# STAT 135 Lab 13 (Review) Linear Regression, Multivariate Random Variables, Prediction, Logistic Regression and the $\delta$ -Method.

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$$y = \beta_0 + \beta_1 x + \epsilon$$

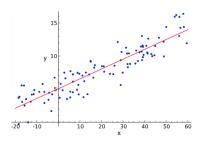
Suppose that there is some global linear relationship between height and weight in the population. For example

Weight = 
$$\beta_0 + \beta_1 \times \text{Height} + \epsilon$$

Obviously height and weight don't fall on a perfectly straight line:

▶ there is some random noise/deviation from the line ( $\epsilon$  is a random variable with  $E(\epsilon) = 0$  and  $Var(\epsilon) = \sigma^2$ ).

Moreover, we don't observe everyone in the population, and so there is no way we can figure out what  $\beta_0$  and  $\beta_1$  are, but what we can do is get estimates from a sample.



We observe a sample (blue points) and fit the best line through the sample. The red fitted line corresponds to

$$\hat{y} = \hat{\beta}_0 + \hat{\beta}_1 x$$

where  $\hat{\beta}_0$  and  $\hat{\beta}_1$  are estimated from our sample using least squares (finding the  $\beta$  values that minimize the distance from the observed points to the line)

We showed that we can write our linear regression model in matrix form:

$$Y = X\beta + \epsilon$$

and the least squares estimate of  $\beta$  is given by

$$\hat{\beta} = \arg \, \min_{\beta} \lVert Y - X\beta \rVert_2^2 = (X^TX)^{-1}X^TY$$

We further showed that  $\hat{\beta}$  was unbiased:

$$E(\hat{\beta}) = \beta$$

and that its variance is given by

$$Var(\hat{\beta}) = \sigma^2 (X^T X)^{-1}$$



The **residuals** are then defined to be the observed difference between the true y (blue dot) and the fitted  $\hat{y}$  (corresponding point on the red line):

$$e_i = y_i - \hat{y}_i = y_i - \hat{\beta}_0 - \hat{\beta}_1 x_i$$

which is different from the unobservable error

$$\epsilon_i = y_i - \beta_0 - \beta_1 x_i$$

(this corresponds to the deviation from the observed  $y_i$  to the true population line, which we don't know!)

Suppose we have n random variables:  $Y_1, ..., Y_n$ , such that  $E(Y_i) = \mu$  and  $Cov(Y_i, Y_j) = \sigma_{ij}$ . Suppose that we want to consider the  $Y_i$ 's jointly as a single multivariate random variable,  $\mathbf{Y}$ 

$$\mathbf{Y} = (Y_1, ..., Y_n)$$

Then this multivariate random variable  $\mathbf{Y}$  has mean *vector* and *covariance matrix*:

mean vector: 
$$E(\mathbf{Y}) = \mu = (\mu_1, ..., \mu_n)$$

covariance matrix: 
$$Cov(\mathbf{Y}) = \Sigma_{Y,Y} = \begin{bmatrix} \sigma_1^2 & \sigma_{1,2} & \dots & \sigma_{1,n} \\ \sigma_{2,1} & \sigma_2^2 & \dots & \sigma_{2,n} \\ \vdots & \vdots & \vdots & \vdots \\ \sigma_{n,1} & \sigma_{n,2} & \dots & \sigma_n^2 \end{bmatrix}$$

$$E(\mathbf{Y}) = \mu$$
  $Cov(\mathbf{Y}) = \Sigma$ 

Suppose we have the following linear transformation of Y:

$$\mathbf{Z} = b + A\mathbf{Y}$$

where b is a fixed vector and A a fixed matrix.

What is the mean vector and covariance matrix of  $\mathbf{Z}$ ?

$$E(\mathbf{Z}) = E(b + A\mathbf{Y}) = b + AE(\mathbf{Y}) = b + A\mu$$

$$Cov(\mathbf{Z}) = Cov(b + A\mathbf{Y}) = Cov(A\mathbf{Y}) = ACov(\mathbf{Y})A^T = A\Sigma A^T$$

Suppose that **Y** is a multivariate random vector:  $\mathbf{Y} = (Y_1, ..., Y_n)$ .

Recall that for scalars, a quadratic transformation of y is given by  $x = ay^2 \in \mathbb{R}$ . The equivalent form for vectors is

$$X = \mathbf{Y}^T A \mathbf{Y} \in \mathbb{R}$$

This is referred to as a  $random\ quadratic\ form\ in\ {f Y}$ 

$$X = \mathbf{Y}^T A \mathbf{Y} \in \mathbb{R}$$

is a  $random\ quadratic\ form$  ia  ${f Y}$ 

How can we calculate the expected value of the quadratic form of a random variable?

We can use the following facts

- 1. Trace and expectation are both linear operators (and so can be interchanged).
- 2.  $X = \mathbf{Y}^T A \mathbf{Y} \in \mathbb{R}$  is a real number (not a matrix or vector), and if  $x \in \mathbb{R}$  then tr(x) = x.
- 3. If A and B are matrices of appropriate dimension, then tr(AB) = tr(BA)

where the trace of a matrix is the sum of its diagonal entries



- 1. Trace and expectation are both linear operators (and so can be interchanged).
- 2. If  $x \in \mathbb{R}$  then tr(x) = x.
- 3. If A and B are matrices, then tr(AB) = tr(BA)

So

$$E[\mathbf{Y}^{T}A\mathbf{Y}] = E[tr(\mathbf{Y}^{T}A\mathbf{Y})] \qquad \text{fact } (2)$$

$$= E[tr(A\mathbf{Y}\mathbf{Y}^{T})] \qquad \text{fact } (3)$$

$$= tr(E[A\mathbf{Y}\mathbf{Y}^{T}]) \qquad \text{fact } (1)$$

$$= tr(AE[\mathbf{Y}\mathbf{Y}^{T}]) \qquad \text{fact } (1)$$

$$= tr(A(\Sigma + \mu\mu^{T})) \qquad \text{calculating expectation}$$

$$= tr(A\Sigma) + tr(A\mu\mu^{T}) \qquad \text{fact } (1)$$

$$= tr(A\Sigma) + tr(\mu^{T}A\mu) \qquad \text{fact } (3)$$

$$= tr(A\Sigma) + \mu^{T}A\mu \qquad \text{fact } (2)$$

The expected value of a quadratic form of a random variable is given by:

$$E\left[\mathbf{Y}^{T} A \mathbf{Y}\right] = tr(A\Sigma) + \mu^{T} A \mu$$

We can use this to show that an unbiased estimate for  $\sigma^2$  is given by

$$\hat{\sigma}^2 = \frac{RSS}{n-p}$$

where

$$RSS = ||e||_2^2 = e^T e$$

is in quadratic form

Recall that the residuals are defined by

$$e = Y - \hat{Y}$$

$$= Y - X\hat{\beta}$$

$$= Y - X(X^{T}X)^{-1}X^{T}Y$$

$$= (I - X(X^{T}X)^{-1}X^{T})Y$$

$$= P_{X^{\perp}}Y$$

Where  $P_{X^{\perp}} := I - X(X^TX)^{-1}X^T$  is a projection matrix onto the space orthogonal to X (check:  $P_{X^{\perp}}X = 0$ ). Note that a **projection matrix** is a matrix, A, that satisfies

- $A^T = A$
- $AA = A^2 = A$

$$e = (I - X(X^TX)^{-1}X^T)Y = P_{X^{\perp}}^TY$$

Recall that the **residual sum of squares** was given by

$$RSS = ||e||_2^2 = e^T e$$

$$= (P_{X^{\perp}}Y)^T (P_{X^{\perp}}Y)$$

$$= Y^T P_{X^{\perp}}^T P_{X^{\perp}}Y$$

$$= Y^T P_{X^{\perp}}Y$$

Thus, since  $E\left[\mathbf{Y}^{T}A\mathbf{Y}\right] = tr(A\Sigma) + \mu^{T}A\mu$ , the **expected RSS** is given by

$$\begin{split} E(RSS) &= E(Y^T P_{X^{\perp}} Y) \\ &= \sigma^2 tr(P_{X^{\perp}}) + E(Y)^T P_{X^{\perp}} E(Y) \qquad (\Sigma = \sigma^2 I_n) \\ &= \sigma^2 (n-p) \end{split}$$

How did we get that last equality!?



$$\begin{split} E(RSS) &= \sigma^2 tr(P_{X^{\perp}}) + E(Y)^T P_{X^{\perp}} E(Y) \\ &= \sigma^2 (n-p) \end{split}$$

To get the last equality, we use our newly acquired knowledge of projection matrices and the trace operator:

▶  $P_{X^{\perp}}$  is a projection matrix orthogonal to X, thus  $P_{X^{\perp}}E(Y) = P_{X^{\perp}}X\beta = 0$ , so

$$E(Y)^T P_{X^{\perp}} E(Y) = 0$$

▶ The trace of an  $m \times m$  identity matrix is m, so

$$tr(P_{X^{\perp}}) = tr(I_n - X(X^T X)^{-1} X^T)$$

$$= n - tr(X(X^T X)^{-1} X^T) \qquad \text{(linearity of trace)}$$

$$= n - tr((X^T X)^{-1} X^T X) \qquad (tr(AB) = tr(BA))$$

$$= n - tr(I_p)$$

$$= n - p$$



Note that we have shown that

$$E(RSS) = \sigma^2(n-p)$$

which tells us that

$$\hat{\sigma}^2 = \frac{RSS}{n-p}$$

is an unbiased estimate of  $\sigma^2$ .

Suppose we want to predict/fit the responses,  $Y_1, ..., Y_n$  corresponding to the observed predictors,  $x_1, ..., x_n$  (each  $x_i$  is a  $1 \times p$  vector), which form the rows of the design matrix X.

Then our **predicted**  $Y_i$ 's (note that these are the same Y's used to define the model) are given by

$$\hat{Y}_i = x_i \hat{\beta} = x_i (X^T X)^{-1} X^T Y$$

Since these  $\hat{Y}_i$ 's are random variables, we might be interested in calculating the variance of these predictions.

Our **predicted**  $Y_i$ 's are given by

$$\hat{Y}_i = x_i \hat{\beta} = x_i (X^T X)^{-1} X^T Y$$

The variance of the  $\hat{Y}_i$ 's are given by

$$Var(\hat{Y}_{i}) = Var(x_{i}(X^{T}X)^{-1}X^{T}Y)$$

$$= x_{i}(X^{T}X)^{-1}X^{T} \ Var(Y) \ X(X^{T}X)^{-1}x_{i}^{T}$$

$$= \sigma^{2}x_{i}(X^{T}X)^{-1}X^{T}X(X^{T}X)^{-1}x_{i}^{T}$$

$$= \sigma^{2}x_{i}(X^{T}X)^{-1}x_{i}^{T}$$

$$Var(\hat{Y}_i) = \sigma^2 x_i (X^T X)^{-1} x_i^T$$

Thus the average variance for across the n observations is:

$$\frac{1}{n} \sum_{i=1}^{n} Var(\hat{Y}_i) = \frac{\sigma^2}{n} \sum_{i=1}^{n} x_i (X^T X)^{-1} x_i^T$$

$$= \frac{\sigma^2}{n} tr(X(X^T X)^{-1} X^T)$$

$$= \frac{\sigma^2}{n} tr((X^T X)^{-1} X^T X)$$

$$= \frac{\sigma^2}{n} tr(I_p)$$

$$= \sigma^2 \frac{p}{n}$$

So the more variables we have in our model, the more variable our fitted/predicted values will be!



For **linear regression**, we have

$$Y = X\beta + \epsilon$$

and Y is continuous, such that  $Y_i|x_i \sim N(\beta^T x_i, \sigma^2)$ 

 $\triangleright$   $x_i$  is the *i*th row/observation in X

We want to use **logistic regression** if Y doesn't take continuous values, but is instead **binary**, i.e.  $Y_i \in \{0, 1\}$ .

The above linear model no longer makes sense, since a linear combination of our (continuous) x's is very unlikely to be equal to 0 or 1.

First step: think of a distribution for  $Y_i|x_i$  that makes more sense for binary Y...



Since  $Y_i$  is either 0 or 1 we can model it as a Bernoulli random variable

$$Y_i|x_i \sim Bernoulli(p(x_i, \beta))$$

where the probability that  $Y_i = 1$  is given by some function of our predictors,  $p(x_i, \beta)$ .

We need our probability,  $p(x_i, \beta)$  to be in [0, 1] and for it to depend on the linear combination of our predictors,  $\beta^T x_i$ , in some way. We choose:

$$p(x_i, \beta) = \frac{e^{\beta^T x_i}}{1 + e^{\beta^T x_i}}$$

This is a nice choice since

- $ightharpoonup \beta^T x_i \ge 0$  implies that  $p(x_i, \beta) \ge 0.5$  so  $Y_i = 1$  is most likely
- $\beta^T x_i \leq 0$  implies that  $p(x_i, \beta) \leq 0.5$  so  $Y_i = 0$  is most likely

We have the following logistic regression model:

$$Y_i|x_i \sim Bernoulli\left(\frac{e^{\beta^T x_i}}{1 + e^{\beta^T x_i}}\right)$$

▶ If we had a new sample x and we knew the  $\beta$  vector, we could calculate the probability that the corresponding Y = 1:

$$P(Y = 1|x) = p(x, \beta) = \frac{e^{\beta^T x}}{1 + e^{\beta^T x}}$$

- ▶ If this probability is greater than 0.5, we would set  $\hat{Y} = 1$ .
- ▶ Otherwise, we would set  $\hat{Y} = 0$ .

But we don't know  $\beta$ : we need to estimate the unknown  $\beta$  vector (just like with linear regression).

Let's try to calculate the MLE for  $\beta$ . The likelihood function is given by

$$lik(\beta) = \prod_{i=1}^{n} P(y_i | X_i = x_i, \beta)$$

$$= \prod_{i=1}^{n} \left( \frac{e^{\beta^T x_i}}{1 + e^{\beta^T x_i}} \right)^{y_i} \left( \frac{1}{1 + e^{\beta^T x_i}} \right)^{1 - y_i}$$

$$= \prod_{i=1}^{n} \left( \frac{e^{\beta^T x_i y_i}}{1 + e^{\beta^T x_i}} \right)$$

So that the log-likelihood is given by

$$\ell(\beta) = \sum_{i=1}^{n} \beta^{T} x_{i} y_{i} - \log\left(1 + e^{\beta^{T} x_{i}}\right)$$

The log-likelihood is given by

$$\ell(\beta) = \sum_{i=1}^{n} \beta^{T} x_i y_i - \log\left(1 + e^{\beta^{T} x_i}\right)$$

Differentiating with respect to  $\beta$  gives

$$\nabla \ell(\beta) = \sum_{i=1}^{n} x_i y_i - \frac{x_i e^{\beta^T x_i}}{1 + e^{\beta^T x_i}}$$
$$= \sum_{i=1}^{n} x_i (y_i - p(x_i, \beta))$$
$$= X^T (y - p)$$

where  $p = (p(x_1, \beta), p(x_2, \beta), ..., p(x_n, \beta)).$ 

Setting  $\nabla \ell(\beta) = 0$  cannot yield a closed form solution for  $\beta$ , so we need to use an iterative approach such as Newton's method.

**Newton's method:** Suppose that we want to find x such that f(x) = 0. Then we could use the iterative approximation given by

$$x_{n+1} = x_n - \frac{f(x_n)}{f'(x_n)}$$

and the more iterations we conduct, the closer we get to the root.

We need to find the vector  $\beta$  such that  $\nabla \ell(\beta) = 0$ . To do this, we need to conduct a vector version of Newton's method:

$$\beta^{n+1} = \beta^n - \left(\frac{\partial^2 \ell(\beta)}{\partial \beta \partial \beta^T}\right)^{-1} \nabla \ell(\beta)$$

**Newton's method for scalars:** Find x such that f(x) = 0 by

$$x_{n+1} = x_n - \frac{f(x_n)}{f'(x_n)}$$

Vector version of Newton's method for  $\beta$ :

$$\beta^{n+1} = \beta^n - \left(\frac{\partial^2 \ell(\beta)}{\partial \beta \partial \beta^T}\right)^{-1} \nabla \ell(\beta)$$

- $f(x) = \nabla \ell(x)$  is the vector-version of the first derivative
- ▶  $f'(x) = \frac{\partial^2 \ell(x)}{\partial x \partial x^T}$  is the vector-version of the second derivative

The first derivative (gradient vector) of  $\ell(\beta)$  with respect to the vector  $\beta$ :

$$\nabla \ell(\beta) = \begin{bmatrix} \frac{\partial \ell}{\partial \beta_0} \\ \frac{\partial \ell}{\partial \beta_1} \\ \vdots \\ \frac{\partial \ell}{\partial \beta_p} \end{bmatrix}$$

The second derivative (Hessian matrix) of  $\ell(\beta)$  with respect to the vector  $\beta$ :

$$\frac{\partial^{2}\ell(\beta)}{\partial\beta\partial\beta^{T}} = \begin{bmatrix} \frac{\partial^{2}\ell}{\partial\beta_{0}\partial\beta_{0}} & \frac{\partial^{2}\ell}{\partial\beta_{0}\partial\beta_{1}} & \cdots & \frac{\partial^{2}\ell}{\partial\beta_{0}\partial\beta_{p}} \\ \frac{\partial^{2}\ell}{\partial\beta_{1}\partial\beta_{0}} & \frac{\partial^{2}\ell}{\partial\beta_{1}\partial\beta_{1}} & \cdots & \frac{\partial^{2}\ell}{\partial\beta_{1}\partial\beta_{p}} \\ \vdots & \vdots & \vdots & \vdots \\ \frac{\partial^{2}\ell}{\partial\beta_{p}\partial\beta_{0}} & \frac{\partial^{2}\ell}{\partial\beta_{p}\partial\beta_{1}} & \cdots & \frac{\partial^{2}\ell}{\partial\beta_{p}\partial\beta_{p}} \end{bmatrix}$$

Recall that we were trying to find the MLE for  $\beta$  in the logistic regression using Newton's method

$$\beta^{n+1} = \beta^n - \left(\frac{\partial^2 \ell(\beta)}{\partial \beta \partial \beta^T}\right)^{-1} \nabla \ell(\beta)$$

We already showed that

$$\nabla(\beta) = X^T(y - p)$$

and one can show that

$$\frac{\partial^2 \ell(\beta)}{\partial \beta \partial \beta^T} = -X^T W X$$

where W is a diagonal matrix whose diagonal entries are given by  $W_{ii} = Var(y_i) = p(x_i, \beta)(1 - p(x_i, \beta))$ 

So our iterative procedure becomes

$$\beta^{n+1} = \beta^n + (X^T W X)^{-1} X^T (y - p)$$
  
=  $(X^T W X)^{-1} X^T W (X \beta^n + W^{-1} (y - p))$   
=  $(X^T W X)^{-1} X^T W z$ 

where 
$$z = X\beta^n + W^{-1}(y-p)$$

Recall the least squares linear regression  $\beta$  estimator

$$\hat{\beta} = (X^T X)^{-1} X^T y$$

and our iterative logistic regression estimator

$$\beta^{n+1} = (X^T W X)^{-1} X^T W z$$

We say that the estimate has been reweighted by W, and so this estimator is referred to as iteratively reweighted least squares

### The $\delta$ -Method

#### The $\delta$ -Method

The  $\delta$ -method tells us that if we have a sequence of random variables,  $X_n$ , such that

$$\sqrt{n}(X_n - \theta) \to N(0, \sigma^2) \tag{1}$$

then, for any differentiable and non-zero function,  $g(\cdot)$ , we have that

$$\sqrt{n}(g(X_n) - g(\theta)) \to N(0, \sigma^2(g'(\theta))^2)$$
 (2)

The most common reason we use the  $\delta$ -method is to identify the **variance** of a function of a random variable.

# Example: The $\delta$ -Method

Suppose that  $X_n \sim Binom(n, p)$ .

Then since  $\frac{X_n}{n}$  is the mean of n iid Bernoulli(p) random variables, the cental limit theorem tells us that

$$\sqrt{n}\left(\frac{X_n}{n} - p\right) \to N(0, p(1-p))$$

and that  $Var(\frac{X_n}{n}) = \frac{p(1-p)}{n}$ 

δ-method: for any non-zero, differentiable function  $g(\cdot)$ , we have

$$\sqrt{n}\left(g\left(\frac{X_n}{n}\right) - g(p)\right) \to N(0, p(1-p)(g'(p))^2)$$

For example, we can use this to calculate  $Var\left(\log\left(\frac{X_n}{n}\right)\right)$ .

# Example: The $\delta$ -Method

$$\sqrt{n}\left(g\left(\frac{X_n}{n}\right) - g(p)\right) \to N(0, p(1-p)(g'(p))^2)$$

For example, we can use this to calculate  $Var\left(\log\left(\frac{X_n}{n}\right)\right)$ .

Select

$$g(x) = \log\left(x\right)$$

So differentiating gives

$$g'(x) = \frac{1}{x}$$

and the  $\delta$ -method says:

$$\sqrt{n}\left(\log\left(\frac{X_n}{n}\right) - \log(p)\right) \to N\left(0, \frac{p(1-p)}{p^2}\right)$$

# Example: The $\delta$ -Method

The  $\delta$ -method says:

$$\sqrt{n}\left(\log\left(\frac{X_n}{n}\right) - \log(p)\right) \to N\left(0, \frac{p(1-p)}{p^2}\right)$$

so we can see that the variance of  $\log\left(\frac{X_n}{n}\right)$  is

$$Var\left(\log\left(\frac{X_n}{n}\right)\right) = \frac{1-p}{pn}$$