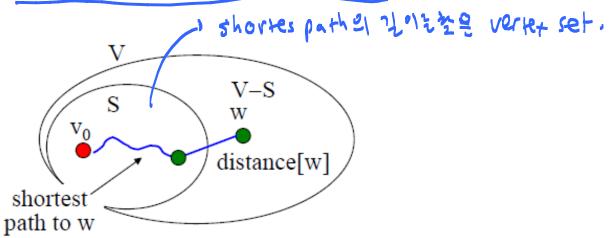
- Dijkstra's Shortest Path Algorithm
 - ◆ Single source all destinations shortest path problem.
 - ◆Find the shortest path from the source v0 to every other vertices.
 Let length[v] be the shortest path length.
 - ◆Let S denote the set of vertices, including v0, whose shortest path has been found.
 - ◆Let distance[w] be the length of the shortest path starting from v0, going through vertices only in S, and ending in w.



- → Dijkstra's Shortest Path Algorithm
 - Initialization

```
S = \{v0\}, distance[v0] = 0
                                  for w \in V - S {
                                                    if (v0, w) \in E distance [w] = cost(v0, w)
                                                                                                                                                                                                                                                                                                                                                       a distance [u] It length[u] ILsya.

2, & shorte: path, from s to u

length
                                                   else distance[w] = \infty
Algorithm
                                1. S = \{v0\}
                                2. while V - S != empty set {
                                 3. u = min\{distance[w], w \in V - S\}
                               4. S = S \cup \{u\}, V - S = (V - S) - \{u\} // U = S \cap \{u\} // U = S 
                                 update distance[w]
                                7.
                                                                                                                                                                                                                                                                                                                                     S
                                                                                                                                                                                                                                                                                                                                                                                                               V-S
                                 8. }
                                                                                                                                                                                                                                                                                                                                                                                                             distance[u]
```

= length[u]

At line 3, length[u] = distance[u]

- ◆A proof that length[u] = distance[u] at Line 3. distance[w]?
 - 1. Suppose that distance[u] > length[u].
 - 2. Let P be a shortest path from v0 to u.
 - 3. The length of P = length[u].
 - 4. P has at least one vertex \notin S.

Otherwise, the length of P = distance[u].

Shortest old &

V-S

u

w

S

- 5. Let $w \in P$ be the vertex which is closest to v0.
- 6. distance[u] > length[u] \geq length[w](= $\forall i$ stance[w])
- This implies that distance[u] > distance[w] since length[w] = distance[w].
- 8. This is a contradiction since the Dijkstra's algorithm selects a vertex whose distance[] is minimum in V S.
- 9. Therefore, distance[u] = length[u].

◆Distance update at Line 6

*After completion of the algorithm, distance[v]=length[v] for all v ∈ V.

diffarce[] array れいたままり

```
◆ An Algorithm with an Adjacency List
  for( i = 0; i < n; i++ ) {
    found[i]=F; distance[i] = +\infty;
                                           Initialization
  found[s]=T; distance[s]=0;
  for( every vertex u adjacent to s )
    distance[u] = cost(s,u);
  for( i=0; i<n-1; i++ ) { // n-1 iterations</pre>
    Choose a vertex u such that found[u]=F and
      distance[u] is minimum; // <u>O(n)</u> ოც ლა
    found[u] = T; // UGS
    for (every vertex w adjacent to u ) // O(|E|)
           distance[u]+cost(u,w) < distance[w] )</pre>
        distance[w] = distance[u] + cost(u, w);
                                                           total 1E/1273
\bullet O(|V|^2) time.
```

◆Remarks

Finding an actual shortest path?

◆If the cost is real? → bactracing buch

◆ If we want to find a shortest path to a specific target vertex, how can we modify the algorithm?

• Shortest path tree: The spanning tree which has the shortest path from the source vertex to every other vertex. We can easily create such a tree.

- May not work when some edges have negative cost.
- Time Complexity : Better implementation is possible.
 - $O((|V|+|E|)\log|V|)$ algorithm(see the next page).
 - $O(|V|\log|V| + |E|)$ algorithm using the Fibonacci heap.

if (distance [U] - cust (u, w) == distance [w]) 9

> LEM 42 pare[w]=43 sely.

25005 240939 240659 240655

spung mee

```
\rightarrow An O((|V|+|E|) log|V|) Algorithm
 for(i = 0; i < n; i++) {
    found[i] = F; distance[i] = -\infty;
                                           O((|V|+|E|)\log|V|)
 found[s] = T; distance[s] = 0;
 for ( every vertex u adjacent to s )
                                            Even if |E| < |V|,
    distance[u] = cost(s,u);
                                            we still need n-1
                                              iterations.
 construct min heap(V-{s});
 for (i=0; i < n-2; i++) { // n-1 iterations (=0(|V|))}
    Choose a vertex u such that distance[u]
                                                              heap
      is minimum; // O(1)
    found[u] = T;
   Delete u from the heap // O(log |V|)
    for (every vertex w adjacent to u ) // O(|E|)
      if ( found[w] == F &&
                                                  total
           distance[u] + cost(u,w) < distance[w] ) {
                                                            well distance
        distance[w] = distance[u] + cost(u,w);
        adjust heap(w); // O(log | V | )
                                                               sheap of oly
                               No removal of elements.
                                                          コ heapsをいもり
                               Just adjust the cost.
```

Scheduling Problems

- Minimizing Total Time in the System
 - **♦** Problem Definition
- •Input : A list of jobs $J_1, J_2, ..., J_n$. Each job J_i has service time t_i and it waits w_i before start execution.
- Question : Find a schedule that minimize $\Sigma(t_i+w_i)$.
- \bullet An Example: Three jobs and service times $t_1=5$, $t_2=10$ and $t_3=4$.

and
$$t_3$$
=4.
Schedule Total Time in the System t_1 t_2 t_3
[1, 2, 3] t_3 t_4 t_5 t_4 t_5 t_4 t_5 t_5

A Greedy Algorithm: Schedule jobs in nondecreasing order by service time. Proof. See the text book.

◆ A Proof of Optimality

➤ Theorem 4.3

The only schedule that minimizes the total time in the system is one that schedules jobs in nondecreasing order by service time.

Proof: For $1 \le i \le n$ 1, let t_i be the service time for the *i*th job scheduled in some particular optimal schedule (one that minimizes the total time in the system). We need to show that the schedule has the jobs scheduled in nondecreasing order by service time. We show this using proof by contradiction.

7/23

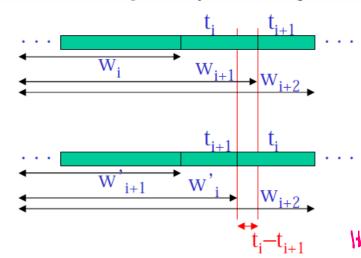
J.
$$J_2 - - - - J_n$$
 J_n J_n J_n optimal schedule of M_n J_n J_n

If they are not scheduled in nondecreasing order, then for at least one iwhere $1 \le i \le n - 1$, $t_i > t_{i+1}$.

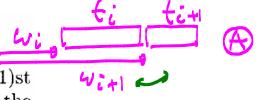
We can rearrange our original schedule by interchanging the ith and (i + 1)st jobs. By doing this, we have taken t_i units off the time the (i+1)st job (in the original schedule) spends in the system. The reason is that it no longer waits while the *i*th job (in the original schedule) is being served. Similarly, we have added t_{i+1} units to the time the *i*th job (in the original schedule) spends in the system. Clearly, we have not changed the time that any other job spends in the system. Therefore, if T is the total time in the system in our original schedule and T' is the total time in the rearranged schedule,

$$T' = T + t_{i+1} - t_i.$$

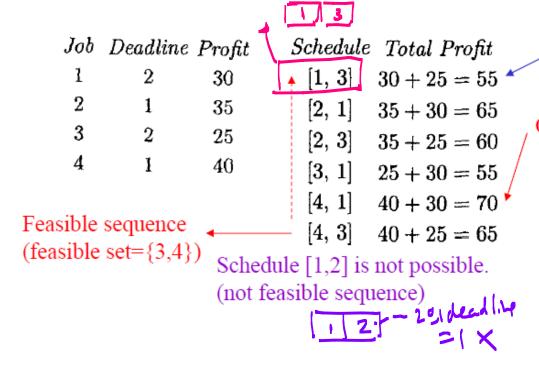
Because $t_i > t_{i+1}, T' < T$, which contradicts the optimality of our original schedule.



time for (i+1)st job: $t_{i+1} + w_i$ (t_i off) time for ith job: $t_{i}+w_{i}+t_{i+1}$ $(t_{i+1} \text{ more})$ (5) $\times 2\omega$; $+2t_{i}+t_{i}$



- Scheduling with Deadlines
 - **♦** Problem Definition
 - ◆Input : A list of jobs $J_1, J_2, ..., J_n$. Each J_i takes a unit time to finish and has a deadline d_i and a profit p_i .
 - Question: Find a schedule that maximize the profit.
 - If a job J_i starts before or at d_i, profit p_i is obtained. Otherwise, no profit is obtained for J_i.



processing the =

 d_1, d_3 be So oth

Others can not be scheduled. So, no profits for other jobs.

Optimal sequence (optimal set= $\{1,4\}$)

Schedule jobs in decreasing order of profits.

- J₄ is scheduled.
- J_2 is not possible to schedule.
- J_1 is scheduled.
- J_3 is not possible.

34 51

```
◆An Algorithm
```

5

3

2

```
sort the jobs in nonincreasing order by profit;

S = \emptyset;

while (the instance is not solved){

select next job; // selection procedure

if (S is feasible with this job added)//feasibility

add this job to S; //check

if (there are no more jobs) // solution check

the instance is solved;

}

S is set to \emptyset.
```

```
Job Deadline Profit 1. S is set to \varnothing.

1 3 40 2 S is set to \{1, \dots, n\}
```

20

15

10

- S is set to {1} because the sequence [1] is feasible.
 S is set to {1, 2} because the sequence [2, 1] is feasible.
- 3. S is set to {1, 2} because the sequence [2, 1] is feasible.

 4. {1, 2, 3} is rejected because there is no feasible sequence for this set.
- 5. S is set to $\{1, 2, 4\}$ because the sequence [2, 1, 4] is feasible.
- 6. {1, 2, 4, 5} is rejected because there is no feasible sequence for this set.
- 7. {1, 2, 4, 6} is rejected because there is no feasible sequence for this set.
- 8. {1, 2, 4, 7} is rejected because there is no feasible sequence for this set.

 $\{1,2,4\}$ is an optimal set.

[2,1,4] and [2,4,1] are optimal sequences. Just choose one.

- ♦ An Efficient Way to Determine Feasibility
 - \blacktriangle Lemma 4.3 Let S be a set of jobs. Then S is feasible if and only if the sequence obtained by ordering the jobs in S according to nondecreasing deadlines is 5 % feasible (=> Sizziz deadline=1
 Et sizziz vight segil feasible.
- **♦** An Algorithm

```
sort the jobs by profit (nonincreasing); // O(nlogn)
void schedule (int n, const int deadline [],
                   sequence_of_integer (i, j) {
                                                            dead he I 2 2 h 5 = 2
  index i;
  sequence_of_integer K; // temp storage
                                                             Titte and
  J = \{1\};
  for (i = 2; i \le n; i++)
    K = J with i added according to
           nondecreasing values of deadline [i]; K
 (K is feasible) // O(i) (일일이 조사)
                                                                     to check feasibility feasible his
          J = K;
                                                          \sum_{i=0}^{n} \left[ \begin{pmatrix} v \\ i-1 \end{pmatrix} + V \right] = n^{2} - 1 \in \Theta\left(n^{2}\right)
Read Theorem4.4 (An optimality proof)
```