

Master in Informatics and Multimedia Engineering

Computer Vision and Mixed Reality

1st Project – Feature BasedFace Detection and Recognition for Augmented Reality

1. Goal

- a. Develop a computer vision application for face detection and recognition that allows the inclusion of virtual elements aligned with real objects.
- b. Familiarization with the OpenCV (**Open**-Source **C**omputer **V**ision) library for real-time application programming.

2. **Development**

a. Face detection

i. Using Haar Cascade Classifier

OpenCV "CascadeClassifier" method is based on the algorithm of object detection using Haar feature-based cascade classifiers proposed by Paul Viola and Michael Jones in their paper, "Rapid Object Detection using a Boosted Cascade of Simple Features" in 2001.

ii. Using OpenCV Deep Neural Network module (dnn)

OpenCV has a deep neural network module and include pre-trained Convolution Neural Network (CNN) for face detection. This network is based on the ResNet architecture with a Single Shot Detector (SSD) for the detection phase.

Use these algorithms to implement face detection in images collected in real time by a camera (see [1,2] for documentation and [3,4] as examples of implementation).

b. Face Recognition

i. Face database

Perform the acquisition of a face database from the students in the class (7 face images for each student). This set will be used in this project as the training and test sets. It may also be used a face database available on the Internet.

ii. Face normalization

Proceed with the normalization of the face images from the training set (rotation, scaling, selection) so that the faces comply with the format defined by MPEG-7 recommendation. That is, each face is represented by a monochrome image (256 levels) with 56 rows and 46 columns, with both eyes, right and left, perfectly aligned horizontally, and located in line 24, columns 16 and 31, respectively.

For eye detection, Haar Cascade classifier can also be used with proper XML classifiers files.

iii. Using EigenFaces

1. Compute the mean face vector μ (column vector with size of 1×2576) and the transformation matrix W_{pca} (with size of 2576×m), containing the first m

VARM – 1st Project Page 2

eigenfaces (where m can be a number between 10 and 20). Use the procedures presented in the slides of the course. View the m+1 obtained vectors by interpreting them as face images (eigenface) and prove that they form an orthogonal basis.

 Preform the projection of some of the training set faces on the face subspace and observe their reconstructions. Compute (and view) the error face (difference between the original face and its reconstruction). Show that the error face is orthogonal to the face subspace.

iv. Using FisherFaces

Repeat the previous points, but now using the algorithm called *fisherfaces*. Use the procedures presented in the slides of the course.

v. Classification

Develop a Nearest-Neighbor (NN) classifier based on the feature vectors resulting from the *m* projection coefficients. Consider an arbitrary number of classes, c (involving all students in the class or just a part of them).

Test the implemented classifiers using the test set (different from the training set).

- c. Combine real and virtual objects.
 - i. Virtual object normalization

Based on the alignment of section b.ii, normalize the virtual object that is intended to be superimposed on the identified face, for example, a hat, glasses, or other object of your choice.

ii. Adding with mask

Add to the image, using a mask.

Bibliography

- [1] https://docs.opencv.org/master/d6/d0f/group__dnn.html#ga33d1b39b53a891e98a654fdeabba22eb
- [2] https://github.com/opencv/opencv/wiki/Deep-Learning-in-OpenCV
- [3] https://opencv-python-

tutroals.readthedocs.io/en/latest/py tutorials/py objdetect/py face detection/py face detection.html

[4] - https://towardsdatascience.com/face-detection-models-which-to-use-and-why-d263e82c302c

VARM – 1st Project Page 3

Main numpy functions

Goal	numpy funtion	
	numpy.array	numpy.matrix
turn array into vector	flatten()	
construct a matrix from blocks (vectors or matrices)	vstack(), hstack(), tile(), concatenate()	bmat(), concatenate()
mean or average	mean()	
transpose of a	a.transpose() or a.T	
matrix multiply	dot()	*
compute eigenvalues and eigenvectors	linalg.eig()	
inverse of square matrix	linalg.inv()	
sort the matrix	sort(), argsort()	mat(sort())
change matrix dimensions	reshape()	

Main OpenCV function

Goal	OpenCV function(s)
Read an image	imread()
Show an image	imshow(), waitKey()
Read images from a camera or a video file	VideoCapture(); VideoCapture.get();
Read images from a camera of a video me	VideoCapture.read();
Add images	add(), addWeighted()
Multiply images	multiply()
Absolute difference	absDiff()
Apply a blur or a median filter	blur(), medianBlur()
Resize an image	resize()
Color conversions	cvtColor()
Contour extraction	Canny()
Image thresholding	threshold()

VARM – 1st Project Page 4