

로봇공학입문설계

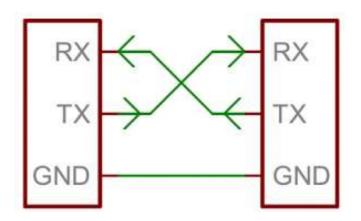
10주차 모바일 로봇(4)

로봇공학과

시리얼 통신

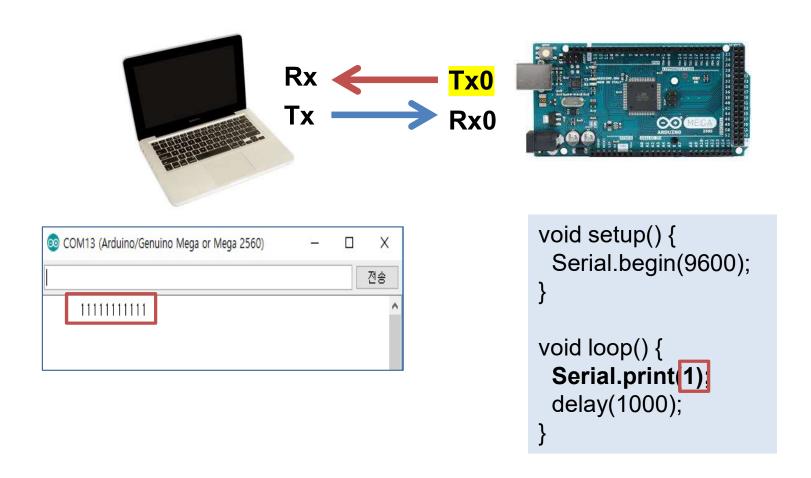
□ 연결방법

- 시리얼 모듈은 각각 Tx(송신), RX(수신), GND의 세가지 라인으로 구성
- RX와 TX라인을 이용하여 두 모듈사이에 통신이 이루어짐
- RX, TX라는 이름은 각 장치 자신의 입장에서 바라봤을 때 라인이 담당하는 역할이므로 두 모듈을 연결할 때에는 RX와 TX를 서로 엇갈리게 연결



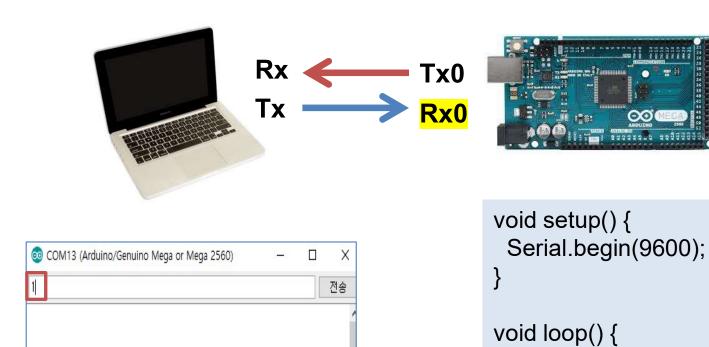
시리얼 통신

□ Arduino ↔ PC



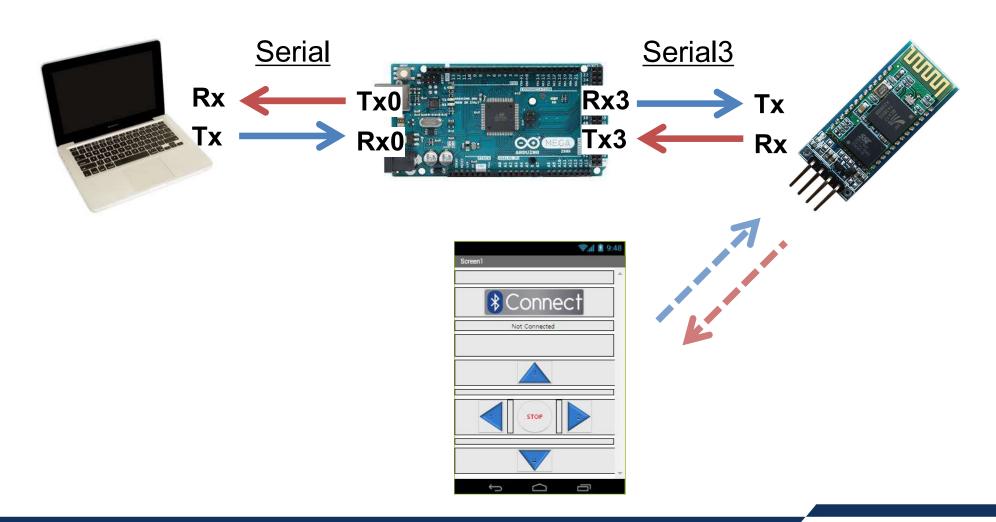
시리얼 통신

□ Arduino ↔ PC



int val = Serial.read();

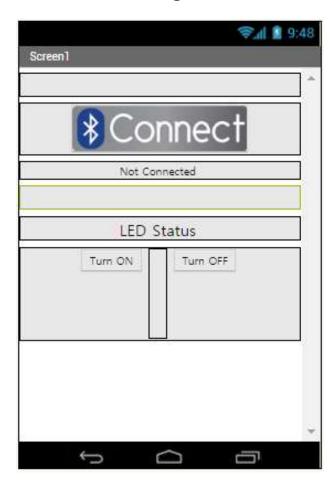
□ 블루투스 통신 구조



MIT App Inventor

□ 프로그램 구성

Designer

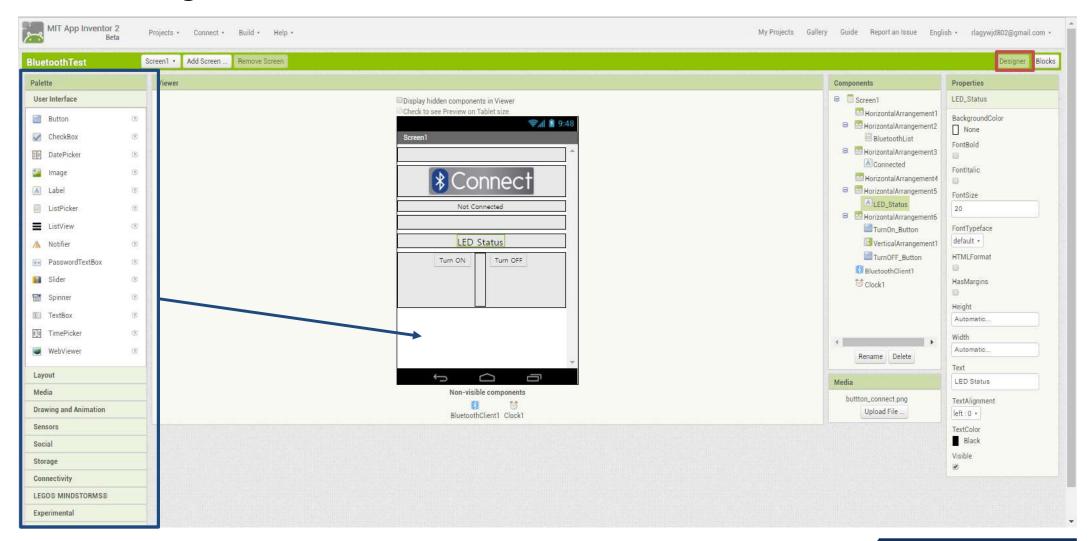


Blocks

```
when BluetoothList BeforePicking
   set BluetoothList . Elements . to BluetoothClient1 . AddressesAndNames .
when BluetoothList AfterPicking
   o if call BluetoothGlient1 .Connect
                               address | Bluetoothuist . Selection
   then set BluetoothList . Elements to BluetoothClient1 . AddressesAndNames
when TurnOn_Button - .Click
set LED_Status . Text to | call BluetoothClient . ReceiveText
                                              numberOfBytes call BluetoothClient1 .BytesAvailableToReceive
when TurnOFF_Button Glick
set LED Status . Text to ( call BluetoothClient) . ReceiveText
                                              numberOfBytes | call Bluetooth@lient1 ... BytesAvailableToReceive
when Clock1 Timer
do 👩 if // BluetoothClient1 💌 IsConnected 🔻
    then set Connected . Text to " Connected "
        set Connected . TextColor . to
   else set Connected . Text to Not Connected
        set connected . Textcolor to
```

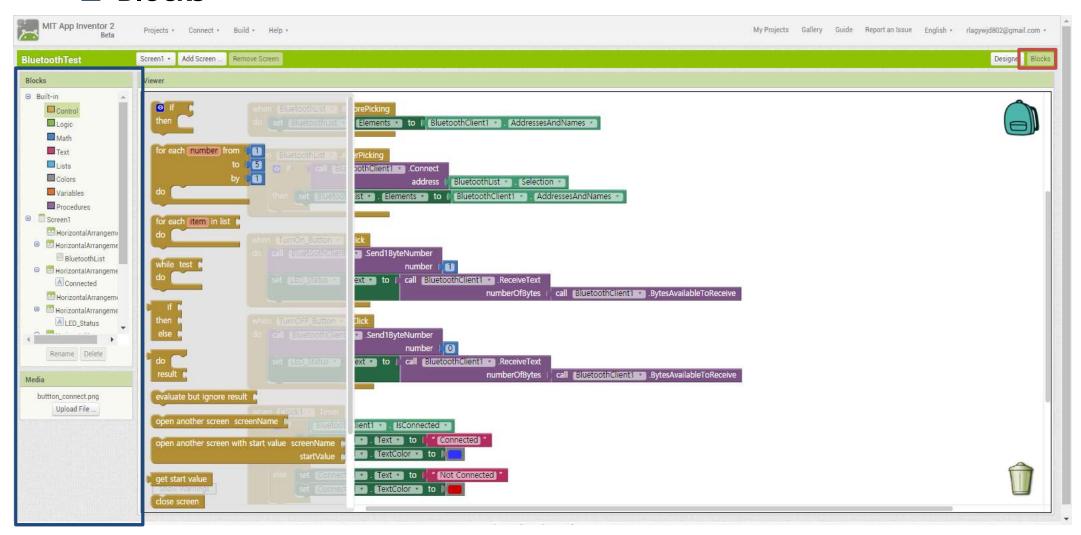
MIT App Inventor

Designer

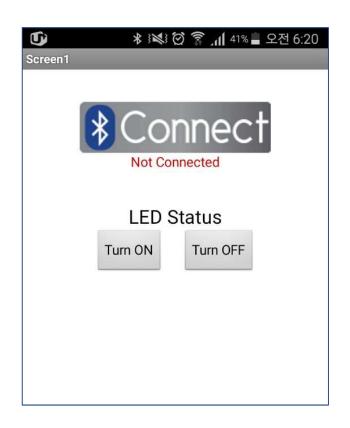


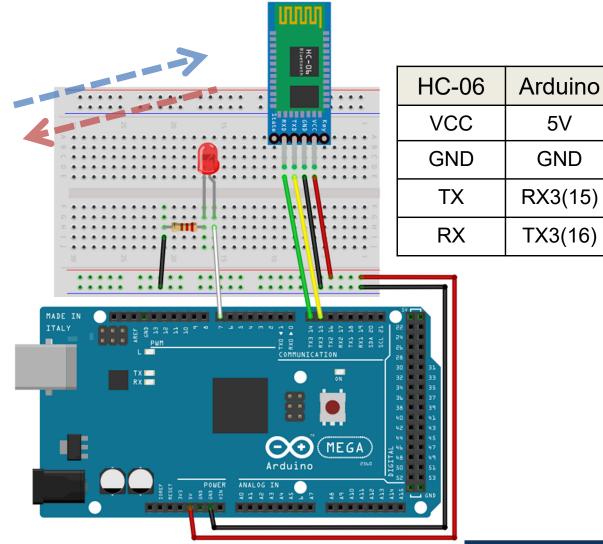
MIT App Inventor

Blocks



[예제1] Bluetooth로 LED키기

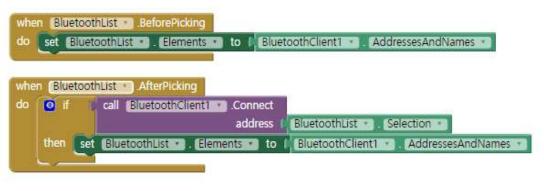








```
when BluetoothList BeforePicking
do set BluetoothList . Elements to | BluetoothClient1 . AddressesAndNames
when BluetoothList AfterPicking
                                                                                                          블루투스 연결부
            call BluetoothClient1 .Connect
                               address
                                      BluetoothList . Selection .
   then set BluetoothList
                                                      AddressesAndNames
                         Elements to
                                       BluetoothClient1 +
when TurnOn_Button - Click
number
   set LED Status . Text to | call BluetoothClient . ReceiveText
                                                          call BluetoothClienti ... BytesAvailableToReceive
                                             numberOfBytes
                                                                                                          버튼 조작부
when TurnOFF_Button Click
   number (10)
    set LED Status . Text to (
                             call BluetoothClient() ... ReceiveText
                                             numberOfBytes | call Bluetooth@lient1 ... BytesAvailableToReceive
when Clock1 Timer
           BluetoothClient1 IsConnected
                       Text to Connected
        set Connected
         set Connected
                       TextColor v to
                                                                                                           타이머
         set Connected . Text to Not Connected
         set connected
                       Textcolor to
```

















```
when TurnOn_Button Click

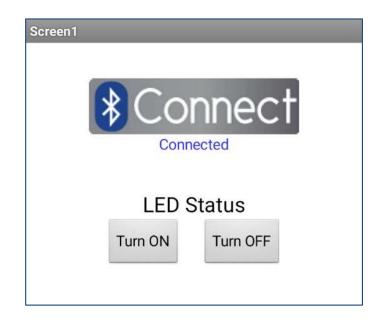
do call BluetoothClient Send1ByteNumber number (1)

set LED_Status Text to ( call BluetoothClient BytesAvailableToReceive numberOfBytes call BluetoothClient BytesAvailableToReceive

when TurnOFF_Button Click

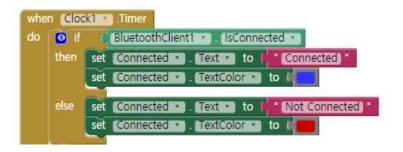
do call BluetoothClient Send1ByteNumber number (0)

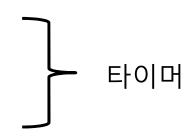
set LED_Status Text to ( call BluetoothClient ReceiveText numberOfBytes call BluetoothClient BytesAvailableToReceive
```



```
void loop() {
  if(Serial3.available()){
   indata = Serial3.read();

  if(indata == 0){
     digitalWrite(ledPin, LOW);
     Serial.println("LED:OFF");
  }
  else if(indata == 1){
     digitalWrite(ledPin, HIGH);
     Serial.println("LED:ON");
  }
  else{
     Serial3.println("Error");
     Serial.println(indata);
  }
}
```



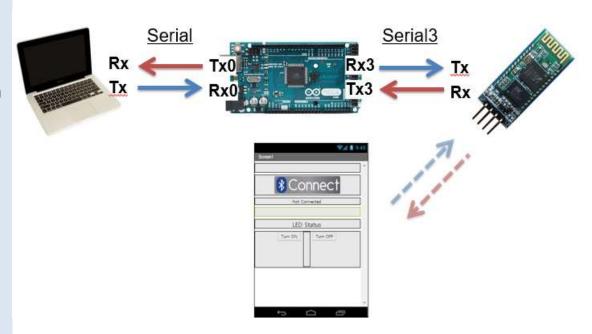




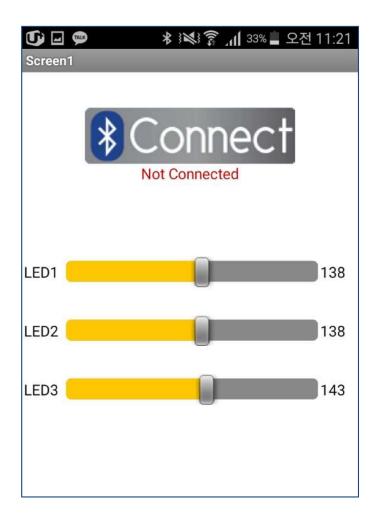


Arduino

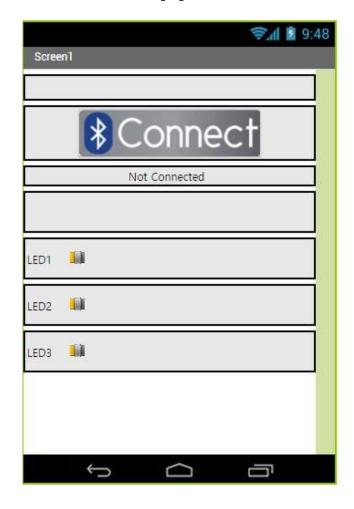
```
#define ledPin 7
unsigned char indata; // 1Byte Number
void setup() {
 pinMode(ledPin, OUTPUT);
 digitalWrite(ledPin, LOW);
 Serial.begin(9600);
 Serial3.begin(9600); // Default baud rate of the Bluetooth
void loop() {
 if(Serial3.available()){
  indata = Serial3.read();
  if(indata == 0){
   digitalWrite(ledPin, LOW);
   Serial.println("LED:OFF");
  else if(indata == 1){
   digitalWrite(ledPin, HIGH);
   Serial.println("LED:ON");
  else{
   Serial3.println("Error");
   Serial.println(indata);
```

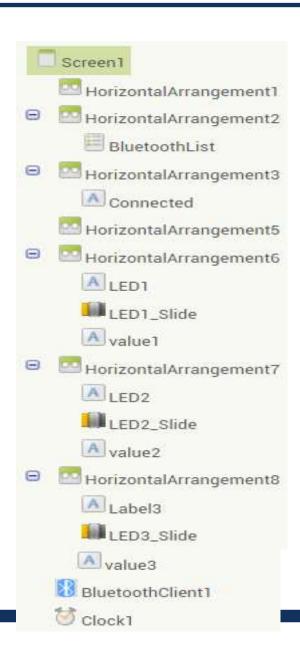


[예제2] Bluetooth로 여러 개 LED 밝기조절









- Components 부분을 사진과 같이 구성
- Properties 부분은 임의로 구성

```
when BluetoothList BeforePicking
do set Bluetoothust . Elements
                               to | BluetoothClient1
                                                    AddressesAndNames •
when BluetoothList AfterPicking
                                                                                           블루투스 연결부
   o if call BluetoothClient .Connect
                                address
                                         BluetoothList . Selection
    then set Bluetoothuist . Elements to (
                                         BluetoothClient1 . AddressesAndNames .
when Clock1 Timer
          BluetoothClient1
                            IsConnected •
         set Connected . Text to Connected
                                                                                           타이머
                        TextColor •
         set Connected .
         set Connected .
                                   Not Connected
         set Connected
                        TextColor •
```

```
when LED1_Slide ... PositionChanged
 thumbPosition
do o if BluetoothClient I sConnected
   then call SendText
   set value : Text to round LED1_Slide ThumbPosition
when LED2_Slide ... PositionChanged
 thumbPosition
do 6 if BluetoothClient1
                           IsConnected *
                                                                                                         슬라이드 조작부
   then call SendText
   set (value2 Text to round LED2_Slide ThumbPosition
when LED3_Slide PositionChanged
 thumbPosition
do 10 if BluetoothClient1 IsConnected
   then call SenaText
   set value3 . Text to round LED3_Slide ThumbPosition
to SendText
do call BluetoothClient1 ... SendText
                               join round
                                                LED1_Slide ThumbPosition
   call BluetoothClient1 .SendText
                                                                                                         함수부
                                                LED2 Slide ThumbPosition
                               join round
   call BluetoothClient1 .SendText
                                                LED3_Slide ThumbPosition
                               o join round
                                        ₩n
```

Arduino

```
#define ledPin1 7
#define ledPin2 8
#define ledPin3 9
void setup() {
 pinMode(ledPin1, OUTPUT);
 pinMode(ledPin2, OUTPUT);
 pinMode(ledPin3, OUTPUT);
 Serial3.begin(9600);
void loop() {
 if(Serial3.available()){
  int val1 = Serial3.parseInt();
  int val2 = Serial3.parseInt();
  int val3 = Serial3.parseInt();
  if(Serial3.read() == '\n'){
   analogWrite(ledPin1, val1);
   analogWrite(ledPin2, val2);
   analogWrite(ledPin3, val3);
```