

Project 4B

CS 111

What is this project about ?

- Project 4 is an IoT project. The final result will be a networked temperature sensor, communicating on a (potentially) encrypted channel
- This week, the goal is to run an application using external sensors and log results on the Beaglebone
- The main difficulty should be reading data from the sensor correctly
 - You will use the temperature sensor for reading
 - You will use the button for shutdown

Assemble Beaglebone

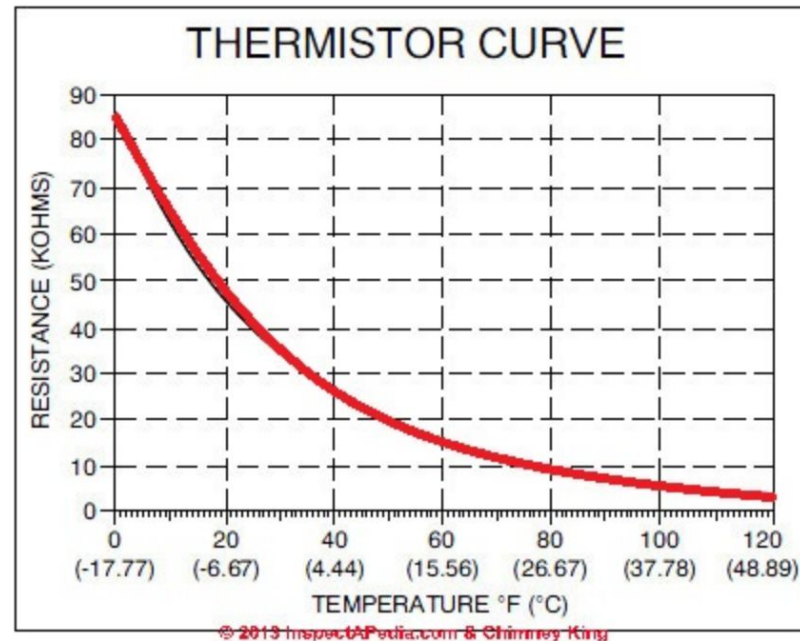
- Plug the Base Shield in the BeagleBone
- Plug the temperature sensor to A0 / A1
 - Will be I/O pin #1
- Plug the push-button to GPIO 50
 - Will be I/O pin #60
- Turn the voltage on the base cape to 5V

Breakdown of the tasks

- Arguments to your program:
 - Period : interval (s) between 2 temperature measurements
 - Scale : choose the reading scale between Celsius and Fahrenheit
 - Log : choose the file where measurements are saved
- You should also accept parameters from stdin:
 - Scale, to switch units during execution
 - Period, to change the period during execution
 - Stop : stop generating reports (you are not exiting, you are still processing input parameters). If already stopped, do nothing.
 - Start : resume reports (if stopped)
 - Log <text> : add <text> to logfile
 - OFF : output and log a timestamped shutdown message, and exit

The Temperature sensor

- Is a thermistor :



- You should set your base cape to 5V for more accurate readings
 - The readings **will** be inaccurate (~15F from real value), this isn't a problem

Temperature sensor

- The equation for determining the temperature is :

$$\frac{1}{T} = \frac{1}{T_o} + \left(\frac{1}{\beta}\right) \cdot \ln\left(\frac{R}{R_o}\right)$$

Reference Temperature: 298.15 K

Beta-value : 4275

Reference resistance at To:
100000 Ohms

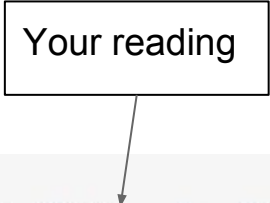
- The above is some background, the implementation is found at :

http://wiki.seeedstudio.com/Grove-Temperature_Sensor_V1.2/

Temperature Sensor

The lines you're interested in on the previous page are :

Your reading



```
float R = 1023.0/a-1.0;  
R = R0*R;
```

```
float temperature = 1.0/(log(R/R0)/B+1/298.15)-273.15;
```

- As a reminder :
 - Kelvin to Celsius : $K - 273.15$
 - Celsius to Fahrenheit: $C * 9/5 + 32$

MRAA : I/O library

- Include headers
- Allocate sensors as `mraa_gpio_context` and `mraa_aio_context` (argument is the pin number from the board)
- Initialize them. The button is an input
 - `mraa_gpio/aio_init(context)`
 - `mraa_gpio_dir(context, direction)` (don't need direction for aio)
- Read from them
 - `mraa_gpio/aio_read(context)`
 - The button will return 0 or 1
 - The temperature sensor will return a voltage
 - Both will return -1 on error
- Close them
 - `mraa_gpio/aio_close(context)`

localtime()

Goal: Return local time

```
struct tm *localtime(const time_t *timer)
```

It will fill up the following structure:

```
struct tm {  
    int tm_sec;           /* seconds, range 0 to 59 */  
    int tm_min;           /* minutes, range 0 to 59 */  
    int tm_hour;          /* hours, range 0 to 23 */  
    int tm_mday;          /* day of the month, range 1 to 31 */  
    int tm_mon;           /* month, range 0 to 11 */  
    int tm_year;          /* The number of years since 1900 */  
    int tm_wday;          /* day of the week, range 0 to 6 */  
    int tm_yday;          /* day in the year, range 0 to 365 */  
    int tm_isdst;         /* daylight saving time */  
};
```

localtime()

To use it properly, you need your timezone to be set on your Beaglebone:

- You can check your current setting using 'date'
- Several ways to change this setting, an easy one would be :
 - apt-get install tzdata
 - dpkg-reconfigure tzdata
 - Follow the steps
- This is optional... we will test your code on another device

Do I need a new measurement?

- Several ways to go about this
- You could use :

```
int gettimeofday(struct timeval *tv, struct timezone *tz)
```

```
struct timezone {  
    int tz_minuteswest;    /* minutes west of Greenwich */  
    int tz_dsttime;        /* type of DST correction */  
};
```

```
struct timeval {  
    time_t      tv_sec;        /* seconds */  
    suseconds_t tv_usec;      /* microseconds */  
};
```

- If enough time has passed and you read, set the time when the next reading is due

Generating reports

- Create an outgoing buffer
- Print the formatted time and temperature to that buffer
 - Watch out, the temperature returned by default is not in the correct format!
- Push that buffer to stdout
- If the logfile is enabled, also push that buffer to the file

Receiving commands

- Commands will come from a pipe, not a keyboard
 - A single read may return partial or multiple lines
- Therefore, use a buffer
 - Check at every iteration if commands can be found
- To wait on commands, `poll()` is appropriate
 - You can't `poll()` on the button
 - You can use several threads (1 for commands, one for sensors)
 - You can simply check the status of the button every second (that frequency is high enough for this project)

DUMMY

- Choose that option if you want to be able to test the base functionality of your code without the board
- In that case, you cannot import the headers
- Instead, define the functions yourself
 - Simply have them return the correct type of data, and take in the correct type of input
- That way you'll be able to test functionality of your code on your laptop, before debugging sensor reads

FAQ

- My program segfaults!
 - This is likely due to the initialization of your I/O. If your sensors aren't initialized properly, the init function will return NULL, and you will segfault when trying to read().
 - Flash your board
 - Run your code from root
- What edge case order of commands should we handle?
 - There will be **no** tricky edge cases, such as:
 - A period of 0
 - Stop and start within a single period
 - Stop and Stop, start and start generate no behavior
 - Changing the period can take effect after the next report
 - On startup, generate first reading before processing input

FAQ

- My program hangs indefinitely?
 - If your shutdown didn't go through, it's possible that your program is still running in the background.
 - `top -U <username>` will help you verify this
 - You can kill your program using its pid if this happens
- UCLA_WEB blocks ntp messages, you won't be able to download the sanity script functions on that network (Use eduroam, your mobile hotspot, or home router)