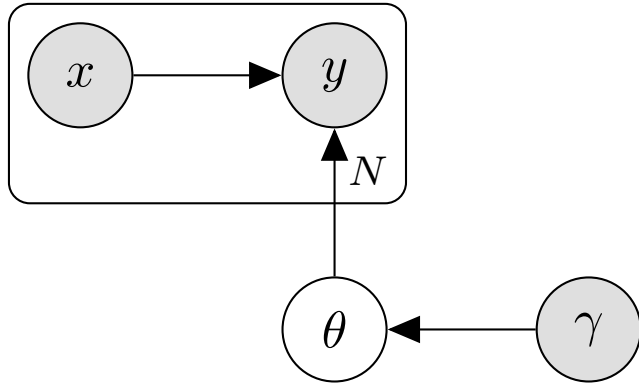


# Theoretical notes on setting priors for Bayesian regression models

# Setting priors for Bayesian regression models

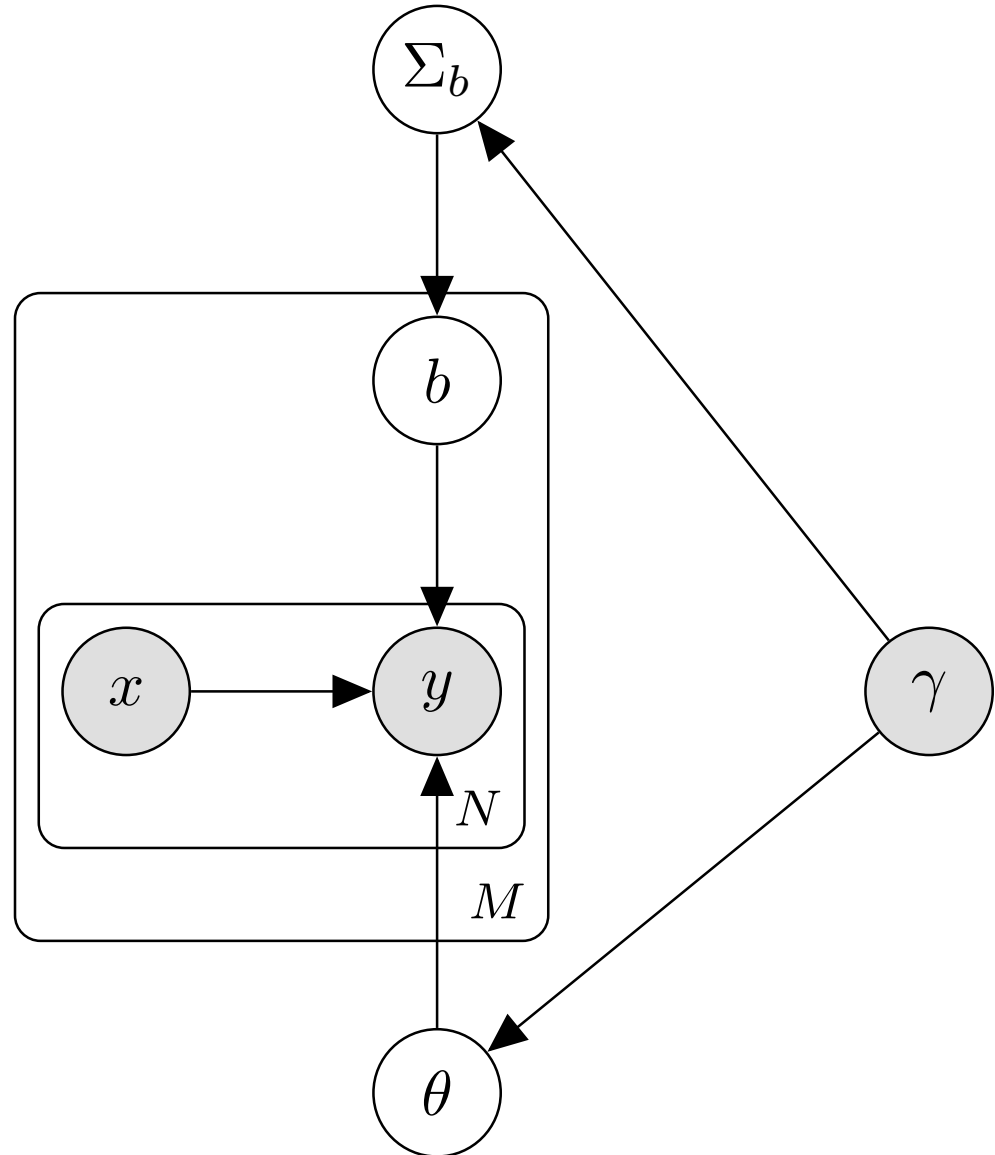
## Single-level model



**General principle:** focus on using priors that do not unduly bias the posterior with respect to the scientific question

(in some sense, use "just enough of a prior to get the Bayesian crank turning")

## Multi-level model




# "Flat" priors versus "uninformative" priors

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- Simple case: Bernoulli coin flip with parameter  $p \in [0,1]$
- Innocent-seeming choice: use a flat, or uniform prior

Probability  
density  
function


$$P(p) = \begin{cases} 1 & p \in [0,1] \\ 0 & \text{otherwise} \end{cases}$$

- But...suppose I prefer to think about my Bernoulli coin flip in terms of **odds ratios**  $r = \frac{p}{1-p}$
- What is the equivalent probability density on  $r$ ?
- To figure this out, you need to know the **change of variables formula for probability density functions**

# Change of variables for probability density

- Consider a continuous random variables  $X$ , and another continuous random variable  $Y = g(X)$
- How do we write the probability density function  $p_Y(Y)$  as a function of  $p_X(X)$ ? It turns out that:

$$p_Y(Y) = p_X(g(X)) \left| \frac{dX}{dY} \right|$$

- The rightmost term is required for properness of  $p_Y(Y)$

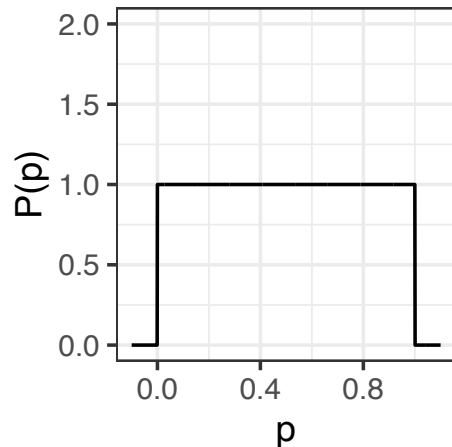
# Transforming Bernoulli success parameter

- Simple example: let  $p$  be uniform on  $[0,1]$  and  $q = p/2$

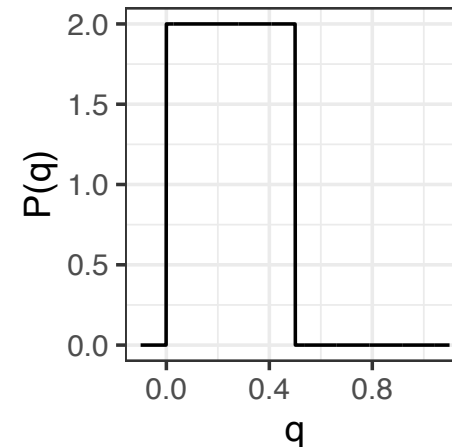
$$P_q(q) = P_p(p) \left| \frac{dp}{dq} \right|$$

$$\left| \frac{dp}{dq} \right| = 2$$

- so  $P_q(q) = 2P_p(p)$



$$\xrightarrow{q = p/2}$$



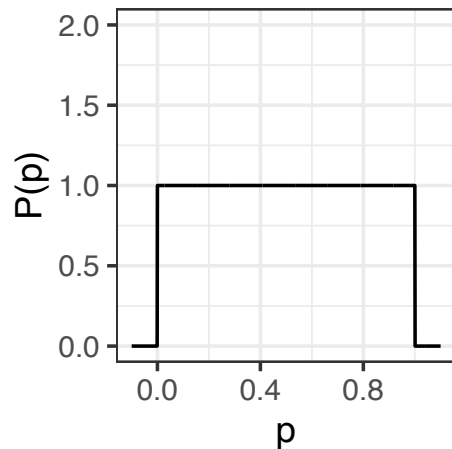
# Transforming Bernoulli success parameter

- Now consider the odds transform  $r = \frac{p}{1-p}$

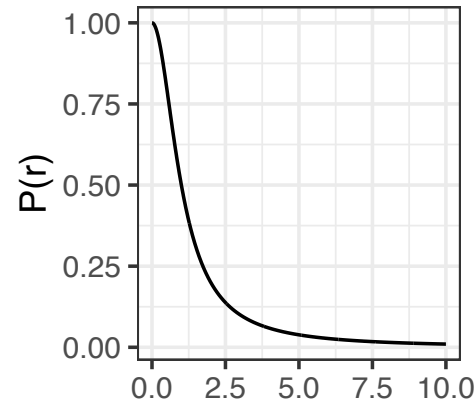
$$P_r(r) = P_p(p) \left| \frac{dp}{dr} \right|$$

$$\left| \frac{dp}{dr} \right| = \frac{1}{1+r^2}$$

- so  $P_q(q) = P_p(p)/(1+r^2)$



$$r = p/(1-p)$$



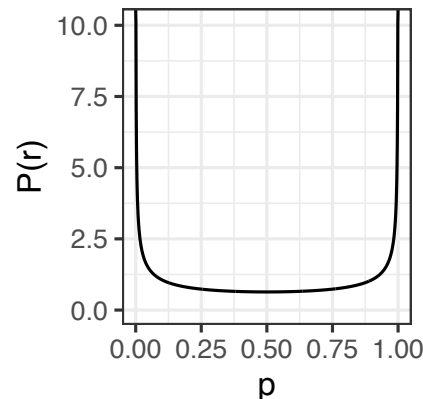
# The Jeffreys prior as "uninformative"

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- The **Jeffreys** prior is a principled choice of "uninformative" prior, in a technical sense: the mass assigned to any volume is parameterization-invariant
- We set  $\pi_J(\theta) \propto \sqrt{I(\theta)}$  –  $I(\theta)$  is the **Fisher information**:

$$I(\theta) = \mathbb{E} \left[ \left( \frac{\partial}{\partial \theta} \log p(x | \theta) \right)^2 \right]$$

- Note that this **depends on the likelihood function!**
- It turns out that for Bernoulli likelihood this leads to a Beta(0.5,0.5) prior



# Practical "uninformative" priors

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- Unfortunately, the Jeffreys prior is not always **proper**
- For example, consider Gaussian data. The Jeffreys prior turns out to be:

$$P(\mu) \propto 1$$

$$P(\sigma) \propto \frac{1}{\sigma}$$

- These results are still very useful!
- But in practice, we need to **bound** the priors to practical ranges
- Additionally, the Jeffreys prior is not even always **analytically tractable**
- Therefore, we often must be more heuristic in prior choice