THE PML₂ LANGUAGE INTEGRATED PROGRAM VERIFICATION IN MI.



RODOLPHE LEPIGRE

MAX PLANCK INSTITUTE FOR SOFTWARE SYSTEMS - 29/11/2018

SEMANTICS AND IMPLEMENTATION OF AN EXTENSION OF ML FOR PROVING PROGRAMS



RODOLPHE LEPIGRE - 18/07/2017

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A PROGRAMMING LANGUAGE, WITH PROGRAM PROVING FEATURES

An ML-like programming language with:

- records, variants (constructors), inductive types,
- polymorphism, general recursion,
- a call-by-value evaluation strategy,
- effects (control operators),
- a light, Curry-style syntax and subtyping.

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For proving program, the type system is enriched with:

- programs as individuals (higher-order layer),
- an equality type $t \equiv u$ (observational equivalence),
- a dependent function type (typed quantification).
- Termination checking is required for proofs.

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EXAMPLE OF PROGRAM AND PROOF

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```
type rec nat = [Zero ; S of nat]

val rec add : nat \Rightarrow nat \Rightarrow nat =
  fun n m { case n { Zero \rightarrow m | S[k] \rightarrow S[add k m] } }

val add_Zero_m : \forallm\innat, add Zero m \equiv m =
  fun m { {} }
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val add Zero m : ∀m∈nat, add Zero m ≡ m =
  fun m { {} }
val rec add n Zero : ∀n∈nat, add n Zero ≡ n =
  fun n {
    case n {
      Zero \rightarrow {}
      S[p] \rightarrow add n Zero p
```

PART I	SPECIFIC TYPE CONSTRUCTORS
PART II	FORMALISATION OF THE SYSTEM AND SEMANTICS
PART III	SEMANTICAL VALUE RESTRICTION
PART IV	Local Subtyping and Choice Operators
PART V	Cyclic Proofs and Termination Checking

PART I

SPECIFIC TYPE CONSTRUCTORS

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PROPERTIES AS PROGRAM EQUIVALENCES

Examples of (equational) program properties:

```
- add (add m n) k \equiv add m (add n k) (associativity of add)

- rev (rev l) \equiv l (rev is an involution)

- map g (map f l) \equiv map (fun x {g (f x)}) l (map and composition)

- sort (sort l) \equiv sort l (sort is idempotent)
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Specification of a sorting function using predicates:

```
    sorted (sort l) ≡ true (sort produces a sorted list)
    permutation (sort l) l ≡ true (sort yields a permutation)
```

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$$\frac{\Gamma; \Xi \vdash t : \top}{\Gamma; \Xi \vdash t : u_1 \equiv u_2} \frac{\text{dec. proc. says "yes"}}{\Gamma; \Xi \vdash t : u_1 \equiv u_2}$$

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$$\frac{\Gamma, x : \top; \Xi, \mathbf{u}_1 \equiv \mathbf{u}_2 \vdash \mathbf{t} : C}{\Gamma, x : \mathbf{u}_1 \equiv \mathbf{u}_2; \Xi \vdash \mathbf{t} : C}$$

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- the *empty type* \perp otherwise.

Remark: cannot be complete since equivalence is undecidable.

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We need a form of typed quantification!

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$$\frac{\Gamma, x : A; \Xi \vdash t : B}{\Gamma; \Xi \vdash \lambda x. t : \forall x \in A.B}$$

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STRUCTURING PROOFS WITH DUMMY PROGRAMS

```
val rec add n Sm : \foralln m\innat, add n S[m] \equiv S[add n m] =
  fun n m {
     case n { Zero \rightarrow {} | S[k] \rightarrow add n Sm k m }
val rec add comm : \foralln m\innat, add n m \equiv add m n \equiv
  fun n m {
     case n {
       Zero \rightarrow add n Zero m
       S[k] \rightarrow add \ n \ Sm \ m \ k; add comm k m
```

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PART II

FORMALISATION OF THE SYSTEM AND SEMANTICS

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REALIZABILITY MODEL

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To construct the model, we need to:

- 1) give the syntax of programs and types,
- 2) define the interpretation of types as sets of terms (uses reduction),
- 3) define adequate typing rules,
- 4) deduce termination, type safety and consistency.

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Advantage: it is a very flexible approach.

CALL-BY-VALUE ABSTRACT MACHINE

Values
$$(\Lambda_i)$$
 $\nu, w := x \mid \lambda x.t \mid \{(l_i = \nu_i)_{i \in I}\} \mid C_k[\nu]$

Terms (Λ) $t, u := \nu \mid t u \mid \nu.l_k \mid [\nu \mid (C_i[x_i] \to t_i)_{i \in I}] \mid \mu \alpha.t \mid [\pi]t$

Stacks (Π) $\pi, \xi := \alpha \mid \epsilon \mid \nu.\pi \mid [t]\pi$ (evaluation context)

Processes $p, q := t * \pi$

CALL-BY-VALUE REDUCTION RELATION

$$\begin{array}{l} t\ u*\pi \ \succ \ u*[t]\pi \\ \\ \nu*[t]\pi \ \succ \ t*\nu.\pi \\ \\ \lambda x.t*\nu.\pi \ \succ \ t[x \coloneqq \nu]*\pi \\ \\ \{(l_i = \nu_i)_{i \in I}\}.l_k*\pi \ \succ \ \nu_k*\pi \\ \\ [C_k[\nu] \mid (C_i[x_i] \to t_i)_{i \in I}]*\pi \ \succ \ t_k[x_k \coloneqq \nu]*\pi \\ \\ \mu\alpha.t*\pi \ \succ \ t[\alpha \coloneqq \pi]*\pi \\ \\ [\pi]t*\xi \ \succ \ t*\pi \end{array} \right. \tag{$k \in I$)}$$

SUCCESSFUL COMPUTATION AND OBSERVATIONAL EQUIVALENCE

The abstract machine may either:

- successfully compute a result (it converges),
- fail with a runtime error or never terminate (it diverges).

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$$(\lambda x.x)$$
 {} * $\varepsilon \downarrow$

$$(\lambda x.x \ x) \ (\lambda x.x \ x) * \varepsilon \uparrow$$

$$(\lambda x.t).l_1 * \varepsilon \uparrow$$

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Types as Sets of Canonical Values

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MEMBERSHIP TYPES AND DEPENDENCY

We consider a new membership type $t \in A$ (with t a term, A a type).

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- and allows the introduction of dependency.

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The dependent function type $\forall x \in A.B$

- is defined as $\forall x.(x \in A \Rightarrow B)$,
- this is a form of relativised quantification scheme.

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SEMANTIC RESTRICTION TYPE AND EQUALITIES

We also consider a new restriction type $A \upharpoonright P$:

- it is build using a type A and a "semantic predicate" P,
- $[A \upharpoonright P]$ is equal to [A] if P is satisfied and to $[\bot]$ otherwise.
- We can use predicates like $t \equiv u$, $\neg P$ or $P \land Q$.

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Remark: refinement types $\{x \in A \mid P\}$ are encoded as $\exists x.(x \in A \upharpoonright P)$.

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What about λ -abstractions which bodies are terms?

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We define a completion operation $[\![A]\!] \mapsto [\![A]\!]^{\perp\!\perp\!\perp}$.

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$$\frac{\Gamma, x : A; \Xi \vdash_{val} x : A}{\Gamma; \Xi \vdash_{val} \lambda x : A} \qquad \frac{\Gamma, x : A; \Xi \vdash t : B}{\Gamma; \Xi \vdash_{val} \lambda x : A \Rightarrow B}$$

Theorem (adequacy lemma):

- if \vdash t : A is derivable then $t \in [\![A]\!]^{\perp \perp}$,
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We only need to check that our typing rules are "correct".

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Proof by induction on the typing derivation.

We only need to check that our typing rules are "correct".

For example
$$\frac{\vdash_{\text{val}} v : A}{\vdash v : A}$$
 is correct since $[\![A]\!] \subseteq [\![A]\!]^{\perp \perp}$.

$$\frac{\Gamma; \Xi \vdash_{\text{val}} \nu : A}{\Gamma; \Xi \vdash_{\text{val}} \nu : \forall X.A} x \notin \Gamma$$

$$\frac{X \vdash_{\text{val}} \nu : A}{\vdash_{\text{val}} \nu : \forall X.A}$$

$$\frac{X \vdash_{\text{val}} v : A}{\vdash_{\text{val}} v : \forall X.A}$$

We suppose $v \in \llbracket A[X := \Phi] \rrbracket$ for all Φ , and show $v \in \llbracket \forall X.A \rrbracket$.

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However we have $\bigcap_{\Phi} \llbracket A[X := \Phi] \rrbracket^{\perp \perp} \not\subseteq \llbracket \forall X.A \rrbracket^{\perp \perp} = \left(\bigcap_{\Phi} \llbracket A[X := \Phi] \rrbracket\right)^{\perp \perp}$.

PROPERTIES OF THE SYSTEM

Theorem (normalisation):

 $t : A \text{ implies } t * \varepsilon > \nu * \varepsilon \text{ for some value } \nu.$

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Theorem (safety for simple datatypes):

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Theorem (consistency):

there is no closed term $t: \bot$.

PART III

SEMANTICAL VALUE RESTRICTION

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DERIVED RULES FOR DEPENDENT FUNCTIONS

$$\frac{x : A \vdash t : B[\alpha \coloneqq x]}{\vdash_{val} \lambda x.t : \forall \alpha \in A.B}$$

$$\frac{\vdash t : \forall \alpha \in A.B \quad \vdash_{val} \nu : A}{\vdash t \nu : B[\alpha := \nu]}$$

DERIVED RULES FOR DEPENDENT FUNCTIONS

$$\frac{x : A \vdash t : B[\alpha \coloneqq x]}{\vdash_{val} \lambda x.t : \forall \alpha \in A.B} \qquad \qquad \frac{\vdash t : \forall \alpha \in A.B}{\vdash t \ \nu : B[\alpha \coloneqq \nu]}$$

$$\frac{ \begin{matrix} \vdash t : \forall \alpha \in A.B \\ \vdash t : \forall \alpha.(\alpha \in A \Rightarrow B) \end{matrix}^{Def}}{ \begin{matrix} \vdash t : \nu \in A \Rightarrow B[\alpha \coloneqq \nu] \end{matrix}^{\forall_e} \end{matrix} \xrightarrow{\begin{matrix} \vdash_{val} \nu : A \\ \vdash_{val} \nu : \nu \in A \end{matrix}^{\in_i}} \\ \vdash t : \nu : B[\alpha \coloneqq \nu]$$

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Value restriction breaks the compositionality of dependent functions.

```
// add_n_Zero : \forall n \in \text{nat}, add n Zero \equiv n add n Zero (add Zero S[Zero]) : add (add Zero S[Zero]) Zero \equiv add Zero S[Zero]
```

We replace
$$\frac{\vdash t : \forall \alpha \in A.B \quad \vdash_{val} \nu : A}{\vdash t \ \nu : B[\alpha \coloneqq \nu]} \quad \text{by} \quad \frac{\vdash t : \forall \alpha \in A.B \quad \vdash u : A \quad \vdash u \equiv \nu}{\vdash t \ u : B[\alpha \coloneqq u]}.$$

We replace
$$\frac{\vdash t : \forall \alpha \in A.B \qquad \vdash_{val} \nu : A}{\vdash t \nu : B[\alpha := \nu]}$$
 by $\frac{\vdash t : \forall \alpha \in A.B \qquad \vdash u : A \qquad \vdash u \equiv \nu}{\vdash t u : B[\alpha := u]}$.

This requires changing $\frac{\vdash_{val} \nu : A}{\vdash_{val} \nu : \nu \in A}$ into $\frac{\vdash t : A \qquad \vdash t \equiv \nu}{\vdash t : t \in A}$.

$$\begin{array}{lll} \text{We replace} & \frac{\vdash t : \forall \alpha \in A.B & \vdash_{\overline{val}} \nu : A}{\vdash t \ \nu : B[\alpha \coloneqq \nu]} & \text{by} & \frac{\vdash t : \forall \alpha \in A.B & \vdash u : A & \vdash u \equiv \nu}{\vdash t \ u : B[\alpha \coloneqq u]}. \\ \\ \text{This requires changing} & \frac{\vdash_{\overline{val}} \nu : A}{\vdash_{\overline{val}} \nu : \nu \in A} & \text{into} & \frac{\vdash t : A & \vdash t \equiv \nu}{\vdash t : t \in A}. \end{array}$$

Can this rule be derived in the system?

$$\begin{array}{lll} \text{We replace} & \frac{\vdash t : \forall \alpha \in A.B & \vdash_{val} \nu : A}{\vdash t \ \nu : B[\alpha \coloneqq \nu]} & \text{by} & \frac{\vdash t : \forall \alpha \in A.B & \vdash u : A & \vdash u \equiv \nu}{\vdash t \ u : B[\alpha \coloneqq u]}. \\ \\ \text{This requires changing} & \frac{\vdash_{val} \nu : A}{\vdash_{val} \nu : \nu \in A} & \text{into} & \frac{\vdash t : A & \vdash t \equiv \nu}{\vdash t : t \in A}. \end{array}$$

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Semantically, this requires that $v \in [\![A]\!]^{\perp \perp}$ implies $v \in [\![A]\!]$.

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The biorthogonal completion should not introduce new values.

The rule seems reasonable, but it is hard to justify semantically.

We do not have $v \in [\![A]\!]^{\text{lil}}$ implies $v \in [\![A]\!]$ in every realizability model.

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We extend the system with a new term constructor $\delta_{v,w}$ such that

$$\delta_{\nu,w} * \pi > \nu * \pi$$
 iff $\nu \not\equiv w$.

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Idea of the proof with $\mathbb{1} = \{p \mid p \downarrow\}$:

- We assume $v \notin [A]$ and show $v \notin [A]^{\perp \perp}$.

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- We need to find $\pi \in \llbracket A \rrbracket^{\perp}$ such that $\nu * \pi \uparrow$.

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- We can take $\pi = [\lambda x.\delta_{x,\nu}]\varepsilon$.

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- $-\ \nu * [\lambda x.\delta_{x,\nu}]\varepsilon > \lambda x.\delta_{x,\nu} * \nu \,.\, \varepsilon > \delta_{\nu,\nu} * \varepsilon \, \!\!\! \uparrow$

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- $\ \nu * [\lambda x.\delta_{x,\nu}] \varepsilon > \lambda x.\delta_{x,\nu} * \nu \,.\, \varepsilon > \delta_{\nu,\nu} * \varepsilon \, \!\!\! \uparrow$
- $w * [\lambda x.\delta_{x,y}] \varepsilon > \lambda x.\delta_{x,y} * w.\varepsilon > \delta_{w,y} * \varepsilon > w * \varepsilon \Downarrow \text{ if } w \in \llbracket A \rrbracket$

Well-defined Construction of Equivalence and Reduction

Problem: the definitions of (>) and (\equiv) are circular.

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We need to rely on a stratified construction of the two relations.

$$(\twoheadrightarrow_{i}) = (\gt) \cup \{(\delta_{\nu,w} * \pi, \nu * \pi) \mid \exists j < i, \nu \not\equiv_{j} w\}$$

$$(\equiv_{i}) = \{(t, u) \mid \forall j \leq i, \forall \pi, \forall \sigma, t \sigma * \pi \downarrow_{j} \Leftrightarrow u \sigma * \pi \uparrow_{j}\}$$

We then take

$$(\twoheadrightarrow) \ = \ \bigcup_{i \in \mathbb{N}} (\twoheadrightarrow_i) \qquad \text{ and } \qquad (\equiv) \ = \ \bigcap_{i \in \mathbb{N}} (\equiv_i).$$

PART IV

LOCAL SUBTYPING AND CHOICE OPERATORS

Rodolphe Lepigre 30 / 40

PML₂ is hard to implement for several reasons:

- it is a Curry-style language (quantifiers are not reflected in terms),
- many of its type constructors don't have "algorithmic contents".

RODOLPHE LEPIGRE 31 / 40

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$$\frac{\Gamma; \; \Xi \vdash \mathbf{t} : A \quad \alpha \notin FV(\Gamma; \; \Xi) \quad \; \Xi \vdash \mathbf{t} \equiv \nu}{\Gamma; \; \Xi \vdash \mathbf{t} : \forall \alpha. A} \qquad \qquad \frac{\Gamma; \; \Xi \vdash \mathbf{t} : \forall \alpha. A}{\Gamma; \; \Xi \vdash \mathbf{t} : A[\alpha \coloneqq u]}$$

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Solution: handle these connectives using *local subtyping*.

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Solution: handle these connectives using *local subtyping*.

We then obtain a type system with:

- one typing for each term (or value) constructor,
- one typing rule for each pair of type constructors (up to commutation).

CHOICE OPERATORS AND LOCAL SUBTYPING

We replace free variables with "choice operators":

- $\varepsilon_{x \in A}(t \notin B)$ denotes some $v \in [A]$ such that $[t[x := a]] \notin [B]^{\perp \perp}$ (if possible),
- and similar things are defined for types and other syntactic elements.
- Choice operators are interpreted using elements of the semantic domain.

RODOLPHE LEPIGRE 32 / 40

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We modify the system by:

- eliminating typing contexts (in favor of choice operators),
- introducing local subtyping judgments of the form $\Xi \vdash t : A \subseteq B$.
- They are interpreted as: "if $\Xi \vdash t : A$ holds, then $\Xi \vdash t : B$ also holds."

Rodolphe Lepigre 32 / 40

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Remark: $\Xi \vdash A \subseteq B$ can be encoded as $\Xi \vdash \varepsilon_{x \in A}(x \notin B) : A \subseteq B$.

$$\frac{\Xi \vdash \lambda x.t : A \Rightarrow B \subseteq C \quad \Xi, \epsilon_{x \in A}(t \notin B) \neq \Box \vdash t[x \coloneqq \epsilon_{x \in A}(t \notin B)] : B}{\Xi \vdash \lambda x.t : C} \Rightarrow_{\iota}$$

$$\frac{\Xi \vdash \lambda x.t : A \Rightarrow B \subseteq C \quad \Xi, \epsilon_{x \in A}(t \notin B) \neq \Box \vdash t[x \coloneqq \epsilon_{x \in A}(t \notin B)] : B}{\Xi \vdash \lambda x.t : C} \Rightarrow_{\iota}$$

$$\frac{\Xi \vdash \epsilon_{x \in A}(t \notin B) : A \subseteq C \quad \Xi \vdash \epsilon_{x \in A}(t \notin B) \neq \square}{\Xi \vdash \epsilon_{x \in A}(t \notin B) : C}_{Ax}$$

$$\frac{\Xi \vdash \lambda x.t : A \Rightarrow B \subseteq C \quad \Xi, \epsilon_{x \in A}(t \notin B) \neq \Box \vdash t[x \coloneqq \epsilon_{x \in A}(t \notin B)] : B}{\Xi \vdash \lambda x.t : C} \Rightarrow_{\iota}$$

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$$\frac{\Xi \vdash t : A \Rightarrow B \quad \Xi \vdash u : A}{\Xi \vdash t \ u : B} \Rightarrow_{e}$$

$$\frac{\Xi \vdash \lambda x.t : A \Rightarrow B \subseteq C \quad \Xi, \epsilon_{x \in A}(t \notin B) \neq \Box \vdash t[x \coloneqq \epsilon_{x \in A}(t \notin B)] : B}{\Xi \vdash \lambda x.t : C} \Rightarrow_{i}$$

$$\frac{\Xi \vdash \epsilon_{x \in A}(t \notin B) : A \subseteq C \quad \Xi \vdash \epsilon_{x \in A}(t \notin B) \neq \square}{\Xi \vdash \epsilon_{x \in A}(t \notin B) : C}_{Ax}$$

$$\frac{\Xi \vdash t : A \Rightarrow B \quad \Xi \vdash u : A}{\Xi \vdash t \ u : B} \Rightarrow_{e}$$

$$\frac{\Xi \vdash \nu : A \quad \Xi \vdash C_k[\nu] : [C_k : A] \subseteq B}{\Xi \vdash C_k[\nu] : B}_{+_i}$$

$$\frac{\Xi \vdash \nu : \{l_k : A; \cdots\}}{\Xi \vdash \nu . l_{\nu} : A} \times_{e}$$

$$\frac{\Xi \vdash t : A[X \coloneqq C] \subseteq B}{\Xi \vdash t : \forall X.A \subseteq B}_{\forall_t} \qquad \frac{\Xi \vdash t : A \subseteq B[X \coloneqq \epsilon_X(t \notin B)] \quad \Xi \vdash \nu \equiv t}{\Xi \vdash t : A \subseteq \forall X.B}$$

$$\frac{\Xi \vdash t : A[X \coloneqq C] \subseteq B}{\Xi \vdash t : \forall X.A \subseteq B}_{\forall_t} \qquad \frac{\Xi \vdash t : A \subseteq B[X \coloneqq \epsilon_X(t \not\in B)] \quad \Xi \vdash \nu \equiv t}{\Xi \vdash t : A \subseteq \forall X.B}$$

$$\frac{\Xi\,,\,u_1\equiv\,u_2\vdash t:A\subseteq B\quad\Xi\vdash\nu\equiv t}{\Xi\vdash t:A\upharpoonright u_1\equiv u_2\subseteq B}{}^{\upharpoonright_{\!t}}\qquad \frac{\Xi\vdash t:A\subseteq B\quad\Xi\vdash u_1\equiv u_2}{\Xi\vdash t:A\subseteq B\upharpoonright u_1\equiv u_2}{}^{\upharpoonright_{\!r}}$$

$$\frac{\Xi \vdash t : A[X \coloneqq C] \subseteq B}{\Xi \vdash t : \forall X.A \subseteq B} \forall_{t} \qquad \frac{\Xi \vdash t : A \subseteq B[X \coloneqq \varepsilon_{X}(t \notin B)] \quad \Xi \vdash \nu \equiv t}{\Xi \vdash t : A \subseteq \forall X.B}$$

$$\frac{\Xi,t\equiv \mathfrak{u}\vdash t:A\subseteq B}{\Xi\vdash t:\mathfrak{u}\in A\subseteq B} \xrightarrow{\Xi\vdash t\equiv \mathfrak{v}}_{\in_{t}} \quad \frac{\Xi\vdash t:A\subseteq B}{\Xi\vdash t:A\subseteq \mathfrak{u}\in B} \xrightarrow{\Xi\vdash t\equiv \mathfrak{v}}_{\in_{r}}$$

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$$\frac{\Xi,t\equiv \mathfrak{u}\vdash t:A\subseteq B}{\Xi\vdash t:\mathfrak{u}\in A\subseteq B} \xrightarrow{\Xi\vdash t\equiv \mathfrak{v}}_{\in_t} \quad \frac{\Xi\vdash t:A\subseteq B}{\Xi\vdash t:A\subseteq \mathfrak{u}\in B} \xrightarrow{\Xi\vdash t\equiv \mathfrak{v}}_{\in_r}$$

$$\frac{\Xi, w \neq \Box \vdash w : A_2 \subseteq A_1 \quad \Xi, w \neq \Box \vdash t \ w : B_1 \subseteq B_2 \quad \Xi \vdash t \equiv \nu}{\Xi \vdash t : A_1 \Rightarrow B_1 \subseteq A_2 \Rightarrow B_2}$$

(where
$$w = \varepsilon_{x \in A_2}(t \ x \notin B_2)$$
)

PART V

CYCLIC PROOFS AND TERMINATION CHECKING

RODOLPHE LEPIGRE 35 / 40

GENERAL RECURSION AND FIXPOINT UNFOLDING

Recursive programs rely on a term $\varphi a.v$ (binding a term in a value).

$$\varphi a.v * \pi \rightarrow v[a := \varphi a v] * \pi$$

$$\frac{\Xi \vdash \nu[\alpha \coloneqq \varphi \alpha. \nu] : A}{\Xi \vdash \varphi \alpha. \nu : A}_{\varphi}$$

GENERAL RECURSION AND FIXPOINT UNFOLDING

Recursive programs rely on a term $\varphi a.v$ (binding a term in a value).

$$\varphi a. \nu * \pi \quad \twoheadrightarrow \quad \nu[a \coloneqq \varphi a. \nu] * \pi \qquad \qquad \frac{\Xi \vdash \nu[a \coloneqq \varphi a. \nu] : A}{\Xi \vdash \varphi a. \nu : A} \varphi$$

Problem: we need to work with infinite proofs.

GENERAL RECURSION AND FIXPOINT UNFOLDING

Recursive programs rely on a term $\varphi a.v$ (binding a term in a value).

$$\varphi a.v * \pi \rightarrow v[a := \varphi a.v] * \pi$$

$$\frac{\Xi \vdash v[a := \varphi a.v] : A}{\Xi \vdash \varphi a.v : A} \varphi$$

Problem: we need to work with infinite proofs.

$$\frac{\forall \alpha \ (\Xi \vdash t : A)}{(\Xi \vdash t : A)[\alpha := \kappa]}^{Gen}$$

$$\frac{\left[\forall \alpha \ (\Xi \vdash t : A)\right]^{i}}{\vdots}$$

$$\frac{(\Xi \vdash t : A)[\alpha \coloneqq \varepsilon_{\alpha}(t \notin A)]}{\forall \alpha \ (\Xi \vdash t : A)}_{Ind[i]}$$

ORDINALS AND INDUCTIVE TYPES

$$\frac{\Xi \vdash t : A \subseteq B[X \coloneqq \mu_{\infty} X.B]}{\Xi \vdash t : A \subseteq \mu_{\infty} X.B}_{\mu_{\tau,\infty}}$$

ORDINALS AND INDUCTIVE TYPES

$$\frac{\Xi \vdash t : A \subseteq B[X \coloneqq \mu_{\infty} X.B]}{\Xi \vdash t : A \subseteq \mu_{\infty} X.B}_{\mu_{\tau,\infty}}$$

$$\frac{\Xi \vdash t : A \subseteq B[X \coloneqq \mu_{\upsilon}X.B] \quad \Xi \vdash \upsilon < \tau}{\Xi \vdash t : A \subseteq \mu_{\tau}X.B}$$

ORDINALS AND INDUCTIVE TYPES

$$\frac{\Xi \vdash t : A \subseteq B[X \coloneqq \mu_{\infty} X.B]}{\Xi \vdash t : A \subseteq \mu_{\infty} X.B}_{\mu_{r,\infty}}$$

$$\frac{\Xi \vdash t : A \subseteq B[X \coloneqq \mu_{\upsilon}X.B] \quad \Xi \vdash \upsilon < \tau}{\Xi \vdash t : A \subseteq \mu_{\tau}X.B}$$

$$\frac{\Xi\,;\,\tau>0\vdash t:A[X\coloneqq\mu_{\epsilon_{\theta<\tau}(t\in A[X:=\mu_{\theta}X.A])}X.A]\subseteq B\quad\Xi\vdash\nu\equiv t}{\gamma\,;\,\Xi\vdash t:\mu_{\tau}X.A\subseteq B}_{\mu_{t}}$$

EXAMPLE OF CYCLIC PROOF

Let us consider the "map" function: $\varphi m.\lambda f.\lambda l.[l|[] \rightarrow []|x::l \rightarrow f x::m f l]$.

It can be given either of the types:

- $\forall X.Y(X \Rightarrow Y) \Rightarrow List(X) \Rightarrow List(X)$,
- $\forall \alpha. \forall X. Y(X \Rightarrow Y) \Rightarrow List(\alpha, X) \Rightarrow List(X)$,
- $\forall \alpha. \forall X. Y(X \Rightarrow Y) \Rightarrow List(\alpha, X) \Rightarrow List(\alpha, X)$.

List(α , X) is defined as $\mu_{\alpha}L.[([\]):\{\}|(::):X\times L].$

Conclusion

FUTURE WORK

- 1) Practical issues (work in progress):
 - Composing programs that are proved terminating.
 - Extensible records and variant types (inference).
- 2) Toward a practical language:
 - Compiler using type information for optimisations.
 - Built-in types (int64, float) with their formal specification.
- **3)** Theoretical questions:
 - Can we handle more side-effects? (mutable cells, arrays)
 - What can we realise with (variations of) $\delta_{\nu,w}$?
 - Can we extend the system with quotient types?
 - Can we formalise mathematics in the system?

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Practical Subtyping for Curry-Style Languages https://lepigre.fr/files/publications/LepRaf2018a.pdf

PML₂: Integrated Program Verification in ML https://lepigre.fr/files/publications/Lepigre2018.pdf

Semantics and Implementation of an Extension of ML for Proving Programs https://lepigre.fr/files/publications/Lepigre2017PhD.pdf

> A Classical Realizability Model for a Semantical Value Restriction https://lepigre.fr/files/publications/Lepigre2016.pdf

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Thanks!