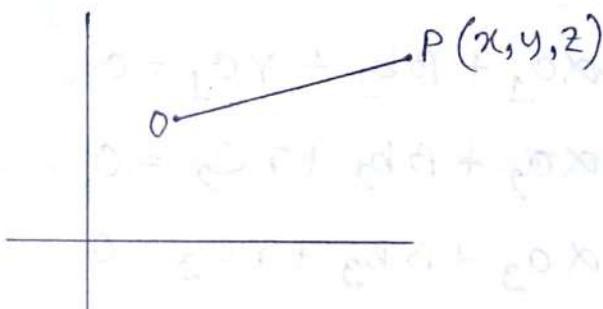


04-02-2018 : 1E : Sunday

A vector is a quantity having both magnitude and direction such as displacement, velocity, force, and acceleration.



$$\vec{OP} = x\hat{i} + y\hat{j} + z\hat{k}$$

→ If \vec{a}, \vec{b} and \vec{c} are three vectors, $\alpha\vec{a} + \beta\vec{b} + \gamma\vec{c}$ is called linear combination.

→ If \vec{a}, \vec{b} and \vec{c} is linearly dependent, $\alpha\vec{a} + \beta\vec{b} + \gamma\vec{c} = 0$ whence, $\alpha, \beta, \gamma \neq 0$

→ If \vec{a}, \vec{b} , and \vec{c} is linearly independent, $\alpha\vec{a} + \beta\vec{b} + \gamma\vec{c} = 0$ whence, $\alpha = \beta = \gamma = 0$

→ If \vec{a}, \vec{b} and \vec{c} is linearly dependent, they are coplanar means they will be in one plane.

→ If \vec{a}, \vec{b} and \vec{c} is linearly independent, they are non-coplanar.

Let,

$$\vec{a} = (a_1, a_2, a_3)$$

$$\vec{b} = (b_1, b_2, b_3)$$

$$\vec{c} = (c_1, c_2, c_3)$$

Now,

$$\alpha\vec{a} + \beta\vec{b} + \gamma\vec{c} = 0$$

$$\Rightarrow \alpha = (\alpha_1, \alpha_2, \alpha_3) + \beta (\beta_1, \beta_2, \beta_3) + \gamma (\gamma_1, \gamma_2, \gamma_3) = (0, 0, 0)$$

$$\Rightarrow (\alpha_1 + \beta \beta_1 + \gamma \gamma_1, \alpha_2 + \beta \beta_2 + \gamma \gamma_2, \alpha_3 + \beta \beta_3 + \gamma \gamma_3) = (0, 0, 0)$$

equalling the co-efficient of each axis,

$$\alpha_1 + \beta \beta_1 + \gamma \gamma_1 = 0$$

$$\alpha_2 + \beta \beta_2 + \gamma \gamma_2 = 0$$

$$\alpha_3 + \beta \beta_3 + \gamma \gamma_3 = 0$$

$$\begin{vmatrix} \alpha_1 & \beta_1 & \gamma_1 \\ \alpha_2 & \beta_2 & \gamma_2 \\ \alpha_3 & \beta_3 & \gamma_3 \end{vmatrix} = \begin{vmatrix} \alpha \\ \beta \\ \gamma \end{vmatrix} = 0$$

- If the determinants of $\begin{vmatrix} \alpha_1 & \beta_1 & \gamma_1 \\ \alpha_2 & \beta_2 & \gamma_2 \\ \alpha_3 & \beta_3 & \gamma_3 \end{vmatrix}$ is zero,

then the solution will be non-zero and $(\vec{\alpha}, \vec{\beta}, \vec{\gamma})$ will be dependent.

- If the determinants of $\begin{vmatrix} \alpha_1 & \beta_1 & \gamma_1 \\ \alpha_2 & \beta_2 & \gamma_2 \\ \alpha_3 & \beta_3 & \gamma_3 \end{vmatrix}$ is non-zero,

then the solution will be zero and $(\vec{\alpha}, \vec{\beta}, \vec{\gamma})$ will be independent.

- If the no. of variable > the no. of equation, the solution is non-zero

- If the no. of variable = the no. of equation, the solution is zero.

→ Show that the three vectors $\vec{A} = 2\hat{i} + \hat{j} - 3\hat{k}$, $\vec{B} = \hat{i} - 4\hat{k}$ and $\vec{C} = 4\hat{i} + 3\hat{j} - \hat{k}$ are linearly dependent. Determine the relation between them.

Solution:

$$\vec{A} = 2\hat{i} + \hat{j} - 3\hat{k}$$

$$\vec{B} = \hat{i} - 4\hat{k}$$

$$\vec{C} = 4\hat{i} + 3\hat{j} - \hat{k}$$

$$\begin{vmatrix} 2 & 1 & -3 \\ 1 & 0 & -4 \\ 4 & 3 & -1 \end{vmatrix} = 2(0+12) - 1(-1+16) - 3(3-0)$$
$$= 24 - 15 - 9 = 0$$

As the determinant is zero, the three vectors will be linearly dependent.

$$\alpha\vec{A} + \beta\vec{B} + \gamma\vec{C} = 0$$

$$\Rightarrow \alpha(2, 1, -3) + \beta(1, 0, -4) + \gamma(4, 3, -1) = 0$$

~~$$\Rightarrow (2\alpha + \beta + 4\gamma, \alpha + 3\gamma, -3\alpha - 4\beta - \gamma)$$~~

~~$$\Rightarrow (2\alpha + \beta + 4\gamma, \alpha + 3\gamma, -3\alpha - 4\beta - \gamma) = (0, 0, 0)$$~~

which implies,

$$2\alpha + \beta + 4\gamma = 0$$

$$\alpha + 3\gamma = 0$$

$$-3\alpha - 4\beta - \gamma = 0$$

the coefficient matrix of the system.

$$C = \left| \begin{array}{ccc|c} 2 & 1 & 4 & 1 \\ 1 & 0 & 3 & 2 \\ -3 & -4 & -1 & -3 \end{array} \right| \xrightarrow{R_{21}} \left| \begin{array}{ccc|c} 1 & 0 & 3 & 1 \\ 2 & 1 & 4 & 2 \\ -3 & -4 & -1 & -3 \end{array} \right|$$

$$\xrightarrow{R_{21}(-2)} \left| \begin{array}{ccc|c} 1 & 0 & 3 & 1 \\ 0 & 1 & -2 & 0 \\ 0 & -4 & 8 & 0 \end{array} \right| \xrightarrow{R_{32}(4)} \left| \begin{array}{ccc|c} 1 & 0 & 3 & 1 \\ 0 & 1 & -2 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right|$$

This is the echelon form of the matrix.
hence the rank of the matrix, $P(C) = 2$
since, $P(C) < n$, the above system has
infinitely many solutions and the number
of free variable = $n - P(C) = 3 - 2 = 1$

Let, ~~α~~ γ be the free variable. and $\gamma = k$
where k is any integer number.
the equivalent system.

$$\alpha + 3\gamma = 0 \quad \therefore \alpha = -3k$$

$$\beta - 2\gamma = 0 \quad \therefore \beta = 2k$$

$$\gamma = k$$

$$\therefore -3k \vec{A} + 2k \vec{B} + k \vec{C} = 0$$

$$\therefore 3\vec{A} - 2\vec{B} - \vec{C} = 0$$

05-02-2018 : 2A : Monday

→ Dot and Cross product :

- Dot product :

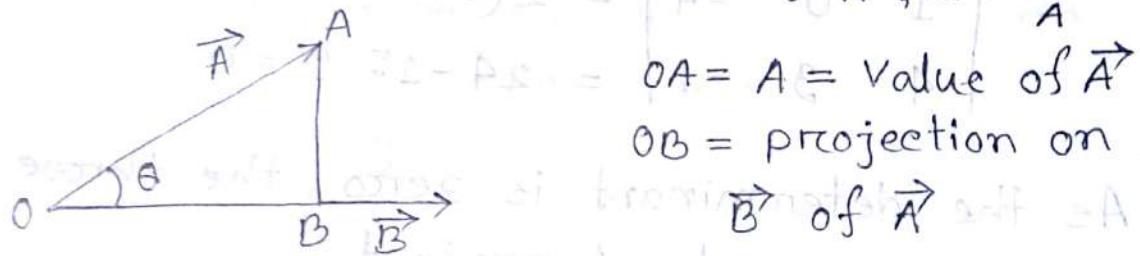
The dot product of two vectors \vec{A} and \vec{B} , denoted by $\vec{A} \cdot \vec{B}$, is defined as the product of the magnitudes of \vec{A} and \vec{B} and the cosine of the angle θ between them.

$$\vec{A} \cdot \vec{B} = AB \cos \theta$$

$$\vec{A} \cdot \vec{B} = \vec{B} \cdot \vec{A}$$

Unit vector :

A unit vector is a vector having unit magnitude. If \vec{A} is a vector with magnitude and $A \neq 0$, then the unit vector of \vec{A} , $\hat{a} = \frac{\vec{A}}{A}$



$$\cos \theta = \frac{OB}{OA} \Rightarrow OB = OA \cos \theta \Rightarrow OB = A \cos \theta$$

$$\vec{A} \cdot \vec{B} = AB \cos \theta$$

$$\Rightarrow \vec{A} \cdot \vec{B} = OB \cdot B$$

$$\Rightarrow OB = \frac{\vec{A} \cdot \vec{B}}{B}$$

$$\Rightarrow OB = \vec{A} \cdot \frac{\vec{B}}{B}$$

$$\Rightarrow OB = \vec{A} \cdot \vec{B}$$

projection of \vec{A} on $\vec{B} = \vec{A} \cdot \vec{B} = \vec{A} \cdot \frac{\vec{B}}{|\vec{B}|}$

projection of \vec{B} on $\vec{A} = \vec{B} \cdot \vec{A} = \vec{B} \cdot \frac{\vec{A}}{|\vec{A}|}$

unit components of any vector in the x-axis

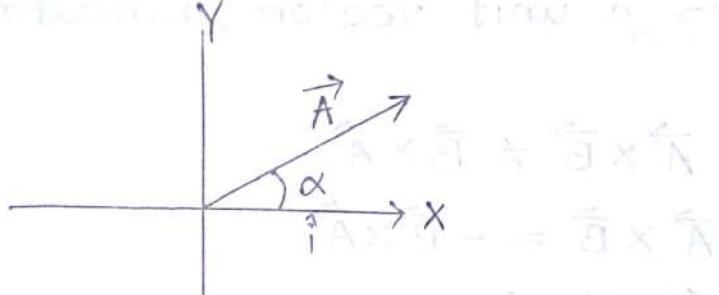
\hat{i} = unit vector along x-axis

\hat{j} = unit vector along y-axis

\hat{k} = unit vector along z-axis

$$\hat{i} \cdot \hat{i} = \hat{j} \cdot \hat{j} = \hat{k} \cdot \hat{k} = 1$$

$$\hat{i} \cdot \hat{j} = \hat{j} \cdot \hat{i} = \hat{j} \cdot \hat{k} = \hat{k} \cdot \hat{j} = \hat{k} \cdot \hat{i} = \hat{i} \cdot \hat{k} = 0$$



$$\vec{A} \cdot \hat{i} = A |\hat{i}| \cos\alpha = A \cos\alpha$$

$$\therefore \cos\alpha = \frac{\vec{A} \cdot \hat{i}}{A} = \vec{a} \cdot \hat{i}$$

$$\vec{A} \cdot \hat{j} = A |\hat{j}| \cos\beta = A \cos\beta$$

$$\therefore \cos\beta = \frac{\vec{A} \cdot \hat{j}}{A} = \vec{a} \cdot \hat{j}$$

$$\vec{A} \cdot \hat{k} = A |\hat{k}| \cos\gamma = A \cos\gamma$$

$$\therefore \cos\gamma = \frac{\vec{A} \cdot \hat{k}}{A} = \vec{a} \cdot \hat{k}$$

$$(\vec{a} + \vec{i}\alpha) \cdot (\vec{a} + \vec{j}\beta + \vec{k}\gamma)$$

$$= \vec{a} \cdot \vec{a} + \vec{a} \cdot \vec{i}\alpha + \vec{a} \cdot \vec{j}\beta + \vec{a} \cdot \vec{k}\gamma$$

$$= a^2 + \vec{a} \cdot \vec{i}\alpha + \vec{a} \cdot \vec{j}\beta + \vec{a} \cdot \vec{k}\gamma$$

- Cross product:

The cross product of \vec{A} and \vec{B} is a vector $\vec{C} = \vec{A} \times \vec{B}$. The magnitude of $\vec{A} \times \vec{B}$ is defined as the product of the magnitudes of \vec{A} and \vec{B} and the sine of the angle θ between them. The direction of the vector $\vec{C} = \vec{A} \times \vec{B}$ is perpendicular to the plane of \vec{A} and \vec{B} and such that \vec{A}, \vec{B} and \vec{C} form a right-handed system. In symbols,

$$\vec{A} \times \vec{B} = AB \sin \theta \hat{n}$$

whence \hat{n} is a unit vector indicating the direction of $\vec{A} \times \vec{B}$.

$$\vec{A} \times \vec{B} \neq \vec{B} \times \vec{A}$$

$$\vec{A} \times \vec{B} = -\vec{B} \times \vec{A}$$

$$\hat{i} \times \hat{i} = \hat{j} \times \hat{j} = \hat{k} \times \hat{k} = 0$$

$$\hat{i} \times \hat{j} = \hat{k}, \hat{j} \times \hat{i} = -\hat{k}$$

$$\hat{j} \times \hat{k} = \hat{i}, \hat{k} \times \hat{j} = -\hat{i}$$

$$\hat{k} \times \hat{i} = \hat{j}, \hat{i} \times \hat{k} = -\hat{j}$$

→ Find the projection of vector $\vec{A} = \hat{i} - 2\hat{j} + \hat{k}$ on the vector $\vec{B} = 4\hat{i} - 4\hat{j} + 7\hat{k}$.

Solution:

$$\begin{aligned}\therefore \text{The projection, } \vec{A} \cdot \vec{B} &= \frac{\vec{A} \cdot \vec{B}}{|\vec{B}|} \\ &= \frac{(\hat{i} - 2\hat{j} + \hat{k}) \cdot (4\hat{i} - 4\hat{j} + 7\hat{k})}{\sqrt{16+16+49}} \\ &= \frac{4+8+7}{9} = \frac{19}{9}\end{aligned}$$

→ Find the work done in moving an object along a vector $\vec{r} = 3\hat{i} + 2\hat{j} - 5\hat{k}$ if the applied force is $\vec{F} = 2\hat{i} - \hat{j} - \hat{k}$

Solution:

$$\begin{aligned}\text{work done} &= \vec{F} \cdot \vec{r} \\ &= (2\hat{i} - \hat{j} - \hat{k}) \cdot (3\hat{i} + 2\hat{j} - 5\hat{k}) \\ &= 6 - 2 + 5 \\ &= 9\end{aligned}$$

work done along a path = $\int_C \vec{F} \cdot d\vec{r}$ Hence, C is the curve or path

→ Determine the unit vector perpendicular to the plane of $\vec{A} = 2\hat{i} - 6\hat{j} - 3\hat{k}$ and $\vec{B} = 4\hat{i} + 3\hat{j} - \hat{k}$.

Solution: Method - 1 :-

$\vec{A} \times \vec{B}$ is a vector perpendicular to the plane of \vec{A} and \vec{B} .

$$\begin{aligned}\vec{A} \times \vec{B} &= \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ 2 & -6 & -3 \\ 4 & 3 & -1 \end{vmatrix} \\ &= \hat{i}(6+9) - \hat{j}(-2+12) + \hat{k}(6+24) \\ &= 15\hat{i} - 10\hat{j} + 30\hat{k}\end{aligned}$$

$$\begin{aligned}\text{unit vector of } \vec{A} \times \vec{B} &= \frac{\vec{A} \times \vec{B}}{|\vec{A} \times \vec{B}|} \\ &= \frac{15\hat{i} - 10\hat{j} + 30\hat{k}}{\sqrt{225+100+900}} \\ &= \frac{1}{7}(3\hat{i} - 2\hat{j} + 6\hat{k})\end{aligned}$$

Method - 2 :- we are given two straight lines with
their equations and we have to find the unit
perpendicular vector, $\vec{c} = xi + yj + zk$

$$\vec{A} \cdot \vec{c} = 2x - 6y - 3z = 0 \quad \text{(i)}$$

$$\vec{B} \cdot \vec{c} = 4x + 3y - 2z = 0 \quad \text{(ii)}$$

$$\frac{x}{6+9} = \frac{y}{-12+2} = \frac{z}{6+24} = p \quad [\text{Let}]$$

$$\Rightarrow x = 15p, y = -10p, z = 30p$$

$$\therefore \vec{c} = 15p\hat{i} - 10p\hat{j} + 30p\hat{k}$$

$$\therefore \text{unit vector} = \frac{\vec{c}}{c}$$

$$\begin{aligned} \text{unit vector} &= \frac{15p\hat{i} - 10p\hat{j} + 30p\hat{k}}{\sqrt{225p^2 + 100p^2 + 900p^2}} \\ &= \frac{5p(3\hat{i} - 2\hat{j} + 6\hat{k})}{35p} \end{aligned}$$

$$= \frac{1}{7}(3\hat{i} - 2\hat{j} + 6\hat{k})$$

→ Prove that the area of a parallelogram with sides \vec{A} and \vec{B} is $|\vec{A} \times \vec{B}|$

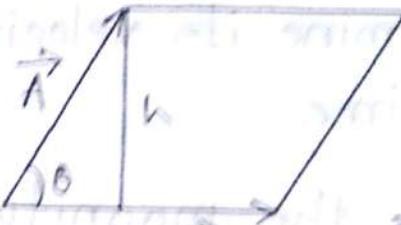
Solution:

Area of parallelogram

$$= h B$$

$$= A \sin \theta B$$

$$= |\vec{A} \times \vec{B}|$$



$$\sin \theta = \frac{h}{A}$$

11-02-2018 : 2E : Sunday

Vector differentiation

$\vec{R}(u)$ is a vector which is a function of u .

The differentiation of $\vec{R}(u)$ is $\frac{d\vec{R}}{du}$. If $\vec{R}(x, y, z)$ is vector which is a function of x, y and z , then the partial differentiation of $\vec{R}(x, y, z)$ is $\frac{\partial \vec{R}}{\partial x}, \frac{\partial \vec{R}}{\partial y}$ and $\frac{\partial \vec{R}}{\partial z}$.

$$\vec{r} = xi + yj + zk$$

$$d\vec{r} = dx\hat{i} + dy\hat{j} + dz\hat{k}$$

$$d\vec{r} \cdot d\vec{r} = dx^2 + dy^2 + dz^2 = ds^2$$

$$|d\vec{r}|^2 = ds^2$$

$$|d\vec{r}| = ds$$

$$\text{surface, } s = x^2 + y^2 + z^2$$

→ A particle moves along a curve whose parametric equations are $x = e^{-t}$, $y = 2\cos 3t$, $z = 2\sin 3t$ where t is the time.

i) Determine its velocity and acceleration at any time.

ii) Find the magnitudes of the velocity and acceleration at $t=0$.

Solution:

We know,

$$\vec{r} = x\hat{i} + y\hat{j} + z\hat{k}$$

$$= e^{-t}\hat{i} + 2\cos 3t\hat{j} + 2\sin 3t\hat{k}$$

(i)

Velocity, $\vec{v} = \frac{d\vec{r}}{dt}$

$$\begin{aligned} &= \frac{d}{dt}(e^{-t}\hat{i} + 2\cos 3t\hat{j} + 2\sin 3t\hat{k}) \\ &= -e^{-t}\hat{i} - 6\sin 3t\hat{j} + 6\cos 3t\hat{k} \end{aligned}$$

$$|\vec{v}| = \sqrt{e^{-2t} + 36\sin^2 3t + 36\cos^2 3t}$$

$$\Rightarrow v = \sqrt{e^{-2t} + 36}$$

Acceleration, $\vec{a} = \frac{d\vec{v}}{dt}$

$$= \frac{d}{dt}(-e^{-t}\hat{i} - 6\sin 3t\hat{j} + 6\cos 3t\hat{k})$$

$$= e^{-t}\hat{i} - 18\cos 3t\hat{j} - 18\sin 3t\hat{k}$$

$$|\vec{a}| = \sqrt{e^{-2t} + 324 \cos^2 3t + 324 \sin^2 3t}$$

$$\Rightarrow a = \sqrt{e^{-2t} + 324}$$

Fix $t = 0$

At $t=0$, \vec{a} is maximum and \vec{v} is minimum.

ii) At $t=0$,

$$v = \sqrt{e^0 + 36} = \sqrt{37}$$

$$a = \sqrt{e^0 + 324} = \sqrt{325}$$

Differential Geometry

If C is a curve defined by the function $\vec{r}(u)$, then $\frac{d\vec{r}}{du}$ is a vector in the direction of the tangent to C . Hence, \vec{T} is the tangent to C , which is the unit tangent vector.

$$\therefore \frac{d\vec{r}}{ds} = \vec{T}$$

The curvature of the curve is $\frac{d\vec{T}}{ds}$ which is equal to $k \vec{N}$

$$\therefore \frac{d\vec{T}}{ds} = k \vec{N}$$

$\rho = \frac{1}{k}$ where, ρ is called the radius of curvature.

Hence, \vec{N} is a unit vector in this normal direction which is called unit normal vector. k is called the curvature of C at the specified point.

$$\vec{B} = \vec{T} \times \vec{N} \cdot \text{to find } k \Rightarrow \text{left side} + \text{right side} + \frac{ds}{s} [k] = 1781$$

where, \vec{B} is called Bi-normal vector of the curve which direction is perpendicular to the plane of \vec{T} and \vec{N} .

Frenet-Serret formula: $\frac{d\vec{B}}{ds} = -\kappa \vec{N}$

$$i) \frac{d\vec{T}}{ds} = \kappa \vec{N} \quad ii) \frac{d\vec{N}}{ds} = \tau \vec{B} - \kappa \vec{T}$$

$$iii) \frac{d\vec{B}}{ds} = -\tau \vec{N}$$

12-02-2018: 3A: Monday

→ Dot Product:

- Exercise:

#57: Find the angle between:

$$a) \vec{A} = 3\hat{i} + 2\hat{j} - 6\hat{k} \text{ and } \vec{B} = 4\hat{i} - 3\hat{j} + \hat{k}$$

$$b) \vec{C} = 4\hat{i} - 2\hat{j} + 4\hat{k} \text{ and } \vec{D} = 3\hat{i} - 6\hat{j} - 2\hat{k}$$

Solution:

a)

$$\vec{A} \cdot \vec{B} = AB \cos \theta = 9$$

$$\Rightarrow \cos \theta = \frac{\vec{A} \cdot \vec{B}}{AB}$$

$$\Rightarrow \cos \theta = \frac{(3\hat{i} + 2\hat{j} - 6\hat{k}) \cdot (4\hat{i} - 3\hat{j} + \hat{k})}{\sqrt{9+4+36} \sqrt{16+9+1}}$$

$$\Rightarrow \theta = \cos^{-1} \left(\frac{0}{7\sqrt{26}} \right)$$

$$\therefore \theta = 90^\circ$$

b)

$$\vec{C} \cdot \vec{D} = CD \cos \theta$$

$$\Rightarrow \cos \theta = \frac{\vec{C} \cdot \vec{D}}{CD}$$

$$\Rightarrow \cos \theta = \frac{(4\hat{i} - 2\hat{j} + 4\hat{k}) \cdot (3\hat{i} - 6\hat{j} - 2\hat{k})}{\sqrt{16+4+16} \sqrt{9+36+4}}$$

$$\Rightarrow \cos \theta = \frac{16}{42}$$

$$\Rightarrow \theta = \cos^{-1}\left(\frac{8}{21}\right) = 67^\circ$$

59: Find the acute angles which the line joining the points $(1, -3, 2)$ and $(3, -5, 1)$ makes with the co-ordinate axes.

Solution:

Let, the vector of the line joining the points $\vec{A} = (3-1)\hat{i} + (-5+3)\hat{j} + (1-2)\hat{k} = 2\hat{i} - 2\hat{j} - \hat{k}$

Again, α, β and γ be the angles which \vec{A} makes with the positive x, y and z axes respectively

$$\vec{A} \cdot \hat{i} = A \|\vec{A}\| \cos \alpha$$

$$\Rightarrow (2\hat{i} - 2\hat{j} - \hat{k}) \cdot \hat{i} = \sqrt{4+4+1} \cos \alpha$$

$$\Rightarrow \cos \alpha = \frac{2}{3} \quad \therefore \alpha = \cos^{-1}\left(\frac{2}{3}\right)$$

$$\text{Q} \quad \vec{A} \cdot \hat{j} = A |\hat{j}| \cos \beta$$

$$\Rightarrow (2\hat{i} - 2\hat{j} - \hat{k}) \cdot \hat{j} = 3 \cos \beta$$

$$\Rightarrow \cos \beta = -\frac{2}{3}$$

$$\therefore \beta = \cos^{-1}\left(-\frac{2}{3}\right)$$

$$\vec{A} \cdot \hat{k} = A |\hat{k}| \cos \gamma$$

$$\Rightarrow (2\hat{i} - 2\hat{j} - \hat{k}) \cdot \hat{k} = 3 \cos \gamma$$

$$\Rightarrow \cos \gamma = -\frac{1}{3}$$

$$\therefore \gamma = \cos^{-1}\left(-\frac{1}{3}\right)$$

60: Find the direction cosines of the line joining the points $(3, 2, -4)$ and $(1, -1, 2)$.

Solution:

Let, the direction cosines of the line is (l, m, n) and direction ratio of the line is (a, b, c)

$$\text{If, } a = (3-1) = 2$$

$$b = (2+1) = 3$$

$$c = (-4-2) = -6$$

$$\therefore l = \frac{a}{\sqrt{a^2+b^2+c^2}} = \frac{2}{\sqrt{4+9+36}} = \frac{2}{7}$$

o.

$$m = \frac{b}{\sqrt{a^2 + b^2 + c^2}} = \frac{-3}{\sqrt{4+9+36}} = \frac{3}{7}$$

$$n = \frac{c}{\sqrt{a^2 + b^2 + c^2}} = \frac{-6}{\sqrt{4+9+36}} = -\frac{6}{7}$$

\therefore direction cosines $(\frac{2}{7}, \frac{3}{7}, -\frac{6}{7})$

If $a = (1-3) = -2$

$$b = (-1-2) = -3$$

$$c = (2+4) = 6$$

$$\therefore l = \frac{a}{\sqrt{a^2 + b^2 + c^2}} = \frac{-2}{\sqrt{4+9+36}} = -\frac{2}{7}$$

$$m = \frac{b}{\sqrt{a^2 + b^2 + c^2}} = \frac{-3}{\sqrt{4+9+36}} = -\frac{3}{7}$$

$$n = \frac{c}{\sqrt{a^2 + b^2 + c^2}} = \frac{6}{\sqrt{4+9+36}} = \frac{6}{7}$$

\therefore direction cosines $(\frac{2}{7}, -\frac{3}{7}, \frac{6}{7})$

63: Find the projection of the vector $2\hat{i} - 3\hat{j} + 6\hat{k}$ on the vector $\hat{i} + 2\hat{j} + 2\hat{k}$.

Solution:

$$\begin{aligned} \text{projection} &= \frac{(2\hat{i} - 3\hat{j} + 6\hat{k}) \cdot (\hat{i} + 2\hat{j} + 2\hat{k})}{\sqrt{1+4+4}} \\ &= \frac{2-6+12}{3} \\ &= \frac{8}{3} \end{aligned}$$

64: Find the projection of the vector $4\hat{i} - 3\hat{j} + \hat{k}$ on the line passing through the points $(2, 3, -1)$ and $(-2, -4, 3)$.

Solution:

The line passing through the points $(-2-2)\hat{i} + (-4-3)\hat{j} + (3+1)\hat{k} = -4\hat{i} - 7\hat{j} + 4\hat{k}$

$$\therefore \text{projection} = \frac{(4\hat{i} - 3\hat{j} + \hat{k})(-4\hat{i} - 7\hat{j} + 4\hat{k})}{\sqrt{16+49+16}} = \frac{-16+21+4}{\sqrt{77}} = \frac{9}{\sqrt{77}} = \frac{9\sqrt{77}}{77}$$

65: If $\vec{A} = 4\hat{i} - \hat{j} + 3\hat{k}$ and $\vec{B} = -2\hat{i} + \hat{j} - 2\hat{k}$, find a unit vector perpendicular to both \vec{A} and \vec{B} .

Solution:

$\vec{A} \times \vec{B}$ is perpendicular to both \vec{A} and \vec{B} .

$$\begin{aligned}\vec{A} \times \vec{B} &= \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ 4 & -1 & 3 \\ -2 & 1 & -2 \end{vmatrix} \\ &= \hat{i}(2+3) - \hat{j}(-8+6) + \hat{k}(4+2) \\ &= -\hat{i} + 2\hat{j} + 2\hat{k}\end{aligned}$$

$$\therefore |\vec{A} \times \vec{B}| = \sqrt{1+4+4} = 3$$

$$\therefore \text{unit vector} = \frac{\vec{A} \times \vec{B}}{|\vec{A} \times \vec{B}|}$$

$$= \frac{-\hat{i} + 2\hat{j} + 2\hat{k}}{3}$$

$$= -\frac{1}{3} (\hat{i} - 2\hat{j} - 2\hat{k})$$

82: Find the area of a parallelogram having diagonals $\vec{A} = 3\hat{i} + \hat{j} - 2\hat{k}$ and $\vec{B} = \hat{i} - 3\hat{j} + 4\hat{k}$

Solution:

Area of the parallelogram

$$= |\vec{A} \times \vec{B}| \times \frac{1}{2}$$

$$= \sqrt{4+196+100} \times \frac{1}{2}$$

$$= 10\sqrt{3} \times \frac{1}{2}$$

$$= 5\sqrt{3}$$

$$\vec{A} \times \vec{B} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ 3 & 1 & -2 \\ 1 & -3 & 4 \end{vmatrix}$$

$$= \hat{i}(4-6) - \hat{j}(12+2) + \hat{k}(9-1)$$

$$= -2\hat{i} - 14\hat{j} + 10\hat{k}$$

83: Find the area of a triangle with vertices at $(3, -1, 2)$, $(1, -1, -3)$ and $(4, -3, 1)$

Solution:

Let, the vertices be $P(3, -1, 2)$, $Q(1, -1, -3)$ and $R(4, -3, 1)$

$$\overrightarrow{PQ} = (1-3)\hat{i} + (-1+1)\hat{j} + (-3-2)\hat{k} = -2\hat{i} - 5\hat{k}$$

$$\overrightarrow{PR} = (4-3)\hat{i} + (-3+1)\hat{j} + (1-2)\hat{k} = \hat{i} - 2\hat{j} - \hat{k}$$

\therefore Area of triangle = $\frac{1}{2} |\vec{PQ} \times \vec{PR}|$

$$= \frac{1}{2} \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ -2 & 0 & -5 \\ 1 & -2 & -1 \end{vmatrix}$$

$$= \frac{1}{2} | \hat{i}(0-10) - \hat{j}(2+5) + \hat{k}(4-0) |$$

$$= \frac{1}{2} |-10\hat{i} - 7\hat{j} + 4\hat{k}|$$

$$= \frac{1}{2} \sqrt{100 + 49 + 16}$$

$$= \frac{1}{2} \sqrt{165} \text{ unit to area}$$

90: Find the volume of the parallelepiped whose edges are represented by $\vec{A} = 2\hat{i} - 3\hat{j} + 4\hat{k}$, $\vec{B} = \hat{i} + 2\hat{j} - \hat{k}$ and $\vec{C} = 3\hat{i} - \hat{j} + 2\hat{k}$.

Solution:

The volume of the parallelepiped

$$= |\vec{A} \cdot (\vec{B} \times \vec{C})| = |\vec{B} \cdot (\vec{C} \times \vec{A})| = |\vec{C} \cdot (\vec{A} \times \vec{B})|$$

$$= \begin{vmatrix} 2 & -3 & 4 \\ 1 & 2 & -1 \\ 3 & -1 & 2 \end{vmatrix}$$

$$= |2(4-1) + 3(2+3) + 4(-1-6)|$$

$$= |6 + 15 - 28| = |7 - 21| = \frac{14}{2} = 7$$

$$= |-7| = 7$$

92: Find the constant a such that the vectors $2\hat{i} - \hat{j} + \hat{k}$, $\hat{i} + 2\hat{j} - 3\hat{k}$ and $3\hat{i} + a\hat{j} + 5\hat{k}$ are coplanar.

Solution:

The vectors will be coplanar if

$$\begin{vmatrix} 2 & -1 & 1 \\ 1 & 2 & -3 \\ 3 & a & 5 \end{vmatrix} = 0$$

$$\Rightarrow 2(10+3a) + 1(5+a) + 1(a-6) = 0$$

$$\Rightarrow 20+6a+5+a-6=0$$

$$\Rightarrow 7a+28=0$$

$$\Rightarrow a = -\frac{28}{7}$$

$$\therefore a = -4$$

100: Prove that, $(\vec{A} \times \vec{B}) \cdot (\vec{C} \times \vec{D}) + (\vec{B} \times \vec{C}) \cdot (\vec{A} \times \vec{D}) + (\vec{C} \times \vec{A}) \cdot (\vec{B} \times \vec{D}) = 0$

Solution:

$$\begin{aligned} \text{L.H.S.} &= (\vec{A} \times \vec{B}) \cdot (\vec{C} \times \vec{D}) + (\vec{B} \times \vec{C}) \cdot (\vec{A} \times \vec{D}) + (\vec{C} \times \vec{A}) \cdot (\vec{B} \times \vec{D}) \\ &= (\cancel{\vec{A} \times \vec{B}}) \cdot \vec{X} \cdot (\vec{C} \times \vec{D}) + \vec{Y} \cdot (\vec{A} \times \vec{D}) + \vec{Z} \cdot (\vec{B} \times \vec{D}) \end{aligned}$$

$$\text{Let, } \vec{A} \times \vec{B} = \vec{X}, \vec{B} \times \vec{C} = \vec{Y}, \vec{C} \times \vec{A} = \vec{Z}$$

$$\begin{aligned} &= (\vec{X} \times \vec{C}) \cdot \vec{D} + (\vec{Y} \times \vec{A}) \cdot \vec{D} + (\vec{Z} \times \vec{B}) \cdot \vec{D} \\ &\quad [\because \vec{A} \cdot (\vec{B} \times \vec{C}) = (\vec{A} \times \vec{B}) \cdot \vec{C}] \end{aligned}$$

$$\begin{aligned}
 &= \{(\vec{A} \times \vec{B}) \times \vec{C}\} \cdot \vec{D} + \{(\vec{B} \times \vec{C}) \times \vec{A}\} \cdot \vec{D} \\
 &\quad + \{(\vec{C} \times \vec{A}) \times \vec{B}\} \cdot \vec{D} \\
 &= \{\vec{B} \cdot (\vec{A} \cdot \vec{C}) - \vec{A} \cdot (\vec{B} \cdot \vec{C})\} \cdot \vec{D} + \{\vec{C} \cdot (\vec{A} \cdot \vec{B}) - \vec{B} \cdot (\vec{A} \cdot \vec{C})\} \cdot \vec{D} \\
 &\quad + \{\vec{A} \cdot (\vec{B} \cdot \vec{C}) - \vec{C} \cdot (\vec{A} \cdot \vec{B})\} \cdot \vec{D}
 \end{aligned}$$

[Spiegel, Page - 28, Prob - 47 (b)]

$$\begin{aligned}
 &= (\vec{B} \cdot \vec{D}) \cdot (\vec{A} \cdot \vec{C}) - (\vec{A} \cdot \vec{D}) \cdot (\vec{B} \cdot \vec{C}) + (\vec{C} \cdot \vec{D}) \cdot (\vec{A} \cdot \vec{B}) \\
 &\quad - (\vec{B} \cdot \vec{D}) (\vec{A} \cdot \vec{C}) + (\vec{A} \cdot \vec{D}) \cdot (\vec{B} \cdot \vec{C}) - (\vec{C} \cdot \vec{D}) \cdot (\vec{A} \cdot \vec{B}) \\
 &= 0 = R.H.S.
 \end{aligned}$$

$\therefore L.H.S = R.H.S.$ (Proved)

→ Vector differentiation:

- Example: $(\vec{a} \times \vec{b}) \cdot (\vec{c} \times \vec{d})$, $(\vec{a} \times \vec{b}) \cdot (\vec{c} \times \vec{a})$.

1: If $\vec{R}(u) = x(u)\hat{i} + y(u)\hat{j} + z(u)\hat{k}$ where x, y, z are differentiable functions of a scalar u . Prove that $\frac{d\vec{R}}{du} = \frac{dx}{du}\hat{i} + \frac{dy}{du}\hat{j} + \frac{dz}{du}\hat{k}$

Solution:

$$L.H.S. = \frac{d\vec{R}}{du} = \lim_{\Delta u \rightarrow 0} \frac{\vec{R}(u + \Delta u) - \vec{R}(u)}{\Delta u}$$

$$[5 \cdot (\vec{a} \times \vec{b}) = (\vec{b} \times \vec{a}) \cdot \vec{b}]$$

$$\begin{aligned}
 &= \lim_{\Delta u \rightarrow 0} \frac{\{x(u+\Delta u)\hat{i} + y(u+\Delta u)\hat{j} + z(u+\Delta u)\hat{k}\} - \{x(u)\hat{i} + y(u)\hat{j} + z(u)\hat{k}\}}{\Delta u} \\
 &= \lim_{\Delta u \rightarrow 0} \frac{x(u+\Delta u) - x(u)}{\Delta u} \hat{i} + \frac{y(u+\Delta u) - y(u)}{\Delta u} \hat{j} + \frac{z(u+\Delta u) - z(u)}{\Delta u} \hat{k} \\
 &= \frac{dx}{du} \hat{i} + \frac{dy}{du} \hat{j} + \frac{dz}{du} \hat{k} \\
 &= \text{R.H.S.}
 \end{aligned}$$

$$\therefore \text{L.H.S.} = \text{R.H.S.} \quad (\text{Proved})$$

#2: Given $\vec{R} = \sin t \hat{i} + \cos t \hat{j} + t \hat{k}$, find

$$a) \frac{d\vec{R}}{dt}, \quad b) \frac{d^2\vec{R}}{dt^2}, \quad c) \left| \frac{d\vec{R}}{dt} \right|, \quad d) \left| \frac{d^2\vec{R}}{dt^2} \right|$$

Solution:

$$\begin{aligned}
 a) \frac{d\vec{R}}{dt} &= \frac{d}{dt}(\sin t) \hat{i} + \frac{d}{dt}(\cos t) \hat{j} + \frac{d}{dt}(t) \hat{k} \\
 &= \cos t \hat{i} - \sin t \hat{j} + \hat{k}
 \end{aligned}$$

$$\begin{aligned}
 b) \frac{d^2\vec{R}}{dt^2} &= \frac{d}{dt}(\cos t) \hat{i} - \frac{d}{dt}(\sin t) \hat{j} + \frac{d}{dt}(1) \hat{k} \\
 &= -\sin t \hat{i} - \cos t \hat{j}
 \end{aligned}$$

$$c) \left| \frac{d\vec{R}}{dt} \right| = \sqrt{\cos^2 t + \sin^2 t + 1} = \sqrt{2}$$

$$d) \left| \frac{d^2\vec{R}}{dt^2} \right| = \sqrt{\sin^2 t + \cos^2 t} = 1$$

4: A particle moves along the curve $x = 2t^2$,
 $y = t^2 - 4t$, $z = 3t - 5$ where t is the time. Find
 the components of its velocity and acceleration
 at time $t=1$ in the direction $\hat{i} - 3\hat{j} + 2\hat{k}$.

Solution:

$$\vec{r} = 2t^2\hat{i} + (t^2 - 4t)\hat{j} + (3t - 5)\hat{k}$$

$$\text{Velocity, } \frac{d\vec{r}}{dt} = \frac{d}{dt}(2t^2)\hat{i} + \frac{d}{dt}(t^2 - 4t)\hat{j} + \frac{d}{dt}(3t - 5)\hat{k}$$

$$= 4t\hat{i} + (2t - 4)\hat{j} + 3\hat{k}$$

at time, $t=1$

$$\text{velocity} = 4\hat{i} - 2\hat{j} + 3\hat{k}$$

unit vector in direction $\hat{i} - 3\hat{j} + 2\hat{k}$

$$= \frac{\hat{i} - 3\hat{j} + 2\hat{k}}{\sqrt{1+9+4}} = \frac{1}{\sqrt{14}}(\hat{i} - 3\hat{j} + 2\hat{k})$$

Component of velocity in the given direction,

$$= \frac{1}{\sqrt{14}}(\hat{i} - 3\hat{j} + 2\hat{k}) \cdot (4\hat{i} - 2\hat{j} + 3\hat{k})$$

$$= \frac{1}{\sqrt{14}}(4 + 6 + 6)$$

$$= \frac{16}{\sqrt{14}} = \frac{8\sqrt{14}}{7}$$

$$= \frac{8\sqrt{2}}{\sqrt{7}}$$

$$\text{Acceleration, } \frac{d^2\vec{r}}{dt^2} = \frac{d}{dt}(4t)\hat{i} + \frac{d}{dt}(2t-4)\hat{j} + \frac{d}{dt}(3)\hat{k}$$

$$= 4\hat{i} + 2\hat{j}$$

Component of the acceleration in the given direction,

$$= \frac{1}{\sqrt{14}} (\hat{i} - 3\hat{j} + 2\hat{k}) \cdot (4\hat{i} + 2\hat{j})$$

$$= \frac{1}{\sqrt{14}} (4 - 6)$$

$$= -\frac{2}{\sqrt{14}}$$

$$= -\frac{\sqrt{14}}{7}$$

#5: A curve C is defined by parametric equation

$x = x(s)$, $y = y(s)$, $z = z(s)$, where s is the inverse of length of C measured from a fixed point on C . If \vec{r} is the position vector of any point on C , show that $\frac{d\vec{r}}{ds}$ is a unit vector tangent to C .

Solution:

The vector, $\frac{d\vec{r}}{ds} = \frac{dx}{ds}\hat{i} + \frac{dy}{ds}\hat{j} + \frac{dz}{ds}\hat{k}$ is tangent to the curve $x = x(s)$, $y = y(s)$, $z = z(s)$.

$$\begin{aligned} \therefore \left| \frac{d\vec{r}}{ds} \right| &= \sqrt{\left(\frac{dx}{ds} \right)^2 + \left(\frac{dy}{ds} \right)^2 + \left(\frac{dz}{ds} \right)^2} \\ &= \sqrt{\frac{(dx)^2 + (dy)^2 + (dz)^2}{(ds)^2}} \\ &= \sqrt{\frac{(ds)^2}{(ds)^2}} \quad [\because (ds)^2 = (dx)^2 + (dy)^2 + (dz)^2] \\ &= 1 \end{aligned}$$

As, then $|\frac{d\vec{r}}{ds}| = \sqrt{1 + (4t)^2 + (2t^2 - 6t)^2}$

So $\frac{d\vec{r}}{ds}$ is a unit vector tangent to C. (Showed)

#6:

a) Find the unit tangent vector to any point on the curve $x = t^2 + 1$, $y = 4t - 3$, $z = 2t^2 - 6t$.

b) Determine the unit tangent at the point where $t = 2$.

Solution:

a)

The curve vector, $\vec{r} = (t^2 + 1)\hat{i} + (4t - 3)\hat{j} + (2t^2 - 6t)\hat{k}$

A tangent vector to the curve

$$\begin{aligned}\frac{d\vec{r}}{dt} &= \frac{d}{dt}(t^2 + 1)\hat{i} + \frac{d}{dt}(4t - 3)\hat{j} + \frac{d}{dt}(2t^2 - 6t)\hat{k} \\ &= 2t\hat{i} + 4\hat{j} + (4t - 6)\hat{k}\end{aligned}$$

$$\therefore |\frac{d\vec{r}}{dt}| = \sqrt{(2t)^2 + 4^2 + (4t - 6)^2}$$

The unit tangent vector, $\vec{T} = \frac{d\vec{r}}{ds}$

$$= \frac{\frac{d\vec{r}}{dt}}{\frac{ds}{dt}}$$

$$\left[\because |\frac{d\vec{r}}{dt}| = \frac{ds}{dt} \right]$$

$$= \frac{d\vec{r}}{dt} \times \frac{1}{\left| \frac{d\vec{r}}{dt} \right|}$$

$$\therefore \vec{T} = \frac{2t\hat{i} + 4\hat{j} + (4t-6)\hat{k}}{\sqrt{(2t)^2 + 4^2 + (4t-6)^2}}$$

b)

$$At . t=2$$

$$\text{the unit tangent vector, } \vec{T} = \frac{(2x2)\hat{i} + 4\hat{j} + \{(4x2)-6\}\hat{k}}{\sqrt{4^2 + 4^2 + 2^2}} \\ = \frac{4\hat{i} + 4\hat{j} + 2\hat{k}}{\sqrt{36}} \\ = \frac{1}{3}(2\hat{i} + 2\hat{j} + \hat{k})$$

~~#7.11~~

#8: If $\vec{A} = 5t^2\hat{i} + t\hat{j} - t^3\hat{k}$ and $\vec{B} = \sin t\hat{i} - \cos t\hat{j}$,

find a) $\frac{d}{dt}(\vec{A} \cdot \vec{B})$, b) $\frac{d}{dt}(\vec{A} \times \vec{B})$, c) $\frac{d}{dt}(\vec{A} \cdot \vec{A})$

Solution:

$$a) \frac{d}{dt}(\vec{A} \cdot \vec{B})$$

$$= \vec{A} \cdot \frac{d\vec{B}}{dt} + \vec{B} \cdot \frac{d\vec{A}}{dt}$$

$$= (5t^2\hat{i} + t\hat{j} - t^3\hat{k}) \cdot \frac{d}{dt}(\sin t\hat{i} - \cos t\hat{j})$$

$$+ (\sin t\hat{i} - \cos t\hat{j}) \cdot \frac{d}{dt}(5t^2\hat{i} + t\hat{j} - t^3\hat{k})$$

$$= (5t^2\hat{i} + t\hat{j} - t^3\hat{k}) \cdot (\cos t\hat{i} + \sin t\hat{j}) \\ + (\sin t\hat{i} - \cos t\hat{j}) \cdot (10t\hat{i} + \hat{j} - 3t^2\hat{k})$$

$$= 5t^2 \cos t + t \sin t + 10t \sin t - \cos t$$

$$= (5t^2 - 1) \cos t + 11t \sin t$$

b)

$$\frac{d}{dt} (\vec{A} \times \vec{B})$$

$$= \vec{A} \times \frac{d\vec{B}}{dt} + \vec{B} \times \frac{d\vec{A}}{dt}$$

$$= \vec{A} \times \frac{d}{dt} (\sin t \hat{i} - \cos t \hat{j}) + \vec{B} \times \frac{d}{dt} (5t^2 \hat{i} + t \hat{j} - t^3 \hat{k})$$

$$= (5t^2 \hat{i} + t \hat{j} - t^3 \hat{k}) \times (\cos t \hat{i} + \sin t \hat{j})$$

$$+ (\sin t \hat{i} - \cos t \hat{j}) \times (10t \hat{i} + \hat{j} - 3t^2 \hat{k})$$

$$= \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ 5t^2 & t & -t^3 \\ \sin t & -\cos t & 0 \end{vmatrix} + \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \cos t & \sin t & 0 \\ 10t & 1 & -3t^2 \end{vmatrix}$$

$$= \hat{i}(0 + t^3 \sin t) - \hat{j}(0 + t^3 \cos t) + \hat{k}(5t^2 \sin t - t \cos t)$$

$$- \{ \hat{i}(3t^2 \cos t - 0) - \hat{j}(-3t^2 \sin t + 0) + \hat{k}(\sin t + 10t \cos t) \}$$

$$= t^3 \sin t \hat{i} - t^3 \cos t \hat{j} + (5t^2 \sin t - t \cos t) \hat{k} - 3t^2 \cos t \hat{i}$$

$$- 3t^2 \sin t \hat{j} + (\sin t + 10t \cos t) \hat{k}$$

$$= (t^3 \sin t - 3t^2 \cos t) \hat{i} - (t^3 \cos t + 3t^2 \sin t) \hat{j}$$

$$+ \{(5t - 1) \sin t + 11t \cos t\} \hat{k}$$

$$\begin{aligned}
 c) \frac{d}{dt} (\vec{A} \cdot \vec{A}) &= \vec{A} \frac{d\vec{A}}{dt} + \vec{A} \frac{d\vec{A}}{dt} \\
 &= 2 \cdot \vec{A} \cdot \frac{d}{dt} (5t^2 \hat{i} + t \hat{j} - t^3 \hat{k}) \\
 &= 2 \cdot (5t^2 \hat{i} + t \hat{j} - t^3 \hat{k}) \cdot (10t \hat{i} + \hat{j} - 3t^2 \hat{k}) \\
 &= 2 \cdot (50t^3 + t + 3t^5) \\
 &= 100t^3 + 2t + 6t^5
 \end{aligned}$$

#9: If \vec{A} has constant magnitude show that \vec{A} and $\frac{d\vec{A}}{dt}$ are perpendicular provided $|\frac{d\vec{A}}{dt}| \neq 0$

Solution:

As, \vec{A} has constant magnitude, $\vec{A} \cdot \vec{A} = \text{constant}$.

$$\therefore \frac{d}{dt} (\vec{A} \cdot \vec{A}) = \vec{A} \frac{d}{dt} (\vec{A}) + \vec{A} \frac{d\vec{A}}{dt} = 2 \cdot \vec{A} \frac{d\vec{A}}{dt} = 0$$

$$\text{since } \frac{d}{dt} (\vec{A} \cdot \vec{A}) = 0 \quad [\because \vec{A} \cdot \vec{A} = \text{constant}]$$

$$\Rightarrow 2 \vec{A} \cdot \frac{d\vec{A}}{dt} = 0$$

$$\therefore \vec{A} \cdot \frac{d\vec{A}}{dt} = 0$$

Since the dot product of \vec{A} and $\frac{d\vec{A}}{dt}$ is 0, \vec{A} and $\frac{d\vec{A}}{dt}$ are perpendicular.

#10: Prove $\frac{d}{du} (\vec{A} \cdot \vec{B} \times \vec{C}) = \vec{A} \cdot \vec{B} \times \frac{d\vec{C}}{du} + \vec{A} \cdot \frac{d\vec{B}}{du} \times \vec{C}$
 $+ \frac{d\vec{A}}{du} \cdot \vec{B} \times \vec{C}$ where $\vec{A}, \vec{B}, \vec{C}$ are differentiable
functions of a scalar u .

Solution:

$$\begin{aligned} \text{L.H.S.} &= \frac{d}{du} (\vec{A} \cdot \vec{B} \times \vec{C}) \\ &= \vec{A} \cdot \frac{d}{du} (\vec{B} \times \vec{C}) + \frac{d\vec{A}}{du} \cdot (\vec{B} \times \vec{C}) \\ &= \vec{A} \cdot \left(\vec{B} \times \frac{d\vec{C}}{du} + \frac{d\vec{B}}{du} \times \vec{C} \right) + \frac{d\vec{A}}{du} \cdot (\vec{B} \times \vec{C}) \\ &= \vec{A} \cdot \vec{B} \times \frac{d\vec{C}}{du} + \vec{A} \cdot \frac{d\vec{B}}{du} \times \vec{C} + \frac{d\vec{A}}{du} \cdot \vec{B} \times \vec{C} \\ &= \text{R.H.S.} \end{aligned}$$

L.H.S. = R.H.S. (Proved)

#11: Evaluate $\frac{d}{dt} (\vec{v} \cdot \frac{d\vec{v}}{dt} \times \frac{d^2\vec{v}}{dt^2})$

Solution:

$$\begin{aligned} &\frac{d}{dt} (\vec{v} \cdot \frac{d\vec{v}}{dt} \times \frac{d^2\vec{v}}{dt^2}) \\ &= \vec{v} \cdot \frac{d}{dt} \left(\frac{d\vec{v}}{dt} \times \frac{d^2\vec{v}}{dt^2} \right) + \frac{d\vec{v}}{dt} \cdot \frac{d\vec{v}}{dt} \times \frac{d^2\vec{v}}{dt^2} \\ &= \vec{v} \left(\cancel{\frac{d\vec{v}}{dt} \times \frac{d^3\vec{v}}{dt^3}} + \frac{d^2\vec{v}}{dt^2} \times \frac{d^2\vec{v}}{dt^2} \right) + \cancel{\vec{v} \cdot \frac{d\vec{v}}{dt} \times \frac{d^2\vec{v}}{dt^2}} \\ &= \vec{v} \cdot \frac{d\vec{v}}{dt} \times \frac{d^3\vec{v}}{dt^3} + \vec{v} \cdot \frac{d^2\vec{v}}{dt^2} \times \frac{d^2\vec{v}}{dt^2} \\ &= \vec{v} \cdot \frac{d\vec{v}}{dt} \times \frac{d^3\vec{v}}{dt^3} \end{aligned}$$

12: A particle moves so that its position vector is given by $\vec{r} = \cos \omega t \hat{i} + \sin \omega t \hat{j}$ where ω is a constant. Show that

- the velocity \vec{v} of the particle is perpendicular to \vec{r}
- the acceleration \vec{a} is directed toward the origin and has magnitude proportional to the distance from the origin.
- $\vec{r} \times \vec{v} = \text{a constant vector.}$

Solution:

$$\text{a) } \vec{v} = \frac{d\vec{r}}{dt} = \frac{d}{dt}(\cos \omega t) \hat{i} + \frac{d}{dt}(\sin \omega t) \hat{j} = -\omega \sin \omega t \hat{i} + \omega \cos \omega t \hat{j}$$

$$\begin{aligned}\vec{r} \cdot \vec{v} &= (\cos \omega t \hat{i} + \sin \omega t \hat{j}) \cdot (-\omega \sin \omega t \hat{i} + \omega \cos \omega t \hat{j}) \\ &= -\omega \sin \omega t \cos \omega t + \omega \sin \omega t \cos \omega t \\ &= 0\end{aligned}$$

As, the dot product of \vec{r} and \vec{v} is zero, \vec{v} is perpendicular to \vec{r} .

b) Given motion along the x-axis with initial position $\vec{R} = 5\hat{i}$ and velocity $\vec{v} = \hat{i}\omega$.

$$\vec{a} = \frac{d^2\vec{R}}{dt^2} = \frac{d}{dt}\vec{v} = \hat{i}\omega^2$$

$$= \frac{d}{dt}(-\omega \sin \omega t)\hat{i} + \frac{d}{dt}(\omega \cos \omega t)\hat{j}$$

$$= -\omega^2 \cos \omega t \hat{i} - \omega^2 \sin \omega t \hat{j}$$

$$= -\omega^2 (\cos \omega t \hat{i} + \sin \omega t \hat{j})$$

at time t , the position is $\vec{R} = 5\hat{i} + \hat{i}\omega t$

The acceleration is opposite to the direction of \vec{R} . It is directed toward the origin. Its magnitude is proportional to $|\vec{R}|$ which is the distance from the origin.

c) $\vec{r} \times \vec{v}$

$$= (\cos \omega t \hat{i} + \sin \omega t \hat{j}) \times (-\omega \sin \omega t \hat{i} + \omega \cos \omega t \hat{j})$$

$$= (\hat{i}\cos \omega t + \hat{j}\sin \omega t) \cdot (\hat{i}\cos \omega t + \hat{j}\sin \omega t) = 0$$

$$= \begin{vmatrix} \cos \omega t & \sin \omega t & 0 \\ -\omega \sin \omega t & \omega \cos \omega t & 0 \end{vmatrix}$$

$$= \hat{i} \times 0 - \hat{j} \times 0 + \hat{k} (\omega \cos^2 \omega t + \omega \sin^2 \omega t)$$

$$= \omega \hat{k} = \text{a constant vector}$$

$\therefore \vec{r} \times \vec{v}$ is a constant vector. (showed)

$$\# 13: \text{Prove: } \vec{A} \times \frac{d^2 \vec{B}}{dt^2} - \frac{d^2 \vec{A}}{dt^2} \times \vec{B} = \frac{d}{dt} \left(\vec{A} \times \frac{d \vec{B}}{dt} - \frac{d \vec{A}}{dt} \times \vec{B} \right)$$

Solution:

$$\text{L.H.S.} = \vec{A} \times \frac{d^2 \vec{B}}{dt^2} - \frac{d^2 \vec{A}}{dt^2} \times \vec{B}$$

$$= \vec{A} \times \frac{d^2 \vec{B}}{dt^2} + \frac{d \vec{A}}{dt} \times \frac{d \vec{B}}{dt} - \frac{d \vec{A}}{dt} \times \frac{d \vec{B}}{dt} - \frac{d^2 \vec{A}}{dt^2} \times \vec{B}$$

$$= \left(\vec{A} \times \frac{d^2 \vec{B}}{dt^2} + \frac{d \vec{A}}{dt} \times \frac{d \vec{B}}{dt} \right) - \left(\frac{d \vec{A}}{dt} \times \frac{d \vec{B}}{dt} + \frac{d^2 \vec{A}}{dt^2} \times \vec{B} \right)$$

$$= \frac{d}{dt} \left(\vec{A} \times \frac{d \vec{B}}{dt} \right) - \frac{d}{dt} \left(\frac{d \vec{A}}{dt} \times \vec{B} \right)$$

$$= \frac{d}{dt} \left(\vec{A} \times \frac{d \vec{B}}{dt} - \frac{d \vec{A}}{dt} \times \vec{B} \right)$$

$$= \text{R.H.S.}$$

$$\therefore \text{L.H.S.} = \text{R.H.S.} \quad (\text{Proved})$$

$$\# 14: \text{show that: } \vec{A} \cdot \frac{d \vec{A}}{dt} = A \frac{dA}{dt}$$

Solution:

$$\vec{A} \cdot \vec{A} = A^2$$

$$\Rightarrow \frac{d}{dt} (\vec{A} \cdot \vec{A}) = \frac{d}{dt} (A^2)$$

$$\Rightarrow 2 \vec{A} \cdot \frac{d \vec{A}}{dt} = 2A \frac{dA}{dt}$$

$$\therefore \vec{A} \cdot \frac{d \vec{A}}{dt} = A \frac{dA}{dt} \quad (\text{showed})$$

15: If $\vec{A} = (2x^2y - x^4)\hat{i} + (e^{xy} - y \sin x)\hat{j} + (x^2 \cos y)\hat{k}$

find $\frac{\partial A}{\partial x}$, $\frac{\partial A}{\partial y}$, $\frac{\partial^2 A}{\partial x^2}$, $\frac{\partial^2 A}{\partial y^2}$, $\frac{\partial^2 A}{\partial xy}$, $\frac{\partial^2 A}{\partial yx}$: solution

Solution:

$$\begin{aligned}\frac{\partial A}{\partial x} &= \frac{\partial}{\partial x} (2x^2y - x^4)\hat{i} + \frac{\partial}{\partial x} (e^{xy} - y \sin x)\hat{j} \\ &\quad + \frac{\partial}{\partial x} (x^2 \cos y)\hat{k} \\ &= (4xy - 4x^3)\hat{i} + (ye^{xy} - y \cos x)\hat{j} \\ &\quad + (2x \cos y)\hat{k}\end{aligned}$$

$$\begin{aligned}\frac{\partial A}{\partial y} &= \frac{\partial}{\partial y} (2x^2y - x^4)\hat{i} + \frac{\partial}{\partial y} (e^{xy} - y \sin x)\hat{j} \\ &\quad + \frac{\partial}{\partial y} (x^2 \cos y)\hat{k} \\ &= 2x^2\hat{i} + (xe^{xy} - \sin x)\hat{j} + \cancel{x^2 \cos y - x^2 \sin y}\hat{k}\end{aligned}$$

$$\begin{aligned}\frac{\partial^2 A}{\partial x^2} &= \frac{\partial}{\partial x} \left(\frac{\partial A}{\partial x} \right) \\ &= \frac{\partial}{\partial x} (4xy - 4x^3)\hat{i} + \frac{\partial}{\partial x} (ye^{xy} - y \cos x)\hat{j} \\ &\quad + \frac{\partial}{\partial x} (2x \cos y)\hat{k} \\ &= (4y - 12x^2)\hat{i} + (y^2 e^{xy} + y \sin x)\hat{j} + (2 \cos y)\hat{k}\end{aligned}$$

$$\begin{aligned}\frac{\partial^2 A}{\partial y^2} &= \frac{\partial}{\partial y} \left(\frac{\partial A}{\partial y} \right) \\ &= \frac{\partial}{\partial y} (2x^2)\hat{i} + \frac{\partial}{\partial y} (xe^{xy} - \sin x)\hat{j} - \frac{\partial}{\partial y} (x^2 \sin y)\hat{k}\end{aligned}$$

$$= 0 + x^2 e^{xy} \hat{i} - x^2 \cos y \hat{k} = x^2 e^{xy} \hat{i} - x^2 \cos y \hat{k}$$

$$\frac{\partial^2 A}{\partial x \partial y} = \frac{\partial}{\partial x} \left(\frac{\partial A}{\partial y} \right)$$

$$= \frac{\partial}{\partial x} (2x^2) \hat{i} + \frac{\partial}{\partial x} (xe^{xy} - \sin x) \hat{j} - \frac{\partial}{\partial x} (-x^2 \sin y) \hat{k}$$

$$= 4x \hat{i} + (xye^{xy} + e^{xy} - \cos x) \hat{j} - (2x \sin y) \hat{k}$$

$$\frac{\partial^2 A}{\partial y \partial x} = \frac{\partial}{\partial y} \left(\frac{\partial A}{\partial x} \right)$$

$$= \frac{\partial}{\partial y} (4xy - 4x^3) + \frac{\partial}{\partial y} (ye^{xy} - y \cos x) \hat{j}$$

$$+ \frac{\partial}{\partial y} (2x \cos y) \hat{k}$$

$$= 4x \hat{i} + (xye^{xy} + e^{xy} - \cos x) \hat{j} - (2x \sin y) \hat{k}$$

16: If $\phi(x, y, z) = xy^2z$ and $\vec{A} = xz \hat{i} - xy^2 \hat{j} + yz^2 \hat{k}$

find $\frac{\partial^3}{\partial x^2 \partial z} (\phi A)$ at the point $(2, -1, 1)$.

Solution:

$$\phi \vec{A} = (xy^2z) (xz \hat{i} - xy^2 \hat{j} + yz^2 \hat{k})$$

$$= x^2y^2z^2 \hat{i} - x^2y^4z \hat{j} + x^2y^2z^3 \hat{k}$$

$$\frac{\partial}{\partial z} (\phi \vec{A}) = \frac{\partial}{\partial z} (x^2y^2z^2) \hat{i} - \frac{\partial}{\partial z} (x^2y^4z) \hat{j} + \frac{\partial}{\partial z} (x^2y^2z^3) \hat{k}$$

$$= 2x^2y^2z \hat{i} - x^2y^4 \hat{j} + 3x^2y^2z^2 \hat{k}$$

$$\frac{\partial^2}{\partial x \partial z} (\phi \vec{A}) = \frac{\partial}{\partial x} (2x^2y^2z) \hat{i} - \frac{\partial}{\partial x} (x^2y^4) \hat{j} + \frac{\partial}{\partial x} (3xy^3z^2) \hat{k}$$

$$= 4xy^2z \hat{i} - 2xy^4 \hat{j} + 3y^3z^2 \hat{k}$$

$$\frac{\partial^3}{\partial x^2 \partial z} (\phi \vec{A}) = \frac{\partial}{\partial x} (4xy^2z) \hat{i} - \frac{\partial}{\partial x} (2xy^4) \hat{j} + \frac{\partial}{\partial x} (3y^3z^2) \hat{k}$$

$$= 4y^2z \hat{i} - 2y^4 \hat{j} + 3y^3z^2 \hat{k}$$

at the point $(2, -1, 1)$

$$\frac{\partial^3}{\partial x^2 \partial z} (\phi \vec{A}) = 4 \times (-1)^2 \times 1 \hat{i} - 2 \times (-1)^4 \hat{j} = 4 \hat{i} - 2 \hat{j}$$

#18: Prove the Frenet-Serret formulae:

$$a) \frac{d \vec{T}}{ds} = k \vec{N}, \quad b) \frac{d \vec{B}}{ds} = -\gamma \vec{N}, \quad c) \frac{d \vec{N}}{ds} = \gamma \vec{B} - k \vec{T}$$

Solution:

a) As, \vec{T} is the unit tangent vector, $\vec{T} \cdot \vec{T} = 1$.
 $\therefore \vec{T} \cdot \frac{d \vec{T}}{ds} = 0$, $\frac{d \vec{T}}{ds}$ is perpendicular to \vec{T} .

If \vec{N} is a unit vector in the direction $\frac{d \vec{T}}{ds}$,

$\frac{d \vec{T}}{ds} = k \vec{N}$ whence k is the curvature.

$$b) \text{Let, } \vec{B} = \vec{T} \times \vec{N}$$

$$\Rightarrow \frac{d \vec{B}}{ds} = \vec{T} \times \frac{d \vec{N}}{ds} + \frac{d \vec{T}}{ds} \times \vec{N}$$

$$= \vec{T} \times \frac{d \vec{N}}{ds} + k \vec{N} \times \vec{N}$$

$$= \vec{T} \times \frac{d \vec{N}}{ds} \quad [\vec{N} \times \vec{N} = 0 \because \vec{N} \text{ is a unit vector}]$$

$$\vec{T} \cdot \frac{d\vec{B}}{ds} = \vec{T} \cdot \vec{T} \times \frac{d\vec{N}}{ds}$$

Since $\frac{d\vec{B}}{ds}$ is in the plane of \vec{T} and \vec{N} and is perpendicular to \vec{T} , then it is parallel to \vec{N} .

$$\therefore \frac{d\vec{B}}{ds} = -\tau \vec{N}$$

where τ is the torsion and $\sigma = \frac{1}{\tau}$ is the radius of torsion.

c) We know, $\vec{N} = \vec{B} \times \vec{T}$ [$\because \vec{T}, \vec{N}$ and \vec{B} form a right-handed system.]

$$\Rightarrow \frac{d\vec{N}}{ds} = \vec{B} \times \frac{d\vec{T}}{ds} + \frac{d\vec{B}}{ds} \times \vec{T}$$

$$\Rightarrow \frac{d\vec{N}}{ds} = \vec{B} \times k \vec{N} + (-\tau \vec{N}) \times \vec{T}$$

$$\Rightarrow \frac{d\vec{N}}{ds} = k(\vec{B} \times \vec{N}) - \tau(\vec{N} \times \vec{T})$$

$$\Rightarrow \frac{d\vec{N}}{ds} = -k\vec{T} + \tau\vec{B}$$

$$\therefore \frac{d\vec{N}}{ds} = \tau\vec{B} - k\vec{T}$$

#19: The space curve $x = 3 \cos t$, $y = 3 \sin t$, $z = 4t$.

find: a) the unit tangent \vec{T}

b) the principal normal \vec{N} , curvature k and radius of curvature ρ

c) the binormal \vec{B} , torsion τ and radius of torsion σ .

Solution:

a) The curve, $\vec{r} = 3\cos t \hat{i} + 3\sin t \hat{j} + 4t \hat{k}$

$$\frac{d\vec{r}}{dt} = -3\sin t \hat{i} + 3\cos t \hat{j} + 4\hat{k}$$

$$\begin{aligned}\frac{ds}{dt} &= \left| \frac{d\vec{r}}{dt} \right| = \sqrt{9\sin^2 t + 9\cos^2 t + 16} \\ &= \sqrt{9+16} = 5\end{aligned}$$

$$\vec{T} = \frac{d\vec{r}}{ds} = \frac{\frac{d\vec{r}}{dt}}{\frac{ds}{dt}} = \frac{1}{5} (-3\sin t \hat{i} + 3\cos t \hat{j} + 4\hat{k}) \quad (0)$$

$$\begin{aligned}b) \frac{d\vec{T}}{dt} &= \frac{d}{dt} \left(\frac{1}{5} (-3\sin t \hat{i} + 3\cos t \hat{j} + 4\hat{k}) \right) \\ &= -\frac{3}{5}\cos t \hat{i} - \frac{3}{5}\sin t \hat{j} \\ \frac{d\vec{T}}{ds} &= \frac{\frac{d\vec{T}}{dt}}{\frac{ds}{dt}} = \frac{1}{25} (-3\cos t \hat{i} - 3\sin t \hat{j})\end{aligned}$$

$$\frac{d\vec{T}}{ds} = k \vec{N} \quad . \vec{T} \times \vec{B} = \frac{\vec{N} b}{eb}$$

$$\Rightarrow \left| \frac{d\vec{T}}{ds} \right| = k |\vec{N}|$$

$$\Rightarrow \left| \frac{d\vec{T}}{ds} \right| = k \cdot 1 \quad [\because \vec{N} \text{ is an unit vector, so } |\vec{N}|=1]$$

$$\Rightarrow k = \sqrt{\frac{1}{625} (9\cos^2 t + 9\sin^2 t)}$$

$$\Rightarrow k = \sqrt{\frac{1}{625} (9)} \quad . \vec{T} \text{ makes right angle with } \vec{B}$$

$$\therefore k = \frac{3}{25} \quad \therefore \rho = \frac{1}{k} = \frac{25}{3}$$

$$\frac{d\vec{T}}{ds} = \kappa \vec{N}$$

$$\Rightarrow \vec{N} = \frac{1}{\kappa} \frac{d\vec{T}}{ds} = q \text{ ved rövid felirat } s=0, (\text{c}) \vec{v} = \vec{v}_0$$

$$= \frac{25}{3} \times \frac{23}{25} (-\cos t \hat{i} - \sin t \hat{j})$$

$$= -\cos t \hat{i} - \sin t \hat{j}$$

$$\text{c) } \vec{B} \times \vec{x} = \vec{T} \times \vec{N}$$

$$= \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\sqrt{5}b}{2b} & \frac{\sqrt{5}b}{2b} & \frac{\sqrt{5}b}{2b} \\ -\frac{3}{5}\sin t & \frac{3}{5}\cos t & \frac{4}{5} \\ -\cos t & -\sin t & 0 \end{vmatrix} = \frac{\sqrt{5}b}{2b} \hat{T}$$

$$= \hat{i} \left(-\frac{4}{5} \sin t \right) - \hat{j} \left(\frac{3 \sin^2 t}{5} + \frac{3 \cos^2 t}{5} \right) + \hat{k} = \frac{\sqrt{5}b}{2b} \hat{T}$$

$$= \hat{i} \left(\frac{4}{5} \sin t \right) - \hat{j} \left(\frac{4}{5} \cos t \right) + \hat{k} \left(\frac{3 \sin^2 t}{5} + \frac{3 \cos^2 t}{5} \right)$$

$$= \frac{4 \sin t}{5} \hat{i} - \frac{4 \cos t}{5} \hat{j} + \frac{3}{5} \hat{k}$$

$$\frac{d\vec{B}}{dt} = \frac{4 \cos t}{5} \hat{i} + \frac{4 \sin t}{5} \hat{j} = \frac{4}{5} \left(\cos t \hat{i} + \sin t \hat{j} \right) = q$$

$$\frac{d\vec{B}}{ds} = \frac{\frac{d\vec{B}}{dt}}{\frac{ds}{dt}} = \frac{1}{5} \left(\frac{4 \cos t}{5} \hat{i} + \frac{4 \sin t}{5} \hat{j} \right) = \frac{4}{25} (\cos t \hat{i} + \sin t \hat{j})$$

$$\vec{T} \vec{N} = - \frac{d\vec{B}}{ds} \cdot \vec{N} = \frac{\sqrt{5}b}{2b} = \frac{\sqrt{5}b}{2b}, \hat{T} = \frac{\sqrt{5}b}{2b}$$

$$\Rightarrow \tau (\cos t \hat{i} + \sin t \hat{j}) = - \frac{4}{25} (\cos t \hat{i} + \sin t \hat{j})$$

$$\Rightarrow \tau = \frac{4}{25} \quad \rho = \frac{1}{\sqrt{\frac{4}{25}}} = \frac{25}{4}$$

$$\sqrt{\frac{ab}{eb}} + \sqrt{\frac{a^2}{eb}} - \sqrt{\frac{b^2}{eb}} =$$

20. Prove that the radius of curvature of the curve with parametric equations $x = x(s)$, $y = y(s)$, $z = z(s)$ is given by $\rho = \left[\left(\frac{d^2x}{ds^2} \right)^2 + \left(\frac{d^2y}{ds^2} \right)^2 + \left(\frac{d^2z}{ds^2} \right)^2 \right]^{-\frac{1}{2}}$

Solution:

The curve, $\vec{r} = x(s)\hat{i} + y(s)\hat{j} + z(s)\hat{k}$

$$\vec{T} = \frac{d\vec{r}}{ds} = \frac{dx}{ds}\hat{i} + \frac{dy}{ds}\hat{j} + \frac{dz}{ds}\hat{k}$$

$$\frac{d\vec{T}}{ds} = \frac{d^2x}{ds^2}\hat{i} + \frac{d^2y}{ds^2}\hat{j} + \frac{d^2z}{ds^2}\hat{k}$$

$$\Rightarrow \vec{kN} = \frac{d^2x}{ds^2}\hat{i} + \frac{d^2y}{ds^2}\hat{j} + \frac{d^2z}{ds^2}\hat{k}$$

$$\Rightarrow \kappa = \sqrt{\left(\frac{d^2x}{ds^2} \right)^2 + \left(\frac{d^2y}{ds^2} \right)^2 + \left(\frac{d^2z}{ds^2} \right)^2}$$

$$\Rightarrow \frac{1}{\rho} = \left[\left(\frac{d^2x}{ds^2} \right)^2 + \left(\frac{d^2y}{ds^2} \right)^2 + \left(\frac{d^2z}{ds^2} \right)^2 \right]^{\frac{1}{2}}$$

$$\Rightarrow \rho = \left[\left(\frac{d^2x}{ds^2} \right)^2 + \left(\frac{d^2y}{ds^2} \right)^2 + \left(\frac{d^2z}{ds^2} \right)^2 \right]^{-\frac{1}{2}}$$

(Prove)

21. Show that $\frac{d\vec{r}}{ds} \cdot \frac{d^2\vec{r}}{ds^2} \times \frac{d^3\vec{r}}{ds^3} = \frac{\tau}{\rho^2}$

Solution:

$$\frac{d\vec{r}}{ds} = \vec{T}, \quad \frac{d^2\vec{r}}{ds^2} = \frac{d\vec{T}}{ds} = \vec{kN}$$

$$\frac{d^3\vec{r}}{ds^3} = \frac{d}{ds}(\vec{kN}) = \vec{k} \frac{d\vec{N}}{ds} + \frac{d\vec{k}}{ds} \vec{N}$$

$$= \kappa (\vec{\tau} \vec{B} - \kappa \vec{\tau}) + \frac{d\kappa}{ds} \vec{N}$$

$$= \kappa \vec{\tau} \vec{B} - \kappa^2 \vec{\tau} + \frac{d\kappa}{ds} \vec{N}$$

$$\begin{aligned}
 L.H.S. &= \frac{d\vec{r}}{ds} \cdot \frac{d^2\vec{r}}{ds^2} \times \frac{d^3\vec{r}}{ds^3} \\
 &= \vec{T} \cdot k \vec{N} \times (k \tau \vec{B} - k^2 \vec{T} + \frac{d\kappa}{ds} \vec{N}) \\
 &= \vec{T} \cdot (k^2 \tau \vec{N} \times \vec{B} - k^3 \vec{T} \times \vec{N} + k \frac{d\kappa}{ds} \vec{N} \times \vec{N}) \\
 &= \vec{T} \cdot (k^2 \tau \vec{T} + k^3 \vec{B}) \\
 &= k^2 \tau \vec{T} \cdot \vec{T} + k^3 \vec{T} \cdot \vec{B} \\
 &= k^2 \tau \\
 &= \frac{\tau}{P^2} = R.H.S.
 \end{aligned}$$

$\therefore L.H.S. = R.H.S.$ (showed)

22. Given the space curve $x=t$, $y=t^2$, $z=\frac{2}{3}t^3$. find

- the curvature k ,
- the torsion τ .

Solution:

a) The curve, $\vec{r} = \hat{i} + t^2 \hat{j} + \frac{2t^3}{3} \hat{k}$

$$\frac{d\vec{r}}{dt} = \hat{i} + \frac{2t}{2} \hat{j} + 2t^2 \hat{k}$$

$$\left| \frac{d\vec{r}}{dt} \right| = \sqrt{1^2 + (2t)^2 + (2t^2)^2}$$

$$\begin{aligned}
 \Rightarrow \frac{ds}{dt} &= \sqrt{1+4t^2+4t^4} \\
 &= \sqrt{(1+2t^2)^2} \\
 &= 1+2t^2
 \end{aligned}$$

$$\vec{T} = \frac{\frac{d\vec{r}}{dt}}{\frac{ds}{dt}} = \frac{\hat{i} + 2t\hat{j} + 2t^2\hat{k}}{1+2t^2}$$

$$\begin{aligned}\frac{d\vec{T}}{dt} &= \frac{(1+2t^2)(2\hat{j} + 4t\hat{k}) - (\hat{i} + 2t\hat{j} + 2t^2\hat{k})(4t)}{(1+2t^2)^2} \\ &= (2+4t^2)\hat{j} + (4t+8t^3)\hat{k} - 4t\hat{i} - 8t^2\hat{j} - 8t^3\hat{k} \\ &= \frac{-4t\hat{i} + (2-4t^2)\hat{j} + 4t\hat{k}}{(1+2t^2)^2}\end{aligned}$$

$$\frac{d\vec{T}}{ds} = \frac{d\vec{T}/dt}{ds/dt} = \frac{-4t\hat{i} + (2-4t^2)\hat{j} + 4t\hat{k}}{(1+2t^2)^3}$$

$$\Rightarrow k\vec{N} = \frac{-4t\hat{i} + (2-4t^2)\hat{j} + 4t\hat{k}}{(1+2t^2)^3}$$

$$\Rightarrow k|\vec{N}| = \frac{\cancel{4t\hat{i} + (2-4t^2)\hat{j} + 4t\hat{k}}}{(1+2t^2)^3} = \frac{\sqrt{(4t)^2 + (2-4t^2)^2 + (4t)^2}}{(1+2t^2)^3}$$

$$\Rightarrow k = \frac{\sqrt{16t^2 + 4 - 16t^2 + 16t^4 + 16t^2}}{(1+2t^2)^3}$$

$$\Rightarrow k = \frac{\sqrt{4(1+2t^2)^2}}{(1+2t^2)^3}$$

$$\Rightarrow k = \frac{2}{(1+2t^2)^2}$$

$$\begin{aligned}b) \vec{N} &= \frac{1}{k} \frac{d\vec{T}}{ds} = \frac{(1+2t^2)^2}{2} \times \frac{-4t\hat{i} + (2-4t^2)\hat{j} + 4t\hat{k}}{(1+2t^2)^3} \\ &= \frac{-2t\hat{i} + (1-2t^2)\hat{j} + 2t\hat{k}}{1+2t^2}\end{aligned}$$

$$\vec{B} = \vec{T} \times \vec{N} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{1}{1+2t^2} & \frac{2t}{1+2t^2} & \frac{2t^2}{1+2t^2} \\ \frac{-2t}{1+2t^2} & \frac{1-2t^2}{1+2t^2} & \frac{2t}{1+2t^2} \end{vmatrix}$$

$$= \frac{1}{(1+2t^2)^2} \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ 1 & 2t & 2t^2 \\ -2t & 1-2t^2 & 2t \end{vmatrix}$$

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$$\text{teilen} = \frac{1}{(1+2t^2)^2} \left\{ \hat{i} (4t^2 - 2t^2 + 4t^4) - \hat{j} (2t + 2t^3) + \hat{k} (1-2t^2 + 4t^2) \right\}$$

$$= \frac{(2t^2 + 4t^4)\hat{i} - (2t + 4t^3)\hat{j} + (1+2t^2)\hat{k}}{(1+2t^2)^2}$$

$$= \frac{2t^2(1+2t^2)\hat{i} - 2t(1+2t^2)\hat{j} + 1(1+2t^2)\hat{k}}{(1+2t^2)^2}$$

$$= \frac{(1+2t^2)(2t^2\hat{i} - 2t\hat{j} + \hat{k})}{(1+2t^2)^2}$$

$$= \frac{2t^2\hat{i} - 2t\hat{j} + \hat{k}}{1+2t^2}$$

$$\frac{d\vec{B}}{dt} = \frac{(1+2t^2)(4t\hat{i} - 2\hat{j}) - (2t^2\hat{i} - 2t\hat{j} + \hat{k})(4t)}{(1+2t^2)^2}$$

$$\frac{d\vec{B}}{ds} = \frac{d\vec{B}/dt}{ds/dt} = \frac{(4t+8t^3-8t^3)\hat{i} + (-2-4t^2+8t^2)\hat{j} - 4t\hat{k}}{(1+2t^2)^3}$$

$$\Rightarrow -T\vec{N} = \frac{4t\hat{i} + (4t^2-2)\hat{j} - 4t\hat{k}}{(1+2t^2)^3}$$

$$\Rightarrow -\tau \left[-\frac{2t\hat{i} - (1-2t^2)\hat{j} - 2t\hat{k}}{1+2t^2} \right] = \frac{2\{2t\hat{i} - (21-2t^2)\hat{j} - 2t\hat{k}\}}{(1+2t^2)^3}$$

$$\Rightarrow \tau = \frac{2\{2t\hat{i} - (1-2t^2)\hat{j} - 2t\hat{k}\}}{(1+2t^2)^3} \times \frac{1+2t^2}{2t\hat{i} + (1-2t^2)\hat{j} - 2t\hat{k}}$$

$$\Rightarrow \tau = \frac{2}{(1+2t^2)^2}$$

Exercise:

32: Find the velocity and acceleration of a particle which moves along the curve $x = 2 \sin 3t$, $y = 2 \cos 3t$, $z = 8t$ at any time $t > 0$. Find the magnitude of the velocity and acceleration.

Solution:

The curve, $\vec{r} = 2 \sin 3t \hat{i} + 2 \cos 3t \hat{j} + 8t \hat{k}$

$$\vec{v} = \frac{d\vec{r}}{dt} = 6 \cos 3t \hat{i} - 6 \sin 3t \hat{j} + 8 \hat{k}$$

$$\therefore |\vec{v}| = \sqrt{36 \cos^2 3t + 36 \sin^2 3t + 64} \\ = \sqrt{36+64} = 10$$

$$\vec{a} = \frac{d\vec{v}}{dt} = -18 \sin 3t \hat{i} - 18 \cos 3t \hat{j} \\ =$$

$$= \sqrt{324 \sin^2 3t + 324 \cos^2 3t}$$

$$= \sqrt{324} = 18$$

35: If $\vec{A} = \sin u \hat{i} + \cos u \hat{j} + u \hat{k}$, $\vec{B} = \cos u \hat{i} - \sin u \hat{j} - 3\hat{k}$
 and $\vec{C} = 2\hat{i} + 3\hat{j} - \hat{k}$. Find $\frac{d}{du} \{\vec{A} \times (\vec{B} \times \vec{C})\}$ at $u=0$.

Solution:

$$\begin{aligned}\vec{A} \cdot \vec{B} \times \vec{C} &= \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \cos u & -\sin u & -3 \\ 2 & 3 & -1 \end{vmatrix} \\ &= \hat{i}(\sin u + 9) - \hat{j}(-\cos u + 6) + \hat{k}(3\cos u + 2\sin u) \\ &= (\sin u + 9)\hat{i} + (\cos u + 6)\hat{j} + (3\cos u + 2\sin u)\hat{k}\end{aligned}$$

$$\begin{aligned}\vec{A} \times (\vec{B} \times \vec{C}) &= \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \sin u + 9 & \cos u - 6 & 3\cos u + 2\sin u \\ \cos u + 6 & -\sin u - 9u & -6\sin u - 9\cos u \end{vmatrix} \\ &= \hat{i}(3\cos^2 u + 2\sin u \cos u - u\cos u + 6u) \\ &\quad - \hat{j}(3\sin u \cos u + 2\sin^2 u - u\sin u - 9u) \\ &\quad + \hat{k}(\sin u \cos u - 6\sin u - \sin u \cos u - 9\cos u) \\ &= \hat{i}(3\cos^2 u + 2\sin u \cos u - u\cos u + 6u) \\ &\quad - \hat{j}(3\sin u \cos u + 2\sin^2 u - u\sin u - 9u) \\ &\quad + \hat{k}(-6\sin u - 9\cos u)\end{aligned}$$

$$\begin{aligned}\therefore \frac{d}{du} \{\vec{A} \times (\vec{B} \times \vec{C})\} &= \hat{i}(-\cancel{\sin u} + 2\cos^2 u - 2\sin^2 u - \cos u \\ &\quad + u\sin u + 6) \\ &\quad - \hat{j}(3\sin^2 u + 3\cos^2 u + 4\sin u \cos u \\ &\quad - \sin u - u\cos u - 9) \\ &\quad + \hat{k}(-6\cos u + 9\sin u)\end{aligned}$$

$$\text{at } u=0, \vec{A} = \hat{i} + 2\hat{j} + \hat{k}, \vec{B} = 2\hat{i} + \hat{j} + \hat{k}, \vec{C} = \hat{i} - \hat{j} + \hat{k}$$

$$\frac{d}{du} \{ \vec{A} \times (\vec{B} \times \vec{C}) \} = \hat{i}(2-1+6) - \hat{j}(3-9) + \hat{k}(-6)$$

$$= 7\hat{i} + 6\hat{j} - 6\hat{k}$$

38: If $\frac{d^2 \vec{A}}{dt^2} = 6t\hat{i} - 24t^2\hat{j} + 4\sin t\hat{k}$, find \vec{A} . Given

that $\vec{A} = 2\hat{i} + \hat{j}$ and $\frac{d\vec{A}}{dt} = -\hat{i} - 3\hat{k}$ at $t=0$

Solution:

$$\frac{d^2 \vec{A}}{dt^2} = 6t\hat{i} - 24t^2\hat{j} + 4\sin t\hat{k}$$

$$\Rightarrow \frac{d}{dt} \left(\frac{d\vec{A}}{dt} \right) = 6t\hat{i} - 24t^2\hat{j} + 4\sin t\hat{k}$$

$$\Rightarrow d \left(\frac{d\vec{A}}{dt} \right) = (6t\hat{i} - 24t^2\hat{j} + 4\sin t\hat{k}) dt$$

By integrating,

$$\int d \left(\frac{d\vec{A}}{dt} \right) = \int (6t\hat{i} - 24t^2\hat{j} + 4\sin t\hat{k}) dt$$

$$\Rightarrow \frac{d\vec{A}}{dt} = 3t^2\hat{i} - 8t^3\hat{j} - 4\cos t\hat{k} + C_1 \quad \dots \dots \dots (i)$$

where C_1 is an integrating constant

at $t=0$,

$$\frac{d\vec{A}}{dt} = -4\hat{k} + C_1$$

$$\Rightarrow -\hat{i} - 3\hat{k} = -4\hat{k} + C_1$$

$$\Rightarrow C_1 = \hat{i} + \hat{k}$$

putting the value of c_1 in equation (i)

$$\frac{d\vec{A}}{dt} = 3t^2\hat{i} - 8t^3\hat{j} - 4\cos t\hat{k} - \hat{i} + \hat{k}$$

$$\Rightarrow \frac{d\vec{A}}{dt} = (3t^2 - 1)\hat{i} - 8t^3\hat{j} - (4\cos t - 1)\hat{k}$$

$$\Rightarrow d\vec{A} = \{(3t^2 - 1)\hat{i} - 8t^3\hat{j} - (4\cos t - 1)\hat{k}\} dt$$

By integrating

$$\int d\vec{A} = \int \{(3t^2 - 1)\hat{i} - 8t^3\hat{j} - (4\cos t - 1)\hat{k}\} dt$$

$$\Rightarrow \vec{A} = (t^3 - t)\hat{i} - 2t^4\hat{j} - (4\sin t - t)\hat{k} + c_2$$

where c_2 is integrating constant.

at $t=0$

$$\vec{A} = c_2(0) + \hat{i}(0) + \hat{j}(0) + \hat{k}(0) = \frac{tb}{\sin b} = \frac{\pi b}{\sin b} = \frac{\pi b}{eb}$$

putting the value of c_2 in equation (ii)

$$\vec{A} = (t^3 - t)\hat{i} - 2t^4\hat{j} - (4\sin t - t)\hat{k} + 2\hat{i} + \hat{j}$$

$$\therefore \vec{A} = (t^3 - t + 2)\hat{i} + (1 - 2t^4)\hat{j} + (t - 4\sin t)\hat{k}$$

- # 47: Find, a) the unit tangent \vec{T} ,
 b) the curvature k , c) the principal normal \vec{N}
 d) the binormal \vec{B} , e) the torsion τ for the
 space curve $x = t - \frac{t^3}{3}$, $y = t^2$, $z = t + \frac{t^3}{3}$

Solution:

a) The curve, $\vec{r} = \left(t - \frac{t^3}{3}\right)\hat{i} + t^2\hat{j} + \left(t + \frac{t^3}{3}\right)\hat{k}$
 $\frac{d\vec{r}}{dt} = (1-t^2)\hat{i} + 2t\hat{j} + (1+t^2)\hat{k}$

$$(ii) \quad \frac{ds}{dt} = \left| \frac{d\vec{r}}{dt} \right| = \sqrt{1-2t^2+t^4+4t^2+1+2t^2+t^4} \\ = \sqrt{2+4t^2+2t^4} = \sqrt{2(1+t^2)^2} \\ = \sqrt{2}(1+t^2)$$

$$\vec{T} = \frac{d\vec{r}}{ds} = \frac{d\vec{r}/dt}{ds/dt} = \frac{(1-t^2)\hat{i} + 2t\hat{j} + (1+t^2)\hat{k}}{\sqrt{2}(1+t^2)}$$

b) $\frac{d\vec{T}}{dt} = \frac{d}{dt} \left(\frac{(1-t^2)\hat{i} + 2t\hat{j} + (1+t^2)\hat{k}}{\sqrt{2}(1+t^2)} \right)$
 ~~\vec{RN}~~ $= \frac{\sqrt{2}(1+t^2)(-2t\hat{i} + 2\hat{j} + 2t\hat{k}) - \sqrt{2}(1+t^2) \cdot 2\sqrt{2}t}{2(1+t^2)^2}$
 ~~\vec{RN}~~ $= \frac{-2t(1+t^2)\hat{i} + 2(1+t^2)\hat{j} + 2t(1+t^2)\hat{k} - 2t(1-t^2)\hat{i} - 4t^2\hat{j} - 2t(1+t^2)\hat{k}}{\sqrt{2}(1+t^2)^2}$
 ~~\vec{RN}~~ $= \frac{(-2t-2t^3-2t+2t^3)\hat{i} + (2+2t^2-4t^2)\hat{j} + (2t+2t^3-2t-2t^3)\hat{k}}{\sqrt{2}(1+t^2)^2}$

$$\Rightarrow \vec{t} = \frac{-4t\hat{i} + (2 - 2t^2)\hat{j}}{\sqrt{2}(1+t^2)^2}$$

$$\Rightarrow \|\vec{t}\| = \frac{\sqrt{16t^2 + 4 - 8t^2 + 4t^4}}{\sqrt{2}(1+t^2)^2}$$

$$\Rightarrow \vec{s} = \frac{4 + 8t^2 + 4t^4}{\sqrt{2}(1+t^2)^2}$$

$$\Rightarrow \vec{s} = \frac{4(1+t^2)}{\sqrt{2}(1+t^2)^2}$$

$$= \frac{2(1+t^2)}{\sqrt{2}(1+t^2)^2}$$

$$= \frac{\sqrt{2}}{1+t^2}$$

$$\frac{d\vec{T}}{ds} = \frac{d\vec{T}/dt}{ds/dt}$$

$$\Rightarrow \vec{k}_N = \frac{\{-4t\hat{i} + (2 - 2t^2)\hat{j}\} (\cancel{1+t^2})}{\sqrt{2}(1+t^2)^2 \sqrt{2}(1+t^2)}$$

$$\Rightarrow k_N = \frac{\sqrt{16t^2 + 4 - 8t^2 + 4t^4}}{2(1+t^2)^3}$$

$$\Rightarrow k = \frac{\sqrt{4(1+t^2)^2}}{2(1+t^2)^3}$$

$$\Rightarrow k = \frac{2(1+t^2)}{2(1+t^2)^3} \therefore k = \frac{1}{(1+t^2)^2}$$

$$c) \frac{d\vec{T}}{ds} = \kappa \vec{N}$$

$$\Rightarrow \vec{N} = \frac{1}{\kappa} \frac{d\vec{T}/dt}{ds/dt}$$

$$= \frac{(1+t^2)^2 \{-4t\hat{i} + (2-2t^2)\hat{j}\}}{2 \cdot (1+t^2)^3}$$

$$= \frac{-4t\hat{i} + (2-2t^2)\hat{j}}{2(1+t^2)}$$

$$= \frac{-2t\hat{i} + (1-t^2)\hat{j}}{(1+t^2)}$$

d)

$$\vec{B} = \vec{T} \times \vec{N}$$

$$= \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{1-t^2}{\sqrt{2}(1+t^2)} & \frac{2t}{\sqrt{2}(1+t^2)} & \frac{1+t^2}{\sqrt{2}(1+t^2)} \\ -\frac{2t}{1+t^2} & \frac{1-t^2}{1+t^2} & 0 \end{vmatrix}$$

$$= \frac{1}{\sqrt{2}(1+t^2)^2} \left[\hat{i} \{(-1+t^4) - j(2t+2t^3)\} + \hat{k} \{ (1-t^2)^2 + 4t^2 \} \right]$$

$$= \frac{1}{\sqrt{2}(1+t^2)^2} \left[(t^4-1)\hat{i} - 2t(1+t^2)\hat{j} + (1+t^2)^2 \hat{k} \right]$$

$$= \frac{1}{\sqrt{2}(1+t^2)^2} (1+t^2) \left[(t^2-1)\hat{i} - 2t\hat{j} + (1+t^2)\hat{k} \right]$$

$$= \frac{1}{\sqrt{2}(1+t^2)} \left[(t^2-1)\hat{i} - 2t\hat{j} + (1+t^2)\hat{k} \right]$$

e)

$$\begin{aligned} \frac{d\vec{B}}{dt} &= \frac{\sqrt{2}(1+t^2)(2t\hat{i} - 2\hat{j} + 2\hat{k}) - \{(t^2-1)\hat{i} - 2t\hat{j} + (1+t^2)\hat{k}\} 2\sqrt{2}t}{2(1+t^2)^2} \\ &= \frac{(2t+2t^3)\hat{i} - (2+2t^2)\hat{j} + (2t+2t^3)\hat{k} - (2t^3-2t)\hat{i} + 4t\hat{j} - (2+2t^4)\hat{k}}{\sqrt{2}(1+t^2)^2} \\ &= \frac{(2t+2t^3-2t^3+2t)\hat{i} + (-2-2t^2+4t)\hat{j} + (2t+2t^3-2t-2t^3)\hat{k}}{\sqrt{2}(1+t^2)^2} \\ &= \frac{4t\hat{i} + (2t^2-2)\hat{j}}{\sqrt{2}(1+t^2)^2} \end{aligned}$$

$$\frac{d\vec{B}}{ds} = \frac{d\vec{B}/dt}{ds/dt}$$

$$\Rightarrow -T\vec{N} = \frac{4t\hat{i} + (2t^2-2)\hat{j}}{\sqrt{2}(1+t^2)^2} \Rightarrow -T\vec{N} = \frac{-\{-4t\hat{i} - (2t^2-2)\hat{j}\}}{2(1+t^2)^3}$$

$$\Rightarrow T|\vec{N}| = \frac{\sqrt{16t^2 + (2t^2-2)^2}}{2(1+t^2)^3} \Rightarrow T|\vec{N}| = \frac{\sqrt{16t^2 + 4t^4 - 8t^2 + 4}}{2(1+t^2)^3}$$

~~$$\Rightarrow T = \frac{\sqrt{4(1+t^2)^2}}{2(1+t^2)^3}$$~~

$$\Rightarrow T = \frac{2(1+t^2)}{2(1+t^2)^3}$$

$$\therefore T = \frac{1}{(1+t^2)^2}$$

49: Find k and T for the space curve $x=t$, $y=t^2$, $z=t^3$ called the twisted cubic.

Solution:

The curve, $\vec{r} = \hat{i} + t^2 \hat{j} + t^3 \hat{k}$

$$\frac{d\vec{r}}{dt} = \hat{i} + 2t \hat{j} + 3t^2 \hat{k}$$

$$\frac{ds}{dt} = \left| \frac{d\vec{r}}{dt} \right| = \sqrt{1^2 + 4t^2 + 9t^4} = \sqrt{9t^4 + 4t^2 + 1}$$

$$T = \frac{d\vec{r}}{ds} = \frac{d\vec{r}/dt}{ds/dt}$$

$$= \frac{\hat{i} + 2t \hat{j} + 3t^2 \hat{k}}{\sqrt{9t^4 + 4t^2 + 1}}$$

$$\frac{dT}{dt} = \frac{(\sqrt{9t^4 + 4t^2 + 1})(2\hat{j} + 6t\hat{k}) - }{9t^4 + 4t^2 + 1} \cdot \frac{(\hat{i} + 2t\hat{j} + 3t^2\hat{k})(36t^3 + 8t)}$$

$$= \frac{2(9t^4 + 4t^2 + 1)(2\hat{j} + 6t\hat{k}) - (\hat{i} + 2t\hat{j} + 3t^2\hat{k})(36t^3 + 8t)}{2(9t^4 + 4t^2 + 1)^{\frac{3}{2}}}$$

$$= \cancel{-\hat{i} + \frac{(36t^4 + 16t^2)}{2}}$$

$$= \cancel{(36t^3 + 8t)\hat{i} + (36t^4 + 16t^2 + 4 - 72t^4 - 16t^2)\hat{j}}$$

$$+ (-)$$

$$2[-(18t^3 + 4t)\hat{i} + (18t^4 + 8t^2 + 2 - 36t^4 - 8t^2)\hat{j}]$$

$$= \cancel{+ (54t^5 + 24t^3 + 6t - 54t^5 - 12t^3)\hat{k}}$$

$$= \frac{2(-18t^3\hat{i} + 18t^4\hat{j} + 8t^2\hat{j} + 2\hat{j} - 36t^4\hat{i} - 8t^2\hat{i} + 54t^5\hat{k} + 24t^3\hat{k} + 6t\hat{k} - 54t^5\hat{k} - 12t^3\hat{k})}{2(9t^4 + 4t^2 + 1)^{\frac{3}{2}}}$$

$$= \frac{-(18t^3 + 4t) \hat{i} + (2 - 18t^4) \hat{j} + (12t^3 + 6t) \hat{k}}{(9t^4 + 4t^2 + 1)^{\frac{3}{2}}}$$

$$\frac{tb}{tb/cb} = \frac{1}{4}$$

$$\frac{1}{4}$$

$$\frac{d\vec{T}}{ds} = \frac{d\vec{T}/dt}{ds/dt} + \vec{i}(L^2 + A + P) \times \frac{\vec{i}(L^2 + A + P)}{L^2 + A + P + C/L^2}$$

$$\Rightarrow k \vec{N} = \frac{-(18t^3 + 4t) \hat{i} + (2 - 18t^4) \hat{j} + (12t^3 + 6t) \hat{k}}{(9t^4 + 4t^2 + 1)^{\frac{3}{2}} (9t^4 + 4t^2 + 1)^{\frac{1}{2}}}$$

$$\Rightarrow k \cdot |\vec{N}| = \frac{\sqrt{324t^6 + 144t^4 + 16t^2 + 4 - 72t^4 + 324t^8 + 144t^6 + 144t^4 + 36t^2}}{(9t^4 + 4t^2 + 1)^2}$$

$$\Rightarrow k = \frac{\sqrt{324t^8 + 468t^6 + 216t^4 + 52t^2 + 4}}{(9t^4 + 4t^2 + 1)^2}$$

$$= \frac{\sqrt{4(81t^8 + 117t^6 + 54t^4 + 13t^2 + 1)}}{(9t^4 + 4t^2 + 1)^2}$$

$$= \frac{2 \sqrt{(9t^4 + 4t^2 + 1)(9t^4 + 9t^2 + 1)}}{L^2 + A^2 + P^2 + C/L^2}$$

$$= \frac{2 \sqrt{(9t^4 + 9t^2 + 1)^2}}{(9t^4 + 4t^2 + 1)^{\frac{3}{2}}} \frac{1}{L^2 + A^2 + P^2 + C/L^2}$$

$$\frac{d\vec{T}}{ds} = \kappa \vec{N}$$

$$\Rightarrow \vec{N} = \frac{1}{\kappa} - \frac{d\vec{T}/dt}{ds/dt}$$

$$= \frac{(9t^4 + 4t^2 + 1)^{\frac{3}{2}}}{2\sqrt{9t^4 + 9t^2 + 1}} \times \frac{-(18t^3 + 4t)\hat{i} + (2 - 18t^4)\hat{j} + (12t^3 + 6t)\hat{k}}{(9t^4 + 4t^2 + 1)^2}$$

$$= \frac{-(18t^3 + 4t)\hat{i} + (2 - 18t^4)\hat{j} + (12t^3 + 6t)\hat{k}}{2\sqrt{(9t^4 + 9t^2 + 1)(9t^4 + 4t^2 + 1)}}$$

$$\vec{B} = \vec{T} \times \vec{N} = \frac{\vec{T} \times \vec{N}}{|T|} = |\vec{N}| \cdot \vec{N}$$

$$= \frac{-(18t^3 + 4t)\hat{i} + (2 - 18t^4)\hat{j} + (12t^3 + 6t)\hat{k}}{2(9t^4 + 4t^2 + 1)\sqrt{9t^4 + 9t^2 + 1}}$$

$$\Rightarrow \frac{i(24t^4 + 12t^2 - 6t^2 + 54t^6) - j(12t^3 + 6t + 54t^5 + 12t^3) + k(2 - 18t^4 + 36t^4 + 8t^2)}{2(9t^4 + 4t^2 + 1)\sqrt{9t^4 + 9t^2 + 1}}$$

$$= \frac{2[2(27t^6 + 12t^4 + 3t^2)\hat{i} - (27t^5 + 12t^3 + 3t)\hat{j} + (9t^4 + 4t^2 + 1)\hat{k}]}{2(9t^4 + 4t^2 + 1)\sqrt{9t^4 + 9t^2 + 1}}$$

$$\begin{aligned}
 &= \frac{3t^2(9t^4 + 4t^2 + 1)\hat{i} - 3t(9t^4 + 4t^2 + 1)\hat{j} + (9t^4 + 4t^2 + 1)\hat{k}}{\cancel{(9t^4 + 4t^2 + 1)}\sqrt{9t^4 + 9t^2 + 1}} \\
 &= \frac{3t^2\hat{i} - 3t\hat{j} + \hat{k}}{\cancel{\sqrt{9t^4 + 9t^2 + 1}}} \\
 \frac{d\vec{B}}{dt} &= \frac{\sqrt{9t^4 + 9t^2 + 1}(6t\hat{i} - 3\hat{j}) - \frac{(3t^2\hat{i} - 3t\hat{j} + \hat{k})(36t^3 + 18t)}{2\sqrt{9t^4 + 9t^2 + 1}}}{9t^4 + 9t^2 + 1} \\
 &= \frac{2(9t^4 + 9t^2 + 1)(6t\hat{i} - 3\hat{j}) - (3t^2\hat{i} - 3t\hat{j} + \hat{k})(36t^3 + 18t)}{2(9t^4 + 9t^2 + 1)^{\frac{3}{2}}} \\
 &= \frac{2[\hat{i}(54t^5 + 54t^3 + 6t - 54t^5 - 27t^3) + \hat{j}(-27t^4 - 27t^2 - 3 + 54t^4 + 27t^2) - (18t^3 + 9t)\hat{k}]}{2(9t^4 + 9t^2 + 1)^{\frac{3}{2}}} \\
 &= \frac{(27t^3 + 6t)\hat{i} + (27t^4 - 3)\hat{j} - (18t^3 + 9t)\hat{k}}{(9t^4 + 9t^2 + 1)^{\frac{3}{2}}}
 \end{aligned}$$

$$\frac{d \vec{B}}{ds} = \frac{d \vec{B}/dt}{ds/dt} = \frac{(L + s + P + A + C) \hat{i} + (L + s + P + A + C) \hat{j} + (L + s + P + A + C) \hat{k}}{(L + s + P + A + C)^2}$$

$$\Rightarrow -T \vec{N} = \frac{-\{-(27t^3 + 6t)\hat{i} - (27t^4 - 3)\hat{j} + (18t^3 + 9t)\hat{k}\}}{(9t^4 + 9t^2 + 1)^{\frac{3}{2}} (9t^4 + 4t^2 + 1)^{\frac{1}{2}}}$$

$$\Rightarrow T |\vec{N}| = \frac{\sqrt{729t^6 + 324t^4 + 36t^2 + 729t^8 - 162t^4 + 9}}{(9t^4 + 9t^2 + 1)^{\frac{3}{2}} (9t^4 + 4t^2 + 1)^{\frac{1}{2}}}$$

$$\Rightarrow T = \frac{\sqrt{729t^8 + 1053t^6 + 486t^4 + 117t^2 + 9}}{(9t^4 + 9t^2 + 1)^{\frac{3}{2}} (9t^4 + 4t^2 + 1)^{\frac{1}{2}}}$$

$$= \frac{\sqrt{9(81t^8 + 117t^6 + 54t^4 + 13t^2 + 1)}}{(9t^4 + 9t^2 + 1)^{\frac{3}{2}} (9t^4 + 4t^2 + 1)^{\frac{1}{2}}}$$

$$= \frac{3 \sqrt{9t^4 + 9t^2 + 1} \sqrt{9t^4 + 4t^2 + 1}}{(9t^4 + 9t^2 + 1)^{\frac{3}{2}} (9t^4 + 4t^2 + 1)^{\frac{1}{2}}}$$

$$= \frac{3}{9t^4 + 9t^2 + 1}$$

#54: Prove that the curvature of the space curve $\vec{r} = \vec{r}(t)$ is given numerically by (a)

$$k = \frac{|\dot{r} \times \ddot{r}|}{|\dot{r}|^3} \text{ where dots denote differentiation}$$

respect to t . (a) if it is known with \vec{r}

Solution:

$$\dot{r} = \frac{d\vec{r}}{dt} = \frac{d\vec{r}}{ds} \times \frac{ds}{dt} = \vec{T} \dot{s}$$

$$|\dot{r}| = \left| \frac{d\vec{r}}{dt} \right| = \frac{ds}{dt} = \dot{s}$$

$$\begin{aligned}\ddot{r} &= \frac{d}{dt}(\dot{r}) \\ &= \dot{s} \vec{T} + \dot{s} \frac{d\vec{T}}{dt} \\ &= \dot{s} \vec{T} + \dot{s} \frac{d\vec{T}}{ds} \times \frac{ds}{dt} \\ &= \dot{s} \vec{T} + (\dot{s})^2 k \vec{N} \quad [\because \frac{d\vec{T}}{ds} = \vec{N} \text{ & } \frac{d\vec{T}}{ds} = k \vec{N}]\end{aligned}$$

$$\dot{r} \times \ddot{r} = \begin{vmatrix} \vec{T} & \vec{N} & \vec{B} \\ \dot{s} & 0 & 0 \\ \ddot{s} & (\dot{s})^2 k & 0 \end{vmatrix}$$

$$= (\dot{s})^3 k \vec{B}$$

$$\therefore |\dot{r} \times \ddot{r}| = (\dot{s})^3 k |\vec{B}| = (\dot{s})^3 k$$

$$\therefore k = \frac{|\dot{r} \times \ddot{r}|}{(\dot{s})^3} = \frac{|\dot{r} \times \ddot{r}|}{|\dot{r}|^3}. \text{ (Proved)}$$

E#55:

a) Prove that $\tau = \frac{\dot{r} \cdot (\ddot{r} \times \ddot{r})}{|\dot{r} \times \ddot{r}|^2}$ for the space curve $\vec{r} = \vec{r}(t)$.

b) If the parameter s is the arc length

s. Show that $\tau = \frac{\frac{d\vec{r}}{ds} \cdot \frac{d^2\vec{r}}{ds} \times \frac{d^3\vec{r}}{ds^3}}{\left(\frac{d^2\vec{r}}{ds^2}\right)^2}$

Solution:

a)

$$\dot{r} = \frac{d\vec{r}}{dt} = \frac{d\vec{r}}{ds} \times \frac{ds}{dt} = \vec{T} \dot{s}$$

$$\ddot{r} = \ddot{s} \vec{T} + \dot{s} \frac{d\vec{T}}{dt}$$

$$= \ddot{s} \vec{T} + \dot{s} \frac{d\vec{T}}{ds} \times \frac{ds}{dt}$$

$$= \ddot{s} \vec{T} + (\dot{s})^2 k \vec{N}$$

$$\ddot{r} = \ddot{s} \vec{T} + \dot{s} \frac{d\vec{T}}{dt} + 2\dot{s}\ddot{s} k \vec{N} + (\dot{s})^2 k \frac{d\vec{N}}{dt}$$

$$= \ddot{s} \vec{T} + \dot{s} \frac{d\vec{T}}{ds} \times \frac{ds}{dt} + 2k\dot{s}\ddot{s} \vec{N} + (\dot{s})^2 k \frac{d\vec{N}}{ds} \times \frac{ds}{dt}$$

$$= \ddot{s} \vec{T} + k\dot{s}\ddot{s} \vec{N} + 2k\dot{s}\ddot{s} \vec{N} + k(\dot{s})^3 (\vec{T} \vec{B} - k \vec{T})$$

$$= \{ \ddot{s} - k^2(\dot{s})^3 \} \vec{T} + 3k\dot{s}\ddot{s} \vec{N} + k\dot{s}(\dot{s})^3 \vec{B}$$

$$\begin{aligned} \ddot{s}(\dot{s}) &= |\ddot{s}|, \quad \ddot{s}(\dot{s}) = |\ddot{s} \times \dot{s}|, \\ (6s^2 + 9) &\cdot \frac{|\dot{s} \times \ddot{s}|}{|\ddot{s}|} = \frac{|\dot{s} \times \ddot{s}|}{\ddot{s}(\dot{s})} = 2 \end{aligned}$$

$$\begin{aligned}\ddot{r} \times \ddot{r} &= \begin{vmatrix} \vec{T} & \vec{N} & \vec{B} \\ 3 & (\dot{s})^2 k & 0 \\ \ddot{s} - k^2(\dot{s})^3 & 3\dot{s}\ddot{s}k + kT(\dot{s})^3 & \end{vmatrix} = \\ &= \vec{T} \left\{ (\dot{s})^5 k^2 T \right\} - \vec{N} \left\{ (\dot{s})^3 \dot{s} k T \right\} + \\ &\quad + \vec{B} \left[3\dot{s}(\dot{s})^2 k - (\dot{s})^2 k \left\{ \ddot{s} - k^2(\dot{s})^3 \right\} \right]\end{aligned}$$

$$\dot{r} \cdot (\ddot{r} \times \ddot{r}) = k^2(\dot{s})^6 T - 0 - 0$$

$$\Rightarrow T = \frac{\dot{r} \cdot (\ddot{r} \times \ddot{r})}{k^2(\dot{s})^6}$$

$$\Rightarrow T = \frac{\dot{r} \cdot (\ddot{r} \times \ddot{r})}{|\ddot{r} \times \ddot{r}|^2} \quad (\text{Proved})$$

$$\begin{aligned}b) R \cdot H \cdot S &= \frac{\frac{d\vec{r}}{ds} \cdot \frac{d^2\vec{r}}{ds^2} \times \frac{d^3\vec{r}}{ds^3}}{\left(\frac{d^2\vec{r}}{ds^2} \right)^2} \\ &= \frac{\vec{T} \cdot \left(\frac{d\vec{T}}{ds} \times \frac{d^2\vec{T}}{ds^2} \right)}{\left(\frac{d\vec{T}}{ds} \right)^2} \\ &= \frac{\vec{T} \cdot \left\{ k\vec{N} \times \frac{d}{ds}(k\vec{N}) \right\}}{(k\vec{N})^2}\end{aligned}$$

$$\begin{aligned}
 &= \frac{\vec{T} \cdot k^2 \{ \vec{N} \times (\tau \vec{B} - k \vec{T}) \}}{(k \vec{N})^2} \\
 &= \frac{\vec{T} \cdot k^2 [\tau (\vec{N} \times \vec{B}) - k (\vec{N} \times \vec{T})]}{k^2 (\vec{N} \cdot \vec{N})} \\
 &= \frac{\vec{T} \cdot k^2 [\tau \vec{T} + k \vec{B}]}{k^2} \\
 &= \frac{k^2 \tau (\vec{T} \cdot \vec{T}) + k^3 (\vec{T} \cdot \vec{B})}{k^2} \\
 &= \frac{k^2 \tau}{k^2} \\
 &= \tau
 \end{aligned}$$

$$= R \cdot H \cdot S.$$

$$\therefore L.H.S. = R.H.S. \quad (\text{showed})$$

58: Find the torsion of the curve

$$x = \frac{2t+1}{t-1}, \quad y = \frac{t^2}{t-1}, \quad z = t+2.$$

Solution:

$$\text{The curve, } \vec{r} = \left(\frac{2t+1}{t-1} \right) \hat{i} + \left(\frac{t^2}{t-1} \right) \hat{j} + (t+2) \hat{k}$$

$$\frac{d\vec{r}}{dt} = -\frac{3}{(t-1)^2} \hat{i} + \frac{t^2-2t}{(t-1)^2} \hat{j} + \hat{k}$$

$$= \left| \frac{d\vec{R}}{dt} \right| = \sqrt{\frac{9}{(t-1)^4} + \frac{(t^2-2t)^2}{(t-1)^4} + 1}$$

$$\therefore \frac{\vec{s}_v}{t-1} + \vec{T} \frac{vb}{tb} = \vec{o}$$

Since at instant time t , \vec{T} is
at 90° from beginning time t_0 at
 t_0 , \vec{T} makes an angle θ with \vec{o}

time t_0 is \vec{v}_0 \vec{v} = \vec{v}_0

\vec{T} instant t_0

$$\vec{T}_v = \vec{v} \leftarrow$$

$$\frac{tb}{tb} \vec{v} + \vec{T} \frac{vb}{tb} = \frac{vb}{tb}$$

$$\frac{cb}{tb} \cdot \frac{tb}{cb} \vec{v} + \vec{T} \frac{vb}{tb} =$$

$$\frac{tb}{cb} \left\{ \frac{cb}{tb} \right\} \vec{v} + \vec{T} \frac{vb}{tb} =$$

$$\vec{v} + \vec{T} \frac{vb}{tb} =$$

$$(b) \vec{v}_0 + \vec{T} \frac{vb}{tb} = \vec{o}$$

18-02-2018: 3E: Sunday

→ Show that the acceleration \vec{a} of a particle which travels along a space curve with velocity v is given by

$$\vec{a} = \frac{dv}{dt} \vec{T} + \frac{v^2}{\rho} \vec{N}$$

where \vec{T} is the unit tangent vector to the space curve \vec{N} is the unit principal normal and ρ is the radius of curvature.

Solution:

Velocity, \vec{v} = magnitude of $|\vec{v}|$ multiplied by unit tangent vector \vec{T}

$$\Rightarrow \vec{v} = v \vec{T}$$

Differentiating,

$$\begin{aligned}\frac{d\vec{v}}{dt} &= \frac{dv}{dt} \vec{T} + v \frac{d\vec{T}}{dt} \\ &= \frac{dv}{dt} \vec{T} + v \frac{d\vec{T}}{ds} \cdot \frac{ds}{dt} \\ &= \frac{dv}{dt} \vec{T} + v \left| \frac{d\vec{T}}{dt} \right| \frac{d\vec{T}}{ds} \\ &= \frac{dv}{dt} \vec{T} + v^2 K \vec{N}\end{aligned}$$

$$\therefore \vec{a} = \frac{dv}{dt} \vec{T} + \frac{v^2}{\rho} \vec{N} \quad (\text{Showed})$$

Ex:66: A particle moves along the curve $\vec{r} = (t^3 - 4t)\hat{i} + (t^2 + 4t)\hat{j} + (8t^2 - 3t^3)\hat{k}$, where t is the time.

Find the magnitudes of the tangential and normal components of its acceleration when $t=2$.

Solution:

Hence,

$$\vec{r} = (3t^2 - 4)\hat{i} + (2t + 4)\hat{j} + (16t - 9t^2)\hat{k}$$

$$\ddot{\vec{r}} = (6t)\hat{i} + 2\hat{j} + (-16 - 18t)\hat{k}$$

We know,

$$\frac{v^2}{\rho} = k v^2$$

$$= \frac{|\dot{\vec{r}} \times \ddot{\vec{r}}|}{|\dot{\vec{r}}|^3} \times v^2 \quad [k = \frac{|\dot{\vec{r}} \times \ddot{\vec{r}}|}{|\dot{\vec{r}}|^3}] = \frac{v^2}{9}$$

$$= \frac{|\dot{\vec{r}} \times \ddot{\vec{r}}|}{v^3} \times v^2 \quad [|\dot{\vec{r}}| = v]$$

$$= \frac{|\dot{\vec{r}} \times \ddot{\vec{r}}|}{v^2}$$

at $t=2$,

$$\vec{r} = 8\hat{i} + 8\hat{j} - 4\hat{k} = 9, \text{ and } v = 9$$

$$\ddot{\vec{r}} = 12\hat{i} + 2\hat{j} - 20\hat{k}$$

$$\dot{\vec{r}} \times \ddot{\vec{r}} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ 8 & 8 & -4 \\ 12 & 2 & -20 \end{vmatrix} = \frac{160}{9}\hat{i} + 48\hat{j} - 80\hat{k}$$

$$= \hat{i}(-160 + 8) - \hat{j}(-160 + 48) + \hat{k}(16 - 96)$$

$$= -152\hat{i} + 112\hat{j} - 80\hat{k}$$

$$|\vec{r} \times \ddot{\vec{r}}| = \sqrt{(-152)^2 + 112^2 + (-80)^2}$$

$$= 24\sqrt{73}$$

$$v = \sqrt{9t^4 - 24t^2 + 16 + 4t^2 + 16t + 16 + 256t^2 - 288t^3 + 8t^4}$$

$$= \sqrt{90t^4 - 288t^3 + 236t^2 + 16t + 32}$$

$$\frac{dv}{dt} = \frac{360t^3 - 864t^2 + 472t + 16}{2\sqrt{90t^4 - 288t^3 + 236t^2 + 16t + 32}}$$

at $t=2$,

$$v = 12, \frac{dv}{dt} = 16$$

$$\frac{v^2}{\rho} = \frac{|\vec{r} \times \ddot{\vec{r}}|}{v} = \frac{24\sqrt{73}}{12} = 2\sqrt{73}$$

Ex:- 67: If a particle has velocity v and acceleration a along a space curve, prove that the radius of curvature of its path is given numerically by $\rho = \frac{v^3}{|\vec{v} \times \vec{a}|}$

Solution:

We know,

$$k = \frac{1}{\rho}$$

$$\Rightarrow v^2 k = \frac{v^2}{\rho}$$

$$(3E-3L) \Rightarrow (v^2) \frac{1}{\rho} \frac{|\vec{v} \times \vec{a}|}{\sqrt{3}} = \frac{v^2}{\rho} \quad [k = \frac{|\vec{v} \times \ddot{\vec{r}}|}{|\vec{v}|^2}]$$

$$= \frac{|\vec{v} \times \vec{a}|}{\sqrt{3}}$$

$$\Rightarrow \rho = \frac{\sqrt{3}}{|\vec{v} \cdot \vec{x}|}$$

$$40\hat{i} - \hat{j} - \hat{k} = \hat{i}(8-3) + \hat{j} - \hat{k}(1+1) = \vec{v}$$

19-02-2018: 4A: Monday

→ Gradient, divergence and curl: $\vec{f} = f_i \hat{i} + f_j \hat{j} + f_k \hat{k}$

- vector differential operators, ∇

$$\nabla = \frac{\partial}{\partial x} \hat{i} + \frac{\partial}{\partial y} \hat{j} + \frac{\partial}{\partial z} \hat{k}, \quad \phi(x, y, z) = \cancel{\phi dx \hat{i} + \phi dy \hat{j} + \phi dz \hat{k}}$$

$$\begin{aligned} d\phi &= \frac{\partial \phi}{\partial x} dx + \frac{\partial \phi}{\partial y} dy + \frac{\partial \phi}{\partial z} dz \\ &= \left(\frac{\partial \phi}{\partial x} \hat{i} + \frac{\partial \phi}{\partial y} \hat{j} + \frac{\partial \phi}{\partial z} \hat{k} \right) \cdot (dx \hat{i} + dy \hat{j} + dz \hat{k}) \end{aligned}$$

$$e = \nabla \phi \cdot d\pi$$

$$= |\nabla \phi| \cdot |d\pi| \cos \theta$$

If, $\theta = 0^\circ$

$\theta = 90^\circ$

$$d\phi = |\nabla \phi| \cdot |d\pi| \cos 0^\circ \rightarrow d\phi = 0$$

Ex: 10

→ Find the directional derivative of $\phi = x^2y^2 + 4x^2z^2$ at $(1, -2, -1)$ in the direction $2\hat{i} - \hat{j} - 2\hat{k}$

Solution:

$$\nabla \phi = \frac{\partial}{\partial x} (x^2y^2 + 4x^2z^2) \hat{i} + \frac{\partial}{\partial y} (x^2y^2 + 4x^2z^2) \hat{j}$$

$$+ \frac{\partial}{\partial z} (x^2y^2 + 4x^2z^2) \hat{k}$$

$$= (2xyz + 8z^2) \hat{i} + (x^2y) \hat{j} + (x^2y + 8x^2z) \hat{k}$$

$\nabla \phi$ at $(1, -2, 1)$

$$\nabla \phi = (4+4)\hat{i} - \hat{j} + (-2-8)\hat{k} = 8\hat{i} - \hat{j} - 10\hat{k}$$

Let,

$$\vec{A} = 2\hat{i} - \hat{j} - 2\hat{k}$$

$$\frac{\vec{A}}{A} = \frac{2\hat{i} - \hat{j} - 2\hat{k}}{\sqrt{4+1+4}} = \frac{1}{3}(2\hat{i} - \hat{j} - 2\hat{k})$$

$$\nabla \phi \cdot \frac{\vec{A}}{A} = (8\hat{i} - \hat{j} - 10\hat{k}) \cdot \left(\frac{2}{3}\hat{i} - \frac{1}{3}\hat{j} - \frac{2}{3}\hat{k}\right)$$

$$= \frac{16}{3} + \frac{1}{3} + \frac{20}{3}$$

$$= \frac{16+1+20}{3} = \frac{37}{3}$$

Ex: 12

Find the angle between the surface $x^2+y^2+z^2=9$ and $z=x^2+y^2-3$ at the point $(2, -1, 2)$.

Solution:

Let,

$$\phi_1 = x^2+y^2+z^2-9 \quad \nabla \phi_1 = 2x\hat{i} + 2y\hat{j} + 2z\hat{k}$$

$$\phi_2 = x^2+y^2-z-3 \quad \nabla \phi_2 = 2x\hat{i} + 2y\hat{j} - \hat{k}$$

$\nabla \phi_1$ and $\nabla \phi_2$ at $(2, -1, 2)$

$$\nabla \phi_1 = 4\hat{i} - 2\hat{j} + 4\hat{k}$$

$$\nabla \phi_2 = 4\hat{i} - 2\hat{j} - \hat{k}$$

If the angle between ϕ_1 and ϕ_2 is θ then

$$\cos \theta = \frac{\nabla \phi_1 \cdot \nabla \phi_2}{|\nabla \phi_1| |\nabla \phi_2|} = \frac{16+4-4}{\sqrt{16+4+16} \sqrt{16+4+1}} = \frac{16}{6\sqrt{21}}$$

$$= \frac{8}{3\sqrt{21}}$$

$$\therefore \theta = \cos^{-1} \left(-\frac{8}{3\sqrt{21}} \right)$$

26-02-2018 : 4E : Monday

→ curl of a vector :

If \vec{v} is a vector then $\nabla \times \vec{v}$ is the curl of a vector.

If $\vec{v} \times \vec{v} = 0$ then the vector is irrotational.

Ex: 29

→ Prove : $\vec{\nabla} \times (\vec{\nabla} \times \vec{A}) = -\vec{\nabla}^2 \vec{A} + \vec{\nabla}(\vec{A} \cdot \vec{A})$

Solution:

$$\text{L.H.S.} = \vec{\nabla} \times (\vec{\nabla} \times \vec{A})$$

$$= \vec{\nabla} \times \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ A_1 & A_2 & A_3 \end{vmatrix}$$

$$= \vec{\nabla} \times \left[\hat{i} \left(\frac{\partial A_3}{\partial y} - \frac{\partial A_2}{\partial z} \right) + \hat{j} \left(\frac{\partial A_1}{\partial z} - \frac{\partial A_3}{\partial x} \right) + \hat{k} \left(\frac{\partial A_2}{\partial x} - \frac{\partial A_1}{\partial y} \right) \right]$$

$$= \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ \frac{\partial A_3}{\partial y} - \frac{\partial A_2}{\partial z} & \frac{\partial A_1}{\partial z} - \frac{\partial A_3}{\partial x} & \frac{\partial A_2}{\partial x} - \frac{\partial A_1}{\partial y} \end{vmatrix}$$

$$= \hat{i} \left[\frac{\partial}{\partial y} \left(\frac{\partial A_2}{\partial x} - \frac{\partial A_1}{\partial y} \right) - \frac{\partial}{\partial z} \left(\frac{\partial A_1}{\partial z} - \frac{\partial A_2}{\partial x} \right) \right]$$

$$+ \hat{j} \left[\frac{\partial}{\partial z} \left(\frac{\partial A_3}{\partial y} - \frac{\partial A_2}{\partial z} \right) - \frac{\partial}{\partial x} \left(\frac{\partial A_2}{\partial x} - \frac{\partial A_3}{\partial y} \right) \right]$$

$$+ \hat{k} \left[\frac{\partial}{\partial x} \left(\frac{\partial A_1}{\partial z} - \frac{\partial A_3}{\partial x} \right) - \frac{\partial}{\partial y} \left(\frac{\partial A_3}{\partial y} - \frac{\partial A_1}{\partial z} \right) \right]$$

$$= \hat{i} \left[-\frac{\partial^2 A_2}{\partial x \partial y} - \frac{\partial^2 A_1}{\partial y^2} - \frac{\partial^2 A_1}{\partial z^2} + \frac{\partial^2 A_3}{\partial x \partial z} \right]$$

$$+ \hat{j} \left[-\frac{\partial^2 A_3}{\partial y \partial z} - \frac{\partial^2 A_2}{\partial z^2} - \frac{\partial^2 A_2}{\partial x^2} + \frac{\partial^2 A_1}{\partial x \partial y} \right]$$

$$+ \hat{k} \left[-\frac{\partial^2 A_1}{\partial x \partial z} - \frac{\partial^2 A_3}{\partial x^2} - \frac{\partial^2 A_3}{\partial y^2} + \frac{\partial^2 A_2}{\partial y \partial z} \right]$$

$$= \left(-\frac{\partial^2 A_1}{\partial y^2} - \frac{\partial^2 A_1}{\partial z^2} \right) \hat{i} + \left(-\frac{\partial^2 A_2}{\partial z^2} - \frac{\partial^2 A_2}{\partial x^2} \right) \hat{j} + \left(-\frac{\partial^2 A_3}{\partial x^2} - \frac{\partial^2 A_3}{\partial y^2} \right) \hat{k}$$

$$+ \left(\frac{\partial^2 A_2}{\partial x \partial y} + \frac{\partial^2 A_3}{\partial x \partial z} \right) \hat{i} + \left(\frac{\partial^2 A_3}{\partial y \partial z} + \frac{\partial^2 A_1}{\partial x \partial y} \right) \hat{j} + \left(\frac{\partial^2 A_1}{\partial x \partial z} + \frac{\partial^2 A_2}{\partial y \partial z} \right) \hat{k}$$

$$= \left(-\frac{\partial^2 A_1}{\partial x^2} - \frac{\partial^2 A_1}{\partial y^2} - \frac{\partial^2 A_1}{\partial z^2} + \frac{\partial^2 A_1}{\partial x^2} \right) \hat{i} + \left(-\frac{\partial^2 A_2}{\partial x^2} - \frac{\partial^2 A_2}{\partial y^2} - \frac{\partial^2 A_2}{\partial z^2} + \frac{\partial^2 A_2}{\partial y^2} \right) \hat{j}$$

$$+ \left(-\frac{\partial^2 A_3}{\partial x^2} - \frac{\partial^2 A_3}{\partial y^2} - \frac{\partial^2 A_3}{\partial z^2} + \frac{\partial^2 A_3}{\partial z^2} \right) \hat{k} + \left(\frac{\partial^2 A_2}{\partial x \partial y} + \frac{\partial^2 A_3}{\partial x \partial z} \right) \hat{i}$$

$$+ \left(\frac{\partial^2 A_1}{\partial x \partial y} + \frac{\partial^2 A_3}{\partial y \partial z} \right) \hat{j} + \left(\frac{\partial^2 A_1}{\partial x \partial z} + \frac{\partial^2 A_2}{\partial y \partial z} \right) \hat{k}$$

$$\begin{aligned}
&= - \left(\frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} + \frac{\partial^2}{\partial z^2} \right) (A_1 \hat{i} + A_2 \hat{j} + A_3 \hat{k}) + i \left(\frac{\partial^2 A_1}{\partial x^2} + \frac{\partial^2 A_2}{\partial x \partial y} + \frac{\partial^2 A_3}{\partial x \partial z} \right) \\
&\quad + j \left(\frac{\partial^2 A_1}{\partial x \partial y} + \frac{\partial^2 A_2}{\partial y^2} + \frac{\partial^2 A_3}{\partial y \partial z} \right) + k \left(\frac{\partial^2 A_1}{\partial x \partial z} + \frac{\partial^2 A_2}{\partial y \partial z} + \frac{\partial^2 A_3}{\partial z^2} \right) \\
&= - \vec{\nabla}^2 \vec{A} + i \frac{\partial}{\partial x} \left(\frac{\partial A_1}{\partial x} + \frac{\partial A_2}{\partial y} + \frac{\partial A_3}{\partial z} \right) + j \frac{\partial}{\partial y} \left(\frac{\partial A_1}{\partial x} + \frac{\partial A_2}{\partial y} + \frac{\partial A_3}{\partial z} \right) \\
&\quad + k \frac{\partial}{\partial z} \left(\frac{\partial A_1}{\partial x} + \frac{\partial A_2}{\partial y} + \frac{\partial A_3}{\partial z} \right) \\
&= - \vec{\nabla}^2 \vec{A} + \vec{\nabla} \left(\frac{\partial A_1}{\partial x} + \frac{\partial A_2}{\partial y} + \frac{\partial A_3}{\partial z} \right) \\
&= - \vec{\nabla}^2 \vec{A} + \vec{\nabla} (\vec{\nabla} \cdot \vec{A}) = R.H.S. - (A_x \vec{\nabla}) \cdot \vec{\nabla}
\end{aligned}$$

∴ L.H.S. = R.H.S. (Proved)

Ex: 84 Prove that the vector $\vec{A} = 3y^{2z^2} \hat{i} + 4x^3 z^2 \hat{j} - 3x^2 y^2 \hat{k}$ is solenoidal.

Solution: If $\vec{\nabla} \cdot \vec{A} = 0$, then it is solenoidal

$$\begin{aligned}
L.H.S. &= \vec{\nabla} \cdot \vec{A} \\
&= \frac{\partial}{\partial x} (3y^{2z^2}) + \frac{\partial}{\partial y} (4x^3 z^2) + \frac{\partial}{\partial z} (3x^2 y^2)
\end{aligned}$$

$$\begin{aligned}
&= 0 + 0 + 0 \\
&= 0 \\
&= R.H.S.
\end{aligned}$$

∴ L.H.S. = R.H.S. (Proved)

Ex: 104

→ If \vec{A} & \vec{B} are irrotational, prove that

$\vec{A} \times \vec{B}$ is solenoidal.

Solution:

As \vec{A} & \vec{B} are irrotational,

$$\vec{\nabla} \times \vec{A} = 0, \vec{\nabla} \times \vec{B} = 0$$

If $\vec{\nabla} \cdot (\vec{A} \times \vec{B}) = 0$, it is solenoidal.

$$\text{L.H.S.} = \vec{\nabla} \cdot (\vec{A} \times \vec{B})$$

$$= \vec{B} \cdot (\vec{\nabla} \times \vec{A}) - \vec{A} \cdot (\vec{\nabla} \times \vec{B})$$

$$= 0 - 0$$

$$= 0 = \text{R.H.S.}$$

∴ L.H.S. = R.H.S. (Proved)

Ex: 102

→ Show that $\vec{A} = (6xy + z^3)\hat{i} + (3x^2 - 2)\hat{j} + (3x^2 - y)\hat{k}$ is irrotational. Find ϕ such that $\vec{A} = \vec{\nabla} \phi$.

Solution:

If $(\vec{\nabla} \times \vec{A}) = 0$, then it is irrotational.

$$\begin{aligned}
 \text{L.H.S.} &= \\
 \vec{A} \times \vec{A} &= \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ 6xy + z^3 & 3x^2 - z & 3x^2 - y \end{vmatrix} \\
 &= i \left[\frac{\partial}{\partial y} (3x^2 - y) - \frac{\partial}{\partial z} (3x^2 - z) \right] \\
 &\quad + j \left[\frac{\partial}{\partial z} (6xy + z^3) - \frac{\partial}{\partial x} (3x^2 - y) \right] \\
 &\quad + k \left[\frac{\partial}{\partial x} (3x^2 - z) - \frac{\partial}{\partial y} (6xy + z^3) \right] \\
 &= i (-1 + 1) + j (3z^2 - 3z^2) + k (6x - 6x) \\
 &= 0 = \text{R.H.S.}
 \end{aligned}$$

$\therefore \text{L.H.S.} = \text{R.H.S.}$ (Showed)

We know,

$$\begin{aligned}
 \frac{d\phi}{d\vec{r}} &= \vec{\nabla}\phi \\
 \Rightarrow d\phi &= \vec{\nabla}\phi \cdot d\vec{r} \\
 &= \vec{A} \cdot d\vec{r} \\
 &= [(6xy + z^3)\hat{i} + (3x^2 - z)\hat{j} + (3x^2 - y)\hat{k}] \\
 &\quad (dx\hat{i} + dy\hat{j} + dz\hat{k}) \\
 &= (6xy + z^3)dx + (3x^2 - z)dy + (3x^2 - y)dz \\
 &= z^3dx + 3x^2dz + 6xydx + 3x^2dy - 2dy - ydz
 \end{aligned}$$

By integrating,

$$\phi = xz^3 + 3x^2y - yz + C$$

Example: Chapter 4

Exm-01: If $\nabla \phi(x, y, z) = 3x^2y - y^3z^2$, find $\nabla \phi$ at the point $(1, -2, -1)$

Solution:

$$\begin{aligned}\vec{\nabla} \phi &= \frac{\partial}{\partial x}(3x^2y - y^3z^2)\hat{i} + \frac{\partial}{\partial y}(3x^2y - y^3z^2)\hat{j} \\ &\quad + \frac{\partial}{\partial z}(3x^2y - y^3z^2)\hat{k} \\ &= 6xy\hat{i} + (3x^2 - 3y^2z^2)\hat{j} - 2y^3z\hat{k}\end{aligned}$$

$\vec{\nabla} \phi$ at $(1, -2, -1)$,

$$\begin{aligned}&\cancel{-12\hat{i}} \cancel{+ 9\hat{j}} \\ &-12\hat{i} - 9\hat{j} - 16\hat{k}\end{aligned}$$

Exm-02: Find $\nabla \phi$ if $\textcircled{a} \phi = \ln |\vec{r}|$, $\textcircled{b} \phi = \frac{1}{|\vec{r}|}$

$$\textcircled{a} \vec{r} = x\hat{i} + y\hat{j} + z\hat{k}$$

$$\therefore \phi = \ln |\vec{r}|$$

$$\text{Then } |\vec{r}| = \sqrt{x^2 + y^2 + z^2}$$

$$= \frac{1}{2} \ln(x^2 + y^2 + z^2)$$

\textcircled{a}

$$\therefore \vec{\nabla} \phi = \frac{1}{2} \vec{\nabla} \ln(x^2 + y^2 + z^2)$$

$$\begin{aligned}&= \frac{1}{2} \left[\frac{\partial}{\partial x} \ln(x^2 + y^2 + z^2) \hat{i} + \frac{\partial}{\partial y} \ln(x^2 + y^2 + z^2) \hat{j} \right. \\ &\quad \left. + \frac{\partial}{\partial z} \ln(x^2 + y^2 + z^2) \hat{k} \right]\end{aligned}$$

$$= \frac{1}{2} \left[\frac{2x}{x^2+y^2+2^2} \hat{i} + \frac{2y}{x^2+y^2+2^2} \hat{j} + \frac{2z}{x^2+y^2+2^2} \hat{k} \right]$$

$$= \frac{1}{2} \frac{2(x\hat{i}+y\hat{j}+z\hat{k})}{x^2+y^2+2^2} = \frac{\vec{r}}{|\vec{r}|^2}$$

⑥ $\vec{\nabla} \phi = \vec{\nabla} \left(\frac{1}{|\vec{r}|} \right)$

$$= \vec{\nabla} \left(\frac{1}{\sqrt{x^2+y^2+z^2}} \right)$$

$$= \frac{\partial}{\partial x} (x^2+y^2+z^2)^{-\frac{1}{2}} \hat{i} + \frac{\partial}{\partial y} (x^2+y^2+z^2)^{-\frac{1}{2}} \hat{j} + \frac{\partial}{\partial z} (x^2+y^2+z^2)^{-\frac{1}{2}} \hat{k}$$

$$= -\frac{1}{2} (x^2+y^2+z^2)^{-\frac{3}{2}} 2x \hat{i} - \frac{1}{2} (x^2+y^2+z^2)^{-\frac{3}{2}} 2y \hat{j} - \frac{1}{2} (x^2+y^2+z^2)^{-\frac{3}{2}} 2z \hat{k}$$

$$= -\frac{1}{(x^2+y^2+z^2)^{\frac{3}{2}}} (x\hat{i}+y\hat{j}+z\hat{k})$$

$$= -\frac{\vec{r}}{|\vec{r}|^3}$$

Ex: 05: Show that $\vec{\nabla} \phi$ is a vector perpendicular to the surface $\phi(x, y, z) = c$ where c is a constant.

Solution:

Let, $\vec{r} = x\hat{i}+y\hat{j}+z\hat{k}$ be the position vector to any point $P(x, y, z)$ on the surface. Then $d\vec{r} = dx\hat{i} + dy\hat{j} + dz\hat{k}$ lies in the tangent plane to the surface at P .

$$\text{But } d\phi = \frac{\partial \phi}{\partial x} dx + \frac{\partial \phi}{\partial y} dy + \frac{\partial \phi}{\partial z} dz = 0$$

$$\Rightarrow \left(\frac{\partial \phi}{\partial x} \hat{i} + \frac{\partial \phi}{\partial y} \hat{j} + \frac{\partial \phi}{\partial z} \hat{k} \right) (dx \hat{i} + dy \hat{j} + dz \hat{k}) = 0$$

$$\therefore \vec{\nabla} \phi \cdot d\vec{r} = 0$$

so, $\vec{\nabla} \phi$ is perpendicular to $d\vec{r}$ and therefore to the surface.

Exm :- 6: Find a unit normal to the surface

$$x^2y + 2xz = 4 \text{ at the point } (2, -2, 3)$$

Solution:

$$\begin{aligned}\vec{\nabla} \phi &= \frac{\partial}{\partial x} (x^2y + 2xz) \hat{i} + \frac{\partial}{\partial y} (x^2y + 2xz) \hat{j} + \frac{\partial}{\partial z} (x^2y + 2xz) \hat{k} \\ &= (2xy + 2z) \hat{i} + x^2 \hat{j} + 2x \hat{k}\end{aligned}$$

at $(2, -2, 3)$ point

$$-2 \hat{i} + 4 \hat{j} + 4 \hat{k}$$

unit normal to the surface

$$\begin{aligned}&\frac{-2 \hat{i} + 4 \hat{j} + 4 \hat{k}}{\sqrt{4 + 16 + 16}} = -\frac{2}{6} \hat{i} + \frac{4}{6} \hat{j} + \frac{4}{6} \hat{k} \\ &= -\frac{1}{3} \hat{i} + \frac{2}{3} \hat{j} + \frac{2}{3} \hat{k}\end{aligned}$$

Ex 07: Find an equation for the tangent plane to the tangent plane to the surface $z = 2x^2 - 3xy - 4x - 7$ at the point $(1, -1, 2)$.

Solution: Let

$$\phi = 2x^2 - 3xy - 4x - 7$$

$$\nabla \phi = (4x - 3y - 4)\hat{i} - 3x\hat{j} + 4x\hat{k}$$

at $(1, -1, 2)$ point

$$\nabla \phi = 7\hat{i} - 3\hat{j} + 8\hat{k}$$

The equation of a plane passing through a point whose position vector is r_0 and which is perpendicular to the normal N is $(r - r_0) \cdot N = 0$. Then required equation.

$$[(x\hat{i} + y\hat{j} + z\hat{k}) - (1\hat{i} - 1\hat{j} + 2\hat{k})] \cdot (7\hat{i} - 3\hat{j} + 8\hat{k}) = 0$$

$$\Rightarrow [(x-1)\hat{i} + (y+1)\hat{j} + (z-2)\hat{k}] \cdot (7\hat{i} - 3\hat{j} + 8\hat{k}) = 0$$

$$\therefore 7(x-1) - 3(y+1) + 8(z-2) = 0$$

$$(f_{xx}(x) \frac{\partial}{\partial x} + f_{xy}(x) \frac{\partial}{\partial y} + f_{xz}(x) \frac{\partial}{\partial z}) \cdot (7\hat{i} - 3\hat{j} + 8\hat{k}) = 0$$

$$f_{xx}(x)g + f_{xy}(x)h + f_{xz}(x)k =$$

Using $f_{xy}(x) = h$

$$g + h - k =$$

Em :- 09 : Show that the greatest rate of change of ϕ i.e. the maximum directional derivative, takes place in the direction of and has the magnitude of the vector $\vec{\nabla}\phi$.

Solution:

$\frac{d\phi}{ds} = \vec{\nabla}\phi \cdot \frac{dr}{ds}$ is the projection of $\vec{\nabla}\phi$ in the direction $\frac{dr}{ds}$. This projection will be a maximum when $\vec{\nabla}\phi$ and $\frac{dr}{ds}$ have the same direction. Then the maximum value of $\frac{d\phi}{ds}$ takes place in the direction of $\vec{\nabla}\phi$ and its magnitude is $|\vec{\nabla}\phi|$.

Em :- 11:

- a) In what direction from the point $(2, 1, -1)$ is the directional derivative of $\phi = x^2y z^3$ a maximum?
- b) What is the magnitude of this maximum?

Solution:

$$\begin{aligned} \textcircled{a} \quad b) \vec{\nabla}\phi &= \frac{\partial}{\partial x}(x^2y z^3)\hat{i} + \frac{\partial}{\partial y}(x^2y z^3)\hat{j} + \frac{\partial}{\partial z}(x^2y z^3)\hat{k} \\ &= 2xyz^2\hat{i} + x^2z^3\hat{j} + 3x^2yz^2\hat{k} \end{aligned}$$

at $(2, 1, -1)$ point

$$-4\hat{i} - 4\hat{j} + 12\hat{k}$$

This is the direction of the directional derivative.

b) The magnitude of this maximum is

$$|\vec{\nabla}f| = \sqrt{16+16+144} = \sqrt{176} = 4\sqrt{11}$$

[Ex: 17]: Prove that $\vec{\nabla}^2\left(\frac{1}{\sqrt{x^2+y^2+z^2}}\right) = 0$

Solution:

$$\begin{aligned} L.H.S. &= \vec{\nabla}^2\left(\frac{1}{\sqrt{x^2+y^2+z^2}}\right) \\ &= \left(\frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} + \frac{\partial^2}{\partial z^2}\right) \left(\frac{1}{\sqrt{x^2+y^2+z^2}}\right) \end{aligned}$$

$$\begin{aligned} \frac{\partial}{\partial x} \left(\frac{1}{\sqrt{x^2+y^2+z^2}}\right) &= -\frac{1}{2} (x^2+y^2+z^2)^{-\frac{3}{2}} 2x \\ &= -x(x^2+y^2+z^2)^{-\frac{3}{2}} \end{aligned}$$

$$\begin{aligned} \frac{\partial^2}{\partial x^2} \left(\frac{1}{\sqrt{x^2+y^2+z^2}}\right) &= \frac{\partial}{\partial x} \left\{ -x(x^2+y^2+z^2)^{-\frac{3}{2}} \right\} \\ &= -\left(-\frac{3x}{2}\right) (x^2+y^2+z^2)^{-\frac{5}{2}} 2x - (x^2+y^2+z^2)^{-\frac{3}{2}} \\ &= 3x^2(x^2+y^2+z^2)^{-\frac{5}{2}} - (x^2+y^2+z^2)^{-\frac{3}{2}} \\ &= \frac{3x^2}{(x^2+y^2+z^2)^{\frac{5}{2}}} - \frac{1}{(x^2+y^2+z^2)^{\frac{3}{2}}} \end{aligned}$$

$$\begin{aligned} &= \frac{3x^2 - x^2 - y^2 - z^2}{(x^2+y^2+z^2)^{\frac{5}{2}}} \\ &= \frac{2x^2 - y^2 - z^2}{(x^2+y^2+z^2)^{\frac{5}{2}}} \end{aligned}$$

$$\frac{\partial^2}{\partial y^2} \left(\frac{1}{\sqrt{x^2+y^2+z^2}} \right) = -\frac{2y^2-x^2-z^2}{(x^2+y^2+z^2)^{\frac{5}{2}}}$$

$$\frac{\partial^2}{\partial z^2} \left(\frac{1}{\sqrt{x^2+y^2+z^2}} \right) = -\frac{2z^2-x^2-y^2}{(x^2+y^2+z^2)^{\frac{5}{2}}}$$

$$\therefore \left(\frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} + \frac{\partial^2}{\partial z^2} \right) \left(\frac{1}{\sqrt{x^2+y^2+z^2}} \right) =$$

$$= -\frac{2x^2-y^2-z^2}{(x^2+y^2+z^2)^{\frac{5}{2}}} + \frac{2y^2-x^2-z^2}{(x^2+y^2+z^2)^{\frac{5}{2}}} + \frac{2z^2-x^2-y^2}{(x^2+y^2+z^2)^{\frac{5}{2}}}$$

$$= 0$$

$$= R.H.S.$$

$$\therefore L.H.S. = R.H.S. \quad (\text{Proved})$$

Exm: 18: Prove that $\frac{\partial}{\partial x} \left(\frac{1}{\sqrt{x^2+y^2+z^2}} \right) = \left(\frac{1}{x^2+y^2+z^2} \right) \frac{\partial}{\partial x}$

$$\textcircled{a} \quad \vec{\nabla} \cdot (\vec{A} + \vec{B}) = \vec{\nabla} \cdot \vec{A} + \vec{\nabla} \cdot \vec{B}$$

$$\textcircled{b} \quad \vec{\nabla} \cdot (\phi \vec{A}) = (\vec{\nabla} \phi) \cdot \vec{A} + \phi (\vec{\nabla} \cdot \vec{A})$$

Solution:

$$\textcircled{a} \quad L.H.S. = \vec{\nabla} \cdot (\vec{A} + \vec{B})$$

$$= \left(\frac{\partial}{\partial x} \hat{i} + \frac{\partial}{\partial y} \hat{j} + \frac{\partial}{\partial z} \hat{k} \right) [(A_1+B_1)\hat{i} + (A_2+B_2)\hat{j} + (A_3+B_3)\hat{k}]$$

$$= \frac{\partial}{\partial x} (A_1+B_1) + \frac{\partial}{\partial y} (A_2+B_2) + \frac{\partial}{\partial z} (A_3+B_3)$$

$$\begin{aligned}
 &= \frac{\partial}{\partial x} A_1 + \frac{\partial}{\partial y} A_2 + \frac{\partial}{\partial z} A_3 + \frac{\partial}{\partial x} B_1 + \frac{\partial}{\partial y} B_2 + \frac{\partial}{\partial z} B_3 \\
 &= \left(\frac{\partial}{\partial x} \hat{i} + \frac{\partial}{\partial y} \hat{j} + \frac{\partial}{\partial z} \hat{k} \right) (A_1 \hat{i} + A_2 \hat{j} + A_3 \hat{k}) + \left(\frac{\partial}{\partial x} \hat{i} + \frac{\partial}{\partial y} \hat{j} + \frac{\partial}{\partial z} \hat{k} \right) \\
 &\quad (B_1 \hat{i} + B_2 \hat{j} + B_3 \hat{k})
 \end{aligned}$$

$$= \vec{\nabla} \cdot \vec{A} + \vec{\nabla} \cdot \vec{B}$$

$$= R.H.S.$$

$$\therefore L.H.S. = R.H.S. \text{ (Proved)}$$

$$(b) L.H.S. = \vec{\nabla} (\phi \vec{A})$$

$$= \vec{\nabla} (\phi A_1 \hat{i} + \phi A_2 \hat{j} + \phi A_3 \hat{k})$$

$$= \frac{\partial}{\partial x} (\phi A_1) + \frac{\partial}{\partial y} (\phi A_2) + \frac{\partial}{\partial z} (\phi A_3)$$

$$= \frac{\partial \phi}{\partial x} A_1 + \phi \frac{\partial A_1}{\partial x} + \frac{\partial \phi}{\partial y} A_2 + \phi \frac{\partial A_2}{\partial y} + \frac{\partial \phi}{\partial z} A_3 + \phi \frac{\partial A_3}{\partial z}$$

$$= \frac{\partial \phi}{\partial x} A_1 + \frac{\partial \phi}{\partial y} A_2 + \frac{\partial \phi}{\partial z} A_3 + \phi \left(\frac{\partial A_1}{\partial x} + \frac{\partial A_2}{\partial y} + \frac{\partial A_3}{\partial z} \right)$$

$$= \phi \left(\frac{\partial \phi}{\partial x} \hat{i} + \frac{\partial \phi}{\partial y} \hat{j} + \frac{\partial \phi}{\partial z} \hat{k} \right) (A_1 \hat{i} + A_2 \hat{j} + A_3 \hat{k})$$

$$+ \phi \left(\frac{\partial}{\partial x} \hat{i} + \frac{\partial}{\partial y} \hat{j} + \frac{\partial}{\partial z} \hat{k} \right) (A_1 \hat{i} + A_2 \hat{j} + A_3 \hat{k})$$

$$= (\vec{\nabla} \phi) \vec{A} + \phi (\vec{\nabla} \cdot \vec{A})$$

$$= R.H.S.$$

$$\therefore L.H.S. = R.H.S. \text{ (Proved)}$$

Em:19: Prove $\vec{\nabla} \left(\frac{\vec{r}}{|\vec{r}|^3} \right) = 0$

Solution:

$$\begin{aligned} L.H.S. &= \vec{\nabla} \left(\frac{\vec{r}}{|\vec{r}|^3} \right) \\ &= \vec{\nabla} \left(\vec{r} \cdot |\vec{r}|^{-3} \right) \\ &= \left(\vec{\nabla} |\vec{r}|^{-3} \right) \vec{r} + |\vec{r}|^{-3} (\vec{\nabla} \cdot \vec{r}) \\ &= -3 |\vec{r}|^{-5} \vec{r} \cdot \vec{r} + |\vec{r}|^{-3} \cdot 3 \quad [\text{from Em:4}] \\ &= -3 |\vec{r}|^{-5} |\vec{r}|^2 + 3 |\vec{r}|^{-3} \\ &= -3 |\vec{r}|^{-3} + 3 |\vec{r}|^{-3} \\ &= 0 \\ &= R.H.S. \end{aligned}$$

$\therefore L.H.S. = R.H.S.$ (Proved)

Em:22: Determine the constant a so that the vector $\vec{v} = (x+3y)\hat{i} + (y-2z)\hat{j} + (x+a_2)\hat{k}$ is solenoidal.

Solution:

The vector, \vec{v} is solenoidal, if $\vec{\nabla} \cdot \vec{v} = 0$

$$\begin{aligned} \vec{\nabla} \cdot \vec{v} &= 0 \\ \Rightarrow \frac{\partial}{\partial x} (x+3y) + \frac{\partial}{\partial y} (y-2z) + \frac{\partial}{\partial z} (x+a_2) &= 0 \\ \Rightarrow 1 + 1 + a &= 0 \\ \therefore a &= -2. \end{aligned}$$

Exm :- 23: If $\vec{A} = x^2 \hat{i} - 2x^2yz \hat{j} + 2y^2z^4 \hat{k}$, find $\vec{\nabla} \times \vec{A}$ at the point $(1, -1, 1)$.

Solution:

$$\begin{aligned}\vec{\nabla} \times \vec{A} &= \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ x^2 & -2x^2yz & 2y^2z^4 \end{vmatrix} \\ &= \hat{i} \left[\frac{\partial}{\partial y} (2y^2z^4) - \frac{\partial}{\partial z} (-2x^2yz) \right] \\ &\quad - \hat{j} \left[\frac{\partial}{\partial x} (2y^2z^4) - \frac{\partial}{\partial z} (x^2z^4) \right] \\ &\quad + \hat{k} \left[\frac{\partial}{\partial x} (-2x^2yz) - \frac{\partial}{\partial y} (x^2z^4) \right] \\ &= \hat{i} [2z^4 + 2x^2y] - \hat{j} [0 - 3x^2z^2] \\ &\quad + \hat{k} [-4xyz - 0] \\ &= 2(x^2y + z^4)\hat{i} + 3x^2z^2\hat{j} - 4xyz\hat{k}\end{aligned}$$

at $(1, -1, 1)$ point

$$= 2(1^2(-1) + 1^4)\hat{i} + 3(1^2(-1)^2)\hat{j} - 4(1)(-1)\hat{k}$$

$$\hat{i} (3 + 1)$$

~~will be $\vec{A} \times \vec{v}$ but, if $\vec{A} = \vec{A}(x, y)$ then $\vec{A} \cdot \vec{v} = \vec{A} \cdot (\vec{v}_x \hat{i} + \vec{v}_y \hat{j}) = A_x v_x + A_y v_y$~~

Exm-24: If $\vec{A} = x^2y \hat{i} - 2xz \hat{j} + 2yz \hat{k}$, find curl curl \vec{A} .

Solution:

$$\begin{aligned} & \text{curl curl } \vec{A} \\ &= \vec{\nabla} \times (\vec{\nabla} \times \vec{A}) \\ &= \vec{\nabla} \times \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ x^2y & -2xz & 2yz \end{vmatrix} \\ &= \vec{\nabla} \times [\hat{i}(2z+2x) - \hat{j}(0-0) + \hat{k}(-2z-x^2)] \\ &= \vec{\nabla} \times [(2x+2z)\hat{i} - (x^2+2z)\hat{k}] \\ &= \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ 2x+2z & 0 & -(x^2+2z) \end{vmatrix} \\ &= \hat{i}(0-0) - \hat{j}(-2x-2) + \hat{k}(0-0) \\ &= (2x+2)\hat{j} \end{aligned}$$

Exm :- 25: Prove

$$\text{a) } \vec{\nabla} \times (\vec{A} + \vec{B}) = \vec{\nabla} \times \vec{A} + \vec{\nabla} \times \vec{B}$$

$$\text{b) } \vec{\nabla} \times (\phi \vec{A}) = (\vec{\nabla} \phi) \times \vec{A} + \phi (\vec{\nabla} \times \vec{A})$$

Solutions:

a) Let,

$$\vec{A} = A_1 \hat{i} + A_2 \hat{j} + A_3 \hat{k}$$

$$\vec{B} = B_1 \hat{i} + B_2 \hat{j} + B_3 \hat{k}$$

$$\begin{aligned}
 & \vec{\nabla} \times (\vec{A} + \vec{B}) \\
 &= \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ A_1 + B_1 & A_2 + B_2 & A_3 + B_3 \end{vmatrix} + \\
 &= \left[\frac{\partial}{\partial y} (A_3 + B_3) - \frac{\partial}{\partial z} (A_2 + B_2) \right] \hat{i} + \left[\frac{\partial}{\partial z} (A_1 + B_1) - \frac{\partial}{\partial x} (A_3 + B_3) \right] \hat{j} + \\
 &\quad + \left[\frac{\partial}{\partial x} (A_2 + B_2) - \frac{\partial}{\partial y} (A_1 + B_1) \right] \hat{k} \\
 &= \left[\frac{\partial A_3}{\partial y} - \frac{\partial B_3}{\partial z} \right] \hat{i} + \left[\frac{\partial A_1}{\partial z} - \frac{\partial B_1}{\partial x} \right] \hat{j} + \left[\frac{\partial A_2}{\partial x} - \frac{\partial B_2}{\partial y} \right] \hat{k} \\
 &\quad + \left[\frac{\partial B_3}{\partial y} - \frac{\partial A_3}{\partial z} \right] \hat{i} + \left[\frac{\partial B_1}{\partial z} - \frac{\partial A_1}{\partial x} \right] \hat{j} + \left[\frac{\partial B_2}{\partial x} - \frac{\partial A_2}{\partial y} \right] \hat{k} \\
 &\quad + \left[\frac{\partial A_3}{\partial y} - \frac{\partial B_3}{\partial z} \right] \hat{i} + \left[\frac{\partial A_1}{\partial z} - \frac{\partial B_1}{\partial x} \right] \hat{j} + \left[\frac{\partial A_2}{\partial x} - \frac{\partial B_2}{\partial y} \right] \hat{k}
 \end{aligned}$$

$$= \vec{\nabla} \times \vec{A} + \vec{\nabla} \times \vec{B}$$

= R.H.S.

$\therefore L.H.S. = R.H.S.$ (Proved)

(b) $L.H.S. = \vec{\nabla} \times (\phi \vec{A})$

$$= \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ \phi A_1 & \phi A_2 & \phi A_3 \end{vmatrix}$$

$$= \left[\frac{\partial}{\partial y} (\phi A_3) - \frac{\partial}{\partial z} (\phi A_2) \right] \hat{i} + \left[\frac{\partial}{\partial z} (\phi A_1) - \frac{\partial}{\partial x} (\phi A_3) \right] \hat{j} + \left[\frac{\partial}{\partial x} (\phi A_2) - \frac{\partial}{\partial y} (\phi A_1) \right] \hat{k}$$

$$= \left[\phi \frac{\partial A_3}{\partial y} + \frac{\partial \phi}{\partial y} A_3 - \phi \frac{\partial A_2}{\partial z} - \frac{\partial \phi}{\partial z} A_2 \right] \hat{i}$$

$$+ \left[\phi \frac{\partial A_1}{\partial z} + \frac{\partial \phi}{\partial z} A_1 - \phi \frac{\partial A_3}{\partial x} - \frac{\partial \phi}{\partial x} A_3 \right] \hat{j}$$

$$+ \left[\phi \frac{\partial A_2}{\partial x} + \frac{\partial \phi}{\partial x} A_2 - \phi \frac{\partial A_1}{\partial y} - \frac{\partial \phi}{\partial y} A_1 \right] \hat{k}$$

$$= \phi \left[\left(\frac{\partial A_3}{\partial y} - \frac{\partial A_2}{\partial z} \right) \hat{i} + \left(\frac{\partial A_1}{\partial z} - \frac{\partial A_3}{\partial x} \right) \hat{j} + \left(\frac{\partial A_2}{\partial x} - \frac{\partial A_1}{\partial y} \right) \hat{k} \right]$$

$$+ \left[\left(\frac{\partial \phi}{\partial y} A_3 - \frac{\partial \phi}{\partial z} A_2 \right) \hat{i} + \left(\frac{\partial \phi}{\partial z} A_1 - \frac{\partial \phi}{\partial x} A_3 \right) \hat{j} + \left(\frac{\partial \phi}{\partial x} A_2 - \frac{\partial \phi}{\partial y} A_1 \right) \hat{k} \right]$$

$$= \phi(\vec{\nabla} \times \vec{A}) + (\vec{\nabla} \phi) \times \vec{A}$$

= R.H.S.

$\therefore L.H.S. = R.H.S. \text{ (Proved)}$

Exm-26: Evaluate $\vec{\nabla} \cdot (\vec{A} \times \vec{R})$ if $\vec{\nabla} \times \vec{A} = 0$

Solution:

Let,

$$\vec{A} = A_1 \hat{i} + A_2 \hat{j} + A_3 \hat{k}$$

$$\vec{R} = x \hat{i} + y \hat{j} + z \hat{k}$$

$$\therefore \vec{A} \times \vec{R} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ A_1 & A_2 & A_3 \\ x & y & z \end{vmatrix}$$

$$= \hat{i}(A_2 z - A_3 y) + \hat{j}(A_3 x - A_1 z) + \hat{k}(A_1 y - A_2 x)$$

$$\therefore \vec{\nabla} \cdot (\vec{A} \times \vec{R}) = \frac{\partial}{\partial x}(A_2 z - A_3 y) + \frac{\partial}{\partial y}(A_3 x - A_1 z) + \frac{\partial}{\partial z}(A_1 y - A_2 x)$$

$$= 2 \frac{\partial A_2}{\partial x} - y \frac{\partial A_3}{\partial x} + x \frac{\partial A_3}{\partial y} - 2 \frac{\partial A_1}{\partial y} + y \frac{\partial A_1}{\partial z} - x \frac{\partial A_2}{\partial z}$$

$$= x \left(\frac{\partial A_3}{\partial y} - \frac{\partial A_2}{\partial z} \right) + y \left(\frac{\partial A_1}{\partial z} - \frac{\partial A_3}{\partial x} \right) + 2 \left(\frac{\partial A_2}{\partial x} - \frac{\partial A_1}{\partial y} \right)$$

$$= (x \hat{i} + y \hat{j} + z \hat{k}) \left[\left(\frac{\partial A_3}{\partial y} - \frac{\partial A_2}{\partial z} \right) \hat{i} + \left(\frac{\partial A_1}{\partial z} - \frac{\partial A_3}{\partial x} \right) \hat{j} \right]$$

$$+ \left(\frac{\partial A_2}{\partial x} - \frac{\partial A_1}{\partial y} \right) \hat{k} \right]$$

$$= \vec{R} \cdot (\vec{\nabla} \times \vec{A})$$

If $\vec{\nabla} \times \vec{A} = 0$ this reduce to zero.

Ex: 27: Prove:

$$\textcircled{a} \quad \vec{\nabla} \times (\vec{\nabla} \phi) = 0 \quad \textcircled{b} \quad \vec{\nabla} \cdot (\vec{\nabla} \times \vec{A}) = 0$$

Solution:

$$\textcircled{a} \quad L.H.S. = \vec{\nabla} \times (\vec{\nabla} \phi)$$

$$= \vec{\nabla} \times \left(\frac{\partial \phi}{\partial x} \hat{i} + \frac{\partial \phi}{\partial y} \hat{j} + \frac{\partial \phi}{\partial z} \hat{k} \right)$$

$$= \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ \frac{\partial \phi}{\partial x} & \frac{\partial \phi}{\partial y} & \frac{\partial \phi}{\partial z} \end{vmatrix}$$

$$= \left[\frac{\partial^2 \phi}{\partial y \partial z} - \frac{\partial^2 \phi}{\partial z \partial y} \right] \hat{i} + \left[\frac{\partial^2 \phi}{\partial x \partial z} - \frac{\partial^2 \phi}{\partial z \partial x} \right] \hat{j} + \left[\frac{\partial^2 \phi}{\partial x \partial y} - \frac{\partial^2 \phi}{\partial y \partial x} \right] \hat{k}$$

$$= R.H.S.$$

$$\textcircled{b} \quad L.H.S. = R.H.S. \quad (\text{Proved})$$

$$\vec{\nabla} \times (\vec{\nabla} \phi) + (\vec{\nabla} \times \vec{A})$$

$$\begin{aligned}
 \textcircled{b} \quad L.H.S. &= \vec{\nabla} \cdot (\vec{\nabla} \times \vec{A}) \\
 &= \vec{\nabla} \cdot \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ A_1 & A_2 & A_3 \end{vmatrix} \\
 &= \vec{\nabla} \cdot \left[\left(\frac{\partial A_3}{\partial y} - \frac{\partial A_2}{\partial z} \right) \hat{i} + \left(\frac{\partial A_1}{\partial z} - \frac{\partial A_3}{\partial x} \right) \hat{j} + \left(\frac{\partial A_2}{\partial x} - \frac{\partial A_1}{\partial y} \right) \hat{k} \right] \\
 &= \frac{\partial^2 A_3}{\partial x \partial y} - \frac{\partial^2 A_2}{\partial x \partial z} + \frac{\partial^2 A_1}{\partial y \partial z} - \frac{\partial^2 A_3}{\partial x \partial y} + \frac{\partial^2 A_2}{\partial x \partial z} - \frac{\partial^2 A_1}{\partial y \partial z} \\
 &= 0 \\
 &= R.H.S.
 \end{aligned}$$

$\therefore L.H.S. = R.H.S.$ (Proved)

[Em: 30]: If $\vec{v} = \vec{\omega} \times \vec{r}$, prove $\vec{\omega} = \frac{1}{2} \operatorname{curl} \vec{v}$, where $\vec{\omega}$ is a constant vector.

Solution:

$$\begin{aligned}
 \operatorname{curl} \vec{v} &= \vec{\nabla} \times \vec{v} \\
 &= \vec{\nabla} \times (\vec{\omega} \times \vec{r}) \\
 &= \vec{\nabla} \times \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \omega_1 & \omega_2 & \omega_3 \\ x & y & z \end{vmatrix}
 \end{aligned}$$

$$= \vec{\nabla} \times [(\omega_2 z - \omega_3 y) \hat{i} + \theta (\omega_3 x - \omega_1 z) \hat{j} + (\omega_1 y - \omega_2 x) \hat{k}]$$

$$= \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ \omega_2 z - \omega_3 y & \omega_3 x - \omega_1 z & \omega_1 y - \omega_2 x \end{vmatrix}$$

$$= \hat{i}(\omega_1 + \omega_1) + \hat{j}(\omega_2 + \omega_2) + \hat{k}(\omega_3 + \omega_3)$$

$$= \theta 2(\omega_1 \hat{i} + \omega_2 \hat{j} + \omega_3 \hat{k}) = 2\vec{\omega}$$

$$\therefore \text{curl } \vec{V} = 2\vec{\omega}$$

$$\therefore \vec{\omega} = \frac{1}{2} \times \text{curl } \vec{V} \quad (\text{Proved})$$

Exercise : Chapter - 4

Ex :- 45 : Find $\vec{V} / |\vec{r}|^3$

Solution :

$$\text{Let, } \vec{r} = x\hat{i} + y\hat{j} + z\hat{k}$$

$$\therefore |\vec{r}| = \sqrt{x^2 + y^2 + z^2}$$

$$\therefore \vec{V} / |\vec{r}|^3$$

$$= \vec{V} \cdot (x^2 + y^2 + z^2)^{\frac{3}{2}}$$

$$\begin{aligned}
 &= \hat{i} \frac{\partial}{\partial x} (x^2 + y^2 + z^2)^{\frac{3}{2}} + \hat{j} \frac{\partial}{\partial y} (x^2 + y^2 + z^2)^{\frac{3}{2}} + \hat{k} \frac{\partial}{\partial z} (x^2 + y^2 + z^2)^{\frac{3}{2}} \\
 &= \hat{i} \left\{ \frac{3}{2} (x^2 + y^2 + z^2)^{\frac{1}{2}} \cdot 2x \right\} + \hat{j} \left\{ \frac{3}{2} (x^2 + y^2 + z^2)^{\frac{1}{2}} \cdot 2y \right\} + \hat{k} \left\{ \frac{3}{2} (x^2 + y^2 + z^2)^{\frac{1}{2}} \cdot 2z \right\} \\
 &= 3\sqrt{x^2 + y^2 + z^2} \left(x\hat{i} + y\hat{j} + z\hat{k} \right) \\
 &= 3|\vec{r}|\vec{r}.
 \end{aligned}$$

[Ex: 85] Show that $\vec{A} = (2x^2 + 8xy^2z)\hat{i} + (3x^3y - 3xy)\hat{j} - (4y^2z^2 + 2x^3z)\hat{k}$ is not solenoidal but $\vec{B} = xy^2z^2\vec{A}$ is solenoidal.

Solution:

If $\nabla \cdot \vec{A} \neq 0$, then it is not solenoidal.

$$\begin{aligned}
 \nabla \cdot \vec{A} &= \frac{\partial}{\partial x} (2x^2 + 8xy^2z) + \frac{\partial}{\partial y} (3x^3y - 3xy) - \frac{\partial}{\partial z} (4y^2z^2 + 2x^3z) \\
 &= (4x + 8y^2z) + (3x^3 - 3x) - (8y^2z + 2x^3)
 \end{aligned}$$

$$\begin{aligned}
 \nabla \cdot \vec{B} &= \frac{\partial}{\partial x} (2x^3y^2z^2 + 8x^2y^3z^3) + \frac{\partial}{\partial y} (3x^4y^2z^2 - 3x^2y^2z^2) \\
 &\quad - \frac{\partial}{\partial z} (4x^3y^2z^3 + 2x^4y^2z^3)
 \end{aligned}$$

$$\begin{aligned}
 &= 6x^2y^2z^2 + 16xy^3z^3 + 6x^4y^2z^2 - 6x^2y^2z^2 \\
 &\quad - 16x^3y^3z^3 - 6x^4y^2z^3 \\
 &= 0
 \end{aligned}$$

$\therefore \vec{B}$ is solenoidal but \vec{A} is not.

Ex:-91: Evaluate $\vec{\nabla} \times \left(\frac{\vec{r}}{|\vec{r}|^2} \right)$

Solution:

$$\vec{\nabla} \times \left(\frac{\vec{r}}{|\vec{r}|^2} \right)$$

$$= \vec{\nabla} \left(|\vec{r}|^{-2} \vec{r} \right)$$

$$= \vec{\nabla} (|\vec{r}|^{-2}) \times \vec{r} + |\vec{r}|^{-2} (\vec{\nabla} \times \vec{r})$$

$$= -2 |\vec{r}|^{-4} (\vec{r} \times \vec{r}) + |\vec{r}|^{-2} \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ x & y & z \end{vmatrix}$$

$$= -2 |\vec{r}|^{-4} \times 0 + |\vec{r}|^{-2} \left[\hat{i} \left(\frac{\partial z}{\partial y} - \frac{\partial y}{\partial z} \right) + \hat{j} \left(\frac{\partial x}{\partial z} - \frac{\partial z}{\partial x} \right) + \hat{k} \left(\frac{\partial y}{\partial x} - \frac{\partial x}{\partial y} \right) \right]$$

$$= 0 + (|\vec{r}|^{-2} \times 0) + (x^2 y^2 z^2) \frac{\partial}{\partial r} = \vec{A} \cdot \vec{r}$$

$$(x^2 + y^2 + z^2)^{-1} - (x^2 + y^2 + z^2) (x^2 - y^2) + (x^2 y^2 + x^2 z^2) =$$

Ex:-92: For what value of the constant a , will the vector $\vec{A} = (axy - z^3) \hat{i} + (a-2)x^2 \hat{j} + (1-a)xz^2 \hat{k}$ have its curl identically equal to zero?

Solution:

Curl identically equal to zero

$$\therefore \vec{\nabla} \times \vec{A} = 0$$

$$0 =$$

Aons of \vec{A} and lobionsloe si $\vec{A} \cdot \vec{v}$

$$\Rightarrow \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ axy - z^3 & (a-2)x^2 & (1-a)xz^2 \end{vmatrix} = 0$$

$$\Rightarrow \hat{i}(0-0) + \hat{j}(-3z^2 - (1-a)z^2) + \hat{k}\{2x(a-2) - ax\} = 0$$

$$\Rightarrow (-3z^2 - z^2 + az^2) \hat{j} + (2ax - 4 - ax) \hat{k} = 0$$

$$\Rightarrow (-4z^2 + az^2) \hat{j} + (ax - 4) \hat{k} = 0$$

$$\Rightarrow (a-4)z^2 \hat{j} + (ax-4) \hat{k} = 0$$

If the co-efficient of \hat{i} , \hat{j} , \hat{k} are zero, the vector is zero

$$(a-4)z^2 = 0$$

$$\therefore a = 4$$

Ex: 93: Prove $\text{curl}(\phi \text{ grad } \phi) = 0$

Solution:

$$\text{L.H.S.} = \text{curl}(\phi \text{ grad } \phi)$$

$$= \vec{\nabla} \times (\phi \vec{\nabla} \phi)$$

$$= \vec{\nabla} \times \left[\phi \left(\frac{\partial \phi}{\partial x} \hat{i} + \frac{\partial \phi}{\partial y} \hat{j} + \frac{\partial \phi}{\partial z} \hat{k} \right) \right]$$

$$\begin{aligned}
 &= \left| \begin{array}{ccc} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ \phi \frac{\partial \phi}{\partial x} & \phi \frac{\partial \phi}{\partial y} & \phi \frac{\partial \phi}{\partial z} \end{array} \right| \quad \text{[} \frac{\partial}{\partial x}(x-y) \text{] } \quad \text{[} \frac{\partial}{\partial y}(y-z) \text{] } \quad \text{[} \frac{\partial}{\partial z}(z-x) \text{] } \\
 &= \hat{i} \left[\frac{\partial}{\partial y} \left(\phi \frac{\partial \phi}{\partial z} \right) - \frac{\partial}{\partial z} \left(\phi \frac{\partial \phi}{\partial y} \right) \right] + \hat{j} \left[\frac{\partial}{\partial z} \left(\phi \frac{\partial \phi}{\partial x} \right) - \frac{\partial}{\partial x} \left(\phi \frac{\partial \phi}{\partial z} \right) \right] \\
 &\quad + \hat{k} \left[\frac{\partial}{\partial x} \left(\phi \frac{\partial \phi}{\partial y} \right) - \frac{\partial}{\partial y} \left(\phi \frac{\partial \phi}{\partial x} \right) \right] \\
 &= \hat{i} \left[\frac{\partial \phi}{\partial y} \cdot \frac{\partial \phi}{\partial z} + \phi \frac{\partial^2 \phi}{\partial y \partial z} - \left(\frac{\partial \phi}{\partial z} \cdot \frac{\partial \phi}{\partial y} + \phi \frac{\partial^2 \phi}{\partial y \partial z} \right) \right] \\
 &\quad + \hat{j} \left[\frac{\partial \phi}{\partial z} \cdot \frac{\partial \phi}{\partial x} + \phi \frac{\partial^2 \phi}{\partial z \partial x} - \left(\frac{\partial \phi}{\partial x} \cdot \frac{\partial \phi}{\partial z} + \phi \frac{\partial^2 \phi}{\partial z \partial x} \right) \right] \\
 &\quad + \hat{k} \left[\frac{\partial \phi}{\partial x} \cdot \frac{\partial \phi}{\partial y} + \phi \frac{\partial^2 \phi}{\partial x \partial y} - \left(\frac{\partial \phi}{\partial y} \cdot \frac{\partial \phi}{\partial x} + \phi \frac{\partial^2 \phi}{\partial x \partial y} \right) \right] \\
 &= 0 = \text{R.H.S.}
 \end{aligned}$$

$\therefore \text{L.H.S.} = \text{R.H.S.}$ (Proved)

$$\left[\left(\frac{\partial \phi}{\partial x} + i \frac{\partial \phi}{\partial y} + j \frac{\partial \phi}{\partial z} \right) \phi \right] \times \vec{v} =$$

Erlöse 98: Prove $(\vec{v} \cdot \vec{\nabla}) \vec{v} = \frac{1}{2} \vec{\nabla} v^2 - \vec{\nabla} \times (\vec{\nabla} \times \vec{v})$

Solution:

$$\text{R.H.S.} = \frac{1}{2} \vec{\nabla} |\vec{v}|^2 - \vec{\nabla} \times (\vec{\nabla} \times \vec{v})$$

$$= \frac{1}{2} 2|\vec{v}|^0 \vec{v} - \vec{\nabla} \times \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ v_1 & v_2 & v_3 \end{vmatrix} (\vec{\nabla} \times \vec{v})$$

$$= \vec{v} - \vec{\nabla} \times \left[\hat{i} \left(\frac{\partial v_3}{\partial y} - \frac{\partial v_2}{\partial z} \right) + \hat{j} \left(\frac{\partial v_1}{\partial z} - \frac{\partial v_3}{\partial x} \right) + \hat{k} \left(\frac{\partial v_2}{\partial x} - \frac{\partial v_1}{\partial y} \right) \right]$$

$$(\vec{v} = \vec{V}) \Rightarrow - \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ v_1 & v_2 & v_3 \\ \frac{\partial v_3}{\partial y} - \frac{\partial v_2}{\partial z} & \frac{\partial v_1}{\partial z} - \frac{\partial v_3}{\partial x} & \frac{\partial v_2}{\partial x} - \frac{\partial v_1}{\partial y} \end{vmatrix}$$

$$= \vec{v} - \hat{i} \left(v_2 \frac{\partial v_2}{\partial x} - v_2 \frac{\partial v_1}{\partial y} - v_3 \frac{\partial v_1}{\partial z} + v_3 \frac{\partial v_3}{\partial x} \right)$$

$$- \hat{j} \left(v_3 \frac{\partial v_3}{\partial y} - v_3 \frac{\partial v_2}{\partial z} - v_1 \frac{\partial v_2}{\partial x} + v_1 \frac{\partial v_1}{\partial y} \right)$$

$$- \hat{k} \left(v_1 \frac{\partial v_1}{\partial z} - v_1 \frac{\partial v_3}{\partial x} - v_2 \frac{\partial v_3}{\partial y} + v_2 \frac{\partial v_2}{\partial z} \right)$$

$$= \vec{v} - \hat{i} \left(v_1 \frac{\partial v_1}{\partial x} + v_2 \frac{\partial v_2}{\partial x} + v_3 \frac{\partial v_3}{\partial x} \right) - \hat{j} \left(v_1 \frac{\partial v_1}{\partial y} + v_2 \frac{\partial v_2}{\partial y} + v_3 \frac{\partial v_3}{\partial y} \right)$$

$$- \hat{k} \left(v_1 \frac{\partial v_1}{\partial z} + v_2 \frac{\partial v_2}{\partial z} + v_3 \frac{\partial v_3}{\partial z} \right) + \hat{i} \left(v_1 \frac{\partial v_1}{\partial x} + v_2 \frac{\partial v_1}{\partial y} + v_3 \frac{\partial v_1}{\partial z} \right)$$

$$+ \hat{j} \left(v_1 \frac{\partial v_2}{\partial x} + v_2 \frac{\partial v_2}{\partial y} + v_3 \frac{\partial v_2}{\partial z} \right) + \hat{k} \left(v_1 \frac{\partial v_3}{\partial x} + v_2 \frac{\partial v_3}{\partial y} + v_3 \frac{\partial v_3}{\partial z} \right)$$

$$\begin{aligned}
 &= \vec{v} - \hat{i}(v_1 + 0 + 0) - \hat{j}(0 + v_2 + 0) - \hat{k}(0 + 0 + v_3) \\
 &\quad + \left\{ (v_1 \hat{i} + v_2 \hat{j} + v_3 \hat{k}) \cdot \left(\frac{\partial}{\partial x} \hat{i} + \frac{\partial}{\partial y} \hat{j} + \frac{\partial}{\partial z} \hat{k} \right) \right\} (v_1 \hat{i} + v_2 \hat{j} + v_3 \hat{k}) \\
 &= \vec{v} - \vec{v} + (\vec{v} \cdot \vec{v}) \cdot \vec{v} \\
 &= (\vec{v} \cdot \vec{v}) \cdot \vec{v} \\
 &= R.H.S.
 \end{aligned}$$

$\therefore L.H.S. = R.H.S. \text{ (Proved)}$

[Ex-99]: Prove $\vec{\nabla} \cdot (\vec{A} \times \vec{B}) = \vec{B} \cdot (\vec{\nabla} \times \vec{A}) - \vec{A} \cdot (\vec{\nabla} \times \vec{B})$

Solution:

~~L.H.S. $\vec{\nabla} \cdot (\vec{A} \times \vec{B})$~~

$$R.H.S. = \vec{B} \cdot (\vec{\nabla} \times \vec{A}) - \vec{A} \cdot (\vec{\nabla} \times \vec{B})$$

$$= \vec{B} \cdot \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ A_1 & A_2 & A_3 \end{vmatrix} - \vec{A} \cdot \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ B_1 & B_2 & B_3 \end{vmatrix}$$

$$\begin{aligned}
 &= (B_1 \hat{i} + B_2 \hat{j} + B_3 \hat{k}) \cdot \left[\hat{i} \left(\frac{\partial A_3}{\partial y} - \frac{\partial A_2}{\partial z} \right) + \hat{j} \left(\frac{\partial A_1}{\partial z} - \frac{\partial A_3}{\partial x} \right) \right. \\
 &\quad \left. + \hat{k} \left(\frac{\partial A_2}{\partial x} - \frac{\partial A_1}{\partial y} \right) \right] - (A_1 \hat{i} + A_2 \hat{j} + A_3 \hat{k}) \cdot \\
 &\quad \left[\hat{i} \left(\frac{\partial B_3}{\partial y} - \frac{\partial B_2}{\partial z} \right) + \hat{j} \left(\frac{\partial B_1}{\partial z} - \frac{\partial B_3}{\partial x} \right) + \hat{k} \left(\frac{\partial B_2}{\partial x} - \frac{\partial B_1}{\partial y} \right) \right]
 \end{aligned}$$

$$\begin{aligned}
 &= B_1 \frac{\partial A_3}{\partial y} - B_1 \frac{\partial A_2}{\partial z} + B_2 \frac{\partial A_1}{\partial z} - B_2 \frac{\partial A_3}{\partial x} + B_3 \frac{\partial A_2}{\partial x} - B_3 \frac{\partial A_1}{\partial y} \\
 &\quad - A_1 \frac{\partial B_3}{\partial y} + A_1 \frac{\partial B_2}{\partial z} - A_2 \frac{\partial B_1}{\partial z} + A_2 \frac{\partial B_3}{\partial x} - A_3 \frac{\partial B_2}{\partial x} + A_3 \frac{\partial B_1}{\partial y} \\
 &= A_2 \frac{\partial B_3}{\partial x} + B_3 \frac{\partial A_2}{\partial x} - A_3 \frac{\partial B_2}{\partial x} - B_2 \frac{\partial A_3}{\partial x} + A_3 \frac{\partial B_1}{\partial y} + B_1 \frac{\partial A_3}{\partial y} \\
 &\quad - A_1 \frac{\partial B_3}{\partial y} - B_3 \frac{\partial A_1}{\partial y} + A_1 \frac{\partial B_2}{\partial z} + B_2 \frac{\partial A_1}{\partial z} - A_2 \frac{\partial B_1}{\partial z} - B_1 \frac{\partial A_2}{\partial z} \\
 &= \frac{\partial}{\partial x} (A_2 B_3) - \frac{\partial}{\partial x} (A_3 B_2) + \frac{\partial}{\partial y} (A_3 B_1) - \frac{\partial}{\partial y} (A_1 B_3) \\
 &\quad + \frac{\partial}{\partial z} (A_1 B_2) - \frac{\partial}{\partial z} (A_2 B_1) \\
 &= \frac{\partial}{\partial x} (A_2 B_3 - A_3 B_2) + \frac{\partial}{\partial y} (A_3 B_1 - A_1 B_3) + \frac{\partial}{\partial z} (A_1 B_2 - A_2 B_1) \\
 &= \vec{\nabla} \cdot (\vec{A} \times \vec{B})
 \end{aligned}$$

$$= R.L.H.S.$$

$$\therefore L.H.S. = R.H.S. \text{ (Proved)}$$

B11 :- 100: Prove $\vec{\nabla} \times (\vec{A} \times \vec{B}) = (\vec{B} \cdot \vec{\nabla}) \vec{A} - \vec{B} (\vec{\nabla} \cdot \vec{A}) - (\vec{A} \cdot \vec{\nabla}) \cdot \vec{B} + \vec{A} (\vec{\nabla} \cdot \vec{B})$

Solution:-

$$R.H.S. = (\vec{B} \cdot \vec{\nabla}) \vec{A} - \vec{B} (\vec{\nabla} \cdot \vec{A}) - (\vec{A} \cdot \vec{\nabla}) \cdot \vec{B} + \vec{A} (\vec{\nabla} \cdot \vec{B})$$

$$= \left(B_1 \frac{\partial}{\partial x} + B_2 \frac{\partial}{\partial y} + B_3 \frac{\partial}{\partial z} \right) (A_1 \hat{i} + A_2 \hat{j} + A_3 \hat{k}) - (B_1 \hat{i} + B_2 \hat{j} + B_3 \hat{k}) \left(\frac{\partial A_1}{\partial x} + \frac{\partial A_2}{\partial y} + \frac{\partial A_3}{\partial z} \right)$$

$$- (A_1 \frac{\partial}{\partial x} + A_2 \frac{\partial}{\partial y} + A_3 \frac{\partial}{\partial z}) \cdot (B_1 \hat{i} + B_2 \hat{j} + B_3 \hat{k}) + (A_1 \hat{i} + A_2 \hat{j} + A_3 \hat{k}) \left(\frac{\partial B_1}{\partial x} + \frac{\partial B_2}{\partial y} + \frac{\partial B_3}{\partial z} \right)$$

$$= \hat{i} \left(B_1 \frac{\partial A_1}{\partial x} + B_2 \frac{\partial A_1}{\partial y} + B_3 \frac{\partial A_1}{\partial z} - B_1 \frac{\partial A_1}{\partial x} - B_1 \frac{\partial A_2}{\partial y} - B_1 \frac{\partial A_3}{\partial z} - A_1 \frac{\partial B_1}{\partial x} - A_2 \frac{\partial B_1}{\partial y} - A_3 \frac{\partial B_1}{\partial z} + A_2 \frac{\partial B_1}{\partial x} + A_1 \frac{\partial B_2}{\partial y} + A_1 \frac{\partial B_3}{\partial z} \right)$$

$$+ \hat{j} \left(B_1 \frac{\partial A_2}{\partial x} + B_2 \frac{\partial A_2}{\partial y} + B_3 \frac{\partial A_2}{\partial z} - B_2 \frac{\partial A_1}{\partial x} - B_2 \frac{\partial A_2}{\partial y} - B_2 \frac{\partial A_3}{\partial z} - A_1 \frac{\partial B_2}{\partial x} - A_2 \frac{\partial B_2}{\partial y} - A_3 \frac{\partial B_2}{\partial z} + A_2 \frac{\partial B_1}{\partial x} + A_2 \frac{\partial B_2}{\partial y} + A_2 \frac{\partial B_3}{\partial z} \right)$$

$$+ \hat{k} \left(B_1 \frac{\partial A_3}{\partial x} + B_2 \frac{\partial A_3}{\partial y} + B_3 \frac{\partial A_3}{\partial z} - B_3 \frac{\partial A_1}{\partial x} - B_3 \frac{\partial A_2}{\partial y} - B_3 \frac{\partial A_3}{\partial z} - A_1 \frac{\partial B_3}{\partial x} - A_2 \frac{\partial B_3}{\partial y} - A_3 \frac{\partial B_3}{\partial z} + A_3 \frac{\partial B_1}{\partial x} + A_3 \frac{\partial B_2}{\partial y} + A_3 \frac{\partial B_3}{\partial z} \right)$$

$$\begin{aligned}
&= \hat{i} \left(A_1 \frac{\partial B_2}{\partial y} + B_2 \frac{\partial A_1}{\partial y} - A_2 \frac{\partial B_1}{\partial y} - B_1 \frac{\partial A_2}{\partial y} - A_3 \frac{\partial B_1}{\partial z} - B_1 \frac{\partial A_3}{\partial z} \right) \\
&\quad + A_1 \frac{\partial B_3}{\partial z} + B_3 \frac{\partial A_1}{\partial z} \right) + \hat{j} \left(A_2 \frac{\partial B_3}{\partial z} + B_3 \frac{\partial A_2}{\partial z} - A_3 \frac{\partial B_2}{\partial z} \right. \\
&\quad \left. - B_2 \frac{\partial A_3}{\partial z} - A_1 \frac{\partial B_2}{\partial x} - B_2 \frac{\partial A_1}{\partial x} + A_2 \frac{\partial B_1}{\partial x} + B_1 \frac{\partial A_2}{\partial x} \right) \\
&\quad + \hat{k} \left(A_3 \frac{\partial B_1}{\partial x} + B_1 \frac{\partial A_3}{\partial x} - A_1 \frac{\partial B_3}{\partial x} - B_3 \frac{\partial A_1}{\partial x} - A_2 \frac{\partial B_3}{\partial y} \right. \\
&\quad \left. - B_3 \frac{\partial A_2}{\partial y} + A_2 \frac{\partial B_2}{\partial y} + B_2 \frac{\partial A_2}{\partial y} \right) \\
&= \hat{i} \left[\frac{\partial}{\partial y} (A_1 B_2) - \frac{\partial}{\partial y} (A_2 B_1) - \frac{\partial}{\partial z} (A_3 B_1) + \frac{\partial}{\partial z} (A_1 B_3) \right] \\
&\quad + \hat{j} \left[\frac{\partial}{\partial z} (A_2 B_3) - \frac{\partial}{\partial z} (A_3 B_2) - \frac{\partial}{\partial x} (A_1 B_2) + \frac{\partial}{\partial x} (A_2 B_1) \right] \\
&\quad + \hat{k} \left[\frac{\partial}{\partial x} (A_3 B_1) - \frac{\partial}{\partial x} (A_1 B_3) - \frac{\partial}{\partial y} (A_2 B_3) + \frac{\partial}{\partial y} (A_3 B_2) \right] \\
&= \hat{i} \left[\frac{\partial}{\partial y} (A_1 B_2 - A_2 B_1) - \frac{\partial}{\partial z} (A_3 B_1 - A_1 B_3) \right] \\
&\quad + \hat{j} \left[\frac{\partial}{\partial z} (A_2 B_3 - A_3 B_2) - \frac{\partial}{\partial x} (A_1 B_2 - A_2 B_1) \right] \\
&\quad + \hat{k} \left[\frac{\partial}{\partial x} (A_3 B_1 - A_1 B_3) - \frac{\partial}{\partial y} (A_2 B_3 - A_3 B_2) \right] \\
&= \vec{J} \times (\vec{A} \times \vec{B}) \\
&= R.L.H.S. \\
&\therefore L.H.S. = R.H.S. \text{ (Proved)}
\end{aligned}$$

$$\boxed{\text{Ex. 101}}: \text{Prove } \nabla(\vec{A} \cdot \vec{B}) = (\vec{B} \cdot \nabla) \vec{A} + (\vec{A} \cdot \nabla) \vec{B} + \vec{B} \times (\nabla \times \vec{A}) + \vec{A} \times (\nabla \times \vec{B})$$

Solution:

$$R.H.S. = (\vec{B} \cdot \nabla) \vec{A} + (\vec{A} \cdot \nabla) \vec{B} + \vec{B} \times (\nabla \times \vec{A}) + \vec{A} \times (\nabla \times \vec{B})$$

$$= \left(B_1 \frac{\partial}{\partial x} + B_2 \frac{\partial}{\partial y} + B_3 \frac{\partial}{\partial z} \right) (A_1 \hat{i} + A_2 \hat{j} + A_3 \hat{k})$$

$$+ \left(A_1 \frac{\partial}{\partial x} + A_2 \frac{\partial}{\partial y} + A_3 \frac{\partial}{\partial z} \right) (B_1 \hat{i} + B_2 \hat{j} + B_3 \hat{k})$$

$$+ \vec{B} \times \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ A_1 & A_2 & A_3 \end{vmatrix} + \vec{A} \times \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ B_1 & B_2 & B_3 \end{vmatrix}$$

$$= \left(B_1 \frac{\partial}{\partial x} + B_2 \frac{\partial}{\partial y} + B_3 \frac{\partial}{\partial z} \right) (A_1 \hat{i} + A_2 \hat{j} + A_3 \hat{k})$$

$$+ \left(A_1 \frac{\partial}{\partial x} + A_2 \frac{\partial}{\partial y} + A_3 \frac{\partial}{\partial z} \right) (B_1 \hat{i} + B_2 \hat{j} + B_3 \hat{k})$$

$$+ \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ B_1 & B_2 & B_3 \\ \frac{\partial A_3}{\partial y} - \frac{\partial A_2}{\partial z} & \frac{\partial A_1}{\partial z} - \frac{\partial A_3}{\partial x} & \frac{\partial A_2}{\partial x} - \frac{\partial A_1}{\partial y} \end{vmatrix}$$

$$[(\partial A_3 / \partial y) \hat{i} + (\partial A_1 / \partial z) \hat{j} + (\partial A_2 / \partial x) \hat{k}]$$

$$+ \begin{vmatrix} A_1 & A_2 & A_3 \\ \frac{\partial B_3}{\partial y} - \frac{\partial B_2}{\partial z} & \frac{\partial B_1}{\partial z} - \frac{\partial B_3}{\partial x} & \frac{\partial B_2}{\partial x} - \frac{\partial B_1}{\partial y} \end{vmatrix}$$

$$\begin{aligned}
&= \hat{i} \left(B_1 \frac{\partial A_1}{\partial x} + B_2 \cancel{\frac{\partial A_1}{\partial y}} + B_3 \cancel{\frac{\partial A_1}{\partial z}} + A_1 \frac{\partial B_1}{\partial x} + A_2 \cancel{\frac{\partial B_1}{\partial y}} + A_3 \cancel{\frac{\partial B_1}{\partial z}} \right. \\
&\quad \left. + B_2 \frac{\partial A_2}{\partial x} - B_2 \cancel{\frac{\partial A_1}{\partial y}} - B_3 \cancel{\frac{\partial A_1}{\partial z}} + B_3 \frac{\partial A_3}{\partial x} + A_2 \frac{\partial B_2}{\partial x} - A_2 \cancel{\frac{\partial B_1}{\partial y}} \right. \\
&\quad \left. - A_3 \cancel{\frac{\partial B_1}{\partial z}} + A_3 \frac{\partial B_3}{\partial x} \right) + \hat{j} \left(B_1 \cancel{\frac{\partial A_2}{\partial x}} + B_2 \frac{\partial A_2}{\partial y} + B_3 \cancel{\frac{\partial A_2}{\partial z}} \right. \\
&\quad \left. + A_1 \cancel{\frac{\partial B_2}{\partial x}} + A_2 \frac{\partial B_2}{\partial y} + A_3 \cancel{\frac{\partial B_2}{\partial z}} + B_3 \frac{\partial A_3}{\partial y} - B_3 \cancel{\frac{\partial A_2}{\partial z}} - B_1 \cancel{\frac{\partial A_2}{\partial x}} \right. \\
&\quad \left. + B_1 \frac{\partial A_1}{\partial y} + A_3 \frac{\partial B_3}{\partial y} - A_3 \cancel{\frac{\partial B_2}{\partial z}} - A_1 \cancel{\frac{\partial B_2}{\partial x}} + A_1 \frac{\partial B_1}{\partial y} \right) \\
&\quad + \hat{k} \left(B_1 \cancel{\frac{\partial A_3}{\partial x}} + B_2 \cancel{\frac{\partial A_3}{\partial y}} + B_3 \frac{\partial A_3}{\partial z} + A_1 \cancel{\frac{\partial B_3}{\partial x}} + A_2 \cancel{\frac{\partial B_3}{\partial y}} + A_3 \frac{\partial B_3}{\partial z} \right. \\
&\quad \left. + B_1 \cancel{\frac{\partial A_1}{\partial z}} - B_1 \cancel{\frac{\partial A_2}{\partial x}} - B_2 \cancel{\frac{\partial A_2}{\partial y}} + B_2 \frac{\partial A_2}{\partial z} + A_1 \cancel{\frac{\partial B_1}{\partial z}} - A_1 \cancel{\frac{\partial B_3}{\partial x}} \right. \\
&\quad \left. - A_2 \cancel{\frac{\partial B_3}{\partial y}} + A_3 \frac{\partial B_2}{\partial z} \right) \\
&= \hat{i} \left[\frac{\partial}{\partial x} (A_1 B_1) + \frac{\partial}{\partial x} (A_2 B_2) + \frac{\partial}{\partial x} (A_3 B_3) \right] \\
&\quad + \hat{j} \left[\frac{\partial}{\partial y} (A_1 B_1) + \frac{\partial}{\partial y} (A_2 B_2) + \frac{\partial}{\partial y} (A_3 B_3) \right] \\
&\quad + \hat{k} \left[\frac{\partial}{\partial z} (A_1 B_1) + \frac{\partial}{\partial z} (A_2 B_2) + \frac{\partial}{\partial z} (A_3 B_3) \right] \\
&= \hat{i} \frac{\partial}{\partial x} (A_1 B_1 + A_2 B_2 + A_3 B_3) + \hat{j} \frac{\partial}{\partial y} (A_1 B_1 + A_2 B_2 + A_3 B_3) \\
&\quad + \hat{k} \frac{\partial}{\partial z} (A_1 B_1 + A_2 B_2 + A_3 B_3)
\end{aligned}$$

$$= \left(\frac{\partial}{\partial x} \hat{i} + \frac{\partial}{\partial y} \hat{j} + \frac{\partial}{\partial z} \hat{k} \right) (A_1 B_1 + A_2 B_2 + A_3 B_3)$$

$$= \vec{\nabla} (\vec{A} \cdot \vec{B})$$

= L.H.S.

L.H.S. = R.H.S. (proved)

27-02-2018:5A: Tuesday

→ Vector integration:

$\vec{R}(u)$ is vector where u is scalar. The integration

$$\vec{R}(u) \text{ is } \int \vec{R}(u) du$$

$$= \int R_1 du \hat{i} + \int R_2 du \hat{j} + \int R_3 du \hat{k} + \text{const}$$

$$\vec{R}(t) = t^2 \hat{i} + 2t \hat{j} + \hat{k}$$

$$\Rightarrow \int \vec{R}(t) = \int t^2 dt \hat{i} + \int 2t dt \hat{j} + \int dt \hat{k}$$

$$= \frac{t^3}{3} \hat{i} + t^2 \hat{j} + t \hat{k} + \text{const}$$

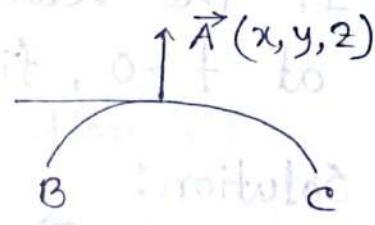
→ Line integration:

Line integration is the integration of the component of the unit tangent vectors of \vec{A} .

the unit tangent vectors of \vec{A} , $\vec{T} = \frac{d\vec{r}}{ds}$

the component of the unit tangent vectors of \vec{A}

$$= \vec{A} \cdot \frac{d\vec{r}}{ds}$$



$$\therefore \text{Line integration} = \int_C \vec{A} \cdot \frac{d\vec{r}}{ds} \cdot ds$$

$$= \int_C \vec{A} \cdot d\vec{r}$$

Ex:1 If $\vec{R}(u) = (u-u^2)\hat{i} + 2u^3\hat{j} - 3u\hat{k}$, find $\int \vec{R}(u) du$.

Solution:

$$= \int (u-u^2) du \hat{i} + \int (2u^3) du \hat{j} + \int (-3u) du \hat{k}$$

$$= \left(\frac{u^2}{2} - \frac{u^3}{3} \right) \hat{i} + \frac{u^4}{2} \hat{j} - 3u^2 \hat{k}$$

where, c is an integrating constant.

Ex:2

The acceleration of a particle at any time $t \geq 0$ is given by $\vec{a} = \frac{d\vec{v}}{dt} = 12 \cos 2t \hat{i} - 8 \sin 2t \hat{j} + 16t \hat{k}$.

If the velocity, \vec{v} and displacement, \vec{r} are zero at $t=0$, find \vec{v} & \vec{r} at any time.

Solution:

$$\vec{a} = \frac{d\vec{v}}{dt} = 12 \cos 2t \hat{i} - 8 \sin 2t \hat{j} + 16t \hat{k}$$

$$\Rightarrow d\vec{v} = (12 \cos 2t) dt \hat{i} - (8 \sin 2t) dt \hat{j} + (16t) dt \hat{k}$$

By integrating,

$$\int d\vec{v} = \int (12 \cos 2t) dt \hat{i} - \int (8 \sin 2t) dt \hat{j} + \int (16t) dt \hat{k}$$

$$\Rightarrow \vec{v} = 6 \sin 2t \hat{i} + 4 \cos 2t \hat{j} + 8t^2 \hat{k} + C_1 \quad \text{--- (i)}$$

$$\Rightarrow \frac{d\vec{r}}{dt} = 6 \sin 2t \hat{i} + 4 \cos 2t \hat{j} + 8t^2 \hat{k} + C_1$$

$$\Rightarrow d\vec{r} = (6 \sin 2t) dt \hat{i} + (4 \cos 2t) dt \hat{j} + (8t^2) dt \hat{k} + C_1 dt$$

By integrating,

$$\int d\vec{r} = \int (6\sin 2t) dt \hat{i} + \int (4\cos 2t) dt \hat{j} + \int (8t^2) dt \hat{k} + \int c_1 dt$$
$$\Rightarrow \vec{r} = -3\cos 2t \hat{i} + 2\sin 2t \hat{j} + \frac{8t^3}{3} \hat{k} + c_1 t + c_2 \quad \text{(ii)}$$

at $t=0$, (i) & (ii) no. equation.

$$\vec{r} = 4\hat{j} + c_1 \therefore c_1 = -4\hat{j}$$

$$0 = -3\hat{i} + c_2 \therefore c_2 = 3\hat{i}$$

putting the value of c_1 in equation (i)

$$\vec{v} = 6\sin 2t \hat{i} + 4\cos 2t \hat{j} + 8t^2 \hat{k} - 4\hat{j}$$

$$\therefore \vec{v} = 6\sin 2t \hat{i} + (4\cos 2t - 4) \hat{j} + 8t^2 \hat{k}$$

putting the value of c_1 and c_2 in equation (ii)

$$\vec{r} = -3\cos 2t \hat{i} + 2\sin 2t \hat{j} + \frac{8t^3}{3} \hat{k} - 4t \hat{j} + 3\hat{i}$$

$$\vec{r} = (3 - 3\cos 2t) \hat{i} + (2\sin 2t - 4t) \hat{j} + \frac{8t^3}{3} \hat{k}$$

Exm: 6 If $\vec{A} = (3x^2 + 6y) \hat{i} - 14yz^2 \hat{j} + 20xz^2 \hat{k}$, evaluate

$\int \vec{A} \cdot d\vec{r}$ from $(0,0,0)$ to along the following path C.

i) $x=t$, $y=t^2$, $z=t^3$

ii) the straight line from $(0,0,0)$ to $(1,0,0)$, then $(1,1,0)$ and then $(1,1,1)$

i)

$$\begin{aligned}
 \int_C \vec{A} \cdot d\vec{r} &= \int_C \{(3x^2 + 6y)\hat{i} - 14yz\hat{j} + 20xz^2\hat{k}\} \cdot (dx\hat{i} + dy\hat{j} + dz\hat{k}) \\
 &= \int_C \{(3x^2 + 6y)dx - (14yz)dy + (20xz^2)dz\} \\
 &= \int_0^1 \{(3t^2 + 6t^2)dt - (14t^5)2tdt + (20t^7)3t^2dt\} \\
 &= \int_0^1 (9t^2 - 28t^6 + 60t^9)dt = 0 \\
 &= [3t^3 - 4t^7 + 6t^{10}]_0^1 = 3 - 4 + 6 = 5.
 \end{aligned}$$

ii)

(ii) not loops in 3-space to evaluate surface fitting

The straight line, $(0,0,0)$ to $(1,0,0)$ $y=0, z=0, dy=0, dz=0$ and only x varies from 0 to 1.

$$\int_C \vec{A} \cdot d\vec{r} = \int_C \{(3x^2 + 6y)\hat{i} - 14yz\hat{j} + 20xz^2\hat{k}\} \cdot (dx\hat{i} + dy\hat{j} + dz\hat{k})$$

$$\text{start from } = \int_C \{(3x^2 + 6y)dx - (14yz)dy + (20xz^2)dz\} \quad \text{at } t=0$$

$$\begin{aligned}
 &= \int_0^1 (3x^2 + 6y)dx - \int_0^1 (14yz)dy + \int_0^1 (20xz^2)dz \\
 &= [x^3]_0^1 + 0 + 0
 \end{aligned}$$

$$\begin{aligned}
 &= (0,0,t) \text{ at } (0,0,0) \text{ and end tangent at } (1,0,0) \\
 &= 1
 \end{aligned}$$

The straight line from $(1, 0, 0)$ to $(1, 1, 0)$
 $x=1, z=0, dx=0, dz=0$ and only y varies from 0 to 1

$$\int \vec{A} \cdot d\vec{r} = \int_C \{(3x^2 + 6y)dx - (14yz)dy + (20xz^2)dz\}$$

$$= \int_1^1 (3x^2 + 6y)dx - \int_0^1 (14yz)dy + \int_0^0 (20xz^2)dz$$

$$= 0(3+6) + i(1+6) = 5i \text{ units ENT}$$

The straight line from $(1, 1, 0)$ to $(1, 1, 1)$

$x=1, y=1, dx=0, dy=0$ and only z varies from 0 to 1

$$\int \vec{A} \cdot d\vec{r} = \int_C \{(3x^2 + 6y)dx - (14yz)dy + (20xz^2)dz\}$$

$$= \int_1^1 (3x^2 + 6y)dx - \int_0^1 (14yz)dy + \int_0^1 (20xz^2)dz$$

$$= \int_0^1 (20z^2)dz$$

$$= \left[\frac{20z^3}{3} \right]_0^1 (1)(1) - (1)(1+6+10) \} =$$

$$= \frac{20}{3} (100 + 100 + 100 - 17) =$$

$$\text{Adding the straight line} = 1 + 0 + \frac{20}{3}$$

$$= \frac{23}{3}$$

$$= [100 + 100 + 100 + 17] =$$

$$= 300 + 300 + 300 + 17 = 917$$

05-03-2018 : 5 E : Monday : most will trip points SNT
 Em:07
 Find the total work done in moving a particle in a forces field (given) by $\vec{F} = 3xy\hat{i} - 5z\hat{j} + 10x\hat{k}$.
 Along the curve $x=t^2+1$, $y=2t^2$, $z=t^3$ from $t=1$ to $t=2$.

Solution:

The curve, $\vec{r} = (t^2+1)\hat{i} + (2t^2)\hat{j} + t^3\hat{k}$

(i.e.) $d\vec{r} = (2t\hat{i} + 4t\hat{j} + 3t^2\hat{k})dt$

1 of 1 The work done from $t=1$ to $t=2$ is

$$\begin{aligned} & \int_C (\vec{F} \cdot d\vec{r}) = \int_1^2 ((3xy\hat{i} - 5z\hat{j} + 10x\hat{k}) \cdot (2t\hat{i} + 4t\hat{j} + 3t^2\hat{k})) dt \\ &= \int_1^2 ((3xy)(2t) - (5z)(4t) + (10x)(3t^2)) dt \\ &= \int_1^2 ((6t^4 + 6t^2)(2t) - (5t^3)(4t) + (10t^2 + 10)(3t^2)) dt \\ &= \int_1^2 (12t^5 + 12t^3 - 20t^4 + 30t^4 + 30t^2) dt \\ &= \int_1^2 (12t^5 + 10t^4 + 12t^3 + 30t^2) dt \\ &= [2t^6 + 2t^5 + 3t^4 + 10t^3]_1^2 \\ &= 128 + 64 + 48 + 80 - 2 - 2 - 3 - 10 = 303 \end{aligned}$$

Ex: 08 If $\vec{F} = 3xy\hat{i} - y^2\hat{j}$, evaluate $\int \vec{F} \cdot d\vec{r}$ where C is the curve in the xy plane $y = 2x^2$, from $(0,0)$ to $(1,2)$.

Solution:

As the curve is in xy plane,

$$d\vec{r} = dx\hat{i} + dy\hat{j}$$

$$y = 2x^2$$

$$\Rightarrow \frac{dy}{dx} = 4x \therefore dy = 4x dx$$

$$\int_C \vec{F} \cdot d\vec{r}$$

$$= \int_C (3xy\hat{i} - y^2\hat{j}) \cdot (dx\hat{i} + dy\hat{j})$$

$$= \int_0^1 (3xy) dx - \int_0^2 (y^2) dy$$

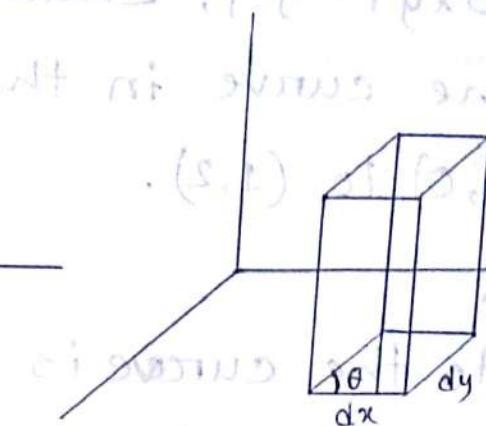
$$= \int_0^1 (6x^3) dx - \int_0^2 (y^2) dy$$

$$= \left[\frac{3x^4}{2} \right]_0^1 - \left[\frac{y^3}{3} \right]_0^2$$

$$= \frac{3}{2} - \frac{8}{3}$$

$$= \frac{9-16}{6} = -\frac{7}{6}$$

→ Surface integration



$$\begin{aligned} \text{surface integration} &= \iint \vec{F} \cdot d\vec{s} \\ &= \iint \vec{F} \cdot \hat{n} \cdot d\vec{s} \end{aligned}$$

From figure,

$$\text{projection} = ds \cos \theta$$

$$\Rightarrow dx dy = ds |\hat{n} \cdot \hat{k}|$$

$$\Rightarrow ds = \frac{dx dy}{|\hat{n} \cdot \hat{k}|}$$

$$\begin{aligned} \hat{n} \cdot \hat{k} &= |\hat{n}| \cdot |\hat{k}| \cos \theta \\ \Rightarrow \cos \theta &= \frac{\hat{n} \cdot \hat{k}}{|\hat{n}| \cdot |\hat{k}|} \\ \Rightarrow \cos \theta &= \hat{n} \cdot \hat{k} \\ [\text{As } \hat{n} \text{ & } \hat{k} \text{ unit vector;} |\hat{n}| = |\hat{k}| = 1] \end{aligned}$$

$$\therefore \text{surface integration} = \iint \vec{F} \cdot \hat{n} \frac{dx dy}{|\hat{n} \cdot \hat{k}|}$$

→ 20-03-2018: EE: Tuesday

Em: 19 Evaluate $\iint \vec{A} \cdot \hat{n} ds$ where $\vec{A} = 18x^2 \hat{i} - 12y^2 \hat{j} + 3y \hat{k}$

and S is $2x + 3y + 6z = 12$ which is located in the first octant.

Solution:

$$\text{Let, } \phi = 2x + 3y + 6z - 12$$

$$\begin{aligned} \vec{\nabla} \phi &= \frac{\partial}{\partial x} (2x) \hat{i} + \frac{\partial}{\partial y} (3y) \hat{j} + \frac{\partial}{\partial z} (6z) \hat{k} \\ &= 2 \hat{i} + 3 \hat{j} + 6 \hat{k} \end{aligned}$$

$$|\vec{\nabla}\phi| = \sqrt{4+9+36} = \sqrt{49} = 7$$

$$\hat{n} = \frac{\nabla\phi}{|\nabla\phi|} = \frac{1}{7}(2\hat{i} + 3\hat{j} + 6\hat{k})$$

As the surface is located at first octant, so it is in xy plane.

$$ds = \frac{dx dy}{|\hat{n} \cdot \hat{k}|}$$

$$\therefore \hat{n} \cdot \hat{k} = \frac{6}{7}$$

$$\therefore \iint \vec{A} \cdot \hat{n} \cdot ds$$

$$= \iint_{x=0, y=0}^6 \left(18\hat{i} - 12\hat{j} + 3y\hat{k} \right) \cdot \frac{1}{7}(2\hat{i} + 3\hat{j} + 6\hat{k}) dx dy \frac{7}{6}$$

$$= \frac{1}{6} \iint_0^6 (362 - 36 + 18y) dx dy$$

$$= \frac{1}{6} \iint_0^6 \left\{ 36 \left(\frac{12-2x-3y}{6} \right) - 36 + 18y \right\} dx dy$$

$$= \frac{1}{6} \iint_0^6 (72 - 12x - 18y - 36 + 18y) dx dy$$

$$= \frac{1}{6} \iint_0^6 (36 - 12x) dy dx$$

$$\therefore \text{In } xy \text{ plane the surface equation, } 2x + 3y = 12$$

$$\therefore y = \frac{12-2x}{3}$$

$$\text{If } y=0, \text{ in the surface equation, } 2x = 12$$

$$\therefore x = 6$$

$$2x + 3y + 6z = 12 \\ \therefore z = \frac{12-2x-3y}{6}$$

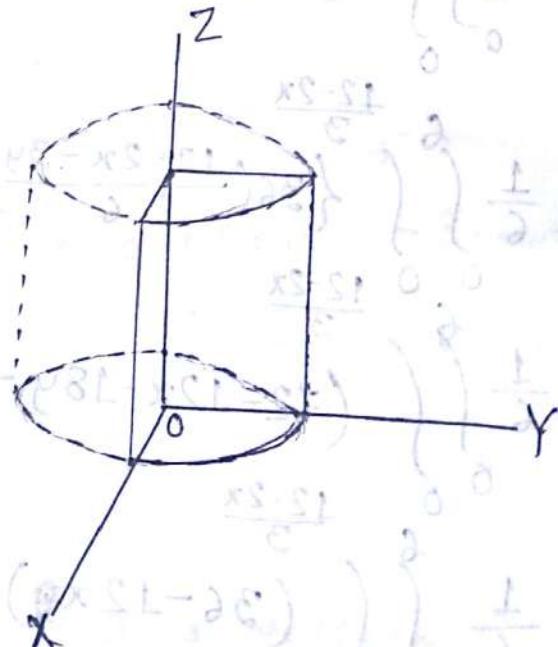
$$\begin{aligned}
 &= \frac{1}{6} \int_0^6 [36y - 12xy]_0^{\frac{12-2x}{3}} dx \\
 &= \frac{1}{6} \int_0^6 (144 - 24x - 48x + 8x^2) dx \\
 &\quad \text{as, terms tends to zero as } x \rightarrow 6 \\
 &= \frac{1}{6} \int_0^6 (144 - 72x + 8x^2) dx \\
 &= \frac{1}{6} \left[144x - 36x^2 + \frac{8x^3}{3} \right]_0^6 \\
 &= \frac{1}{6} [6(144 - 216 + 96)] \\
 &= 24
 \end{aligned}$$

Ex: 20 Evaluate: $\iint_S \vec{A} \cdot \hat{n} ds$ where $\vec{A} = 2\hat{i} + x\hat{j} - 3y^2\hat{k}$
 and S is the surface of the cylinder
 $x^2 + y^2 = 16$ include first octant between $z=0$ and $z=5$.

Solution:

$$\begin{aligned}
 \text{Let, } \phi &= x^2 + y^2 - 16 \\
 \nabla \phi &= \frac{\partial x^2}{\partial x} \hat{i} + \frac{\partial y^2}{\partial y} \hat{j} \\
 &= 2x\hat{i} + 2y\hat{j}
 \end{aligned}$$

$$\begin{aligned}
 |\nabla \phi| &= \sqrt{4x^2 + 4y^2} \\
 &= 2\sqrt{x^2 + y^2} \\
 &= 2\sqrt{16} = 8
 \end{aligned}$$



$$\hat{n} = \frac{\nabla \phi}{|\nabla \phi|} = \frac{2x\hat{i} + 2y\hat{j}}{8} = \frac{x\hat{i} + y\hat{j}}{4}$$

As surface, project on x_2 , not xy plane,

$$ds = \frac{dx dy}{|\hat{n} \cdot \hat{j}|}$$

In the x_2 -plane
surface equation

$$\therefore \hat{n} \cdot \hat{j} = \frac{y}{4}$$

$$x^2 = 16$$

at common origin set to $x=4$ it will be
int $\int \int \vec{A} \cdot \hat{n} ds$ consider parametrization of

$$= \int_{x=0}^4 \int_{z=0}^{16-x^2} (2\hat{i} + x\hat{j} - 3y^2\hat{k}) \frac{1}{4} (x\hat{i} + y\hat{j}) \frac{4}{y} dx dy$$

$$= \int_0^4 \int_0^{16-x^2} \left(\frac{x_2 + xy}{y} \right) dx dy$$

$$= \int_0^4 \int_0^{16-x^2} \left(\frac{x_2}{y} + x \right) dx dy$$

$$= \int_0^4 \int_0^{16-x^2} \left(\frac{x_2}{\sqrt{16-x^2}} + x \right) dx dy \quad \left| \begin{array}{l} x^2 + y^2 = 16 \\ y = \sqrt{16-x^2} \end{array} \right.$$

$$= \int_0^4 \left[\frac{x_2}{2} + \frac{x^2}{2} \right]_0^{16-x^2} dx$$

$$= \int_0^4 (42 + 8) dx = \left[22x \right]_0^4 = [22^2 + 8^2] = 50$$

$$= 2 \times 5^2 + 8 \times 5 = 90$$

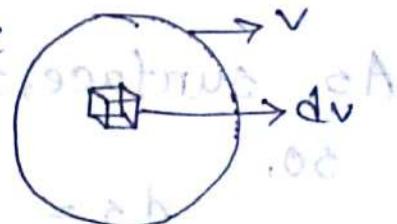
21-03-2018: 7A: Wednesday

→ Volume integral:

Consider a closed surface in space enclosing a volume V .

Then,

$$\iiint dV = \iiint dx dy dz$$



Ex 27

→ Find the volume of the region common to two intersecting cylinders $x^2 + y^2 = a^2$ and $x^2 + z^2 = a^2$.

Solution:

$$\iiint dV = \iiint dx dy dz$$

$$x^2 + y^2 = a^2$$

$$\Rightarrow x^2 = a^2 - y^2$$

$$\Rightarrow x^2 = a^2 [y=0]$$

$$\Rightarrow x = \pm a$$

$$x = [0, a]$$

$$x^2 + y^2 = a^2$$

$$\Rightarrow y^2 = a^2 - x^2$$

$$\Rightarrow y = \pm \sqrt{a^2 - x^2}$$

$$\therefore y = [0, \sqrt{a^2 - x^2}]$$

$$x^2 + z^2 = a^2$$

$$z^2 = a^2 - x^2$$

$$z = \pm \sqrt{a^2 - x^2}$$

In x, y, z the limit of x, y, z is $[0, \sqrt{a^2 - x^2}]$
only positive value is taken because hence, the
volume of the first quadrant is being

determined.

$$\iiint_{x=0, y=0, z=0}^a \int_{\sqrt{a^2-x^2}}^{\sqrt{a^2-x^2}} dx dy dz$$

$$= \int_{x=0, y=0}^a \int_{y=0}^{\sqrt{a^2-x^2}} [2]_0^{\sqrt{a^2-x^2}} dy dx$$

$$= \int_{x=0, y=0}^a \int_{y=0}^{\sqrt{a^2-x^2}} \sqrt{a^2-x^2} dy dx$$

$$= \int_{x=0}^a \sqrt{a^2-x^2} [y]_0^{\sqrt{a^2-x^2}} dx$$

$$= \int_0^a (a^2-x^2) dx$$

$$= \left[a^2x - \frac{x^3}{3} \right]_0^a$$

$$= a^3 - \frac{a^3}{3}$$
$$= \frac{2a^3}{3}$$

∴ As every quadrant has two sides, upper and lower, so the value of the quadrant need to be multiplied by 8 to get the full volume.

$$\therefore \text{Volume} = 8 \times \frac{2a^3}{3}$$
$$= \frac{16a^3}{3}$$

$$= \left[i(x^2 - \frac{x^3}{3}) + i(x^2 - \frac{x^3}{3}) + i(x^2 - \frac{x^3}{3}) \right]$$

Ex: 26

Let, $\vec{F} = 2xz\hat{i} - x\hat{j} + y^2\hat{k}$. Evaluate $\iiint \vec{F} dV$ where V is the region bounded by the surfaces $x=0, y=0, y=6, z=x^2, z=4$.

Solution:

$$z = x^2$$

$$\Rightarrow x^2 = 4$$

$$\therefore x = 2$$

$$\therefore \iiint \vec{F} dV$$

$$= \iiint_{x=0, y=0, z=x^2}^{x=2, y=6, z=4} (2xz\hat{i} - x\hat{j} + y^2\hat{k}) dx dy dz$$

cont. from above (Ans)

at base, $x=0, y=0, z=0$

$$= \int_{x=0}^2 \int_{y=0}^6 \left[x^2\hat{i} - x\hat{j} + y^2\hat{k} \right]_{x^2}^4 dy dx$$

$$= \int_{x=0}^2 \int_{y=0}^6 \left[(16x\hat{i} - 4x\hat{j} + 4y^2\hat{k} - x^5\hat{i} + x^3\hat{j} + x^2y^2\hat{k}) \right] dy dx$$

$$= \int_{x=0}^2 \int_{y=0}^6 \left[(16x - x^5)\hat{i} + (x^3 - 4x)\hat{j} + (4y^2 - x^2y^2)\hat{k} \right] dy dx$$

$$\begin{aligned}
 &= \int_{x=0}^2 \left[(16x - x^5) \hat{i} + (x^3 - 4x) \hat{j} + \left(\frac{4x^3}{3} - \frac{x^2 y^3}{3} \right) \hat{k} \right]_0^6 dx \\
 &= \int_0^2 \left[(96x - 6x^5) \hat{i} + (6x^3 - 24x) \hat{j} + (288 - 72x^2) \hat{k} \right] dx \\
 &= \left[(48x^2 - x^6) \hat{i} + \left(\frac{3x^4}{2} - 12x^2 \right) \hat{j} + (288x - 24x^3) \hat{k} \right]_0^2 \\
 &= (192 - 64) \hat{i} + (24 - 48) \hat{j} + (576 - 192) \hat{k} \\
 &= 128 \hat{i} - 24 \hat{j} + 384 \hat{k}
 \end{aligned}$$

Ex: 70 If $\vec{F} = (2x^2 - 32) \hat{i} - 2xy \hat{j} - 4x \hat{k}$, evaluate $\iiint \nabla \cdot \vec{F} \cdot dV$
 where V is the closed region bounded by the
 planes $x=0$, $y=0$, $z=0$ and $2x+2y+z=4$.

Solution:

$$2x+2y+z=4$$

$$\therefore z = 4 - 2x - 2y$$

If, $z=0$, the equation of the plane,

$$2x+2y=4$$

$$\Rightarrow y = 2 - x$$

If, $y=2=0$, the equation of the plane,

$$2x=4$$

$$\therefore x=2$$

$$\therefore \iiint \vec{\nabla} \cdot \vec{F} \cdot d\vec{v}$$

$$= \iiint_{x=0, y=0, z=0}^{x=2, y=2-x, z=4-2x-2y} \left[\frac{\partial u}{\partial x} (2x^2 - 3z) - \frac{\partial u}{\partial y} (2xy) - \frac{\partial u}{\partial z} (4x) \right] dx dy dz$$

$$= \iiint_{x=0, y=0, z=0}^{x=2, y=2-x, z=4-2x-2y} i(4x - 2x^2) dz dy dx = i(P_2 - S_2) =$$

$$= \int_{x=0}^2 \int_{y=0}^{2-x} \left[2x^2 \right]_{0}^{4-2x-2y} dy dx$$

$$= \int_{x=0}^2 (8x - 4x^2 - 4xy) dy dx$$

$$= \int_{x=0}^2 \left[8xy - 4x^2y - 2xy^2 \right]_0^{2-x} dx$$

$$= \int_0^2 (16x - 16x^2 - 8x^3 + 4x^4 - 8x + 8x^2 - 2x^3) dx$$

$$= \int_0^2 (2x^3 - 8x^2 + 8x) dx = \left[\frac{x^4}{2} - \frac{8x^3}{3} + 4x^2 \right]_0^2 = 8 - \frac{64}{3} + 16 = \frac{8}{3}$$

02-04-2018: 8C: Monday

Ex: 32

The acceleration \vec{a} of a particle at any time $t \geq 0$ is given by $\vec{a} = e^{-t}\hat{i} - 6(t+1)\hat{j} + 3\sin t \hat{k}$ if the velocity \vec{v} and displacement \vec{r} are zero at $t=0$, find \vec{v} and \vec{r} at any time.

Solution:

$$\vec{a} = e^{-t}\hat{i} - 6(t+1)\hat{j} + 3\sin t \hat{k}$$

By integrating,

$$\int \vec{a} dt = \int e^{-t}\hat{i} dt - \int 6(t+1)\hat{j} dt + \int 3\sin t \hat{k} dt$$

$$\Rightarrow \vec{v} = -e^{-t}\hat{i} - (3t^2 + 6t)\hat{j} - 3\cos t \hat{k} + C_1$$

$$\Rightarrow 0 = -\hat{i} - 3\hat{k} + C_1$$

$$\therefore C_1 = \hat{i} + 3\hat{k}$$

$$\therefore \vec{v} = -e^{-t}\hat{i} - (3t^2 + 6t)\hat{j} - 3\cos t \hat{k} + \hat{i} + 3\hat{k}$$

$$\Rightarrow \vec{v} = (1 - e^{-t})\hat{i} - (3t^2 + 6t)\hat{j} + (3 - 3\cos t)\hat{k}$$

By integrating,

$$\int \vec{v} dt = \int (1 - e^{-t})\hat{i} dt - \int (3t^2 + 6t)\hat{j} dt + \int (3 - 3\cos t)\hat{k} dt$$

$$\Rightarrow \vec{r} = (t + e^{-t})\hat{i} - (t^3 + 3t^2)\hat{j} + (3t - 3\sin t)\hat{k} + C_2$$

$$\Rightarrow 0 = \hat{i} + C_2 \therefore C_2 = -\hat{i}$$

$$\therefore \vec{r} = (t + e^{-t})\hat{i} - (t^3 + 3t^2)\hat{j} + (3t - 3\sin t)\hat{k}$$

$$= (t-1+e^{-t})\hat{i} - (t^3 + 3t^2)\hat{j} + (3t - 3\sin t)\hat{k}$$

Ex: 34

Evaluate: $\int_2^3 \vec{A} \cdot \frac{d\vec{A}}{dt} dt$ if $\vec{A}(2) = 2\hat{i} - \hat{j} + 2\hat{k}$

$$\text{and } \vec{A}(3) = 4\hat{i} - 2\hat{j} + 3\hat{k}.$$

Solution:

$$\begin{aligned} \frac{d}{dt}(\vec{A} \cdot \vec{A}) &= \vec{A} \cdot \frac{d\vec{A}}{dt} + \frac{d\vec{A}}{dt} \cdot \vec{A} \\ \Rightarrow \frac{d}{dt}(\vec{A} \cdot \vec{A}) &= 2\vec{A} \cdot \frac{d\vec{A}}{dt} \\ \therefore \vec{A} \cdot \frac{d\vec{A}}{dt} &= \frac{1}{2} \frac{d}{dt}(\vec{A} \cdot \vec{A}) \end{aligned}$$

$$\begin{aligned} \therefore \int_2^3 \vec{A} \cdot \frac{d\vec{A}}{dt} dt &= \int_2^3 \frac{1}{2} \frac{d}{dt}(\vec{A} \cdot \vec{A}) dt \quad [\text{By integrating}] \\ &= \frac{1}{2} \int_2^3 d(\vec{A} \cdot \vec{A}) \end{aligned}$$

$$\begin{aligned} &= \frac{1}{2} [\vec{A} \cdot \vec{A}]_2^3 \\ &= \frac{1}{2} [\{\vec{A}(3) \cdot \vec{A}(3)\} - \{\vec{A}(2) \cdot \vec{A}(2)\}] \\ &= \frac{1}{2} [(16+4+9) - (4+1+2)] \\ &= \frac{1}{2} [29-9] = 10 \end{aligned}$$

Eri 37 If $\vec{A} = (2y+3)\hat{i} + xz\hat{j} + (yz-x)\hat{k}$, evaluate $\int \vec{A} \cdot d\vec{r}$ along the following paths C :

- $x = 2t^2, y = t, z = t^3$ from $t=0$ to $t=1$.
- the straight line from $(0,0,0)$ to $(0,0,1)$ then to $(0,1,1)$ and then to $(2,1,1)$
- the straight line joining $(0,0,0)$ and $(2,1,1)$.

Solution:

$$a) d\vec{r} = dx\hat{i} + dy\hat{j} + dz\hat{k}$$

$$\begin{aligned} & \int_C \vec{A} \cdot d\vec{r} \\ &= \int_C [(2y+3)dx + xzdy + (yz-x)dz] \\ &= \int_0^1 [(2t+3)4t dt + (2t^5)dt + (t^4 - 2t^2)3t^2 dt] \\ &= \int_0^1 (8t^2 + 12t + 2t^5 + 3t^6 - 6t^4) dt \\ &= \left[\frac{8t^3}{3} + 6t^2 + \frac{2t^6}{3} + \frac{3t^7}{7} - \frac{6t^5}{5} \right]_0^1 \\ &= \frac{8}{3} + 6 + \frac{1}{3} + \frac{3}{7} - \frac{6}{5} \\ &= \frac{280 + 630 + 35 + 45 - 126}{105} = \frac{864}{105} = \frac{288}{35} \end{aligned}$$

b) A) starts from $(0,0,0)$ to $(0,0,1)$
 $x=0, y=0, dx=0, dy=0$ only z varies from 0 to 1

$$\int_C \vec{A} \cdot d\vec{r} = \int_{(0,0,0)}^{(0,0,1)} [(2y+3)dx + (xz)dy + (yz-x)dz]$$

$$= \int_0^1 dy [0 + 0 + 0] = 0$$

$$= 0$$

The straight line from $(0,0,1)$ to $(0,0,1)$
 $x=0, z=1, dx=0, dz=0$ only y varies from 0 to 1

$$\int_C \vec{A} \cdot d\vec{r} = \int_{(0,0,1)}^{(0,1,1)} [(2y+3)dx + (xz)dy + (yz-x)dz]$$

$$= \int_0^1 dy \left[0 + \frac{x}{y} + \frac{z}{y} + 1 + \frac{1}{y} \right]$$

$$= 0$$

$$= \frac{88S - 1428}{60E} = \frac{28L - 6P + 6S + 1082 + 08S}{60L}$$

The straight line from $(0, 1, 1)$ to $(2, 1, 1)$
 $y=1, z=1, dy=0, dz=0$ only x varies from 0 to 2

$$\int_C \vec{A} \cdot d\vec{r} = \int_{(0,1,1)}^{(2,1,1)} [(2y+3)dx + (xz)dy + (yz-x)dz]$$

$$= \int_0^2 (2+3)dx \quad [\because y=1 \& dy=dz=0] \quad \text{86:77}$$

$$= [5x]_0^2$$

~~so solve~~ \therefore ~~int~~ is a bms ~~is test~~ \therefore $x=10$
~~brackets~~ $= 10$
 \therefore Adding the straight lines $= 0 + 0 + 10 = 10$

c) The straight line joining $(0, 0, 0)$ and $(2, 1, 1)$
 is given in parametric form by $x=2t$,
 $y=t$, $z=t$. Then,

$$\int_C \vec{A} \cdot d\vec{r} = \int_{(0,0,0)}^{(2,1,1)} [(2y+3)dx + (xz)dy + (yz-x)dz]$$

$$= \int_0^1 [(2t+3)2dt + (2t^2)dt + (t^2 - 2t)dt]$$

$$= \int_0^1 (4t+6+2t^2+t^2-2t)dt$$

$$\begin{aligned}
 &= \int_0^1 \left(3t^2 + 2t + 6 \right) dt \\
 &= \left[t^3 + \frac{2}{3}t^2 + 6t \right]_0^1 = 5b \cdot \cancel{\pi} \\
 &= 1 + 1 + 6 = 8
 \end{aligned}$$

Ex: 58 Evaluate: $\iint_S \vec{A} \cdot \hat{n} ds$ for each of the following cases.

a) $\vec{A} = 2y\hat{i} + 2x\hat{j} - 2\hat{k}$ and S is the surface of the plane $2xy = 6$ in the first octant cut off by the plane $z = 4$.

b) $\vec{A} = (x+y^2)\hat{i} - 2x\hat{j} + 2y\hat{k}$ and S is the surface of the plane $2x+y+2z = 6$ in the first octant.

Solution:

a) Let, $\phi = 2x+y-6$

$$\nabla \phi = \frac{\partial \phi}{\partial x}(2x)\hat{i} + \frac{\partial \phi}{\partial y}(y)\hat{j}$$

$$|\nabla \phi| = \sqrt{4+1} = \sqrt{5}$$

$$\therefore \hat{n} = \frac{\vec{\nabla} \phi}{|\vec{\nabla} \phi|} = \frac{1}{\sqrt{5}} (2\hat{i} + \hat{j})$$

As the surface is on the plane in the first octant and cut off by the plane $z=4$, so the surface is on the xz plane.

$$ds = \frac{dx dz}{|\hat{n} \cdot \hat{j}|}$$

$$\hat{n} \cdot \hat{j} = \frac{1}{\sqrt{5}}$$

In the xz plane, the surface equation is,

$$2x = 6$$

$$\therefore x = 3$$

$$\therefore \iiint_S \vec{A} \cdot \hat{n} \cdot ds$$

$$= \iint_{x=0}^3 \int_{z=0}^4 (y\hat{i} + 2x\hat{j} - 2\hat{k}) \frac{1}{\sqrt{5}} (2\hat{i} + \hat{j}) \frac{dx dz}{\frac{1}{\sqrt{5}}}$$

$$= \int_{x=0}^3 \int_{z=0}^4 (2y + 2x) dx dz$$

$$= \int_{x=0}^3 \left[2(6-2x)^2 + 2x^2 \right]_0^4 dx \quad [\because 2x+y=6 \Rightarrow y=6-2x]$$

$$= \int_0^3 [12x^2 - 2x^2]_0^4 dx = \int_0^3 (48 - 8x) dx$$

$$= [48x - 4x^2]_0^3 \quad (\hat{i} + \hat{j} + \hat{k}) \cdot \frac{\nabla \phi}{|\nabla \phi|} = \frac{\nabla \phi}{|\nabla \phi|} = \hat{n}$$

terit $144 - 36 = 108$ no ei seotne ent ea
ent $\phi = 2x + y + 2z - 6$ seotne ent yd Ho two bno tnotoo

b) seotne ent no ei seotne ent
the ent $\phi = 2x + y + 2z - 6$ seotne ent

$$\vec{\nabla} \phi = \frac{\partial \phi}{\partial x} \hat{i} + \frac{\partial \phi}{\partial y} \hat{j} + \frac{\partial \phi}{\partial z} \hat{k} \\ = 2\hat{i} + \hat{j} + 2\hat{k}$$

$$|\vec{\nabla} \phi| = \sqrt{4+1+4} = \sqrt{9} = 3$$

$$\therefore \hat{n} = \frac{\vec{\nabla} \phi}{|\vec{\nabla} \phi|} = \frac{1}{3}(2\hat{i} + \hat{j} + 2\hat{k})$$

As the surface is in the first octant
of xyz plane, so it is in xy plane.

$$ds = \frac{dx dy}{|\hat{n} \cdot \hat{k}|} \quad 2x + y + 2z = 6 \\ \therefore z = \frac{6 - 2x - y}{2}$$

$$[\hat{n} \cdot \hat{k} = \frac{2}{3}] \quad ds = \frac{dx dy}{\frac{2}{3}} = \frac{3}{2} dx dy$$

In the xy plane the surface equation

$$2x + y = 6 \quad \text{when } y = 0$$

$$\Rightarrow y = 6 - 2x \quad 2x = 6$$

$$\therefore x = 3$$

$$\iint_S \vec{A} \cdot \hat{n} \, dS$$

$$= \iint_{\substack{x \geq 0 \\ y \geq 0}}^{3} \left[(x+y^2) \hat{i} - (2x) \hat{j} + (2yz) \hat{k} \right] \frac{1}{3} (2\hat{i} + \hat{j} + 2\hat{k}) \frac{dx dy}{\frac{2}{3}}$$

$$= \frac{1}{2} \iint_{\substack{x \geq 0 \\ y \geq 0}}^{3} (2x+2y^2-2x+4yz) \, dx dy$$

$$= \int_{x=0}^3 \int_{y=0}^{6-2x} \left\{ 6y^2 + 2y \left(\frac{6-y-2x}{2} \right) \right\} dy \, dx$$

$$= \int_{x=0}^3 \int_{y=0}^{6-2x} (y^2 + 6y - y^2 - 2xy) dy \, dx$$

$$= \int_{x=0}^3 \int_{y=0}^{6-2x} (6y - 2xy) dy \, dx$$

$$= \int_{x=0}^3 \left[3y^2 - xy^2 \right]_0^{6-2x} dx$$

$$= \int_{x=0}^3 (3[(3-x)(6-2x)^2]) dx$$

$$\begin{aligned}
 &= \int_0^3 [(3-x)(36-24x+4x^2)] dx \\
 &= \int_0^3 (108 - 72x + 12x^2 - 36x + 24x^2 - 4x^3) dx \\
 &= \int_0^3 (108 - 108x + 36x^2) dx \\
 &= [108x - 54x^2 + 12x^3] \Big|_0^3 \\
 &= 324 - 486 + 324 - 81 \\
 &= 81.
 \end{aligned}$$

Ex 6-38: If $\vec{F} = (5xy - 6x^2)\hat{i} + (2y - 4x)\hat{j}$, evaluate $\int \vec{F} \cdot d\vec{r}$ along the curve C in the xy plane, $y = x^3$ from the point $(1,1)$ to $(2,8)$.

Solution:

As the curve is in xy plane,

$$d\vec{r} = dx\hat{i} + dy\hat{j}$$

$$y = x^3$$

$$\Rightarrow dy = 3x^2 dx$$

$$\int_C \vec{F} \cdot d\vec{r} \text{ at } (0,0) \text{ most serial type point but } \\ \text{at } 0 \text{ most serializing value ok } b, 0 = 0 \\ = \int_{(1,1)}^{(2,8)} [(5xy - 6x^2) dx + (2y - 4x) dy]$$

$$= \int_1^2 (5x^4 - 6x^2) dx + \int_1^8 (2y - 4\sqrt[3]{y}) dy \left[(2x^3 - 4x) 3x^2 dx \right]$$

$$= [x^5 - 2x^3]_1^2 + \int_1^2 (6x^5 - 12x^3) dx$$

$$= (32 - 16 - 1 + 2) + [x^6 - 3x^4]_1^2$$

$$= 17 + 64 - 48 - 1 + 3$$

$$= 35$$

Ex :- 39: If $\vec{F} = (2x+y)\hat{i} + (3y-x)\hat{j}$, evaluate $\int_C \vec{F} \cdot d\vec{r}$
 where C is the curve in the xy plane consisting
 of the straight lines from $(0,0)$ to $(2,0)$ and
 then to $(3,2)$.

Solution: As the curve is in xy plane,

$$d\vec{r} = dx\hat{i} + dy\hat{j} (t - t) + tb(t\hat{i} + t\hat{j}) =$$

The straight line from $(0,0)$ to $(2,0)$
 $y=0, dy=0$ only x varies from 0 to 2

$$\int_C \vec{F} \cdot d\vec{r} = \int_0^2 [x^2(2x-y) + xy(x-y)] dx$$

$$= \int_0^2 [(2x^3 - x^2y) + xy(x-y)] dx$$

$$= \int_0^2 (3y - 0) dy \quad [\because dx=0] = \int_0^2 (2x - 0) dx \quad [\because dy=0]$$

$$= \left[\frac{3y^2}{2} \right]_0^2 = \left[\frac{x^2}{2} \right]_0^2 + 4(8-2L-SC)$$

~~26~~

~~C + (2,0) P - (3,2)~~

The straight line from ~~(0,2)~~ to ~~(2,3)~~ is given in parametric form by $x=2t$, $y=2t+2$. Then,

$$\int_C \vec{F} \cdot d\vec{r} = \int_0^1 [(2x+y)dx + (3y-x)dy]$$

$$= \int_{(2,0)}^{(3,2)} [(2x+y)dx + (3y-x)dy]$$

$$= \int_0^1 [(2t+2t+2)dt + (6t-t)(2dt)]$$

$$= \int_0^1 (4t + 10t) dt$$

initial value at (0,0)

$$= \left[\frac{14t^2}{2} \right]_0^1$$

not differentiated in resp. eq.

$$= 7$$

now want to set t=1, b=0

Add the straight line $= 4t + 7 = 11$

~~40~~: Find the work done in moving a particle in the force field $\vec{F} = 3x^2\hat{i} + (2x - y)\hat{j} + 2\hat{k}$ along

- the straight line from $(0,0,0)$ to $(2,1,3)$
- the space curve $x = 2t^2, y = t, z = 4t^2 - 1$ from $t=0$ to $t=1$
- the curve defined by $x^2 = 4y, 3x^3 = 8z$ from $x=0$ to $x=2$.

Solutions

a) The straight line from $(0,0,0)$ to $(2,1,3)$ is given in parametric form by $x=2t, y=t, z=3t$. Then, work [done]

$$\int_C \vec{F} \cdot d\vec{r} = \int_{(0,0,0)}^{(2,1,3)} [(3x^2)dx + (2xz - y)dy + (z)dz]$$

$$= \int_0^1 [(42t^2)dt + (12t^2 - t)dt + (3t)3dt]$$

$$= \int_0^1 (24t^2 + 12t^2 - t + 9t)dt$$

$$= \int_0^1 (36t^2 + 8t)dt$$

$$= [12t^3 + 4t^2]_0^1$$

$$= 12 + 4 = 16$$

b)

$$\begin{aligned}
 x &= 2t^2 & y &= t & z &= 4t^2 - 1 \\
 \Rightarrow dx &= 4t dt & \Rightarrow dy = dt & \Rightarrow dz = (8t-1) dt
 \end{aligned}$$

Work done = $\int_C \vec{F} \cdot d\vec{r}$

$$\begin{aligned}
 &= \int_C [(3x^2) dx + (2xz - y) dy + (z) dz] \\
 &= \int_0^1 [(12t^4) 4t dt + (16t^4 - 4t^3 - t) dt + (4t^2 - t) \cdot (8t-1) dt] \\
 &= \int_0^1 (48t^5 + 16t^4 - 4t^3 - t + 32t^3 - 8t^2 - 4t^2 + t) dt \\
 &= \int_0^1 (48t^5 + 16t^4 + 28t^3 - 12t^2) dt \\
 &= \left[8t^6 + \frac{16t^5}{5} + 7t^4 - \frac{4t^3}{3} \right]_0^1 \\
 &= 8 + \frac{16}{5} + 7 - 4 \\
 &= \frac{40 + 16 + 35 - 20}{5} \\
 &= \frac{71}{5} = 14.2
 \end{aligned}$$

c)

$$x^2 = 4y$$

$$3x^3 = 8z$$

$$\Rightarrow y = \frac{x^2}{4}$$

$$z = \frac{3x^3}{8}$$

$$\therefore y = 1$$

$$\therefore z = 3$$

$$\Rightarrow 2x dx = 4 dy$$

$$\Rightarrow 9x^2 dx = 8 dz$$

$$\therefore dy = \frac{x dx}{2}$$

$$\Rightarrow dz = \frac{9x^2 dx}{8}$$

work done

$$= \int_C \vec{F} \cdot d\vec{r}$$

$$= \int_C [(3x^2) dx + (2xz - y) dy + (z) dz]$$

$$= \int_0^2 [(3x^2) dx + \left(\frac{3x^4}{4} - \frac{x^2}{4}\right) \frac{x dx}{2} + \left(\frac{3x^3}{8}\right) \frac{9x^2 dx}{8}]$$

$$= \int_0^2 \left(3x^2 + \frac{3x^5 - x^3}{8} + \frac{27x^5}{64}\right) dx$$

$$= \left[x^3 + \frac{12x^6 - x^4}{32} + \frac{9x^6}{128}\right]_0^2$$

$$= \left[8 + \frac{128 - 16}{32} + \frac{144}{128}\right]$$

$$= 8 + \frac{7}{2} + \frac{9}{16} = \frac{16 + 56 + 9}{16} = \frac{71}{16} = 16$$

42) [Ex :- 41] Evaluate $\int \vec{F} \cdot d\vec{r}$ where $\vec{F} = (x-3y)$
 $+ (y-2z)\hat{j}$ and C is the closed curve in
 the xy plane, $x = 2\cos t$, $y = 3\sin t$ from
 $t=0$ to $t=2\pi$.

Solution:

$$x = 2\cos t \quad y = 3\sin t$$

$$\Rightarrow dx = -2\sin t dt \quad \Rightarrow dy = 3\cos t dt$$

$$\int \vec{F} \cdot d\vec{r}$$

$$= \int_C [(x-3y)dx + (y-2z)dy]$$

$$= \int_0^{2\pi} [(2\cos t - 9\sin t)(-2\sin t) + (3\sin t - 4\cos t)(3\cos t)] dt$$

$$= \int_0^{2\pi} (18\sin^2 t - 4\sin t \cos t + 9\sin t \cos t - 12\cos^2 t) dt$$

$$= \int_0^{2\pi} (18\sin^2 t + 5\sin t \cos t - 12\cos^2 t) dt$$

$$= \int_0^{2\pi} \left[\frac{5}{2}(2\sin t \cos t) - 12(\cos^2 t - \sin^2 t) + 6\sin^2 t \right] dt$$

$$\begin{aligned}
 &= \int_0^{2\pi} \left\{ \frac{5}{2} \sin 2t - 12 \cos 2t + 3 - (1 - \cos 2t) \right\} dt \\
 &= \int_0^{2\pi} \left\{ \frac{5}{2} \sin 2t - 12 \cos 2t + 3 \right\} dt \quad t \text{ of } 0 = b \\
 &= \left[-\frac{5}{4} \sin 2t - \frac{15}{2} \cos 2t + 3t \right]_0^{2\pi} \\
 &= \left[-\frac{5}{4} - 0 + 6\pi + \frac{5}{4} + 0 - 0 \right] \\
 &= 6\pi
 \end{aligned}$$

Ex 13: If $\vec{F} = (2x+y^2)\hat{i} + (3y-4x)\hat{j}$, evaluate $\oint \vec{F} \cdot d\vec{r}$ around the triangle C of the figure

a) in the indicated direction

b) opposite to the indicated direction

Solution:

a) The straight line from $(0,0)$ to $(2,0)$.
 $y=0, dy=0$, only x varies from 0 to 2.

$$\int (\vec{F} \cdot d\vec{r}) = \int [(2x+y^2)dx + (3y-4x)dy]$$

$$= \int_0^2 2x dx + 0 = [x^2]_0^2 = 4$$

The straight line from $(2,0)$ to $(2,1)$
 $x=2$, $dx=0$, only y varies from 0 to 1.

$$\int \vec{F} \cdot d\vec{r} = \int_{(2,0)}^{(2,1)} [(2x+y^2)dx + (3y-4x)dy]$$

$$= 0 + \int_0^1 (3y - 4 \times 2) dy$$

$$= \left[\frac{3y^2}{2} - 8y \right]_0^1$$

$$= \frac{3}{2} - 8 = -\frac{13}{2}$$

The straight line from $(2,1)$ to $(0,0)$ is given in parametric form by $x=2t$, $y=t$.

$$\begin{aligned} \int \vec{F} \cdot d\vec{r} &= \int_{(2,1)}^{(0,0)} [(2x+y^2)dx + (3y-4x)dy] \\ &= \int_1^0 [(8+4t+t^2)2dt + (3t-8t)dt] \\ &= \int_1^0 (2t^2 + 8t - 5t) dt \\ &= \int_{-1}^0 (2t^2 + 3t) dt = \left[\frac{2t^3}{3} + \frac{3t^2}{2} \right]_1^0 \\ &= \frac{-4-9}{6} = -\frac{13}{6} \end{aligned}$$

\therefore Adding the ~~triangular~~ lines of the ~~triangle~~ formed by the points $(0,0)$, $(0,2)$, $(2,0)$

$$= 4 - \frac{13}{2} - \frac{13}{6}$$

$$= \frac{24 - 39 - 13}{6} = -\frac{28}{6} = -\frac{14}{3}$$

b)

The straight line from $(0,0)$ to $(2,1)$ is given in parametric form by $x=2t$, $y=t$.

$$\int \vec{F} \cdot d\vec{r} = \int_{(0,0)}^{(2,1)} [(2xy^2) dx + (3y - 4x) dy]$$

moving along $\vec{c}(0,0)$ to $\vec{c}(2,1)$ the points will be plotted as

$$= \int [(4t+t^2) 2dt + (3t - 8t) dt]$$

$$= \int (8t+2t^2-5t) dt$$

$$= \int_0^1 (2t^2+3t) dt$$

$$= \left[\frac{2t^3}{3} + \frac{3t^2}{2} \right]_0^1$$

$$= \frac{2}{3} + \frac{3}{2} = \frac{4+9}{6} = \frac{13}{6}$$

The straight line from $(2,1)$ to $(2,0)$
 $x=2$, $dx=0$, only y varies from 1 to 0

$$\int \vec{F} \cdot d\vec{r} = \int_{(2,1)}^{(2,0)} [(2x+y^2)dx + (3y-4x)dy]$$

$$= 0 + \int_1^0 [3y - (4 \cdot 2)] dy$$

$$= \int_1^0 (3y - 8) dy = \left[\frac{3y^2}{2} - 8y \right]_1^0$$

$$= -\frac{3}{2} + 8 = \frac{13}{2}$$

The straight line from $(2,1)$ to $(0,0)$
 $y=0$, $dy=0$, only x varies from 2 to 0

$$\int \vec{F} \cdot d\vec{r} = \int_{(2,0)}^{(0,0)} [(2x+y^2)dx + (3y-4x)dy]$$

$$= \int_2^0 2x dx$$

$$= [x^2]_2^0 = 4$$

$$\text{Adding (the) offlines} = \frac{13}{6} + \frac{13}{2} - 4$$

$$= \frac{13+39-24}{6} = \frac{28}{6}$$

$$[\nu b(xA - yC) + xb(fu+xv)] = \frac{14}{6}$$

[Eng-58]: Evaluate $\iint \vec{A} \cdot \hat{n} dS$ for each of the following cases:

$$a) \vec{A} \left[\nu b \left(xA - yC \right) \right] = \nu b (8 - \nu C)$$

[Eng-59]: If $\vec{F} = 2y\hat{i} - 2\hat{j} + x^2\hat{k}$ and S

is the surface of the parabolic cylinder $y^2 = 8x$ in the first octant bounded by the planes $y=4$ and $z=6$, evaluate

$$\iint_S \vec{F} \cdot \hat{n} dS [\nu b(xA - yC) + xb(fu+xv)] = 56.5$$

Solution:

Let,

$$\begin{aligned} \phi &= y^2 - 8x \\ &= -8x + y^2 \end{aligned}$$

$$\vec{\nabla} \phi = \frac{\partial}{\partial x} (-8x)\hat{i} + \frac{\partial}{\partial y} (y^2)\hat{j} = -8\hat{i} + 2y\hat{j}$$

$$\therefore |\vec{\nabla} \phi| = \sqrt{64 + 4y^2}$$

$$\hat{n} = \frac{\vec{\nabla} \phi}{|\vec{\nabla} \phi|} = \frac{1}{\sqrt{64+4y^2}} (-8\hat{i} + 2y\hat{j})$$

As the surface project on yz plane, not xy ,

$$ds = \frac{dy dz}{|\hat{n} \cdot \hat{i}|}$$

$$\hat{n} \cdot \hat{i} = -\frac{8}{\sqrt{64+4y^2}}$$

$$\iint \vec{F} \cdot \hat{n} ds$$

$$= \iint_{\substack{y=0 \\ z=0}}^{4 \times 6} (2y\hat{i} - 2\hat{j} + \hat{k}) \frac{(-8\hat{i} + 2y\hat{j})}{\sqrt{64+4y^2}} \frac{dy dz}{8}$$

$$= \iint_{\substack{z=0 \\ y=0}}^{6 \times 4} \left(\frac{-16y - 2y^2}{-8} \right) dy dz$$

$$= \frac{1}{4} \iint_{\substack{z=0 \\ y=0}}^{6 \times 4} (8y + y^2) dy dz$$

$$= \frac{1}{4} \int_{z=0}^6 \left[4y^2 + \frac{y^3}{3} \right]_0^4 dz = \frac{1}{4} \int_0^6 (64 + 64z) dz$$

$$= \int_0^6 (16 + 16z) dz$$

$$\begin{aligned}
 \vec{F} \cdot \hat{n} &= \left[-16z + z^2 \right]_0^{6+2} = \frac{1}{2\pi} \left[-16z + z^2 \right]_0^{6+2} = \frac{1}{2\pi} \left[-16(6+2) + (6+2)^2 \right] = \\
 &= 96 + 36 = 132
 \end{aligned}$$

Ex :- 60: Evaluate $\iint_S \vec{A} \cdot \hat{n} dS$ over the entire surface S of the region bounded by the cylinder $x^2 + z^2 = 9$, $x=0$, $y=0$, $z=0$ and $y=8$, if $\vec{A} = 6z\hat{i} + (2xy)\hat{j} - x\hat{k}$

Solution: Let

$$\phi = x^2 + z^2 - 9$$

$$\begin{aligned}
 \vec{\nabla} \phi &= \frac{\partial}{\partial x} x^2 \hat{i} + \frac{\partial}{\partial z} z^2 \hat{k} \\
 &= 2x\hat{i} + 2z\hat{k}
 \end{aligned}$$

$$|\vec{\nabla} \phi| = \sqrt{4x^2 + 4z^2} = 2\sqrt{x^2 + z^2} = 2\sqrt{9} = 6$$

$$\hat{n} = \frac{\vec{\nabla} \phi}{|\vec{\nabla} \phi|} = \frac{2(x\hat{i} + z\hat{k})}{6} = \frac{x\hat{i} + z\hat{k}}{3}$$

As the surface projected on xy plane

$$dS = \frac{dx dy}{\hat{n} \cdot \hat{k}}$$

$$\hat{n} \cdot \hat{k} = \frac{2}{3} \quad \text{(now } z \text{ has a value)} \rightarrow \text{scalar product}$$

both axes also have to be converted with (0)

$\iint_S \vec{A} \cdot \hat{n} \, dS$ now correctly transformed and yet

S

$$= \iint_{x=0, y=0}^3 (6x_2 - x_2) \frac{dxdy}{2} \rightarrow \text{convert with (0)}$$

(0,0,0) to instead with

$$= \iint_{x=0, y=0}^3 5x \, dy \, dx$$

$$= \int_{x=0}^3 [5xy]_0^8 \, dx$$

$$= \int_0^3 40x \, dx$$

$$= \left[40 \frac{x^2}{2} \right]_0^3$$

$$= 20 \times 3^2$$

$$= 180$$

[Ex:-6]: Evaluate $\iint_S \vec{r} \cdot \hat{n} ds$ over:

- the surface S of the unit cube bounded by the coordinate planes and the planes $x=1, y=1, z=1$.
- the surface of a sphere of radius a with center at $(0,0,0)$

Solution:

a) Surface ~~AABCGr~~:

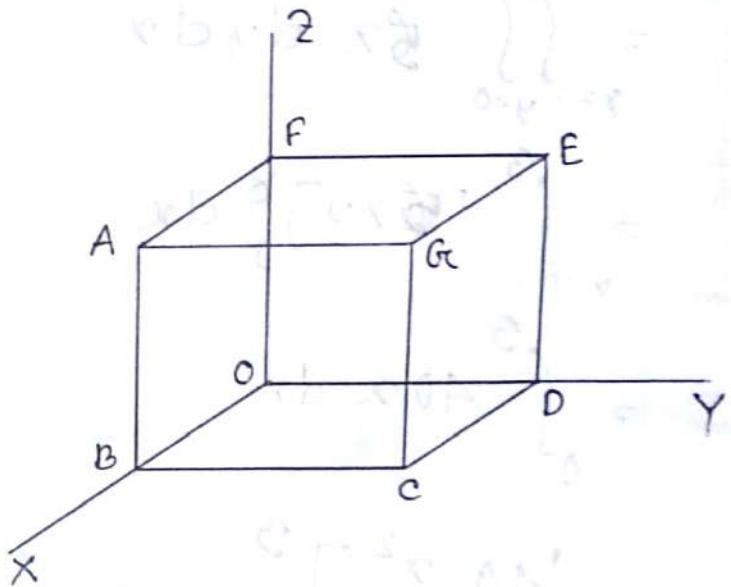
$$\hat{n} = \hat{i}, x=1,$$

$$\iint_S \vec{r} \cdot \hat{n} ds$$

$$= \iint_{y=0, z=0}^1 (x\hat{i} + y\hat{j} + z\hat{k}) \hat{i} dy dz$$

$$= \iint_0^1 x dy dz$$

$$= \iint_0^1 dy dz = \int_0^1 [y]_0^1 dz = \int_0^1 dz = [z]_0^1 = 1$$



Surface ODEF:

$$\hat{n} = -\hat{i}, x=0$$

$$\iint_S \vec{r} \cdot \hat{n} ds$$

$$= \iint_0^1 -x dy dz = 0$$

surface CDEG:

$$\hat{n} = \hat{j}, \quad y=1$$

$$\iint \vec{F} \cdot \hat{n} \, ds$$

$$= \iint_0^1 y \, dx \, dz$$

$$= \iint_0^1 1 \, dx \, dz = 1$$

surface ABOF:

$$\hat{n} = -\hat{j}, \quad y=0$$

$$\iint \vec{F} \cdot \hat{n} \, ds = \iint_0^1 -y \, dx \, dz = 0$$

surface AFEG:

$$\hat{n} = \hat{k}, \quad z=1$$

$$\iint \vec{F} \cdot \hat{n} \, ds = \iint_0^1 2 \, dx \, dy = \iint_0^1 1 \, dx \, dy = 1$$

surface ABCD:

$$\hat{n} = -\hat{k}, \quad z=0$$

$$\iint \vec{F} \cdot \hat{n} \, ds = \iint_0^1 -2 \, dx \, dy = 0$$

$$\begin{aligned} \text{Adding surface} &= 1 + 0 + 1 + 0 + 1 + 0 \\ &= 3 \end{aligned}$$

b) $\text{Find the volume of a cube whose surface area is } 150 \text{ cm}^2.$

$\text{Surface area of a cube} = 6a^2$

$$150 = 6a^2$$

$$a^2 = \frac{150}{6}$$

$$a^2 = 25$$

$$a = \sqrt{25} = 5$$

$$\text{Volume} = a^3 = 5^3 = 125 \text{ cm}^3$$

17. A rectangular block has a length of 12 cm, width of 8 cm and height of 5 cm. Find its volume.

$$\text{Volume} = l \times b \times h$$

$$= 12 \times 8 \times 5$$

$$= 480 \text{ cm}^3$$

18. A rectangular block has a length of 15 cm, width of 10 cm and height of 6 cm. Find its volume.

$$\text{Volume} = l \times b \times h$$

$$= 15 \times 10 \times 6$$

$$= 900 \text{ cm}^3$$

19. A rectangular block has a length of 10 cm, width of 5 cm and height of 4 cm. Find its volume.

$$\text{Volume} = l \times b \times h$$

$$= 10 \times 5 \times 4$$

$$= 200 \text{ cm}^3$$

20. Calculate the volume of a cuboid of dimensions 12 cm by 8 cm by 6 cm.

$$\text{Volume} = l \times b \times h$$

$$= 12 \times 8 \times 6$$

$$= 576 \text{ cm}^3$$

Erc :- 62: Evaluate $\iint \vec{A} \cdot \hat{n} dS$ over the entire surface of the region above the xy plane bounded by the cone $z^2 = x^2 + y^2$ and the plane $z = 4$, if

$$\vec{A} = 4xz\hat{i} + xyz^2\hat{j} + 3z\hat{k}.$$

Solution:

Ex :- 68 :- Evaluate $\iiint_V (2x+y) dv$, where V is the closed region bounded by the cylinder $z=4-x^2$ and the planes $x=0, y=0, y=2$ and $z=0$

Solution:

$$\iiint_V (2x+y) dv$$

$$= \iiint_{V} (2x+y) dx dy dz$$

$$= \int_0^2 \int_0^2 \left[2x^2 + y^2 \right]_0^{4-x^2} dx dy$$

$$= \int_0^2 \int_0^2 (8x - 2x^3 + 4y - yx^2) dy dx$$

$$= \int_0^2 \left[8xy - 2x^3y + 2y^2 - \frac{yx^2}{2} \right]_0^2 dx$$

$$= \int_0^2 (16x - 4x^3 + 8 - \frac{8x^2}{2}) dx$$

$$= \left[8x^2 - x^4 + 8x - \frac{8x^3}{3} \right]_0^2$$

$$= 32 - 16 + 16 - \frac{16}{3}$$

$$= \frac{80}{3}$$

Example 6 Chapter 5: Evaluate $\int \vec{A} \times \frac{d^2 \vec{A}}{dt^2} dt$

Em:-03: Evaluate $\int \vec{A} \times \frac{d^2 \vec{A}}{dt^2} dt$

Solution:

$$\frac{d}{dt} \left(\vec{A} \times \frac{d \vec{A}}{dt} \right)$$

$$= \vec{A} \times \frac{d^2 \vec{A}}{dt^2} + \frac{d \vec{A}}{dt} \times \frac{d \vec{A}}{dt}$$

$$= \vec{A} \times \frac{d^2 \vec{A}}{dt^2}$$

$$\therefore \int \vec{A} \times \frac{d^2 \vec{A}}{dt^2} dt$$

$$= \int \frac{d}{dt} \left(\vec{A} \times \frac{d \vec{A}}{dt} \right) dt$$

$$= \int d \left(\vec{A} \times \frac{d \vec{A}}{dt} \right)$$

$$= \vec{A} \times \frac{d \vec{A}}{dt} + C$$

Em:-09: Find the work done in moving a particle once around a circle C in the xy plane, if the circle has center at the origin and radius 3 and if the force field is given by

$$\vec{F} = (2x - y + z)\hat{i} + (x + y - z^2)\hat{j} + (3x - 2y + 4z)\hat{k}$$

Solution:

In the xy plane force field, \vec{F} and movement of the particle, $d\vec{r}$,

$$\vec{F} = (2x-y)\hat{i} + (x+y)\hat{j} + (3x-2y)\hat{k}$$

$$d\vec{r} = dx\hat{i} + dy\hat{j}$$

$$\therefore \text{work done} = \int \vec{F} \cdot d\vec{r}$$

$$= \int (2x-y)dx + (x+y)dy$$

The parametric equations of the circle as
 $x = 3\cos t$, $y = 3\sin t$ where t varies from 0 to 2π .

So the line integral,

$$\begin{aligned} & \int_0^{2\pi} (6\cos t - 3\sin t)(-3\sin t dt) + (3\cos t + 3\sin t)(3\cos t dt) \\ &= \int_0^{2\pi} (-18\sin^2 t + 9\sin^2 t + 9\cos^2 t + 9\sin t \cos t) dt \\ &= \int_0^{2\pi} (9 - 9\sin t \cos t) dt \\ &= \int_0^{2\pi} \left(9 - \frac{9}{2}\sin 2t\right) dt \\ &= \left[9t - \frac{9}{4}\cos 2t\right]_0^{2\pi} = 18\pi - 0 - \frac{9}{4} + \frac{9}{4} \\ &= 18\pi \end{aligned}$$

Ex:- 12:

- a) Show that $\vec{F} = (2xy + z^3)\hat{i} + x^2\hat{j} + 3xz^2\hat{k}$ is a conservative force field.
- b) Find the scalar potential.
- c) Find the work done in moving an object in this field from $(1, -2, 1)$ to $(3, 1, 4)$.

Solution:

a) If \vec{F} is a conservative force field,

$$\text{curl } \vec{F}, \vec{\nabla} \times \vec{F} = 0$$

$$L.H.S. = \vec{\nabla} \times \vec{F}$$

$$\begin{aligned} &= \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ 2xy + z^3 & x^2 & 3xz^2 \end{vmatrix} \\ &= (x^2 - 3z^2) + (3z^2 - 3z^2) + (2x - 2x) \end{aligned}$$

$$= \hat{i}(0-0) + \hat{j}(3z^2 - 3z^2) + \hat{k}(2x - 2x)$$

$$= 0$$

$$= R.H.S.$$

$\therefore L.H.S. = R.H.S.$ (Showed)

b) we know $(b^2 \sin x + x b^2 \cos x)^2 + (x b^2 x + x b^2 x \cos x)^2$

$$\vec{F} \cdot d\vec{r} = \vec{\nabla} \phi \cdot d\vec{r}$$

$$= \frac{\partial \phi}{\partial x} dx + \frac{\partial \phi}{\partial y} dy + \frac{\partial \phi}{\partial z} dz$$

$$= d\phi$$

∴

$$\therefore d\phi = \vec{F} \cdot d\vec{r}$$

$$= (2xy + z^3) dx + x^2 dy + 3xz^2 dz$$

$$= (2xy dx + x^2 dy) + (z^3 dx + 3xz^2 dz)$$

$$\therefore d\phi = d(x^2y) + d(xz^3)$$

By integrating,

$$\phi = x^2y + x^2z^3 + C$$

where, C is an integrating constant.

c) work done

$$\int_{(1,-2,1)}^{(3,1,4)} \vec{F} \cdot d\vec{r}$$

$$= \int [(2xy + z^3) dx]$$

$$= \int [(2xy + z^3) dx + x^2 dy + 3xz^2 dz]$$

$$(1,-2,1)$$

θ

$$\begin{aligned}
 & \int_{(1,-2,1)}^{(3,1,4)} [(2xy \, dx + x^2 \, dy) + (z^2 \, dx + 3xz^2 \, dz)] \\
 &= \int_{(1,-2,1)}^{(3,1,4)} [d(x^2y) + d(xz^3)] \\
 &= \left[x^2y + xz^3 \right]_{(1,-2,1)}^{(3,1,4)} \\
 &= 9 + 192 + 2 - 1 = 202
 \end{aligned}$$

Ex 6-14:

a) show that a necessary and sufficient condition that $F_1 \, dx + F_2 \, dy + F_3 \, dz$ be an exact differential is that $\vec{\nabla} \times \vec{F} = 0$ where $\vec{F} = F_1 \hat{i} + F_2 \hat{j} + F_3 \hat{k}$.

b) show that $(y^2 z^3 \cos x - 4x^3 z) \, dx + 2z^3 y \sin x \, dy + (3y^2 z^2 \sin x - x^4) \, dz$ is an exact differential of a function ϕ and find ϕ .

Solution: $(x^3y - xz\cos^2\theta)\hat{i} + (x\sin^2\theta y^2 - xz\sin^2\theta)\hat{j} -$

a) Let, $(x^3y - xz\cos^2\theta)\hat{i} + (x\sin^2\theta y^2 - xz\sin^2\theta)\hat{j} -$

$$f_1 dx + f_2 dy + f_3 dz$$

$$= d\phi = \frac{\partial \phi}{\partial x} dx + \frac{\partial \phi}{\partial y} dy + \frac{\partial \phi}{\partial z} dz, \text{ an exact differential.}$$

Since x, y and z are independent variables

$$f_1 = \frac{\partial \phi}{\partial x}, f_2 = \frac{\partial \phi}{\partial y}, f_3 = \frac{\partial \phi}{\partial z}$$

$$\therefore \vec{F} = \frac{\partial \phi}{\partial x} \hat{i} + \frac{\partial \phi}{\partial y} \hat{j} + \frac{\partial \phi}{\partial z} \hat{k} = \vec{\nabla} \phi$$

$$\therefore \vec{\nabla} \times \vec{F} = \vec{\nabla} \times \vec{\nabla} \phi = 0$$

$\therefore f_1 dx + f_2 dy + f_3 dz = d\phi$, an exact differential
 $\therefore f_1 dx + f_2 dy + f_3 dz = d\phi + (\text{showed})$

(b) If $\text{curl } \vec{F} = 0$, then \vec{F} is

Let, $\vec{F} = (y^2 z^3 \cos x - 4x^3 z) \hat{i} + 2z^3 y \sin x \hat{j} + (3y^2 z^2 \sin x - x^4) \hat{k}$

If $\text{curl } \vec{F} = 0$, then $\vec{F} \cdot d\vec{r}$ is an exact differential of a function ϕ

$$\vec{\nabla} \times \vec{F} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ (y^2 z^3 \cos x - 4x^3 z) & 2z^3 y \sin x & (3y^2 z^2 \sin x - x^4) \end{vmatrix}$$

$$= \hat{i}(6yz^2\sin x - 6yz^2\sin x) + \hat{j}(3y^2z^2\cos x - 4x^3 - 3y^2z^2\cos x + 4x^3) + \hat{k}(2z^3y\cos x - 2yz^3\cos x)$$

$$= 0$$

As, $\nabla \times \vec{F} = 0$

$$\vec{F} \cdot d\vec{r} = d\phi$$

$$\Rightarrow \vec{F} \cdot d\vec{r} = d\phi$$

$$\Rightarrow d\phi = (y^2z^3\cos x - 4x^3)dx + 2z^3y\sin x dy + (3y^2z^2\sin x - x^4)dz$$

$$\Rightarrow d\phi = (y^2z^3\cos x dx + 2z^3y\sin x dy + 3y^2z^2\sin x dz) + (-4x^3z dx + x^4z dz)$$

$$\Rightarrow d\phi = d(y^2z^3\sin x) - d(x^4z)$$

By integrating, from top to bottom tip

$$\phi = y^2z^3\sin x - x^4z + C$$

where, C is an integrating constant

Exm :- 16: If $\phi = 2xyz^2$, $\vec{F} = xy\hat{i} - 2\hat{j} + x^2\hat{k}$ and C is the curve $x=t^2$, $y=2t$, $z=t^3$ from $t=0$ to $t=1$ evaluate the line integrals $\textcircled{a} \int \phi d\vec{r}$, $\textcircled{b} \int \vec{F} \cdot d\vec{r}$

Solution:

$$\textcircled{a} \quad \phi = 2xyz^2 = 2t^2 \cdot 2t \cdot t^6 = 2t^9$$

$$\vec{r} = x\hat{i} + y\hat{j} + z\hat{k} = t^2\hat{i} + 2t\hat{j} + t^3\hat{k}$$

$$d\vec{r} = (2t\hat{i} + 2\hat{j} + 3t^2\hat{k}) dt$$

$$\int \phi \cdot d\vec{r} = \int (2t^9) (2t\hat{i} + 2\hat{j} + 3t^2\hat{k}) dt = \left(\frac{2t^{10}}{10} + \frac{2t^9}{9} + \frac{3t^7}{7} \right) \Big|_0^1$$

$$= \int_0^1 (8t^{10}\hat{i} + 8t^9\hat{j} + 12t^7\hat{k}) dt$$

$$= \left[\frac{8t^{11}}{11}\hat{i} + \frac{8t^{10}}{10}\hat{j} + \frac{12t^8}{8}\hat{k} \right]_0^1 = \frac{8}{11}\hat{i} + \frac{4}{5}\hat{j} + \frac{3}{2}\hat{k}$$

$$= \frac{8}{11}\hat{i} + \frac{4}{5}\hat{j} + \hat{k}$$

\textcircled{b}

$$\vec{F} = xy\hat{i} - 2\hat{j} + x^2\hat{k}$$

$$= 2t^3\hat{i} - 2\hat{j} + t^4\hat{k}$$

$$d\vec{r} = (2t\hat{i} + 2\hat{j} + 3t^2\hat{k}) dt$$

Ex-20: Evaluate $\int \vec{F} \cdot d\vec{r}$

$$\begin{aligned}
 &= \left(\begin{array}{|ccc|c}
 \hat{i} & \hat{j} & \hat{k} & \\
 \hline
 2t^3 & -t^3 & t^4 & dt \\
 2t & 2 & 3t^2 &
 \end{array} \right) \\
 &= \int_0^1 \left[\hat{i}(-3t^5 - 2t^4) + \hat{j}(2t^5 - 6t^5) + \hat{k}(4t^3 + 2t^4) \right] dt \\
 &= \int_0^1 \left[-\hat{i}(3t^5 + 2t^4) - 4t^5 \hat{j} + \hat{k}(4t^3 + 2t^4) \right] dt \\
 &= \left[-\hat{i}\left(\frac{t^6}{2} + \frac{2t^5}{5}\right) - \frac{2t^6}{3} \hat{j} + \hat{k}\left(t^4 + \frac{2t^5}{5}\right) \right]_0^1 \\
 &= -\hat{i}\left(\frac{1}{2} + \frac{2}{5}\right) - \frac{2}{3} \hat{j} + \left(1 + \frac{2}{5}\right) \hat{k} \\
 &= -\frac{9\hat{i}}{10} - \frac{2\hat{j}}{3} + \frac{7\hat{k}}{5}
 \end{aligned}$$

Ex-21: Evaluate $\iint_S \phi \, dS$ where $\phi = \frac{3}{8}xyz^2$ and S is the surface of the cylinder $x^2 + y^2 = 16$ included in the first octant between $z=0$ and $z=5$.

Solution:

Let,

$$\textcircled{1} \quad w = x^2 + y^2 = 16$$

$$\vec{w} = 2xi + 2yj$$

$$\hat{n} = \frac{\vec{\nabla} w}{|\vec{\nabla} w|} = \frac{2x\hat{i} + 2y\hat{j}}{\sqrt{4x^2 + 4y^2}} = \frac{x\hat{i} + y\hat{j}}{2}$$

As the surface project on xz plane,

$$ds^2 = \frac{dx dz}{|\hat{n} \cdot \hat{j}|}$$

$$\hat{n} \cdot \hat{j} = \frac{y}{4}$$

$$\iint \partial \phi \hat{n} ds$$

$$= \iint \frac{3}{8} xyz (xi +$$

$$= \iint_{x=0}^4 \iint_{z=0}^5 \frac{3}{8} xyz \left(\frac{xi + yj}{4} \right) \frac{dx dz}{\frac{y}{4}}$$

$$= \iint_0^4 \iint_0^5 \left(\frac{3x^2 z}{8} \hat{i} + \frac{3xyz}{8} \hat{j} \right) dx dz$$

$$= \frac{3}{8} \iint_0^4 \iint_0^5 \left[(x^2 z) \hat{i} + 0(x^2 \sqrt{16-x^2}) \hat{j} \right] dx dz$$

$$= \frac{3}{8} \int_0^4 \left[\left(\frac{x^2 z^2}{2} \right) \hat{i} + \left(\frac{x^2 z \sqrt{16-x^2}}{2} \right) \hat{j} \right] dz$$

$$= \frac{3}{8} \int_0^4 \left[\frac{25x^2}{2} \hat{i} + \frac{25x \sqrt{16-x^2}}{2} \hat{j} \right] dx$$

$$= \frac{3}{8} \left[\frac{25x^3}{6} \hat{i} + \frac{25x^3}{6} \right]_0^4$$

$$= \frac{3}{8} \left(\frac{800}{3} \hat{i} + \frac{800}{3} \hat{j} \right)$$

$$= 100\hat{i} + 100\hat{j}$$

Exm:-22: If $\vec{F} = y\hat{i} + (x-2xz)\hat{j} - xy\hat{k}$, evaluate $\iint (\nabla \times \vec{F}) \cdot \hat{n} dS$ where S is the surface of the sphere $x^2 + y^2 + z^2 = a^2$ above the xy plane.

Solution:

$$\nabla \times \vec{F} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ y & x-2xz & -xy \end{vmatrix}$$

$$\begin{aligned} &= \hat{i}(-x+2z) + \hat{j}(0+y) + \hat{k}(1-2z-1) \\ &= -x\hat{i} + y\hat{j} - 2z\hat{k} \end{aligned}$$

$$\text{Let, } \phi = x^2 + y^2 + z^2 - a^2$$

$$\therefore \nabla \phi = 2x\hat{i} + 2y\hat{j} + 2z\hat{k}$$

$$\hat{n} = \frac{\nabla \phi}{|\nabla \phi|} = \frac{2x\hat{i} + 2y\hat{j} + 2z\hat{k}}{\sqrt{4x^2 + 4y^2 + 4z^2}} = \frac{x\hat{i} + y\hat{j} + z\hat{k}}{a}$$

As the surface on the xy plane

$$dS = \frac{dx dy}{\hat{n} \cdot \hat{k}}$$

$$\hat{n} \cdot \vec{k} = \frac{2}{a}$$

$$\iint (\nabla \times \vec{F}) \cdot \hat{n} \, ds$$

$$= \iint_{x=-a}^a \frac{x^2 + y^2 - 2z^2}{2} \, dy \, dx$$

$$= \iint_{x=-a}^a \frac{3(x^2 + y^2) - 2a^2}{\sqrt{a^2 - x^2 - y^2}} \, dy \, dx \quad [x^2 + y^2 + z^2 = a^2]$$

To evaluate the double integral, transform to polar coordinates (ρ, ϕ) where $x = \rho \cos \phi$, $y = \rho \sin \phi$ and $dy \, dx$ is replaced by $\rho d\phi \, d\rho$.

$$\int_0^{2\pi} \int_0^a \frac{3\rho^2 - 2a^2}{\sqrt{a^2 - \rho^2}} \rho \, d\rho \, d\phi$$

$$= \int_0^{2\pi} \int_0^a \frac{3(\rho^2 - a^2) + a^2}{\sqrt{a^2 - \rho^2}} \rho \, d\rho \, d\phi$$

$$= \int_0^{2\pi} \int_0^a \left(-3\rho \sqrt{a^2 - \rho^2} + \frac{a^2 \rho}{\sqrt{a^2 - \rho^2}} \right) \, d\rho \, d\phi$$

$$= \int_{\phi=0}^{2\pi} \left[(a^2 - p^2)^{\frac{3}{2}} - a^2 \sqrt{a^2 - p^2} \right]_{p=0}^a d\phi$$

$$= \int_{\phi=0}^{2\pi} (a^3 - a^3) d\phi = 0$$

[Ex 6-23]: If $\vec{F} = 4xz\hat{i} - y^2\hat{j} + yz\hat{k}$, evaluate $\iint \vec{F} \cdot \hat{n} dS$ where S is the surface of the cube bounded by $x=0, x=1, y=0, y=1, z=0, z=1$.

Solution:

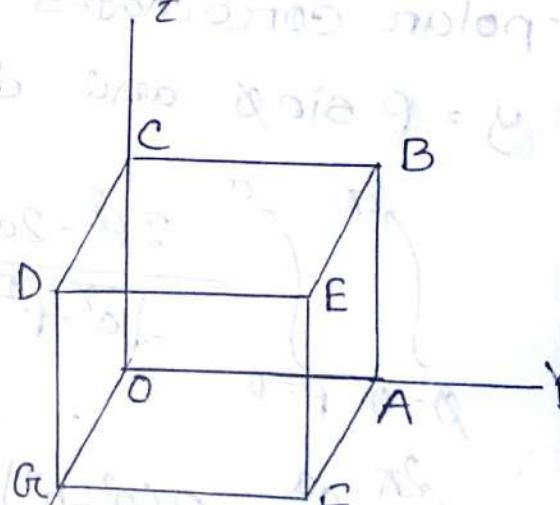
~~In ABCO: $\hat{n} = -$~~

In DEFG: $\hat{n} = \hat{i}, x=1$, then,

$$\iint \vec{F} \cdot \hat{n} dS$$

$$= \iint_{0,0}^{1,1} (4z\hat{i} - y^2\hat{j} + yz\hat{k}) \cdot \hat{i} dy dz$$

$$= \iint_{0,0}^{1,1} 4z dy dz = \int_0^1 [4yz]_0^1 dz = \int_0^1 4z dz = [2z^2]_0^1 = 2$$



In ABCO: $\hat{n} = -\hat{i}$, $x=0$

$$\iint \vec{F} \cdot \hat{n} \, ds$$

$$= \iint_{\Delta} \cancel{-4z \, dy \, dz} = \iint_{\Delta} (-y^2 \hat{j} + y \hat{k}) (-\hat{i}) \, dy \, dz \\ = 0$$

In ABEF: $\hat{n} = \hat{j}$, $y=1$

$$\iint \vec{F} \cdot \hat{n} \, ds = \iint_{\Delta} (4xz \hat{i} - \hat{j} + 2\hat{k}) \hat{j} \, dx \, dz$$

$$= \iint_{\Delta} -dx \, dz = - \left[x \right]_0^1 dz = - \int_0^1 dz = -1$$

In OGD^C: $\hat{n} = \hat{j}$, $y=0$

$$\iint \vec{F} \cdot \hat{n} \, ds$$

$$= \iint_{\Delta} (4xz \hat{i}) \cdot (-\hat{j}) \, dx \, dz = 0$$

In BCDE: $\hat{n} = \hat{k}$, $z=1$

$$\iint \vec{F} \cdot \hat{n} \, ds$$

$$= \iint_{\Delta} (4xi - y^2 \hat{j} + y \hat{k}) \hat{k} \, dx \, dy = \iint_{\Delta} y \, dx \, dy$$

$$= \int_0^1 \left[\frac{y^2}{2} \right]_0^1 dx$$

$$= \frac{1}{2} \int_0^1 dx \left(\frac{1}{2} (x^2 + 1) - \frac{1}{2} \right) = \frac{1}{2} \int_0^1 (x^2 - \frac{1}{2}) dx$$

$$= \frac{1}{2}$$

Q In AFGO: $\hat{n} = -\hat{k}$, $z=0$

$$\iint \vec{F} \cdot \hat{n} ds$$

$$= \int_0^1 \int_0^1 (-y^2 \hat{j}) (-\hat{k}) dy dx = 0$$

$$= 0$$

$$= 0$$

$$= 0$$

$$= 0$$

$$= 0$$

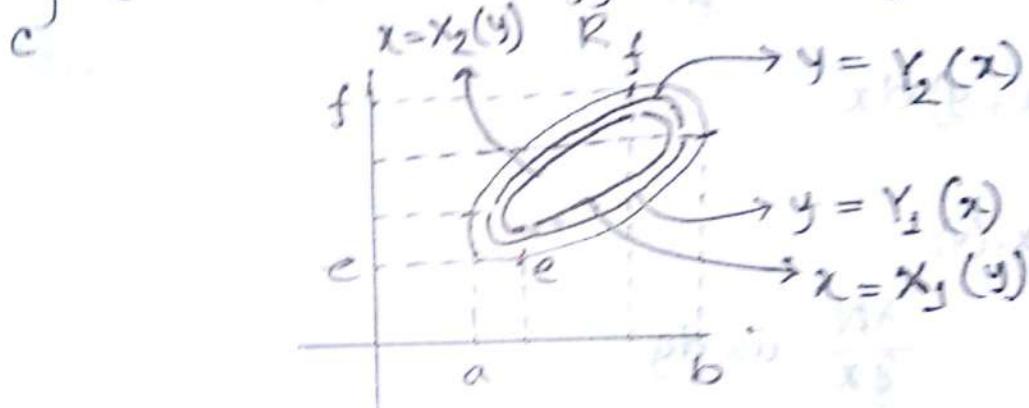
$$= 0$$

04-04-2018 : 8E : Wednesday

→ Green's theorem in the plane

If R is a region in closed path C and M, N
are continuous function in R then

$$\oint_C (M dx + N dy) = \iint_R \left(\frac{\partial N}{\partial x} - \frac{\partial M}{\partial y} \right) dx dy$$



$$= \int_a^b \left\{ \int_{Y_1(x)}^{Y_2(x)} -\frac{\partial M}{\partial y} dx dy \right\}$$

$$= \int_a^b \left\{ \left\{ \int_{Y_1}^{Y_2} -\frac{\partial M}{\partial y} dy \right\} dx \right\}$$

$$= \int_a^b [M(x, y)]_{Y_1}^{Y_2} dx$$

$$= \int_a^b [m(x, y_2) - m(x, y_1)] dx$$

$$= - \int_b^a m(x, y_2) dx - \int_a^b m(x, y_1) dx$$

$$= - \left\{ \int_a^b m(x, y_1) dx + \int_b^a m(x, y_2) dx \right\}$$

$$= - \oint m(x, y) dy$$

$$\int_{y=e}^f \int_{x=x_1(y)}^{x_2(y)} \frac{\partial N}{\partial x} dx dy$$

$$= \int_e^f \left\{ \int_{x_1}^{x_2} \frac{\partial N}{\partial x} dx \right\} dy$$

$$= \int_e^f [N(x, y)]_{x_1}^{x_2} dy$$

$$= \int_e^f [N(x_2, y)] dy - \int_e^f [N(x_1, y)] dy$$

$$= \int_e^f [N(x_2, y)] dy + \int_f^e [N(x_1, y)] dy$$

$$= \oint N(x, y) dy$$

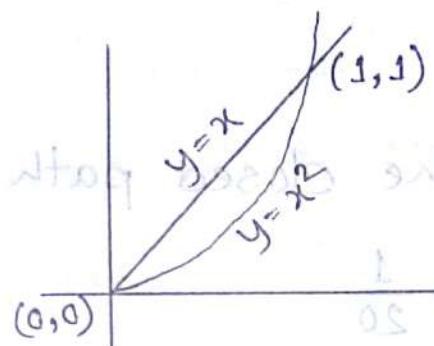
$$\therefore \oint (M dx + N dy) = \iint_R \left(\frac{\partial N}{\partial x} - \frac{\partial M}{\partial y} \right) dx dy$$

Ex:-02

→ Verify Green's theorem for $\oint [xy+y^2] dx + x^2 dy$

where C is the closed curve of region bounded by $y=x$, $y=x^2$

Solution:



Integration along the path $(y=x^2)$

$$\int_0^1 [(x^3 + x^4) dx + 2x^3 dx]$$

$$= \int_0^1 (3x^3 + x^4) dx$$

$$= \left[\frac{3x^4}{4} + \frac{x^5}{5} \right]_0^1$$

$$= \frac{3}{4} + \frac{1}{5} = \frac{15+4}{20} = \frac{19}{20}$$

Integration along the path ($y=x$ + xb M)

$$\int_1^0 [(x^2+x^2) dx + x^2 dx] = \int_1^0 [3x^2] dx = [x^3]_1^0 = -1$$

∴ Integration of the closed path

$$L.H.S. = \frac{19}{20} - 1 = -\frac{1}{20}$$

$$R.H.S. = \iint_{\substack{x=0 \\ y=x^2}}^1 \left\{ \frac{\partial(x^2)}{\partial x} - \frac{\partial(xy+y^2)}{\partial y} \right\} dx dy$$

$$= \iint_{\substack{x=0 \\ y=x^2}}^1 (2x - x - 2y) dx dy$$

$$= \iint_{\substack{x=0 \\ y=x^2}}^1 (x - 2y) dx dy$$

$$= \int_0^1 [xy - y^2]_{x^2}^x dx$$

$$= \int_0^1 (x^2 - x^2 - x^3 + x^4) dx$$

$$\begin{aligned}
 &= \int_0^1 [x^2 - x^2 - x^3 + x^4] dx \\
 &= \int_0^1 [x^4 - x^3] dx = \left[\frac{x^5}{5} - \frac{x^4}{4} \right]_0^1 = \frac{1}{5} - \frac{1}{4} = -\frac{1}{20} \\
 &= \frac{1}{5} - \frac{1}{4} = \frac{4-5}{20} = -\frac{1}{20} \quad \text{using anti primitive}
 \end{aligned}$$

$$\therefore L.H.S. = R.H.S. \quad (\text{Proved})$$

Ex:-37: Verify Green's theorem in the plane for
 $\oint [(3x^2 - 8y^2) dx + (4y - 6xy) dy]$ where C is the boundary of the region defined by

a) $y = \sqrt{x}$, $y = x^2$

b) $x = 0$, $y = 0$, $x + y = 1$

Solution:

a) Integration along the path $y = \sqrt{x}$

$$\begin{aligned}
 &\int_0^1 [(3x^2 - 8x) dx + (4\sqrt{x} - 6x\sqrt{x}) \frac{dx}{2\sqrt{x}}] \\
 &= \int_0^1 (3x^2 - 8x + 2 - 3x) dx \\
 &= \int_0^1 (3x^2 - 11x + 2) dx
 \end{aligned}$$

$$= \left[x^3 - \frac{11x^2}{2} + 2x \right]_{0,1}^{10}$$

Integrating along the path $y = x^2$

$$\int_0^1 [(3x^2 - 8x^4) dx + (4x^2 - 6x^3) 2x dx]$$

$$\begin{aligned} &= \int_0^1 (3x^2 - 8x^4 + 8x^3 - 12x^4) dx \\ &= \int_0^1 (3x^2 + 8x^3 - 20x^4) dx \\ &= \left[x^3 + 2x^4 - 4x^5 \right]_0^1 \\ &= -1 + 2 - 4 = -1 \end{aligned}$$

Integration of the closed path

$$L.H.S. = \frac{5}{2} - 1 = \frac{3}{2}$$

$$R.H.S. = \int_0^1 \int_{x^2}^{\sqrt{x}} \left\{ \frac{\partial(4y - 6xy)}{\partial x} - \frac{\partial(3x^2 - 8y^2)}{\partial y} \right\} dx dy$$

(20) [prob (sP) + 0]

$$= \int_0^1 \int_{x^2}^{\sqrt{x}} (-6y + 16y) dx dy$$

[es] = 2 - \frac{1}{2}

$$= \int_0^1 \int_{x^2}^{\sqrt{x}} (10y) dy dx \text{ add prob no longer for I}$$

$$= \int_0^1 [5y^2]_{x^2}^{\sqrt{x}} dx$$

$$= \int_0^1 (5x - 5x^4) dx$$

1 - prob ant prob no longer for L

$$= \left[\frac{5x^2}{2} - \frac{5x^5}{5} \right]_0^1$$

$$[xb(sx^2 + x^2 - x^4 - 1) - xb\{^s(x-L)8 - ^s(x^2)\}]$$

$$= \frac{5}{2} - 1 = \frac{3}{2}$$

$$\therefore L.H.S. = R.H.S. \text{ (verified)}$$

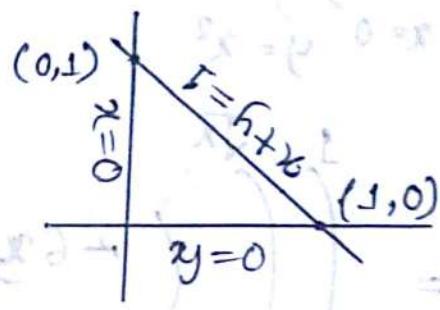
$$xb(sL - x^2S + ^s(xL))$$

b) Integration along the path $x=0$

$$\int_1^0 [0 + (4y) dy]$$

$$= [2y^2]_1^0$$

$$= -2$$



Integration along the path $y=0$

$$\int_0^1 [(3x^2) dx + 0]$$

$$= [x^3]_0^1 = 1$$

Integration along the path $x+y=1$

$$\int_1^0 [\{3x^2 - 8(1-x)^2\} dx - (4 - 4x - 6x + 6x^2) dx]$$

$$= \int_1^0 (3x^2 - 8 + 16x - 8x^2 - 4 + 10x - 6x^2) dx$$

$$= \int_1^0 (-11x^2 + 26x - 12) dx$$

$$= \frac{11}{3} - 13 + 12$$

$$= \frac{11 - 39 + 36}{3} = \frac{8}{3}$$

Integration of the closed path

$$\text{L.H.S.} = -2 + 1 + \frac{8}{3}$$

resistant to propagation ←

$$\text{solution is } = \frac{-6 + 3 + 8}{3} \text{ hence employ } \rho \cdot \nabla \times \mathbf{H}$$

$$= \frac{5}{3} \text{ no net flux } \rho \cdot \nabla \times \mathbf{H} \text{ across}$$

$$\text{R.H.S.} = \int_{x=0}^1 \int_{y=0}^{1-x} \left[\frac{\partial(4y - 6xy)}{\partial x} - \frac{\partial(3x^2 - 8y^2)}{\partial y} \right] dx dy$$

$$\frac{\partial A_x}{\partial y} + \frac{\partial A_y}{\partial z} + \frac{\partial A_z}{\partial x} = \nabla \cdot \mathbf{A} = 0$$

$$= 0 \cdot H$$

$$= \int_{x=0}^1 \int_{y=0}^{1-x} [-6y + 16y] dy dx$$

$$= \int_{x=0}^1 \int_{y=0}^{1-x} (10y) dy dx$$

$$= \int_0^1 [5y^2]_0^{1-x} dx$$

$$= \int_0^1 5(1-x)^2 dx = \int_0^1 (5 - 10x + 5x^2) dx$$

$$= \left[5x - 5x^2 + \frac{5x^3}{3} \right]_0^1 = 5 - 5 + \frac{5}{3} = \frac{5}{3}$$

$\therefore L.H.S. = R.H.S.$ (verified)

18-04-2018 : 9E : Wednesday

→ Divergence theorem

If V is a volume bounded by a surface S and \vec{A} is any vector on the surface

$$\iiint_V \nabla \cdot \vec{A} dV = \iint_S \vec{A} \cdot \hat{n} dS$$

$$\nabla \cdot \vec{A} = \frac{\partial A_1}{\partial x} + \frac{\partial A_2}{\partial y} + \frac{\partial A_3}{\partial z}$$

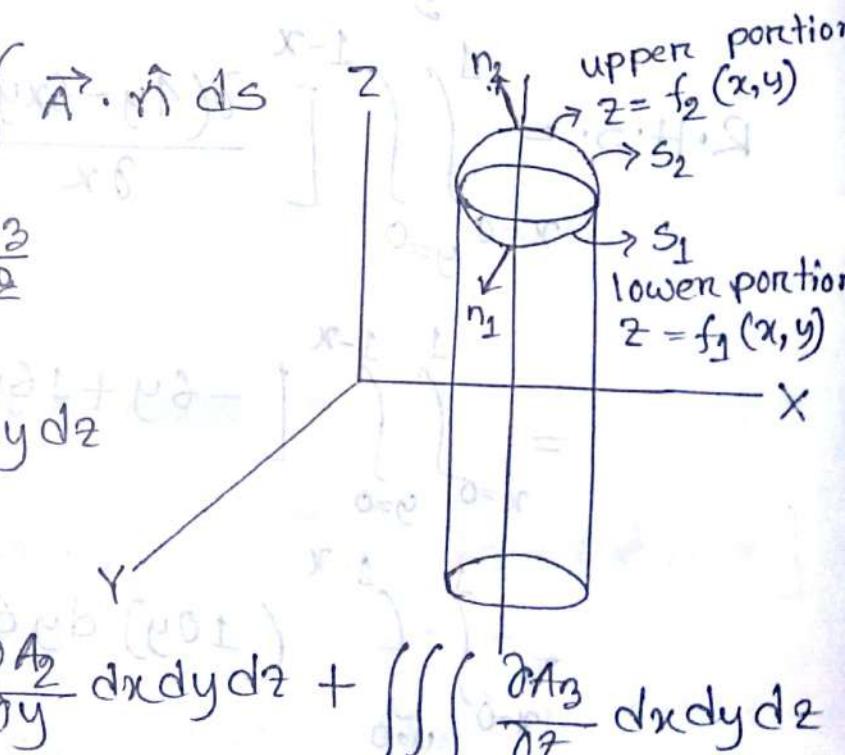
L.H.S. =

$$\iiint \left(\frac{\partial A_1}{\partial x} + \frac{\partial A_2}{\partial y} + \frac{\partial A_3}{\partial z} \right) dx dy dz$$

$$= \iiint \frac{\partial A_1}{\partial x} dx dy dz + \iiint \frac{\partial A_2}{\partial y} dx dy dz + \iiint \frac{\partial A_3}{\partial z} dx dy dz$$

$$\therefore \iiint \frac{\partial A_3}{\partial z} dx dy dz$$

$$= \iint \left\{ \int \frac{\partial A_3}{\partial z} dz \right\} dy$$



$$= \iiint \left\{ \int_{f_1}^{f_2} \frac{\partial A_3}{\partial z} dz \right\} dx dy$$

$$= \iiint [A_3(x, y, z)]_{f_1}^{f_2} dx dy$$

$$= \iint [A_3(x, y, f_2) - A_3(x, y, f_1)] dx dy$$

$$= \iint_{S_2} A_3(x, y, f_2) dx dy - \iint_{S_1} A_3(x, y, f_1) dx dy$$

$$ds_1 = \frac{dx dy}{\cos(180-\theta)}$$

$$\Rightarrow ds_1 = \frac{dx dy}{-\cos\theta}$$

$$\Rightarrow ds_1 = -\frac{dx dy}{\hat{n}_1 \cdot \hat{k}} \quad \therefore dx dy = -ds_1 |\hat{n}_1 \cdot \hat{k}|$$

$$ds_2 = \frac{dx dy}{\cos\theta}$$

$$\Rightarrow ds_2 = \frac{dx dy}{\hat{n}_2 \cdot \hat{k}}$$

$$\therefore dx dy = ds_2 \hat{n}_2 \cdot \hat{k}$$

$$\therefore \iint_{S_2} A_3(\hat{k} \cdot \hat{n}_2 ds_2) + \iint_{S_1} A_3(\hat{k} \cdot \hat{n}_1 ds_1)$$

$$= \iint_S A_3 \cdot \hat{k} \cdot \hat{n} dS$$

$$\iiint \frac{\partial A_1}{\partial x} dx dy dz = \iint A_1 \cdot \hat{i} \cdot \hat{n} ds$$

$$\iiint \frac{\partial A_2}{\partial y} dx dy dz = \iint A_2 \hat{j} \cdot \hat{n} ds$$

$$\therefore L.H.S. = \iiint \left(\frac{\partial A_1}{\partial x} + \frac{\partial A_2}{\partial y} + \frac{\partial A_3}{\partial z} \right) dx dy dz$$

$$= \iint_S (A_1 \hat{i} + A_2 \hat{j} + A_3 \hat{k}) \cdot \hat{n} ds$$

$$= \iint_S \vec{A} \cdot \hat{n} ds$$

$$= R.H.S.$$

$\therefore L.H.S. = R.H.S.$ (Proved)

Ex:-17: Evaluate $\iint_S \vec{F} \cdot \hat{n} ds$ where $\vec{F} = 4x^2 \hat{i} - y^2 \hat{j} + yz \hat{k}$ and S is the surface of the cube bounded by $x=0, x=1, y=0, y=1, z=0, z=1$.

Solution:

$$\iint_S \vec{F} \cdot \hat{n} ds = \iiint \nabla \cdot \vec{F} dx dy dz$$

$$\begin{aligned}
 &= \iiint_{\substack{x=0 \\ y=0 \\ z=0}}^{\substack{1 \\ 1 \\ 1}} \left\{ \frac{\partial}{\partial x} (4xz) - \frac{\partial}{\partial y} (y^2) + \frac{\partial}{\partial z} (yz) \right\} dx dy dz \\
 &= \iiint_{\substack{0 \\ 0 \\ 0}}^{\substack{1 \\ 1 \\ 1}} (4z - 2y + y) dx dy dz \\
 &= \iiint_{\substack{0 \\ 0 \\ 0}}^{\substack{1 \\ 1 \\ 1}} (4z - y) dz dy dx \\
 &= \int_0^1 \int_0^1 [2z^2 - yz]_0^1 dy dx \\
 &= \int_0^1 \int_0^1 (2-y) dy dx \\
 &= \int_0^1 [2y - \frac{y^2}{2}]_0^1 dx \\
 &= \int_0^1 (2 - \frac{1}{2}) dx \\
 &= \int_0^1 \frac{3}{2} dx = \left[\frac{3x}{2} \right]_0^1 = \frac{3}{2}
 \end{aligned}$$

05-05-2018 : 10E : Saturday

→ Stoke's theorem

Let S be a surface which is such that its projections on the xy and xz planes are regions bounded by simple closed curves, as indicated in the adjoining figure. Assume S to have representation $z = f(x, y)$ or $x = g(y, z)$ or $y = h(x, z)$, where f, g, h are single valued, continuous and differentiable functions.

$$\iint_S (\vec{\nabla} \times \vec{A}) \cdot \hat{n} \, ds = \oint_C \vec{A} \cdot d\vec{r}$$

$$\vec{A} = A_1 \hat{i} + A_2 \hat{j} + A_3 \hat{k}$$

$$\begin{aligned} \text{L.H.S.} &= \iint_S \{ \vec{\nabla} \times (A_1 \hat{i} + A_2 \hat{j} + A_3 \hat{k}) \} \cdot \hat{n} \, ds \\ &= \iint_S (\vec{\nabla} \times A_1 \hat{i}) \cdot \hat{n} \, ds + \iint_S (\vec{\nabla} \times A_2 \hat{j}) \cdot \hat{n} \, ds \\ &\quad + \iint_S (\vec{\nabla} \times A_3 \hat{k}) \cdot \hat{n} \, ds \end{aligned}$$

$$\begin{aligned}
 \vec{\nabla} \times A_1 \hat{i} &= \left| \begin{array}{ccc} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ A_1 & 0 & 0 \end{array} \right| \cdot (\vec{i} \cdot \vec{A}) \frac{\hat{i}}{|\vec{i}|^2} = \hat{i} (\vec{i} \cdot \vec{A} \times \vec{\nabla}) \\
 C(\vec{v} \cdot \vec{v}) &= v \cdot v = 1 \\
 &= \hat{i} (0 - 0) + \hat{j} (0 - \frac{\partial A_1}{\partial z}) + \hat{k} (0 - \frac{\partial A_1}{\partial y}) \\
 &= -\frac{\partial A_1}{\partial z} \hat{j} - \frac{\partial A_1}{\partial y} \hat{k}
 \end{aligned}$$

$$(\vec{\nabla} \times A_1 \hat{i}) \hat{n} = \left| \begin{array}{ccc} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ A_1 & 0 & 0 \end{array} \right| \cdot (\vec{i} \cdot \vec{A} \times \vec{\nabla}) \hat{n}$$

$$A(x, y, z) = A_1(x, y, z) + A_2(x, y, z) + A_3(x, y, z)$$

$$\begin{aligned}
 A_1(x, y, z) &= f(x, y) \\
 &= f(x, y)
 \end{aligned}$$

$$\vec{r} = x\hat{i} + y\hat{j} + z\hat{k} = x\hat{i} + y\hat{j} + f(x, y)\hat{k}$$

$$\frac{\partial \vec{r}}{\partial y} = 0 + \hat{j} + \frac{\partial f}{\partial y} \hat{k}$$

$$\Rightarrow \hat{n} \cdot \frac{\partial \vec{r}}{\partial y} = \hat{n} \cdot \hat{j} + \frac{\partial f}{\partial y} \hat{n} \cdot \hat{k}$$

$$\Rightarrow 0 = \hat{n} \cdot \hat{j} + \frac{\partial f}{\partial y} \hat{n} \cdot \hat{k}$$

$$\Rightarrow \hat{n} \cdot \hat{j} = -\frac{\partial f}{\partial y} \hat{n} \cdot \hat{k}$$

$$(\vec{\nabla} \times A_1 \hat{i}) \hat{n} = -\frac{\partial f}{\partial y} (\hat{n} \cdot \hat{k}) \frac{\partial A_1}{\partial z} - \hat{n} \cdot \hat{k} \frac{\partial A_1}{\partial y} \quad i \text{, } j \text{, } k$$

$$= -\hat{n} \cdot \hat{k} \left(\frac{\partial z}{\partial y} \cdot \frac{\partial A_1}{\partial z} + \frac{\partial A_1}{\partial y} \right) \quad [\because z = f(x, y)]$$

~~$$\left(\frac{\partial A_1}{\partial y} \right) \hat{n} \cdot \hat{k} \left(\frac{\partial A_1}{\partial y} + \frac{\partial A_1}{\partial y} \right) \hat{i} =$$~~
~~$$= -\hat{n} \cdot \hat{k} \left(\frac{\partial F}{\partial y} \right) \hat{i} =$$~~

$$\therefore \iint_S (\vec{\nabla} \times A_1 \hat{i}) \hat{n} dS = - \iint_S \hat{n} \cdot \hat{k} \cdot \frac{\partial F}{\partial y} dS \quad i \text{, } j \text{, } k$$

$$(S, \nu, \omega) \hat{n} + (S, \nu, \omega) \frac{\partial F}{\partial y} dS \cdot A = (S, \nu, \omega) A$$

$$= \int - \left\{ \int \frac{\partial F}{\partial y} dy \right\} dx \cdot (S, \nu, \omega) A$$

$$\begin{aligned} \int (S, \nu, \omega) &= \int F dx = \int S + \int U + \int \omega = \int \\ &= \int A_1 dx = \int \frac{25}{x^2} + \int 1 + \int 0 = \int \frac{25}{x^2} \end{aligned}$$

Similarly,

$$\iint_S (\vec{\nabla} \times A_2 \hat{j}) \hat{n} dS = \int A_2 dy \quad \hat{i} \cdot \hat{n} = \frac{25}{x^2} \cdot \hat{i} \neq 0$$

$$\iint_S (\vec{\nabla} \times A_3 \hat{k}) \hat{n} dS = \int A_3 dz \quad \hat{i} \cdot \hat{n} = \hat{j} \cdot \hat{n} = 0$$

$$\begin{aligned}
 L.H.S. &= \iint \{ \vec{\nabla} \times (A_1 \hat{i} + A_2 \hat{j} + A_3 \hat{k}) \cdot \hat{n} \, ds \\
 &= \int (A_1 dx + A_2 dy + A_3 dz) (\cancel{dx\hat{i} + dy\hat{j} + dz\hat{k}}) \\
 &= \int \vec{A} \cdot d\vec{r} \\
 &= R.H.S.
 \end{aligned}$$

$\therefore L.H.S. = R.H.S.$ (Proved)

23-06-2018: 11E: Saturday:

→ Verify the divergence theorem for $\vec{A} = 4x\hat{i} - 2xy^2\hat{j} + z^2\hat{k}$ taken over the region bounded by $x^2 + y^2 = 4$, $z = 0$ and $z = 2$.

Solution:

$$\text{Prove: } \iiint \nabla \cdot \vec{A} dv = \iint \vec{A} \cdot \hat{n} ds$$

$$\begin{aligned} &= \frac{d}{dx}(4x) - \frac{d}{dy}(2y^2) + \frac{d}{dz}(z^2) \\ &= 4 - 4y + 2z \end{aligned}$$

$$\therefore \text{L.H.S.} = \iiint \nabla \cdot \vec{A} dv$$

$$= \iiint_{\substack{x=-2 \\ y=-\sqrt{4-x^2} \\ z=0}}^{x=2 \\ y=\sqrt{4-x^2} \\ z=2} (4 - 4y + 2z) dx dy dz$$

$$= \int_{-2}^{2} \left[4x - 4y^2 + 2z \right]_0^2 dx dy$$

$$= \int_{-2}^{2} \left[12 - 12y + 9 \right] dy$$

In xy plane

$$\begin{aligned} &\text{In } x^2 + y^2 = 4 \\ &\Rightarrow y^2 = 4 - x^2 \\ &\therefore y = \pm \sqrt{4 - x^2} \end{aligned}$$

In x axis

$$x^2 = 4$$

$$\therefore x = \pm 2$$

$$\begin{aligned}
 &= \int_{-2}^2 \int_{-\sqrt{4-x^2}}^{\sqrt{4-x^2}} (21 - 12y) dx dy \\
 &= \int_{-2}^2 [21y - 6y^2] \Big|_{-\sqrt{4-x^2}}^{\sqrt{4-x^2}} dx \\
 &= \int_{-2}^2 [21\sqrt{4-x^2} - 6(4-x^2) + 21\sqrt{4-x^2} + 6(4-x^2)] dx \\
 &= 42 \int_{-2}^2 2\sqrt{4-x^2} dx \\
 &= 42 \left[\frac{x\sqrt{4-x^2}}{2} + 2\sin^{-1}\frac{x}{2} \right]_{-2}^2 \\
 &= 42 [0 + \pi - 0 + \pi] \\
 &= 84\pi
 \end{aligned}$$

$$\begin{aligned}
 \text{R.H.S.} &= \iint_S \vec{A} \cdot \hat{n} \cdot dS \\
 &= \iint_{S_1} \vec{A} \cdot \hat{n} dS_1 + \iint_{S_2} \vec{A} \cdot \hat{n} dS_2 + \iint_{S_3} \vec{A} \cdot \hat{n} dS_3
 \end{aligned}$$

On S_1 surface $z=0 \Rightarrow \vec{n} = -\hat{k}$

$$\therefore \vec{A} \cdot \hat{n} = -2^2 = 0$$

$$\therefore \iint_{S_1} \vec{A} \cdot \hat{n} dS_1 = 0$$

$$S_1 \text{ is a circle}$$

On S_2 surface $z=3$ ($\vec{n} = \hat{k}$)

$$\therefore \vec{A} \cdot \hat{n} = 2^2 = 9$$

$$\therefore \iint_{S_2} \vec{A} \cdot \hat{n} dS_2 = 9 \iint_{S_2} dS_2 \text{ where } (dS_2) = [(\sin \theta \cos \phi, \sin \theta \sin \phi, \cos \theta)] d\Omega$$

$$= 9 \iint_{S_2} dS_2 \text{ where } (\sin \theta \cos \phi, \sin \theta \sin \phi, \cos \theta)$$

$$= 9 \times 4\pi \left[\iint_{S_2} dS_2 \text{ is the area of the circle } x^2 + y^2 = 4 \right] \text{ Area} = \pi r^2 = \pi \times 2^2 = 4\pi$$

$$= 36\pi$$

On S_3 surface,

$$\text{Let, } \phi = x^2 + y^2 - 4$$

$$\hat{n} = \frac{\vec{\nabla} \phi}{|\vec{\nabla} \phi|} = \frac{2(x\hat{i} + y\hat{j})}{2\sqrt{x^2 + y^2}} = \frac{x\hat{i} + y\hat{j}}{\sqrt{4}} = \frac{x\hat{i} + y\hat{j}}{2}$$

$$\therefore \vec{A} \cdot \hat{n} = 2x^2 - y^2$$

$$\therefore \iint_{S_3} \vec{A} \cdot \hat{n} dS_3$$

$\left[\begin{array}{l} x = r \cos \theta, y = r \sin \theta \\ ds = r d\theta dz \end{array} \right]$

Let, $r = 2$

$$= \iint_{S_3} (2x^2 - y^2) dS_3$$

$$= \iint_{-2\pi}^{2\pi} \int_0^3 (8\cos^2 \theta - 8\sin^2 \theta) 2 d\theta dz$$

$$= 16 \int_{-\pi}^{\pi} \left[(\cos^2 \theta - \sin^2 \theta)(2) \right]_0^3 d\theta$$

$$= 48 \int_{-\pi}^{\pi} (\cos^2 \theta - \sin^2 \theta) d\theta$$

$$= 48 \int_{-\pi}^{\pi} \cos^2 \theta d\theta - 48 \int_{-\pi}^{\pi} \sin^2 \theta d\theta$$

$$= 24 \int_0^{\pi} 2\cos^2 \theta d\theta - 0 \quad \left[\text{As } \sin^2 \theta \text{ is odd function} \right]$$

$$= 24 \int_0^{\pi} (1 + \cos 2\theta) d\theta$$

$$= 24 \int_0^{\pi} d\theta + 24 \int_0^{\pi} \cos 2\theta d\theta$$

$$= 24 \left[\theta \right]_0^{2\pi} + 24 \left[\frac{\sin 2\theta}{2} \right]_0^{2\pi}$$

$$= 48\pi$$

$$\therefore R.H.S. = \iint_{S_1} \vec{A} \cdot \hat{n} dS_1 + \iint_{S_2} \vec{A} \cdot \hat{n} dS_2 + \iint_{S_3} \vec{A} \cdot \hat{n} dS_3$$

$$= 0 + 36\pi + 48\pi \quad \therefore L.H.S. = R.H.S. \\ = 84\pi \quad (\text{verified})$$

30-06-2018: 12E: Saturday

→ Verify Stoke's theorem for $\vec{A} = (2x-y)\hat{i} - y^2\hat{j} - y^2z\hat{k}$ where S is the upper half surface of the sphere $x^2+y^2+z^2=1$ and C is its boundary.

Solution:

$$\oint \vec{A} \cdot d\vec{r} = \iint (\nabla \times \vec{A}) \cdot \hat{n} dS$$

Let, $x = \rho \cos t, y = \rho \sin t, z = 0$ $t = 0, 2\pi$

$$\Rightarrow dx = -\rho \sin t dt, dy = \rho \cos t dt, dz = 0$$

$$d\vec{r} = dx\hat{i} + dy\hat{j} + dz\hat{k}$$

$$\vec{A} \cdot d\vec{r} = (2x-y)dx + -y^2dy - y^2zdz$$

$$= -(2\rho \cos t - \rho \sin t) \sin t dt$$

$$= (\sin^2 t - 2 \sin t \cos t) dt$$

$$= (\sin^2 t - \sin 2t) dt$$

$$\begin{aligned}
 \text{L.H.S.} &= \oint \vec{A} \cdot d\vec{r} \\
 &= \int_0^{2\pi} (\sin^2 t - \sin 2t) dt \\
 &= \frac{1}{2} \int_0^{2\pi} (1 - \cos 2t) dt - \int_0^{2\pi} \sin 2t dt \\
 &= \frac{1}{2} \left[t - \frac{\sin 2t}{2} \right]_0^{2\pi} + \left[\frac{\cos 2t}{2} \right]_0^{2\pi} \\
 &= \frac{1}{2} [2\pi] + [1 - 1] \\
 &= \pi
 \end{aligned}$$

$$\begin{aligned}
 \text{R.H.S.} &= \iint_S (\vec{\nabla} \times \vec{A}) \cdot \hat{n} ds \\
 \text{So } \vec{\nabla} \times \vec{A} &= \left| \begin{array}{ccc} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ 2x-y & -yz^2 & -y^2z \end{array} \right| \\
 &= \hat{i}(-2yz + yz) - \hat{j}(0-0) + \hat{k}(0+1)
 \end{aligned}$$

$$\begin{aligned}
 ds &= \frac{dx dy}{\hat{n} \cdot \hat{k}} \\
 \text{R.H.S.} &= \iint_S (\vec{\nabla} \times \vec{A}) \cdot \hat{n} ds \\
 &= \iint_S \hat{k} \cdot \hat{n} \cdot \frac{dx dy}{\hat{n} \cdot \hat{k}}
 \end{aligned}$$

$\iint_{\text{circle}} dx dy$ = π (not monochromatic plane)

smooth surface & no discontinuity $\Rightarrow \iint_{\text{circle}} (\rho + S) dA$

In xy -plane, $\rho = \rho(x, y), S = S(x, y)$

$$x^2 + y^2 = 1 \quad [\text{from } x^2 + y^2 + z^2 = 1]$$

$$\Rightarrow y = \pm \sqrt{1-x^2}$$

(In x -axis, $x^2 = 1 \Rightarrow x = \pm 1$)

$$\therefore L.H.S. = \iint_{\text{circle}} \rho dA = \int_{-1}^{+1} \int_{-\sqrt{1-x^2}}^{\sqrt{1-x^2}} \rho dxdy$$

$$= \int_{-1}^{+1} [y]_{-\sqrt{1-x^2}}^{\sqrt{1-x^2}} dx$$

$$= \int_{-1}^{+1} (\sqrt{1-x^2} + \sqrt{1-x^2}) dx$$

$$= \int_{-1}^{+1} 2\sqrt{1-x^2} dx$$

$$= 2 \left[\frac{x\sqrt{1-x^2}}{2} + \frac{1}{2} \sin^{-1} x \right]_{-1}^{+1}$$

$$= 2 \left[0 + \frac{1}{2} \cdot \frac{\pi}{2} - 0 - \left(-\frac{1}{2} \cdot \frac{\pi}{2} \right) \right]$$

$$= 2 \left[\frac{\pi}{4} + \frac{\pi}{4} \right] = 2 \cdot \frac{\pi}{2} = \pi$$

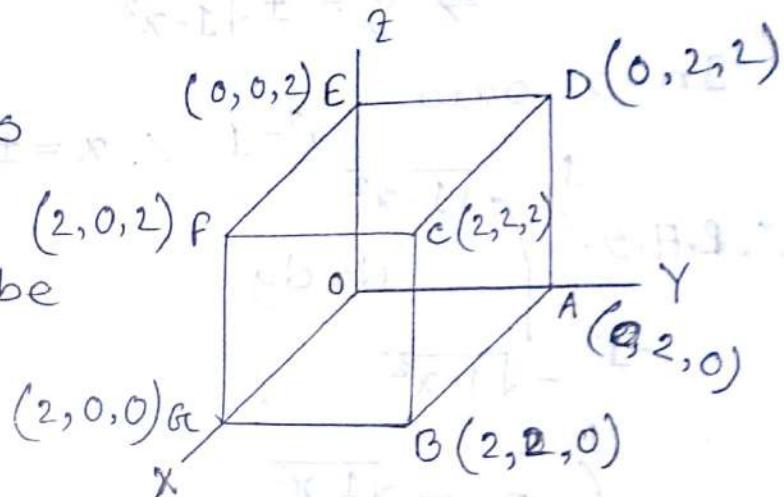
$\therefore L.H.S. = R.H.S. \text{ (verified)}$

→ Verify stoke's theorem for $\vec{A} = (y-z+2)\hat{i} + (yz+4)\hat{j} - xz\hat{k}$ whence S is the surface of the cube $x=0, y=0, z=0, x=2, y=2, z=2$ above the xy plane.

Solution:

$$\oint \vec{A} \cdot d\vec{r} = \iint (\nabla \times \vec{A}) \cdot \hat{n} dS$$

surface of the cube
is CDEF.



$$\therefore L.H.S. = \oint \vec{A} \cdot d\vec{r}$$

$$= \int_{CD} \vec{A} \cdot d\vec{r} + \int_{DE} \vec{A} \cdot d\vec{r} + \int_{EF} \vec{A} \cdot d\vec{r} + \int_{FC} \vec{A} \cdot d\vec{r}$$

$$\vec{A} \cdot d\vec{r} = (y-z+2) dx + (yz+4) dy - xz dz$$

For C :

$y = 2, z = 2$, only x varies from 2 to 0.

$$dy = 0, dz = 0$$

$$\int_{CD} \vec{A} \cdot d\vec{r}$$

$$= \int_{CD} (2-z)(y-z+2) dx$$

$$= \int_2^0 (2-2+2) dx$$

when $y = 0, z = x$: 0 to 2
 $\partial z/\partial x = 0 = \partial y/\partial x$
 $y = 0 \Rightarrow 0 = 2 - x \Rightarrow x = 2$

$$= [2x]_2^0$$

$$= -4$$

Forc DE: $x=0, z=2$, only y varies from 2 to 0
 $dx=0, dz=0$

$$\int \vec{A} \cdot d\vec{r}$$

$$DE(b\hat{x}) + ab\hat{y} + b^2\hat{z} = 0 \quad \text{Hence}$$

$$= \int_{DE} (yz + 4) dy$$

$$= \int_2^0 (2y + 4) dy$$

$$= \left[\frac{y^2}{2} + 4y \right]_2^0$$

$$= -4 - 8$$

$$= -12$$

(L-0) $\hat{i} + (L+8-) \hat{j} - (8-0) \hat{k}$ from 0 to 2

Forc EF: $y=0, z=2$, only x varies from 0 to 2

$$dy=0, dz=0$$

$$\int_{EF} \vec{A} \cdot d\vec{r}$$

$$= \int_{EF} (y-2+2) dx = \int_0^2 (0-2+2) dx = 0$$

For FC: $x=2, z=2$, only y varies from 0 to 2
 $dx=0, dz=0$

$$\int_{FC} \vec{A} \cdot d\vec{r}$$

$$= \int_{FC} (y^2 + 4) dy$$

$$= \int_0^2 (2y + 4) dy$$

$$= [y^2 + 4y]_0^2 = 4 + 8 = 12$$

$$\therefore L.H.S. = \int_{CD} \vec{A} \cdot d\vec{r} + \int_{DE} \vec{A} \cdot d\vec{r} + \int_{EF} \vec{A} \cdot d\vec{r} + \int_{FC} \vec{A} \cdot d\vec{r}$$

$$= -4 - 12 + 0 + 12$$

$$= -4$$

$$\vec{\nabla} \times \vec{A} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ y-2+2 & y^2+4 & -x^2 \end{vmatrix}$$

$$= \hat{i}(0-y) - \hat{j}(-z+1) + \hat{k}(0-1)$$

$$= -y\hat{i} + (z-1)\hat{j} - \hat{k}$$

on CDEF surface $\hat{n} = \hat{k}, z=2$

$$\therefore R.H.S. = \iint_{CDEF} (\vec{\nabla} \times \vec{A}) \cdot \hat{n} ds$$

$$CDEF = xb(S+E-O) = xb(S+E-V)$$

$$\begin{aligned}
 &= \iint_0^2 \left\{ -y\hat{i} + (2-x)\hat{j} - \hat{k} \right\} \cdot \hat{k} \cdot dx dy \\
 &= - \iint_0^2 dx dy \left[\exp(x) + \exp(y) - \exp(x+y) \right] = \\
 &= - \int_0^2 [y]^2_0 dx \\
 &= - \int_0^2 2 dx \left[\exp(x) + \exp(y) - \exp(x+y) \right] = \\
 &\stackrel{\text{Integrating w.r.t. } y}{=} -2 \left[x \right]_0^2 \left[\exp(x) + \exp(y) - \exp(x+y) \right] = \\
 &= -4 \left[\exp(2) + \exp(2) - \exp(4) \right] = \\
 &\therefore \text{L.H.S.} = \text{R.H.S. (verified)}
 \end{aligned}$$

07-07-2018: 13E: Saturday

→ Verify divergence theorem for $\vec{A} = 2x^2y\hat{i} - y^2\hat{j} + 4xz^2\hat{k}$ taken over the region on the first octant bounded by $y^2 + z^2 = 9$ and $x=2$.

Solution:

$$\begin{aligned}
 \iiint \vec{\nabla} \cdot \vec{A} dv &= \iint \vec{A} \cdot \hat{n} dS = \\
 \vec{\nabla} \cdot \vec{A} &= \frac{\partial}{\partial x}(2x^2y) - \frac{\partial}{\partial y}(y^2) + \frac{\partial}{\partial z}(4xz^2) \\
 &= 4xy - 2y + 8xz
 \end{aligned}$$

$$\begin{aligned}
 \therefore L.H.S. &= \iiint \vec{\nabla} \cdot \vec{A} dv \\
 &= \int_{x=0}^2 \int_{y=0}^3 \int_{z=0}^{\sqrt{9-y^2}} (4xy - 2y + 8xz) dx dy dz \\
 &= \int_0^2 \int_0^3 [4xyz - 2yz + 8xz^2]_0^{\sqrt{9-y^2}} dx dy \\
 &= \int_0^2 \int_0^3 [4xy\sqrt{9-y^2} - 2y\sqrt{9-y^2} + 36x - 4xy^2] dx dy \\
 &= \int_0^2 \left[\frac{4xy^3}{3} - \frac{2y^3}{3} + 36xy - \frac{4xy^3}{3} \right]_0^3 dx \\
 &\text{Now, } \vec{E} = \int_0^2 (36x - 18 + 108x - 36x) dx \\
 &= \int_0^2 (108x - 18) dx \\
 &= \left[54x^2 - 18x \right]_0^2
 \end{aligned}$$

$$\begin{aligned}
 &= (54 \cdot 4 - 18 \cdot 2) - (54 \cdot 0 - 18 \cdot 0) = 180
 \end{aligned}$$

Volume of the first octant has three surface.

On S_1 ($x=0$), $\hat{n} = \hat{k}$, $n = 0$

$$\iint_{S_1} \vec{A} \cdot \hat{n} dS_1 = \iint_{S_1} (-y^2 \hat{j}) \cdot (\hat{k}) dS_1 = 0$$

On S_2 ($x=2$), $\hat{n} = \hat{i}$, $n = 2$

$$\iint_{S_2} \vec{A} \cdot \hat{n} dS_2 = \iint_{S_2} (8y \hat{i} - y^2 \hat{j} + 8z^2 \hat{k}) \cdot \hat{i} \cdot dy dz$$

$$= \iint_{S_2} 8y dy dz \text{ (using } \hat{i} \cdot \hat{i} = 1)$$

$$= 8 \int_0^3 [y^2]_0^{\sqrt{9-y^2}} dy$$

$$= 8 \int_0^3 y \sqrt{9-y^2} dy$$

$$= 8 \left[\frac{y^3}{3} \right]_0^3$$

$$= 8 \times 9$$

$$= 72$$

On S_3 ($y^2 + z^2 = 9$),

Let, $\phi = y^2 + z^2 - 9$, $(0 = r)$ is w.p.

$$\vec{\nabla} \phi = 2y\hat{j} + 2z\hat{k}$$

$$|\vec{\nabla} \phi| = \sqrt{4y^2 + 4z^2}$$

$$= 2\sqrt{y^2 + z^2} = 2x^3 = 6$$

$$\therefore \hat{n} = \frac{\vec{\nabla} \phi}{|\vec{\nabla} \phi|} = \frac{2y\hat{j} + 2z\hat{k}}{6} = \frac{y\hat{j} + z\hat{k}}{3}$$

sub. in $(A \cdot \hat{n}) ds_3$

$$\hat{n} \cdot \hat{j} = \frac{y}{3} \quad ds_3 = \frac{dxdz}{\hat{n} \cdot \hat{j}}$$

$$\begin{aligned} A \cdot \hat{n} &= \left(2x^2y\hat{i} - y^2\hat{j} + 4x^2z\hat{k}\right) \left(\frac{y\hat{j} + z\hat{k}}{3}\right) \\ &= \frac{1}{3} \left(-y^3 + 4x^2z^3\right) \end{aligned}$$

$$\iint_{S_3} \vec{A} \cdot \hat{n} ds_3$$

$$= \iint_{\substack{x^2=0 \\ z^2=0}}^2 \left(-\frac{y^3}{3} + 4x^2z^3\right) \frac{3dxdz}{y}$$

$$= \iint_{\substack{x^2=0 \\ z^2=0}}^2 \left(-y^2 + \frac{4x^2z^3}{y}\right) dxdz$$

$$\begin{aligned}
&= \int_0^2 \int_0^3 \left[-(9-z^2) + \frac{4xz^3}{\sqrt{9-z^2}} \right] dz dx \quad [y^2 = 9-z^2] \\
&= \int_0^2 \left[-9z + \frac{z^3}{3} + 4x \left(9z - \frac{z^3}{3} \right) \right]_0^3 dx \\
&= \int_0^2 \left[-27 + 9 + 4x(27-9) \right] dx \\
&= \int_0^2 (72x - 18) dx \\
&\Rightarrow [36x^2 - 18x]_0^2 = 144 - 36 = 108
\end{aligned}$$

$$\begin{aligned}
\therefore L.H.S. &= \iint_S \vec{A} \cdot \hat{n} dS \\
&= \iint_{S_1} \vec{A} \cdot \hat{n} dS_1 + \iint_{S_2} \vec{A} \cdot \hat{n} dS_2 + \iint_{S_3} \vec{A} \cdot \hat{n} dS_3 \\
&= 0 + 72 + 108 \\
&= 108
\end{aligned}$$

$$\therefore L.H.S. = R.H.S. \text{ (verified)}$$