Robert Mattila

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Research Interests

- Identification, control and inference in stochastic dynamical systems
- Hidden Markov models and (partially observed) Markov decision processes
- Machine learning and optimization

Education

KTH Royal Institute of Technology

Stockholm, Sweden

PhD, Department of Automatic Control

2015 - 2020 (Projected)

- Supervisors: Prof. Bo Wahlberg and Assoc. Prof Cristian R. Rojas.
- Topic: Identification and control of hidden Markov models.

KTH Royal Institute of Technology

Stockholm, Sweden

B.Sc. Engineering Physics, M.Sc. Systems, Control and Robotics

2010 - 2015

- The Swedish degree of Civilingenjör i Teknisk Fysik.
- The graduation date was one semester earlier than nominal time.
- B.Sc. GPA of 4.98/5.0 and M.Sc. GPA of 5.0/5.0 .

UCM, Universidad Cumplutense de Madrid

Madrid, Spain

ERASMUS Exchange studies

Spring 2013

- All (five) courses taken were taught in Spanish (including reading material).
- GPA of 8.13/10.0.

THG, Thorildsplans gymnasium

Stockholm, Sweden

Natural Sciences with specialization on Mathemathics and Computer Science

2007 - 2010

Skills, Merits and Awards

• Computer Skills:

Programming: Matlab, Python, Julia, Java Operating Systems: OSX, Linux, Windows

Other: LAT_EX, git

• Languages: Native in Swedish, fluent in English and proficient (B2) in Spanish

• Awards:

- Awarded the KTH Electrical Engineering Scholarship of Excellence (1 MSEK) in 2015.
- Awarded a SURF scholarship from Caltech to work with Prof. Richard Murray in 2014.

- Awarded the Henrik Göransson's Sandviken Scholarship and the KTH Student Scholarship (twice) for outstanding grades.
- Participated in Wallenbergs Fysikpris 2010 (Swedish qualifications for the International Physics Olympiad). Reached the final with the best result amongst all participants from Stockholm (in the qualification round) and placed 7th in the final.
- Awarded scholarship for outstanding grades when graduating from THG.
- Reviewer for the IEEE Conference on Decision and Control (CDC), the IFAC American Control Conference (ACC) and the IFAC Automatica journal.
- **KIBok** (www.kibok.se): Have founded and developed a marketplace for used textbooks for students of Karolinska Institutet. The environment used is Python with Django.
- Hold a Swedish driver's license (B).

Publications

Journals

• Robert Mattila, Cristian. R. Rojas, Vikram. Krishnamurthy, and Bo Wahlberg, Asymptotically Efficient Identification of Known-Sensor Hidden Markov Models. IEEE Signal Processing Letters, 2017, 24.12: 1813-1817.

Conferences

- Robert Mattila, Cristian R. Rojas, Vikram Krishnamurthy and Bo Wahlberg, Inverse Filtering for Hidden Markov Models. In the 31st Annual Conference on Neural Information Processing Systems (NIPS'17), Long Beach, USA, 2017.
- Robert Mattila, Cristian R. Rojas, Vikram Krishnamurthy and Bo Wahlberg, *Identification of Hidden Markov Models Using Spectral Learning with Likelihood Maximization*. In the 56th IEEE Conference on Decision and Control (CDC'17), Melbourne, Australia, 2017.
- Antti Siika, Robert Mattila, Bo Wahlberg and Joy Roy. An Optimal Gender-Specific Treatment Policy for Abdominal Artic Aneurysms Constructed Using a Markov Decision Process Model. In the Society for Vascular Surgery's Vascular Annual Meeting (VAM'17), San Diego, USA, 2017.
- Robert Mattila, Cristian R. Rojas, Vikram Krishnamurthy, Bo Wahlberg, Computing monotone policies for Markov decision processes: a nearly-isotonic penalty approach. In the 20th IFAC World Congress, Toulouse, France, 2017.
- Robert Mattila, Antti Siika, Joy Roy and Bo Wahlberg, A Markov Decision Process Model to Guide Treatment of Abdominal Aortic Aneurysms. In the IEEE Conference on Control Applications (CCA'16), Buenos Aires, Argentina, 2016.
- Robert Mattila, Vikram Krishnamurthy and Bo Wahlberg, Recursive Identification of Chain Dynamics in Hidden Markov Models Using Non-Negative Matrix Factorization. In 54th IEEE Conference on Decision and Control (CDC'15), Osaka, Japan, 2015.
- Robert Mattila, Yilin Mo and Richard M. Murray, An Iterative Abstraction Algorithm for Reactive Correct-by-Construction Controller Synthesis. In 54th IEEE Conference on Decision and Control (CDC'15), Osaka, Japan, 2015.

• Robert Mattila, Cristian R. Rojas and Bo Wahlberg, Evaluation of Spectral Learning for the Identification of Hidden Markov Models. In 17th IFAC Symposium on System Identification (SYSID'15), Beijing, China, 2015.

Other

- Robert Mattila, Cristian R. Rojas, Vikram Krishnamurthy and Bo Wahlberg, Inverse Filtering for Hidden Markov Models. Poster at the 2017 Workshop of the European Research Network on System Identification (ERNSI), September, Lyon, France.
- Robert Mattila, Cristian R. Rojas, Vikram Krishnamurthy and Bo Wahlberg, Method of Moments Identification of Hidden Markov Models with Known Sensor Uncertainty Using Convex Optimization. Poster at the 2016 Workshop of the European Research Network on System Identification (ERNSI), September, Cison di Valmarino, Italy.
- Robert Mattila, Cristian R. Rojas, Vikram Krishnamurthy and Bo Wahlberg, Method of Moments Identification of Hidden Markov Models with Known Sensor Uncertainty Using Convex Optimization. Poster at Reglermötet 2016, June, Göteborg, Sweden.
- Robert Mattila, Vikram Krishnamurthy and Bo Wahlberg, Recursive Method of Moments Identification of Hidden Markov Models using Convex Optimization. Poster at the 2015 Workshop of the European Research Network on System Identification (ERNSI), September, Varberg, Sweden.
- Robert Mattila, On Identification of Hidden Markov Models Using Spectral and Non-Negative Matrix Factorization Methods. Master's thesis, KTH Royal Institute of Technology. Stockholm, Sweden, 2015. Supervisors: Prof. Bo Wahlberg and Assoc. Prof. Cristian R. Rojas.
- Robert Mattila, Including Bathymetric Data in Autonomous Surface Vessels' Maneuvering Optimisation Tool. Bachelor's thesis, KTH Royal Institute of Technology. Stockholm, Sweden, 2015. Supervisors: Prof. Juan Jiménez and José María Benítez.

Academic Experience

Cornell Tech, Cornell University

Invited researcher by Prof. Vikram Krishnamurthy

VUB-ELEC, Workshop on System Identification

Included courses on

Manhattan, USA Summer 2017

Brussels, Belgium Summer 2017

- Frequency response function measurements (non-parametric tools), dynamic system identification (parametric tools) and control-oriented system identification by, among others, John Lataire, Yves Rolain, Rik Pintelon, Ivan Markovsky, Philippe Dreesen and Simone Formentin.

S³CS, Swedish Summer School in Computer Science

The courses were taught bu

Djurö, Sweden Summer 2016

- Michael Mitzenmacher (Hashing Algorithms);
- Sergei Vassilvitskii (Algorithms for Modern Parallel Systems).

UBC, University of British Columbia

Invited researcher by Prof. Vikram Krishnamurthy

UBC, University of British Columbia

Master thesis with Prof. Vikram Krishnamurthy

Vancouver, Canada Summer 2015

Vancouver, Canada Autumn 2014

Caltech, California Institute of Technology

SURF in the Control and Dynamical Systems (CDS) group

Pasadena, USA Summer 2014

- Supervisors: Prof. Richard M. Murray and Asst. Prof. Yilin Mo
- Developed an improved abstraction algorithm for the correct-by-construction controller synthesis framework TuLiP (implemented in Python).

KTH, Royal Institute of Technology

Stockholm, Sweden

Research intern for Prof. Bo Wahlberg

Summer 2013

ZJU, Zhejiang University

Hangzhou, China

Participated in the Joint Research Center of Photonics Workshop

Summer, 2012

- Implemented optical logic gates exploiting non-linearities in fibers.

Industry Experience

Stockholm Vatten AB

Stockholm, Sweden

Summer intern

Summer 2011 and 2012

- Warehouse work including collecting and delivering items; cleaning and repairing machines; contacting customers; administrative work in the supply system Agresso.

Teaching

•	EL2800 Stochastic Control and Optimization	KTH
	Teaching assistant	Autumn~2017
•	Master Thesis	KTH
	Supervisor for Daniel Merkoulova	Spring 2017
•	EL1000 Automatic Control	KTH
	Teaching assistant	$Autumn\ 2016$
•	EH1010 Project Course in Electrical Engineering	KTH
	Supervisor	Spring 2016
•	EL1000 Automatic Control	KTH
	Teaching assistant	$Autumn\ 2015$

PhD Courses

- Partially observed Markov decision processes
- Game theory
- Mathematical methods in signals, systems and control
- Bayesian networks
- Hybrid systems (stability, stabilization, abstraction and formal verification)
- Probabilistic verification and synthesis
- Matrix algebra
- Probability and random processes
- Convex optimization
- Stochastic control and optimization
- Deep learning in data science (attended lectures)