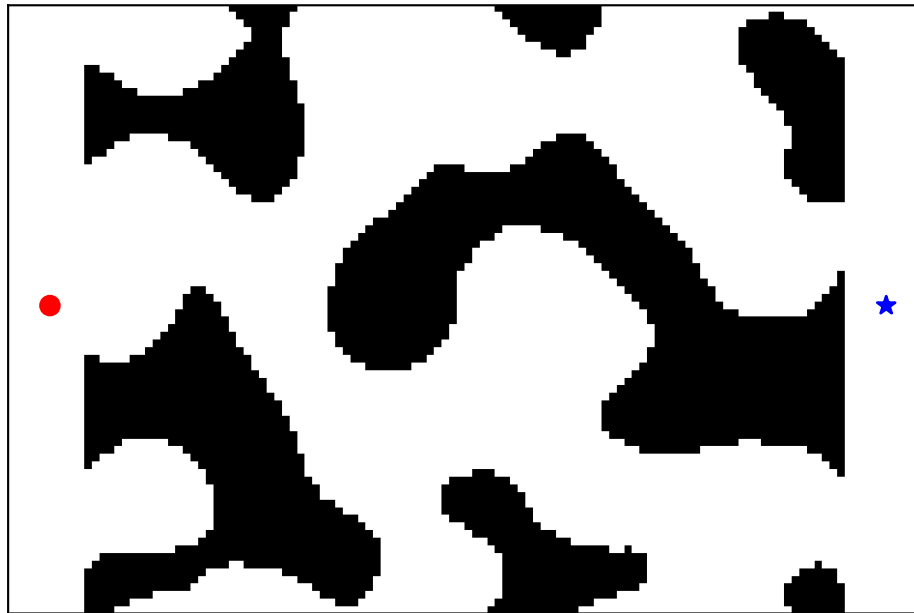
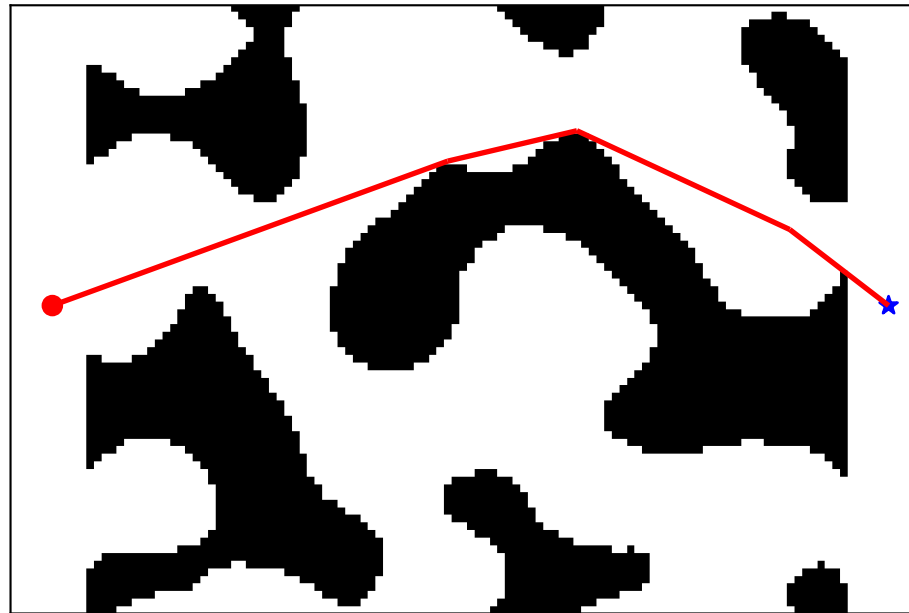


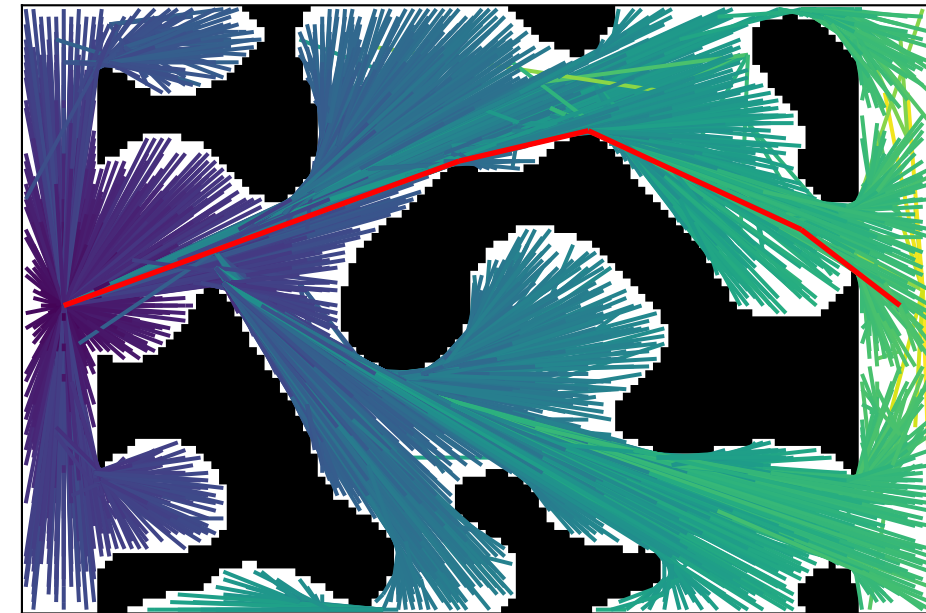
RRT\* ( $\mathbb{R}^2$  Distance Heuristic) Cspace Only



RRT\* ( $\mathbb{R}^2$  Distance Heuristic) Path



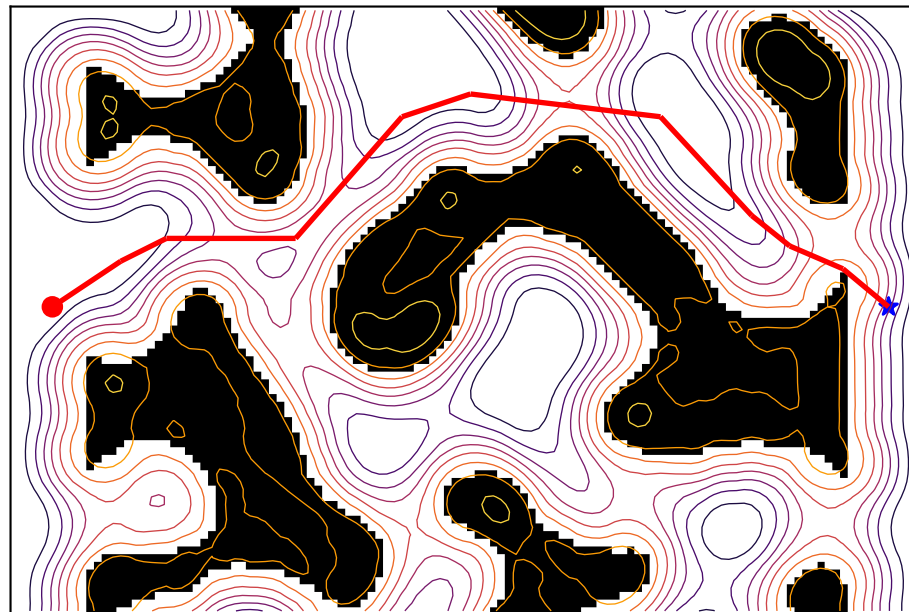
RRT\* ( $\mathbb{R}^2$  Distance Heuristic) Tree



RRT\* (Optimal Cost Heuristic) Cspace Only



RRT\* (Optimal Cost Heuristic) Path



RRT\* (Optimal Cost Heuristic) Tree

