

TUTORIAL : CONFIGURING A BLE DEVICE (RN4871) AS A WIRELESS ACTUATOR FOR DRAGONBOARD 410C

[1] RN4871 MODULE CONFIGURATION

STEP	COMMAND / ACTIVITY	DESCRIPTION
1	Connect BLE RN4871 device to a USB port of the PC	<code>screen /dev/tty.usbmodem1411 115200</code>
2	<code>\$\$\$ +</code>	Put the RN4871 into command mode
3	<code>PZ</code>	Clear all services
4	<code>R,1</code>	Reboot the RN4871
5	<code>\$\$\$ +</code>	Put the RN4871 into command mode
6	Generate 3 UUIDs of 128 bits through https://www.uuidgenerator.net/	UUID0: 59c88760536411e7b114b2f933d5fe66 UUID1: 59c889e0536411e7b114b2f933d5fe66 UUID2: 59c88d6e536411e7b114b2f933d5fe66
7	<code>PS,59c88760536411e7b114b2f933d5fe66</code>	Create private service with given UUID0
8	<code>PC,59c889e0536411e7b114b2f933d5fe66,12,01</code>	Create GATT characteristic with UUID1 Property: Notification / Read Data Bytes: 1 Characteristic : 0072 (automatically defined)
9	<code>PC,59c88d6e536411e7b114b2f933d5fe66,16,01</code>	Create GATT characteristic with UUID2 Property: Notification / Read / Write without response Data Bytes: 1 Characteristic : 0075 (automatically defined)
10	<code>SW,0A,00</code>	Remove special functionality on PIN P12 of the module (pin index 0A)
11	<code>SW,0B,00</code>	Remove special functionality on PIN P13 of the module (pin index 0B)
12	<code>SN,DRAGONWALLY</code>	Set module name to "DRAGONWALLY"
13	<code>R,1</code>	Reboot the module

STEP	COMMAND / ACTIVITY	DESCRIPTION
14	\$\$\$ +	Put the RN4871 into command mode
15	WC	Clear current script
16	R,1	Reboot the module
17	\$\$\$ +	Put the RN4871 into command mode
18	WW	Enter script input mode
19	<pre>@PW_ON # power on event O,18,00 # turn leds on O,18,18 # turn leds off SHW,0072,57 # write "W" (0x57) in characteristic 0072 SHW,0075,18 # write 0x18 in characteristic 0075 SM,2,0064 # start timer 2 with T=1s @CONN # connection event SM,2,0064 # reset timer 2 with T=1s @DISCON # disconnection event SM,2,0064 # reset timer 2 with T=1s @TMR2 # timer 2 event \$VAR1=SHR,0075 # read characteristic 0075 and O,18,\$VAR1 # write the value to the led outputs SM,2,0064 # reset timer 2 with T=1s</pre>	Copy this script from a text editor and paste into the screen terminal
20	Type ESC	Exit Script input mode
21	R,1	Reboot the module
22	\$\$\$ +	Put the RN4871 into command mode
23	SR,4040	Set module to run script after power on and with no prompt
24	R,1	Reboot the module

[2] BLUEPY INSTALLATION

BLUEPY is a convenient library for accessing the Bluetooth Low Energy features of the **DragonBoard 410c**.

Reference : <https://github.com/IanHarvey/bluepy>

To install the current released version, on most Debian-based systems:

```
$ sudo apt-get install python-pip libglib2.0-dev  
$ sudo pip install bluepy
```

[3] BLUEPY DOCUMENTATION

Reference : <http://ianharvey.github.io/bluepy-doc/>

[4] PYTHON SCRIPT (EXAMPLE)

```
#!/usr/bin/python

#####
#  bluepy_dw_write.py      #
#####
from bluepy.btle import Scanner, DefaultDelegate
from bluepy.btle import Peripheral, UUID
import sys

#####
# List of Known UUIDs      #
#####
uuid = [ '59c88760-5364-11e7-b114-b2f933d5fe66', # UUID0 (service UUID)
         '59c889e0-5364-11e7-b114-b2f933d5fe66', # UUID1 (characteristic 0072)
         '59c88d6e-5364-11e7-b114-b2f933d5fe66'] # UUID2 (characteristic 0075)

#####
# BLE Target                #
#####
ble_module_name = "DRAGONWALLY"
ble_target_uuid = uuid[2] # UUID2
ble_target_value = [int(str(sys.argv[1]),16)] if (len(sys.argv)==2) else [0x00]

#####
# convert Vektor to String  #
#####
def makestring(bytes):
    return "".join(map(chr,bytes))

#####
# Scan Delegate #
#####
class ScanDelegate(DefaultDelegate):
    def __init__(self):
        DefaultDelegate.__init__(self)

    def handleDiscovery(self, dev, isNewDev, isNewData):
        if isNewDev:
            print "Discovered device", dev.addr
        elif isNewData:
            print "Received new data from", dev.addr
```

```

#####
# Scan Devices #
#####
print("[SCAN DEVICES]")
scanner = Scanner().withDelegate(ScanDelegate())
devices = scanner.scan(10.0)
mydevice = None

#####
# Analyze Devices #
#####
print("[ANALYZE DEVICES NAMES]")
for dev in devices:
    print "Device %s (%s), RSSI=%d dB" % (dev.addr, dev.addrType, dev.rssi)
    for (atype, desc, value) in dev.getScanData():
        #####
        # print Complete Local Name #
        #####
        if (desc == "Complete Local Name"):
            print "    %s = %s" % (desc, value)
            #####
            # find target device by its name #
            #####
            if (desc == "Complete Local Name") and (value == ble_module_name) :
                mydevice = dev
                print "[Device %s found as %s]" % (mydevice.addr,value)

#####
# Target Device was Found #
#####
if mydevice is not None:
    #####
    # Open Peripheral and #
    # Search Services #
    #####
    p = Peripheral(mydevice.addr,mydevice.addrType)
    print "Get Services ..."
    services = p.getServices()
    print "Done."
    #####
    # Analyze Services #
    #####
    for serv in services:
        print "Peripheral Addr=%s , UUID=%s" % (serv.peripheral.addr,serv.uuid)
        characteristics = serv.getCharacteristics()
        for ch in characteristics:
            print "    UUID=%s , Properties=%s , Value=%s" % (UUID(ch.uuid).getCommonName(),ch.propertiesToString(),ch.read() if ch.supportsRead() else
"-")
            #####
            # Write Value of the Target Characteristic #
            #####
            if (UUID(ch.uuid).getCommonName() == ble_target_uuid):
                ch.write(makestring(ble_target_value))
                print("[Writing Value to Target UUID]")

```

[4.1] PYTHON SCRIPT DESCRIPTION

This example script ("**bluepy_dw_write.py**") scans all nearby BLE devices, looking for its **addresses** and **complete local names**.

Once the "target name" (**ble_module_name**) is found, the script traverses all its services and characteristics, looking for the "target UUID" (**ble_target_uuid**).

If a match occurs, the "target value" (**ble_target_value**) is written to the characteristic.

Any Python script accessing the **BLUEPY** library must run as "**superuser**":

```
$ chmod +x bluepy_dw_write.py  
$ sudo ./bluepy_dw_write.py <value>
```

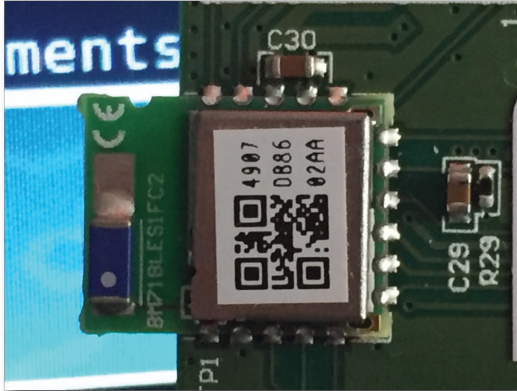
<value>	LED1	LED0
0x00	ON	ON
0x18	OFF	OFF
0x08	ON	OFF
0x10	OFF	ON

Usage example:

```
$ sudo ./bluepy_dw_write.py 0x00    (turn both LEDs ON)
```

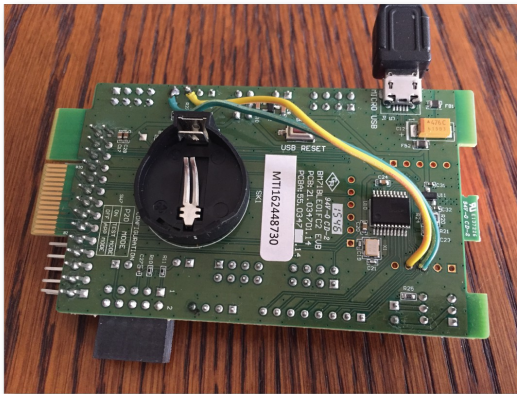
[5] SOME PICTURES

The RN4871 BLE Module



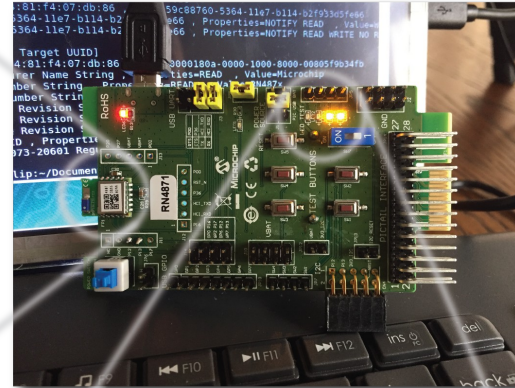
(very tiny : 9 mm x 11.5 mm)

Required Wire Connections

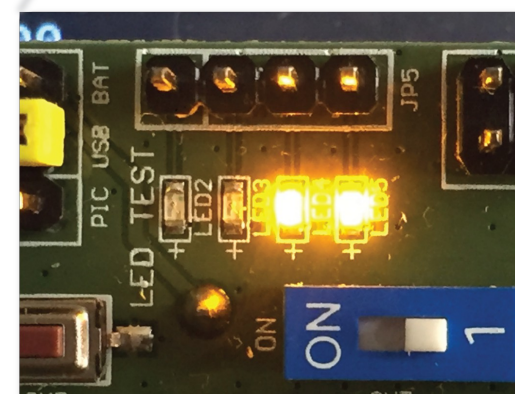


RN4871 P12 (GREEN, LED0)
RN4871 P13 (YELLOW, LED1)

The RN4871 Evaluation Board



LED1 (ON) and LED0 (ON)



DragonWally Test Setup



The **DragonWally** project uses Bluetooth Low Energy (BLE) for the communication between the **DragonBoard 410c** and wireless actuators and sensors. This demonstration shows the **RN4871** module acting as a two output digital actuator (for access grant or deny)

[6] ADITIONAL REFERENCES

[6.1] DragonBoard 410c

<https://developer.qualcomm.com/hardware/dragonboard-410c>

[6.2] RN4871 Bluetooth Low Energy PICtail / PICtail Plus Daughter Board

<http://www.microchip.com/DevelopmentTools/ProductDetails.aspx?PartNO=RN-4871-PICTAIL>

[6.3] RN4871 Bluetooth Low Energy Module

<http://www.microchip.com/wwwproducts/en/RN4871>

Cezar Menezes

cezar.menezes@live.com