

Q1.

```
1.          ORG 0000h

Loop:      MOV p0, #01H

          ACALL Delay

          MOV p0, #00H

          ACALL Delay

          SJMP Loop

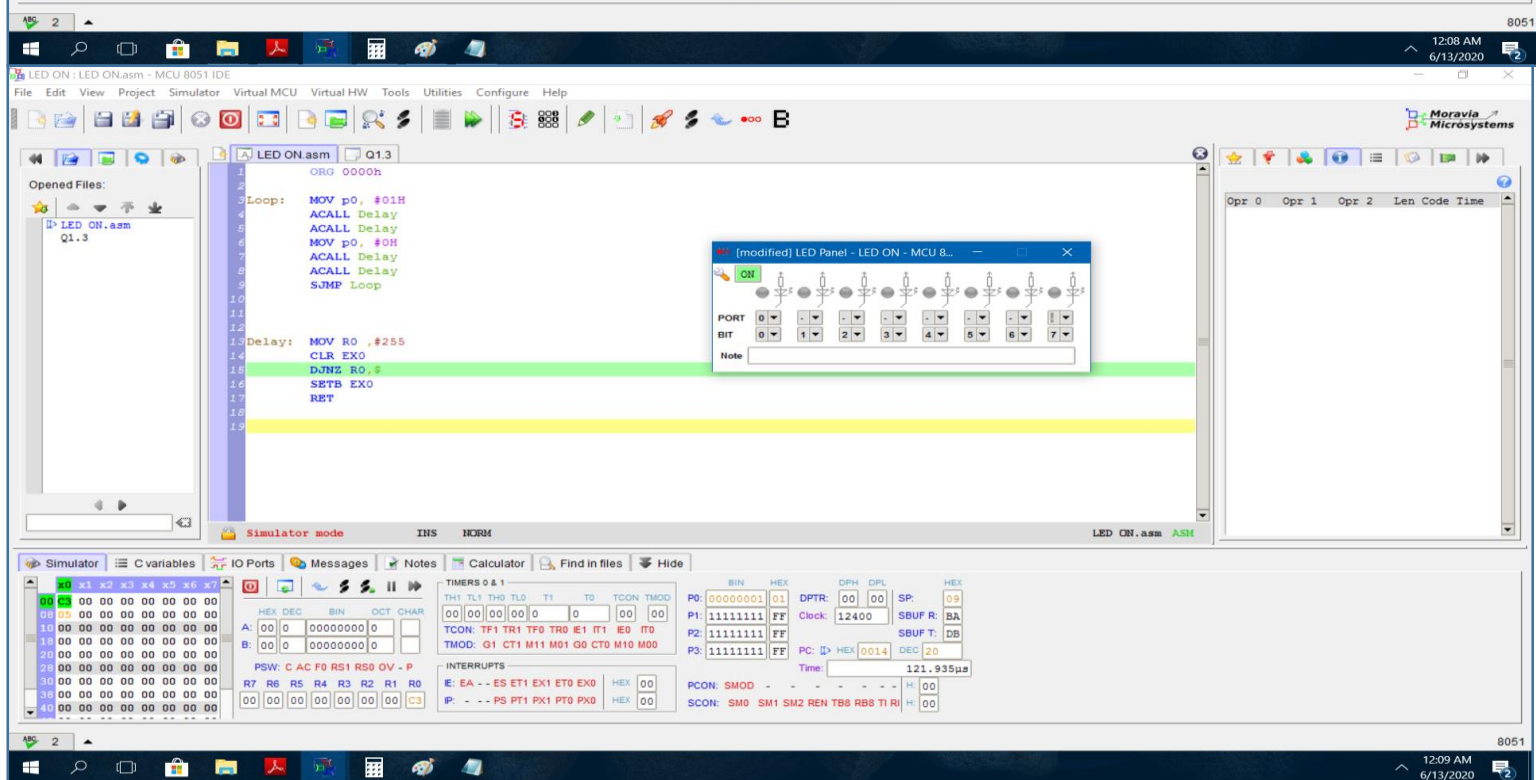
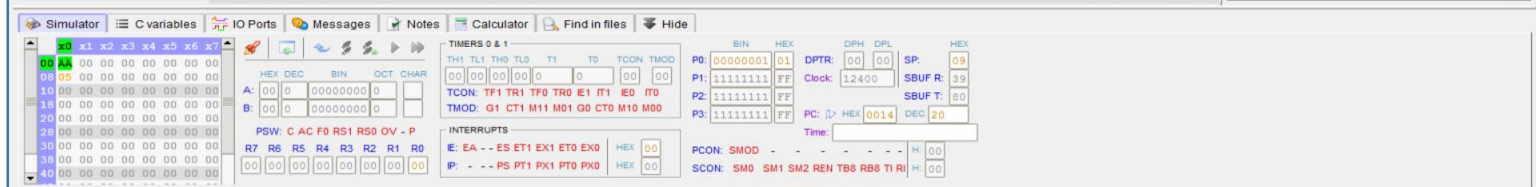
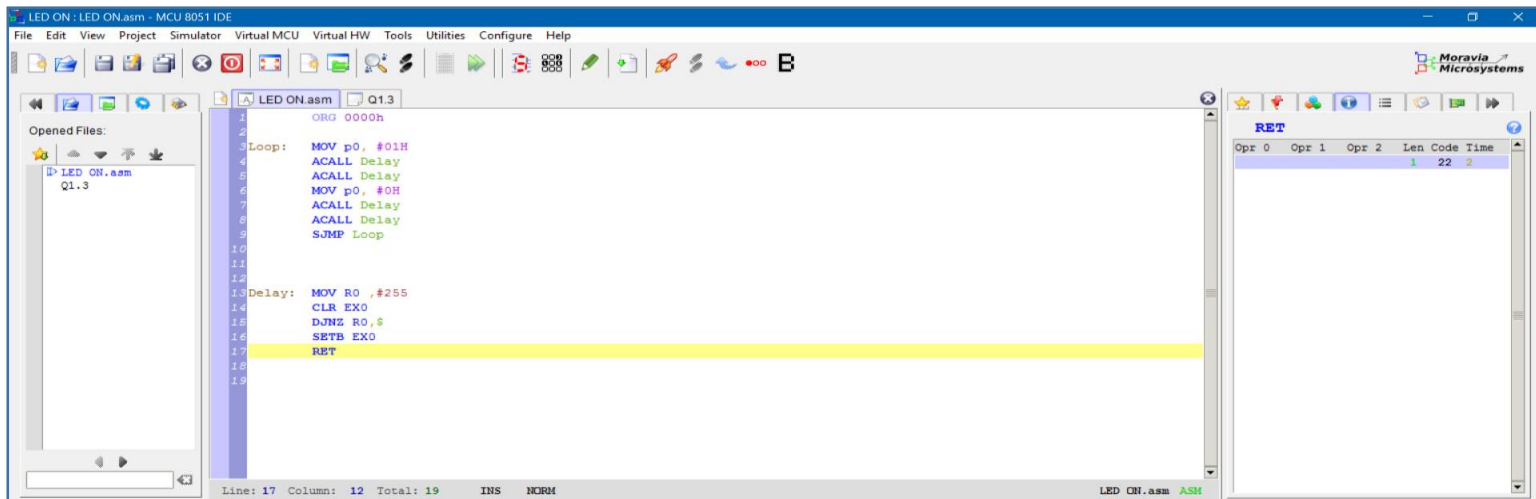
Delay:     MOV    R1, #015h

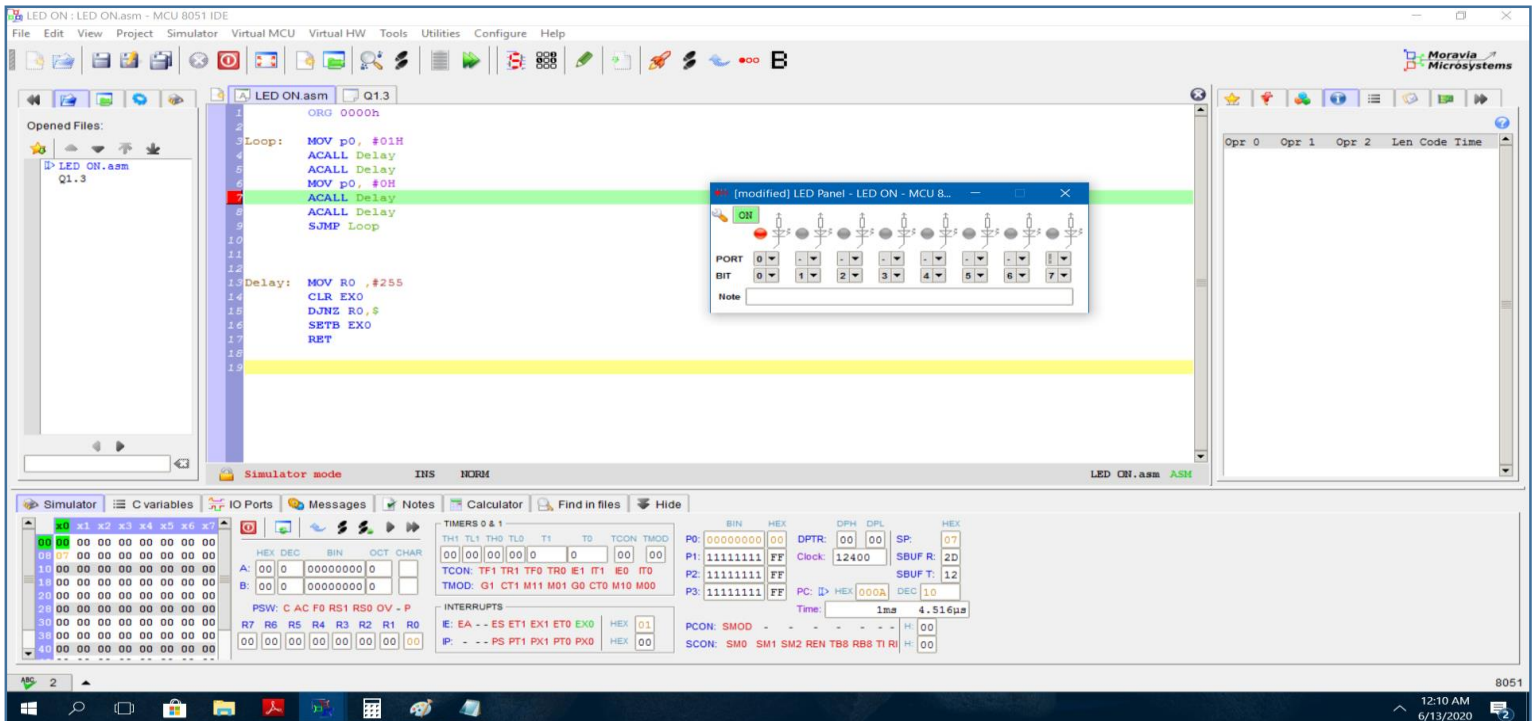
          MOV    R0, #0F4h

          DJNZ   R0, $

          DJNZ   R1, $-4

          RET
```





```

3.          ORG 0000h

Loop:      MOV p0,#01H

           ACALL Delay

           MOV p0,#0H

           ACALL Delay

           SJMP Loop

Delay:     MOV TMOD,#00001000B

           MOV TL1,#0A3H

           MOV TH1,#0D7H

           SETB TR1

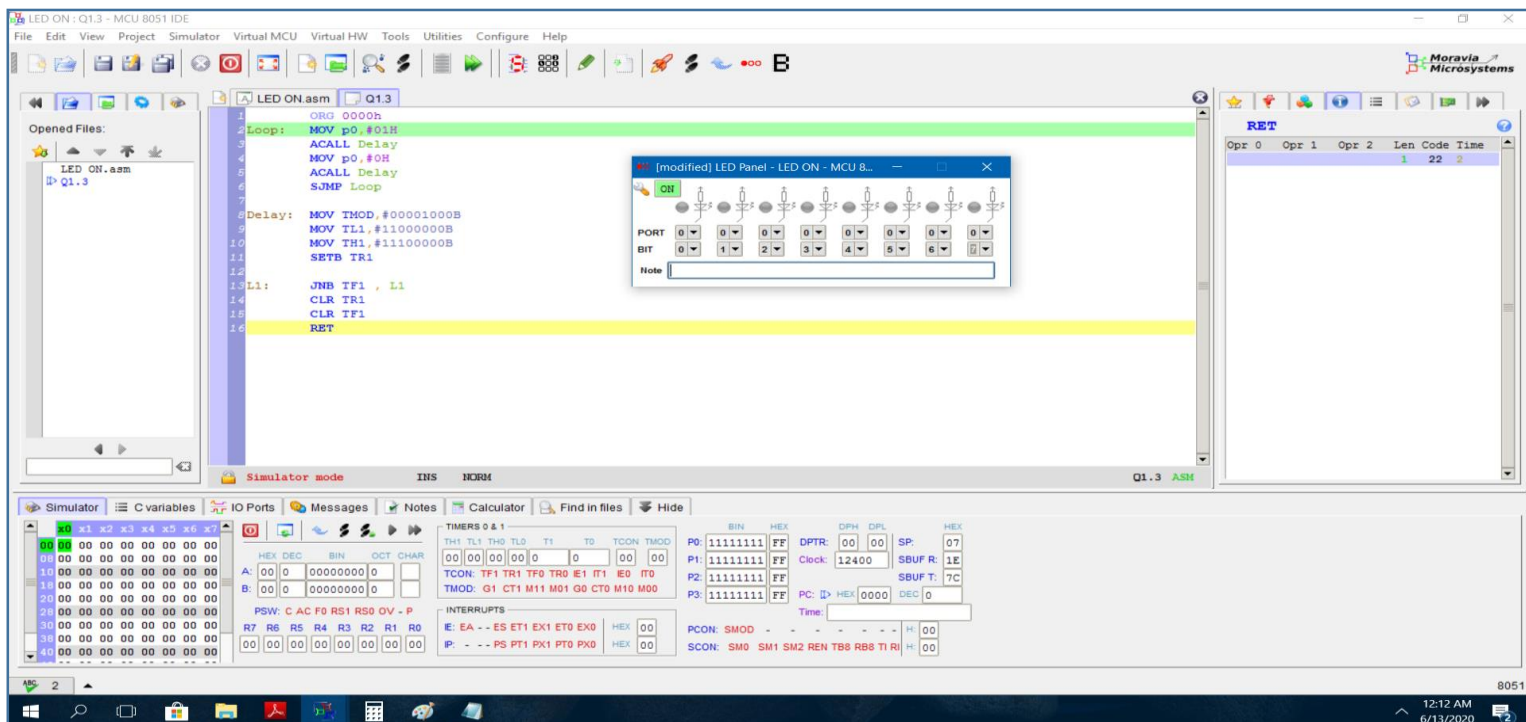
L1:        JNB TF1 , L1

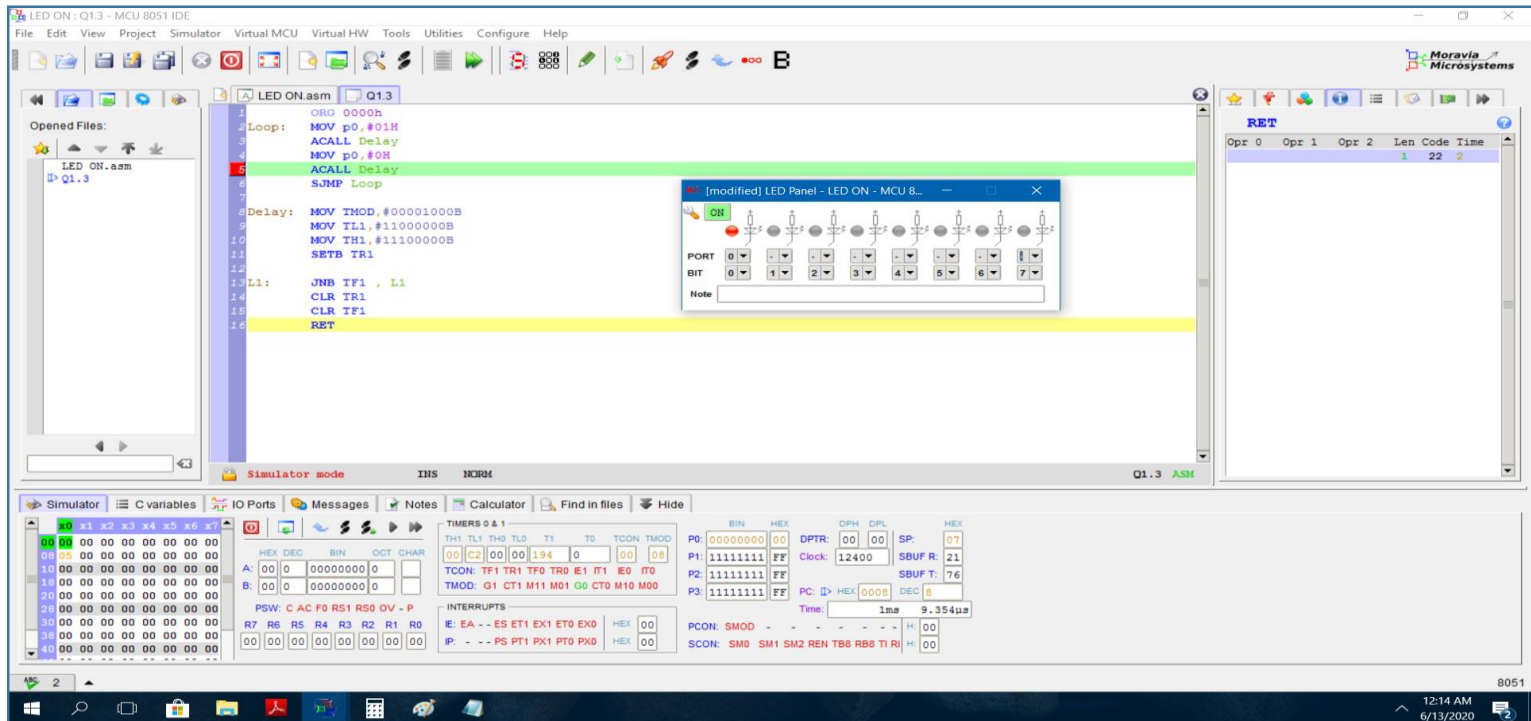
           CLR TR1

           CLR TF1

           RET

```





## Task 02

```

ORG      0000H

L1:      JNB

ORG 0003H

START

        LCALL    INTERRUPT

ORG      0010H

        MOV      TMOD, #00000110B

START:   SETB    P0.0

        SETB     TR0

MAIN:

        SETB     P0.0

        MOV      TH0, #0FBH

        MOV      TL0, #0F7H

        JNB      TF0, L1

INTERRUPT:

        CLR      P0.0

        CLR      TR0

        MOV      R1, #006h

        MOV      R0, #0AAh

        DJNZ     R0, $

        DJNZ     R1, $-4

        SETB     P0.0

        RET

END

```

## Task 3

1)

ORG 0000H

MOV A,#'I'

ACALL Display

MOV A,#'S'

ACALL Display

MOV A,#'H'

ACALL Display

MOV A,#'A'

ACALL Display

MOV A,#'R'

ACALL Display

MOV A,#'A'

ACALL Display

Display: MOV P1,A

SETB P3.5

CLR P3.4

SETB P3.3

CLR P3.3

MOV R3,#0

DJNZ R3,\$

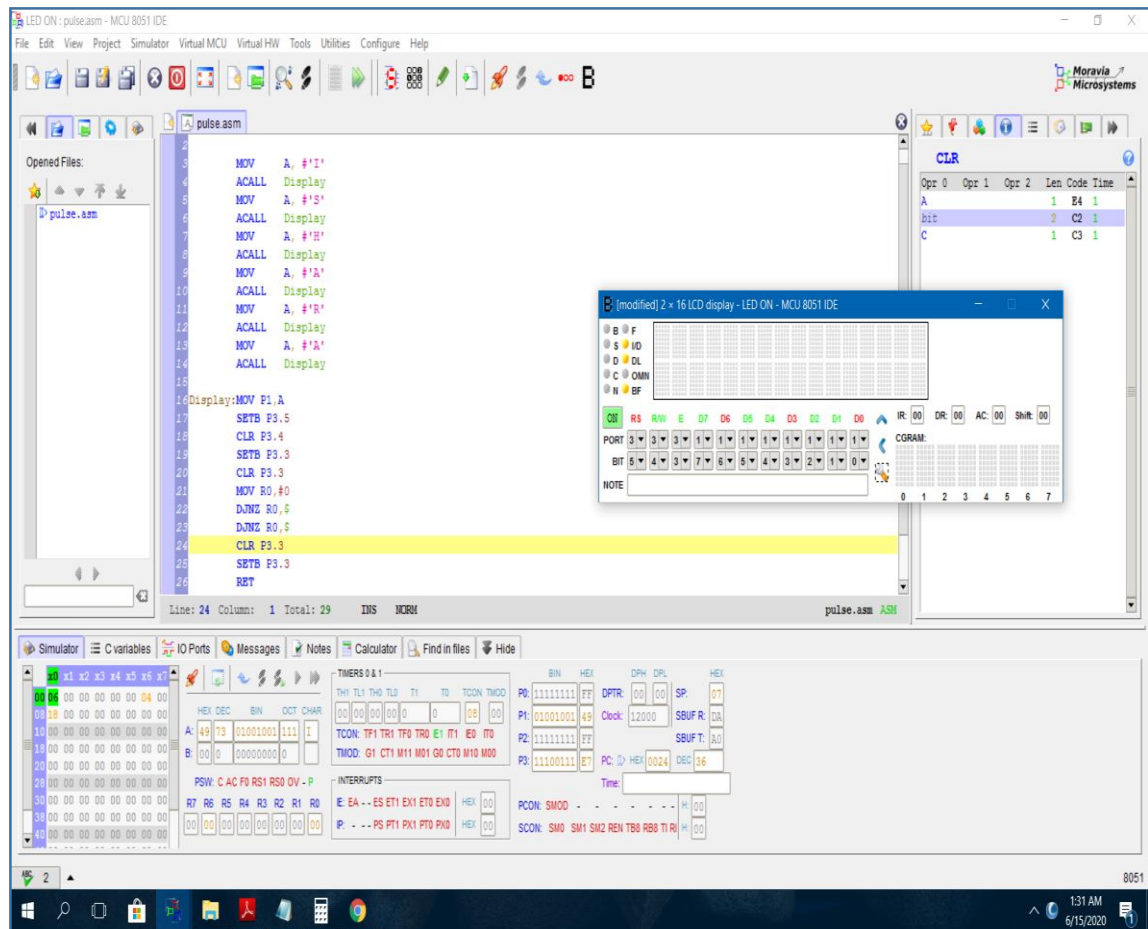
DJNZ R3,\$

CLR P3.3

SETB P3.3

RET

END



2)

ORG 0000H

START: MOV P0,#00000011B

ACALL DELAY

MOV P0,#10011111B

ACALL DELAY

MOV P0,#01000101B

ACALL DELAY

MOV P0,#00001101B

ACALL DELAY

MOV P0,#10011001B

ACALL DELAY

MOV P0,#00101001B

ACALL DELAY

MOV P0,#00100001B

ACALL DELAY

MOV P0,#10001111B

ACALL DELAY

MOV P0,#0000001B

ACALL DELAY

MOV P0,#10001001B

ACALL DELAY

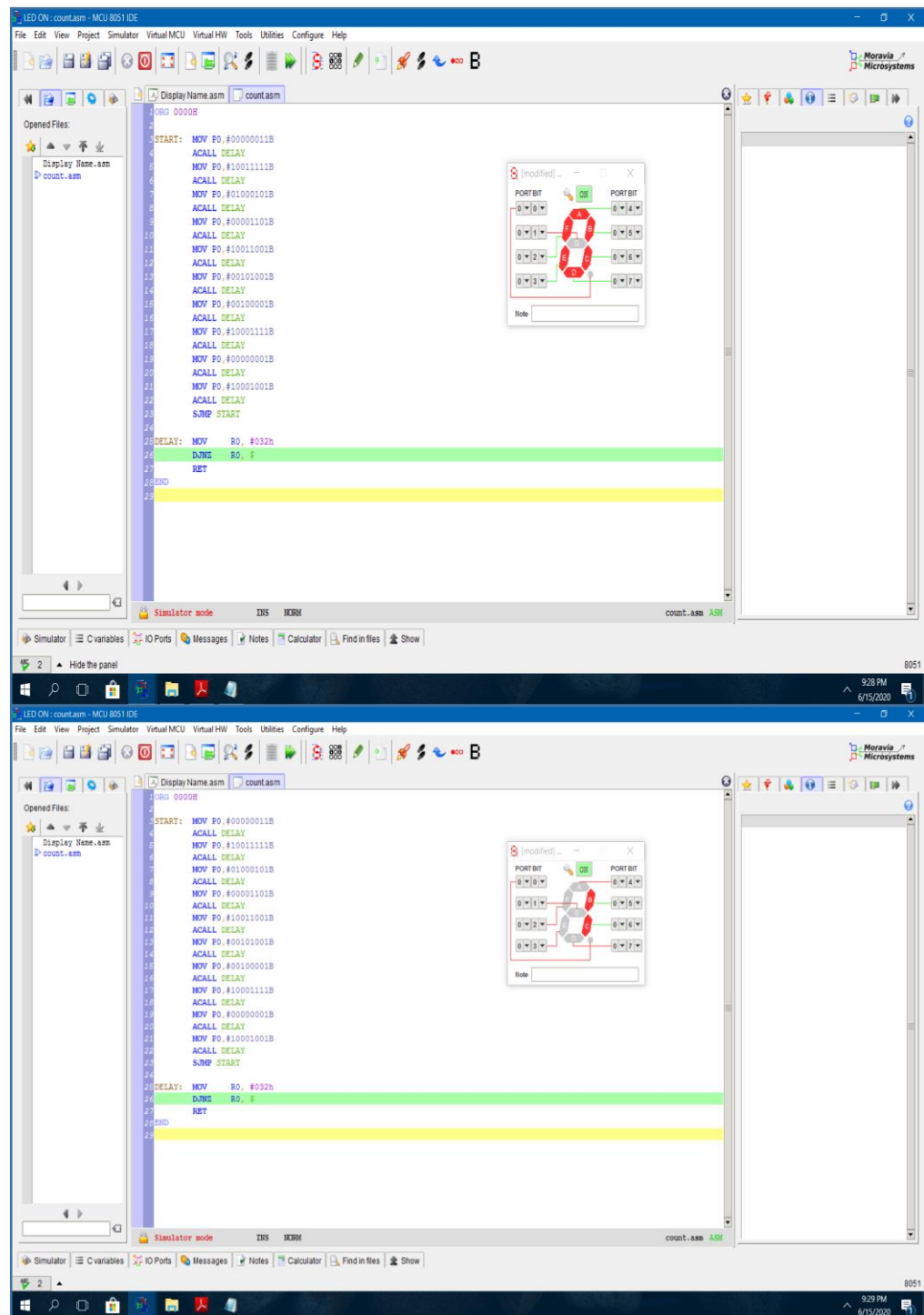
SJMP START

DELAY: MOV R0, #032h

DJNZ R0, \$

RET

END





## Task 4

// Here the motor is Starts after Port 3 pin 2 is switched.

//The signal goes to a Electric switch, then ignites high tention current.

//Manual switch is assumed as bounce back switch.

//After 20m the motor is automatically turne off.

//20m is the time taken to fill the tank.

ORG 0000H

JB P3.2,\$ ; Switch Control

START: SETB P0.1

ACALL DELAY

CLR P0.1

CLR P3.2

RET

DELAY: MOV R5, #017h ; 20m time delay

MOV R4, #04Ah

MOV R3, #0A6h

MOV R2, #003h

MOV R1, #0E4h

MOV R0, #000h

NOP

DJNZ R0, \$

DJNZ R1, \$-5

DJNZ R2, \$-9

DJNZ R3, \$-13

DJNZ R4, \$-17

DJNZ R5, \$-21

MOV R6, #005h

MOV R5, #0C2h

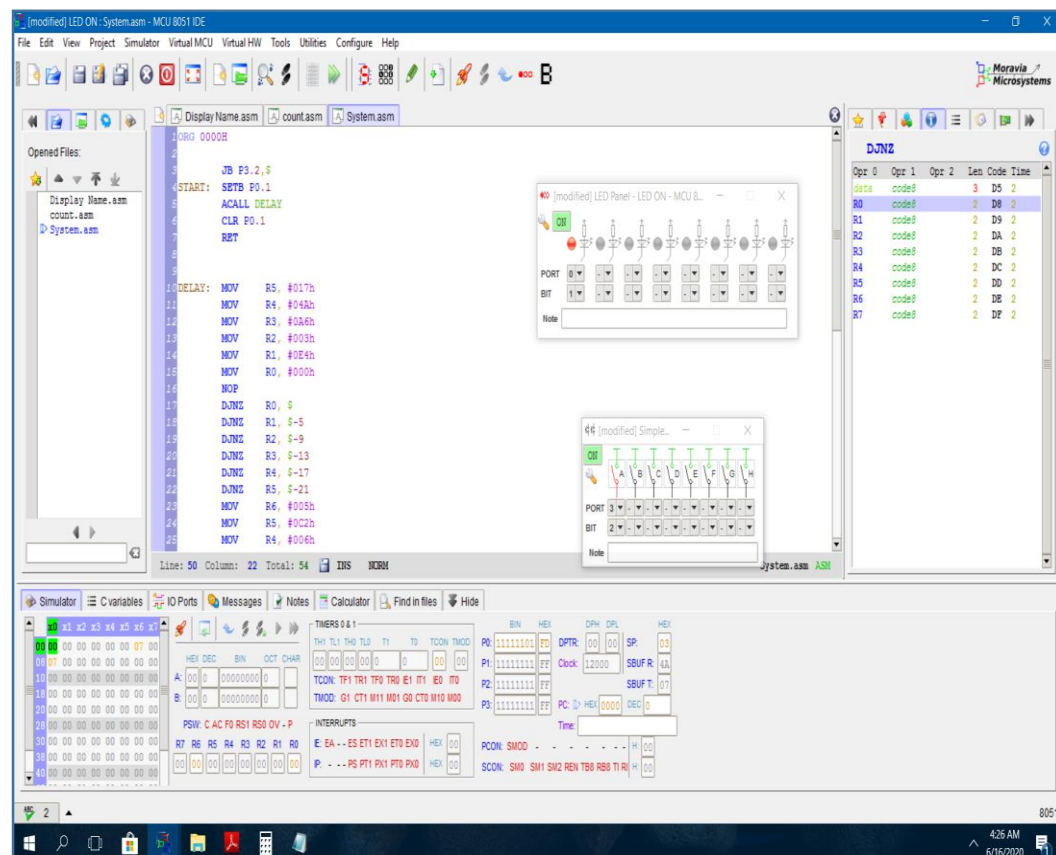
MOV R4, #006h

MOV R3, #006h

MOV R2, #022h

MOV R1, #020h

MOV R0, #004h



```
NOP

DJNZ    R0, $
DJNZ    R1, $-5
DJNZ    R2, $-9
DJNZ    R3, $-13
DJNZ    R4, $-17
DJNZ    R5, $-21
DJNZ    R6, $-25
MOV     R3, #00Ah
MOV     R2, #0EDh
MOV     R1, #01Dh
MOV     R0, #01Bh
NOP

DJNZ    R0, $
DJNZ    R1, $-5
DJNZ    R2, $-9
DJNZ    R3, $-13
MOV     R1, #002h
MOV     R0, #0DFh
NOP

DJNZ    R0, $
DJNZ    R1, $-5

RET
```

END