that I carried out this thesis independently, and only with the cited sources, literature and other professional sources.

I also declare that this thesis has not been and will not be, submitted in whole or in part to another University for the award of any other degree.

*Brighton, United Kingdom,*

*July 20, 2024*

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# Acknowledgements

School of Mathematical and Physical Sciences, University of Sussex

DOCTORAL THESIS

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by Róbert Králik

**ABSTRACT**

Measuring an enhanced neutrino magnetic moment would be a clear indication of physics beyond the Standard Model (BSM), shedding light on the correct BSM theory or the potential Majorana nature of neutrinos. It would manifest in the NOvA near detector as an excess of neutrino-on-electron elastic scattering interactions at low electron recoil energies. Leveraging an intense and highly pure muon neutrino beam, along with the finely segmented liquid scintillator detector technology specifically designed for electromagnetic shower separation, enables NOvA to achieve a potentially world-leading sensitivity in probing the effective muon neutrino magnetic moment. Despite facing statistical limitations stemming from the low cross section of the signal process, systematic uncertainties have a significant impact on this result. To address these challenges, the NOvA Test Beam experiment focuses on mitigating some of the largest systematic uncertainties within NOvA by investigating particle interactions and energy deposition in a small-scale replica NOvA detector. This thesis describes the calibration of the NOvA Test Beam detector, which is a crucial step in analysing the Test Beam data before they can be utilised to reduce NOvA systematic uncertainties.  
*COMMENT: Add final numbers for the analyses, also the POT and such*

Keywords: neutrino NOvA electromagnetic testbeam calibration

# Contents

<b>Acknowledgements</b>	<b>ii</b>
<b>List of Figures</b>	<b>vi</b>
<b>List of Tables</b>	<b>viii</b>
<b>Preface</b>	<b>ix</b>
<b>1 The NOvA Experiment</b>	<b>1</b>
1.1 The Neutrino Beam . . . . .	1
1.2 The NOvA Detectors . . . . .	4
1.3 Readout and Data Acquisition . . . . .	6
1.4 Simulation . . . . .	8
1.5 Data Processing and Event Reconstruction . . . . .	11
1.6 Detector Calibration . . . . .	14
1.6.1 Scale . . . . .	17
1.6.2 Threshold and Shielding Correction . . . . .	17
1.6.3 Relative Calibration . . . . .	18
1.6.4 Absolute Calibration . . . . .	21
1.7 Energy Estimation . . . . .	22
1.8 Systematic Uncertainties . . . . .	22
<b>2 Measuring the Muon Neutrino Magnetic Moment</b>	<b>26</b>
2.1 Theory of the Neutrino Magnetic Moment . . . . .	28
2.1.1 Neutrino Electric and Magnetic Dipole Moments . . . . .	30
2.1.2 Measuring the Neutrino Magnetic Moment . . . . .	33
2.2 Analysis Overview . . . . .	39
2.3 Event Selection . . . . .	42
2.3.1 Data Collection Quality . . . . .	43
2.3.2 Reconstruction Quality . . . . .	43
2.3.3 Pre-Selection . . . . .	47
2.3.4 Fiducial and Containment Cuts . . . . .	51

2.3.5	Multivariate Analysis Cuts . . . . .	53
2.4	Systematic Uncertainties . . . . .	69
2.5	Results . . . . .	72
2.5.1	Hypothesis Testing . . . . .	74
2.5.2	Nuisance Parameters . . . . .	77
2.5.3	Unbinned Parameter Estimation . . . . .	78
2.6	Discussion . . . . .	78
2.7	Summary . . . . .	79
	<b>Acronyms</b>	<b>81</b>
	<b>Bibliography</b>	<b>84</b>

# List of Figures

1.1	The schematic of the NuMI beam facility . . . . .	2
1.2	NuMI neutrino beam components in the NOvA near detector . . . . .	3
1.3	The NOvA off-axis beam concept . . . . .	3
1.4	NOvA detectors . . . . .	4
1.5	NOvA Avalanche Photo Diodes . . . . .	6
1.6	NOvA Front End Board . . . . .	7
1.7	NOvA reconstruction of a single electron . . . . .	12
1.8	NOvA detectors event topologies . . . . .	13
1.9	Tricell condition for calibration hits in NOvA . . . . .	16
1.10	Fibre Brightness bins for the NOvA calibration . . . . .	17
1.11	Example attenuation fit for NOvA Relative calibration . . . . .	19
1.12	Example LOWESS correction for NOvA relative calibration . . . . .	20
1.13	Example distributions for the NOvA absolute calibration . . . . .	21
2.1	Effective coupling of neutrinos with one photon electromagnetic field. . . . .	28
2.2	Neutrino-on-electron elastic scattering diagram . . . . .	33
2.3	Electron recoil energy versus recoil angle . . . . .	34
2.4	Comparison of the neutrino magnetic moment and Standard Model cross sections . . . . .	36
2.5	Ratio of the neutrino magnetic moment and Standard Model cross sections . . . . .	38
2.6	Vertex reconstruction quality cut . . . . .	45
2.7	Prong and hits reconstruction quality cuts . . . . .	46
2.8	Low calorimetric energy cut for reconstruction quality . . . . .	48
2.9	Number of hits cut for pre-selection . . . . .	49
2.10	Length of the longest prong cut for pre-selection . . . . .	50
2.11	$E\theta^2$ cut for pre-selection . . . . .	52
2.12	Vertex x containment cut . . . . .	54
2.13	Vertex y containment cut . . . . .	55
2.14	Vertex z containment cut . . . . .	56

2.15 Hit minimum x containment cut . . . . .	57
2.16 Hit maximum x containment cut . . . . .	58
2.17 Hit minimum y containment cut . . . . .	59
2.18 Hit maximum y containment cut . . . . .	60
2.19 Hit minimum z containment cut . . . . .	61
2.20 Hit maximum z containment cut . . . . .	62
2.21 Shower E fraction and number of hits cuts . . . . .	66
2.22 Reconstructed energy and $E\theta^2$ cuts . . . . .	67
2.23 NuoneID and EPi0ID cuts . . . . .	68
2.24 Background composition of final selection . . . . .	69
2.25 Summary of systematic uncertainties . . . . .	70
2.26 Neutrino flux systematic uncertainty . . . . .	71
2.27 Detector systematic uncertainties . . . . .	72
2.28 Final prediction and data comparison . . . . .	73
2.29 Fit results . . . . .	75

# List of Tables

1.1	Models and tunes used in the NOvA simulation of neutrino interactions.	10
2.1	Overview of the simulation samples and analysis weight used for the different signal and background components. . . . .	42
2.2	Event selection summary . . . . .	44
2.3	Event selection cutflow table for the reconstruction quality cuts . . . . .	47
2.4	Event selection cutflow table for the pre-selection . . . . .	51
2.5	Event selection cutflow table for the containment cuts . . . . .	63
2.6	Multivariate analysis cutflow table . . . . .	65
2.7	Interactions contributing to the SM background . . . . .	69

# Preface

In this Preface, I provide an overview of the research presented in this thesis, highlighting my personal contributions to the work presented in each chapter.

In chapter ?? I present an overview of the relevant literature of neutrinos and their place in the particle physics theory and experiments.

In chapter 1 I introduce the NOvA experiment, relying on publicly available information from published articles , theses, and presentations, as well as on internal NuMI Off-axis  $\nu_e$  Appearance (NOvA) documentation when a higher detail is required. This chapter presents a complete overview of the experiment’s technical aspects relevant to either the measurement of the effective muon neutrino magnetic moment, or to the calibration of the NOvA Test Beam detector. This chapter is mainly a collection of work of my NOvA collaborators, their technical design reports for the NOvA experiment and official results. My only contribution to this chapter lies in the addition of new external measurements from the NA61 experiment, to improve the neutrino beam prediction in NOvA.

Chapter ?? details the calibration of the NOvA Test Beam detector, divided into three main sections.

Section ?? describes the Test Beam detector itself, as designed and constructed by my NOvA Test Beam experiment colleagues.

Section ?? presents the data-based simulation of cosmic muons used for the calibration, which originates as a simpler version of the simulation by my colleague. I then improved the event selection, implemented the energy and charge assignment, and produced and validated the simulation and the corresponding calibration samples.

Lastly, Sec. ?? describes the Test Beam detector calibration itself, which uses the NOvA codebase for calibration. I fully implemented the NOvA calibration

Chapter 2 describes the measurement of the effective muon neutrino magnetic moment. Introduces the experimental and theoretical context for the measurement, describes the details of the analysis, including the event selection and the systematic uncertainties and describes the results and discusses their implications.

Finally, chapter ?? concludes the findings of this thesis.

## Data-based Simulation of Cosmic Muons

I also inherited the first-version of the data-based simulation of cosmic muons for the Test Beam detector. However, this version of the simulation was just directly taken from the simulation of the muon-removed sample and did not work properly for the Test Beam detector.

I developed and validated the event selection of cosmic muons for the data-based simulation, implemented the energy and charge correction. I developed the data-based simulation of cosmic muons described in Sec. Specifically, I developed the event selection, implemented the energy and charge corrections, actually produced the simulation and the calibration samples, and validated them

## Calibration of the NOvA Test Beam Detector

The Test Beam detector calibration (Sec. ??) uses the same calibration techniques as are used for the other NOvA detectors. I inherited the Test Beam detector calibration when it was technically working, but not for simulation. Therefore, I was the first person to calibrate the simulated Test Beam detector and therefore complete the entire Test Beam detector calibration chain. This allowed for the first proper production of data for the Test Beam analysers. Starting from here, I included the fibre brightness for the Test Beam detector in the same way as is used for the Near and Far NOvA detectors (Sec. ??).

I implemented the NOvA calibration procedure in full for the Test Beam calibration, specifically adding the Fibre Brightness dependency and implementing it for all the data and simulation samples. I've created my own fibre brightness maps, my own threshold and shielding corrections (found out about the issue), improved the NOvA calibration code, made the attenuation fits for all the samples, did the same for absolute calibration, figured out there is a mistake in geometry, figured out we need to add the underfilled cells to the dead channels, changed the TS correction limits, improved the systematic uncertainty for the absolute calibration, validated the calibration, developed code for the validation

## Measurement of the Effective Muon Neutrino Magnetic Moment

I was just told its an interesting analysis, there was a previous NOvA thesis, but it wasn't very well developed, did not use the standard NOvA techniques and did not properly incorporate systematics into their fits/limits. From the ND group, I got the event classifier and the event selection, which however did not work very well for our signal. Additionally, I got the nuone and the nueccmec enhanced samples and the radiative correction weight from them. From NOvA in general I got the nominal ND sample and the data sample, the cross section and PPFX weights and the fitting infrastructure in general. From the LDM analysis I got the general structure of the fitting framework.

I have done the literature review of what is the neutrino magnetic moment and what are its current limits and state of the art measurements. I designed the neutrino magnetic moment weight and developed my own event selection, including using the TMVA, which is not used elsewhere, and the general analysis infrastructure for the neutrino magnetic moment ana. I helped (re)produce the systematic samples for the nueccmec enhanced sample. Technically I also investigated the nominal ND sample and whether it would be better to use the decaf sample, but this led nowhere... Technically I also analysed the electron recoil energy and angle resolution and decided on the binning (although not finished and talked about here). I did the systematics study and implemented the systematic shifts for the detector systematics for numm. I implemented the fitting framework for the neutrino magnetic moment analysis for both the template fit (not used here) and the counting experiment. I did the actual fit and got the final results.

# CHAPTER 1

## The NOvA Experiment

The NOvA [1] experiment is a long-baseline neutrino oscillation experiment based at the Fermi National Accelerator Laboratory (Fermilab) [2]. NOvA receives an off-axis  $\nu_\mu$  and  $\bar{\nu}_\mu$  beam from Fermilab’s Neutrinos from the Main Injector (NuMI) neutrino source (Sec. 1.1) and measures  $\nu_e$  or  $\bar{\nu}_e$  appearance and  $\nu_\mu$  or  $\bar{\nu}_\mu$  disappearance between its two highly active and finely segmented detectors (Sec. 1.4) [3].

The capability to measure both  $\nu_e$  and the  $\bar{\nu}_e$  appearance, coupled with a significant matter effect induced by its long baseline, allows NOvA to address some of the most important questions in neutrino physics to date, such as the neutrino mass ordering, the octant of  $\theta_{23}$ , and the possible Charge conjugation - Parity (CP) symmetry violation in the neutrino sector [3–7]. NOvA data also enables measurements of  $\theta_{13}$ ,  $\theta_{23}$  and  $|\Delta m_{32}^2|$  [3], measurements of neutrino differential cross sections in the Near Detector (ND) [8–11], constraints on possible sterile neutrino models [12, 13], monitoring for supernova neutrino activity [14, 15], searches for magnetic monopoles [16], and constraints on the neutrino electromagnetic properties (this thesis). Using two functionally identical detectors mitigates the dominant systematic uncertainties of neutrino oscillation measurements, described in Sec. 1.8.

NOvA started taking data in February 2014 and is expected to run through 2026 [17], or until Fermilab begins redirecting its efforts towards the startup of the upcoming Deep Underground Neutrino Experiment (DUNE) experiment [18].

### 1.1 The Neutrino Beam

The neutrino beam for NOvA comes from the Fermilab-based NuMI neutrino source [19]. The schematic description of NuMI is shown in Fig. 1.1, starting on the left hand side with 120 GeV protons from the Main Injector (MI), part of the Fermilab accelerator complex. The proton beam is divided into 10  $\mu\text{s}$  long pulses, with  $\sim 5 \times 10^{13}$

Protons On Target (POT) per spill every  $\sim 1.3$  s long cycle time, resulting in a proton beam power of  $\sim 800$  kW (current record 959 kW [20]), with upgrades currently underway to surpass 1 MW [21].

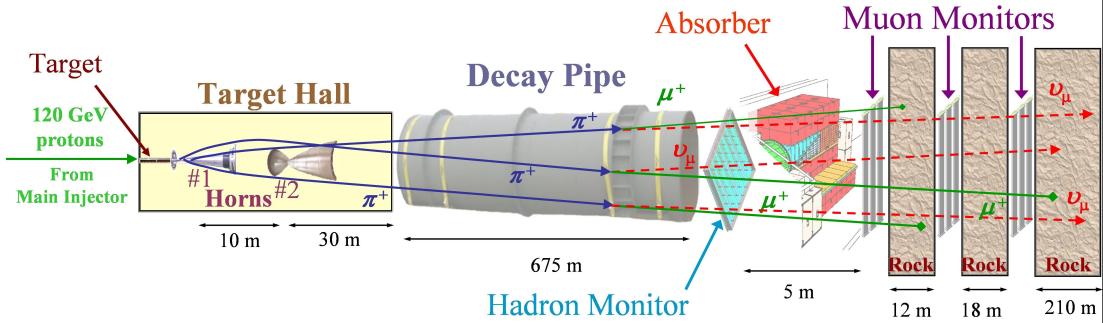


Figure 1.1: The NuMI neutrino beam starts on the left hand side with protons from the MI impinged on a graphite target producing mainly pions and kaons. These are then focused and charge-selected by two focusing horns, after which they decay inside the decay pipe into a high-purity  $\nu_\mu$  or  $\bar{\nu}_\mu$  beam. The residual hadrons are stopped and monitored in the hadron absorber and the remaining muons are recorded with muon monitors and absorbed inside the rock. Figure from [19].

The proton beam passes through a collimating baffle before hitting a  $\sim 1.2$  m-long (equal to about two interaction lengths) graphite target [22], producing hadrons, predominantly pions and kaons [19]. These are then focused and selected by two parabolic magnetic ‘horns’. The focused hadrons pass through a 675 m-long decay pipe filled with helium to create a low density environment for hadrons to propagate and decay in flight into either neutrinos or antineutrinos. High energy hadrons that do not decay in the decay pipe are absorbed within a massive aluminium, steel, and concrete hadron absorber and monitored with a hadron monitor. The leftover muons are ranged out in dolomite rock after the absorber and monitored using three muon monitors. The hadron and muon monitors are ionization chambers, used to monitor the quality, location and relative intensity of the beam.

Using a positive current inside the horns focuses positively charged particles, which then decay into neutrinos, and removes negatively charged particles. Reversing the horn current focuses negatively charged particles, which decay into antineutrinos, and defocuses positively charged particles. The neutrino mode is therefore called Forward Horn Current (FHC) and the antineutrino mode is called Reverse Horn Current (RHC). The composition of the neutrino beam for both these modes at the NOvA ND is shown in Fig. 1.2, displaying the very high purity of the  $\nu_\mu$  or  $\bar{\nu}_\mu$

component in the **FHC** ro **RHC** beam respectively [19].

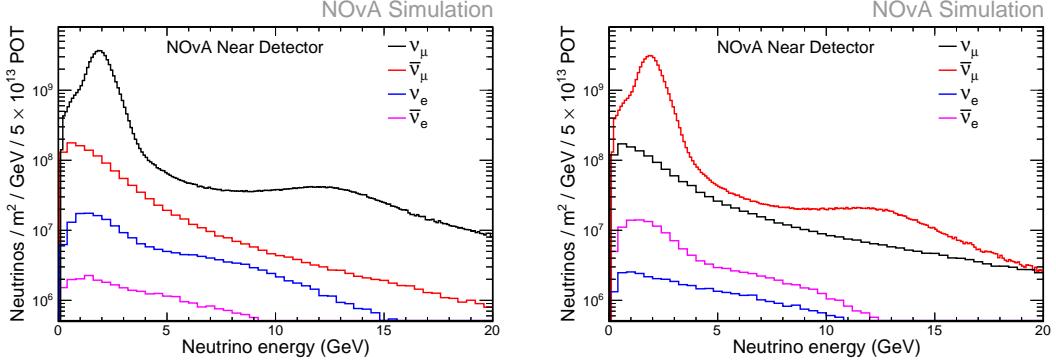


Figure 1.2: The components of the neutrino beam at the **NOvA ND** per one **NuMI** spill in the **FHC** regime shown on the left and the **RHC** regime on the right. The  $\nu_\mu$  ( $\bar{\nu}_\mu$ ) composition in the **FHC** (**RHC**) regime is 93.8% (92.5%), with a wrong sign contribution of 5.3% (6.6%) and only 0.9% (0.9%) contamination by  $\nu_e$  ( $\bar{\nu}_e$ ), showing the high purity of  $\nu_\mu$  and  $\bar{\nu}_\mu$  in the neutrino beam for **NOvA**. Beam composition values calculated for neutrinos with energies between 1 – 5 GeV. Figures are from internal **NOvA** repository [23].

The resulting neutrino beam energy distribution is peaked at  $\sim 7$  GeV with a wide energy band. However, thanks to the kinematics of the dominant pion decay, by placing the **NOvA ND** and Far Detector (FD) 14.6 mrad ( $\approx 0.8^\circ$ ) off the main **NuMI** beam axis, **NOvA** achieves a narrow band neutrino flux peaked at 1.8 GeV [7, 24], as can be seen in Fig. 1.3. Using an off-axis neutrino flux increases the neutrino beam around 2 GeV about 5-fold compared to the on-axis flux and narrow-band peak enhances background rejection for the  $\nu_e$  appearance analysis [24].

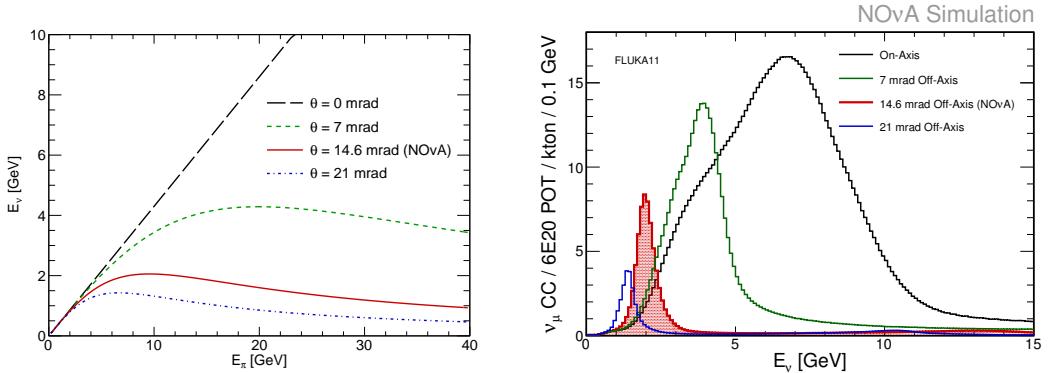


Figure 1.3: (Left) Dependence of the neutrino energy on the parent pion's energy and (right) neutrino energy distribution for an on-axis beam and three different off-axis beam designs. The case for **NOvA** is shown in red and results in a narrow neutrino energy distribution around 2 GeV, with limited dependence on the parent pion's energy. Figure from [24]

## 1.2 The NOvA Detectors

The two main NOvA detectors are the ND, located in Fermilab  $\sim 1$  km from the NuMI target and  $\sim 100$  m under ground, and the FD, located  $\sim 810$  km from Fermilab at Ash River in north Minnesota, partially underground with a rock overburden [24]. NOvA also operated a detector prototype called Near Detector on the Surface (NDOS), which was used for early research and development of detector components and analysis [4]. Additionally, NOvA operated a Test Beam detector, described in detail in Sec. ???. The scales of the ND and FD are shown in Fig. 1.4.

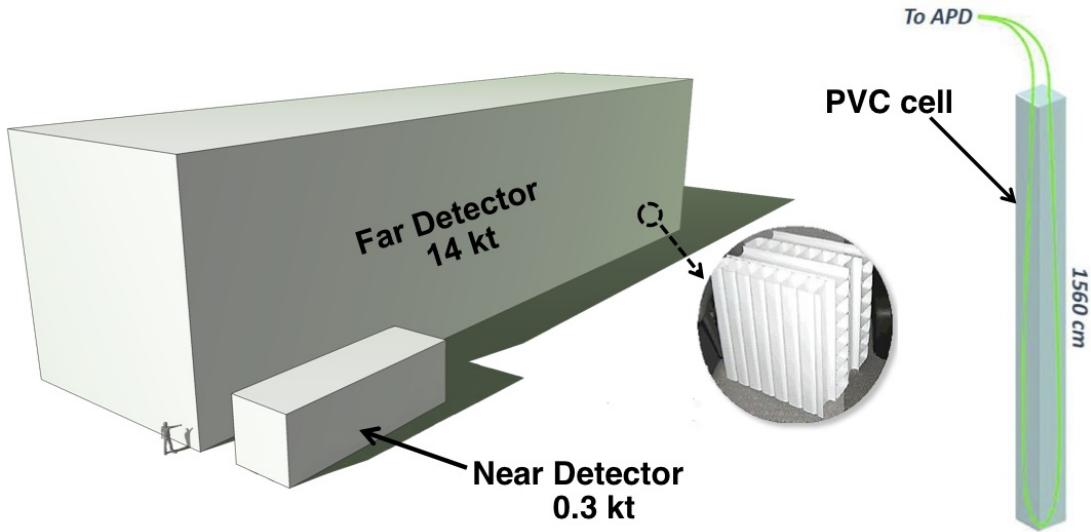


Figure 1.4: Schematic description of the scale and composition of the NOvA ND and FD. The inset shows a photo of the orthogonal planes made out of PVC cells. An example of a FD cell containing liquid scintillator and a looped WLS fibre attached to an APD is shown on the right [25].

All NOvA detectors are highly segmented, highly active, functionally identical tracking calorimeters made up of Polyvinyl chloride (PVC) cells filled with liquid scintillator. Each cell is a long rectangular cuboid with depth of 5.9 cm and width of 3.8 cm (with some variations), with cell length extending to the full width/height of each detector, which is  $\sim 4.1$  m for the ND and  $\sim 15.6$  m for the FD [24]. An example of a FD cell is shown on the right of Fig. 1.4.

Cells are connected side-by-side into a 16 cell-wide extrusions with 3.3 mm-wide walls between cells and 4.9 mm-wide walls on the outsides of the extrusions. The first and last cell of each extrusion are  $\sim 3$  mm narrower than the rest of the cells. Two extrusions are connected side-by-side to form a 32 cell-wide module, with each

module having a separate readout (see Sec. 1.3). In the **FD**, 12 modules are connected side-by-side to form one plane of the detector. In the **ND** only 3 modules make up a plane. Planes are positioned one after another, alternating between vertical and horizontal orientation, and grouped into diblocks, each containing 64 planes. The **FD** contains 14 diblocks, totalling 896 planes, whereas the **ND** contains 3 diblocks totalling 192 planes. The **ND** also contains a Muon Catcher region, positioned right after the active region, consisting of 22 planes of the normal **NOvA** detector design, 2 modules high and 3 modules wide, sandwiched with 10 steel plates to help range out muons mainly from the  $\nu_\mu$  charged current interactions [4, 24].

The **NOvA** coordinate system is centred with  $(0, 0, 0)$  in the centre of the first plane, relative to the beam direction. The x axis runs from left to right when facing the detector, y axis from bottom to top and z axis runs perpendicular to the planes along the beam direction.

Each cell is filled with a liquid scintillator consisting of mineral oil with 4.1% pseudocumene as the scintillant [26]. Each cell contains a single wavelength shifting fibre with double the length of the cell, looping at one end and connecting to the readout at the other. The **PVC** walls of the cells are loaded with highly reflective titanium dioxide, with light typically bouncing off the **PVC** walls  $\sim 8$  times before being captured by the Wavelength Shifting (WLS) fibre [24].

The final dimensions of the **FD** are  $15.6\text{ m} \times 15.6\text{ m} \times 60\text{ m}$  with a total mass of 14 kT and for the **ND** the dimensions are  $3.8\text{ m} \times 3.8\text{ m} \times 12.8\text{ m}$  with a mass of about 0.3 kT [17]. The active volume, consisting only of the liquid scintillator without the **PVC** structure, makes up about 70% of the total detector volume [24].

The **NOvA** detectors are specifically designed for electromagnetic shower identification, with a radiation length of 38 cm, which amounts to  $\sim 7$  planes for particles travelling perpendicular to the detector planes [4]. This is particularly useful to distinguish electrons from  $\pi^0$ s.

We can calculate the minimum energy an electron needs to have to cross one cell (5.9 cm) of the **NOvA** detector by using the measured scintillator density  $0.86\text{ g/cm}^3$  [27], which gives us the required range of  $\sim 5\text{ g/cm}^2$ . Comparing this to measured values for the electron range [28] in the continuous slowing down approximation in a Polyethylene (approximation of the **NOvA** scintillator [29]), gives us an estimate of

the lowest detectable electron energy as  $E_e \gtrsim 10$  MeV.

### 1.3 Readout and Data Acquisition

The signal from the WLS fibres is read out by an Avalanche Photodiode (APD), converting the scintillation light into electrical signal, with a high quantum efficiency of  $\sim 85\%$  and a gain of 100 [24]. An example APD is shown in Fig. 1.5. Both ends of each fibre correspond to a single readout channel and are connected to one of the 32 pixels on the APD, organized in four rows of 8 pixels, with each APD reading out signal from one module. To maximise the signal to noise ratio, the APDs are cooled to  $-15^\circ\text{C}$  by a thermoelectric cooler, with heat carried away by a water cooling system.

The combination of the APD quantum efficiency and the light yield, determined by the PVC reflectivity and the scintillator and WLS fibre responses, result in a signal requirement of at least 20 Photo Electron (PE) in response to minimum ionizing radiation at the far end of the FD cell.

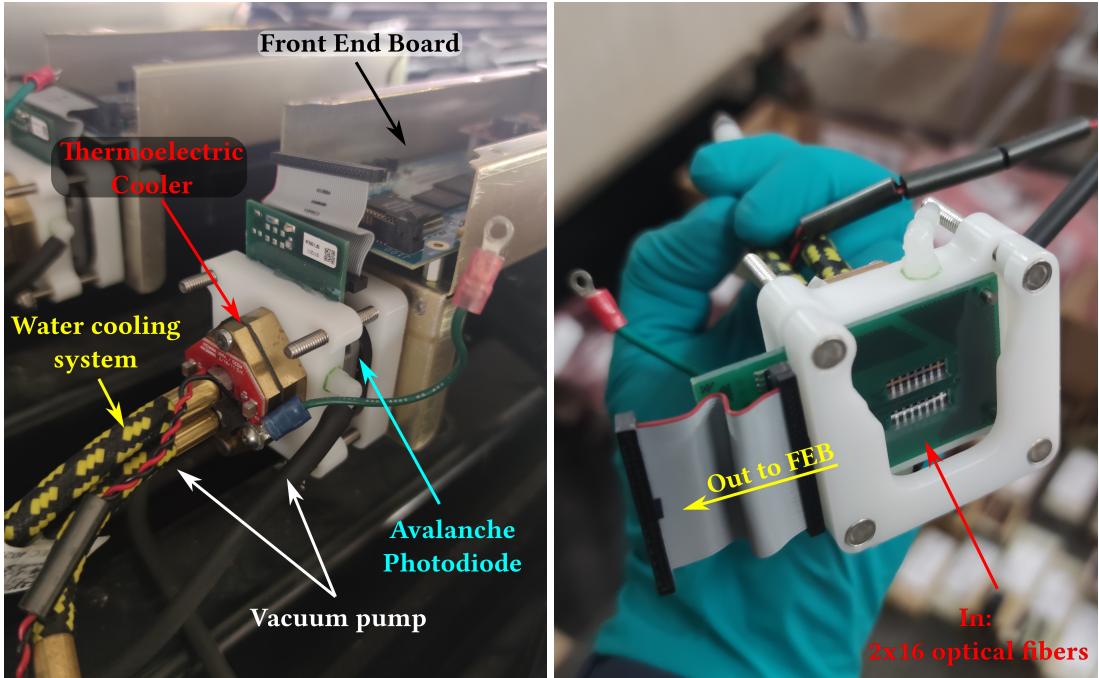


Figure 1.5: The modules with APDs for NOvA mounted on top of the detector on the left picture, and shown from the bottom on the right. The individual components of the module are described. The left picture shows a disconnected ribbon cable and ground cable, which are normally connected to the front end board.

Each APD is connected to a single Front End Board (FEB), shown in Fig. 1.6. The FEB amplifies and integrates the APD signal, determines its amplitude and arrival

time, before passing it to the Data Acquisition (DAQ) system. On the **FEB** the **APD** signal is first passed to a custom **NOvA** Application-Specific Integrated Circuit (ASIC), which is designed to maximize the detector sensitivity to small signals. **ASICs** amplify, shape and combine the signal, before sending it to an Analog-to-Digital Converter (ADC). The combined noise from the **APD** and the amplifier is equivalent to about 4 **PEs**, which, compared to an average **PE** yield from the far end of the **FD** cell of 30, results in a good signal and noise separation [24]. The digitized data from an **ADC** is sent to a Field Programmable Gate Array (FPGA), which extracts the time and amplitude of the **ADC** signals, while subtracting noise based on a settable threshold. The **FPGAs** employ multiple correlated sampling methods to reduce noise and improve time resolution of the signal [30].

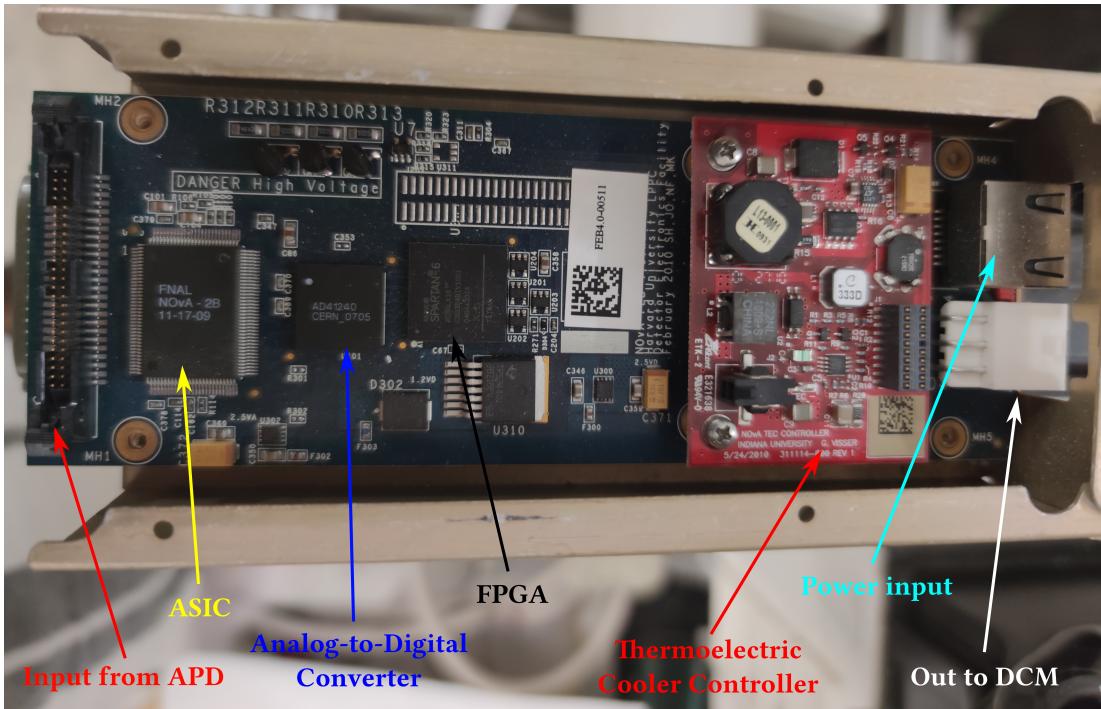


Figure 1.6: An example of a **NOvA FEB** with individual components labelled.

All of the **NOvA** front end electronics (**APDs** and **FEBs**) are operated in a continuous readout mode, without requiring any external triggers [24]. Due to higher detector activity during beam spills, the **ND FEBs** work at a higher frequency of 8 MHz, whereas the **FD FEBs** suffice with 2 MHz sampling frequency [30].

Data from up to 64 **FEBs** are concentrated in a Data Concentration Module (DCM), which concatenates and packages the data into 5 ms time slices, before sending it to the buffer nodes. **DCMs** are also connected to the timing system and pass a single

unified timing measurement to the [FEBs](#) to maintain synchronization across the detector [30].

The buffer nodes cache the data for at least 20 seconds while receiving information from the trigger system. Each trigger uses a time window based either on the time of the [NuMI](#) beam spill, on a periodic interval for monitoring and for the readout of cosmic events, or on one of the activity-based data-driven triggers [30]. Data that fall within any of the trigger windows are sent to a data logger system, where they are merged to form events, before being written to files for offline processing and sent to an online monitoring system. Files are organized based on a unique combination of run and subrun numbers, with runs corresponding to data taking periods with constant detector conditions and limited to either 64 subruns or 24 hours. Subruns are delineated either by a 2 GB file size constraint or a 1-hour timeout limit [31].

The detectors are continuously monitored to ensure data stability and quality. Subruns with suboptimal detector conditions or with events failing basic quality criteria are flagged as ‘bad’ and recorded in a ‘bad runs list’ [31]. Additionally, individual readout channel are assessed on a per-subrun basis, with those with too high or too low hit rates marked as ‘bad’ [32]. Both the ‘good runs’ list and the ‘bad channel’ maps are used to inform event processing and during simulation to emulate real detector conditions.

## 1.4 Simulation

To extract neutrino oscillation parameters, or to test a hypothesis, [NOvA](#) uses a series of simulations to make predictions according to various physical models [33]. The simulation chain can be divided into four parts: simulation of the neutrino beam, simulation of neutrino interactions within the [NOvA](#) detectors, simulation of cosmic particles interacting in the [NOvA](#) detector and simulation of the detector and readout response.

To simulate the neutrino beam, [NOvA](#) uses a simulation based on the GEANT4 v9.2.p03 [34] Monte Carlo (MC) event generator with a detailed model of the [NuMI](#) beamline [35], as described in Sec. 1.1. The simulation starts with the 120 GeV/c [MI](#) protons interacting within the long carbon target and producing hadrons, mainly

$\pi$ ,  $K$  and secondary protons. This is followed by transport and possible further interaction of hadrons within the focusing system, until finally ending with hadron decays producing the neutrino beam.

To account for the inherently imprecise theoretical models used in GEANT4, **NOvA** uses the Package to Predict the Flux (**PPFX**) to incorporate external measurements of yields and cross sections of hadron interactions inside the target and the other **NuMI** materials into the neutrino beam prediction [36]. The current version of **PPFX** is limited by the results available during its creation and only corrects the most frequent interactions while assigning conservative systematic uncertainties to the rest (see Sec. 1.8). For the most common  $\pi$ ,  $K$  and  $p$  production, **PPFX** uses the NA49 measurements [37–39] of 158 GeV/c protons interacting on a thin (few percent of interaction length) carbon target. To expand the kinematic coverage, **PPFX** uses a few data points from Barton et al [40] for the  $\pi$  production and  $K/\pi$  ratios from the Main Injector Particle Production (MIPP) [41] experiment for the production of  $K$ . These results have to be scaled to the 20 – 120 GeV/c incident proton moment seen throughout **NuMI** using the FLUKA [42, 43] **MC** generator.

There are two new experiments that measure the production and interaction of hadrons on various targets and incident energies, specifically designed to improve the prediction of neutrino beams. The most impactful measurements from the NA61 experiment are of the 120 GeV/c protons on a thin carbon target [44–46], of the hadron incident interactions on various materials [47], and of the 120 GeV/c protons on a **NuMI** replica target [48]. Additionally, the Fermilab-based EMPHATIC experiment [49] is currently analysing a broad range of hadron production and secondary and tertiary interaction measurements for neutrino beam prediction with a significant involvement of **NOvA** and **DUNE** collaborators. Inclusion of the results from both of these measurement is currently under way and will significantly improve the neutrino beam prediction in **NOvA** [48].

The output of the neutrino beam simulation is passed to the simulation of neutrino interactions inside the detectors, which is done with the GENIE v3.0.6 [50] neutrino **MC** generator. GENIE allows users to choose the particular models for different types of neutrino interactions and particle propagation within the nucleus, as well as possible tunes to external measurements. The four main interaction modes in GENIE are

the Quasi-Elastic (QE) Charged Current (CC) scattering, the Resonant baryon production (Res), the Deep Inelastic Scattering (DIS), and the Coherent  $\pi$  (COH $\pi$ ) production. The special case of the two particle - two hole (2p2h) interaction via Meson Exchange Current (MEC) and the Final State Interaction (FSI) inside a nucleus are also considered. The initial state of the nucleus is represented by a local Fermi gas in the QE and 2p2h models, while a global relativistic Fermi gas is used for all other processes. All of these are set by the Comprehensive Model Configuration (CMC), which is currently N1810j0000 for NOvA. Additionally, NOvA adds a costume tune to the NOvA  $\nu_\mu$ CC data for a better constraint of the CCMEC interactions. NOvA also uses a set of external  $\pi$  interaction measurements to constrain the FSI model. Table 1.1 shows the list of models and tunes for different interaction modes in NOvA [7].

Table 1.1: Models and tunes used in the NOvA simulation of neutrino interactions.

Interaction	Model	Tune
CCQE	València [51]	External $\nu$ – D data [52]
CCMEC	València [53, 54]	NOvA $\nu_\mu$ CC data
Res & COH $\pi$	Berger-Sehgal [55, 56]	External $\nu$ – A data
DIS	Bodek-Yang [57, 58]	External $\nu$ – A data
FSI	Semi-classical cascade [59]	External $\pi$ – $^{12}$ C data

Since the FD is on the surface NOvA also uses a simulation of cosmic rays generated with the MC Cosmic-Ray Shower Generator (CRY) [60]. The simulated cosmic muons are also used to calibrate NOvA detectors [36].

Particles that are created from neutrino interactions and cosmic rays are propagated through the NOvA detectors using the GEANT4 v10.4.p02 [34], which outputs the energy deposited in the scintillator. This is then passed to a custom NOvA software of the light model [36], which calculates the amount of scintillation light produced for the deposited energy based on a Poisson distribution. The scintillation light production is parametrized using the Birks-Chou model [61], which corrects for the recombination in organic scintillators at high deposited energies. The scintillator light yield and the inherent production of the Cherenkov light, which can affect the light readout, are tuned to NOvA data [9]. The light collection by the WLS fibres, its transport to the APDs, and the APD response use a parametrized simulation, as the NOvA cells and their readout are generally the same across the detectors [36]. The simulation of the readout electronics is done by another custom NOvA parametrized

model, which accounts for random noise in the readout electronics and outputs true events in the same format as the real data.

Due to the high neutrino rate in the **ND**, there are neutrinos interacting in the surrounding rock creating particles, mainly muons, that make it to the detector and act as background. However, since only a few ‘rock muons’ make it into the detector, it would be very time consuming to run a simulation which includes the rock around the **ND** for every neutrino. Instead, **NOvA** creates a separate simulation that includes the surrounding rock and then overlays these results into the nominal **NOvA** simulation chain to match the **NuMI** neutrino rate [36].

## 1.5 Data Processing and Event Reconstruction

Both data and simulation events for all **NOvA** detectors are passed through the same event reconstruction and particle identification algorithms. The reconstruction was specifically developed with the  $\nu_e$  appearance search in mind, focusing on identifying the  $\nu_e$ **CC** signal against the  $\nu_\mu$ **CC** and Neutral Current (NC) backgrounds. Each **NOvA** detector has to deal with different challenges, with multiple neutrinos interacting during one beam spill in the **ND**, and a large cosmic background in the **FD** [62].

The output from the **DAQ** system for each channel is called a *raw hit*. Hits are grouped into 550  $\mu\text{s}$ -long windows and passed to an offline reconstruction chain [62]. Reconstruction starts by grouping hits into *slices* based on their proximity to other hits in both time and space [63]. Slices are designed to ideally contain only a single neutrino interaction event.

For events that produce hadronic and electromagnetic showers, reconstruction first identifies straight lines through major features using a modified Hough transform [64], representing particle directions. These lines are passed to the Elastic Arms algorithm [65] to identify *vertex* candidates from their intersection points. Hits are then clustered into *prongs*, which are collections of hits with a start point, based on the vertex, and a direction, using a k-means algorithm called FuzzyK [66, 67]. Here ‘fuzzy’ means that each hit can belong to multiple prongs. Prongs are first created separately for each view (also called 2D prongs) and then, if possible, view-matched into 3D prongs (from here on referred to as prongs) [62]. Figure 1.7 shows an exam-

ple of a simulated electron shower, where the reconstructed vertex is shown as a red cross and the prong as a red shaded area. The prong groups together all the hits that are part of the shower, while removing the background hits, shown in grey.

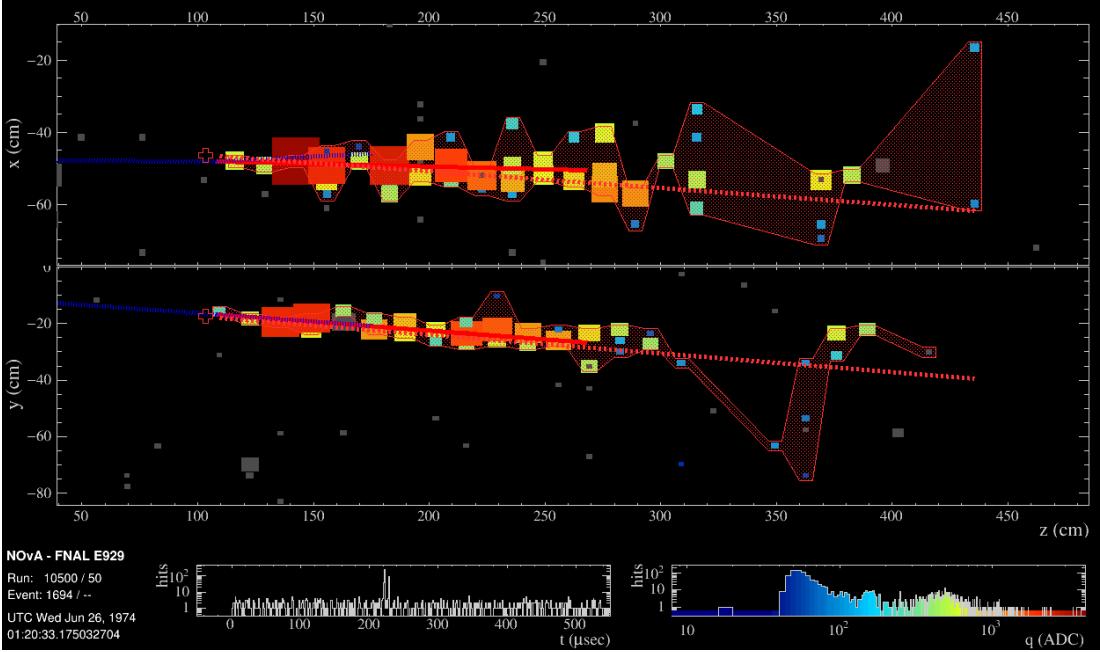


Figure 1.7: Reconstruction of a simulated single electron event in the **NOvA** ND. The red cross is the reconstructed vertex, the shaded area shows the cluster of hits into a prong and the dotted red line shows the estimated shower direction. The blue dotted line shows the true direct of the scattering neutrino and the solid red line the true momentum of the scattered electron. Figure from internal **NOvA** database [68].

For particles that are represented by tracks rather than showers (especially muons), the reconstruction takes the slice hits and forms ‘Kalman tracks’ based on a Kalman filter [69]. In addition to the start point and the direction, which exist also for prongs, tracks also contain information on the vector of trajectory points that make up the track and on the end point - and therefore on the track length. A parallel tracking algorithm takes in the Elastic Arms vertex and the Fuzzy-K prongs and forms Break Point Fitter (BPF) tracks [70, 71], using a model of Coulomb scattering and energy loss. BPF tracks also contain an information on the particle 4-momenta based on various particle assumptions, most notably the muon assumption. For cosmic particles, mostly muons, **NOvA** uses another track reconstruction algorithm, called ‘window cosmic track’ [72]. It uses a sliding 5 plane-long window, in which it fits a straight line to the recorded hits. The window starts from the end of the detector and then slides forward and repeats the fitting process until all hits are processed. This way it

accounts for possible Coulomb scattering of cosmic muons. The intersection of each cosmic track with the edge of the detector (or extrapolation of the track to the edge of the detector) is reconstructed as the ‘cosmic ray vertex’.

To identify individual particles and remove backgrounds, NOvA uses several Machine Learning (ML) algorithms, outputs of which are used in combination with the information from classical reconstruction algorithms for Particle Identification (PID). The most common topologies for particles interacting in NOvA detectors are shown in Fig. 1.8. Muons are easily identifiable as single long tracks which decay into an electron (or positron) if stopping inside of the detector. Both electrons and  $\pi^0$ ’s produce electromagnetic showers, but thanks to the low-Z composition and high granularity of the detector, there is a gap between the interaction vertex and the electromagnetic shower for the  $\pi^0$ .

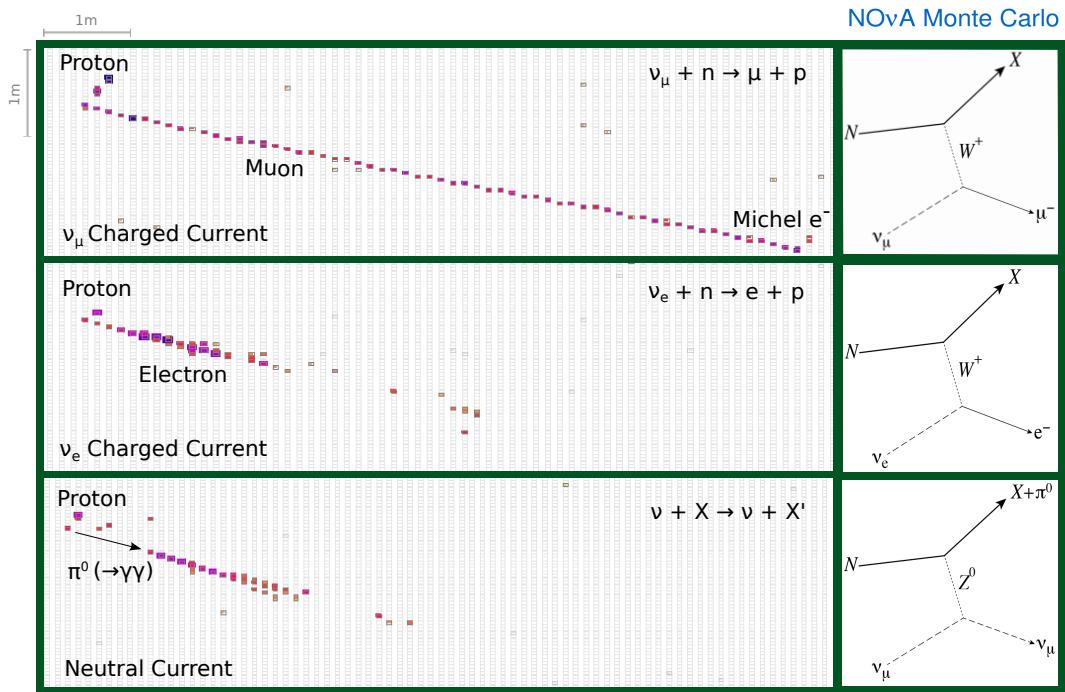


Figure 1.8: Different event topologies as seen in the NOvA detectors with corresponding Feynman diagrams [62]. Each event is a simulated 2.15 GeV neutrino interacting in a NOvA detector producing a 0.78 GeV proton and a second 1.86 GeV particle depending on the interactions type. The figure shows only one view and the colouring represents the deposited energy.

One of the ML algorithms that NOvA employs is a Convolutional Neural Network (CNN) based on the GoogLeNet [73] architecture named Convolutional Visual Network (CVN) [74]. When it is applied to identify entire events it is called *EventCVN*

and uses slice hits to classify interactions into one of the five categories:  $\nu_e$ ,  $\nu_\mu$ ,  $\nu_\tau$ , NC, or cosmic. The same architecture, but applied to the Fuzzy-K prongs, is called *ProngCVN* [75], and is used to identify what particles the prongs most likely correspond to. This assignment is useful in calculation of prong energy, as described in Sec. 1.7. Another ML algorithm is specifically designed for identifying muons and is based on a Boosted Decision Tree (BDT). It is called Reconstructed Muon Identifier (ReMid) [69] and uses the reconstructed Kalman tracks as inputs.

## 1.6 Detector Calibration

The energy deposited within NOvA detectors is represented by the peak ADC values for each cell the particle passed through, obtained from the readout electronics, as described in Sec. 1.3. The conversion of the peak ADC values into physical units of energy requires calibrating the NOvA detectors [76], while accounting for the attenuation of light along the WLS fibres, or for differences between individual cells. The purpose of calibration is to calculate a conversion factor from ADC → MeV for every part of the detector, so that the same energy deposited anywhere and at any time, is recorded as the same value of the reconstructed energy.

NOvA uses cosmic ray muons for calibration due to their abundance in the NOvA detectors and their consistent energy deposition. To calculate the absolute energy scale, NOvA selects a subsample of muons stopping inside of the detectors when they are almost exactly Minimum Ionising Particle (MIP) and therefore have a well understood energy deposition. The cosmic muons are collected using a periodic trigger with the same length as the beam trigger, whilst removing events with timestamps overlapping with the beam spill window. The simulation of cosmic muons is created using the CRY [60] MC generator, as outlined in Sec. 1.4.

Cosmic muon tracks are reconstructed using the window cosmic track algorithm described in Sec. 1.5. The selection of well reconstructed cosmic tracks requires that at least 80% of all hits from the reconstructed slice contribute to the track [29]. Each track must have at least 2 hits in both the x and y views and the difference in the number of planes the track crossed between the views must be at most 10% of the total number of planes. Also, the plane where each track starts or stops in one view

must be within 3 planes of the start or stop plane in the other view. Additionally, since tracks that do not cross many planes tend to not be reconstructed very well, the extent of each track in the z direction must be at least 70 cm and tracks must have at least 20% of their total track direction in the z axis. Tracks with on average more than 6 cells per plane and with path lengths through the cell larger than 10 cm are removed for the same reason. Furthermore, all the reconstructed tracks must start at most 10 cm from the edge inside of the detector and stop at most 10 cm outside of the detector. Lastly, tracks with trajectory points far away from each other are also removed. The selection of stopping muons for the absolute energy scale relies on identifying Michel electrons, which are produced by decaying muons at the end of their tracks, as can be seen on the top panel of Fig. 1.8.

Since the energy deposited in a cell is proportional to the distance the particle travels through the cell, the input variable for calibration is the deposited energy divided by the path length through the cell  $PE/cm$ . To ensure the path length is well calculated, all hits used in calibration must satisfy the so-called ‘tricell’ condition, shown in Fig. 1.9. This means that for each calibration hit, there must be a corresponding hit in both of the surrounding cells in the same plane for the same track. The path length can then be calculated simply from the height of the cell and the angle of the reconstructed track. In case there is a bad channel in a neighbouring cell (right side of Fig. 1.9), this channel is ignored and the tricell condition looks one cell further [76]. If the tricell condition fails, the hit can still pass the ‘z tricell’ condition, which is a longitudinal equivalent of the tricell condition and requires a hit in both the neighbouring planes in the same view and with the same cell number. The ‘z tricell’ hits are saved separately and may be used if there are no hits satisfying the original tricell condition. This is especially useful for the cells on the edge of the detector, which fail the tricell condition due to only having one neighbouring cell.

The calibration conversion factor from the signal recorded by the detector readout to the deposited energy can be expressed by as

$$E_{dep} \text{ [MeV]} = \text{Signal [ADC]} \times S_d \times TS_{d,i}^{\text{CALIB}} \times R_{d,i}(t) \times A_d(t). \quad (1.1)$$

The calibration scale therefore consists of four separate and complementary factors: the Scale ( $S_d$ ), the Threshold and Shielding correction ( $TS_{d,i}$ ), the Relative calibra-

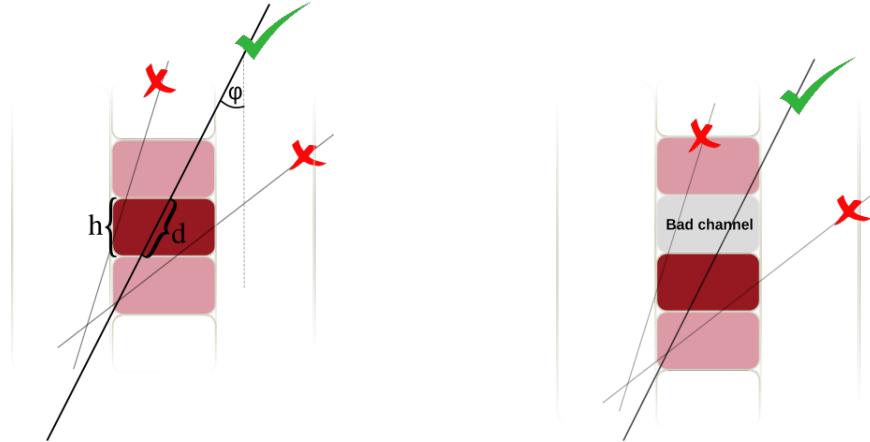


Figure 1.9: Illustration of the tricell condition. Only the hits with two surrounding hits in the same plane are used in the NOvA calibration, as shown on the left plot. This is to ensure a good quality of the path length ( $d$ ) reconstruction, which is calculated from the known cell height ( $h$ ) and the reconstructed track angle ( $\varphi$ ). In case the hit is next to a bad channel, as shown on the right plot, the bad channel is ignored and the tricell condition requires a hit in the next cell over.

tion ( $R_{d,i}(t)$ ) and the Absolute calibration ( $A_d(t)$ ), all described below. Each part is calculated for each detector separately, as indicated by the subscript  $d$ . The threshold and shielding correction is only used during calibration and is omitted when applying the calibration results. The relative and absolute calibrations are calculated for each time period separately to account for possible changes in the energy deposition throughout the time, possibly caused by the ageing of the scintillator oil, or of the readout electronics. The time periods are either determined by a fixed time interval, or by running conditions separated by significant changes to the readout or the DAQ systems, including the summer shutdown.

The threshold and shielding correction and the relative calibration calculate a calibration factor for each position within the detector to account for variations caused by the attenuation of light as it travels through the WLS fibres, or by differences between individual cells. This is expressed with a subscript  $i$  in Eq. 1.1. For data, the position of a hit in the detector is described by the plane number, cell number and the position within the cell ( $w$ ).  $w$  is calculated as the projection of the cosmic track to the central cell axis and its value is equivalent to the x axis (y axis) coordinate of the projection for the horizontal (vertical) cells, with the 0 value at the centre of the cell [76].

For simulation, the calibration does not use the plane number to determine the po-

sition within a detector, as by construction all detector planes should have the same readout. This significantly reduces the requirements for the number of events that need to be simulated, reconstructed, and calibrated, especially for the **FD** with 896 planes. However, in reality there are some variations in the detector response between individual planes, caused by different *brightness* qualities of the fibres, zipped or twisted fibres, different qualities of the scintillator, possible air bubbles, and potentially other factors. To include these differences in simulation without having to simulate every cell individually, all the cells are divided into 12 equally populated Fibre Brightness (FB) bins based on the uncorrected average response in the center of that cell, as shown in Fig. 1.10. These **FB** bins describe the relative differences in the detector response between individual cells [77].

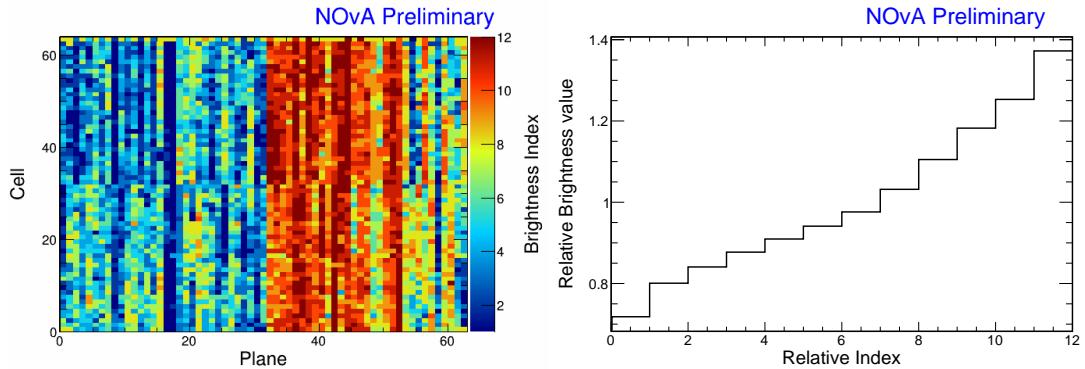


Figure 1.10: Distribution of the **NOvA** detector cells into 12 brightness bins (left plot), each representing a relative difference in energy response (right plot) due to different brightnesses of the fibres, scintillators, or readout. This is an example from the **NOvA** Test Beam detector, described in Sec. ??, where the left side of the detector (planes 1-32) has clearly lower response relative to the right side of the detector (planes 33-64).

### 1.6.1 Scale

The scale calibration factor from Eq. 1.1 is a simple conversion from the peak **ADC** value into the number of **PEs**. This factor only depends on the **APD** gain (which was different in the beginning of **NOvA** data taking) and on the **FEB** type (different between detectors, as described in Sec. 1.3).

### 1.6.2 Threshold and Shielding Correction

The threshold and shielding correction accounts for two assumptions, which hold true in most cases in **NOvA**, but fall short for some hits at the bottom of the detector,

or far away from the readout, especially for the **FD** [76].

The first assumption is that the **ADC** response to the photon signal is linear, which is mostly true except close to the **APD** threshold. Energy deposited far away from the readout may produce photons that get attenuated enough to be shifted below the threshold. However, due to natural fluctuations of the number of photons created by the energy deposition, the same deposited energy may also produce photons that would make it over the threshold, therefore making it appear that the actual deposited energy was higher than in reality, introducing a bias to the calibration. The threshold correction is calculated using simulation, as the ratio between the mean of the Poisson distribution of the true number of the created **PE** ( $\text{PE}_{\text{Poisson}\lambda}$ ) and the number of the ‘reconstructed’ **PE** seen by the **APD** ( $\text{PE}_{\text{Reco}}$ ).

The second assumption is that the spectrum of cosmic muons is uniform within each detector. Again, this is generally true, but breaks down in the **FD**, which is big enough for the top of the detector to shield the bottom of the detector and therefore affect the energy distribution. The shielding correction is calculated from simulation as a ratio between the expected deposited energy if the particle was a **MIP** ( $E_{\text{MIP}}$ ), which is estimated from simulation for the **NOvA** scintillator as  $E_{\text{MIP}} = 1.78 \text{ MeV/cm}$  and the true deposited energy ( $E_{\text{true}}$ ).

The total threshold and shielding correction is calculated for simulated events in each cell, **FB** bin and  $w$  as

$$TS_i = \frac{\text{PE}_{\text{Poisson}\lambda}}{\text{PE}_{\text{Reco}}} \frac{E_{\text{MIP}}}{E_{\text{True}}}. \quad (1.2)$$

To ensure that the correction changes smoothly across each cell position, the final correction is calculated as a fit to the mean correction value along  $w$  in each cell and **FB** bin.

### 1.6.3 Relative Calibration

The main goal of the relative calibration is to correct for the attenuation of the scintillator light as it travels through the **WLS** fibre to the readout. The attenuation in each cell is estimated by performing an ‘attenuation fit’ to the mean response in **PE/cm**, as shown in Fig. 1.11. The relative calibration scale is then calculated as the ratio be-

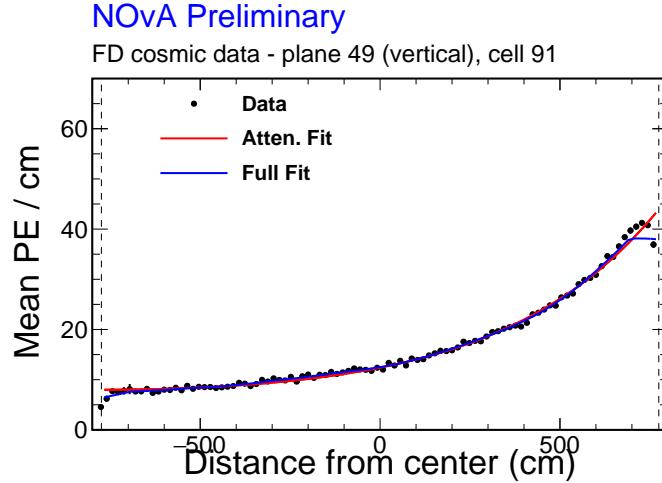


Figure 1.11: Example attenuation fit for a single cell in the NOvA FD across its full length, as shown by dashed vertical lines. The red line shows the initial exponential fit and the blue line shows the full fit after the LOWESS correction, both described in text. Figure from [78].

tween the average response in PE/cm across the entire detector (can differ between detectors) and the result of the attenuation fit in each particular position within the detector. The response after applying the relative calibration scale is expressed as Corrected Photo Electronss (PECorrs). Since the relative calibration scale is calculated for each cell independently, it effectively corrects for the relative differences between detector cells as well as for the attenuation. Therefore, the resulting distribution of PEcorr/cm should be uniform across the detector, especially along the plane, cell and  $w$  [76].

The first step to do the attenuation fit is to create ‘attenuation profiles’ for each cell. Attenuation profiles are profile histograms of mean detector response over the path length through the cell, in the units of PE/cm, along the position within the cell. An example attenuation profile is shown in Fig. 1.11 as black dots. The threshold and shielding correction described in Sec. 1.6.2 is applied to the attenuation profiles before doing the attenuation fit, which consists of two steps.

1. The first step is a three-parameter exponential fit according to

$$y = C + A \left( \exp \left( \frac{w}{X} \right) + \exp \left( -\frac{L+w}{X} \right) \right), \quad (1.3)$$

where  $y$  is the fitted response,  $L$  is the length of the cell and  $C$ ,  $A$  and  $X$  are

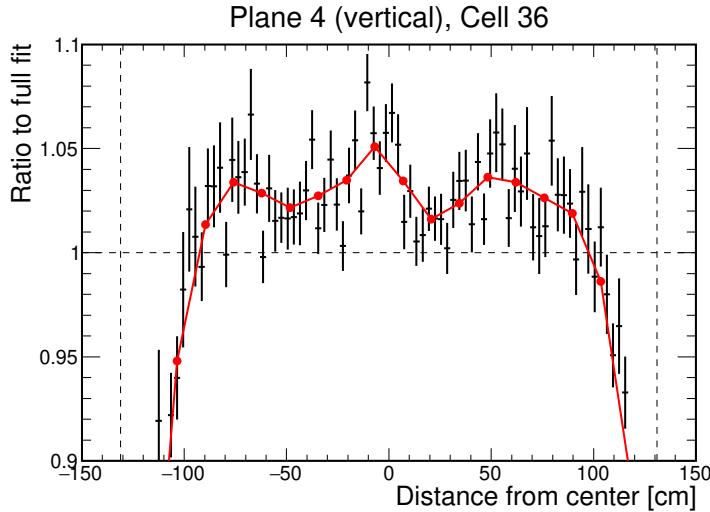


Figure 1.12: Example LOWESS correction for the residual differences after the exponential part of the attenuation fit of the NOvA relative calibration. This is an example for a single cell in the NOvA Test Beam detector with black points showing the residual differences and red line the LOWESS correction, both described in text.

the fitted parameters representing the background, attenuation scale and attenuation length respectively. An example of the exponential fit is shown as a red curve in Fig. 1.11.

2. The second step is the smoothing out of residual differences between the exponential fit and the original distribution with the Locally Weighted Scatter plot Smoothing (LOWESS) method, shown in Fig. 1.12. The residual differences get evened out by creating a smooth distribution of 20 locally weighted points across the length of each cell. The result of the LOWESS correction is then combined with the exponential fit into the full attenuation fit, shown as a blue line in Fig. 1.11.

Even after applying the LOWESS correction, there are sometimes large differences between the attenuation fit and the fitted response. This is usually caused by a small number of events in that cell, common for cells at the edge of the detector. To ensure a good quality of the attenuation fit, the total  $\chi^2$  between the attenuation fit and the fitted response is calculated and only cells with the final  $\chi^2 \leq 0.2$  are counted as *calibrated*. Cells with  $\chi^2 > 0.2$  are ignored in further processing and marked as *uncalibrated*.

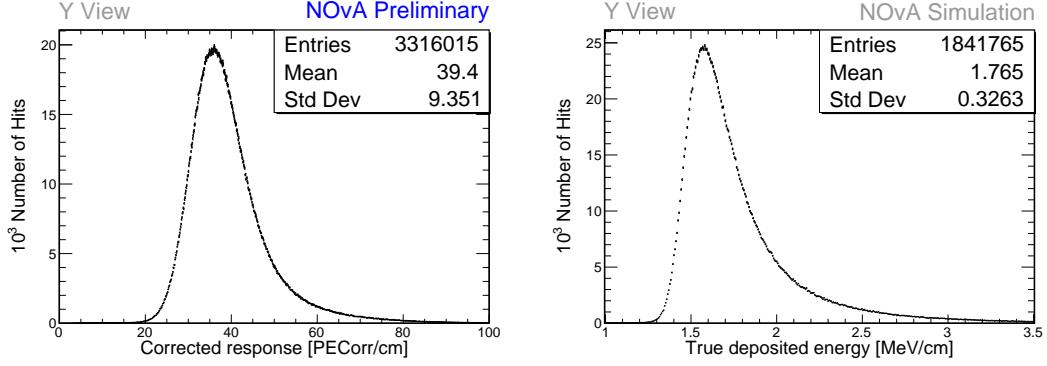


Figure 1.13: The absolute energy scale is calculated as the ratio between the simulated mean true deposited energy (right) and the mean reconstructed energy response (left) for selected stopping muons in each view and each data period or simulation.

#### 1.6.4 Absolute Calibration

The absolute calibration only uses hits from muons stopping inside of the detector, in a track window 1 – 2 m from the end of their tracks. This is when they are approximately MIP and their energy deposition is well understood. Additionally, hits at the edges of each cell are removed to mitigate the effects at the end of the WLS fibres and the lower number of events at the edge of the detector [29].

First, the relative calibration results are applied to the selected stopping muon hits to get a distribution of the corrected detector response in *PECorr*/cm, as shown on the left of Fig. 1.13. The mean of this distribution is called the *reconstructed Muon Energy Unit* (MEU) and is calculated separately in each of the two views, and in each time period or version of simulation. Analogously, the mean of the true deposited energy in MeV/cm from simulation, shown on the right of Fig. 1.13, is called the *true MEU*. The absolute energy scale (the absolute calibration scale) is then the ratio between the true and the reconstructed MEU value, where both the MEU values are taken as a simple average over the two views

$$\text{Absolute Energy Scale} = \frac{\text{MEU}_{\text{True}} \text{ [MeV/cm]}}{\text{MEU}_{\text{Reco}} \text{ [PECorr/cm]}}. \quad (1.4)$$

The values of the absolute energy scales for each data period and simulation, as well as the results of the attenuation fit, are saved in a set of lookup tables, which are then used any time a hit is recorded in the NOvA detector and processed and reconstructed with the NOvA algorithms described above.

## 1.7 Energy Estimation

The deposited energy from detector calibration (Sec. 1.6) is only the first step in estimating the neutrino energy ( $E_\nu$ ) required for the main [NOvA](#) analyses.

For the  $\nu_\mu$  disappearance analysis, the  $\nu_\mu$  energy is measured as the sum of the muon energy and the energy of the hadronic shower [7]. The muon energy is identified from the length of its track, without the need of the calibration results. The energy of the hadronic shower is estimated from simulation as a fit to the 2D distribution of the true  $\nu_\mu$  energy minus the reconstructed muon energy, versus the visible (not corrected for the dead material) deposited energy of the hadronic system [75].

For the  $\nu_e$  appearance analysis, the  $\nu_e$  energy is calculated using a quartic fit to the 2D distribution of the electromagnetic versus the hadronic calorimetric energies, both corrected for the energy deposition in the dead material (PVC cells) [75]. The dead material correction is currently just a simple scaling of the deposited energy from calibration for all particles and is calculated from the measurement of the  $\pi^0$  mass peak in the [NOvA ND](#). This correction is correct only for electromagnetic showers and is not directly applicable to hadronic showers. The fit to determine the  $\nu_e$  energy keeps the normalization of both the electromagnetic and the hadronic energies free, so the exact value of the dead material correction is not important. It is however used in other, non-neutrino oscillation analyses.

## 1.8 Systematic Uncertainties

There are several known unknowns that can affect the results of [NOvA](#) measurements, represented by systematic shifts of predictions. The impact of systematic uncertainties is assessed by varying prediction independently for each systematic shift and passing all predictions through the same analysis procedures as the nominal (non-shifted) sample. The nominal and systematically shifted predictions are then compared to determine the systematic uncertainty on the measured parameters. This approach inherently accounts for the effects of systematic uncertainties on background composition, event selection, reconstruction, and other aspects of the analysis.

The primary sources of systematic uncertainties in [NOvA](#) include the simulations of neutrino flux, neutrino interaction, and detector modelling, all explained in Sec. 1.4,

as well as the detector calibration procedure. Other sources of systematic uncertainties are relevant only to specific analyses and are not discussed here. In **NOvA**, the 3-flavour [7] and the sterile [13] neutrino oscillation analyses use the **ND** data to constrain the **FD** prediction by fitting the **ND** prediction to data, significantly reducing the effect of the neutrino beam and neutrino interaction systematic uncertainties. On the other hand, these are the leading sources of systematic uncertainties for the **ND**-only analyses, such as the cross section analyses [8–11], or the neutrino magnetic moment analysis. Detector calibration and modelling uncertainties are significant across all **NOvA** measurements.

The systematic uncertainty on the neutrino beam prediction arises from two sources: hadron production and beam focusing [36]. Hadron production uncertainties are estimated using the multi-universe technique within the **PPFX** (see Sec. 1.4), which involves creating 100 alternative universes where inputs from external measurements of hadron production cross-sections are varied within their respective uncertainties. Beam focusing uncertainties are contained in 20 parameters accounting for uncertainties in horn and target positions, horn current, beam position on the target, beam spot size, and the effect of Earth’s magnetic field in the beam pipe. Since all these uncertainties can be correlated, particularly in an off-axis detector such as **NOvA**, a Principal Component Analysis (PCA) is performed to estimate the bin-to-bin covariances in true energy for each neutrino flavour, detector and beam mode [79]. PCA reduces the number of required neutrino flux systematic uncertainty parameters from  $20 \times 100$  to only 8 “*principal components*” (each with positive and negative shifts) for the **ND** analyses, or 5 principal components for the **ND+FD** analyses. Additionally, principal components are uncorrelated by construction and ordered by the scale of their effect on the neutrino beam prediction.

Neutrino interaction-related systematic uncertainties involve 77 adjustable parameters, most of which are provided directly by GENIE [50] to account for the theoretical uncertainties of the prediction [7]. These include knobs to adjust the axial and vector masses of **QE** and **Res** interactions,  $\pi$  angular distribution in the **Res** $\pi$  production, parameters of the Bodek-Yang **DIS** model, or branching ratios for the radiative and single  $\eta$  resonance decays. Additionally, **NOvA** developed its own set of systematic uncertainties [80], either based on its own measurements, or on discrepancies

observed in other experiments. For example, the **NOvA MEC** tune has associated uncertainties based on its dependence on the transferred four momentum or on the neutrino energy. Furthermore, a discrepancy between data on the **Res** interactions at low transfer energies and their prediction in the **NOvA ND** motivated a conservative 100 % one-sided systematic uncertainty, allowing for a complete suppression of **Res** events with low energy transfers.

For the long-range dependence of **CCQE** interactions **NOvA** adapted a theory-based systematic uncertainty developed outside **NOvA** and **GENIE** [81, 82]. Several data-simulation discrepancies in external experiments motivated additional systematic uncertainties, such as for the **DIS** interactions at high neutrino energies [83], for the distance that a parton travels before hadronization in **DIS** interactions [84], for **COH $\pi$**  production [85], or for the **FSI** model [86]. Lastly **NOvA** applies a 2 % systematic uncertainty on the ratio of  $\nu_e$ **CC** and  $\nu_\mu$ **CC** cross sections to account for their potential differences due to radiative corrections or second class currents [87].

Systematic uncertainties on the simulation of the detector response arise mainly from the light model tuning described in Sec. 1.4. This includes the uncertainty on the overall normalization of the amount of light produced by deposited energy and an additional uncertainty for the Cherenkov light contribution. The Cherenkov light uncertainty is calculated by profiling over various Cherenkov scaling factors during the light model tune and using the  $3\sigma$  confidence interval around the best fit value as the Cherenkov systematic uncertainty. This results in a  $\pm 6.2\%$  systematic uncertainty on the predicted amount of Cherenkov light. The light level systematic uncertainty is determined in the same way by profiling over the overall light level scaling factor, resulting in a  $\pm 5\%$  uncertainty.

There are three systematic uncertainties arising from the calibration procedure: the absolute energy scale, the calibration shape and the detector ageing uncertainty. Measurements of some "standard candle" processes, mainly in the **ND**, are used to set the systematic uncertainty on the absolute energy scale, calculated as the data-simulation difference. These standard candles include beam muons, beam protons, rock muons, Michel electrons and the  $\pi^0$  mass peak. Their combined results lead to a 5 % systematic uncertainty on the absolute energy scale [88]. The calibration shape uncertainty accounts for the residual variations in the relative energy depo-

sition along the cell, especially on cell edges. The shape and size of the calibration shape systematic uncertainty is determined by a fit to a ratio of data and simulation, resulting in a steep rise at cell edges, where the uncertainty is up to 30 %, while being fixed to 0 % in the cell centre [89]. Lastly, the detector ageing uncertainty is implemented as time-dependent decrease of the overall light level scaling by 4.5 % per year, with a corresponding increase in the overall calibration scale to compensate [90].

## CHAPTER 2

# Measuring the Muon Neutrino Magnetic Moment

In this analysis, I aim to detect a potential signal of the effective muon neutrino magnetic moment in the NOvA ND. This signal would manifest as an excess of neutrino-on-electron ( $\nu$ -on-e) elastic scattering interactions at low electron recoil energies, proportional to the value of the effective neutrino magnetic moment, over the Standard Model (SM) background. If no significant excess is observed, I will establish an upper limit on the effective muon neutrino magnetic moment.

Detecting the neutrino magnetic moment ( $\mu_\nu$ ) would provide definitive evidence of new Beyond Standard Model (BSM) physics, and measuring its value would help identify the appropriate BSM theory. As current and planned experiments can only detect an anomalously large neutrino magnetic moment, observing such a signature would strongly suggest that neutrinos are Majorana particles and would have significant implications for astrophysics and cosmology [91].

The best model-independent experimental results on the neutrino magnetic moment come from experiments searching for dark matter using xenon-based detectors. These highly sensitive detectors detect solar neutrinos, which are part of the background in dark matter searches but can be reanalyzed for other purposes. In 2020, the XENON1T experiment observed [92] a low energy excess of solar neutrinos, which could correspond to a signal from an anomalously large effective magnetic moment within  $\mu_{\nu_\odot} \in (0.14, 0.29) \times 10^{-10} \mu_B$  at 90 % Confidence Level (C.L.), where  $\nu_\odot$  marks solar neutrinos. However, this result was disfavoured by the follow-up XENONnT experiment in 2022 [93], which saw no excess and set the current world-leading limit on neutrino magnetic moment at  $\mu_{\nu_\odot} < 0.063 \times 10^{-10} \mu_B$  at 90 % C.L.. Other solar neutrino experiments also reported null results regarding neutrino magnetic moment [94, 95], placing less stringent limits on its value. Given some basic assumptions [95, 96] this limit for solar neutrinos would correspond to a limit on muon neutrino

effective magnetic moment of  $\mu_{\nu_\mu} < 0.137 \times 10^{-10} \mu_B$ . However, the relationship between effective magnetic moments of different neutrino flavours may be non-trivial, especially in the context of possible new **BSM** physics, and studying muon neutrinos remains an important endeavour [97].

The best results for  $\nu_\mu$  and  $\bar{\nu}_\mu$  come from accelerator-based stopped pion neutrino sources [98, 99], which also do not observe any low energy excess and provide an upper limit on the effective muon neutrino magnetic moment of  $\mu_{\nu_\mu} < 6.8 \times 10^{-10} \mu_B$  at 90 % **C.L.** [98]. Stopped pion neutrino sources provide well-understood beams made up of  $\nu_\mu$ ,  $\bar{\nu}_\mu$  and  $\nu_e$  with energies up to 52.8 MeV. Slightly looser limits come from pion decay-in-flight accelerator-based measurements (similar to **NOvA**) [100, 101], which provide a limit of  $\mu_{\nu_\mu} < 8.5 \times 10^{-10} \mu_B$  at 90 % **C.L..**

Thanks to the very intense and highly pure beam of muon neutrinos and antineutrinos, and a detector designed for the reconstruction and identification of events with electrons in the final state, **NOvA** is well-positioned to provide a highly competitive, and possibly even world-leading, measurement (or limit) of the effective muon neutrino magnetic moment. A previous analysis of **NOvA ND** data for a measurement of the effective muon neutrino magnetic moment was presented in a thesis [102], providing a (statistics-only) limit of  $\mu_{\nu_\mu} < 15.8 \times 10^{-10} \mu_B$  at 90 % **C.L..**

Additionally,  $\nu$ -on-e elastic scattering interactions are used in various other analyses in **NOvA**, specifically in efforts to constrain the neutrino beam prediction [103, 104] and in the search for Light Dark Matter (LDM) [105]. These analyses developed various tools and methods that can be utilized in the search for a neutrino magnetic moment.

In this chapter, I will provide an overview of the theory of neutrino electromagnetic interactions in Sec. 2.1, focusing on the effective neutrino magnetic moment and its implications for  $\nu$ -on-e measurements and other theoretical considerations. In Sec. 2.2, I will discuss the analysis strategy, the signal and background definition, as well as the data and simulation samples and the analysis weights. Following this, in Sec. 2.3 I will explain the selection of events for this analysis, while in Sec. 2.4 I will address the relevant systematic uncertainties. I will present the results of this analysis in Sec. 2.5 and discuss their implications in Sec. 2.6. Finally, section 2.7 will summarise the findings of this analysis.

## 2.1 Theory of the Neutrino Magnetic Moment

As was described in Sec. ??, neutrinos in the **SM** are massless and electrically neutral particles. However, even **SM** neutrinos can have electromagnetic interaction through loop diagrams involving charged leptons and the W boson, covered by the neutrino charge radius [91].

In general **BSM** theories, considering interactions with a single photon as shown on Fig. 2.1, neutrino electromagnetic interactions can be described by an effective interaction Hamiltonian [106]

$$\mathcal{H}_{em}^{(\nu)}(x) = \sum_{k,j=1}^N \bar{\nu}_k(x) \Lambda_\mu^{kj} \nu_j(x) A^\mu(x). \quad (2.1)$$

Here  $\nu_k(x)$ ,  $k = 1, \dots, N$ , are neutrino fields in the mass basis with  $N$  neutrino mass states,  $\Lambda_\mu^{kj}$  is a general vertex function and  $A^\mu(x)$  is the electromagnetic field.

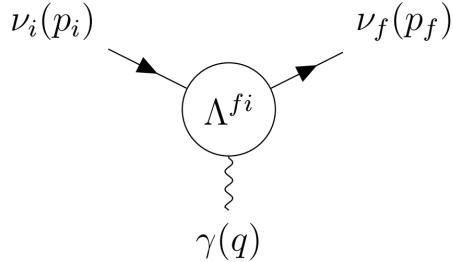


Figure 2.1: Effective coupling of neutrinos with one photon electromagnetic field.

The vertex function  $\Lambda_\mu^{fi}(q)$  is generally a matrix and, in the most general case consistent with the **SM** gauge invariance [107, 108], can be written in terms of linearly independent products of Dirac matrices ( $\gamma$ ) and only depends on the four momentum of the photon ( $q = p_f - p_i$ ):

$$\begin{aligned} \Lambda_\mu^{fi}(q) = & \mathbb{F}_1^{fi}(q^2) q_\mu + \mathbb{F}_2^{fi}(q^2) q_\mu \gamma_5 + \mathbb{F}_3^{fi}(q^2) \gamma_\mu + \mathbb{F}_4^{fi}(q^2) \gamma_\mu \gamma_5 + \\ & \mathbb{F}_5^{fi}(q^2) \sigma_{\mu\nu} q^\nu + \mathbb{F}_6^{fi}(q^2) \epsilon_{\mu\nu\rho\gamma} q^\nu \sigma^{\rho\gamma}, \end{aligned} \quad (2.2)$$

where  $\mathbb{F}_i^{fi}(q^2)$  are six Lorentz invariant form factors and  $\delta$  and  $\epsilon$  are the Dirac delta and the Levi-Civita symbols respectively.

Applying conditions of hermiticity  $(\mathcal{H}_{em}^{(\nu)\dagger} = \mathcal{H}_{em}^{(\nu)})$  and of the gauge invariance

of the electromagnetic field, the vertex function can be rewritten as

$$\Lambda_\mu^{fi}(q) = (\gamma_\mu - q_\mu q^2/q^2) \left[ \mathbb{F}_Q^{fi}(q^2) + \mathbb{F}_A^{fi}(q^2) q^2 \gamma_5 \right] - i\sigma_{\mu\nu} q^\nu \left[ \mathbb{F}_M^{fi}(q^2) + i\mathbb{F}_E^{fi}(q^2) \gamma_5 \right], \quad (2.3)$$

where  $\mathbb{F}_Q^{fi}$ ,  $\mathbb{F}_M^{fi}$ ,  $\mathbb{F}_E^{fi}$  and  $\mathbb{F}_A^{fi}$  are hermitian matrices representing the charge, dipole magnetic, dipole electric and anapole neutrino form factors respectively. It is clear that the vertex function only depends on the square of the four momentum of the photon  $q^2$ . In coupling with a real photon ( $q^2 = 0$ ) these form factors become the neutrino charge and magnetic, electric and anapole moments respectively. Additionally, the neutrino charge radius corresponds to the second term in the expansion of the charge form factor [106].

The above expression can be simplified [109] as

$$\Lambda_\mu^{fi}(q) = \gamma_\mu \left( Q_{\nu_{fi}} + \frac{q^2}{6} \langle r^2 \rangle_{\nu_{fi}} \right) - i\sigma_{\mu\nu} q^\nu \mu_{\nu_{fi}}, \quad (2.4)$$

where  $Q_{\nu_{fi}}$ ,  $\langle r^2 \rangle_{\nu_{fi}}$ , and  $\mu_{\nu_{fi}}$  are the neutrino charge, effective charge radius (also containing anapole moment), and an effective magnetic moment (also containing electric moment) respectively. This is possible thanks to the similar effects of the neutrino charge radius and the anapole moment, and of the neutrino magnetic and electric moments, on neutrino interactions. Therefore, these are the three neutrino electromagnetic properties (charge, effective charge radius and effective magnetic moment) measured in experiments.

The neutrino electric charge is primarily constrained through measurements of the neutrality of matter and through cosmological observations, which provide much better constraints than neutrino oscillation experiments [106]. On the other hand, the neutrino charge radius would manifest as an increase in the size of the  $\nu$ -on-e elastic scattering coupling constants, allowing it to be studied in neutrino oscillation experiments such as NOvA. Additionally, the value of the neutrino charge radius in the SM is only an order of magnitude smaller than the current world-leading limits [110] and measuring it could either confirm the validity of neutrino interactions in the SM, or open possibilities to non-standard contributions to neutrino scattering [106]. However, measurement of the neutrino charge radius is not part of this analysis, but may be included in the future re-analysis of the  $\nu$ -on-e interactions in the NOvA ND.

### 2.1.1 Neutrino Electric and Magnetic Dipole Moments

The size and effect of neutrino electromagnetic properties depend on the specific [BSM](#) theory applied. Evaluating one loop diagrams in the minimally extended [SM](#) with three right-handed Dirac neutrinos, as described in Sec. ??, gives the first approximation of the electric and magnetic moments, which are now  $3 \times 3$  matrices with elements:

$$\left. \begin{aligned} \mu_{kj}^D \\ i\epsilon_{kj}^D \end{aligned} \right\} \simeq \frac{3eG_F}{16\sqrt{2}\pi^2} (m_k \pm m_j) \left( \delta_{kj} - \frac{1}{2} \sum_{l=e,\mu,\tau} U_{lk}^\star U_{lj} \frac{m_l^2}{m_W^2} \right), \quad (2.5)$$

where  $m_k, m_j$  are the neutrino masses and  $m_l$  are the masses of charged leptons which appear in the loop diagrams [106]. The  $D$  superscript denotes Dirac neutrinos and  $M$  denotes Majorana neutrinos throughout this section. Also,  $e$  is the electron charge,  $G_F$  is the Fermi coupling constant,  $U$  is the Pontecorvo-Maki-Nakagawa-Sakata (PMNS) neutrino oscillation matrix, and  $m_W$  is the mass of the  $W$  boson. Higher order electromagnetic corrections were neglected, but can also have a significant contribution, depending on the theory.

It can be seen that Dirac neutrinos have no diagonal electric moments ( $\epsilon_{kk}^D = 0$ ) and their diagonal magnetic moments are approximately

$$\mu_{kk}^D \simeq \frac{3eG_F m_k}{8\sqrt{2}\pi^2} \simeq 3.2 \times 10^{-19} \left( \frac{m_k}{\text{eV}} \right) \mu_B, \quad (2.6)$$

where  $\mu_B$  is the Bohr magneton which represents the value of the electron magnetic moment [106]. Neutrino magnetic moments are therefore strongly suppressed by the smallness of neutrino masses, with theoretical predictions in Eq. 2.6 several orders of magnitude below the reach of current experiments [109].

The transition magnetic moments in the minimally extended [SM](#) from Eq. 2.5 are suppressed with respect to the largest of the diagonal magnetic moments by at least a factor of  $10^{-4}$  due to the  $m_W^2$  in the denominator. The transition electric moments are even smaller due to the mass difference in Eq. 2.5. Therefore an experimental observation of a magnetic moment larger than in Eq. 2.6 would indicate physics beyond the minimally extended [SM](#) [106, 111].

The suppression of the neutrino magnetic moment by the smallness of its mass

can be also expressed in a general case [111]. The ‘natural’ upper limits on the size of the neutrino magnetic moment for any **BSM** theory that has New Physics (NP) generated at a scale  $\Lambda_{NP}$  can be expressed as [112]

$$\mu_\nu^D(\mu_B) \lesssim 3 \times 10^{-15} \frac{m_\nu^D \text{ (eV)}}{[\Lambda_{NP} \text{ (TeV)}]^2}. \quad (2.7)$$

Therefore for  $\Lambda_{NP} \simeq 1 \text{ TeV}$  and  $m_\nu^D \lesssim 1 \text{ eV}$  the limit becomes  $\mu_\nu^D \lesssim 3 \times 10^{-15} \mu_B$ , well below the current experimental capabilities. However, these upper bounds only apply if NP is generated well above the electroweak scale  $\Lambda_{EW} \sim 100 \text{ GeV}$  [106].

For Majorana neutrinos, the magnetic and electric form factors (and therefore the magnetic and electric moment matrices) are antisymmetric, thus Majorana neutrinos only have transition moments. The simplest extension of the **SM** that includes Majorana neutrinos requires either the addition of a Higgs triplet, or right-handed neutrinos together with a Higgs singlet [106]. Neglecting the Feynman diagrams which depend on the model of the scalar sector, the magnetic and electric dipole moments are

$$\left. \begin{aligned} \mu_{kj}^M \\ \epsilon_{kj}^D \end{aligned} \right\} \simeq \mp \frac{3ieG_F}{16\sqrt{2}\pi^2} (m_k \pm m_j) \sum_{l=e,\mu,\tau} \text{Im/Re} [U_{lk}^\star U_{lj}] \frac{m_l^2}{m_W^2}, \quad (2.8)$$

where Im is for  $\mu_{kj}^M$  and Re is for  $\epsilon_{kj}^D$ . These are difficult to compare to the Dirac case, due to possible presence of Majorana phases in the **PMNS** matrices, but it is clear that they have the same order of magnitude as Dirac transition dipole moments. However, the neglected model dependent contributions can enhance the transition dipole moments for Majorana neutrinos [106].

The natural upper bound on the Majorana magnetic moment is less strict compared to the Dirac neutrinos, due to the antisymmetric nature of Majorana magnetic moment, which requires additional Yukawa couplings in the **BSM** theory compared to Dirac neutrinos, which can enhance the maximal possible magnetic moment [111]. The limit for Majorana neutrinos can be expressed as

$$\mu_{\alpha\beta}^M(\mu_B) \leq 4 \times 10^{-9} \frac{[m_\nu^M]_{\alpha\beta} \text{ (eV)}}{[\Lambda_{NP} \text{ (TeV)}]^2} \frac{m_\tau^2}{|m_\alpha^2 - m_\beta^2|}, \quad \alpha, \beta \in \{e, \mu, \tau\}. \quad (2.9)$$

Here, the neutrino magnetic moment is expressed in the flavour basis instead of the mass basis, since the charged lepton masses are diagonal here. The two bases are

related by

$$\mu_{ij} = \sum_{\alpha\beta} \mu_{\alpha\beta} U_{\alpha i}^* U_{\beta j}. \quad (2.10)$$

and the effect of the neutrino magnetic moment on neutrino interactions does not depend on the choice of the basis[113].

These considerations imply, that if a magnetic moment  $\mu \gtrsim 10^{-15} \mu_B$  were measured, neutrinos are almost certainly Majorana particles [111].

### Effective neutrino magnetic moment

As mentioned above, the neutrino magnetic moment measured in experiments is the so-called effective neutrino magnetic moment, which is a combination of electric and magnetic dipole moments and depends on the neutrino source and oscillations. In the ultra-relativistic limit, the effective neutrino magnetic moment is

$$\mu_{\nu_l}^2 (L, E_\nu) = \sum_j \left| \sum_k U_{lk}^* e^{\mp i \Delta m_{kj}^2 L / 2E_\nu} (\mu_{jk} - i\epsilon_{jk}) \right|^2, \quad (2.11)$$

where the minus sign in the exponent is for neutrinos and the plus sign for antineutrinos [106]. Therefore, the only difference between the effective neutrino and antineutrino magnetic moment is in the phase induced by neutrino oscillations. For experiments with baselines short enough that neutrino oscillations would not have time to develop ( $\Delta m^2 L / 2E_\nu \ll \sim 1$ ), such as the NOvA ND, the effective magnetic moment is the same for neutrinos and antineutrinos and is independent of the neutrino energy.

Since the effective magnetic moment depends on the initial neutrino flavour, it is different for experiments studying neutrinos from different sources. Additionally, experiments such as solar neutrino experiments, need to include matter effects on the neutrino oscillations. Therefore the reports on the value (or upper limit) of the effective neutrino magnetic moment are not directly comparable between different types of neutrino experiments.

## 2.1.2 Measuring the Neutrino Magnetic Moment

The most sensitive method to measure the neutrino magnetic moment is the low energy elastic scattering of (anti)neutrinos on electrons [106]. The schematic diagram for this interaction is shown in Fig. 2.2, where the recoil electron's kinetic energy is defined as ( $T_e = E_{e'} - m_e$ ) and the recoil angle with respect to the incoming neutrino beam ( $\theta$ ) is shown.

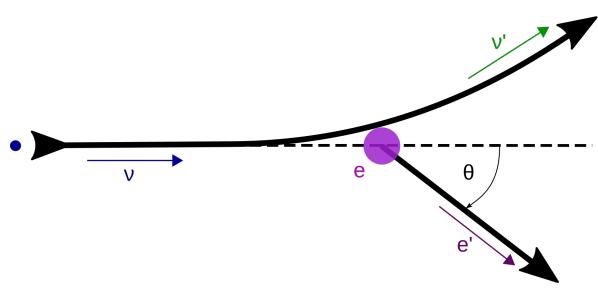


Figure 2.2: Neutrino-on-electron elastic scattering diagram

Since the  $\nu$ -on- $e$  interaction is governed by simple  $2 \rightarrow 2$  kinematics, it can be shown that

$$(P_\nu - P_{e'})^2 = (P_{\nu'} - P_e)^2, \quad (2.12)$$

$$m_\nu^2 + m_e^2 - 2E_\nu E_{e'} + 2E_\nu p_{e'} \cos \theta = m_\nu^2 + m_e^2 - 2E_{\nu'} m_e. \quad (2.13)$$

From the energy conservation

$$E_\nu + m_e = E_{\nu'} + E_{e'} = E_{\nu'} + T_e + m_e \Rightarrow E_{\nu'} = E_\nu - T_e \quad (2.14)$$

it follows that

$$E_\nu p_{e'} \cos \theta = E_\nu E_{e'} - E_{\nu'} m_e = E_\nu (T_e + m_e) - (E_\nu - T_e) m_e = T_e (E_\nu + m_e), \quad (2.15)$$

$$\cos \theta = \frac{E_\nu + m_e}{E_\nu} \sqrt{\frac{T_e^2}{E_{e'}^2 - m_e^2}} = \frac{E_\nu + m_e}{E_\nu} \sqrt{\frac{T_e^2}{T_e^2 + 2T_e m_e}}. \quad (2.16)$$

And finally

$$\cos \theta = \frac{E_\nu + m_e}{E_\nu} \sqrt{\frac{T_e}{T_e + 2m_e}}. \quad (2.17)$$

Which can be rearranged to get

$$T_e = \frac{2m_e E_\nu^2 \cos^2 \theta}{(E_\nu + m_e)^2 - E_\nu^2 \cos^2 \theta}. \quad (2.18)$$

The electron's kinetic energy is therefore constrained as

$$T_e \leq \frac{2E_\nu^2}{2E_\nu + m_e}, \quad (2.19)$$

which corresponds to the limit  $\cos \theta \rightarrow 1$  when the recoil electron goes exactly forward in the incident neutrino direction, as depicted in Fig. 2.3.

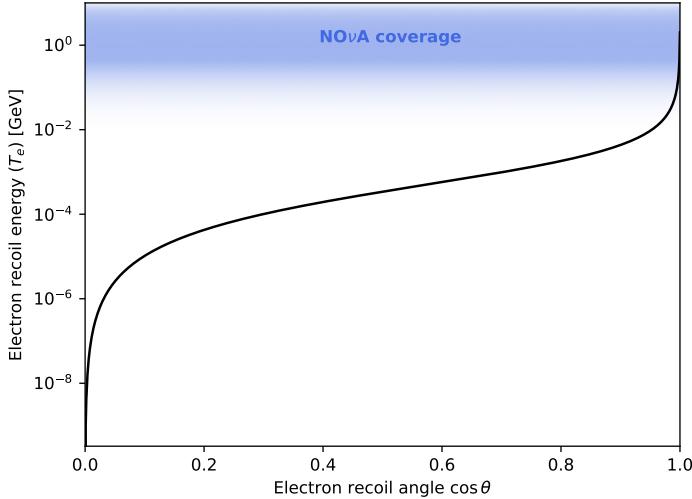


Figure 2.3: Relation between the recoil electron's kinetic energy and angle for the  $\nu$ -on-e elastic scattering. The coverage of the NOvA detectors for measuring the electron recoil energy is shown in blue. Only very forward electrons are therefore recorded in NOvA.

Considering  $E_\nu \sim \text{GeV}$ , it is useful to approximate  $\frac{m_e^2}{E_\nu^2} \rightarrow 0$ . Additionally, considering only very small electron recoil angles, meaning  $\theta^2 \cong (1 - \cos^2 \theta)$ , applied to Eq. 2.17 results in

$$T_e \theta^2 \cong T_e \left( 1 - \left( \frac{E_\nu + m_e}{E_\nu} \right)^2 \frac{T_e}{T_e + 2m_e} \right) = T_e \left( 1 - \left( 1 + \frac{2m_e}{E_\nu} \right) \frac{T_e}{T_e + 2m_e} \right), \quad (2.20)$$

therefore

$$T_e \theta^2 \cong \frac{2m_e T_e}{T_e + 2m_e} \left( 1 - \frac{T_e}{E_\nu} \right) = 2m_e \left( \frac{1}{1 + \frac{2m_e}{T_e}} \right) \left( 1 - \frac{T_e}{E_\nu} \right), \quad (2.21)$$

and finally

$$T_e \theta^2 \cong 2m_e \left( 1 - \frac{T_e}{E_\nu} \right) < 2m_e. \quad (2.22)$$

This is a strong limit that very clearly distinguishes the  $\nu$ -on-e elastic scattering events from other similar interactions involving single electron (mainly the  $\nu_e$ CC interactions).

### Neutrino Magnetic Moment Cross Section

In the ultra-relativistic limit, the neutrino magnetic moment interaction flips the neutrino helicity, while the SM weak interaction conserves it, which means it is possible to add the two contributions to the total  $\nu$ -on-e cross section incoherently (without interference terms) [106]:

$$\frac{d\sigma_{\nu\text{-on-e}}}{dT_e} = \left( \frac{d\sigma_{\nu\text{-on-e}}}{dT_e} \right)_{\text{SM}} + \left( \frac{d\sigma_{\nu\text{-on-e}}}{dT_e} \right)_{\text{MAG}}. \quad (2.23)$$

The SM contribution can be expressed as [106, 114]:

$$\left( \frac{d\sigma_{\nu\text{-on-e}}}{dT_e} \right)_{\text{SM}} = \frac{2G_F^2 m_e}{\pi} \left\{ g_1^2 + g_2^2 \left( 1 - \frac{T_e}{E_\nu} \right)^2 - g_1 g_2 \frac{m_e T_e}{E_\nu^2} \right\}, \quad (2.24)$$

where the coupling constants  $g_1$  and  $g_2$  differ between neutrino flavours and between neutrinos and antineutrinos. Their values are:

$$g_1^{\nu_e} = g_2^{\bar{\nu}_e} = \sin^2 \theta_W + 1/2, \quad g_2^{\nu_e} = g_1^{\bar{\nu}_e} = \sin^2 \theta_W, \quad (2.25)$$

$$g_1^{\nu_{\mu,\tau}} = g_2^{\bar{\nu}_{\mu,\tau}} = \sin^2 \theta_W - 1/2, \quad g_2^{\nu_{\mu,\tau}} = g_1^{\bar{\nu}_{\mu,\tau}} = \sin^2 \theta_W, \quad (2.26)$$

where  $\sin^2 \theta_W \cong 0.23$ .

The total SM cross section, and therefore the number of SM  $\nu$ -on-e interactions, depends on the neutrino energy and the minimum measured electron recoil energy. However, in general the cross section for  $\nu_e$  is about 2.5 times larger than for the  $\bar{\nu}_e$ , about 6 times larger than for  $\nu_{\mu/\tau}$  and about 7 times larger than for  $\bar{\nu}_{\mu/\tau}$ .

The neutrino magnetic moment contribution is [106, 115]:

$$\left( \frac{d\sigma_{\nu\text{-on-e}}}{dT_e} \right)_{\text{MAG}} = \frac{\pi \alpha^2}{m_e^2} \left( \frac{1}{T_e} - \frac{1}{E_\nu} \right) \left( \frac{\mu_{\nu_l}}{\mu_B} \right)^2, \quad (2.27)$$

where  $\alpha$  is the fine structure constant and  $\mu_{\nu_l}$  is the effective magnetic moment of  $\nu_l$ . The total cross section now only depends on the neutrino energy and on the effective magnetic moment, but is the same for neutrinos and antineutrinos.

The comparison of the **SM** and the neutrino magnetic moment differential cross sections is shown in Fig.2.4. Whereas the **SM** cross section is approximately uniform for  $T_e \rightarrow 0$ , the neutrino magnetic moment cross section rises to infinity. However, this reach is limited by the experimental capabilities of detecting electrons with very low energies. The (possible) **NOvA** coverage is shown with a shaded blue region, with current capability reaching  $T_e = 0.5$  GeV. Future analyses might extend this reach to lower  $T_e$ , with the lowest possible detectable electron recoil energy  $T_{e,min} \approx 0.01$  GeV, as discussed in Sec. 1.2.

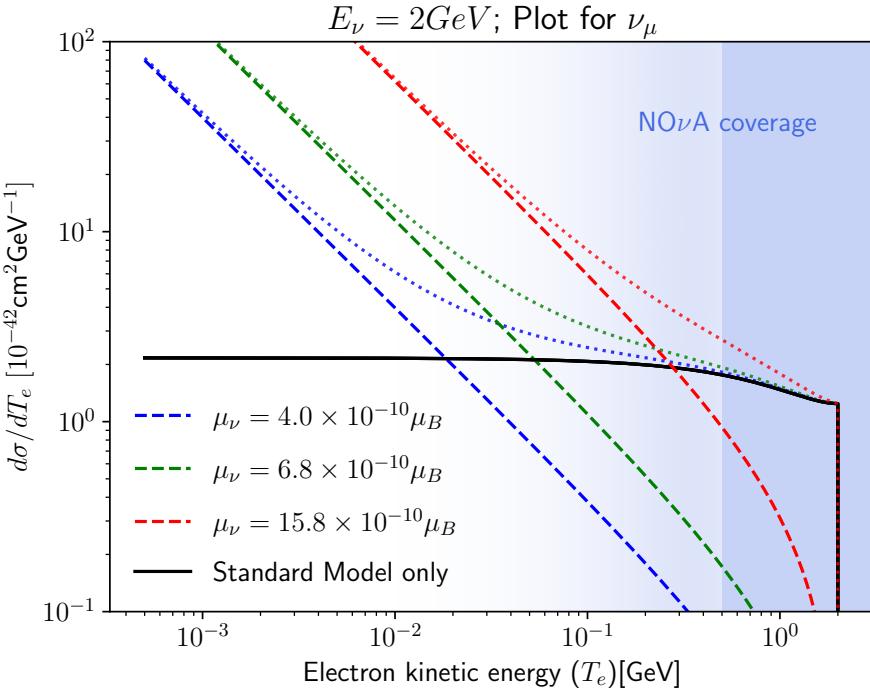


Figure 2.4: Comparison of the neutrino magnetic moment (coloured) and the **SM** (black) cross sections for the  $\nu$ -on-e elastic scattering. Different colours depict different values of the neutrino magnetic moment, with red corresponding to the previous **NOvA** measurement, green the LSND result, and blue a possible ultimate **NOvA** sensitivity, as discussed in the introduction to this chapter. Dashed lines are the individual cross sections and dotted lines are the added total cross section with the standard model contribution. **NOvA** coverage of electron recoil energies is shown in shaded blue.

Calculating the ratio of the neutrino magnetic moment and the **SM** cross sections, as shown in Fig. 2.5, can serve as a proxy to estimate the number of neutrino magnetic

moment events in relation to the predicted number of **SM** events, if the  $E_\nu$  and  $T_e$  are known. Additionally, comparing the ratio of the total cross sections can reveal the expected total number of neutrino magnetic moment events as a function of the predicted number of **SM** events. Considering  $E_\nu = 2 \text{ GeV}$ ,  $\mu_\nu = 6.8 \times 10^{-10} \mu_B$  (current best limit for  $\nu_\mu$  from LSND), and integrating differential cross sections for  $\nu_\mu$  in Eq. 2.24 and 2.27 from  $T_{e,min}$  to  $T_{e,max} \rightarrow 2 \text{ GeV}$  results in

$$\frac{\sigma_{\text{MAG}}}{\sigma_{\text{SM}}} \approx \begin{cases} 0.035 & T_{e,min} = 0.5 \text{ GeV}, \\ 0.14 & T_{e,min} = 0.01 \text{ GeV}. \end{cases} \quad (2.28)$$

Therefore, at the current **NOvA** detection capabilities, there are about 0.035 times as many neutrino magnetic moment  $\nu$ -on-e events than **SM** ones. This can be compared with the expected statistical uncertainty on the **SM** background, which in the case of Poisson distributed events is the square root of the number of predicted events. Consequently, it is possible to assess the minimal number of **SM**  $\nu$ -on-e events necessary for the magnetic moment signal to be detected above the **SM** background (without considering systematic uncertainties) as

$$N_{\text{SM}} > 1/0.035^2 \approx 816. \quad (2.29)$$

However, this approximation is calculated only for one value of  $E_\nu$ , but can be used to assess the sensitivity of the experiment.

As can be seen in Fig. 2.4 and Fig. 2.5, the magnetic moment contribution exceeds the **SM** contribution for low enough  $T_e$ . This can be approximated as [106]:

$$T_e \lesssim \frac{\pi^2 \alpha^2}{G_F^2 m_e^3} \left( \frac{\mu_\nu}{\mu_B} \right)^2 \simeq 2.9 \times 10^{19} \left( \frac{\mu_\nu}{\mu_B} \right)^2 [\text{MeV}], \quad (2.30)$$

which does not depend on the neutrino energy. Therefore, experiments sensitive to lower energetic electrons are significantly more sensitive to the neutrino magnetic moment.

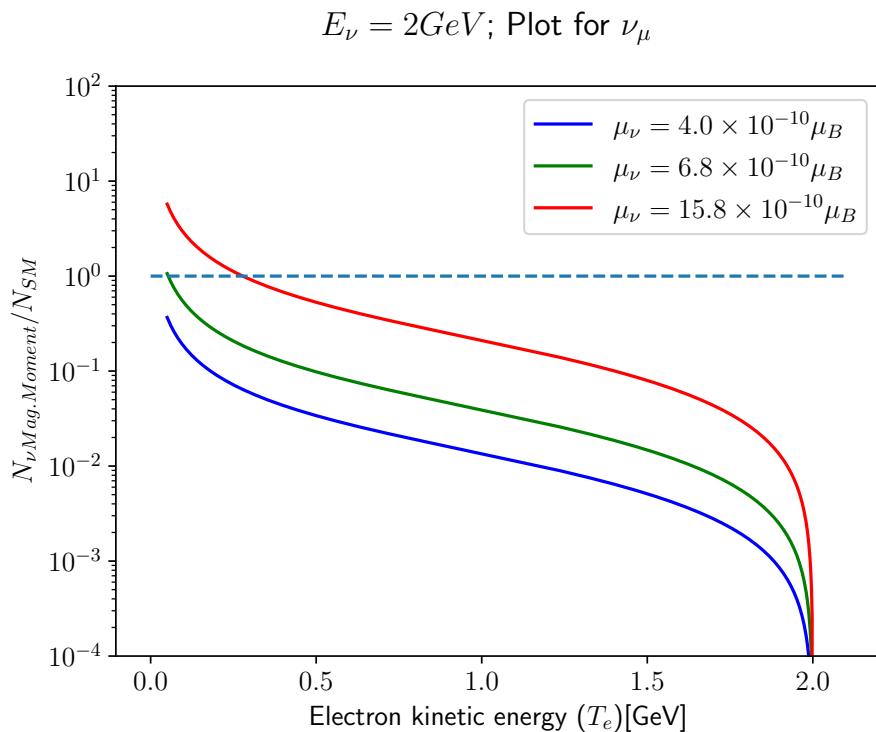


Figure 2.5: Ratio of the neutrino magnetic moment cross section to the SM cross section for the  $\nu$ -on-e elastic scattering of 2 GeV  $\nu_\mu$ . Different colours depict different effective muon neutrino magnetic moment values, with red corresponding to the previous NOvA measurement, green the LSND result, and blue a possible ultimate NOvA sensitivity, as discussed in the introduction to this chapter.

## 2.2 Analysis Overview

Our analysis strategy for measuring the effective muon neutrino magnetic moment in the **NOvA ND** is based on comparing the total number of reconstructed and selected events in data with the prediction. The predicted events consist of the signal, which depends on the size of the effective muon neutrino magnetic moment, and of the background, which corresponds to the **SM**-only (null) hypothesis without any neutrino magnetic moment. We define the signal as true  $\nu\text{-on-e}$  elastic scattering interactions, created with the use of the neutrino magnetic moment cross section instead of the **SM** cross section, as described in Sec. 2.1.2. Additionally, the signal events are required to have their true interaction vertex contained within the **ND** to exclude events originating from outside of the detector.

The data used in this analysis were collected from the start of **NOvA ND** data taking on the August 22<sup>nd</sup>, 2014, until February 3<sup>rd</sup>, 2021. This is the **ND** data that were used in the latest **NOvA** neutrino oscillations result [7], with an additional year. Although more data have been collected since February 2021, they are still being processed and are not available at the time of writing this thesis. The total exposure of the data sample is approximately  $13.8 \times 10^{20}$  **POT**. This exposure is used throughout this chapter to scale the predicted distributions and number of events.

This analysis uses the standard **NOvA** simulation and reconstruction tools, as were discussed in Sec. 1.4 and 1.5. The simulation was created with approximately four times larger statistics than the data to limit statistical uncertainties from simulation. The total exposure for the simulation is approximately  $55.4 \times 10^{20}$  **POT**. For the systematic uncertainty studies only a portion of this full sample is used, specifically  $19.3 \times 10^{20}$  **POT**.

Corrections for known limitations in the simulation are applied in the form of analysis weights applied to each event based on how it is affected by specific variations in the simulation. This includes the corrections for the neutrino beam prediction based on the external measurements used by the **PPFX** (Sec. 1.4), and, for the non- $\nu\text{-on-e}$  background only, also the internal and external measurements that constrain the neutrino interaction prediction inside **GENIE**.

The cross section corrections are not applied to the  $\nu\text{-on-e}$  events, as they are assumed to be known precisely from theory. However, the **GENIE MC** simulation

only considers tree-level SM  $\nu$ -on-e interactions [103], as described in Sec. 2.1.2, and doesn't account for any higher order terms, which are described by radiative corrections. Radiative corrections can be expressed by two adjustments to the tree-level SM  $\nu$ -on-e cross section [116]. First, the values of the weak coupling constants are changed as [117]

$$g_1^{\nu_e} \rightarrow 0.7276, \quad g_1^{\nu_\mu} \rightarrow -0.2730, \quad g_2 \rightarrow 0.2334. \quad (2.31)$$

Second, there are additional terms added to the cross section equation. Considering only one-loop corrections, the full  $\nu$ -on-e cross section can be expressed as<sup>1</sup> [118]

$$\left( \frac{d\sigma_{\nu\text{-on-e}}}{dy} \right)_{\text{Rad. Corr.}} = \frac{G_F^2 s}{\pi} \left\{ g_1^2 \left( 1 + \frac{\alpha}{\pi} X_1 \right) + g_2^2 (1-y)^2 \left( 1 + \frac{\alpha}{\pi} X_2 \right) - g_1 g_2 \frac{m_e y}{E_\nu} \right\}, \quad (2.32)$$

where

$$y = \frac{T_e + E_\gamma}{E_\nu}, \quad (2.33)$$

$s = 2E_\nu m_e + m_e^2$  is the Mandelstam variable,

$$X_1 = -\frac{2}{3} \log \left( \frac{2yE_\nu}{m_e} \right) + \frac{y^2}{24} - \frac{5y}{12} - \frac{\pi^2}{6} + \frac{23}{72} \quad (2.34)$$

and

$$X_2 = -\frac{2}{3} (1-y)^2 \log \left( \frac{2yE_\nu}{m_e} \right) - \frac{y^2}{18} - \frac{\pi^2}{6} (1-y)^2 - \frac{2y}{9} + \frac{23}{72}. \quad (2.35)$$

In practice, radiative corrections can be implemented as a weight, where each true  $\nu$ -on-e event is weighted by a ratio

$$\text{weight}_{\text{Rad. Corr.}}(E_\nu, T_e) = \left( \frac{d\sigma_{\nu\text{-on-e}}}{dy} \right)_{\text{Rad. Corr.}} / \left( \frac{d\sigma_{\nu\text{-on-e}}}{dy} \right)_{\text{GENIE 3}} ; \quad (2.36)$$

Analogically to the radiative correction weight, it is possible to create a neutrino magnetic moment weight as a ratio between the neutrino magnetic moment and the SM differential cross sections for the  $\nu$ -on-e interactions. This can then serve to predict the number of  $\nu$ -on-e events created by the neutrino magnetic moment interac-

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<sup>1</sup>There is technically a third correction term  $X_3$  by the  $g_1 g_2$  term, which is however negligible for  $E_\nu \sim \text{GeV}$ .

tion (which make up the signal), without the need for an additional simulation. This is possible thanks to the theoretically very well understood properties of the  $\nu$ -on-e interaction, as described in Sec. 2.1.2. Therefore, the signal sample is created from the true  $\nu$ -on-e sample, with the magnetic moment weight applied. The weight has a form:

$$\text{weight}_{\nu\text{-Mag. Mom.}}(E_\nu, T_e) = \left( \frac{d\sigma_{\nu\text{-on-e}}}{dy} \right)_{\nu\text{-Mag. Mom.}} \Bigg/ \left( \frac{d\sigma_{\nu\text{-on-e}}}{dy} \right)_{\text{GENIE 3}}, \quad (2.37)$$

where

$$\left( \frac{d\sigma_{\nu\text{-on-e}}}{dy} \right)_{\nu\text{-Mag. Mom.}} = E_\nu \left( \frac{d\sigma_{\nu\text{-on-e}}}{dT_e} \right)_{\nu\text{-Mag. Mom.}}. \quad (2.38)$$

Due to the relatively low cross section of the  $\nu$ -on-e interaction, the nominal simulation sample contains very few  $\nu$ -on-e events, which could result in a significant statistical uncertainty from simulation. To avoid this, we created a  $\nu$ -on-e-enhanced simulation sample, which is mainly made up of  $\nu$ -on-e events with a total exposure of  $1.72 \times 10^{24}$  POT. There are a few non- $\nu$ -on-e background events overlaid on top of the  $\nu$ -on-e events to properly account for the possible reconstruction effects of the pileup of neutrino interactions in a single spill [103], since in the real detector, the hits from the true  $\nu$ -on-e interaction can be clustered together into another interaction, or additional hits can be clustered together into the  $\nu$ -on-e event. To save up on unnecessary disk space and processing usage, the enhanced  $\nu$ -on-e sample does not include any cross section related parameters and variables, as the  $\nu$ -on-e interaction is assumed to be known exactly from theory. Therefore, we do not apply cross section weights or account for cross section systematic uncertainties for  $\nu$ -on-e events.

The cross section tuning procedure in NOvA (Sec. 1.4) applies large weights to MEC events in some parts of the parameter space. However, after the full event selection (Sec. 2.3) only a small number of MEC events remain in the detector. This was shown to be an issue especially for the  $\nu_e$ CC MEC events [103]. Applying large tuning corrections to a small number of events results in large statistical fluctuations. To avoid this, we created another special sample with enhanced number of  $\nu_e$ CC MEC events, following the same procedure as for the  $\nu$ -on-e-enhanced sample, with an exposure of  $1.99 \times 10^{24}$  POT.

A summary of the simulation samples and analysis weights for the four different

types of signal and background components is shown in Tab. 2.1. In the following chapter, the  $\nu_e$ CC MEC background is added into the ‘Other background’ sample, even though it is created from a separate simulation.

Table 2.1: Overview of the simulation samples and analysis weight used for the different signal and background components.

Signal type	Sample	Weight
Signal	Enhanced $\nu$ -on-e	Flux & $\nu$ Mag. Moment
$\nu$ -on-e background	Enhanced $\nu$ -on-e	Flux & Rad. Corr.
$\nu_e$ CC MEC background	Enhanced $\nu_e$ CC MEC	Flux & Cross Sec.
Other background	Nominal ND	Flux & Cross Sec.

## 2.3 Event Selection

We are searching for  $\nu$ -on-e elastic scattering events, characterised by a single very forward going electron shower, specifically focusing on low electron recoil energies. The main backgrounds for our analysis come from  $\nu_e$ CC interactions, which produce an electron with additional activity, and interactions that produce  $\pi^0$ , which decays into two photons producing electromagnetic showers, where each can look similar to the  $\nu$ -on-e signal. Additionally, there are  $\nu_\mu$ CC interactions, which are generally easy to distinguish from our signal, however, their very high abundance in the NOvA ND makes them a dominant background nevertheless.

I explain the motivation behind each cut of the event selection and discuss their effect on the neutrino magnetic moment events below. I also consider possible improvements to the event selection for a future (re-)analysis.

The strategy for event selection is as follows. First, I remove events that failed reconstruction or data collection, described in Sec. 2.3.1 and 2.3.2. Then, I apply pre-selection cuts that remove obvious background (Sec. 2.3.3), while limiting the reduction of the signal efficiency to about 0.25 %. Following this, I apply the containment cuts (Sec. 2.3.4) that remove events that are either not fully contained within the detector, or events that originate from outside of the detector, such as rock muons. Afterwards, I perform a cut-based Multi Variate Analysis (MVA) on a selection of variables useful for distinguishing the signal from the background, discussed in Sec. 2.3.5,

and evaluate their combined performance on the signal selection. I choose the cut values that result in the best statistical significance, based on a chosen Figure Of Merit (FOM). Given that we are searching for a very limited number of signal events on top of a large background, I chose a simple statistics-only FOM

$$\text{FOM} = \frac{\text{Signal}}{\sqrt{\text{Background}}}. \quad (2.39)$$

The summary of the cut values for the event selection of neutrino magnetic moment signal is presented in Tab. 2.2, showing the label for the event selection variable, its description and the cut value chosen. After the full event selection, the predicted number of signal events for  $\mu_\nu = 10^{-9}\mu_B$  is 56.80 and the total number of background events under the SM hypothesis is 700.33.

### 2.3.1 Data Collection Quality

To ensure good data quality, we apply the following criteria to data (not applied to simulation) [119]. A cut on the time of each spill relative to other spills and on the exposure of each spill, where every spill is required to have at least  $2^{12}$  POT. Additionally, the current in the focusing horn is required to be within  $-202\text{ kA} < I_{Horn} < -196.4\text{ kA}$ , the position of the beam to be within  $\pm 2\text{ cm}$  in both x and y axis, and that the width of the beam to be within 0.57 and 1.58 cm. Furthermore, incomplete events, or events with issues in one or more DCMs are removed.

### 2.3.2 Reconstruction Quality

As described in Sec. 1.5, electrons are reconstructed by slicing, then vertexing, then clustering into prongs. To identify electrons we require a valid reconstructed vertex and at least one reconstructed prong. Even though electrons only consist of a single shower, we don't reject events with more than one prong in a slice, as the reconstruction can wrongly assign noise hits as a separate prong. These false secondary prongs can be removed later in the event selection.

Figure 2.6 and Tab. 2.3 show that about 68 % of signal events do not have a valid reconstructed vertex. This is due to the concentration of signal events at very low electron recoil energies, which results in events that can consist of a small number

of hits, or even a single hit. As can be seen in the bottom plot in Fig. 2.6, events with small true electron recoil energies have much smaller vertex reconstruction efficiency than the higher energetic electrons. However, ongoing work is improving the vertex reconstruction in the **NOvA** detectors with a use of **ML** instead of the currently used Hough transform combined with Elastic Arms [120]. Improving **NOvA** vertex reconstruction at low energies can enhance our event selection in the future.

Table 2.2: Summary of the variables and their cut values for the event selection of neutrino magnetic moment signal. Showing the category of the event selection variable, its label, description and the cut value chosen.

	<b>Label</b>	<b>Description</b>	<b>Cut</b>
<b>Reco Qual.</b>	<b>Valid Vtx</b>	Valid reconstructed vertex	$> 0$
	<b>Nº Prongs</b>	Number of reconstructed prongs	$> 0$
	<b>Hits / Plane</b>	Number of hits per plane	$< 6$
	<b>Low <math>E_{Shower}</math></b>	Low cut on calorimetric energy of the most energetic shower	$> 0.5 \text{ GeV}$
<b>Pre-selection</b>	<b>Nº Hits Loose</b>	Preliminary cut on the total number of hits for all prongs in a slice	$< 280$
	<b>Prong Length</b>	Length of the longest prong	$< 640 \text{ cm}$
	<b><math>E\theta^2</math> Loose</b>	Preliminary cut on the product of the calorimetric energy and angle squared of the leading shower	$< 0.064 \text{ GeV} \times \text{rad}^2$
<b>Fiducial</b>	<b>Vertex</b>	x position	$> -177 \text{ cm}$
		y position	$< 177 \text{ cm}$
		z position	$> -177 \text{ cm}$ $< 177 \text{ cm}$ $> 50 \text{ cm}$ $< 1170 \text{ cm}$
	<b>Containment</b>	Minimum hit position in x Maximum hit position in x Minimum hit position in y Maximum hit position in y Minimum hit position in z Maximum hit position in z	$> -177 \text{ cm}$ $< 177 \text{ cm}$ $> -185 \text{ cm}$ $< 177 \text{ cm}$ $> 55 \text{ cm}$ $< 1270 \text{ cm}$
<b>Selection</b>	<b><math>E_{Shower}/E_{Tot}</math></b>	Fraction of energy contained in the most energetic shower	$> 0.91$
	<b>Nº Hits</b>	Total number of hits for all prongs in a slice	$< 116$
	<b>High <math>E_{Shower}</math></b>	Calorimetric energy of the most energetic shower	$< 1.4 \text{ GeV}$
	<b><math>\nu\text{-on-e ID}</math></b>	CVN-based $\nu\text{-on-e}$ identifier	$> 0.65$
	<b><math>E\pi^0</math> ID</b>	CVN-based $\nu\text{-on-e}$ and $\pi^0$ identifier	$> 0.63$
	<b><math>E\theta^2</math></b>	Product of the calorimetric energy and angle squared of the leading shower	$< 0.0048 \text{ GeV} \times \text{rad}^2$

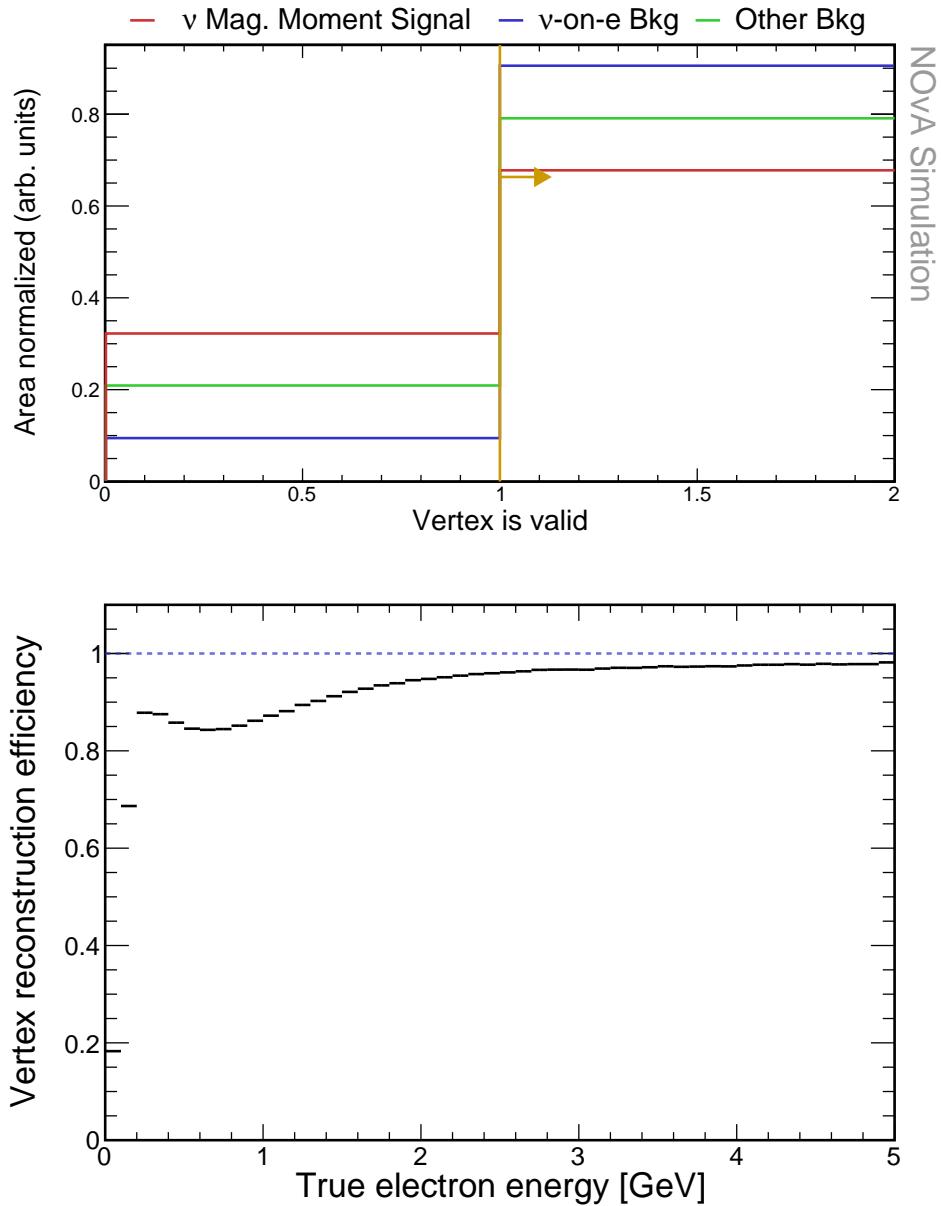


Figure 2.6: Top: Relative comparison of the signal (red),  $\nu$ -on-e background (blue), and other background (green) events for the vertex reconstruction quality selection. Each histogram is area-normalised and the first bin corresponds to events without a valid vertex and second bin to events with correctly reconstructed vertex. The yellow line indicates the chosen cut value, where all events have to have a valid reconstructed vertex. Bottom: profile histogram of the ‘vertex is valid’ variable as a function of the true electron energy for the true signal events, showing the significant drop in vertex reconstruction efficiency at low electron recoil energies. No selection was applied prior to making these plots.

Additionally, we limit the number of hits per plane to  $< 6$ . This is to remove the so-called ‘FEB flashers’, which are caused by such a high energy deposit in one cell, that it affects all the other channels on the same APD [121]. The cut value was chosen so that it removes approximately 0.25 % signal events, which is the same criterion as is used for the pre-selection cuts described below. Relative comparisons between signal and background for the number of prongs and the number of hits per plane are shown in Fig. 2.7.

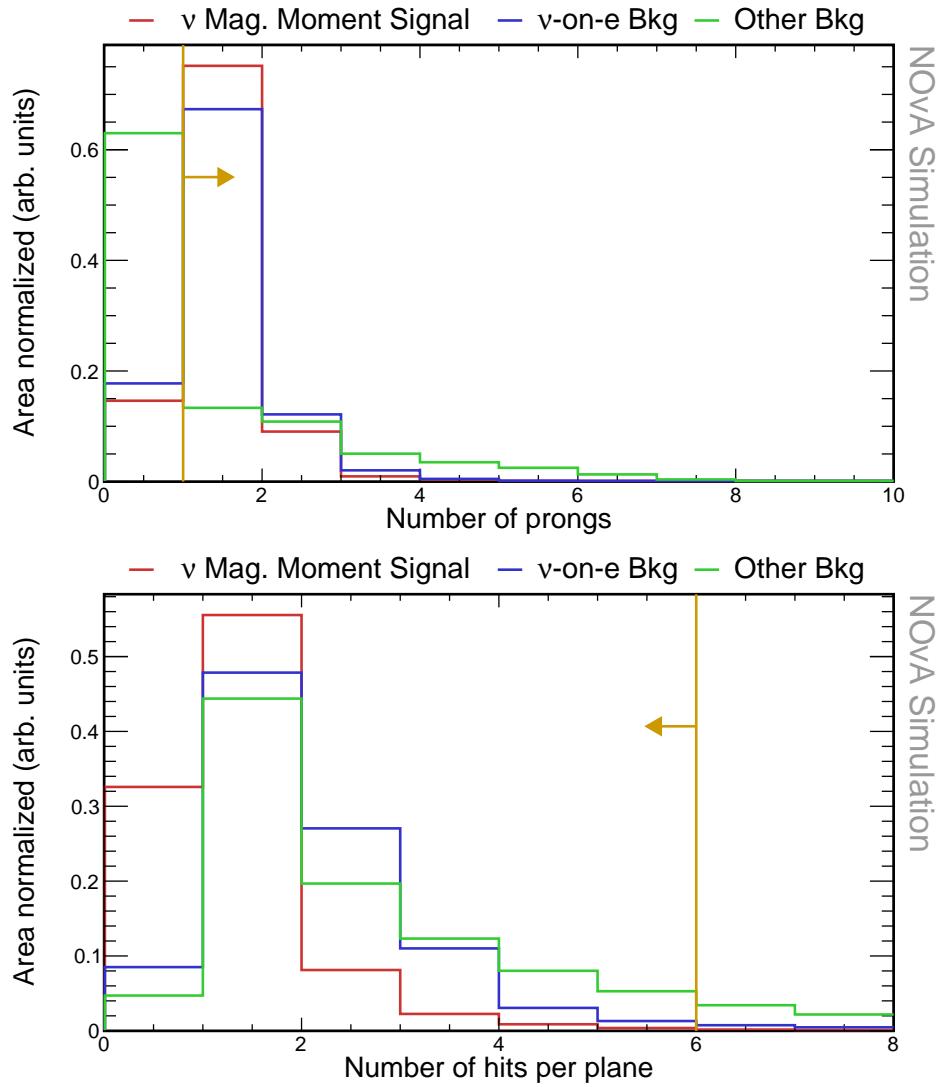


Figure 2.7: Relative comparison of signal (red),  $\nu$ -on-e background (blue), and other background (green) events in the number of prongs (top) and the number of hits per plane (bottom) distributions. Events in both plots are required to have a valid reconstructed vertex and in the bottom plot also at least one reconstructed prong. Yellow lines indicate the cut values for the shown variables, with arrows pointing towards the preserved events. All histograms are area-normalised.

Furthermore, the reconstructed calorimetric energy of the primary shower is re-

quired to be  $E_{cal} > 0.5 \text{ GeV}$  as shown in Fig. 2.8. This is primarily due to the limitations of the currently used **CVN**-based  $\nu\text{-on-e}$  identifiers described in Sec. 2.3.5, which were developed and validated for  $\nu\text{-on-e}$  events with energies above this limit, to avoid the large background at low energies. However, due to the nature of the neutrino magnetic moment signal, which is concentrated at low electron recoil energies, this cut also removes a majority of our signal events, specifically 66.8 %. This large reduction severely impacts the significance of our measurement. On the other hand, it also marks potentially the most impactful improvement available in a future re-analysis. There are other event identifying algorithms available in **NOvA** that could be explored for  $\nu\text{-on-e}$  events to leverage the low energy sample. Additionally, it is possible to develop a purpose-built  $\nu\text{-on-e}$  identifier focusing on low electron recoil energies.

Table 2.3: Event selection cutflow table for the reconstruction quality cuts showing the number of events and the relative efficiency of each cut for each signal sample. The relative efficiency is calculated as number of events remaining after applying the corresponding cut divided by number of events for all the previous cuts. All the cuts are listed in sequence as they are applied.

<b>Selection</b>	<b>Signal</b>		<b><math>\nu\text{-on-e}</math> bkg</b>		<b>Other bkg</b>	
	$N_{evt}$	$\epsilon_{rel} (\%)$	$N_{evt}$	$\epsilon_{rel} (\%)$	$N_{evt}$	$\epsilon_{rel} (\%)$
<b>No Cut</b>	817.34	100	$6.82 \times 10^3$	100	$2.96 \times 10^8$	100
<b>Valid Vtx</b>	553.86	67.76	$6.17 \times 10^3$	90.55	$2.34 \times 10^8$	79.10
<b>N° Prongs</b>	472.90	85.38	$5.08 \times 10^3$	82.25	$8.66 \times 10^7$	37.00
<b>Hits / Plane</b>	471.14	99.63	$4.97 \times 10^3$	97.85	$7.32 \times 10^7$	89.56
<b>Low <math>E_{Shower}</math></b>	156.37	33.19	$3.53 \times 10^3$	71.09	$4.06 \times 10^7$	55.12

### 2.3.3 Pre-Selection

Pre-selection aims to remove obvious background events without significantly affecting the signal. The criterion we chose for the selection of these cuts is determined by the reduction of the signal efficiency by approximately 0.25 % with each cut. This results in the total pre-selection reduction of the signal efficiency by approximately 1 %.

The first two variables used for our pre-selection are the same as were used in the event selection for the  $\nu_e$  appearance **ND** constraint for the three flavour neutrino oscillation measurements [7]. As we are searching for single electron showers, we

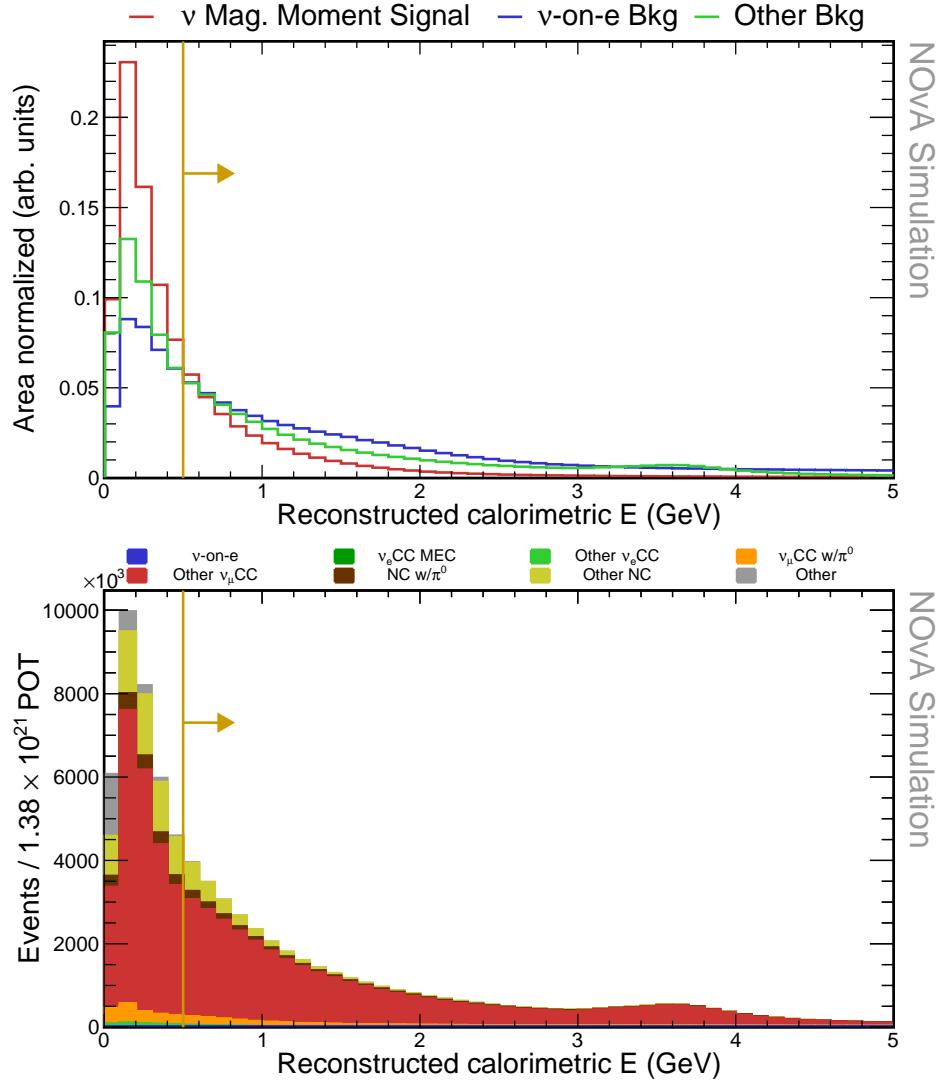


Figure 2.8: Top: Relative comparison of signal (red),  $\nu$ -on-e background (blue), and other background (green) events in the reconstructed calorimetric energy distribution. All histograms are area-normalised. Bottom: Decomposition of background into various sub-samples, normalised to the data POT exposure. Events in both plots are required to have a valid reconstructed vertex, at least one reconstructed prong and less than 6 hits per plane. Yellow lines indicate the cut value for the reconstructed calorimetric energy, with arrows pointing towards the preserved events.

can reduce backgrounds with multiple final state particles by limiting the total activity in the detector. Specifically, we require that the total number of hits assigned to all the reconstructed prongs is  $< 280$ . This is shown in Fig. 2.9. In general, the main background in NOvA consists of the  $\nu_\mu$ CC interactions, which are characterised by long muon tracks. We therefore limit the length of the longest reconstructed prong to be  $< 640$  cm, as shown in Fig. 2.10.

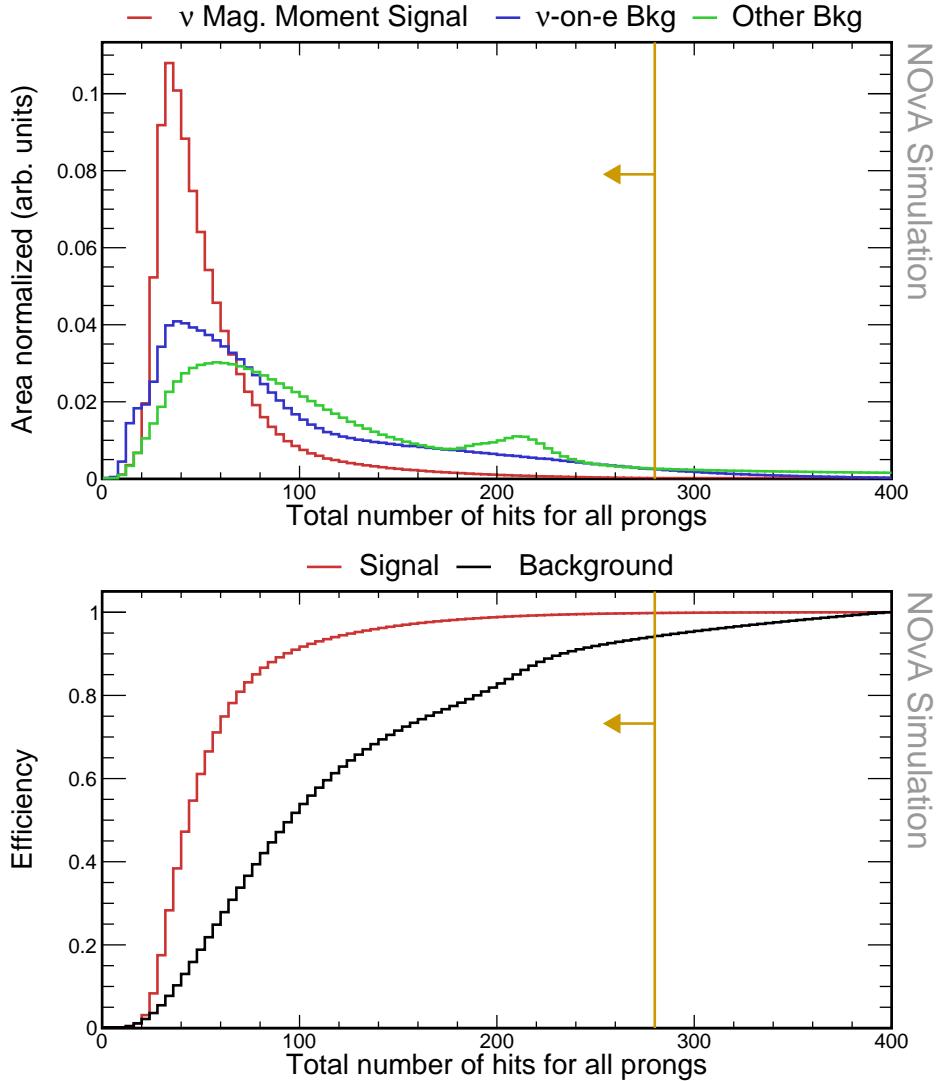


Figure 2.9: Top: Relative comparison of signal (red),  $\nu$ -on-e background (blue), and other background (green) events in the distribution of total number of hits from all reconstructed prongs in the slice. All histograms are area-normalised. Bottom: Cumulative signal (red) and background (black) efficiency calculated as number of signal/background events left of the bin divided by the total number of signal/background events. Yellow lines indicate the cut value for the maximum number of hits, with arrows pointing towards the preserved events. The reconstruction quality cuts were applied before making these plots.

Additionally, as discussed in Sec. 2.1.2, simple  $2 \rightarrow 2$  kinematics dictate that

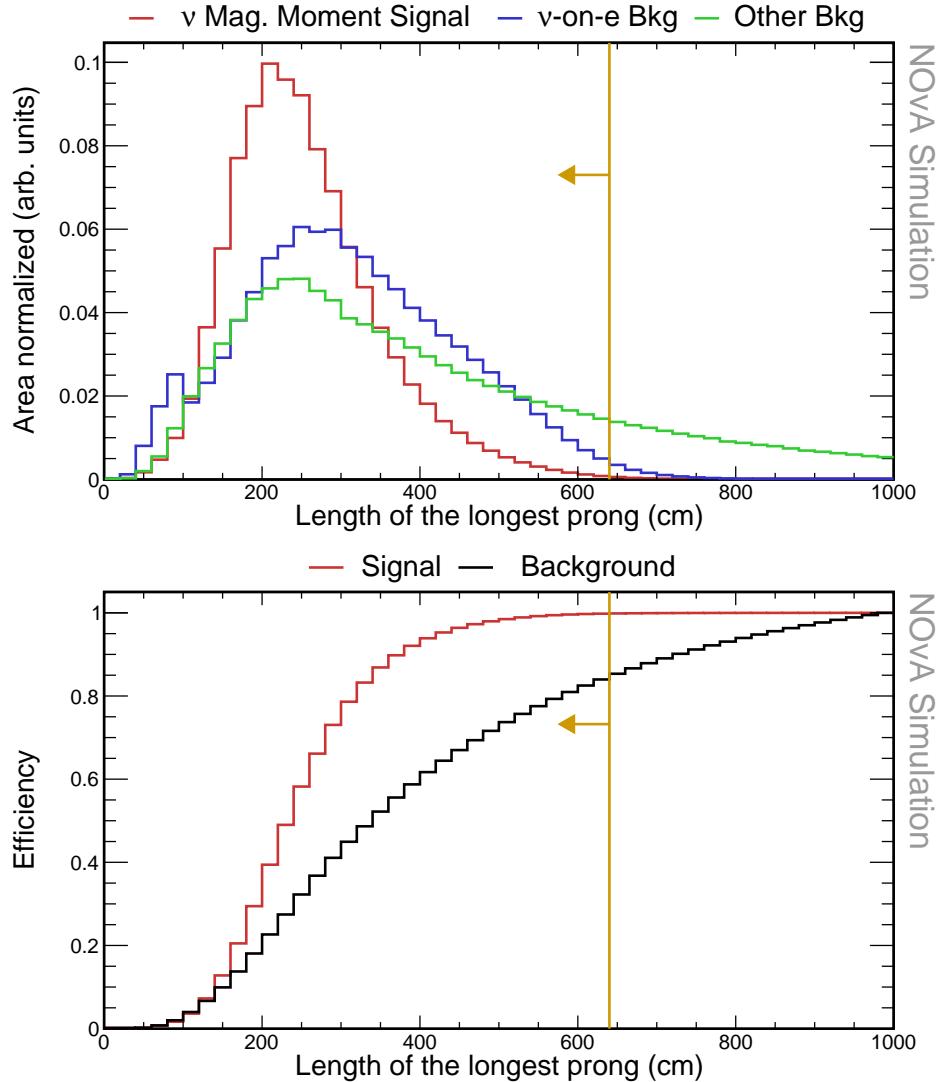


Figure 2.10: Top: Relative comparison of signal (red),  $\nu$ -on-e background (blue), and other background (green) events in the distribution of the length of the longest reconstructed prong in slice. All histograms are area-normalised. Bottom: Cumulative signal (red) and background (black) efficiency calculated as number of signal/background events left of the bin divided by the total number of signal/background events. Yellow lines indicate the cut value for the maximum length of the longest prong, with arrows pointing towards the preserved events. The reconstruction quality cuts and the number of hits cut were applied before making these plots.

the true electron recoil energy and angle for the  $\nu$ -on-e interaction are limited by  $E\theta^2 < 2m_e$ . This can be used to distinguish  $\nu$ -on-e elastic scattering from  $\nu_e$ CC interactions, which also have an electron in the final state. However, due to unavoidable reconstruction deficiencies, the reconstructed  $E\theta^2$  does not have such a strict cut-off value, and we are placing the pre-selection cut at  $E\theta^2 < 0.064$ , as can be seen in Fig. 2.11. Furthermore, some of the signal events can be reconstructed with the opposite direction with respect to the beam, which would result in  $\theta \approx \pi$  rad. However, this reconstruction failure likely does not impact other reconstructed qualities and these events should be preserved for the final sample. For that reason, we are calculating the angle between the outgoing electron and the neutrino beam direction as  $\arccos(\text{abs}(\cos \theta))$ , which gives the same value whether the shower is reconstructed forward or backwards.

The effect of the pre-selection cuts on the signal and background samples are summarised in Tab. 2.4, where the first row lists the number of events after applying all the reconstruction quality cuts from Sec. 2.3.2. All three of the variables used for the pre-selection are employed again in the MVA, as described in Sec. 2.3.5.

Table 2.4: Pre-selection cutflow table showing the number of events and the relative efficiency of each cut for each signal sample. The relative efficiency is calculated as number of events remaining after applying the corresponding cut divided by number of events for all the previous cuts. All the cuts are listed in sequence as they are applied. The top row corresponds to the sample after applying the reconstruction quality cuts.

<b>Selection</b>	<b>Signal</b>		<b><math>\nu</math>-on-e bkg</b>		<b>Other bkg</b>	
	$N_{\text{evt}}$	$\epsilon_{\text{rel}} (\%)$	$N_{\text{evt}}$	$\epsilon_{\text{rel}} (\%)$	$N_{\text{evt}}$	$\epsilon_{\text{rel}} (\%)$
<b>Reco Quality</b>	156.37	100	$3.53 \times 10^3$	100	$4.28 \times 10^7$	100
<b>No Hits Loose</b>	156.05	99.79	$3.41 \times 10^3$	96.46	$3.61 \times 10^7$	84.35
<b>Prong Length</b>	155.7	99.78	$3.37 \times 10^3$	98.85	$2.61 \times 10^7$	72.36
<b><math>E\theta^2</math> Loose</b>	155.14	99.64	$3.33 \times 10^3$	98.83	$8.83 \times 10^6$	33.82

### 2.3.4 Fiducial and Containment Cuts

To ensure all the deposited energy of the recoil electron is contained within the detector and to remove events originating outside of the detector (such as rock muons for the ND), we constrain the position of the reconstructed vertex and all the prongs in the slice. The decision on where to place the exact cut values is made based on the maximum FOM value.

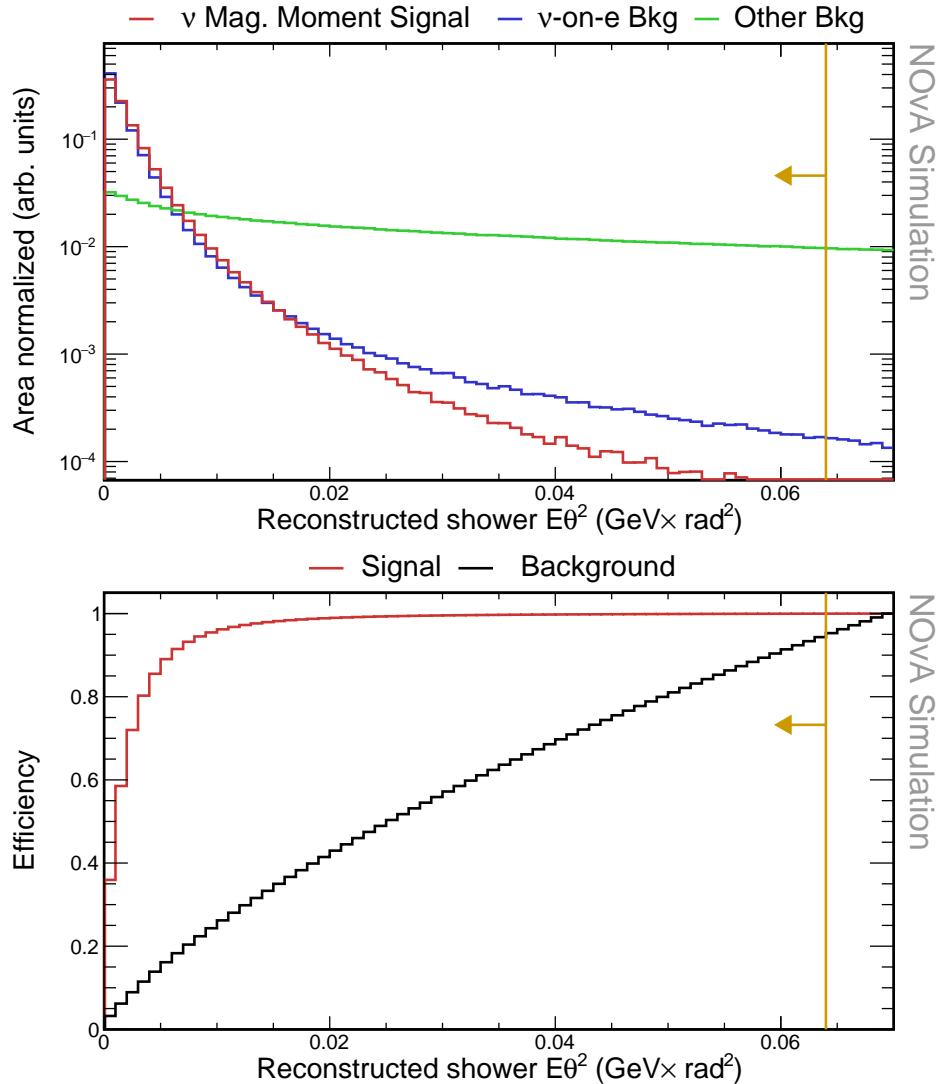


Figure 2.11: Top: Relative comparison of signal (red),  $\nu$ -on-e background (blue), and other background (green) events in the distribution of the reconstructed energy of the leading shower multiplied by its angle from the incoming neutrino beam direction squared. All histograms are area-normalised with logarithmic y axis. Bottom: Cumulative signal (red) and background (black) efficiency calculated as number of signal/background events left of the bin divided by the total number of signal/background events. Yellow lines indicate the cut value for the depicted variable, with arrows pointing towards the preserved events. The reconstruction quality cuts, the number of hits cut, and the length of the longest prong cuts were applied before making both of these plots.

The reconstructed vertex is required to be within the fiducial volume, which represents a well-understood volume of the detector. To select the fiducial volume, we investigate distributions of the reconstructed vertex in the x, y and z direction, shown in Fig. 2.12, 2.13 and 2.14 respectively. Basic reconstruction quality and pre-selection cuts are applied to make these distributions. Additionally, for the x and y position distributions, we require that the vertex is not placed inside of the Muon Catcher by requiring  $Vtx_Z < 1270$  cm, as it can significantly affect these distributions. The slanted distributions in x and y are caused by the off-axis nature of the NuMI beam and the periodic peaks are due to a combination of the detector structure and the choice of binning.

The reconstructed vertex is required to be contained within the following volume:

$$-175 \text{ cm} < Vtx_X < 175 \text{ cm}, \quad (2.40)$$

$$-175 \text{ cm} < Vtx_Y < 175 \text{ cm}, \quad (2.41)$$

$$95 \text{ cm} < Vtx_Z < 1170 \text{ cm}. \quad (2.42)$$

Furthermore, we constrain the extreme positions (minimum and maximum) of all the hits within the most energetic prong, which is assumed to represent the electron shower for the signal events. We apply the reconstruction quality, pre-selection and fiducial (vertex position) cuts to their distributions, shown in Fig. 2.15-2.20. The extreme hit positions are required to be within the following volume:

$$-175 \text{ cm} < \min_X, \max_X < 175 \text{ cm}, \quad (2.43)$$

$$-175 \text{ cm} < \min_Y, \max_Y < 175 \text{ cm}, \quad (2.44)$$

$$105 \text{ cm} < \min_Z, \max_Z < 1270 \text{ cm}. \quad (2.45)$$

### 2.3.5 Multivariate Analysis Cuts

Following the removal of obvious backgrounds and events not contained within the detector, we aim to optimise the event selection to achieve the highest significance for measuring the effective muon neutrino magnetic moment. This goal is equivalent to maximising our FOM from Eq. 2.39.

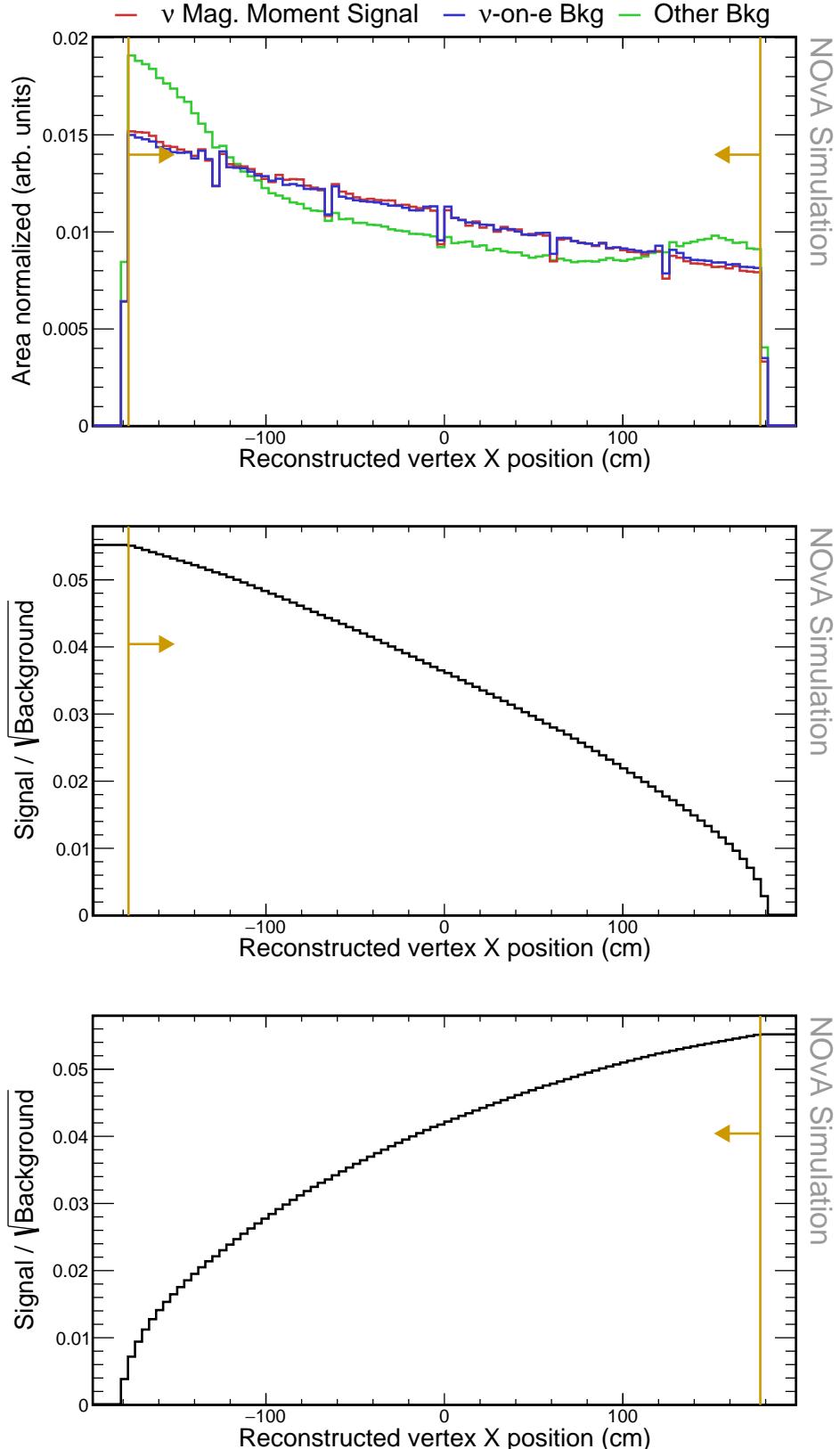


Figure 2.12: Top: Relative comparison of signal (red),  $\nu$ -on-e background (blue), and other background (green) events in the distribution of the x position of the reconstructed vertex. All histograms are area-normalized. Middle and bottom: Cumulative FOM calculated as the number of signal events, divided by the number of background events from that bin until the end of the plot to the right (middle) or left (bottom). The reconstruction quality and pre-selection cuts were applied prior to making these plots. Additionally, vertex is required to be within the active region of the detector ( $Vtx_Z < 1270$  cm). Yellow lines show the cut values that create the fiducial volume, with arrows pointing towards the preserved events.

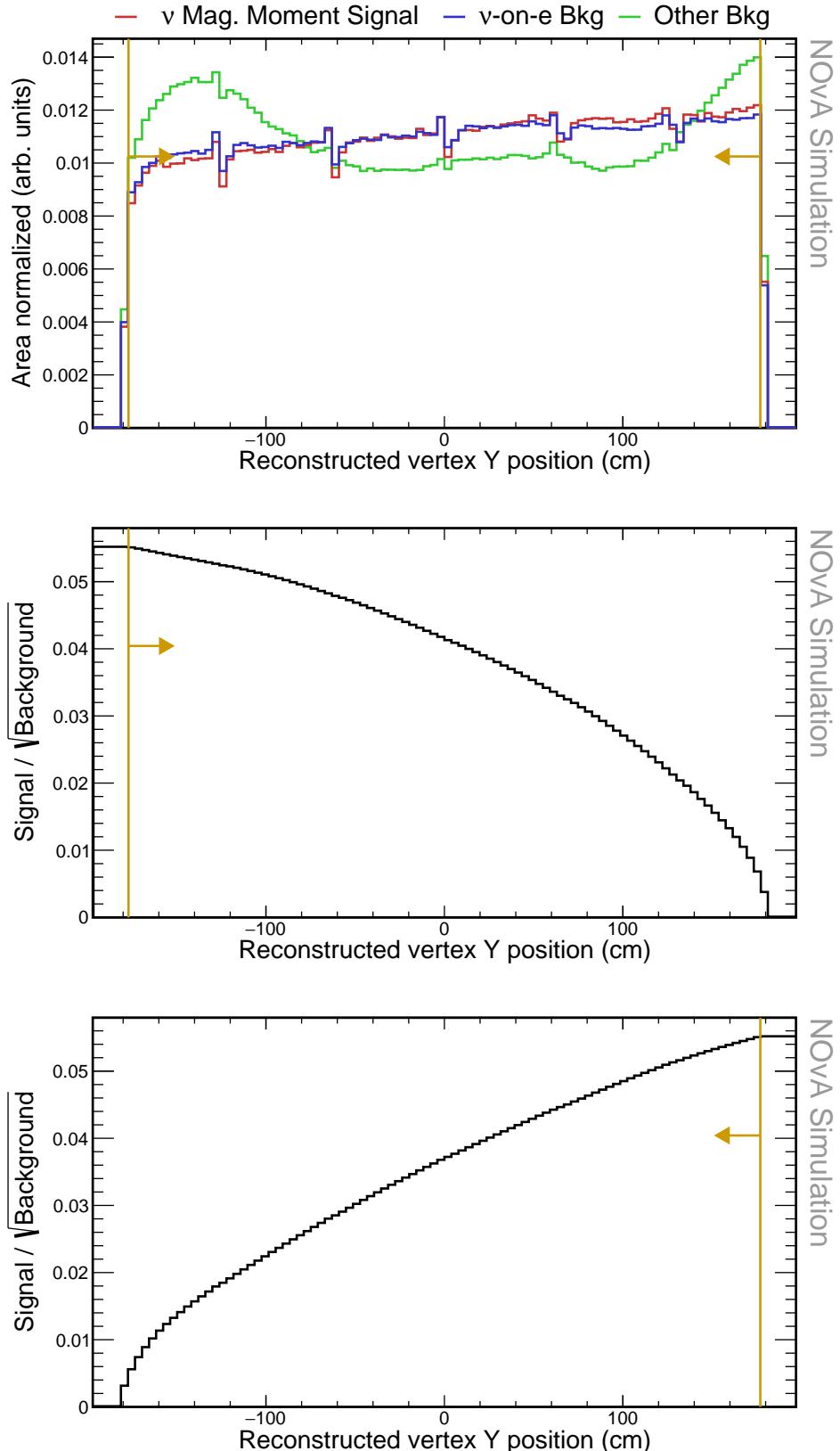


Figure 2.13: Top: Relative comparison of signal (red),  $\nu$ -on-e background (blue), and other background (green) events in the distribution of the y position of the reconstructed vertex. All histograms are area-normalized. Middle and bottom: Cumulative FOM calculated as the number of signal events, divided by the number of background events from that bin until the end of the plot to the right (middle) or left (bottom). The reconstruction quality and pre-selection cuts were applied prior to making these plots. Additionally, vertex is required to be within the active region of the detector ( $Vtx_Z < 1270$  cm). Yellow lines show the cut values that create the fiducial volume, with arrows pointing towards the preserved events.

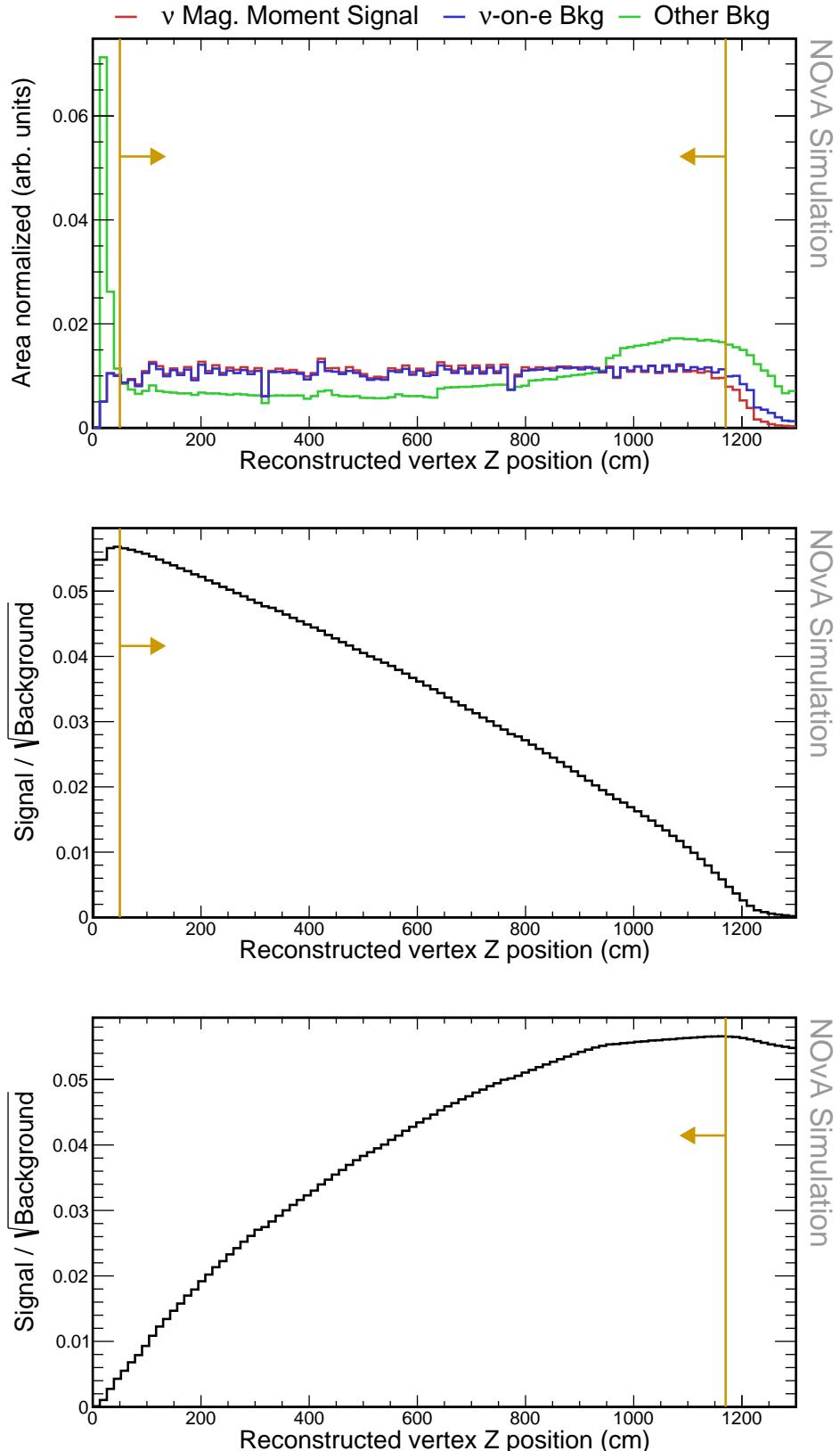


Figure 2.14: Top: Relative comparison of signal (red),  $\nu$ -on-e background (blue), and other background (green) events in the distribution of the z position of the reconstructed vertex. All histograms are area-normalized. Middle and bottom: Cumulative FOM calculated as the number of signal events, divided by the number of background events from that bin until the end of the plot to the right (middle) or left (bottom). The reconstruction quality and pre-selection cuts were applied prior to making these plots. Yellow lines show the cut values that create the fiducial volume, with arrows pointing towards the preserved events.

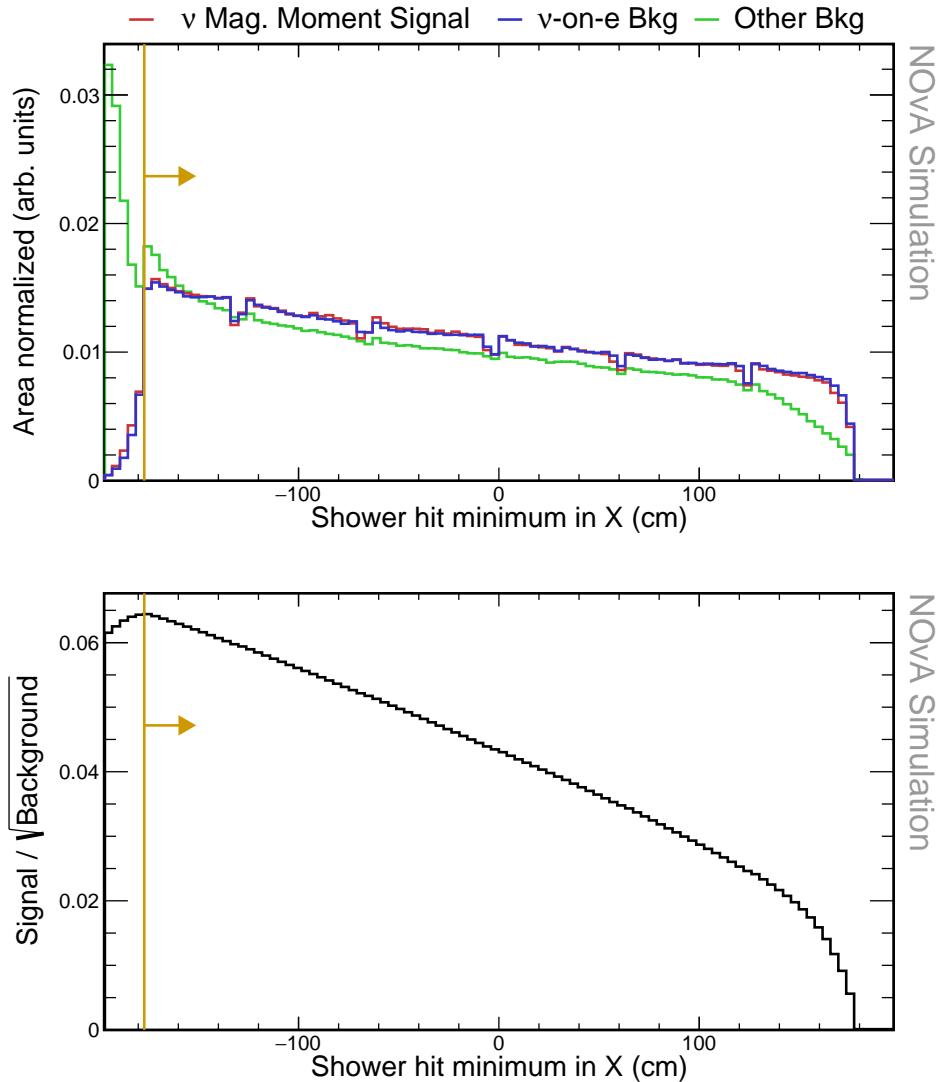


Figure 2.15: Top: Relative comparison of signal (red),  $\nu$ -on-e background (blue), and other background (green) events in the distribution of the minimum hit position of the most energetic prong along the x axis. All histograms are area-normalized. Bottom: Cumulative FOM calculated as the number of signal events, divided by the number of background events from that bin until the end of the plot in the direction of the yellow arrow. The reconstruction quality, pre-selection and fiducial cuts were applied prior to making these plots. Yellow lines show the cut values that create the containment volume, with arrows pointing towards the preserved events.

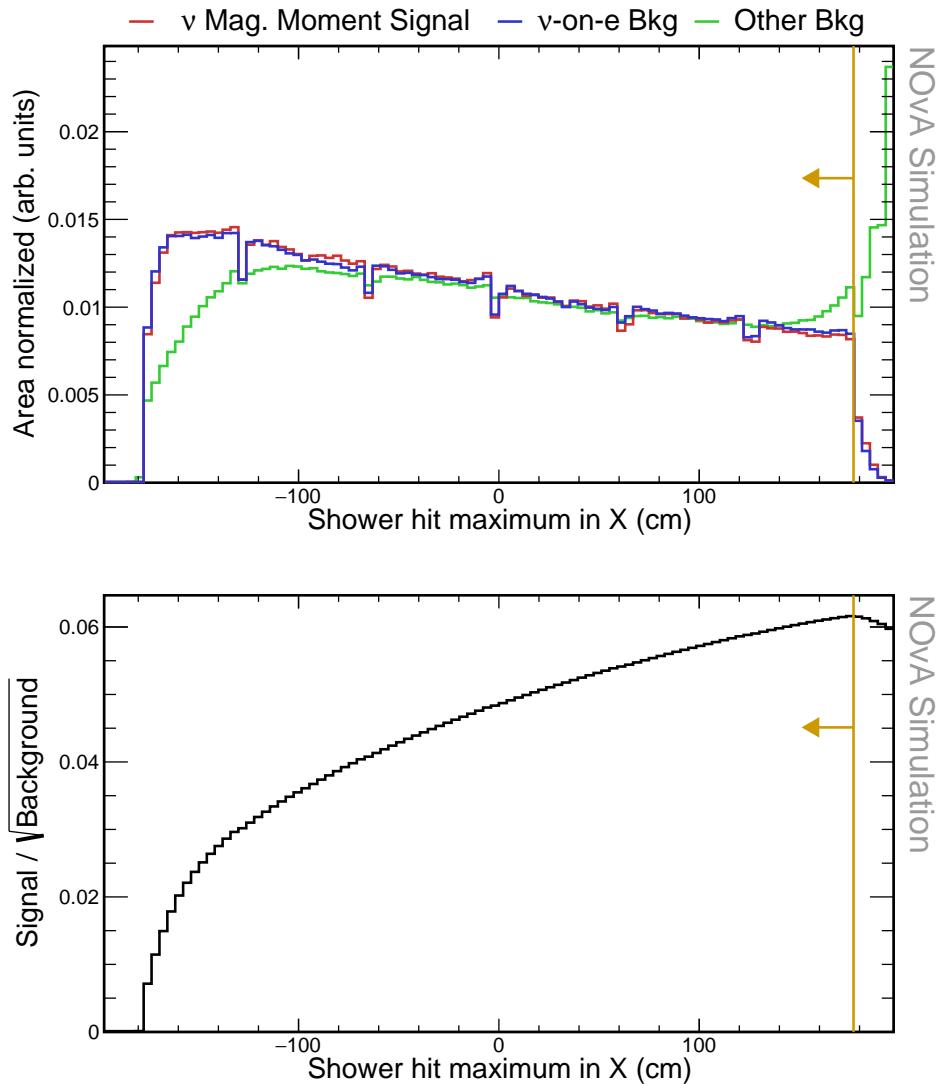


Figure 2.16: Top: Relative comparison of signal (red),  $\nu$ -on-e background (blue), and other background (green) events in the distribution of the maximum hit position of the most energetic prong along the x axis. All histograms are area-normalized. Bottom: Cumulative FOM calculated as the number of signal events, divided by the number of background events from that bin until the end of the plot in the direction of the yellow arrow. The reconstruction quality, pre-selection and fiducial cuts were applied prior to making these plots. Yellow lines show the cut values that create the containment volume, with arrows pointing towards the preserved events.

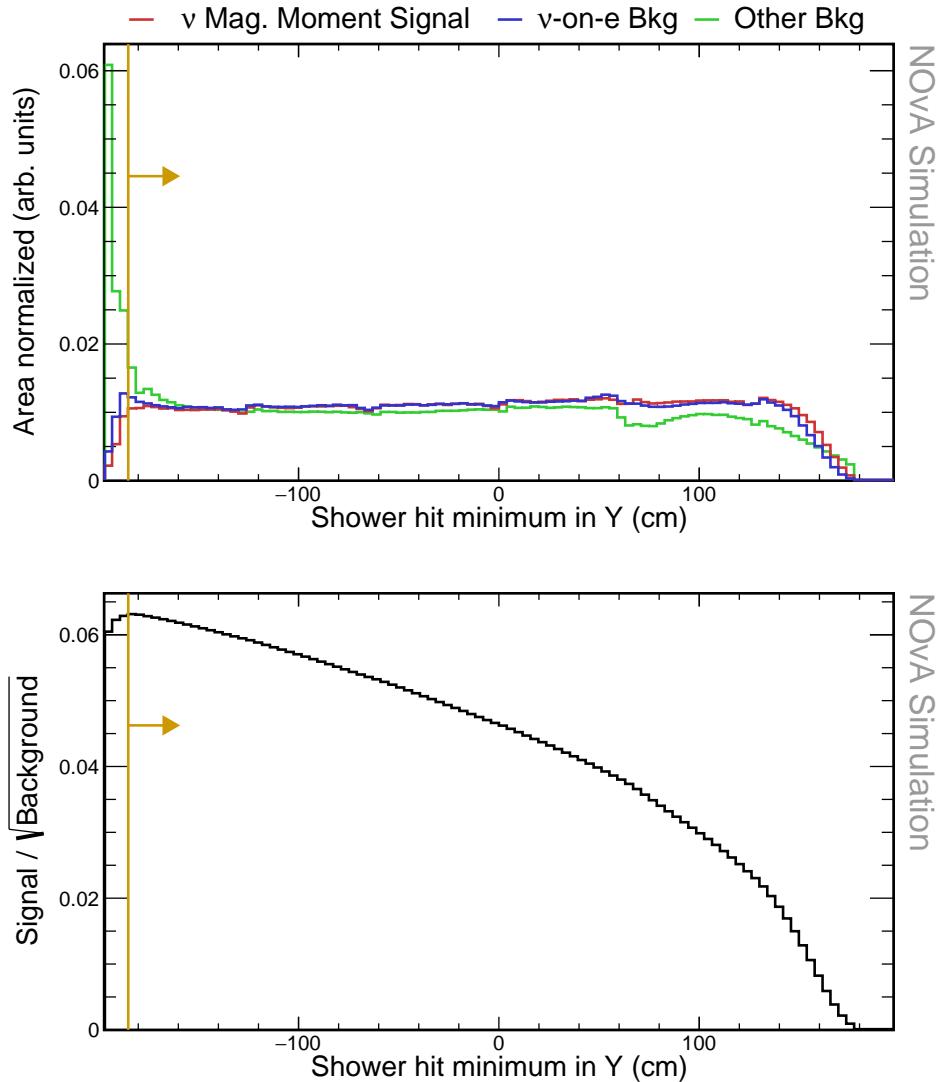


Figure 2.17: Top: Relative comparison of signal (red),  $\nu$ -on-e background (blue), and other background (green) events in the distribution of the minimum hit position of the most energetic prong along the y axis. All histograms are area-normalized. Bottom: Cumulative FOM calculated as the number of signal events, divided by the number of background events from that bin until the end of the plot in the direction of the yellow arrow. The reconstruction quality, pre-selection and fiducial cuts were applied prior to making these plots. Yellow lines show the cut values that create the containment volume, with arrows pointing towards the preserved events.

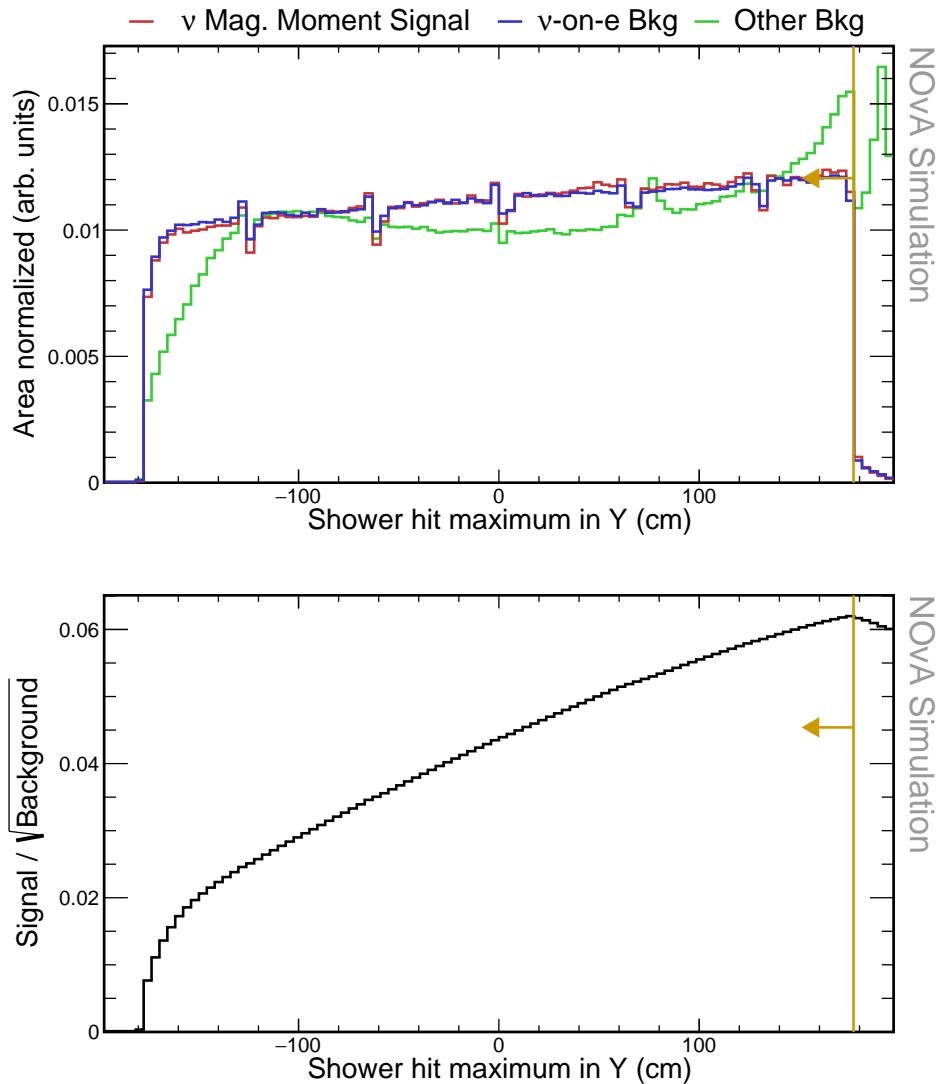


Figure 2.18: Top: Relative comparison of signal (red),  $\nu$ -on-e background (blue), and other background (green) events in the distribution of the maximum hit position of the most energetic prong along the y axis. All histograms are area-normalized. Bottom: Cumulative FOM calculated as the number of signal events, divided by the number of background events from that bin until the end of the plot in the direction of the yellow arrow. The reconstruction quality, pre-selection and fiducial cuts were applied prior to making these plots. Yellow lines show the cut values that create the containment volume, with arrows pointing towards the preserved events.

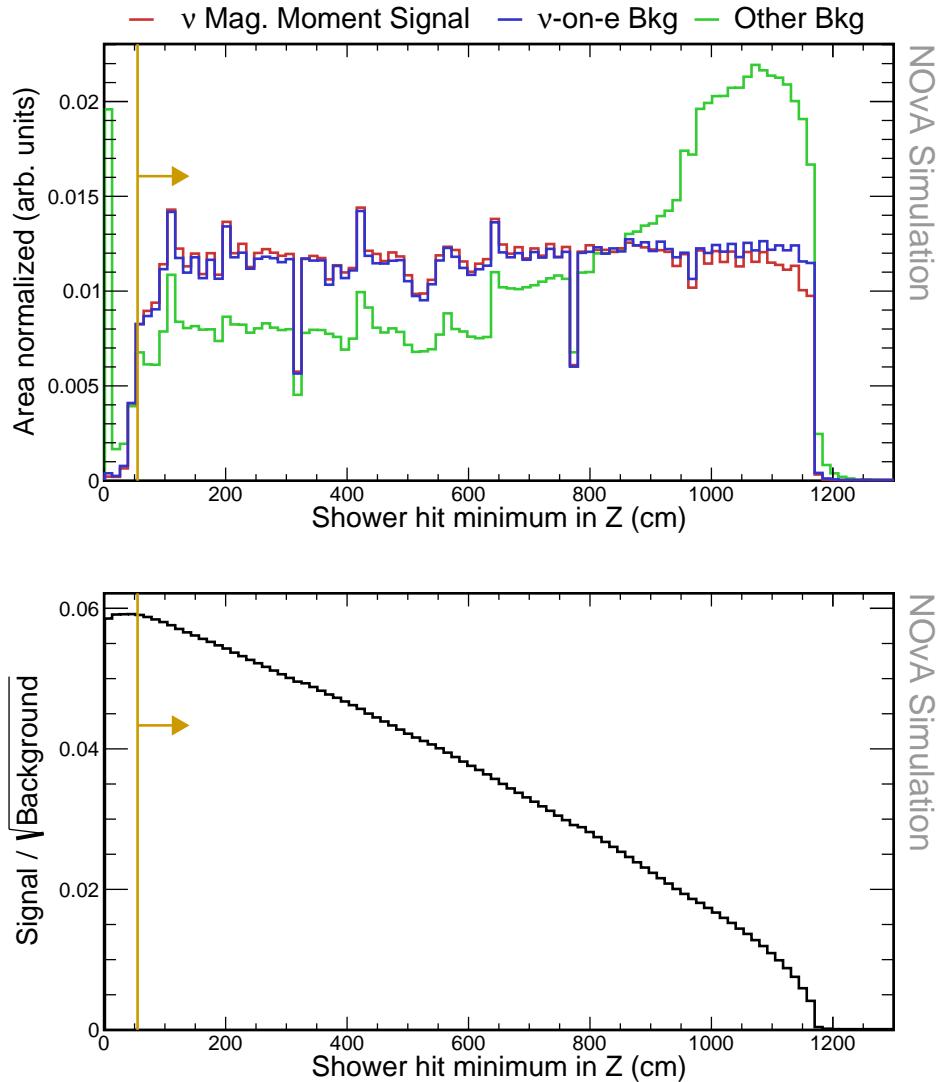


Figure 2.19: Top: Relative comparison of signal (red),  $\nu$ -on-e background (blue), and other background (green) events in the distribution of the minimum hit position of the most energetic prong along the z axis. All histograms are area-normalized. Bottom: Cumulative FOM calculated as the number of signal events, divided by the number of background events from that bin until the end of the plot in the direction of the yellow arrow. The reconstruction quality, pre-selection and fiducial cuts were applied prior to making these plots. Yellow lines show the cut values that create the containment volume, with arrows pointing towards the preserved events.

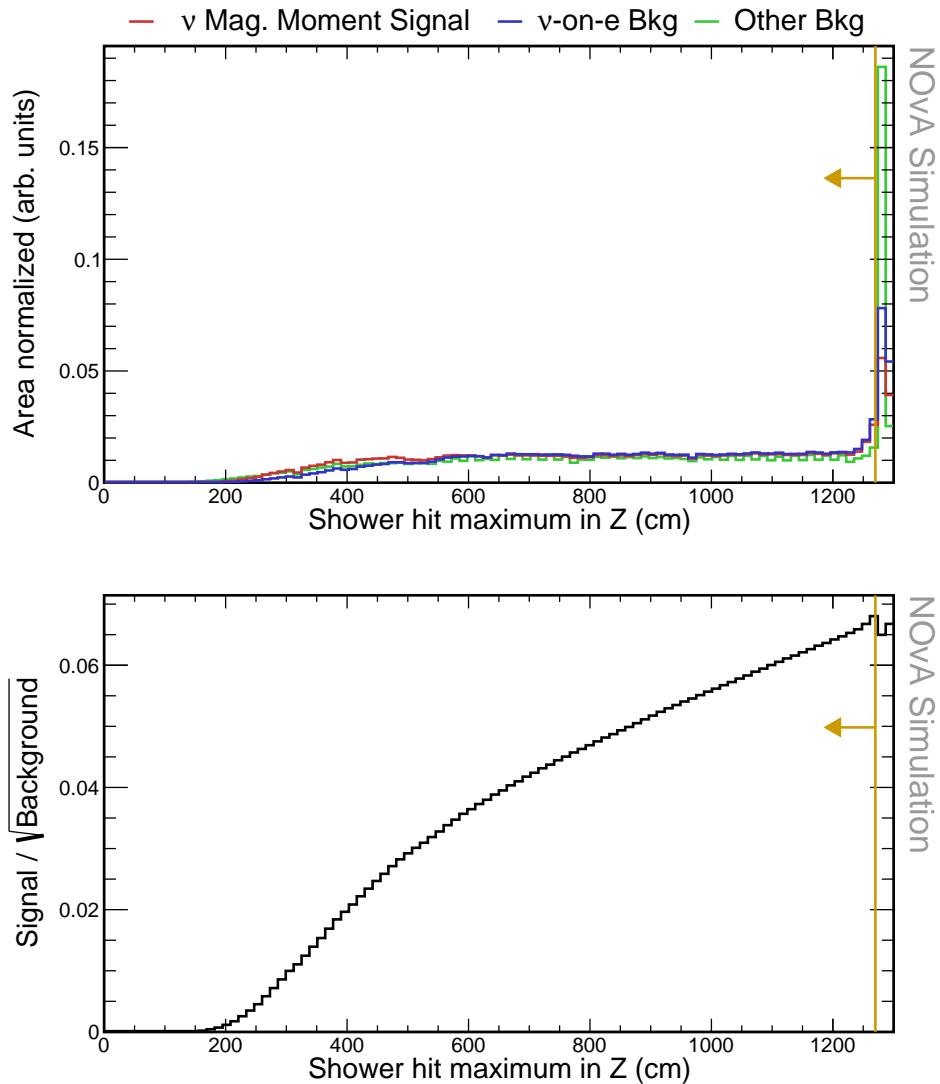


Figure 2.20: Top: Relative comparison of signal (red),  $\nu$ -on-e background (blue), and other background (green) events in the distribution of the maximum hit position of the most energetic prong along the z axis. All histograms are area-normalized. Bottom: Cumulative FOM calculated as the number of signal events, divided by the number of background events from that bin until the end of the plot in the direction of the yellow arrow. The reconstruction quality, pre-selection and fiducial cuts were applied prior to making these plots. Yellow lines show the cut values that create the containment volume, with arrows pointing towards the preserved events.

For this purpose, we utilised ROOT’s [122] Tool for MVA (TMVA) [123]. Specifically, we employed the rectangular cut optimisation method, which uses multivariate parameter fitters to maximise background rejection across the full range of signal efficiencies. We used the MC sampling fitting method, assuming that for each input variable, there is a single cut value (maximum or minimum) that optimally discriminates between signal and background.

TMVA generally performs better with a limited number of input variables that have strong discriminating power. Therefore, we investigated several input variables and selected only those that achieved significant background rejection. There are additional variables not mentioned here that might achieve better final results, providing opportunities for future re-analyses. Additionally, we do not apply any transformations to the input variables prior to optimisation, which might also improve the final result after dedicated study.

The variables considered include those already used in the pre-selection: the total number of hits for all prongs in slice, the length of the longest prong, and  $E\theta^2$ , as discussed in Sec. 2.3.3. During the TMVA optimisation, we found that the length of the longest prong did not significantly enhance discriminating power and thus removed it from the set of input variables. Additionally, we included the reconstructed energy of the most energetic shower, as used for reconstruction quality selection in Sec. 2.3.2, intending to restrict events with higher energies, since our signal is concentrated at low electron recoil energies.

Additionally, we considered all the variables used for the NOvA  $\nu$ -on-e analysis for the neutrino flux constraint [103]. The first is the fraction of the reconstructed

Table 2.5: Event selection cutflow table for the containment cuts showing the number of events and the relative efficiency of each cut for each signal sample. The relative efficiency is calculated as number of events remaining after applying the corresponding cut divided by number of event for all the previous cuts. All the cuts are listed in sequence as they are applied. The top row corresponds to the sample after applying the reconstruction quality and pre-selection cuts.

<b>Selection</b>	<b>Signal</b>		<b><math>\nu</math>-on-e bkg</b>		<b>Other bkg</b>	
	$N_{evt}$	$\epsilon_{rel}$ (%)	$N_{evt}$	$\epsilon_{rel}$ (%)	$N_{evt}$	$\epsilon_{rel}$ (%)
<b>Pre-selection</b>	155.14	100	$3.33 \times 10^3$	100	$8.83 \times 10^6$	100
<b>Fiducial</b>	143.02	92.19	$2.88 \times 10^3$	85.60	$5.96 \times 10^6$	67.57
<b>Containment</b>	117.41	82.09	$2.08 \times 10^3$	72.12	$1.10 \times 10^6$	18.38

energy of the most energetic shower ( $E_{Shower}$ ) to the total energy of all the reconstructed prongs in the entire slice ( $E_{Tot}$ ). This variable distinguished our signal events, which only have a single shower, from events with multiple showers or additional activity. The second is the gap between the vertex and the most energetic shower, which can distinguish between electron and  $\pi^0$  events, as the latter should have a characteristic gap several cells long. Additionally, we examined the amount of energy contained within  $\pm 8$  planes away from the vertex, besides the energy associated with the most energetic prong, which should distinguish the purely leptonic signal from backgrounds with significant hadronic activity. However, the gap and the vertex energy variables underperformed compared to others and were ultimately not used within the TMVA.

We also utilised two CNN-based event classifiers developed for the NOvA  $\nu$ -on-e analysis for the neutrino flux constraint [103, 104]. These classifiers are specifically designed to identify  $\nu$ -on-e interactions. The first, named  $\nu$ -on-e ID, is trained to select  $\nu$ -on-e events from the primary  $\nu_\mu$ CC background, while the second, named  $E\pi^0$  ID, is trained on events passing the  $\nu$ -on-e ID selection to reject the remaining background with a  $\pi^0$ . These classifiers use a pixel map of the entire slice as input and are designed with the same CNN architecture as ProngCVN and EventCVN described in Sec. 1.5.

The result of the TMVA is a set of cuts on each of the input variables that maximises the FOM. The input variables and the cuts that were selected for them are shown in Fig. 2.21, 2.22, and 2.23. The effect of these cuts is summarised in Tab. 2.6. Applying the TMVA cuts reduces the signal by 51.62 %, the  $\nu$ -on-e background by 75.03 % and other background by 99.98 %. The specific values of the cuts resulting

from the TMVA are

$$E_{Shower}/E_{Tot} > 0.91, \quad (2.46)$$

$$\text{Total } N^o \text{ hits for all prongs} < 116, \quad (2.47)$$

$$E_{Shower} < 1.4 \text{ GeV}, \quad (2.48)$$

$$E\theta^2 < 0.0048 \text{ GeV} \times \text{rad}^2, \quad (2.49)$$

$$\nu - on - eID > 0.65, \quad (2.50)$$

$$E\pi^0 ID > 0.63. \quad (2.51)$$

Table 2.6: Event selection cutflow table for the results of the cut-based Multivariate analysis, showing the number of events and the relative efficiency of each cut for each signal sample. The relative efficiency is calculated as number of events remaining after applying the corresponding cut divided by number of event for all the previous cuts. All the cuts are listed in sequence as they are applied. The top row corresponds to the sample after applying the reconstruction quality, pre-selection, fiducial and containment cuts.

<b>Selection</b>	<b>Signal</b>		<b><math>\nu</math>-on-e bkg</b>		<b>Other bkg</b>	
	$N_{evt}$	$\epsilon_{rel} (\%)$	$N_{evt}$	$\epsilon_{rel} (\%)$	$N_{evt}$	$\epsilon_{rel} (\%)$
<b>Contained</b>	117.41	100	$2.08 \times 10^3$	100	$1.10 \times 10^6$	100
$E_{Shower}/E_{Tot}$	113.03	96.28	$2.02 \times 10^3$	97.32	$4.53 \times 10^5$	41.30
<b>N<sup>o</sup> Hits</b>	106.48	94.20	$1.45 \times 10^3$	71.53	$4.02 \times 10^5$	88.78
<b>High <math>E_{Shower}</math></b>	85.51	80.31	777.91	53.76	$3.01 \times 10^5$	74.84
<b><math>\nu</math>-on-e ID</b>	72.23	84.47	652.32	83.86	$4.40 \times 10^3$	1.46
<b><math>E\pi^0</math> ID</b>	67.35	93.24	608.19	93.23	$2.83 \times 10^3$	64.34
<b><math>E\theta^2</math></b>	56.80	84.33	519.09	85.35	181.24	6.40

After the full event selection, the predicted number of signal events for  $\mu_\nu = 10^{-9} \mu_B$  is 56.80, and the total number of background events under the SM hypothesis is 700.33. The decomposition of background into interaction types is shown in Fig. 2.24 and listed in Tab. 2.7. The event selection results in

$$\text{Signal Purity} = \frac{\text{Signal}}{\text{Signal+Background}} = 7.50 \%, \quad (2.52)$$

$$\text{Signal Efficiency} = \frac{\text{Signal}}{\text{Signal}_{\text{No Cut}}} = 6.95 \%. \quad (2.53)$$

Also,

$$\frac{\text{Signal}}{\sqrt{\text{Background}}} = 2.15 \quad (2.54)$$

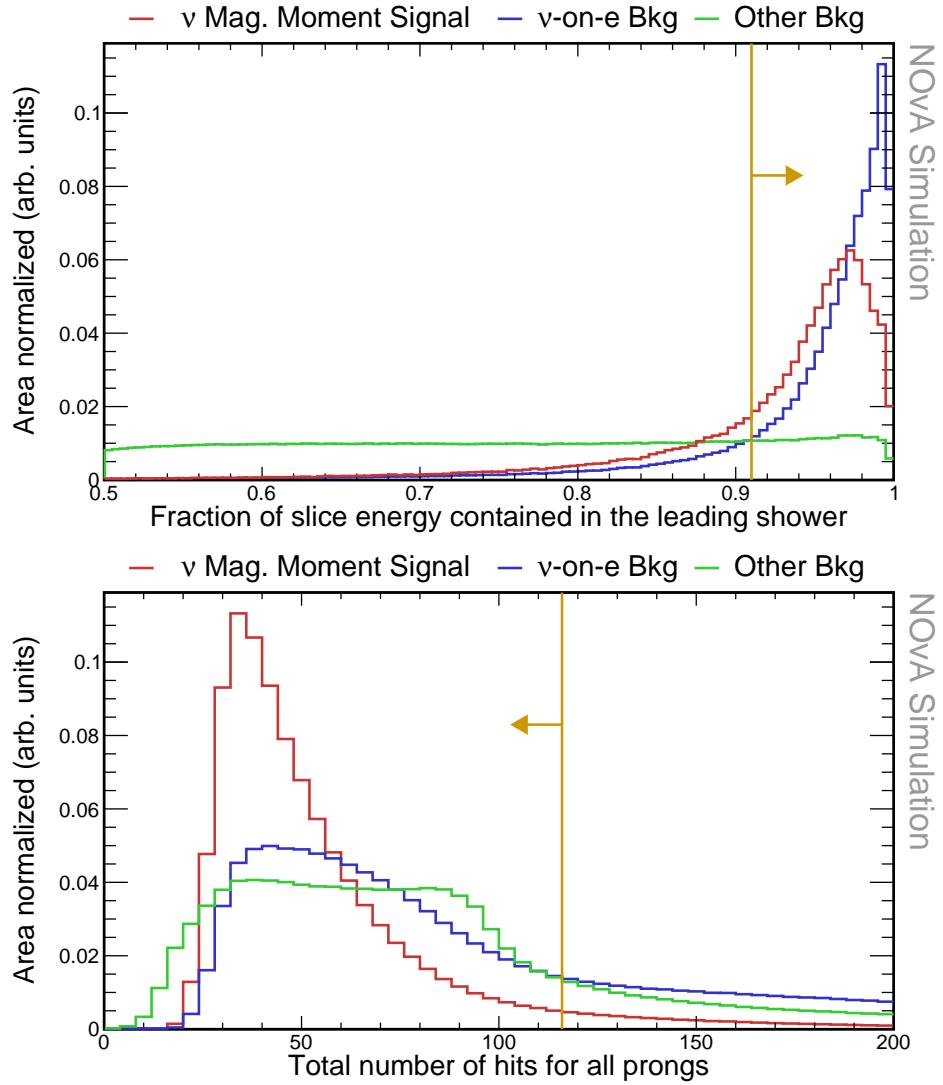


Figure 2.21: Relative comparison of signal (red),  $\nu$ -on-e background (blue), and other background (green) events in the distribution of the fraction of the total energy contained in the primary shower (top) and of the total number of hits in the slice (bottom). All histograms are area-normalized. The reconstruction quality, pre-selection, fiducial and containment cuts were applied prior to making these plots. Yellow lines show the cut values on the depicted variables, with arrows pointing towards the preserved events.

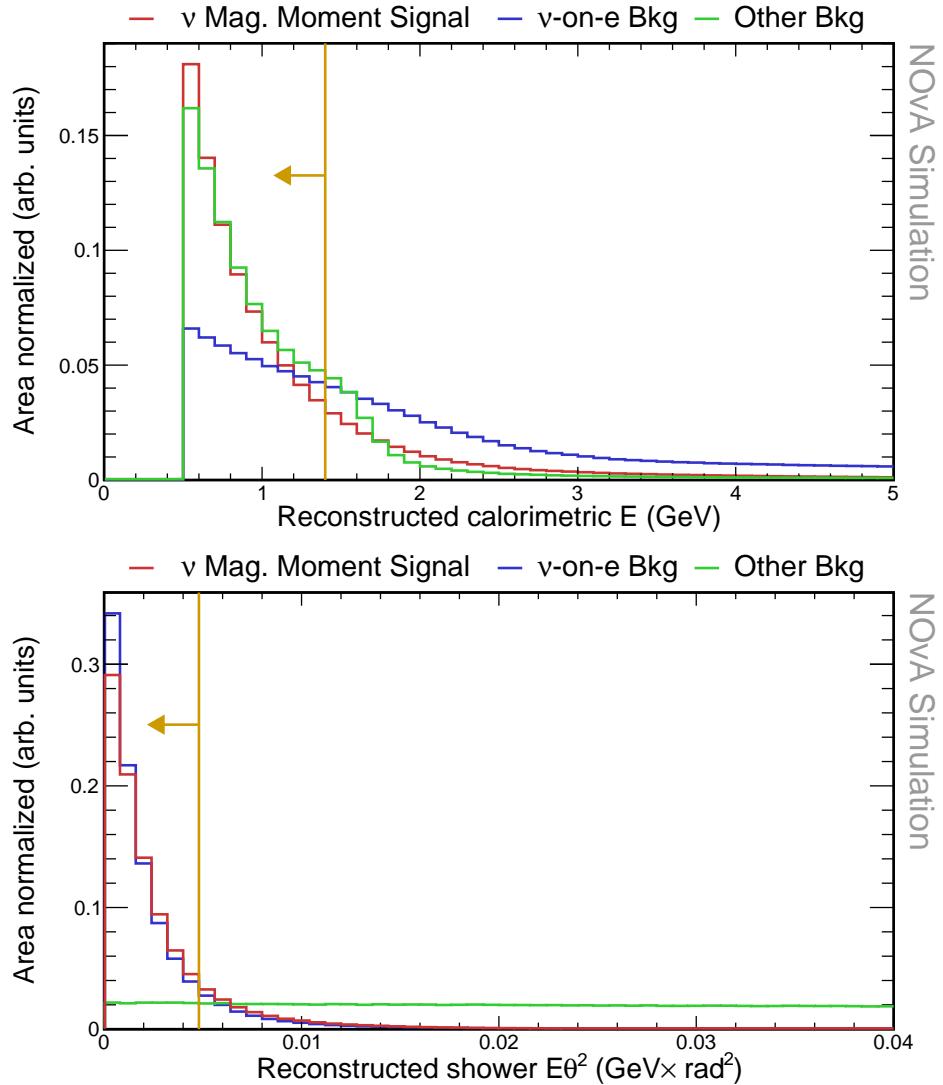


Figure 2.22: Relative comparison of signal (red),  $\nu$ -on-e background (blue), and other background (green) events in the distribution of the reconstructed energy of the primary shower (top) and of the reconstructed energy multiplied by the angle from the incoming neutrino beam direction squared.(bottom). All histograms are area-normalized. The reconstruction quality, pre-selection, fiducial and containment cuts were applied prior to making these plots. Yellow lines show the cut values on the depicted variables, with arrows pointing towards the preserved events.

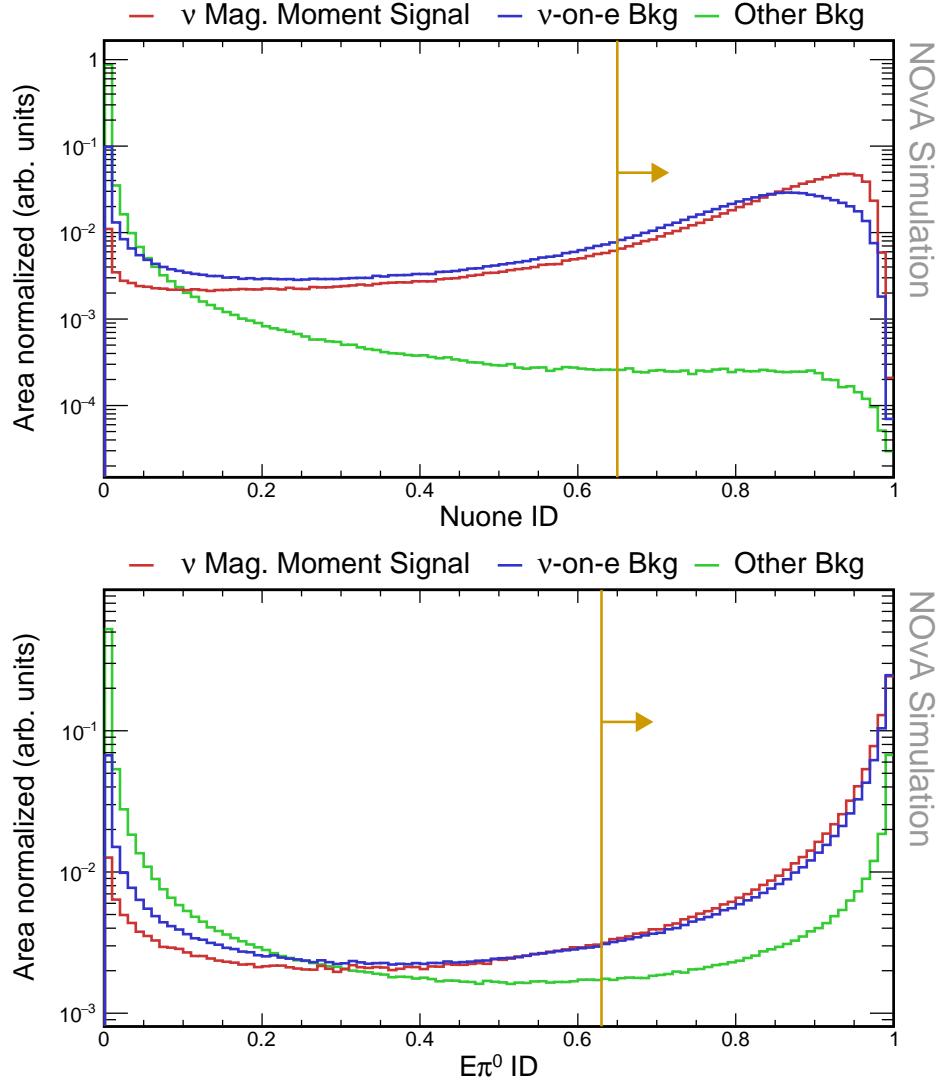


Figure 2.23: Relative comparison of signal (red),  $\nu$ -on-e background (blue), and other background (green) events in the distribution of the NuoneID (top) and EPi0ID (bottom) event identifiers. All histograms are area-normalized and logarithmic in the y axis. The reconstruction quality, pre-selection, fiducial and containment cuts were applied prior to making these plots. Yellow lines show the cut values on the depicted variables, with arrows pointing towards the preserved events.

and

$$\text{FOM} = \frac{\text{Signal}}{\sqrt{\text{Signal+Background}}} = 2.06. \quad (2.55)$$

Table 2.7: Interaction types contributing to the SM background after full event selection. Interactions with/without  $\pi^0$  in the final state are specifically selected due to their significant contribution to the  $\nu$ -on-e background.

<b>Interaction</b>	<b>Number of events</b>
$\nu$ -on-e .....	519.09
NC w/ $\pi^0$ .....	72.96
NC w/o $\pi^0$ .....	21.51
$\nu_\mu$ CC w/ $\pi^0$ .....	28.07
$\nu_\mu$ CC w/o $\pi^0$ .....	25.67
$\nu_e$ CCMEC .....	2.22
Other $\nu_e$ CC .....	9.83
Other .....	20.98
<b>Total</b> .....	700.33

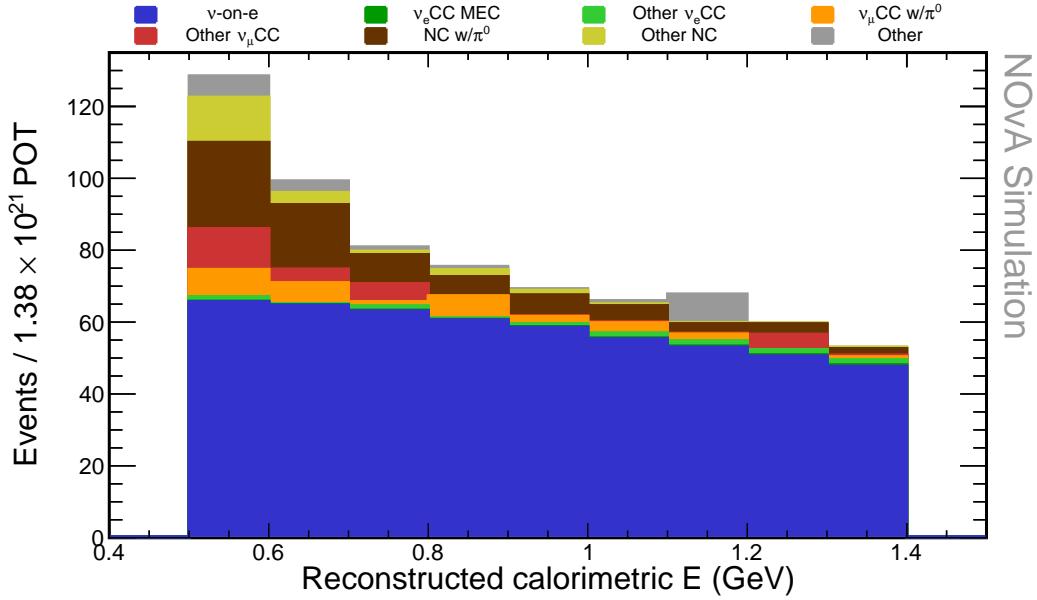


Figure 2.24: Background composition of events passing the full event selection as a function of the reconstructed energy of the leading shower - electron for  $\nu$ -on-e events. Events are scaled to the data exposure. Origin of the "Other" background events between 1.1 – 1.2 GeV is not known.

## 2.4 Systematic Uncertainties

We consider all the standard NOvA systematic uncertainties described in Sec. 1.8, grouped into four categories: neutrino flux, detector calibration, detector modelling,

and neutrino interaction systematic uncertainties. Summary of the effects of both systematic and statistical uncertainties on the predicted number of SM background events is shown in Fig. 2.25. The four categories of systematic uncertainties are assumed to be uncorrelated between each other, allowing to calculate their combined effect by adding their individual contribution in quadrature. The total prediction of the number of SM background events can be expressed as

$$N_{SM} = 700.33 \pm 26.46 \text{ (stat.)}^{+72.48}_{-62.99} \text{ (syst.)}. \quad (2.56)$$

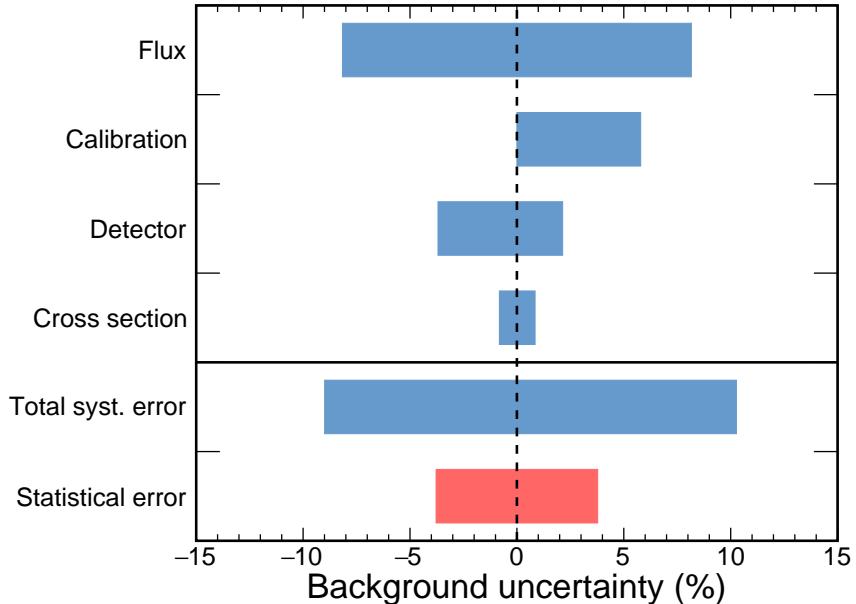


Figure 2.25: Relative effect of systematic and statistical uncertainties on the number of SM background events. The total systematic uncertainty (blue bottom bar) is calculated as a square root of the sum of squares of the four categories of systematic uncertainties, shown ordered by the size of their effect. These are the neutrino flux, detector calibration, detector modelling, and neutrino cross section systematic uncertainties.

To assess the effect of the neutrino flux systematic uncertainty, we use 8 ND-only principal components. Figure 2.26 shows their combined effect on the predicted SM background as a function of the primary shower's reconstructed energy. Since the principal components are uncorrelated by construction, the total systematic uncertainty for each bin is calculated by adding the effect of all the principal components in quadrature. The effect of the neutrino flux systematic uncertainty does not depend on the primary shower's calorimetric energy and altering the neutrino flux predic-

tion can be represented by a normalization shift. The final effect of the neutrino flux systematic uncertainty on the total number of SM background events is  $\pm 8.16\%$  and is symmetric around the nominal prediction.

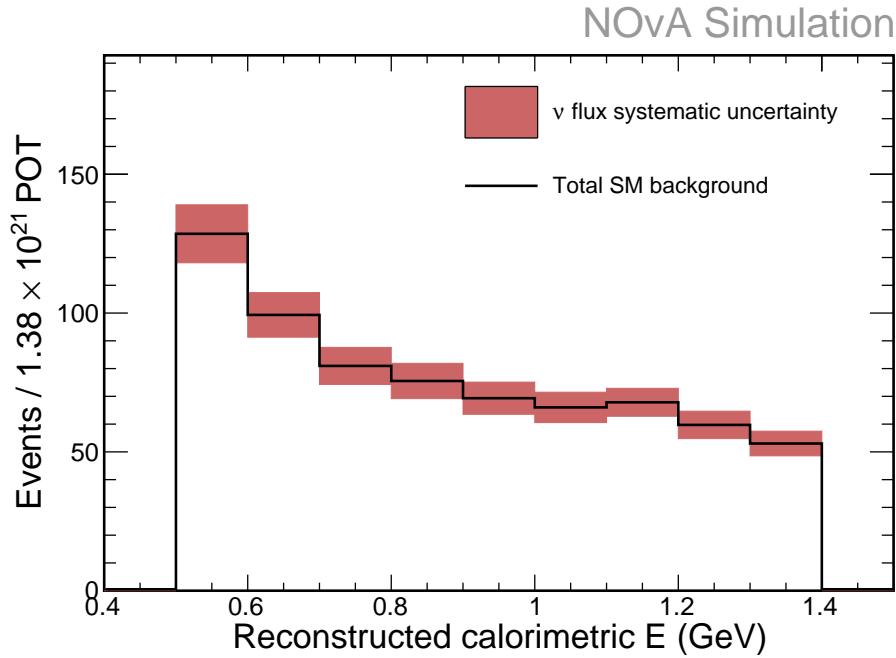


Figure 2.26: Effect of the total neutrino flux systematic uncertainty on the primary shower energy distribution of the SM background events.

The effect of the total detector modelling and calibration systematic uncertainties on the number of SM background events is asymmetrical, increasing the number of events by  $+6.17\%$  and decreasing by  $3.69\%$ . The effect of these uncertainties depends on the energy of the primary shower (which is the recoil electron for  $\nu$ -on-e events), as can be seen in Fig. 2.27. This means that the energy distribution of the SM background events can be significantly altered due to the detector uncertainties. The largest contribution comes from the absolute energy scale uncertainty, which has a one-sided effect of  $+5.72\%$ . This is due to both the positive and the negative shift in the absolute energy scale increasing the total number of SM background events. The light level and Cherenkov systematic uncertainties are asymmetrical and alter the number of SM background events in both directions by  $^{+1.13\%}_{-3.39\%}$  and  $^{+1.82\%}_{-1.46\%}$  respectively. The detector ageing and calibration shape systematic uncertainties are one sided by default and increase the number of the SM background events by  $+0.55\%$  and  $+0.69\%$  respectively.

Since we assume that the  $\nu$ -on-e interaction is known precisely, the dominant

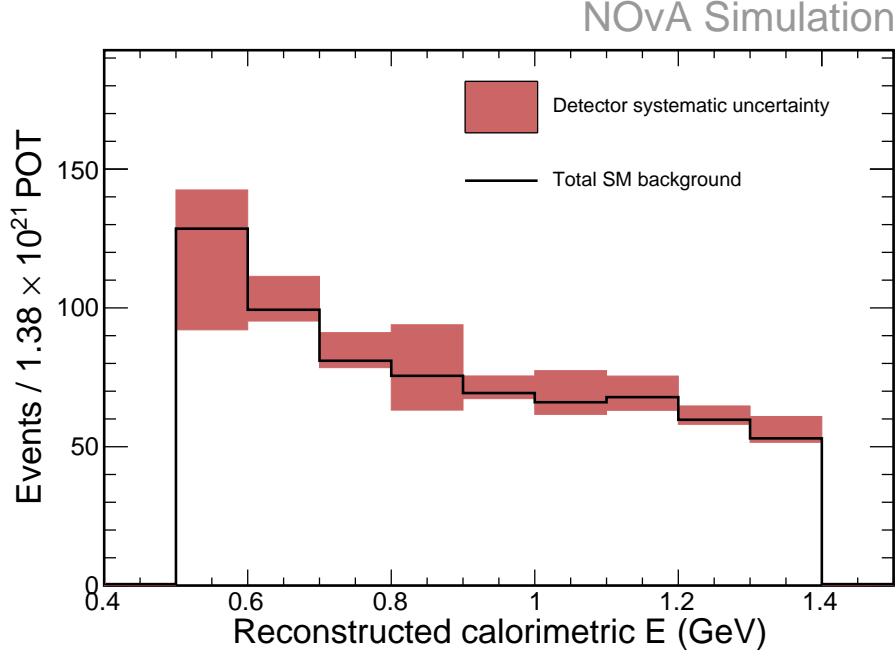


Figure 2.27: Effect of the total detector systematic uncertainty on the primary shower energy distribution of the SM background. The detector uncertainty consists of the absolute calibration, calibration shape, detector ageing, light level, and Cherenkov systematic uncertainties.

$\nu$ -on-e component of the SM background has no systematic uncertainty from neutrino interactions. Therefore, the neutrino interaction systematic uncertainty affects only the 181 "Other background" events, which make up 34.9 % of the total SM background. Consequently, the total neutrino interaction uncertainty on the SM background is relatively small, with a combined effect on the number of SM background events of  $^{+1.54\%}_{-1.49\%}$ . The most dominant neutrino interaction systematic uncertainties are related to interactions with  $\pi^0$  in the final state, such as the axial mass ( $^{+0.97\%}_{-0.90\%}$ ) and the vector mass ( $^{+0.41\%}_{-0.35\%}$ ) of the NCRes interactions, the scaling of the COH $\pi$ NC interactions ( $^{+0.85\%}_{-0.85\%}$ ), or the mean free path of pions before they undergo an interaction ( $^{+0.30\%}_{-0.43\%}$ ). Other neutrino interaction systematic uncertainties have only a marginal ( $< 0.3\%$ ) effect on the number of SM background events.

## 2.5 Results

The final distribution of the predicted SM background, the signal for  $\mu_\nu = 10^{-9} \mu_B$  and the measured data in the primary shower reconstructed calorimetric energy is shown in Fig. 2.28. We do not use the energy distribution of events, but we are using

this distribution to cross check the validity of our analysis. It appears that everything is grand. The data appears to be within the systematic and statistical uncertainty for all the displayed bins. The only exception is the bin within (0.9 GeV, 1.0 GeV), which is however still within two standard variations from the accepted values and therefore can be safely ignored.

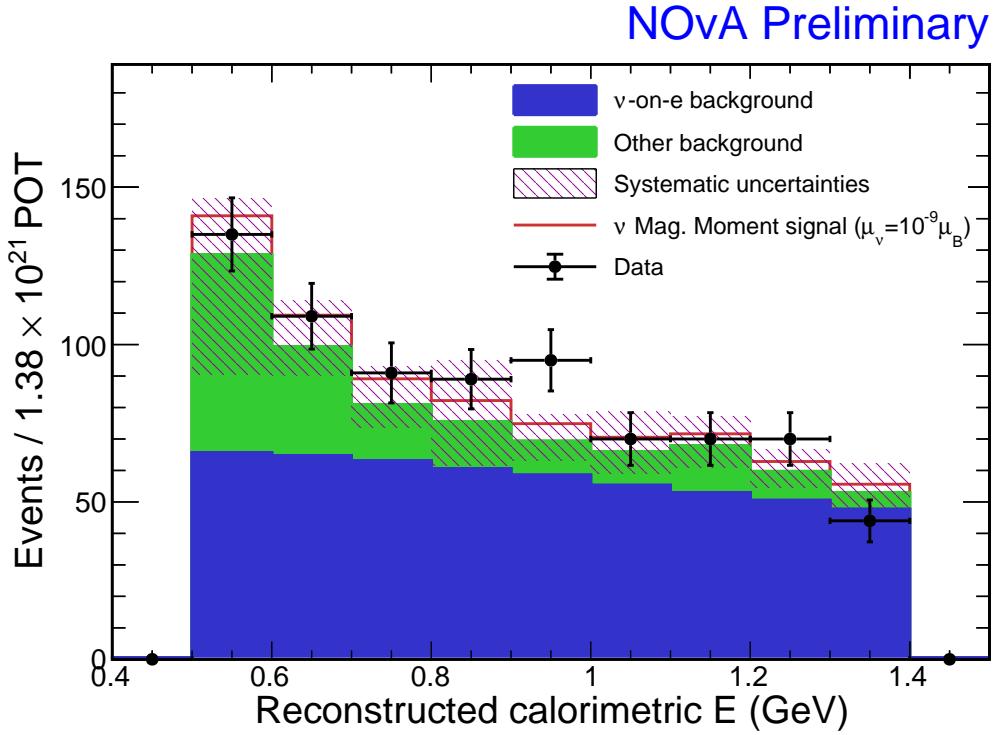


Figure 2.28: comparison of the prediction to the observed data.

The total number of observed events passing our selection is

$$N_{\text{Observed}} = 177. \quad (2.57)$$

The total number of predicted events for the SM background (without neutrino magnetic moment) is

$$N_{\text{Predicted}} = 700.33 \pm 26.46 \text{ (stat.)}^{+72.48}_{-62.99} \text{ (syst.)} \quad (2.58)$$

If the neutrino magnetic moment is  $\mu_\nu = 10^{-9} \mu_B$ , there would be 56.80 additional observed events.

### 2.5.1 Hypothesis Testing

We are testing the validity of the null hypothesis, which is in our case that there is no neutrino magnetic moment and therefore all the observed events are purely due to the SM processes.

Write out the total number of measured events and their corresponding uncertainties

Explain what are the results of the fit and the limits, discuss the statistical significance of the result

We are basically doing two separate things:

1. Testing a hypothesis that there is no magnetic moment present in the signal.

Can we reject the null hypothesis given our data?

2. If we can reject the null hypothesis we want to estimate the best fit of the parameter. Additionally, we want to put a limit (set a confidence interval) on the magnetic moment parameter.

What should be included here:

- Fit methodology: Detail the fitting techniques used to extract the muon neutrino magnetic moment from the data.
- Fit validation: Describe how the fit is validated, including any statistical tests used.

Error on the best fit point - how to calculate? [NOvAResultsNuOnly2018.pdf] TABLE VI. Sources of uncertainty and their estimated average impact on the oscillation parameters in the joint fit. This impact is quantified using the increase in the one-dimensional 68% C.L. interval, relative to the size of the interval when only statistical uncertainty is included in the fit.

Nitish's thesis: pg 156: As mentioned before, the nuisance parameters in the likelihood fit are derived by interpolating between shifts at given numerical sigma values for the above uncertainties for each analysis bin. One can then evaluate the size of the uncertainties in many ways. For the appearance channel, one can compare different systematics based on the effect it has on the total number of predicted signal and background events when varied by  $\pm 1\sigma$ , as shown in Fig. 4.12. One can also estimate

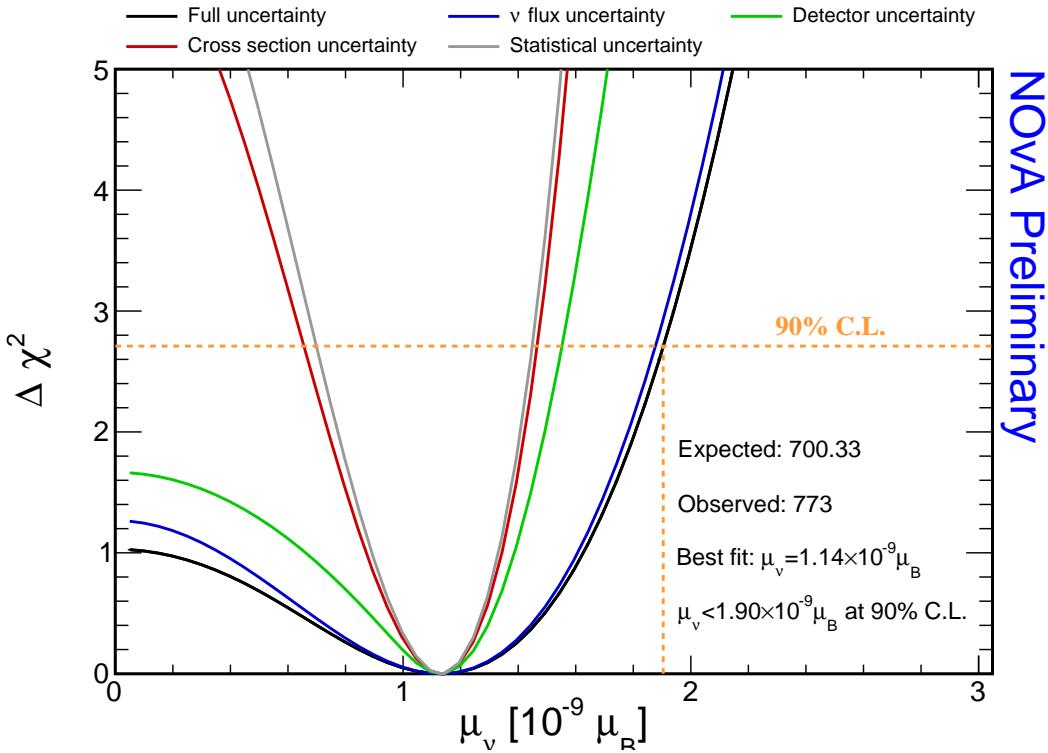


Figure 2.29: Results of the fit of the prediction to the observed data, with the neutrino magnetic moment as the sole fit parameter. We are profiling over the full range of systematic uncertainties.

its effect by fitting to Asimov data using the central value prediction and varying the MC expectation based on the systematic variation. This takes the form of the effect of the systematic on the individual oscillation parameters [79], as shown in Figs. 4.13 and 4.14. All of these metrics show that the analysis is statistically limited, i.e the systematic error is smaller than the statistical error in the prediction. - I think this basically mean, that I should use the best fit point in the fit`bestFitPoint.C script and see what I get? Like the syst pulls?

Maximum likelihood with binned data:

READ NITISH NAYAK'S THESIS PAGE 132! [79]

N bins with a vector of data  $n = (n_1, \dots, n_N)$  with expectation values  $\mu = E[n]$  and probabilities  $f(n; \mu)$ . Suppose the mean values  $\mu$  can be determined as a function of a set of parameters  $\theta$  (I assume for us there's either only one parameter - magnetic moment, or three parameters - mag. moment, scale of SM signal and scale of SM background). Then one may maximize the likelihood function based on the contents of the bins.

If the  $n_i$  is regarded as independent and Poisson distributed (which I'd say is the

case for us), then the data are instead described by a product of Poisson probabilities,

$$f_p(n; \theta) = \prod_{i=1}^N \frac{\mu_i^{n_i}}{n_i!} e^{-\mu_i}, \quad (2.59)$$

where the mean values  $\mu_i$  are given functions of  $\theta$ . The total number of events  $n_{tot}$  thus follows a Poisson distribution with mean  $\mu_{tot} = \sum_i \mu_i$ .

When using maximum likelihood with binned data, one can find the maximum likelihood estimators and at the same time obtain a statistic usable for a test of goodness-of-fit. Maximizing the likelihood  $L(\theta) = f_P(n; \theta)$  is equivalent to maximizing the likelihood ratio  $\lambda(\theta) = f_P(n; \theta) / f(n; \hat{\mu})$ , where in the denominator  $f(n; \hat{\mu})$  is a model with an adjustable parameter for each bin,  $\mu = (\mu_1, \dots, \mu_N)$ , and the corresponding estimators are  $\hat{\mu} = (n_1, \dots, n_N)$  (called the ‘saturated model’).

Equivalently one often minimizes the quantity  $-2 \ln \lambda(\theta)$ . For independent Poisson distributed  $n_i$  this is

$$-2 \ln \lambda(\theta) = 2 \sum_{i=1}^N \left[ \mu_i(\theta) - n_i + n_i \ln \frac{n_i}{\mu_i(\theta)} \right], \quad (2.60)$$

where for bins with  $n_i = 0$ , the last term is zero. In our term  $\mu_i(\theta)$  is the **expected number of events in bin i if magnetic moment is  $\theta$**  and  $n_i$  is the observed (measured) number of events in that bin.

A smaller value of  $-2 \ln \lambda(\hat{\theta})$  corresponds to better agreement between the data and the hypothesized form of  $\mu(\theta)$ . The value of  $-2 \ln \lambda(\hat{\theta})$  can thus be translated into a **p-value as a measure of goodness-of-fit**. Assuming the model is correct, then according to **Wilks’s theorem**, for **sufficiently large  $\mu_i$**  and provided certain regularity conditions are met, **the minimum of  $-2 \ln \lambda$  follows a  $\chi^2$  distribution**. If there are  $N$  bins and  $M$  fitter parameters, then the number of degrees of freedom for the  $\chi^2$  distribution is  $N - M$  if the data are treated as Poisson distributed - which they are for us.

The method of least squares coincides with the method of maximum likelihood in a special case where the independent variables are Gaussian distributed - so I suppose this means that if I have enough events in each single bin, then I could equate the method of log likelihood and the method of least squares...

### 2.5.2 Nuisance Parameters

In general the model is not perfect, which is to say it cannot provide an accurate description of the data even at the most optimal point of its parameter space. As a result, the estimated parameters can have a systematic bias. One can improve the model by including in it additional parameters. That is,  $P(x|\theta)$  is replaced by a more general model  $P(x|\theta, \nu)$ , which depends on parameters of interest  $\theta$  and *nuisance parameters*  $\nu$ . The additional parameters are not of intrinsic interest but must be included for the model to be sufficiently accurate for some point in the enlarged parameter space.

Although including additional parameters may eliminate or at least reduce the effect of systematic uncertainties, their presence will result in increased statistical uncertainties for the parameters of interest. This occurs because the estimators for the nuisance parameters and those of interest will in general be correlated, which results in an enlargement of the contour.

To reduce the impact of the nuisance parameters one often tries to constrain their values by means of control or calibration measurements, say, having data  $y$  (I assume for us this would represent a control sample - like they use in the ND group). For example, some components of  $y$  could represent estimates of the nuisance parameters, often from separate experiments. Suppose the measurements  $y$  are statistically independent from  $x$  and are described by a model  $P(y|\nu)$ . The joint model for both  $x$  and  $y$  is in this case therefore the product of the probabilities for  $x$  and  $y$ , and thus the likelihood function for the full set of parameters is

$$L(\theta, \nu) = P(x|\theta, \nu) P(y|\nu). \quad (2.61)$$

Note that in this case if one wants to simulate the experiment by means of Monte Carlo, both the primary and control measurements,  $x$  and  $y$ , must be generated for each repetition under assumption of fixed values for the parameters  $\theta$  and  $\nu$ .

Using all of the parameters  $(\theta, \nu)$  to find the statistical errors in the parameters of interest  $\theta$  is equivalent to using the *profile likelihood*, which depends only on  $\theta$ . It is defined as

$$L_p(\theta) = L(\theta, \hat{\nu}(\theta)), \quad (2.62)$$

This equation is supposed to have double hat for the neutrino on RHS but that throws

an error when compiling... where the double-hat notation indicates the profiled values of the parameters  $\nu$ , defined as values that maximize  $L$  for the specified  $\theta$ .

### 2.5.3 Unbinned Parameter Estimation

If the total number of data values is small, the unbinned maximum likelihood method is preferred, since binning can only result in a loss of information, and hence the larger statistical errors for the parameter estimates. Doesn't this mean that if the number of events for the neutrino magnetic moment analysis is small, it would be better to do a completely unbinned maximum likelihood method, instead of a single bin method?

## 2.6 Discussion

What should be included here:

- Interpretation: Interpret the results in the context of the current understanding of neutrino physics.
- Implications: Explain the broader implications of your findings for the field of particle physics.
- Future work: Suggest directions for future research based on your results.
  - Improvements in NOvA, more FHC data, including RHC data, better reconstruction, better simulation and calibration, better event selection, including sideband samples, more systematics studies, better fitting techniques...
  - Future beyond NOvA - DUNE
    - \* What are the possibilities for DUNE?

If we do an energy dependent fit, we would have to consider the energy dependency of the systematic uncertainties, which might substantially impact the results of this analysis. Same applies if we decide to extend the event selection to lower electron energies below 0.5GeV.

Due to the energy dependent contribution of the NC interactions with a  $\pi^0$  in the final state, it may be important to consider these uncertainties for an energy dependent analysis.

## 2.7 Summary

Summarize the results and compare them to the introduction, including comparisons to other experiments and theory. Restate the significant of the measurement

Closing remarks



# Acronyms

**$\nu$ -on-e** neutrino-on-electron (interaction). [26](#), [27](#), [29](#), [33–42](#), [44–52](#), [54–69](#), [71](#), [72](#)

**2p2h** two particle - two hole. [10](#)

**ADC** Analog-to-Digital Converter. [7](#), [14](#), [17](#), [18](#)

**APD** Avalanche Photodiode. [4](#), [6](#), [7](#), [10](#), [17](#), [18](#), [46](#)

**ASIC** Application-Specific Integrated Circuit. [7](#)

**BDT** Boosted Decision Tree. [14](#)

**BPF** Break Point Fitter. [12](#)

**BSM** Beyond Standard Model. [26–28](#), [30](#), [31](#)

**C.L.** Confidence Level. [26](#), [27](#)

**CC** Charged Current. [10](#), [11](#), [24](#), [35](#), [41](#), [42](#), [49](#), [51](#), [64](#), [69](#)

**CMC** Comprehensive Model Configuration. [10](#)

**CNN** Convolutional Neural Network. [13](#), [64](#)

**COH $\pi$**  Coherent  $\pi$  (production). [10](#), [24](#), [72](#)

**CP** Charge conjugation - Parity (symmetry). [1](#)

**CRY** Cosmic-Ray Shower Generator. [10](#), [14](#)

**CVN** Convolutional Visual Network. [13](#), [44](#), [47](#)

**DAQ** Data Acquisition. [7](#), [11](#), [16](#)

**DCM** Data Concentration Module. [7](#), [43](#)

**DIS** Deep Inelastic Scattering. [10](#), [23](#), [24](#)

**DUNE** Deep Underground Neutrino Experiment. [1](#), [9](#)

**FB** Fibre Brightness. [17](#), [18](#)

**FD** Far Detector. 3–7, 10, 11, 17–19, 23

**FEB** Front End Board. 6–8, 17, 46

**Fermilab** Fermi National Accelerator Laboratory. 1, 4, 9

**FHC** Forward Horn Current (neutrino mode). 2, 3

**FOM** Figure Of Merit. 43, 51, 53–62, 64, 69

**FPGA** Field Programmable Gate Array. 7

**FSI** Final State Interaction. 10, 24

**LDM** Light Dark Matter. 27

**LOWESS** Locally Weighted Scatter plot Smoothing. 19, 20

**MC** Monte Carlo. 8–10, 14, 39, 63

**MEC** Meson Exchange Current. 10, 24, 41, 42, 69

**MEU** Muon Energy Unit. 21

**MI** Main Injector. 1, 2, 8

**MIP** Minimum Ionising Particle. 14, 18, 21

**MIPP** Main Injector Particle Production (experiment). 9

**ML** Machine Learning. 13, 14, 44

**MVA** Multi Variate Analysis. 42, 51, 63, 83

**NC** Neutral Current. 11, 14, 69, 72, 79

**ND** Near Detector. 1–5, 7, 11, 12, 22–24, 26, 27, 29, 32, 39, 42, 47, 51, 70

**NDOS** Near Detector on the Surface. 4

**NOvA** NuMI Off-axis  $\nu_e$  Appearance (experiment). ix, 1–14, 16–24, 26, 27, 29, 32, 34, 36–39, 41, 42, 44, 47, 49, 63, 64, 69

**NP** New Physics. 31

**NuMI** Neutrinos from the Main Injector. 1–4, 8, 9, 11, 53

**PCA** Principal Component Analysis. 23

**PE** Photo Electron. 6, 7, 15, 17–19

**PECorr** Corrected Photo Electrons. 19, 21

**PID** Particle Identification. 13

**PMNS** Pontecorvo-Maki-Nakagawa-Sakata. 30, 31

**POT** Protons On Target. 2, 39, 41, 43, 48

**PPFX** Package to Predict the Flux. 9, 23, 39

**PVC** Polyvinyl chloride. 4–6, 22

**QE** Quasi Elastic (interaction). 10, 23, 24

**ReMId** Reconstructed Muon Identifier. 14

**Res** Resonant baryon production. 10, 23, 24, 72

**RHC** Reverse Horn Current (antineutrino mode). 2, 3

**SM** Standard Model. 26, 28–31, 35–40, 43, 65, 69–74

**TMVA** Tool for MVA. 63–65

**WLS** Wavelength Shifting (fibre). 4–6, 10, 14, 16, 18, 21

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