

Presentation Title

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Example citation [1]

- [1] Liu, Y., Wensing, P. M., Orin, D. E., and Zheng, Y. F., “Dynamic walking in a humanoid robot based on a 3D actuated Dual-SLIP model,” *2015 IEEE International Conference on Robotics and Automation (ICRA)*, IEEE, 2015, pp. 5710–5717.