

Network Data and Graph Workflows

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Why Networks Matter

Many social processes are fundamentally relational:

- Conflict and cooperation
- Information diffusion
- Influence and dependency
- Collective action

Networks make relations explicit.

What Is Network Data

Network data consist of:

- Nodes (actors, units)
- Edges (relations, interactions)
- Attributes on both

The unit of analysis is often the *tie*, not the node.

From Tables to Graphs

Network construction requires choices:

- What counts as a node?
- What counts as a tie?
- Directional or undirected?
- Weighted or binary?

Representation decisions shape inference.

Graph Construction (Conceptual)

```
import networkx as nx

G = nx.from_pandas_edgelist(
    df,
    source='i',
    target='j',
    create_using=nx.DiGraph()
)
```

```
library(igraph)

g ← graph_from_data_frame(
    df,
    directed = TRUE
)
```

Centrality Measures

Centrality captures different notions of importance:

- Degree
- Betweenness
- Eigenvector / PageRank

No single measure is universally correct.

Community Detection

Communities identify:

- Clusters of dense ties
- Functional groupings
- Latent structure

Algorithms impose assumptions about structure.

Statistical Network Models

Statistical models treat networks as outcomes:

- Ties are random variables
- Structure is explained, not assumed
- Dependence is explicit

ERGMs (Local Dependence)

```
# PSEUDOCODE: Exponential Random Graph Model (ERGM)

initialize theta
repeat until convergence:
    propose Y_prime
    delta_g = g(Y_prime) - g(Y_observed)
    accept Y_prime with prob min(1, exp(theta + delta_g))
    update theta

return theta
```

ERGMs explain why certain *local configurations* appear.

AME Models (Latent Structure)

```
# PSEUDOCODE: Additive-Multiplicative Effects (AME)
```

```
for each dyad (i, j):
    y_ij = X_ij beta + a_i + b_j + u_i' v_j + error

initialize beta, a, b, u, v
repeat until convergence:
    update beta
    update a_i and b_j
    update latent positions u_i, v_j

return beta, latent_positions
```

AMEs capture unobserved dependence with low-rank geometry.

Diffusion Models

```
# PSEUDOCODE: Network Diffusion / Event History
```

```
for time t:  
    for actor i:  
        exposure_i = sum_j w_ij * events_j(t-1)  
        hazard_i = f(exposure_i, covariates_i, baseline_t)  
        if random_draw < hazard_i:  
            events_i(t) = 1
```

Diffusion models make time and exposure explicit.

Graph Neural Networks (GNNs)

```
# PSEUDOCODE: Graph Neural Network (Message Passing)

initialize h_i^0 = X_i

for layer l in 1:L:
    for node i:
        messages = aggregate(h_j^(l-1) for j in neighbors(i))
        h_i^l = update(h_i^(l-1), messages)

use h_i^L for prediction
```

GNNs learn representations optimized for prediction.

Model Comparison

ERGMs:

- Explain local structure
- Interpretable parameters
- Scale poorly

AMEs:

- Explain latent dependence
- Scalable, interpretable geometry

Diffusion models:

- Explain temporal contagion
- Causal intuition

GNNs:

- Optimize prediction
- Limited interpretability

Validation in Network Analysis

Validation challenges include:

- Dependence across observations
- Overfitting structure
- Temporal instability

Out-of-sample checks are essential.

What We Emphasize in Practice

- Start with clear representations
- Match models to questions
- Be explicit about dependence
- Validate aggressively

Discussion

- Which network choices feel most consequential?
- When do black-box models make sense?
- How should uncertainty be communicated?