

수학 복습



Scale

Rotation

Translation



벡터와 행렬

$$\vec{v} = [x \quad y \quad z \quad 1] \quad M = \begin{bmatrix} m_{11} & m_{12} & m_{13} & m_{14} \\ m_{21} & m_{22} & m_{23} & m_{24} \\ m_{31} & m_{32} & m_{33} & m_{34} \\ m_{41} & m_{42} & m_{43} & m_{44} \end{bmatrix}$$

$$\left\{ \begin{array}{l} X = xm_{11} + ym_{21} + zm_{31} + m_{41} \\ Y = xm_{12} + ym_{22} + zm_{32} + m_{42} \\ Z = xm_{13} + ym_{23} + zm_{33} + m_{43} \end{array} \right.$$

SCALE

Scale

ROTATION

Rotation
Z

$$R_x(\phi) = \text{Roll}(\phi) = \begin{bmatrix} 1 & 0 & 0 \\ 0 & \cos \phi & -\sin \phi \\ 0 & \sin \phi & \cos \phi \end{bmatrix}$$

$$R_y(\theta) = \text{Pitch}(\theta) = \begin{bmatrix} \cos \theta & 0 & \sin \theta \\ 0 & 1 & 0 \\ -\sin \theta & 0 & \cos \theta \end{bmatrix}$$

$$R_z(\psi) = \text{Yaw}(\psi) = \begin{bmatrix} \cos \psi & -\sin \psi & 0 \\ \sin \psi & \cos \psi & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

ROTATION

Rotation

TRANSLATION

Translation



Scale

Rotation

Translation

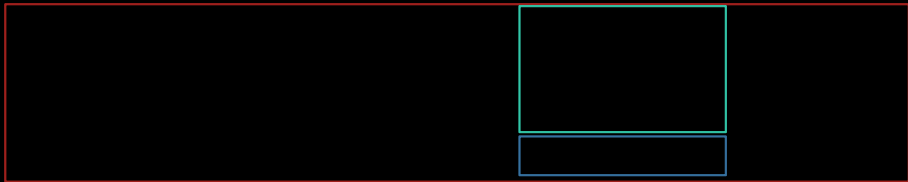
Rotation

Parent

스 자 이 공 부



좌표계 변환

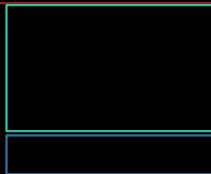


(B 좌표계 기준) A의 좌표

좌표계 변환

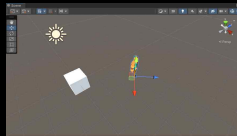
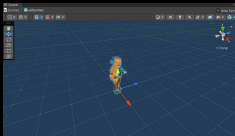


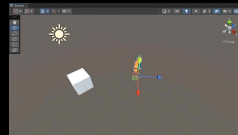
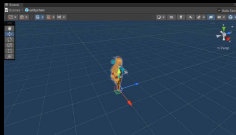
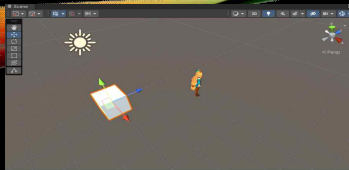
무엇이 다를까?



(B 좌표계 기준) A의 좌표

WORLD MATRIX



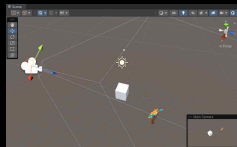
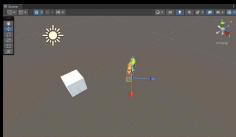
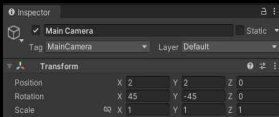


Scale

Rotation

Translation

VIEW MATRIX



C++

```
XMMATRIX XM_CALLCONV XMMatrixLookAtLH(  
    FXMVECTOR EyePosition,  
    FXMVECTOR FocusPosition,  
    FXMVECTOR UpDirection  
);
```

Parameters

`EyePosition`

Position of the camera.

`FocusPosition`

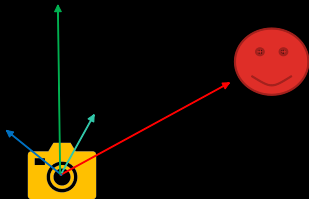
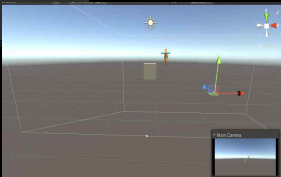
Position of the focal point.

`UpDirection`

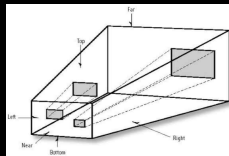
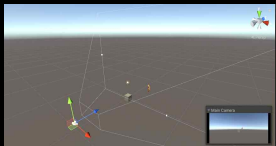
Up direction of the camera, typically $\langle 0.0f, 1.0f, 0.0f \rangle$.

Return value

Returns a view matrix that transforms a point from world space into view space.



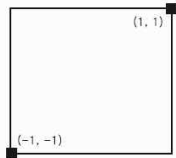
PROJECTION MATRIX



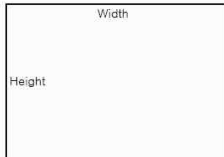


SCREEN SPACE (WINDOW SPACE)

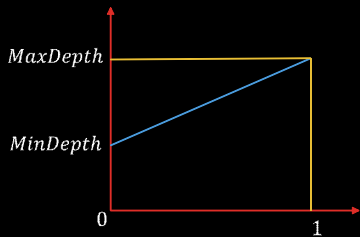
Normalized Coordination Space



Mapping

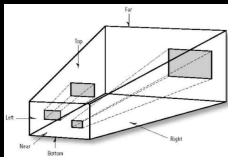
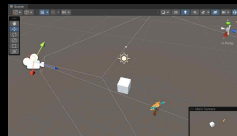
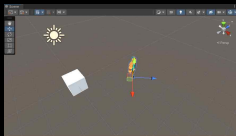
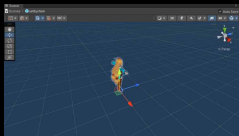


Actual Viewport

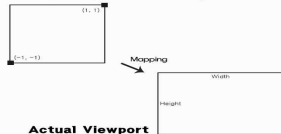


$$M = \begin{bmatrix} \frac{W}{2} & 0 & 0 & 0 \\ 0 & -\frac{H}{2} & 0 & 0 \\ 0 & 0 & MaxD - MinD & 0 \\ \frac{W}{2} + Left & \frac{H}{2} + Top & MinD & 1 \end{bmatrix}$$

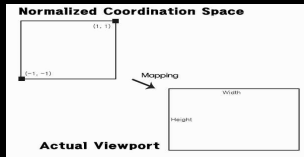
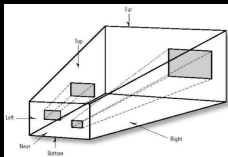
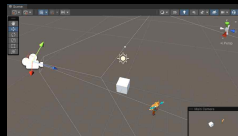
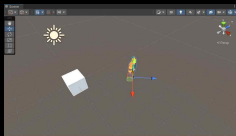
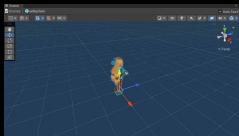
SPACE TRANSFORMATION



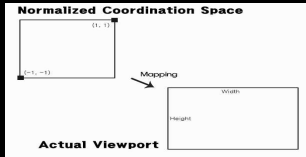
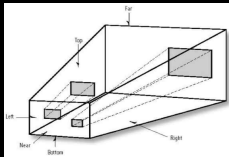
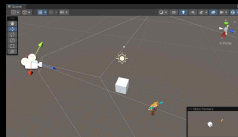
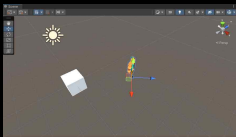
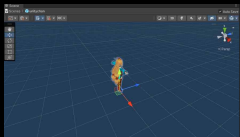
Normalized Coordination Space



QUIZ1 : 지난번에 이런 거 안 했는데 왜 이미지가 뺏을까?



QUIZ2 : 콘텐츠 작업한다면 좌표는 어느 공간의 좌표일까?



QUIZ3 : 화면 공간을 클릭하면 어느 공간의 좌표일까?

