

Collisions Lab Report

AP Physics B Block — Lab #3

Ryan McCrystal

January 22, 2020

Contents

1	Approach	4
1.1	Elastic Collisions	5
1.2	Inelastic Collisions	6
1.3	Recoil	7
2	Calculations	8
2.1	Derivation of Equations	8
2.1.1	Elastic Collisions	8
2.1.2	Inelastic Collisions	8
2.1.3	Recoil	8
2.2	Example Calculations	9
2.2.1	Elastic Collisions With Springs	9
2.2.2	Elastic Collisions With Magnets	9
2.2.3	Inelastic Collisions With Springs	9
2.2.4	Inelastic Collisions Without Springs	10
2.2.5	Inelastic Collisions With Magnets	10
2.2.6	Recoil	10
3	Results and Conclusions	11
A	Appendix	14
A.1	Elastic Collisions With Springs	14
A.2	Elastic Collisions With Magnets	14
A.3	Inelastic Collisions With Springs	15
A.4	Inelastic Collisions Without Springs	15
A.5	Inelastic Collisions With Magnets	16
A.6	Recoil	16

Abstract

The purpose of this experiment is to determine the weight of a glider on a frictionless airtrack and the most accurate method for doing so. To do this, a frictionless air track, a large metal track with many small holes which were pumped with compressed air was used. On this airtrack, two gliders were placed which had virtually no friction because they were floating on a small cushion of air. The airtrack was set up with two photogates measuring the speeds of the two gliders before and after a collision between them. Our setups consisted of an inelastic collision with springs, without springs, and with magnets, an elastic collision with magnets and with springs, and two gliders recoiling off of each other with magnets. Due to the (assumed) conservation of momentum in these collisions, the conservation of momentum equation was used to calculate the mass of the second glider given the mass of the first glider which we measured before conducting the experiment. Assumptions other than ideal conservation of momentum include negligible friction and constant velocities for both gliders. After conducting all of the trials, we determined that the most accurate method was the elastic collision using springs method with a percent inaccuracy of only 0.09%.

1 Approach

In the experiment, a frictionless air track, two photogates, a timer for the photogates, and two gliders setup to emulate certain types of collisions were used. A frictionless airtrack is a triangular prism with many small holes in it releasing pressured air created by a pump. This air slightly levitated each glider to reduce the friction between the glider and the track as much as possible. On the air track, two photogates were positioned which connected to the timer which displayed the velocities it recorded. These photogates had an LED and a light sensor which could measure the time something was passed through it. On each glider, there was a small flag which would pass through the photogate. The photogate would find the time the led was covered for by the flag and using that information it could determine the speed of said glider. Before we began the experiment, the track was leveled by turning on the pump, placing a glider on the track, and adjusting the hight of each side of the track to reduce the force of gravity on the glider as much as possible. The glider setup was slightly modified to emulate the type of collision for each trial. The respective setups are shown below.

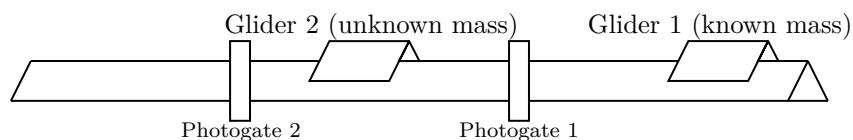


Figure 1: The General Setup

1.1 Elastic Collisions

In this method, the two gliders were setup to undergo an elastic collision. In one setup, the magnets were attached to the gliders which would repel each other to emulate an elastic collision and the other setup, springs were attached to each glider to also emulate an elastic collision. Two different methods were used to determine which method was the most accurate. Glider 2 was held stationary on the track and glider 1 was pushed through the first photogate where it then maintained a constant speed until colliding with glider 2. Upon collision, glider 1 would bounce back and go through photogate 1 and glider 2 would pass through photogate 2. Using this data and the mass of glider 1 which varied with springs and magnets, the mass of glider 2 could be calculated.

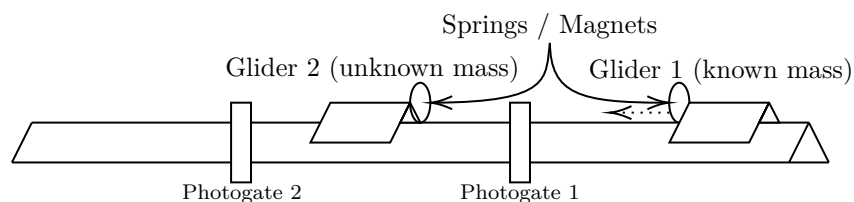


Figure 2a: Elastic Collision Setup

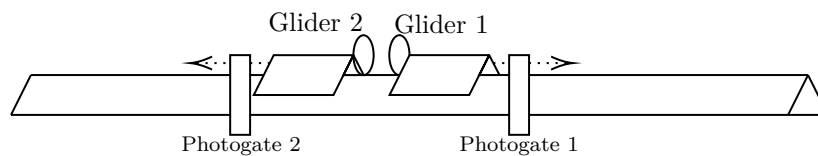


Figure 2b: Elastic Collision Setup (Post Collision)

1.2 Inelastic Collisions

In this method, the two gliders were configured to undergo an inelastic collision. In one setup, velcro was attached to the springs to ensure the two gliders would not separate after they collided, in another velcro was attached to the glider itself, and in the third, magnets were situated on each glider to attract each other. Similar to the elastic collision setup, glider 2 was held stationary on the track and glider 1 was pushed through the first photogate where it maintained a constant speed until colliding with glider 2. After the collision, the two gliders would stick together and pass through the second photogate at a reduced speed. Using this data and the mass of glider 1 which varied with velcro with springs, velcro, and with magnets, the mass of glider 2 could be calculated.

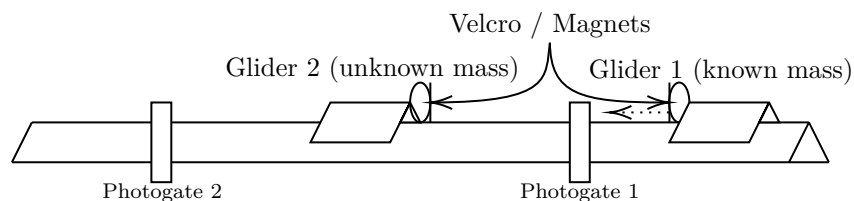


Figure 3a: Inelastic Collision Setup

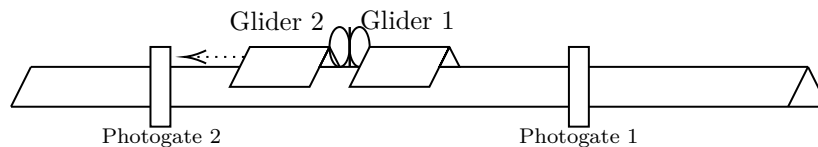


Figure 3b: Inelastic Collision Setup (Post Collision)

1.3 Recoil

In this last method, two magnets which repelled each other were installed on each glider. These two gliders were held close together to allow a sufficient speed through the photogates, but not too close so they wouldn't fly off the track. After releasing the two gliders, they repelled off each other where they would go through both photogates. The mass of glider 2 would then be calculated using the speed of each glider after they repelled each other and the mass of glider 1.

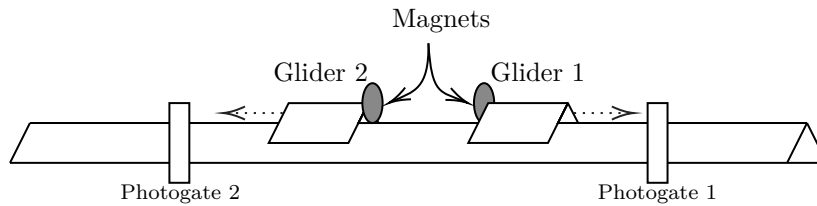


Figure 4: Recoil Setup

For each method, 5 trials were conducted to get as accurate of measurements as possible and to determine how inaccurate each method was. Because the photogates measure speed and not velocity, the velocities were adjusted to match the direction the gliders were moving. To calculate the mass of glider 2, the conservation of momentum equation ($m_1v_1 + m_2v_2 = m_1v'_1 + m_2v'_2$) was used.

2 Calculations

The full set of data can be found in the appendix.

2.1 Derivation of Equations

2.1.1 Elastic Collisions

$$\begin{aligned}
 m_a v_a + \cancel{m_b v_b} &\stackrel{0}{=} m_a v'_a + m_b v'_b && \text{Conservation of Momentum} \\
 m_b v'_b &= m_a v_a - m_a v'_a \\
 m_b v'_b &= m_a (v_a - v'_a) \\
 m_b &= \frac{m_a (v_a - v'_a)}{v'_b}
 \end{aligned} \tag{1}$$

2.1.2 Inelastic Collisions

$$\begin{aligned}
 m_a v_a + \cancel{m_b v_b} &\stackrel{0}{=} m_a v'_a + m_b v'_b && \text{Conservation of Momentum} \\
 m_a v_a &= m_a v' + m_b v' && \text{note: } v'_a = v'_b \\
 m_b v' &= m_a v_a - m_a v' \\
 m_b v' &= m_a (v_a - v') \\
 m_b &= \frac{m_a (v_a - v')}{v'}
 \end{aligned} \tag{2}$$

2.1.3 Recoil

$$\begin{aligned}
 \cancel{m_a v_a} + \cancel{m_b v_b} &\stackrel{0}{=} m_a v'_a + m_b v'_b && \text{Conservation of Momentum} \\
 m_b v'_b &= -m_a v'_a \\
 m_b &= \frac{-m_a v'_a}{v'_b}
 \end{aligned} \tag{3}$$

2.2 Example Calculations

2.2.1 Elastic Collisions With Springs

$$\begin{aligned} m_b &= \frac{m_a(v_a - v'_a)}{v'_b} \\ &= \frac{189.4g(16.2\frac{cm}{s} - (-3.8\frac{cm}{s}))}{11.1\frac{cm}{s}} \\ &= 341.26g \rightarrow 341.3g \end{aligned} \tag{4}$$

2.2.2 Elastic Collisions With Magnets

$$\begin{aligned} m_b &= \frac{m_a(v_a - v'_a)}{v'_b} \\ &= \frac{225.5g(46.9\frac{cm}{s} - (-9.5\frac{cm}{s}))}{28.2\frac{cm}{s}} \\ &= 451.0g \end{aligned} \tag{5}$$

2.2.3 Inelastic Collisions With Springs

$$\begin{aligned} m_b &= \frac{m_a(v_a - v')}{v'} \\ &= \frac{189.4g(21.5\frac{cm}{s} - 8\frac{cm}{s})}{8\frac{cm}{s}} \\ &= 319.61g \rightarrow 319.6g \end{aligned} \tag{6}$$

2.2.4 Inelastic Collisions Without Springs

$$\begin{aligned}m_b &= \frac{m_a(v_a - v')}{v'} \\&= \frac{193.5g(20.2\frac{cm}{s} - 5.6\frac{cm}{s})}{5.6\frac{cm}{s}} \\&= 504.48g \rightarrow 504.5g\end{aligned}\tag{7}$$

2.2.5 Inelastic Collisions With Magnets

$$\begin{aligned}m_b &= \frac{m_a(v_a - v')}{v'} \\&= \frac{225.5g(26.9\frac{cm}{s} - 10.4\frac{cm}{s})}{10.4\frac{cm}{s}} \\&= 357.76g \rightarrow 357.8g\end{aligned}\tag{8}$$

2.2.6 Recoil

$$\begin{aligned}m_b &= \frac{-m_a v'_a}{v'_b} \\&= \frac{-(225.5g)(-21.1\frac{cm}{s})}{9.5\frac{cm}{s}} \\&= 500.85g \rightarrow 500.8g\end{aligned}\tag{9}$$

3 Results and Conclusions

The most accurate method was the method with elastic collisions with springs. This method produced a mass of B of $340.4g$, only 0.09% off from the actual mass of B: $340.1g$. The second most accurate method was the inelastic collision with springs, followed by the inelastic collision with magnets, the inelastic collision without springs, the recoil method, and the least accurate method was the elastic collision with magnets.

Each method had its own uncertainties of varying magnitude due to different reasons. Although the most accurate method, the elastic collision with springs almost perfectly emulated an ideal elastic collision, a very small amount of energy could be lost due to friction between the two springs. Despite this, the method was by far the most accurate because the springs could store the kinetic energy and release almost exactly the same amount.

The least accurate method was the elastic collision with magnets with an uncertainty of 40.9% . This inaccuracy was likely caused by external forces caused by the magnetic attraction of the gliders. When the glider was placed on the track, it seemed to have a constant force going one direction. Another possible reason for this external force is the glider being weighed down on one side because of the weight of the magnet. This would cause the air from the airtrack to shoot out one direction, and the fact that the glider moved towards the side the magnet was not on reinforces this. To mitigate this, a weight of similar weight to the magnets could be installed on the other side

of the glider in order to balance it out. The other method with magnets, the inelastic collision with magnets method, had a difference of 11.1%.

The inelastic collision with velcro and springs method had a difference of only 3.5%, only slightly more inaccurate than the previous method. The velcro held the two carts together so the collision would be inelastic and the springs would help reduce the energy loss due to friction by dampening the collision. When the springs were removed and the velcro was placed directly on the glider, the inaccuracy increased to 29.3%. This was because the springs were not there anymore to dampen the collision and significantly more energy was lost due to friction in the velcro, as all of the energy had to travel through that.

The recoil method had a difference of 25.6%. When we released the two gliders after them being held together, we noticed that the two gliders were lifted off the track which we had to compensate for by increasing the distance between the gliders. Although this effect was much less noticeable after increasing the distance, it was still there which could be a source for uncertainty. Another source of uncertainty is the external forces that the magnets create described above.

In conclusion, the most accurate method was the elastic collision with springs method. As said before, the springs provided very little friction and could store the kinetic energy during the collision extremely efficiently. After conducting five trials with this method, it produced a result of $340.4g$, only $0.3g$ off from the actual mass of the glider: $340.1g$. Although this remains

the most accurate method, the closeness of the produced result to the actual weight could have been due to mere chance as the results for each trial varied up to 2.2% from the average. Taking more trials with this method could further determine exactly how accurate it is.

A Appendix

A.1 Elastic Collisions With Springs

Mass of A = 189.4g

Average mass of B = 340.4g

Actual mass of B = 340.1g

Percent Difference = 0.09%

Trial	V_a (cm/s)	V'_b (cm/s)	V'_a (cm/s)	Mass of B (g)
1	16.2	11.1	-3.8	341.3
2	24.9	17.6	-6.1	333.6
3	36.9	25.1	-9.2	347.9
4	25.9	18.1	-6.3	336.9
5	30.7	21.2	-7.6	342.2

A.2 Elastic Collisions With Magnets

Mass of A = 225.5g

Average mass of B = 581.3g

Actual mass of B = 343.2g

Percent Difference = 40.9%

Trial	V_a (cm/s)	V'_b (cm/s)	V'_a (cm/s)	Mass of B (g)
1	46.9	28.2	-9.5	451.0
2	54	18.9	-13.3	803.0
3	47.9	21.3	-12.1	635.2
4	44.2	24.2	-9.7	502.3
5	41.1	22.6	-10.5	514.9

A.3 Inelastic Collisions With Springs

Mass of A = 189.4g

Average mass of B = 352.4g

Actual mass of B = 340.1g

Percent Difference = 3.5%

Trial	V_a (cm/s)	V' (cm/s)	Mass of B (g)
1	21.5	8	319.6
2	33.7	11.7	356.1
3	44	14.7	377.5
4	15.6	5.5	347.8
5	31.1	10.7	361.1

A.4 Inelastic Collisions Without Springs

Mass of A = 193.5g

Average mass of B = 450.5g

Actual mass of B = 343.1g

Percent Difference = 23.8%

Trial	V_a (cm/s)	V' (cm/s)	Mass of B (g)
1	20.2	5.6	504.5
2	23.8	7.4	428.8
3	23.2	7.4	413.1
4	24.4	7.3	453.3
5	29.4	8.8	453.0

A.5 Inelastic Collisions With Magnets

Mass of A = 225.5g

Average mass of B = 385.7g

Actual mass of B = 343.1g

Percent Difference = 11.1%

Trial	V_a (cm/s)	V' (cm/s)	Mass of B (g)
1	26.9	10.4	357.8
2	28.4	9.8	428.0
3	26.3	10.7	328.8
4	30.4	11.6	365.5
5	27.8	9.3	448.6

A.6 Recoil

Mass of A = 225.5g

Average mass of B = 504.1g

Actual mass of B = 375.2g

Percent Difference = 25.6%

Trial	$V_{a'}$ (cm/s)	$V_{b'}$ (cm/s)	Mass of B (g)
1	-21.1	9.5	500.8
2	-20.7	6.5	718.1
3	-22.1	12.5	398.7
4	-24.6	14.8	374.8
5	-21.3	9.1	527.8