## Robert Mattila

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rmattila.github.io

I am a Ph.D. student whose research concerns learning and controlling stochastic dynamical systems. My interests are in machine learning, data analytics and their future applications in real-world scenarios – for example, in next-generation health-care.

#### Research Interests

- Identification, control and inference in stochastic dynamical systems
- Hidden Markov models and (partially observed) Markov decision processes
- Machine learning and optimization

#### Education

## KTH Royal Institute of Technology

Stockholm, Sweden

Ph.D., Department of Automatic Control

2015 - 2020 (Projected)

- Supervisors: Prof. Bo Wahlberg and Assoc. Prof Cristian R. Rojas.
- Topic: Markovian models: Learning, control and application.

## KTH Royal Institute of Technology

Stockholm, Sweden

Licentiate Degree. Department of Automatic Control

March, 2018

- Title: Hidden Markov models: Identification, control and inverse filtering.
- Opponent: **Prof. Eric Moulines** of Ecole Polytechnique (Paris, France).

#### KTH Royal Institute of Technology

Stockholm, Sweden

B.Sc. Engineering Physics, M.Sc. Systems, Control and Robotics

2010 - 2015

- The Swedish degree of Civilingenjör i Teknisk Fysik.
- Graduated in 4.5 years, instead of nominal 5 years.
- B.Sc. GPA of 4.98/5.0 and M.Sc. GPA of 5.0/5.0 .

# UCM, Universidad Cumplutense de Madrid

Madrid, Spain

ERASMUS Exchange studies

Spring 2013

- All (five) courses taken were taught in Spanish (including reading material).
- GPA of 8.13/10.0.

## THG, Thorildsplans gymnasium

Stockholm, Sweden

Natural Sciences with specialization on Mathemathics and Computer Science

2007 - 2010

#### Ph.D. Courses

- Partially observed Markov decision processes
- Game theory
- Mathematical methods in signals, systems and control

- Bayesian networks
- Hybrid systems (stability, stabilization, abstraction and formal verification)
- Probabilistic verification and synthesis
- Matrix algebra
- Probability and random processes
- Convex optimization
- Stochastic control and optimization
- Deep learning in data science (attended lectures)
- Optimal filtering (attended lectures)

#### Skills. Merits and Awards

• Computer Skills:

Programming: Matlab, Python, Julia, Java Operating Systems: OSX, Linux, Windows

Other: LATEX, git

• Languages: Swedish (native), English (fluent) and Spanish (intermediate).

#### • Awards:

- Awarded Jubilee Appropriation from the Knut and Alice Wallenberg foundation in 2018.
- Awarded the KTH Electrical Engineering Scholarship of Excellence (1 MSEK) in 2015.
- Awarded travel scholarship from the Borgquist Foundation in 2015.
- Awarded a SURF scholarship from Caltech to work with Prof. Richard Murray in 2014.
- Awarded the Henrik Göransson's Sandviken Scholarship and the KTH Student Scholarship (twice) for outstanding grades during B.Sc. and M.Sc. studies.
- Participated in the final of Wallenbergs Fysikpris 2010 (Swedish qualifications for the International Physics Olympiad).
- Awarded scholarship for outstanding grades when graduating from THG.

#### • Reviewer for:

- IFAC American Control Conference (ACC),
- IFAC Automatica journal,
- IEEE Conference on Decision and Control (CDC),
- ACL Conference on Learning Theory (COLT),
- IEEE Signal Processing Letters (SPL).
- KIBok (www.kibok.se): A website for buying and selling used medical textbooks, aimed for students at the Karolinska Institute. The website was developed using Python and Django, and has been running since 2013.
- Hold a Swedish driver's license (B).

## Teaching

## EL2805 Reinforcement Learning

KTH

Teaching assistant, 120 students

Autumn 2018

Bachelor Thesis

KTH

Supervisor of two projects on inverse Markowitz portfolio optimization:

Spring 2018

- Portfolio Optimization with Market State Analysis by Ossian Krödel and Rasmus Jerndal.
- Portfolio Inversion: Finding Market State Probabilities from Optimal Portfolios by Gustav Ekman and Fredrik Rubin.

### EL2800 Stochastic Control and Optimization

KTH

Teaching assistant

Autumn 2017

Master Thesis

KTH

Supervisor of:

Spring 2017

 Optimal Input Design by Model Predictive Control for System Identification by Daniel Merkoulova

## EL1000 Automatic Control

KTH

Teaching assistant

Autumn 2016

EH1010 Project Course in Electrical Engineering

KTH

Supervisor

Spring 2016

EL1000 Automatic Control

KTH

Teaching assistant

Autumn 2015

### **Publications**

#### **Journals**

• Robert Mattila, Cristian R. Rojas, Vikram Krishnamurthy, and Bo Wahlberg. Asymptotically efficient identification of known-sensor hidden Markov models. *IEEE Signal Processing Letters*, 24(12):1813–1817, 2017.

#### Conferences

- Robert Mattila, Cristian R. Rojas, Vikram Krishnamurthy, and Bo Wahlberg. Inverse filtering for linear Gaussian state-space systems. In *Proceedings of the 57th IEEE Conference on Decision and Control (CDC'18)*, 2018.
- Roberto G. Ramírez-Chavarría, Gustavo Quintana-Carapia, Matias I. Müller, Robert Mattila, Daniel Matatagui, Celia Sánchez-Pérez, Bioimpedance parameter estimation using fast spectral measurements and regularization. In *Proceedings of the 18th IFAC Symposium on System Identification (SYSID'18)*, 2018.
- Robert Mattila, Cristian R. Rojas, Vikram Krishnamurthy, and Bo Wahlberg. Inverse filtering for hidden Markov models. In *Advances in Neural Information Processing Systems (NIPS'17)*, pages 4207–4216, 2017.

- Robert Mattila, Cristian R. Rojas, Vikram Krishnamurthy, and Bo Wahlberg. Identification of hidden Markov models using spectral learning with likelihood maximization. In *Proceedings of the 56th IEEE Conference on Decision and Control (CDC'17)*, pages 5859–5864, 2017.
- Antti Siika, Robert Mattila, Bo Wahlberg, and Joy Roy. An optimal gender- specific treatment policy for abdominal aortic aneurysms constructed using a Markov decision process model. *Journal of Vascular Surgery*, 65(6, Supplement):175S, 2017. Abstracts of the 2017 Vascular Annual Meeting (VAM'17).
- Robert Mattila, Cristian R. Rojas, Vikram Krishnamurthy, and Bo Wahlberg. Computing monotone policies for Markov decision processes: a nearly-isotonic penalty approach. In *Proceedings* of the 20th IFAC World Congress, volume 50, pages 8429 8434, 2017.
- Robert Mattila, Antti Siika, Joy Roy, and Bo Wahlberg. A Markov decision process model to guide treatment of abdominal aortic aneurysms. In *Proceedings of the IEEE Conference on Control* Applications (CCA'16), pages 436–441, 2016.
- Robert Mattila, Vikram Krishnamurthy, and Bo Wahlberg. Recursive identification of chain dynamics in hidden Markov models using non-negative matrix factorization. In *Proceedings of the 54th IEEE Conference on Decision and Control (CDC'15)*, pages 4011–4016, 2015.
- Robert Mattila, Yilin Mo, and Richard M. Murray. An iterative abstraction algorithm for reactive correct-by-construction controller synthesis. In *Proceedings of the 54th IEEE Conference on Decision and Control (CDC'15)*, pages 6147–6152, 2015.
- Robert Mattila, Cristian R. Rojas, and Bo Wahlberg. Evaluation of spectral learning for the identification of hidden Markov models. *Proceedings of the 17th IFAC Symposium on System Identification (SYSID'15)*, 48(28):897–902, 2015.

#### Theses

- Robert Mattila, *Hidden Markov models: Identification, control and inverse filtering*. Licentiate thesis, KTH Royal Institute of Technology. Stockholm, Sweden, 2018. Supervisors: Prof. Bo Wahlberg and Assoc. Prof. Cristian R. Rojas.
- Robert Mattila, On Identification of Hidden Markov Models Using Spectral and Non-Negative Matrix Factorization Methods. Master's thesis, KTH Royal Institute of Technology. Stockholm, Sweden, 2015. Supervisors: Prof. Bo Wahlberg and Assoc. Prof. Cristian R. Rojas.
- Robert Mattila, *Including Bathymetric Data in Autonomous Surface Vessels' Maneuvering Optimisation Tool.* Bachelor's thesis, KTH Royal Institute of Technology, Stockholm, and Universidad Cumplutense de Madrid (UCM), 2013. Supervisors: Prof. Juan Jiménez and José María Benítez.

#### Other

- Robert Mattila, Cristian R. Rojas, Vikram Krishnamurthy and Bo Wahlberg, *Method of Moments for Learning Hidden Markov models*. Poster at the 2018 Workshop of the European Research Network on System Identification (ERNSI), September, Cambridge, UK.
- Robert Mattila, Cristian R. Rojas, Vikram Krishnamurthy and Bo Wahlberg, *Inverse Filtering for Linear Gaussian State-Space Models*. Presentation at the 2018 Swedish Control Conference (Reglermötet), June, Stockholm, Sweden.

- Robert Mattila, Cristian R. Rojas, Vikram Krishnamurthy and Bo Wahlberg, *Inverse Filtering for Hidden Markov Models*. Poster at the 2018 WASP AI4X Industry, February, Stockholm, Sweden.
- Robert Mattila, Cristian R. Rojas, Vikram Krishnamurthy and Bo Wahlberg, *Inverse Filtering for Hidden Markov Models*. Poster at the 2017 Workshop of the European Research Network on System Identification (ERNSI), September, Lyon, France.
- Robert Mattila, Cristian R. Rojas, Vikram Krishnamurthy and Bo Wahlberg, Method of Moments Identification of Hidden Markov Models with Known Sensor Uncertainty Using Convex Optimization. Poster at the 2016 Workshop of the European Research Network on System Identification (ERNSI), September, Cison di Valmarino, Italy.
- Robert Mattila, Cristian R. Rojas, Vikram Krishnamurthy and Bo Wahlberg, Method of Moments Identification of Hidden Markov Models with Known Sensor Uncertainty Using Convex Optimization. Poster at Reglermötet 2016, June, Göteborg, Sweden.
- Robert Mattila, Vikram Krishnamurthy and Bo Wahlberg, Recursive Method of Moments Identification of Hidden Markov Models using Convex Optimization. Poster at the 2015 Workshop of the European Research Network on System Identification (ERNSI), September, Varberg, Sweden.

# Academic Experience

IFAC Symposium on System Identification (SYSID'18)

Stockholm, Sweden

Volunteer in the organizing crew

Summer 2018

Cornell Tech, Cornell University

Manhattan, USA

Invited researcher by Prof. Vikram Krishnamurthy

Summer 2017

- Worked on inverse problems for Bayesian optimal filters.

# VUB-ELEC, Workshop on System Identification

Included courses on

Brussels, Belgium
Summer 2017

 Frequency response function measurements (non-parametric tools), dynamic system identification (parametric tools) and control-oriented system identification by, among others, John Lataire, Yves Rolain, Rik Pintelon, Ivan Markovsky, Philippe Dreesen and Simone Formentin

# S<sup>3</sup>CS, Swedish Summer School in Computer Science

Djurö, Sweden Summer 2016

The courses were taught by

- Michael Mitzenmacher (Hashing Algorithms);

- Sergei Vassilvitskii (Algorithms for Modern Parallel Systems).

## UBC, University of British Columbia

Vancouver, Canada

Invited researcher by Prof. Vikram Krishnamurthy

Summer 2015

- Worked on method of moments for hidden Markov models.

## UBC, University of British Columbia

Vancouver, Canada

Master thesis with Prof. Vikram Krishnamurthy

Autumn 2014 Pasadena, USA

# Caltech, California Institute of Technology

a and a

SURF in the Control and Dynamical Systems (CDS) group

Summer 2014

- Supervisors: Prof. Richard M. Murray and Asst. Prof. Yilin Mo
- Developed an improved abstraction algorithm for the correct-by-construction controller synthesis framework TuLiP (implemented in Python).

KTH, Royal Institute of Technology

Research intern for Prof. Bo Wahlberg

ZJU, Zhejiang University

Participated in the Joint Research Center of Photonics Workshop

- Implemented optical logic gates exploiting non-linearities in fibers.

Stockholm, Sweden Summer 2013 Hangzhou, China Summer, 2012

# **Industry Experience**

Stockholm Vatten AB

Summer intern

Stockholm Vatten AB

Summer intern

Stockholm, Sweden  $Summer\ 2012$ 

Stockholm, Sweden  $Summer\ 2011$ 

- Warehouse work including: collecting and delivering items; cleaning and repairing machines; contacting customers; administrative work in the supply system Agresso.