



MATRIX



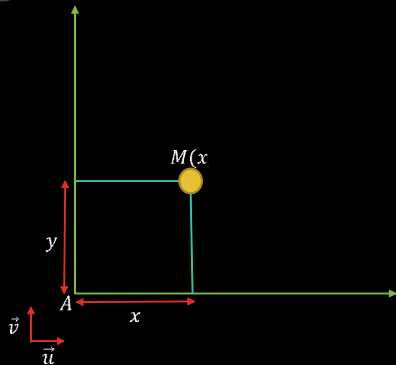
Scale

Rotation

Translation



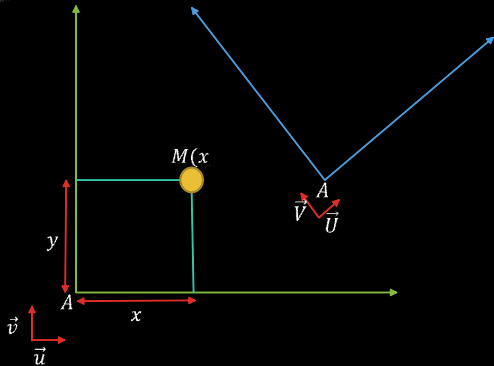
좌표계 변환



$$\overrightarrow{AM} = x \cdot \vec{u} + y \cdot \vec{v}$$

좌표계 변환

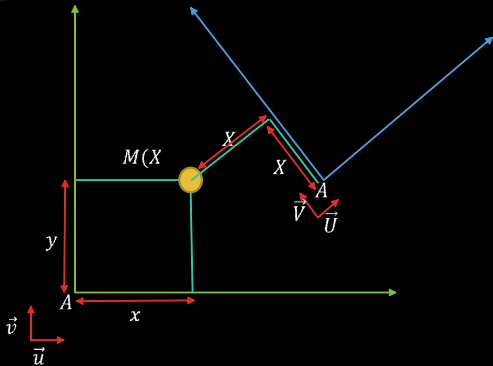
$$\overrightarrow{AM} = x \cdot \vec{u} + y \cdot \vec{v}$$



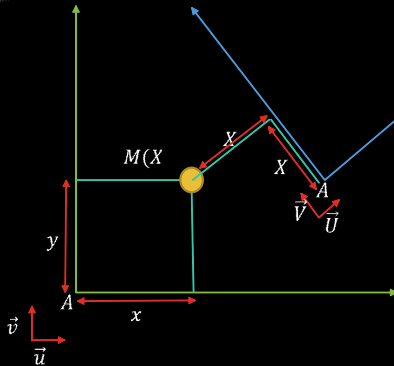
좌표계 변환

$$\overrightarrow{AM} = x \cdot \vec{u} + y \cdot \vec{v}$$

$$\overrightarrow{BM} = X \cdot \vec{U} + Y \cdot \vec{V}$$



좌표계 변환



$$\overrightarrow{AM} = \overrightarrow{AB} + \overrightarrow{BM}$$

$$\begin{aligned}\overrightarrow{AM} &= (x \cdot \vec{u} + y \cdot \vec{v}) \\ &= x(u_x \cdot \vec{U} + u_y \cdot \vec{V}) + y(v_x \cdot \vec{U} + v_y \cdot \vec{V}) \\ &= (xu_x + yv_x) \vec{U} + (xu_y + yv_y) \vec{V}\end{aligned}$$

$$\begin{aligned}\overrightarrow{BM} &= \overrightarrow{AM} - \overrightarrow{AB} = \overrightarrow{AM} + \overrightarrow{BA} \\ &= (xu_x + yv_x) \vec{U} + (xu_y + yv_y) \vec{V} + (Q_x \vec{U} + Q_y \vec{V}) \\ &= (xu_x + yv_x + Q_x) \vec{U} + (xu_y + yv_y + Q_y) \vec{V}\end{aligned}$$

$$\vec{u} = u_x \cdot \vec{U} + u_y \cdot \vec{V}$$

$$\vec{v} = v_x \cdot \vec{U} + v_y \cdot \vec{V}$$

$$\overrightarrow{AM} = \overrightarrow{AB} + \overrightarrow{BM}$$

$$\begin{aligned}\overrightarrow{AM} &= (x \cdot \vec{u} + y \cdot \vec{v}) \\ &= x(u_x \cdot \vec{U} + u_y \cdot \vec{V}) + y(v_x \cdot \vec{U} + v_y \cdot \vec{V}) \\ &= (xu_x + yv_x) \vec{U} + (xu_y + yv_y) \vec{V}\end{aligned}$$

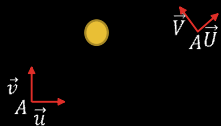
$$\begin{aligned}\overrightarrow{BM} &= \overrightarrow{AM} - \overrightarrow{AB} = \overrightarrow{AM} + \overrightarrow{BA} \\ &= (xu_x + yv_x) \vec{U} + (xu_y + yv_y) \vec{V} + (Q_x \vec{U} + Q_y \vec{V}) \\ &= (xu_x + yv_x + Q_x) \vec{U} + (xu_y + yv_y + Q_y) \vec{V}\end{aligned}$$

좌표계 변환

$$\vec{v} = [x \quad y \quad z \quad 1] \quad M = \begin{bmatrix} u_x & u_y & u_z & 0 \\ v_x & v_y & v_z & 0 \\ w_x & w_y & w_z & 0 \\ Q_x & Q_y & Q_z & 1 \end{bmatrix}$$

$$\vec{V} = [X \quad Y \quad Z \quad 1]$$

좌표계 변환



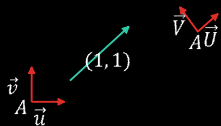
(B 좌표계 기준) \vec{u} , \vec{v} , \vec{w} 의 성분

$$\vec{v} = [x \quad y \quad z \quad 1] \quad M = \begin{bmatrix} u_x & u_y & u_z & 0 \\ v_x & v_y & v_z & 0 \\ w_x & w_y & w_z & 0 \\ Q_x & Q_y & Q_z & 1 \end{bmatrix}$$

(B 좌표계 기준) A의 좌표

$$\vec{V} = [X \quad Y \quad Z \quad 1]$$

좌표계 변환



(B 좌표계 기준) \vec{u} , \vec{v} , \vec{w} 의 성분

무엇이 다를까?

$$\vec{v} = [x \quad y \quad z \quad \boxed{1}]$$

$$M = \begin{bmatrix} u_x & u_y & u_z & 0 \\ v_x & v_y & v_z & 0 \\ w_x & w_y & w_z & 0 \\ Q_x & Q_y & Q_z & 1 \end{bmatrix}$$

(B 좌표계 기준) A의 좌표

$$\vec{V} = [X \quad Y \quad Z \quad 1]$$