Subtleties in mixed effects models

Let's talk linear mixed models

- Here is a key result from the Gauss-Markov theorem, which I mentioned earlier this semester:
 - If errors in a linear regression model are uncorrelated with equal variance and expectation zero, then ordinary least squares (OLS) is the best (minimum variance) linear unbiased estimator (BLUE) of the model coefficients β
- In the most basic linear regression setting IID normal errors – this assumption is met:
 - $\mathbf{y} = \beta \mathbf{X} + \epsilon$, $\epsilon \sim N(0, \sigma I)$, I being the identity matrix
- What about a mixed linear model?

$$y_{ij} = \beta X_{ij} + b_i Z_{ij} + \epsilon_{ij}, \ b \sim N(0, \Sigma_b), \ \epsilon \sim N(0, \sigma_\epsilon)$$

Correlated errors in linear mixed models

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- The stochastic part of y_{ij} is a linear combination of jointly Gaussian random variables (the b_i s and ϵ_{ij}) with weights given by the vector Z_{ij}
- Recall from early in the semester: a linear combination of Gaussian random variables is also Gaussian!
 - And the mean is the weighted sum of the means!
- This means that a linear mixed model with IID b's and ϵ 's can be re-expressed as a **simple linear regression**...

$$y_{ij} = \beta X_{ij} + \epsilon_{ij}$$

• ...with correlated intra-group Gaussian errors $\{e_{i.}\}$

Correlated errors in linear mixed models

$$y_{ij} = \beta X_{ij} + \epsilon_{ij}$$
 with correlated mean-zero errors $\{\epsilon_{ij}\}$

An interesting (and possibly puzzling) consequence:

$$\hat{\beta} = (X^{\top}X)^{-1}X^{\top}Y$$
 (OLS regression equation)
$$E[\hat{\beta}] = (X^{\top}X)^{-1}X^{\top}E[Y] \qquad \text{(linearity of the expectation)}$$

$$= (X^{\top}X)^{-1}X^{\top}X\beta \qquad \text{(errors are mean-zero)}$$

$$= \beta \qquad \rightarrow \text{OLS is unbiased!!!}$$

 We'll now look at OLS versus mixed-linear model estimation of a simple simulated example where the true generative process is a mixed linear model

```
Linear mixed model fit by REML ['lmerMod']
Formula: value ~ 1 + condition + (1 | participant)
  Data: df.slopes
REML criterion at convergence: 83.6
Scaled residuals:
   Min
             10 Median
                                   Max
-3.5808 -0.3184 0.0130 0.4551 2.0913
Random effects:
            Name
                        Variance Std.Dev.
Groups
participant (Intercept) 0.0000
                                 0.0000
Residual
                        0.4512 0.6717
Number of obs: 40, groups: participant, 20
Fixed effects:
             Estimate Std. Error t value
(Intercept) 0.190524
                      0.150197
condition2 -0.001941 0.212411 -0.009
Correlation of Fixed Effects:
           (Intr)
condition2 -0.707
optimizer (nloptwrap) convergence code: 0 (OK)
boundary (singular) fit: see help('isSingular')
```

"A common issue with "maximal" linear mixed-effects models is that not all random effects can be estimated. These estimation issues are noted by warnings from lme4 such as boundary (singular) fit or Model failed to converge. These warnings indicate that the model is too complex for the data at hand."

It is very common for overfitted mixed models to result in singular fits. Technically, singularity means that the random effects variance-covariance matrix is of *less than full rank*.

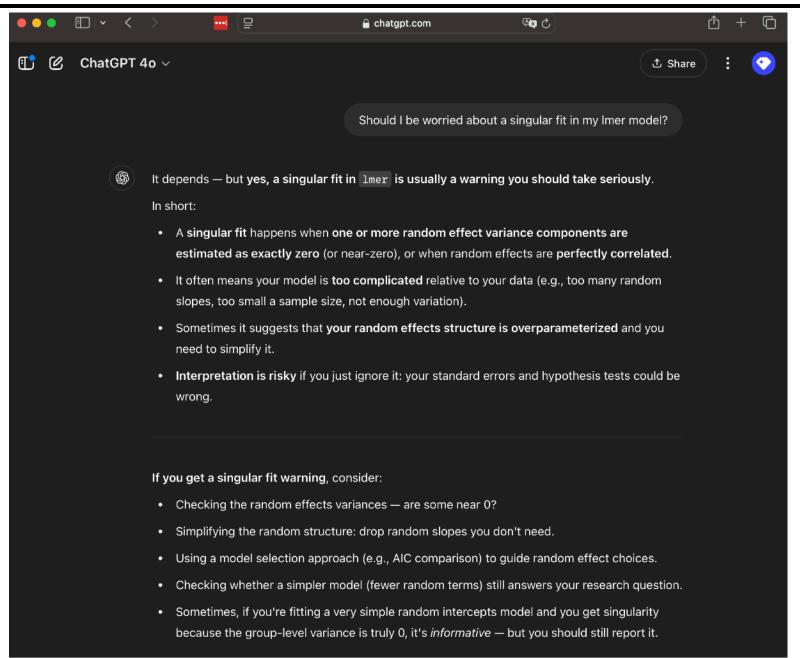
[...]

At present there are a variety of strong opinions about how to resolve such problems, which are sometimes conflated with the general problem of how to decide on the appropriate complexity of the random-effects component of a model. Briefly:

[...]

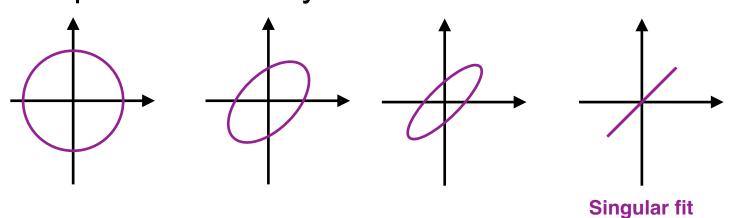
• Barr et al. (2013) suggest always starting with the maximal model (i.e. the most random-effects component of the model that is *theoretically* identifiable given the experimental design) and then dropping terms when singularity or non-convergence occurs (please see the paper for detailed recommendations ...)

The word singular does not appear in Barr et al. 2013!!!



The generally correct thing to do about singular fits

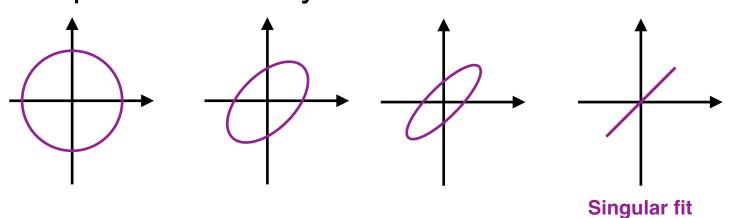
- Remember, a mixed effects model, the random effects b are assumed to be drawn from a multivariate normal distribution: $b \sim N(0, \Sigma_b)$
- A "singular fit" simply means that the random-effects covariance matrix Σ_b is **less than full rank**
- That is, the distribution of b lives on a **subspace** of the vector space defined by Z



This may well maximize the data likelihood – so leave it alone!

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 If this maximizes the data likelihood, then it maximizes the data likelihood – so leave it alone!