# **Double Q-Learning**

Yaroslav Ganin

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Reinforcement Learning class (COMP 767)

### Optimal action-value function and Q-Learning

We are interested in finding the solution to the **Bellman equation**:

$$Q^*(s, a) = \sum_{s'} P_{sa}^{s'} \left( R_{sa}^{s'} + \gamma \max_b Q^*(s', b) \right)$$

One possible option – Q-learning

$$Q_{t+1}(s, a) \leftarrow Q_t(s, a) + lpha \left(r + \gamma \max_b Q_t(s', b) - Q_t(s, a)
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Major problem

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- Q-Learning **overestimates** Q\*
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## Why is that?

 $Q_t$  is a **noisy approximation** of  $Q^*$ .

In presence of noise we get:

$$\mathbb{E}\left[\max_{b}Q_{t}(s',b)
ight] > \max_{b}\mathbb{E}\left[Q_{t}(s',b)
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That's because Q-Learning is based on a *so-called* **single estimator** for each variable (as opposed to the **double estimator** proposed in the paper).

## The Single Estimator

Quite often (also in Q-Learning) we have a set of RVs  $Z = \{Z_1, \dots, Z_M\}$  and we want to estimate:

$$\max_{i} \mathbb{E}[Z_i]$$

Say, we have a set of **unbiased** estimators  $\{\mu_1, \dots, \mu_M\}$ , s.t.  $\mathbb{E}[\mu_i] = \mathbb{E}[Z_i]$ . Then an obvious estimator is

$$\max_i \mu_i pprox \max_i \mathbb{E}[Z_i]$$

Turns out to be positively biased! From Jensen's inequality

$$\mathbb{E}\left[\max_{i}\mu_{i}\right] \geq \max_{i}\mathbb{E}[\mu_{i}] = \max_{i}\mathbb{E}[Z_{i}]$$

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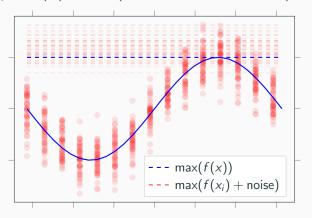
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So, often  $\max_i \mu_i > \max_i \mathbb{E}[Z_i]$ .

## The Single Estimator (cont.)

#### Illustration:

- Let  $Z_i$  be deterministic  $f(x_i)$  (blue curve)
- Let  $\mu_i = f(x_i) + \text{noise}$  (an unbiased estimate of  $Z_i$ )



### The Double Estimator

We tackle the overestimation by introducing **two sets of** estimates:  $\mu^A = \{\mu_1^A, \dots, \mu_M^A\}$  and  $\mu^B = \{\mu_1^B, \dots, \mu_M^B\}$ :

- ullet Obtained on two non-overlapping subsets of the samples  $\Rightarrow$  independent
- ullet Both are unbiased:  $\mathbb{E}\left[\mu_i^A\right] = \mathbb{E}\left[\mu_i^B\right] = \mathbb{E}[Z_i]$

### The proposed estimator:

- Select maximizing argument from one set:  $a^* = \arg \max_i \mu_i^A$
- Plug it into the other set:  $\mu_{a^*}^B \approx \max_i \mathbb{E}[Z_i]$

### The Double Estimator underestimates

#### Lemma

Let  $\mathcal{M} = \{j \mid \mathbb{E}[Z_j] = \max_i \mathbb{E}[Z_i]\}$  be the set of elements that maximize the expected values. Let  $a^*$  be an element that maximizes  $\mu^A$ . Then

$$\mathbb{E}\left[\mu_{a^*}^B\right] = \mathbb{E}\left[Z_{a^*}\right] \le \max_i \mathbb{E}[Z_i].$$

Furthermore, the inequality is strict **iff**  $\mathbb{P}[a^* \notin \mathcal{M}] > 0$ .

This lemma tells us that the Double Estimator has a **negative** bias (underestimates).

#### **Proof:**

The maximizer  $a^*$  can be either in  $\mathcal{M}$  or not in  $\mathcal{M}$  (obviously):

Consider  $a^* \in \mathcal{M}$ , then

$$\mathbb{E}\left[\mu_{a^*}^B \mid a^* \in \mathcal{M}\right] = \mathbb{E}\left[\sum_{i} \mu_i^B \, \mathbb{1}\{a^* = i\} \mid a^* \in \mathcal{M}\right]$$

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Now consider  $a^* \notin \mathcal{M}$  and choose  $j \in \mathcal{M}$ , then

$$\mathbb{E}\left[\mu_{a^*}^{\mathcal{B}} \mid a^* \notin \mathcal{M}\right] = \mathbb{E}\left[Z_{a^*} \mid a^* \notin \mathcal{M}\right] < \mathbb{E}\left[Z_j\right] = \max_i \mathbb{E}[Z_i]$$

Let's combine the expectations above

$$\begin{split} \mathbb{E}\left[\mu_{a^*}^B\right] &= \mathbb{P}\left[a^* \in \mathcal{M}\right] \, \mathbb{E}\left[\mu_{a^*}^B \,|\, a^* \in \mathcal{M}\right] + \\ &\quad \mathbb{P}\left[a^* \not\in \mathcal{M}\right] \, \mathbb{E}\left[\mu_{a^*}^B \,|\, a^* \not\in \mathcal{M}\right] \\ &= \mathbb{P}\left[a^* \in \mathcal{M}\right] \, \max_i \mathbb{E}[Z_i] + \mathbb{P}\left[a^* \not\in \mathcal{M}\right] \, \mathbb{E}\left[\mu_{a^*}^B \,|\, a^* \not\in \mathcal{M}\right] \\ &\leq \mathbb{P}\left[a^* \in \mathcal{M}\right] \, \max_i \mathbb{E}[Z_i] + \mathbb{P}\left[a^* \not\in \mathcal{M}\right] \, \max_i \mathbb{E}[Z_i] \\ &= \max_i \mathbb{E}[Z_i] \end{split}$$

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### Double Q-Learning

### **Algorithm** Double Q-Learning

```
1: Initialize Q^A(s,a) and Q^B(s,a), \forall s \in \mathcal{S}, a \in \mathcal{A}(s)
 2: for each episode do
        Initialize s
 3.
        for each step of the episode do
 4:
 5.
            Choose a from s using policy derived from Q_A and Q_B
            Take action a, observe r, s'
 6:
           Toss a fair coin
 7.
            if heads then
 8:
                 Q^A(s,a) \leftarrow Q^A(s,a) + \alpha \left(r + \gamma Q^B(s', \operatorname{arg\,max}_a Q^A(S',a)) - Q^A(s,a)\right)
 g.
            else
10:
                 Q^{B}(s, a) \leftarrow Q^{A}(s, a) + \alpha \left(r + \gamma Q^{A}(s', \arg\max_{a} Q^{B}(S', a)) - Q^{B}(s, a)\right)
11:
            end if
12:
            s \leftarrow s'
13.
        end for
14:
15: end for
```