

$0 \leq \xi \leq 1$:

$$0 \leq X_\xi \leq \boxed{\frac{1}{1-\gamma}}$$

$$\text{up } 1-\gamma, \quad X_\xi \leq \frac{\varepsilon}{2}$$

$$\exists \gamma > 0: \mathbb{E}[X_\xi] \leq \varepsilon$$

$$G_\xi = \{X_\xi \leq \frac{\varepsilon}{2}\}$$

$$\forall \xi \in [0, 1]: \quad \mathbb{E}[X_\xi] = \mathbb{E}[X_\xi \mathbb{I}_{G_\xi}] + \mathbb{E}[X_\xi \mathbb{I}_{G_\xi^c}]$$

$(P[G_\xi^c]) \leq \zeta$

$$X_\xi \mathbb{I}_{G_\xi} \leq \frac{\varepsilon}{2}$$

$$X_\xi \mathbb{I}_{G_\xi^c} \leq \frac{1}{1-\gamma} \mathbb{I}_{G_\xi^c}$$

$$\Rightarrow \mathbb{E}[X_\xi] \leq \mathbb{E}\left[\frac{\varepsilon}{2}\right] + \mathbb{E}\left[\frac{1}{1-\gamma} \mathbb{I}_{G_\xi^c}\right]$$

$$= \frac{\varepsilon}{2} + \underbrace{\frac{1}{1-\gamma} \mathbb{P}(G_\xi^c)}_{\leq \zeta} \leq \frac{\varepsilon}{2} + \frac{1}{1-\gamma} \cdot \zeta$$

$$\zeta = (1-\gamma) \frac{\varepsilon}{2} \Rightarrow \mathbb{E}[X_\xi] \leq \varepsilon.$$

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$$|A| = O(1)$$

Fixed-horizon

local planning

$$H > 0$$

U* realizability

Gellert Weisz

Thm: \exists planer P s.t.

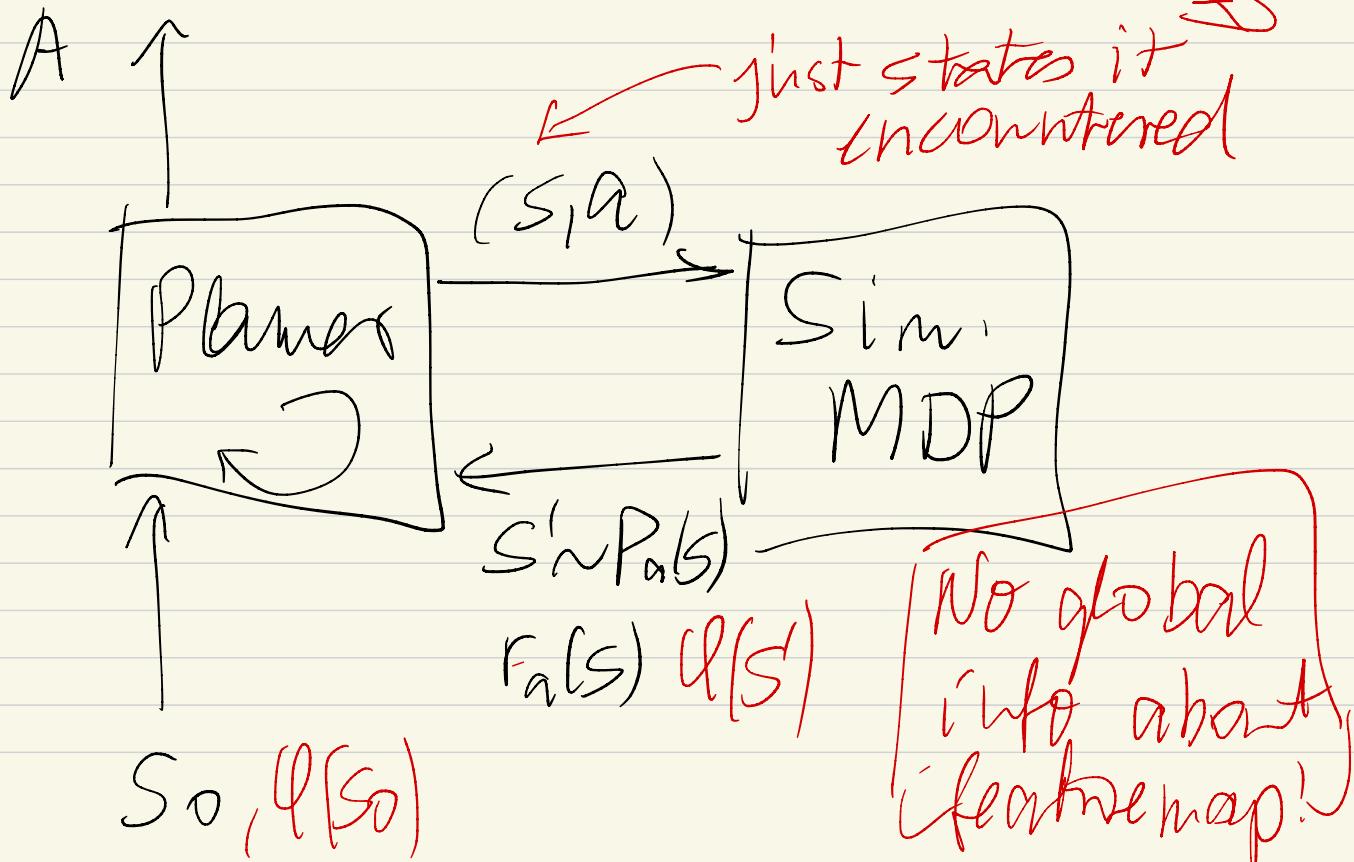
5- suboptimal policy w. local

$$\text{planj} \quad \# q = \text{poly}\left(\left(\frac{dH}{\delta}\right)^A, B\right)$$

Compute cost = ?

$$V_h^*(s) = \ell(s)^T \theta_*$$

$$\|\theta_k\|_2 \leq B$$



Idea of Alg:

$$\Theta \subseteq \mathbb{R}^d$$

$$[\Theta = \{\theta \in \mathbb{R}^d \mid \|\theta\|_2 \leq B\}]$$



Phases:

$$s_0 \in S$$

$$\theta_* \in \Theta$$

$$\boxed{\hat{\theta} = \operatorname{argmax}_{\theta \in \Theta} \varphi_1(s_0)^T \theta}$$

$$V_1^*(s) = \varphi_1(s)^T \theta_*$$

local consistency

$$V_h^*(s) = r_a(s) + \langle P_a(s), V_{h+1}^* \rangle$$

B.O.E.

$$V_h^*(s) = \max_a r_a(s) + \langle P_a(s), V_{h+1}^* \rangle$$

$$V_{H+1}^* = 0$$

$$\varphi_h(s)^T \hat{\theta} \stackrel{?}{=} \max_a r_a(s) + \sum_{s'} \underbrace{\langle P_a(s) \varphi_{h+1}(s'), \hat{\theta} \rangle}_{P_a(s) \varphi_{h+1} \in \mathbb{R}^d}$$

$$P_a(s) \varphi_{h+1} \in \mathbb{R}^d$$

$$= \max_a r_a(s) + \langle P_a(s) \varphi_{h+1}, \hat{\theta} \rangle$$

$$\boxed{\Delta(\theta, h, s, a) = \underbrace{r_a(s) + \langle P_a(s) \varphi_{h+1}, \theta \rangle - \varphi_h(s)^T \theta}_{\Delta(\theta^*, h, s, a) = 0}}$$

Loc. cons: $\forall h, s \quad \exists a \quad \text{s.t. } \Delta(\theta^*, h, s, a) = 0.$

$$A_{h,s}$$

$$\prod_a \Delta(\theta^*, h, s, a) = 0$$

$$\prod_{a \in A} \Delta(\theta, h, s, a) = 0 \quad \text{linear in } f(\theta)$$

$${}^v\theta^2 = \theta \theta^T = (\theta_i \theta_j)_{i,j}$$

$${}^n\theta^3 = \theta \otimes \theta \otimes \theta = (\theta_i \theta_j \theta_k)_{i,j,k}$$

$$\Delta(\theta, h, s, a) = \underbrace{\langle r_a(s)(P_a(s)U_{h+} - U_h(s)) \rangle}_{V_a} \overline{1 \theta}$$

$$\prod_a \langle V_a, U_a \rangle =$$

$$= \langle \otimes V_a, \otimes U_a \rangle \xrightarrow{f(s, h)}$$

$$\prod_a \Delta(\theta, h, s, a) = \langle \otimes_a \overbrace{r_a(s)(P_a(s)U_{h+} - U_h(s))}^{g(\theta)}, g(\theta) \rangle \xrightarrow{(\overline{1 \theta})^{\otimes A}}$$

$$V^{\otimes A} = \bigoplus_{\alpha=1}^A V$$

Loc. cons:

$$\Theta = \langle$$

$$\langle \otimes_{\alpha} r_{\alpha}(s) P_{\alpha}(s) \ell_{n+1} - \ell_n(s) \rangle \Theta \rangle \in \mathbb{R}^{(d+1)^A}$$

$\hat{\theta}$ given

$$S' \Rightarrow S_0$$

$$\langle \ell_n(s), \hat{\theta} \rangle = r_{\alpha}(s) + \langle P_{\alpha}(s) \ell_{n+1}, \hat{\theta} \rangle$$

$$\langle r_{\alpha} \rangle$$

take it.

$$S := S' - P_{\alpha}(s)$$

FAIL

$$\ell_n(s_0)^T \hat{\theta}$$

verifying this!



Dealing with noise?

→ Flnder dnn.