

# Unified Diagnostic Services (UDS) – ISO 14229



your connection to excellence

## UDS and OBD Positioning in the ISO/OSI Layer Model

International Standard Organization's Open System Interconnect 7 Layer Communication Model

Layer	Description	Standards for UDS	Standards for OBD
„8“	Diagnostic Application	User	ISO 15031-5
7	Application Layer	ISO 14229-1 ISO 15765-3	ISO 15031-5
6	Presentation Layer	Not applicable	Not applicable
5	Session Layer	ISO 15765-3	Not applicable
4	Transport Layer	ISO 15765-2	Not applicable
3	Network Layer	ISO 15765-2	ISO 15765-4
2	Data Link Layer	ISO 11898-1	ISO 15765-4
1	Physical Layer	ISO 11898-2 ISO 11898-3	ISO 15765-4

\*) The bus physics used is to be selected by the user. Therefore, several standards for different physical layer for e.g. High-Speed- (ISO 11898-2) or Fault-Tolerant-CAN (ISO 11898-3) can be used

## Diagnostic Messages - Structures and Types

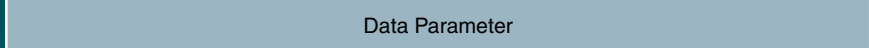
Request without Sub-Function or Positive Response



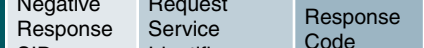
Requests with Sub-Function Byte



UUDT-Responses



Negative Responses



## The Sub-Function Byte of UDS

Services without Sub-Function-Byte: \$84, \$23, \$24, \$2A, \$2E, \$3D, \$14, \$2F, \$34, \$35, \$36, \$37

Suppress Positive Response Message Indication Bit

Bit 7 Sub-Function (Bit 6 to 0)

Bit 7 Bit 6 Sub-Function (Bit 5 to 0)

Storage State

Bit 7: suppressPosRespMsgIndicationBit  
This Bit defines whether a positive response of the ECU is wanted.  
0 = FALSE: the ECU shall send a response, that is, no suppression of a positive response shall be done  
1 = TRUE: Suppression of the positive response, that is, the ECU must not send a positive response  
Negative responses shall be sent by the ECU independent of this bit

Bit 6 to 0: sub-function parameter value  
The Bits 0 to 6 contain the value for a Sub-Function parameter for diagnostic services

Remarks:  
A service, which uses the suppressPosRespMsgIndicationBit only, shall set the value of the Sub-Function parameter to 0 to support the sending of the bit 7  
The Bits 0 to 6 are meaningless then

## Periodic Message Types of UDS

Responses in a CAN data field according to ISO 15765-3

Unacknowledged Segmented Data Transfer (USDT)



Unacknowledged Unsegmented Data Transfer (UUDT)



Responses can be of two different formats/types:

Type 1: with Response Service Identifier  
Type 2: without Response Service Identifier

The type is respected by the Service \$2A Read Data by Periodic Identifier

## Error Memory Functions

1) Erase Error Memory (\$14 Clear Diagnostic Information)

Parameter 1: Service ID = \$14  
Parameter 2: Diagnostic Trouble Code (DTC) with three byte length

2) Sub-Functions for Service \$19 Read DTC Information

Hex	Description
01	Report number of DTC by Status Mask
02	Report DTC by Status Mask
03	Report DTC Snapshot Identification
04	Report DTC Snapshot Record by DTC number
05	Report DTC Snapshot Record by Record number
06	Report DTC Extended Data Record by DTC number
07	Report number of DTC by Severity Mask Record
08	Report DTC by Severity Mask Record
09	Report Severity Information of DTC
0A	Report Supported DTC
0B	Report First Test Failed DTC
0C	Report First Confirmed DTC
0D	Report Most Recent Test Failed DTC
0E	Report Most Recent Confirmed DTC
0F	Report Mirror Memory DTC by Status Mask
10	Report Mirror Memory DTC Extended Data Record by DTC number
11	Report number of Mirror Memory DTC by Status Mask
12	Report number of Emissions Related OBD DTC by Status Mask
13	Report Emissions Related OBD DTC by Status Mask
14	Report DTC Fault Detection Counter
15	Report DTC with Permanent Status

## Service Overview

Functional Unit	SID	Available in Default Session	Available for RoE	Has Sub-Function	Service Name	Mnemonic
Diagnostic and Communication Management	\$10	✓		✓	Diagnostic Session Control	DSC
	\$11	✓		✓	ECU Reset	ER
	\$27			✓	Security Access	SA
	\$28			✓	Communication Control	CC
	\$3E	✓		✓	Tester Present	TP
	\$83			✓	Access Timing Parameter	ATP
	\$84			✓	Secured Data Transmission	SDT
	\$85			✓	Control DTC Setting	CDTCS
Data Transmission	\$86	✓		✓	Response On Event	ROE
	\$87			✓	Link Control	LC
	\$22	✓	✓		Read Data By Identifier	RDBI
	\$23	✓			Read Memory By Address	RMBI
	\$24	✓			Read Scaling Data By Identifier	RSDBI
	\$2A				Read Data By Periodic Identifier	RDBPI
	\$2C	✓		✓	Dynamically Define Data Identifier	DDI
	\$2E	✓			Write Data By Identifier	WDBI
Stored Data Transmission	\$3D	✓			Write Memory By Address	WMBI
	\$14	✓			Clear Diagnostic Information	CDTCI
	\$19	✓	✓	✓	Read DTC Information	RDTCI
	\$2F		✓		Input Output Control By Identifier	IOCBPI
Input Output Control	\$31	✓		✓	Routine Control	RC
Remote Activation of Routine						
Upload & Download	\$34				Request Download	RD
	\$35				Request Upload	RU
	\$36				Transfer Data	TD
	\$37				Request Transfer Exit	RTE

## Functional Units

Diagnostic and Communication Management

Services to manage the connection between testers and ECUs

Data Transmission

Services to transmit data from and to the ECU

Stored Data Transmission

Services to transmit stored data from the ECU to the Tester

Primarily, these data is error memory content and environment data

Input Output Control

Services to control output and read input devices of the ECU

Remote Activation of Routine

Function stored in the ECU can be triggered by these services

Upload & Download

These services serve to transport larger content of memory areas of ECUs to the Tester, but as well to the ECU send by the Tester

## Common Response Codes

Hex	Mnemonic	Description
10	GR	General reject
11	SNS	Service not supported
12	SFNS	Sub-Function not supported
13	IMLOIF	Incorrect message length or invalid format
14	RTL	Response too long
21	BRR	Busy repeat request
22	CNC	Conditions not correct
24	RSE	Request sequence error
25	NRFSC	No response from sub-net component
26	FPEORA	Failure prevents execution of requested action
31	ROOR	Request out of range
33	SAD	Security access denied
35	IK	Invalid key
36	ENOA	Exceeded number of attempts
37	RTDNE	Required time delay not expired
38-4F	RBEDLS	Reserved by Extended Data Link Security Document
70	UDNA	Upload/Download not accepted
71	TDS	Transfer data suspended
72	GPF	General programming failure
73	WBSC	Wrong Block Sequence Counter
78	RCRRP	Request correctly received, but response is pending
7E	SFNSIAS	Sub-Function not supported in active session
7F	SNSIAS	Service not supported in active session

All values not described are reserved for future definition

## Specific conditions driven Response Codes

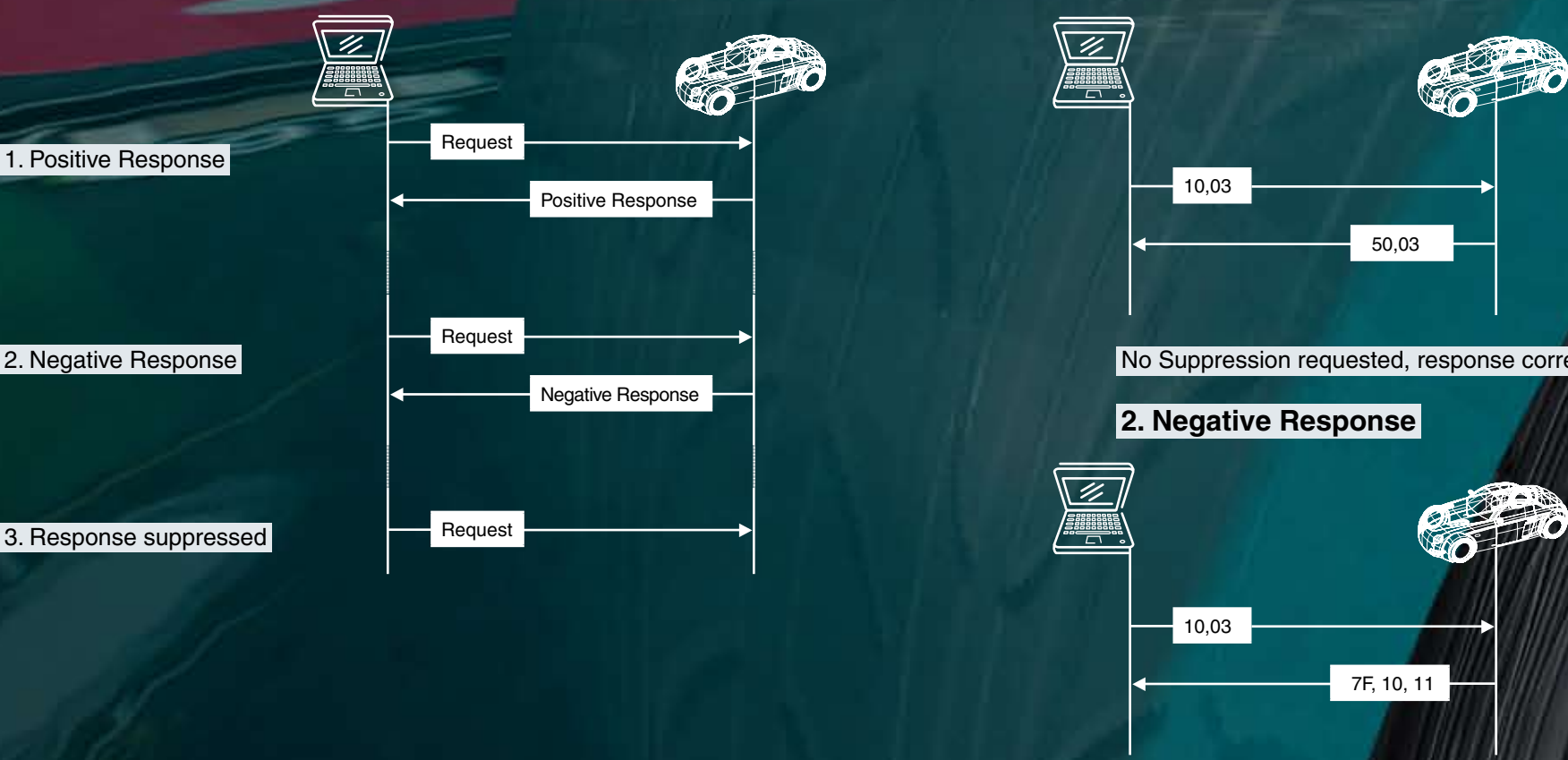
Hex	Mnemonic	Description
81	RPMTH	rpm too high
82	RPMTL	rpm too low
83	EIR	Engine is running
84	EINR	Engine is not running
85	ERTTL	Engine run-time too low
86	TEMPH	Temperature too high
87	TEMPTL	Temperature too low
88	VSTH	Vehicle speed too high
89	VSTL	Vehicle speed too low
8A	TPH	Throttle/Pedal too high
8B	TPTL	Throttle/Pedal too low
8C	TRNIN	Transmission range not in neutral
8D	TRNIG	Transmission range not in gear
8F	BSNC	Brake switch(es) not closed
90	SLNIP	Shifter lever not in park
91	TCCL	Torque converter clutch locked
92	VTH	Voltage too high
93	VTL	Voltage too low

All values not described are reserved for future definition

## Simple/Polling Diagnostic Services

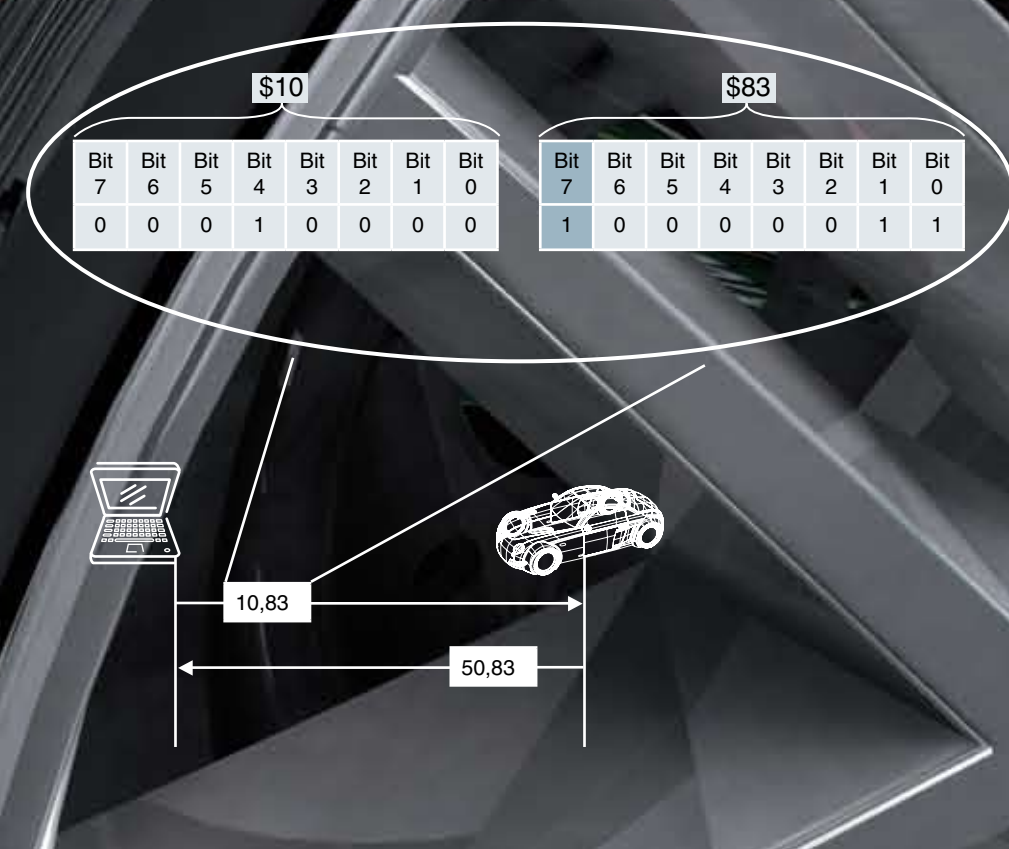
These services consist of one request and one response (max.) for physical addressing, or a group of responses for functional addressing

Three Potential Polling Communication Flows when using the Sub-Function Byte



Erroneous Communication with Sub-Function Byte

Suppression requested (Bit 7 of Byte 2 is set to "1", but response is sent by the ECU)



## Periodic Service Execution (Service \$2A)

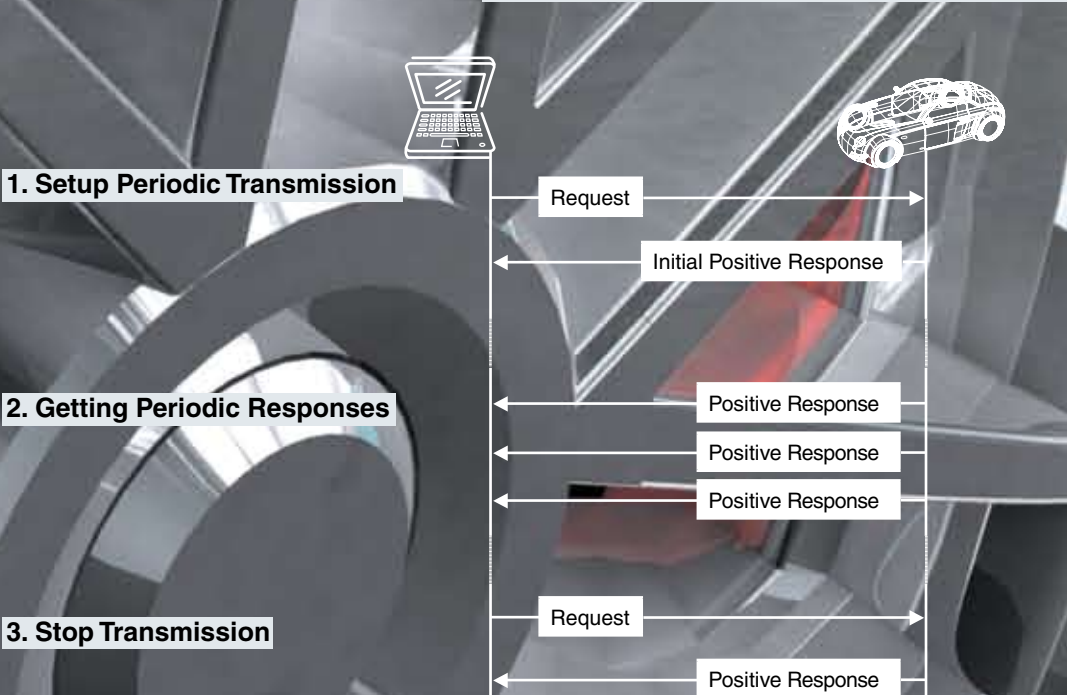
For one Request follows one initial Response. After that, periodically more responses will follow. The sending can be stopped by using a simple diagnostic service

Service parameter "Transmission Mode"

The frequency of the data transmission can be configured using the Transmission Mode. The UDS-Standard defines abstract values as:

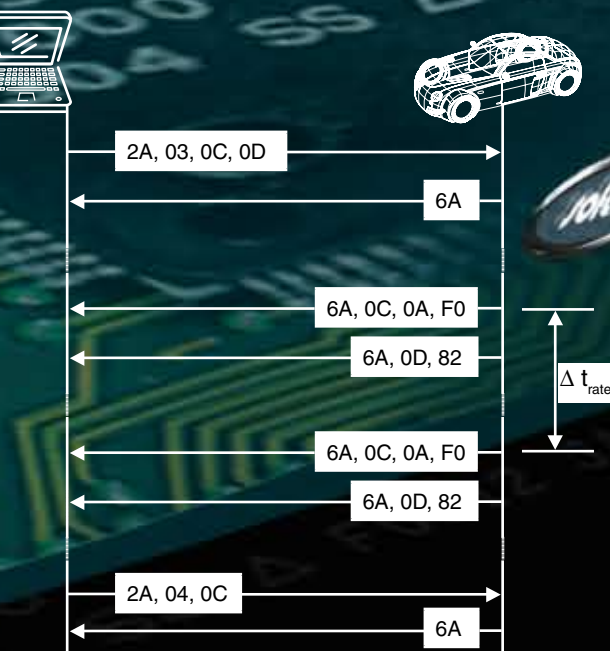
Slow = \$01  
Medium = \$02  
Fast = \$03  
Stop sending = \$04  
The real values in Hertz for each frequency need to be defined between OEM and ECU supplier

Generic Periodic Communication Flow



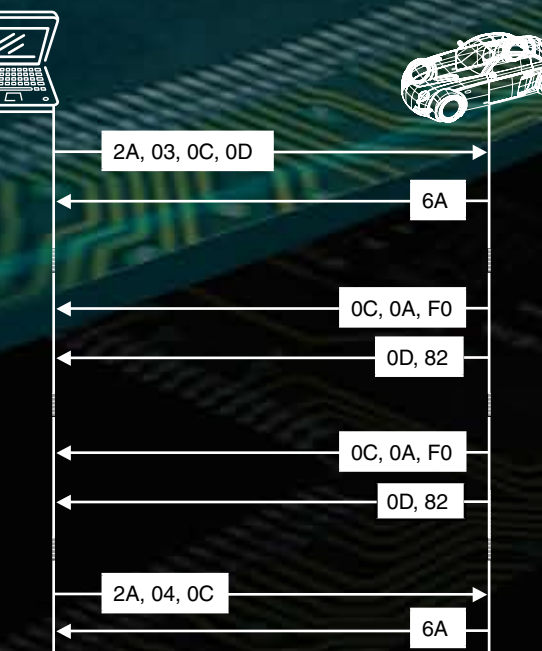
Type 1 Communication Flow

A Response Service-ID is sent by the ECU



Type 2 Communication Flow

NO Response Service-ID is sent by the ECU



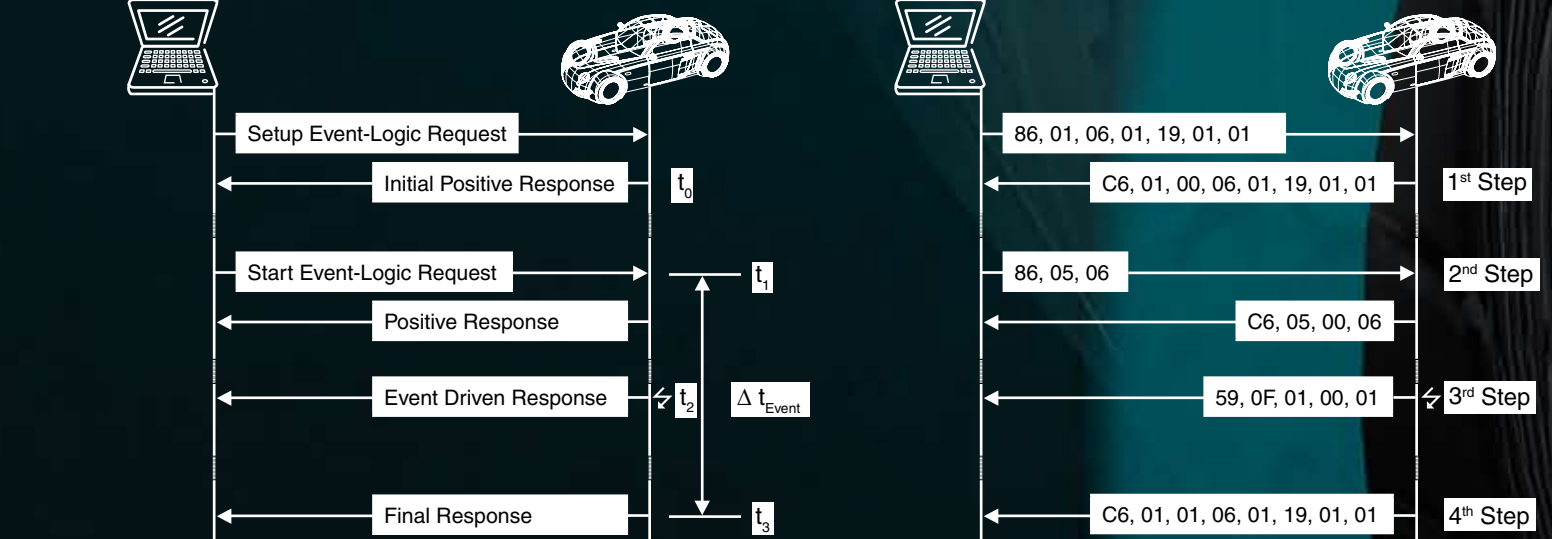
## Response on Event – RoE (Service \$86)

For one or two setup and start Requests one or two initial Responses are given, followed by 0 to n event-driven Responses depending on the number of occurrences of tracked events. The distance between several events is non-deterministic.

• The RoE mechanism can be activated in any Session, including the Default-Session

• It does not need Tester Present messages to stay active

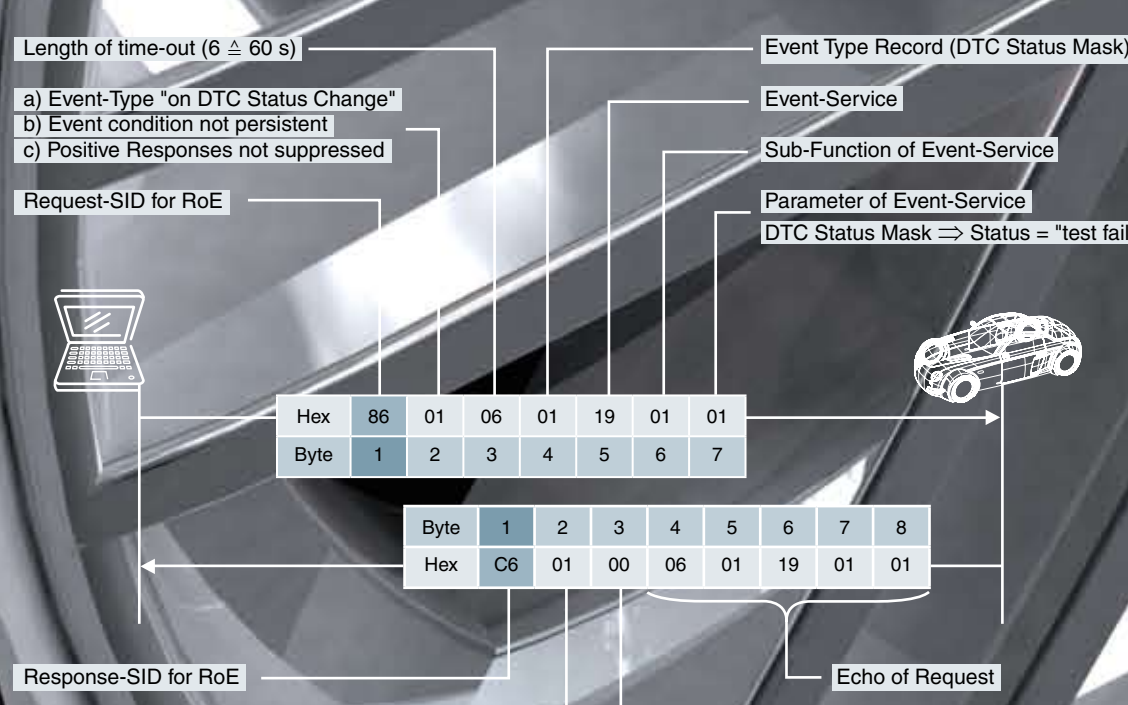
Generic Event-Driven Communication Flow



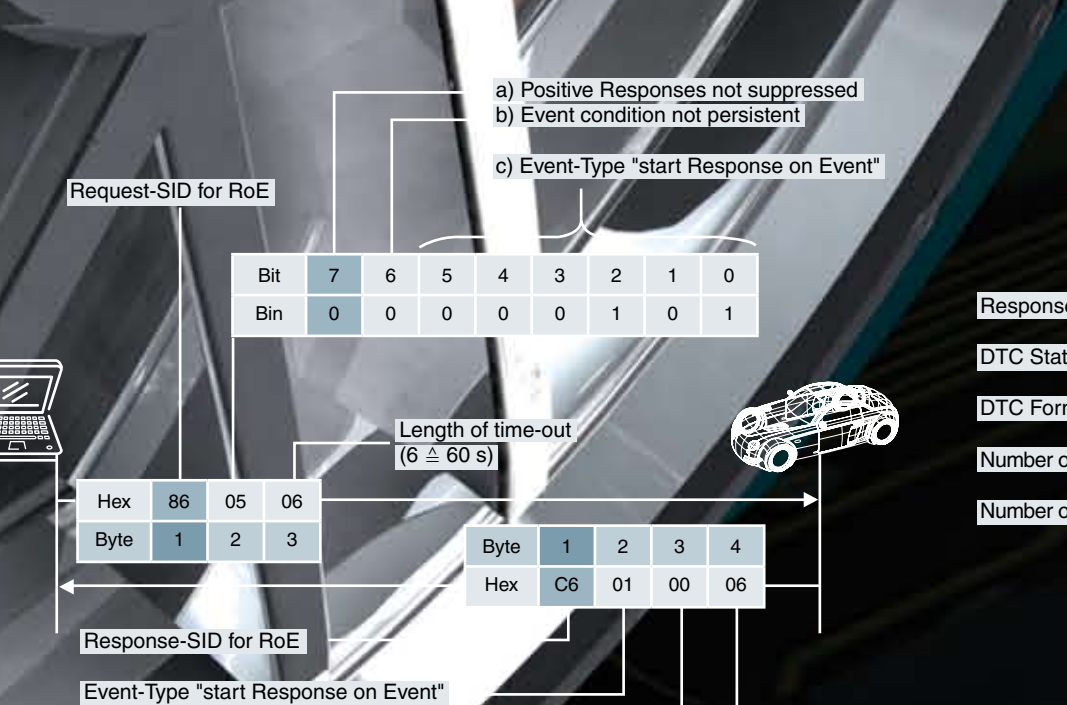
Pre-defined values for parameter Event Type (6 Bits)  
\$0 Stop Event-Logic  
\$1 Event on change of error memory, e.g. number of errors matching to mask has increased  
\$3 Event on change of measurement's value, which is described by a data identifier  
\$5 Start Event-Logic  
\$6 Clear Event-Logic

## RoE Example - DTC Status Change

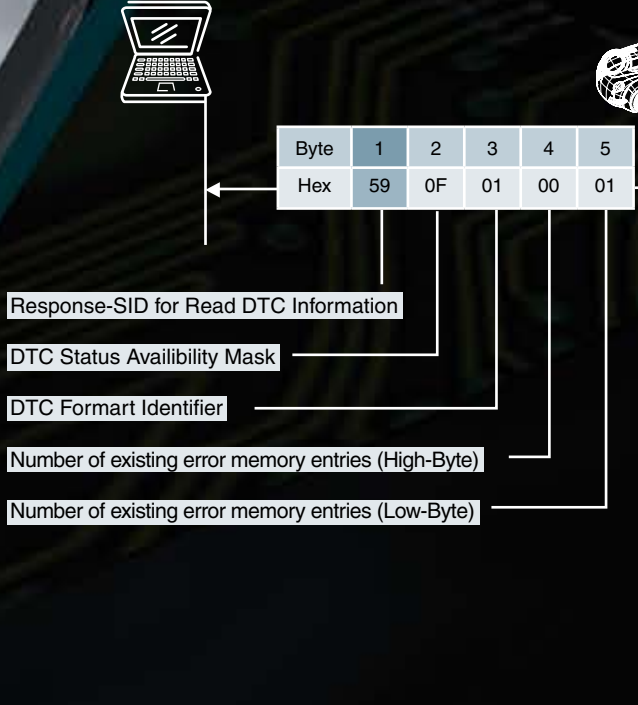
1st Step – Setup of Event-Logic



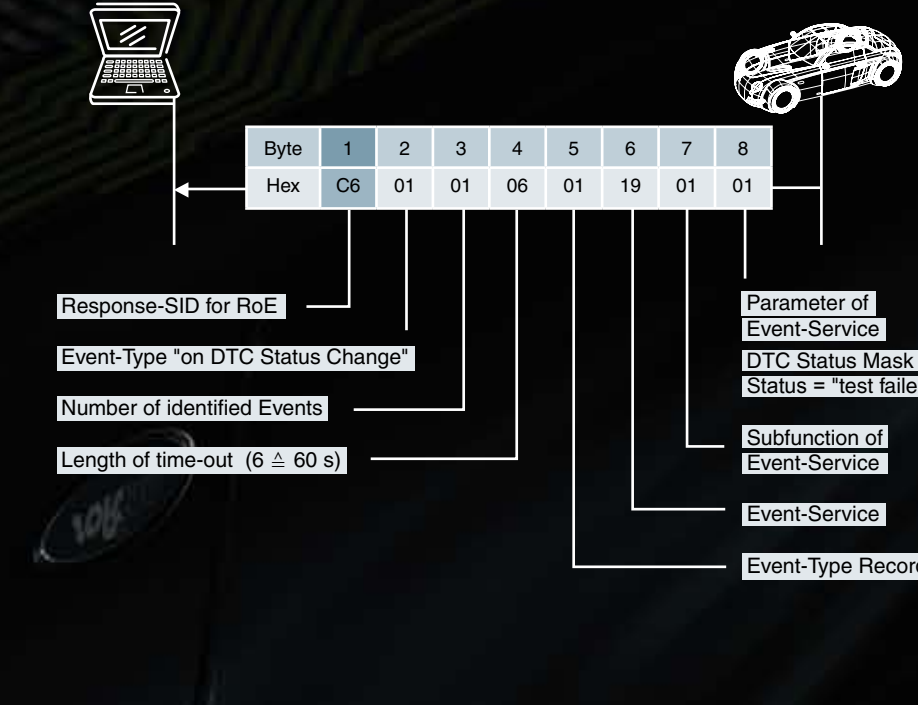
2nd Step – Start of Event-Logic



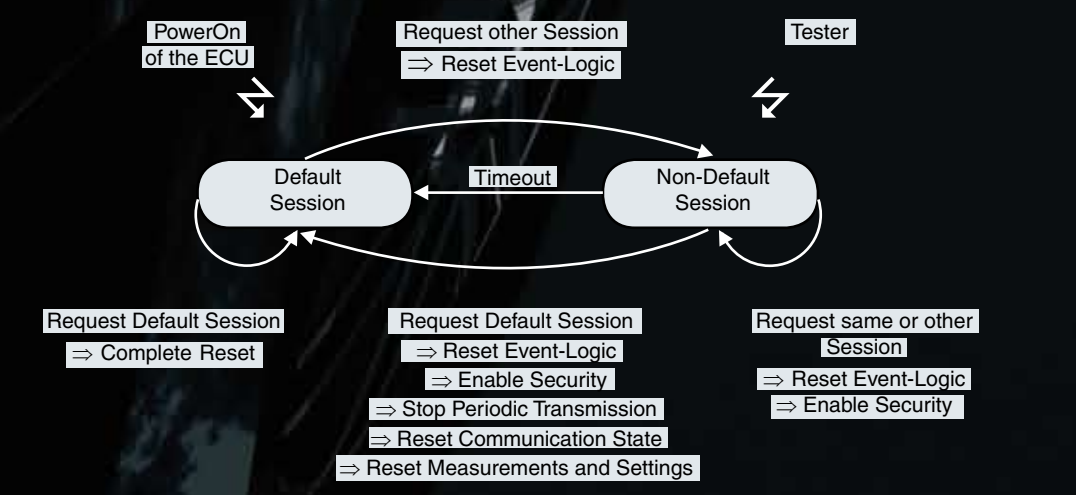
3rd Step – Event occurs



4th Step – Event Windows expires



## Session Handling



Standardized values of Parameter "Diagnostic Session Type"

\$01 Default Session  
\$02 Programming Session  
\$03 Extended Diagnostic Session  
\$04 Safety System Diagnostic Session

www.softing.com

+49 (89) 456 56 420