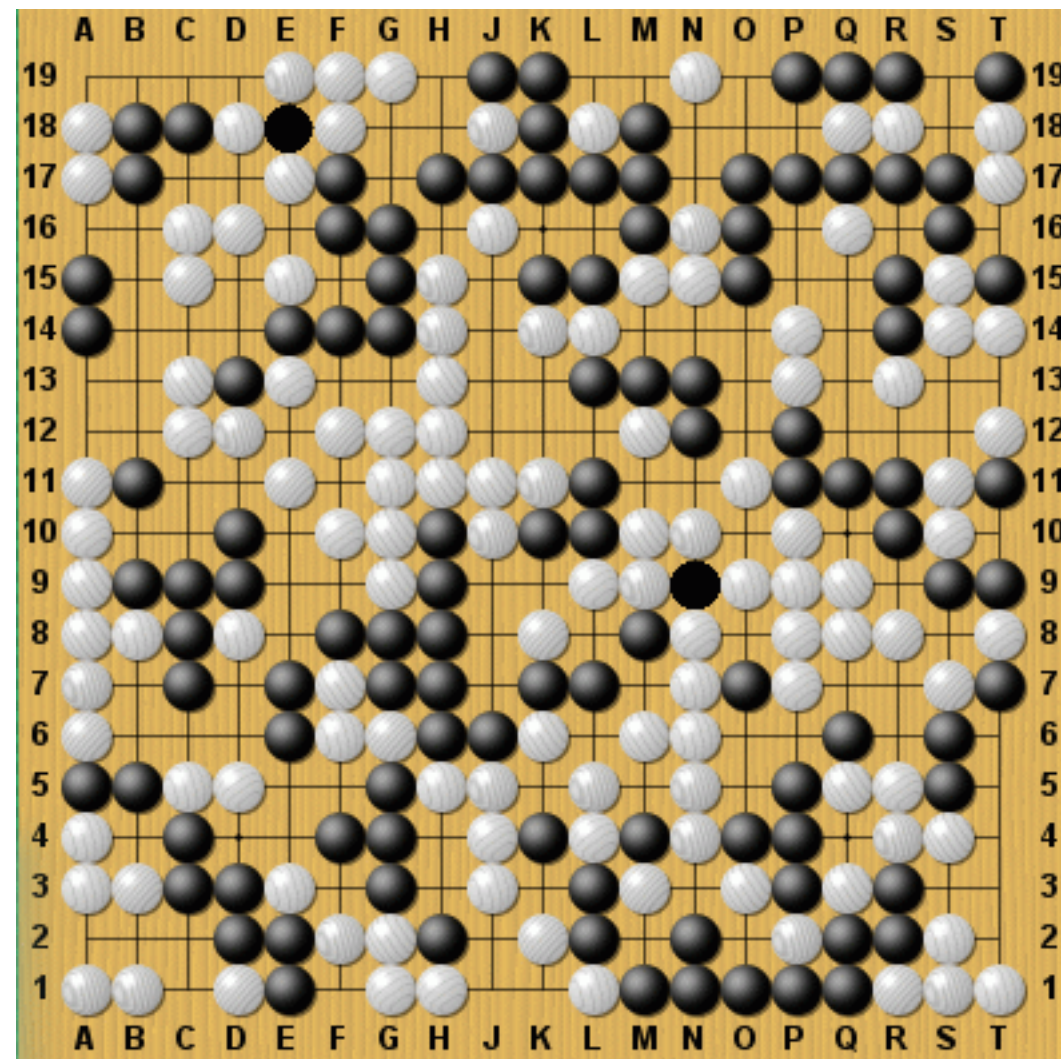


AlphaGo Zero

Part I Game Tree Search Techniques

- Game tree search
 - MinMax
 - Alpha-Beta pruning
- Monte-Carlo tree search
- AlphaGo Zero

Go



Some numbers

Chess

$\sim 10^{46} - 10^{49}$ legal positions

$\sim 10^{123}$ game tree size

~ 35 branching 80 ply

Go

9x9

$\sim 10^{38}$ legal positions

45 ply

19x19

2081681993819799846994786333448627702865224538845305484256394
5682092741961273801537852564845169851964390725991601562812854
6089888314427129715319317557736620397247064840935

$\sim 10^{169}$ legal positions

~ 250 branching 150 ply

1996 Deep Blue defeats Gary Kasparov
(but loses the match 2-4)

1997 Deep Blue defeats Gary Kasparov
(wins the match 3 1/2-2 1/2)

2007 MoGo defeats Gu Ju (5P) in 9x9 Go

Arpad Rimmel, Olivier Teytaud, Chang-Shing Lee, Shi-Jim Yen, Mei-Hui Wang, et al.. "Current Frontiers in Computer Go". IEEE Transactions on Computational Intelligence and AI in games, IEEE Computational Intelligence Society, 2010

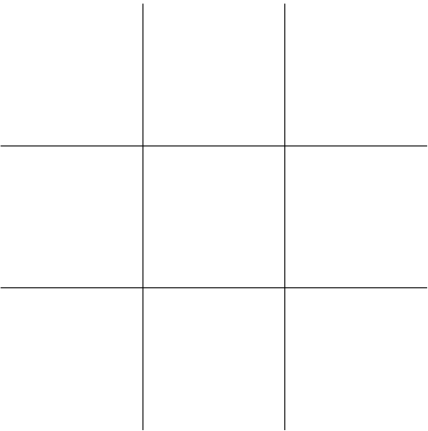
- October 2015
AlphaGo Fan defeats European Champion Fan Hui (2 professional Dan)
- March 2016
AlphaGo Lee defeats Lee Sedol (9 professional Dan).
- 2016/17
AlphaGo Zero defeats both those programs and all other existing Go programs ..
- 2017
Alpha Zero defeats best chess playing program Stockfish

„Mastering the game of Go without human knowledge”, D. Silver et al.,
Nature **550**, 354–359 (2017)

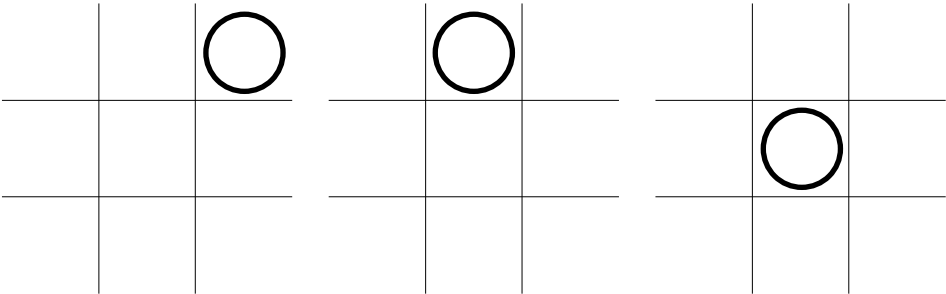
„Mastering Chess and Shogi by Self-Play with a General Reinforcement Learning Algorithm”, D. Silver et al., arXiv:1712.1815v1

Game tree

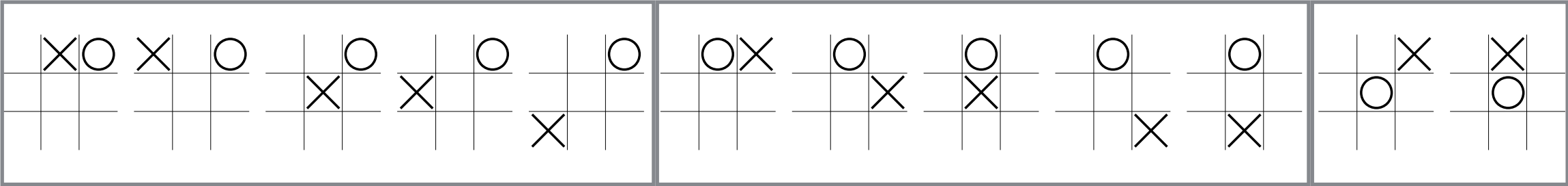
max



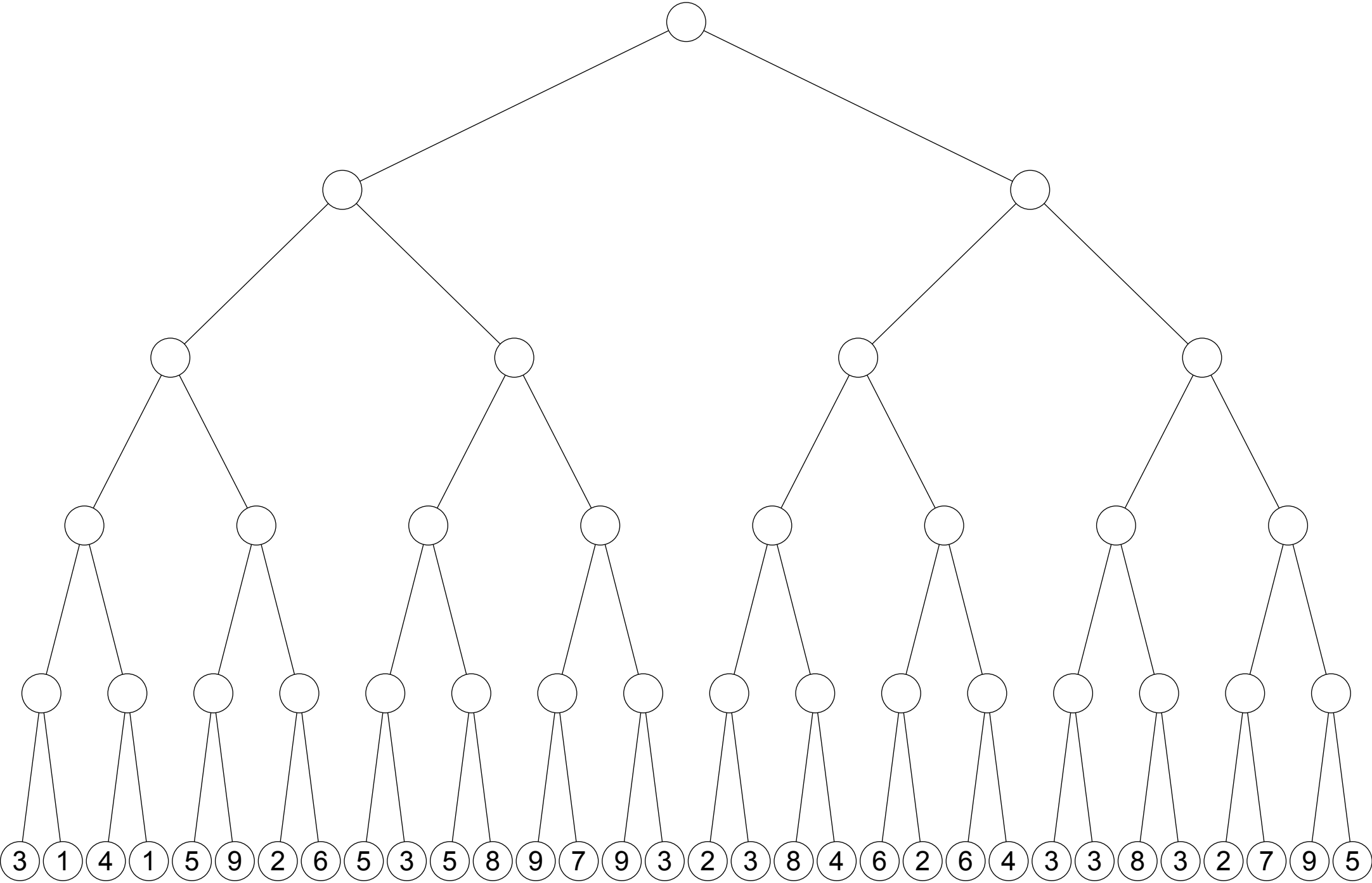
min

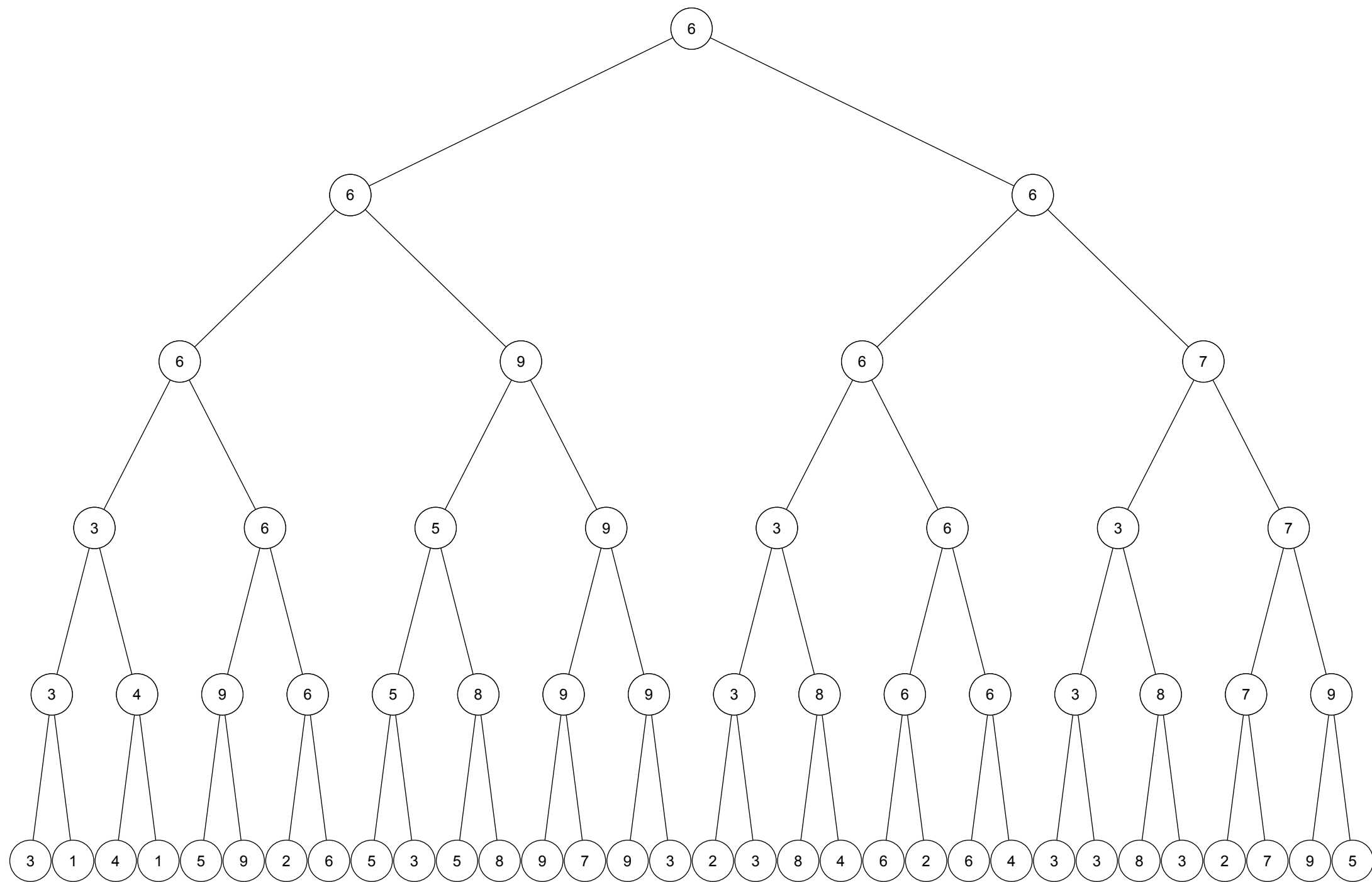


max



MinMax

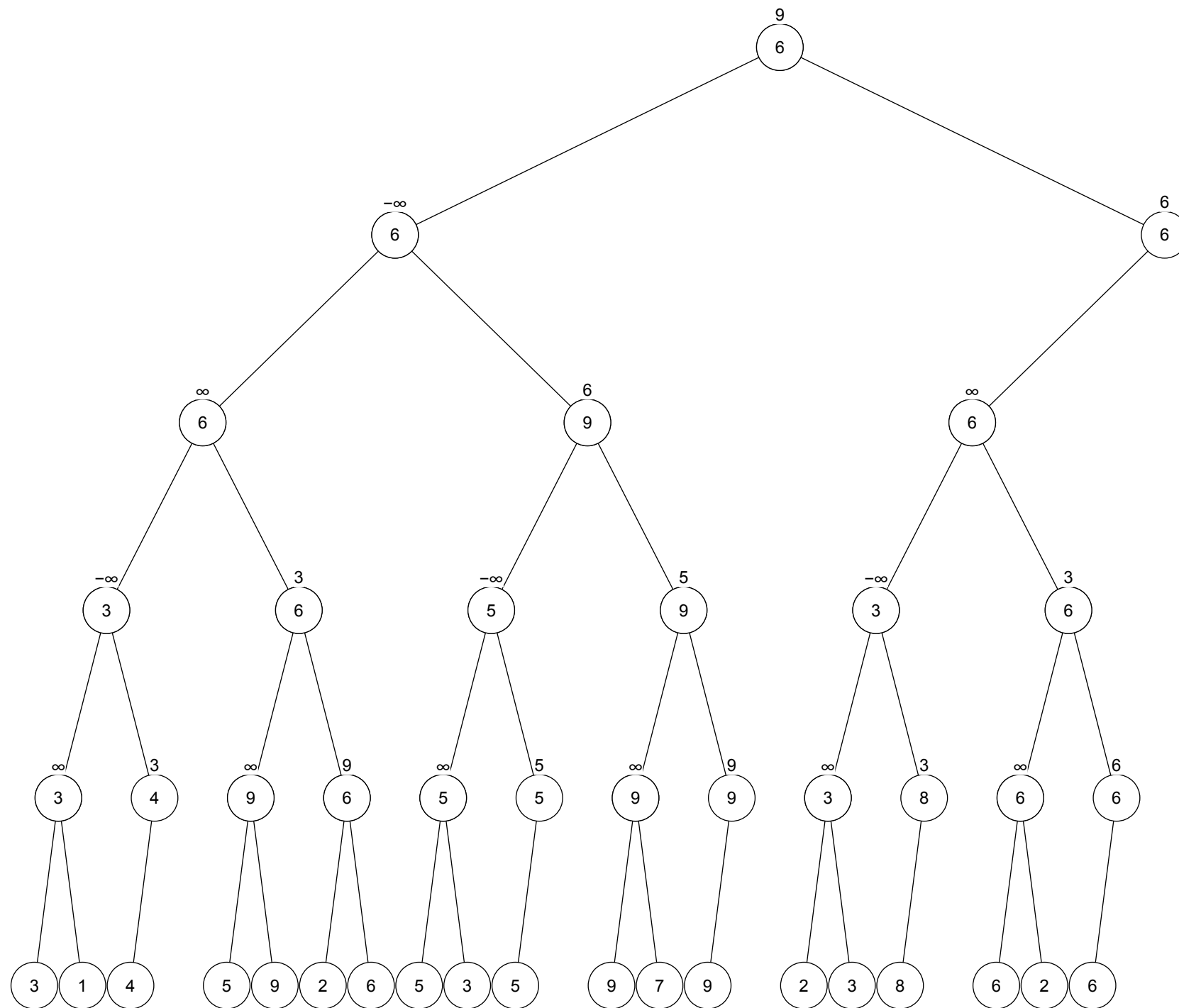




Min Max

```
minS[node_] := node  
maxS[node_] := node  
maxS[node_List] := Max[minS /@ node]  
minS[node_List] := Min[maxS /@ node]
```

Branch and cut



Branch and cut

```
BBMinS[node_, bound_] := node
```

```
BBMaxS[node_, bound_] := node
```

```
BBMaxS[node_List, bound_] :=
```

```
Module[{m = -Infinity, t, i, n, nodes = {}},
```

```
For[i = 1, i <= Length[node], i++,
```

```
  t = BBMinS[node[[i]], m];
```

```
  m = If[t > m, t, m];
```

```
  If[m >= bound, Break[]]
```

```
];
```

```
m
```

```
]
```

```
BBMinS[node_List, bound_] :=
```

```
Module[{m = Infinity, t, i, n, nodes = {}},
```

```
For[i = 1, i <= Length[node], i++,
```

```
  t = BBMaxS[node[[i]], m];
```

```
  m = If[t < m, t, m];
```

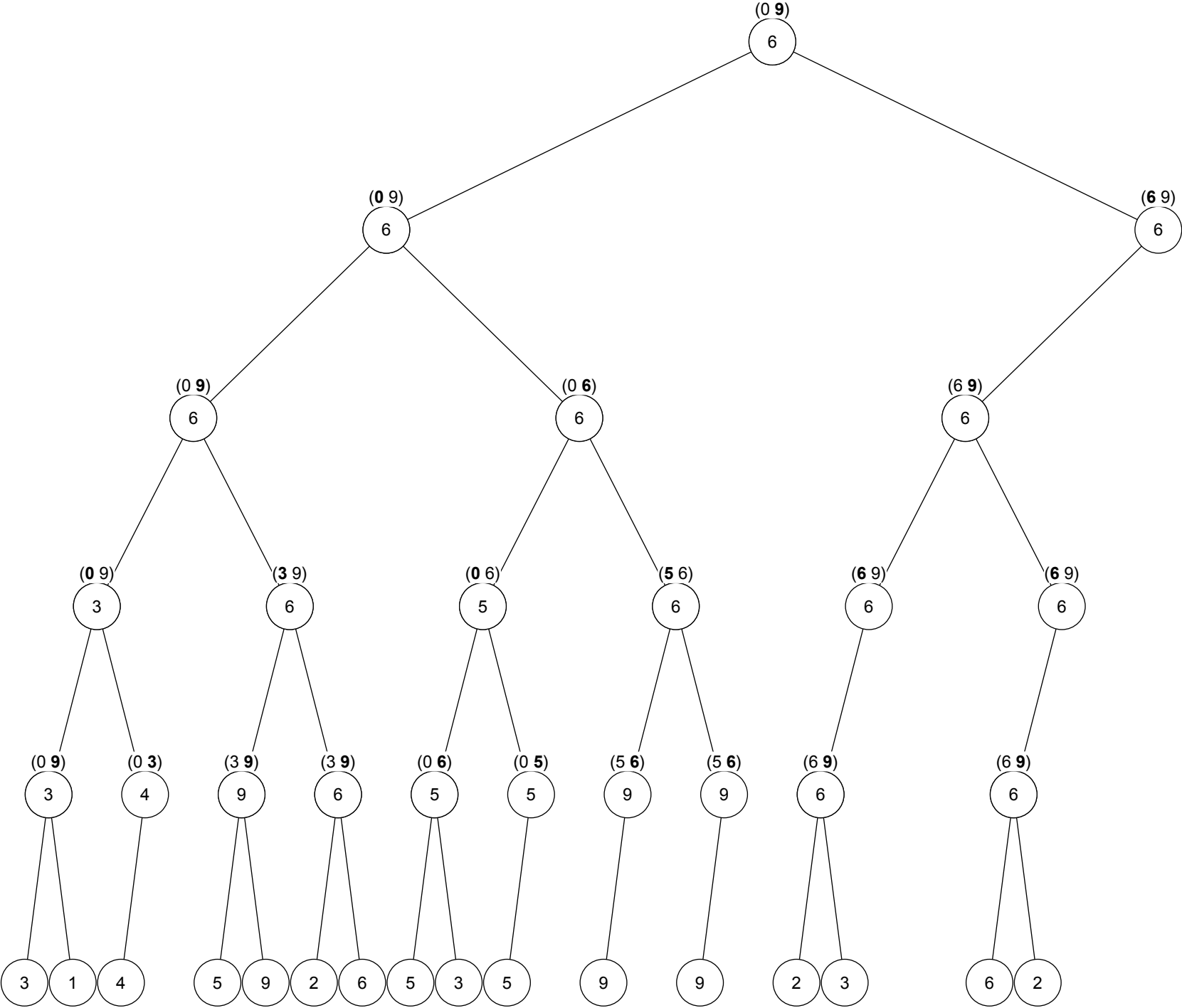
```
  If[m <= bound, Break[]]
```

```
];
```

```
m
```

```
]
```

$\alpha - \beta$ pruning



Alpha - Beta pruning

```
AlphaBetaMinS[node_, \[Alpha]_, \[Beta]_] := node
AlphaBetaMaxS[node_, \[Alpha]_, \[Beta]_] := node
```

```
AlphaBetaMaxS[node_List, \[Alpha]_, \[Beta]_] :=
Module[{m = \[Alpha], t, i, n, nodes = {}},
  For[i = 1, i <= Length[node], i++,
    t = AlphaBetaMinS[node[[i]], m, \[Beta]];

    m = If[t > m, t, m];
    If[m >= \[Beta], Break[]];
  ];
m
]
```

```
AlphaBetaMinS[node_List, \[Alpha]_, \[Beta]_] :=
Module[{m = \[Beta], t, i, n, nodes = {}},
  For[i = 1, i <= Length[node], i++,
    t = AlphaBetaMaxS[node[[i]], \[Alpha], m];

    m = If[t < m, t, m];
    If[m <= \[Alpha], Break[]];
  ];
m
]
```

D.E. Knuth, R.W. Moore
„An Analysis of Alpha-Beta Pruning”
Artificial Intelligence **6** (1975) 293.

Heuristics

In most games tree cannot be evaluated completely

Enhancements

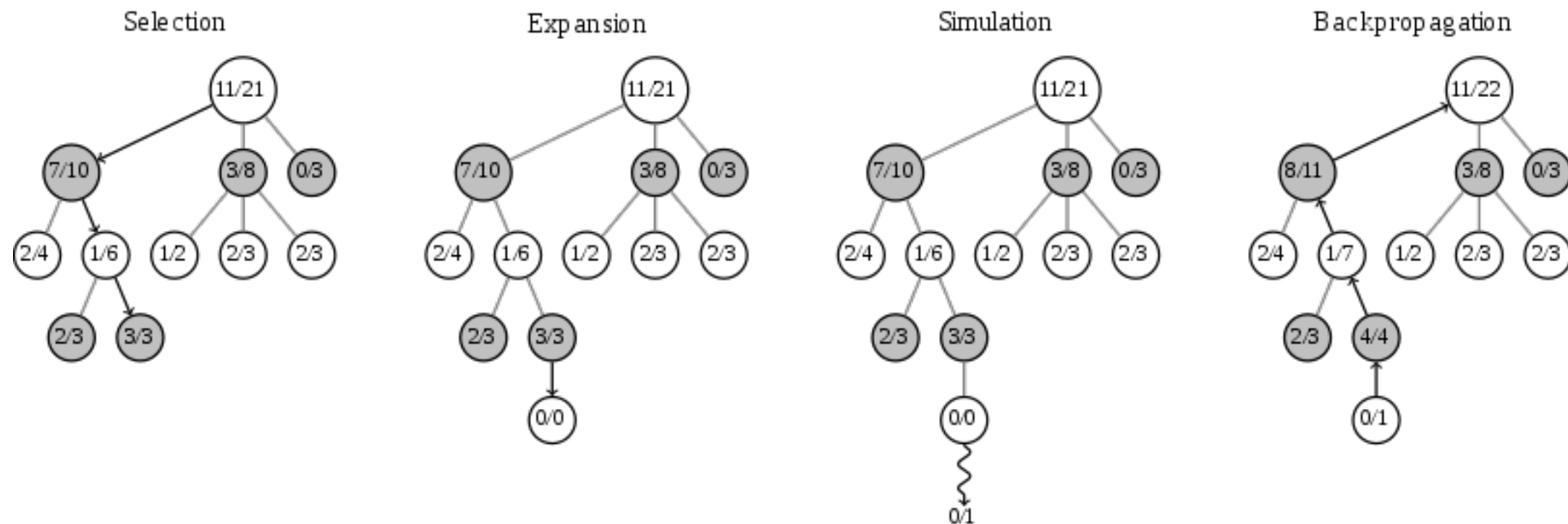
Move ordering

Iterative deepening

Transposition tables

Parallelisation

Monte-Carlo tree search



Monte-Carlo tree search

- Selection
- Expansion
- Simulation
- Backpropagation

Multi armed bandit

K - distribution

Maximize gain

Minimize regret

$$nE(X_{i_{max}}) - E\left(\sum_{t=1}^n X_{i_t}\right)$$

Exploitation vs. Exploration

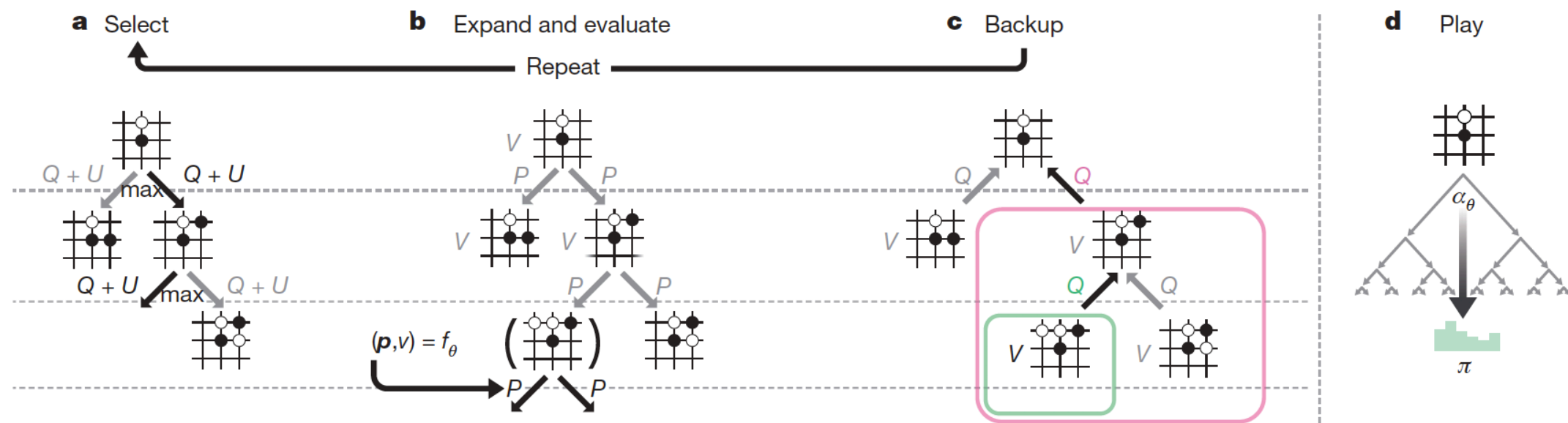
UCB1

$$I_t = \operatorname{argmax}_{i \in \{1, \dots, K\}} \left\{ \overline{X}_{i, T_i(t-1)} + \sqrt{\frac{2 \ln(t-1)}{T_i(t-1)}} \right\}$$

UCT

$$I_t = \operatorname{argmax}_{v' \in \text{children of } v} \left\{ \frac{Q(v')}{N(v')} + c \sqrt{\frac{2 \ln N(v)}{N(v')}} \right\}$$

AlphaGo Zero



$$\pi(a|s) = \frac{N(a, s)^{\frac{1}{\tau}}}{\sum_b N(b, s)^{\frac{1}{\tau}}}$$

Alpha Go Zero PUCT

$$(\mathbf{p}, \nu) = f_{\theta}(s) \quad p_a = P(a|s)$$

$$\operatorname{argmax}_a \left\{ \frac{Q(s, a)}{N(s, a)} + c_{puct} p_a \frac{\sum_b N(s, b)}{N(s, a)} \right\}$$