Rotman

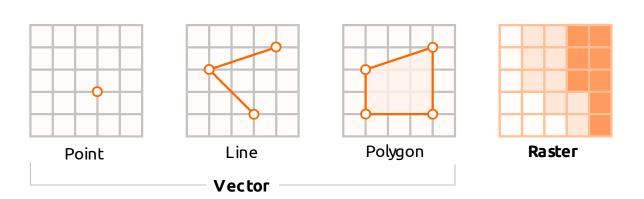
INTRO TO DATA VISUALIZATION

Part II Plotting Maps with GeoPandas & Matplotlib



Spatial Data

- A spatial dataset is a combination of...
 - location data and spatial dimensions (the where)
 - attribute data (the what)
- Two most common forms of spatial data
 - Vector
 - Raster



Source/Ref: Introduction to (Q)GIS by Jeff Allen

Vector Data

 Use geographic coordinates, or a series of coordinates, to create points, lines, and polygons representing real-world features

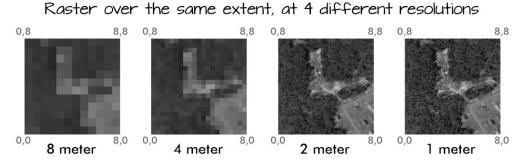
- Two most common vector data format
 - GeoJSON (a plain text file; .geojson, .json)
 - Shapefile (3 mandatory binary files + ...)
 - Shape (.shp) contains feature geometry
 - Shape index (.shx): facilitates fast search
 - Attribute (.dbf): contains attributes for each shape

```
An example of GeoJSON file.
```

```
{
  "type": "Feature",
  "geometry": {
    "type": "Point",
    "coordinates": [125.6, 10.1]
  },
  "properties": {
    "name": "Dinagat Islands"
  }
}
```

Source/Ref: Introduction to (Q)GIS by Jeff Allen

Raster Data



- Represents space as a continuous grid with equal cell sizes
 - Each cell represents a square area (whose size depends on map resolution)
- Each cell contains a value pertaining to the type of feature it represents
 - Quantitative value (e.g., elevation, flood index)
 - Categorical value (e.g., type of land use)
- Examples of raster data (.tif, .jpeg, .png, etc.)
 - digital elevation models (DEMs)
 - Flood Susceptibility Index (FSI) map
 - satellite imagery (e.g., color image with 3 bands/layers: RGB)

1 3 9 7 7 2 8 7 7 8 6 7 3 5 7 7 6 5 5 6 8 6 5 6 4 0,5 5,5 EON.

Source/Ref: 1) Introduction to (Q)GIS by Jeff Allen; 2) Raster 00 tutorial from NEON.

Coordinate Reference System (CRS)

Any geo-spatial dataset comes with a CRS

Without CRS, one cannot plot and process geospatial data correctly

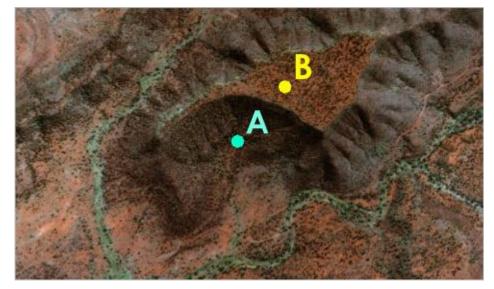
 CRS is "a framework used to precisely measure locations on the surface of Earth as coordinates." (wikipedia)

- CRS is a COMPLEX topic
 - Let's attempt to understand some basics.

Motivation

• "URGENT: Rescue signal detected from satellite phone — coordinates 134.577° E, 24.006° S. Immediate response required."

- Where is it on the Earth's surface?
 - A or B?
 - GCS (Geographic Coordinate Systems)
- How to get there?
 - Map! -> 2D flat
 - PCS (Projected Coordinate Systems)



A if GCS is Australian Geodetic Datum 1984 B if GCS is WGS (World Geodetic System) 1984

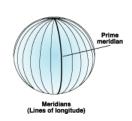
Source/Ref: GCS vs PCS

Two Main Types of CRS

- Geographic Coordinate Systems (GCS)
 - Round (where on the earth's surface)
 - Records locations in angular units (e.g., degrees)
 - Latitude: degrees north or south of equator
 - Longitude: degrees west or east of a prime meridian
 - Different models for the Earth surface -> Many GCS
 - e.g. World Geodetic System 1984 (WGS84)



GCS

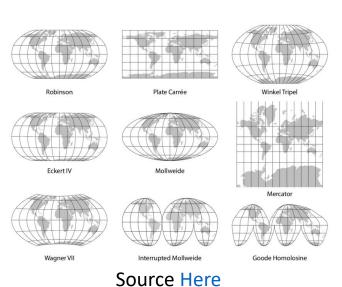


4,452,924.3 m.

1.838.290.1 m



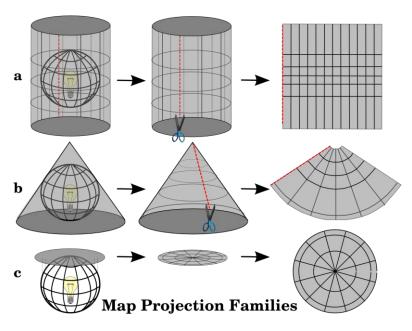
- Projected Coordinate Systems (PCS)
 - Flat (how to draw on a 2d/flat paper)
 - Records locations in linear units (e.g., meters)
 - Many ways to project -> Many PCS
 - e.g., Universal Transverse Mercator (UTM)



Source/Ref: 1) CRS Wikipedia; 2) GCS vs PCS

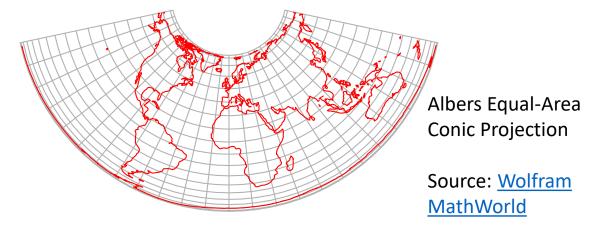
Projections

- MANY different projections
 - Three main families, but there are more
 - Within each family, there are many projections



Source: QGIS Doc

- A projection can preserve one or more properties below but never all
 - Direction
 - Distance
 - Area
 - Shape



Source/Ref: 1) List of map projections wiki; 2) Map projection wiki

Components of CRS

- Coordinate system
 - E.g., longitude & latitude, x & y, etc.
- Datum: binds abstract coordinate system to real space on the Earth
 - Datum usually consists of
 - an estimate of the shape of the Earth (usually an ellipsoid)
 - one or more anchor points for which the measurement is documented
 - Examples of dataum
 - Global datum: WGS84, North American Datum (NAD83)
 - Local datum: NAD27 (A local datum aligns its ellipsoid to closely fit the earth's surface in a particular area)
- Projection (if it is a PRS)

Source/Ref: CRS wiki

CRS is a "Stack" of Dependent Specifications

EPSG Code	Name	Ellipsoid	Horizontal Datum	CS Type	Projection	Origin	Axes	Unit of Measure
4326₺	GCS WGS 84	GRS 80	WGS 84	ellipsoidal (lat, lon)	N/A	equator/ prime meridian	equator, prime meridian	degree of arc
26717 년	UTM Zone 17N NAD 27	Clarke 1866	NAD 27	cartesian (x,y)	Transverse Mercator: central meridian 81°W, scaled 0.9996	500 km west of (81°W, 0°N)	equator, 81°W meridian	meter
6576 ₺	SPCS Tennessee Zone NAD 83 (2011) ftUS	GRS 80	NAD 83 (2011 epoch)	cartesian (x,y)	Lambert Conformal Conic: center 86°W, 34°20'N, standard parallels 35°15'N, 36°25'N	600 km grid west of center point	grid east at center point, 86°W meridian	US survey foot

Source/Ref: CRS wiki

GIS (Geographic Information Systems)

 GIS are tools to analyze, manipulate, and visualize spatial information on a computer

- Many GIS tools
 - QGIS, ArcGIS, MapBox, etc.

- We will only focus on visualization with <u>GeoPandas</u>'s plot() function
 - GeoPandas's plot() is a method on GeoSeries or GeoDataFrame
 - GeoPandas's plot() builds on Matplotlib

Source/Ref: Introduction to (Q)GIS by Jeff Allen

Geopandas - 1

Make working with geospatial data in Python easier

- Extends <u>pandas</u> to allow spatial operations on geometric types
 - Geometric operations built on shapely
 - File access built on <u>fiona</u>
 - Plotting built on <u>matplotlib</u>

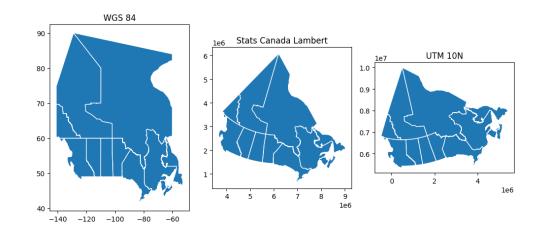


Geopandas - 2

- Load dataset containing geometry info
- Manage Coordinate Reference System (CRS)
 - Store CRS info
 - translate between CRSs
- Geospatial operations
 - Calculate areas bounded by polygons
 - Spatial join
 - Spatial aggregation
 - Many more

•	P	lot
		-

	PRENAME	PREABBR	LANDAREA	geometry
0	Newfoundland and Labrador	N.L.	3.581704e+05	POLYGON ((7644464.869 2980078.217, 7648864.423
1	Prince Edward Island	P.E.I.	5.681179e+03	POLYGON ((8427184.671 1638777.314, 8427169.677
2	Nova Scotia	N.S.	5.282471e+04	MULTIPOLYGON (((8693947.526 1494906.237, 86935
3	New Brunswick	N.B.	7.124850e+04	POLYGON ((8188457.820 1707919.583, 8188444.194
4	Quebec	Que.	1.298600e+06	MULTIPOLYGON (((8396476.571 1754341.151, 83956
5	Ontario	Ont.	8.924118e+05	POLYGON ((6378273.940 2296884.400, 6378455.637
6	Manitoba	Man.	5.403102e+05	POLYGON ((6039718.643 2636909.880, 6039717.720
7	Saskatchewan	Sask.	5.770604e+05	POLYGON ((5248633.914 2767057.263, 5249285.640
8	Alberta	Alta.	6.346583e+05	POLYGON ((5228304.177 2767597.891, 5228098.463
9	British Columbia	B.C.	9.206866e+05	POLYGON ((4018904.414 3410247.271, 4019429.869
10	Yukon	Y.T.	4.723454e+05	POLYGON ((4561932.471 4312865.174, 4564007.580
11	Northwest Territories	N.W.T.	1.127712e+06	POLYGON ((5689672.257 4324508.314, 5685498.029
12	Nunavut	Nvt.	1.836994e+06	POLYGON ((7297737.369 3983558.454, 7316653.440



Hands-on: Warm-up – Geopandas Basics

- Load data
 - Canada province boundary shape file

Determine CRS and convert between CRSs

- Perform geospatial operations
 - Example: calculating areas

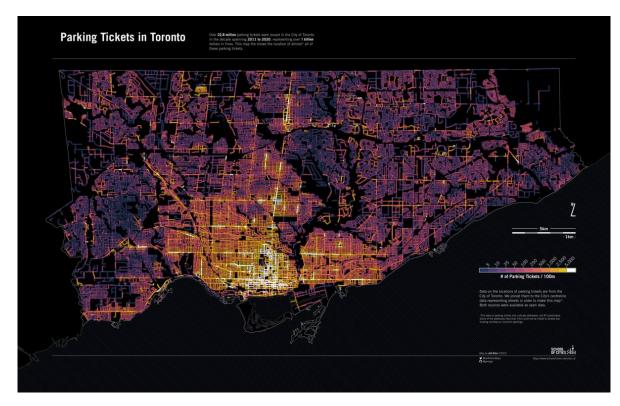
Plot maps

Walk-through — Toronto Parking Ticket

 Reproduce (almost) Jeff Alan's <u>Toronto Parking</u> <u>Tickets</u> Visualization

 I believe Jeff's plot is done using QGIS and Inkscape

 We will use GeoPandas with Matplotlib

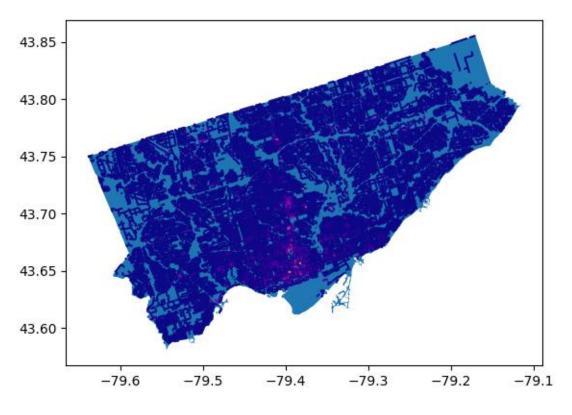


Parking Tickets in Toronto by Jeff Alan

Ref: 1) https://schoolofcities.github.io/parking-tickets-toronto/

2) https://github.com/schoolofcities/parking-tickets-toronto/tree/main

Walk-through – Our Implementation

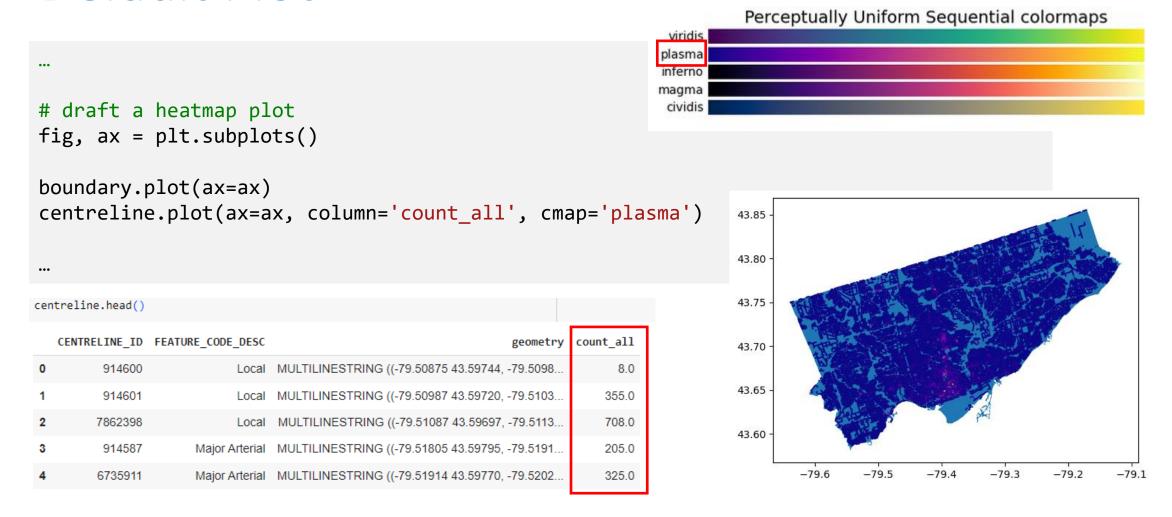


the default plot from Geopandas/Matplotlib



the refined plot

Default Plot



Ref: 1) https://geopandas.org/en/stable/docs/reference/api/geopandas.GeoDataFrame.plot.html

2) https://matplotlib.org/stable/users/explain/colors/colormaps.html

Refine 1. Better Orientation

```
# rotate centreline
                                                                   930000
# turn EPSG:4326 to EPSG:3347 first to avoid shape
# distortion after rotation
                                                                   925000
cline 3347 = centreline.to crs(epsg=3347)
                                                                              7.21
                                                                                      7.22
                                                                                              7.23
# rotate with respect to the centroid of all centrelines
cline_3347_rotated = cline_3347.rotate(-28, origin=cline_3347.union_all().centroid)
    .rename("geometry 3347 rotate")
# combine the original centreline GeoDataFrame with the rotated GeoSeries
centreline rotated = centreline.join(cline 3347 rotated)
# rotate boundary
# turn EPSG:4326 to EPSG:3347 first to avoid shape distortion after rotation
# rotate with respect to the centroid of all centrelines to match centreline rotation centroid
boundary rotated = boundary.to crs(epsg=3347).rotate(-28, origin=cline 3347.union all().centroid)
```

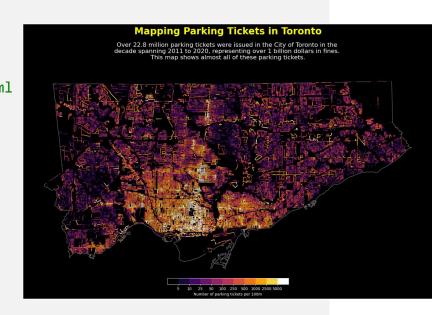
945000

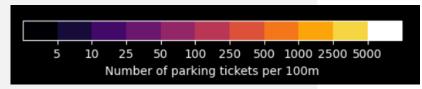
935000

7.24

Refine 2. Colormap on Discrete Intervals

```
# Generate a colormap index based on discrete intervals
# https://matplotlib.org/stable/api/ as gen/matplotlib.colors.Colormap.html
# https://matplotlib.org/stable/api/ as gen/matplotlib.colors.BoundaryNorm.html
cmap = plt.colormaps['inferno'].with extremes(over="white")
bounds = [5, 10, 25, 50, 100, 250, 500, 1000, 2500, 5000]
norm = BoundaryNorm(bounds, cmap.N, extend='both')
# plot centreline heatmap
centreline rotated.plot(ax=ax, column='count all',
                        cmap=cmap,
                        norm=norm,
                        markersize=0.5,
                        legend=True,
                        legend kwds={
                            'shrink': 0.3,
                            'orientation': 'horizontal',
                            'pad': 0,
                            'anchor': (0.5, 1),
                            'extendfrac': 'auto',
                            'extendrect': True,
                            'label': 'Number of parking tickets per 100m'})
```





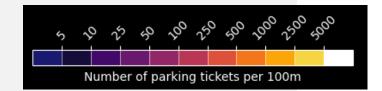
Ref: 1) Discrete and extended colorbar with continuous colorscale

2) In general, you can use <u>mapclassify</u> to auto-generate classification schemes for choropleth maps.

Refine 3. Better Colorbar

```
# plot coloarbar legend separately so as to customize its look
cbar = fig.colorbar(ScalarMappable(norm=norm, cmap=cmap),
                    ax=ax,
                    orientation='horizontal',
                    shrink=0.3,
                    pad=-0.02,
                    anchor=(0.5, 1),
                    extendfrac='auto',
                    extendrect=True,
                    drawedges=True,
                    label='Number of parking tickets per 100m')
cbar.ax.tick params('x',
                    bottom=False, labelbottom=False,
                    top=True, labeltop=True,
                    labelrotation=45)
```





Refine 4. Map Scale, North Arrow, & Notes

```
# add scalebar
# https://geopandas.org/en/stable/gallery/matplotlib scalebar.html
scale = ScaleBar(dx=1,
                  location='lower right',
                  color='grey',
                  box alpha=0,
                  width fraction=0.005,
                  border pad=5)
= ax.add artist(scale)
                                                                             Note: This is an attempt to reproduce Jeff Allan's Toronto
                                                                             Parking Tickets Map using Matplotlib. Find the original plot
                                                                             at https://schoolofcities.github.io/parking-tickets-toronto/.
# add north arrow
# https://matplotlib.org/stable/users/explain/text/annotations.html
                                                                             Data source and data processing code can be found therein.
                                                                                                                                              5 km
= ax.annotate("N",
                 xy=(0.91, 0.25), xycoords='figure fraction',
                 xytext=(0.9, 0.19), textcoords='figure fraction',
                 ha='center',
                 color='gray',
                 arrowprops=dict(arrowstyle="fancy", color="gray"))
# add notes
= ax.text(0.6, 0.11,
             ("Note: This is an attempt to reproduce Jeff Allan's Toronto \nParking Tickets Map using Matplotlib."
              "Find the original plot \nat https://schoolofcities.github.io/parking-tickets-toronto/.\n\n"
             "Data source and data processing code can be found therein."),
            transform=ax.transAxes,
            wrap=True,
            fontsize=8,
            horizontalalignment='left',
            bbox=dict(boxstyle='square', pad=1, facecolor='black', edgecolor='black'))
```