

# Image Generation Using Disentanglement

Ron Mokady

# What is Disentanglement?

No formal definition which is widely accepted.

Our definition: a change in a single underlying factor of variation in the sample  $x$  should lead to a change in a single factor in the learned representation  $r(x)$ .

# Disentanglement for Generative model

A change in a single underlying factor of variation in the generated image  $G(z)$  should lead to a change in a single factor in the learned representation  $z$ .

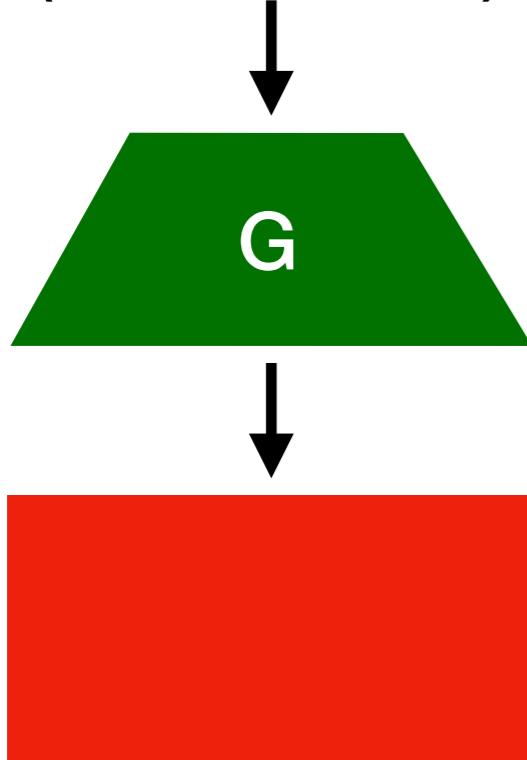
Factors could be style, content, rotation, size, etc.



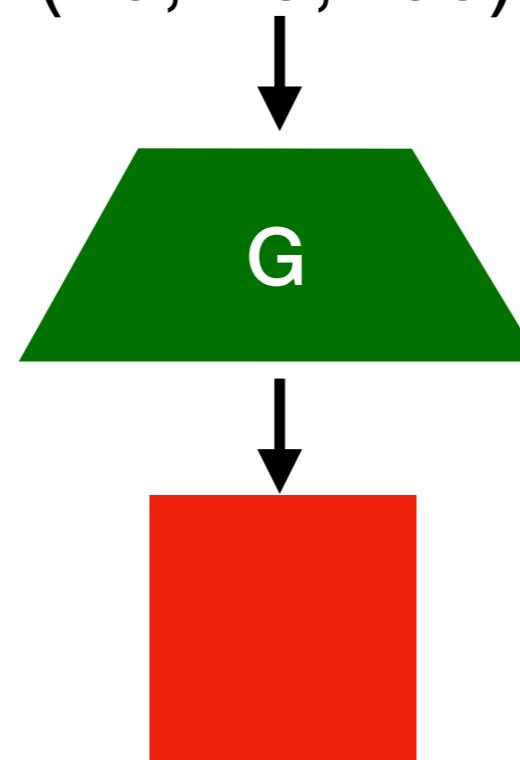
# Example - Rectangles

$z = (\text{height}, \text{width}, \text{color})$

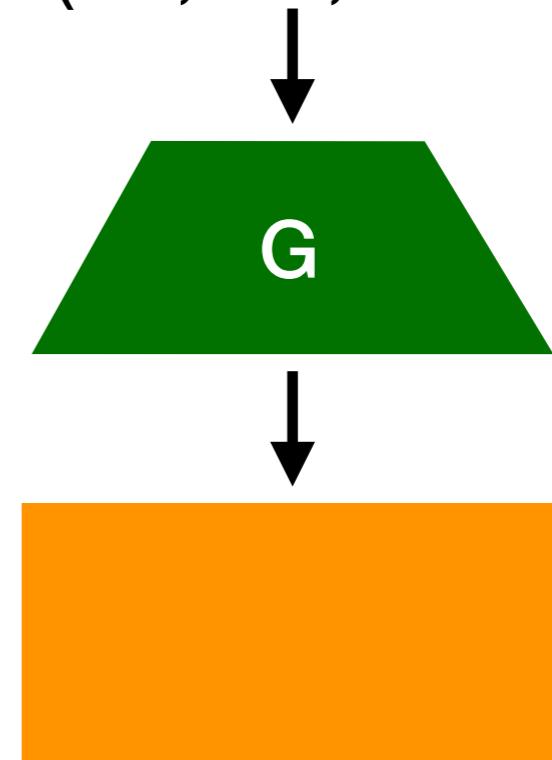
(10, 20, red)



(10, 10, red)

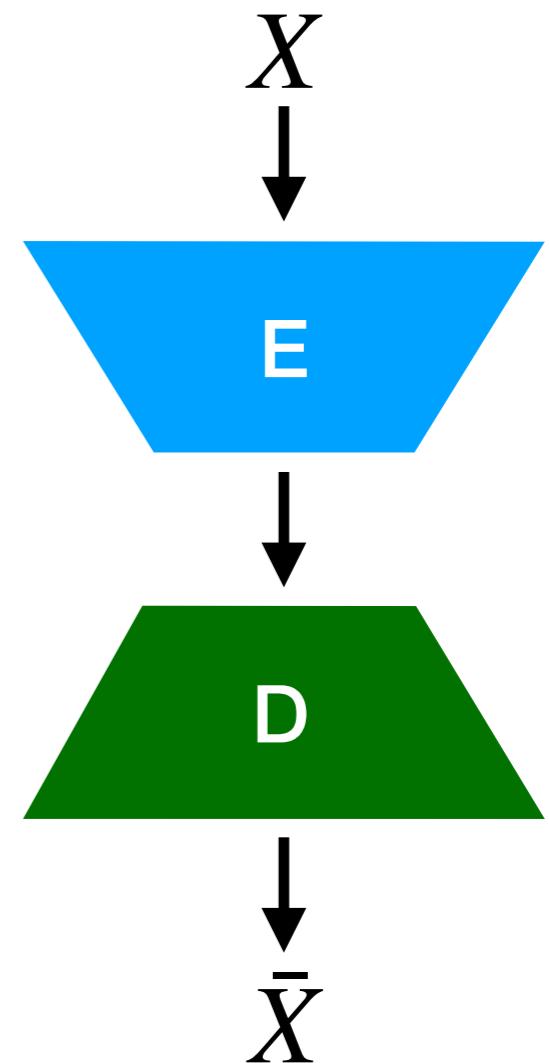


(10, 20, orange)



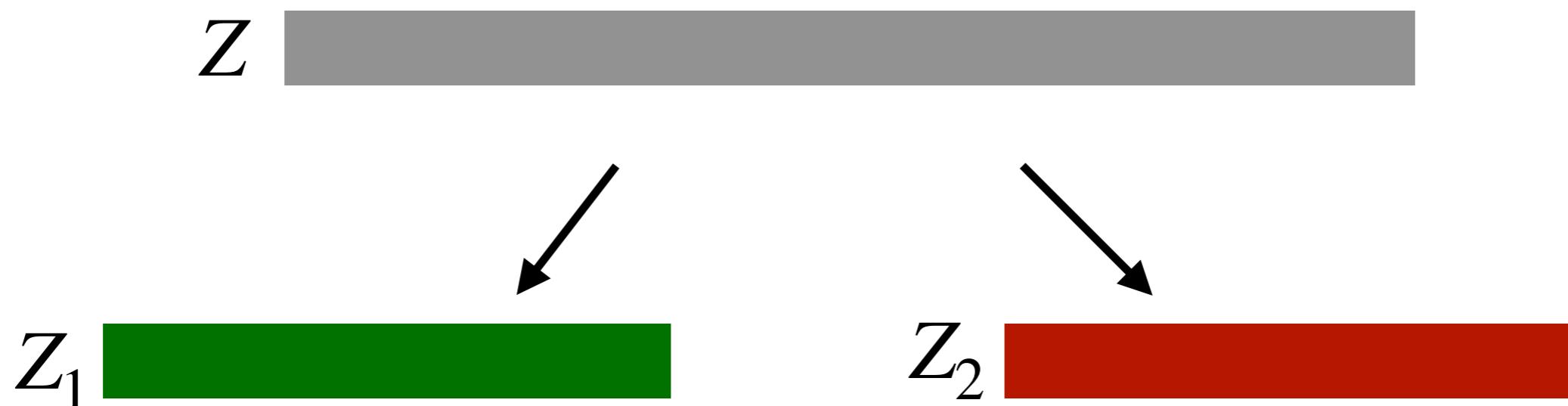
# Example - Autoencoder

Using standard  
Autoencoder, we likely to  
get entangled latent space.



# Separate the Latent Space

We usually want to separate the latent space, such that each part control one or more factors.

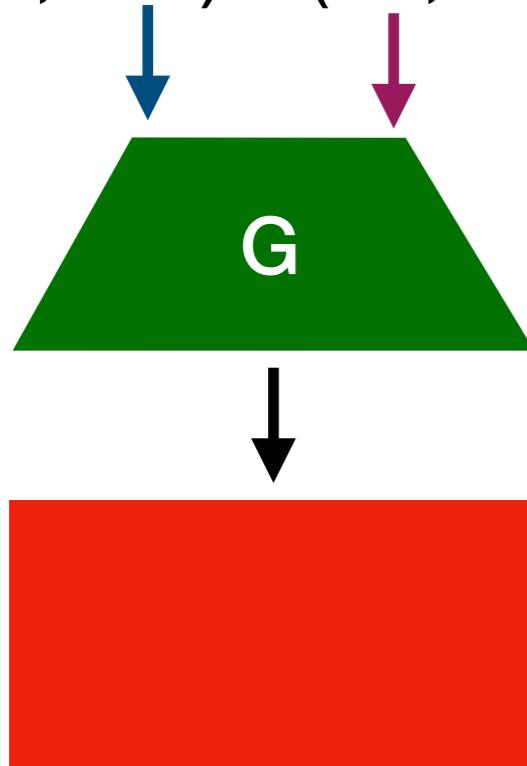


# Generative model

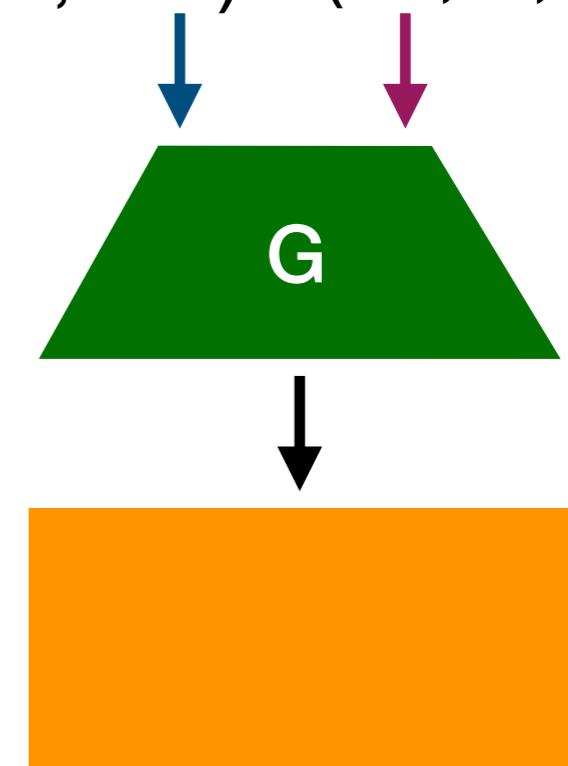
The disentanglement is with respect to the generative model.

For example:

(10, 20, red)    (10, 20, red)



(10, 20, red)    (10, 9, orange)



# Supervision

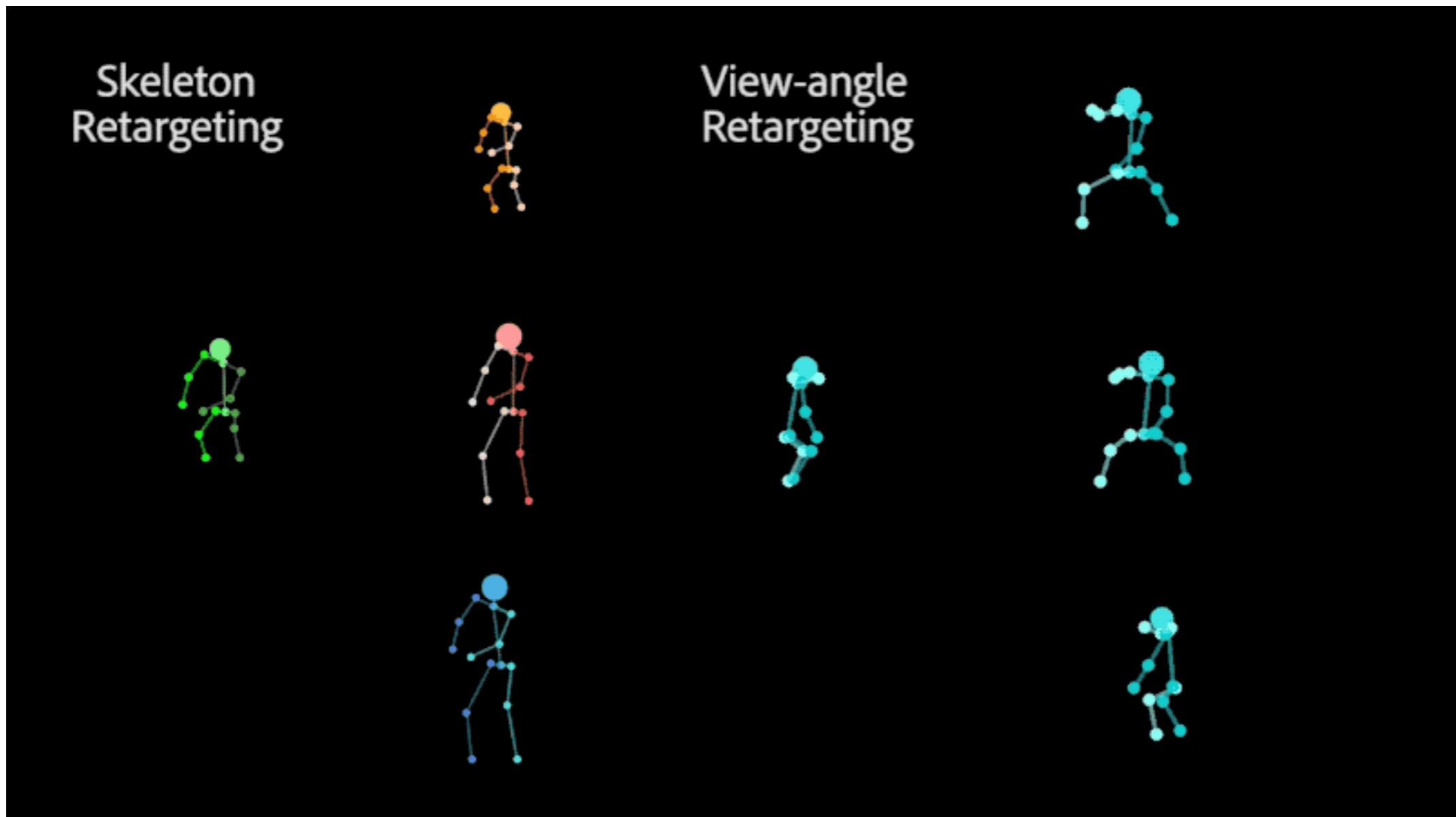


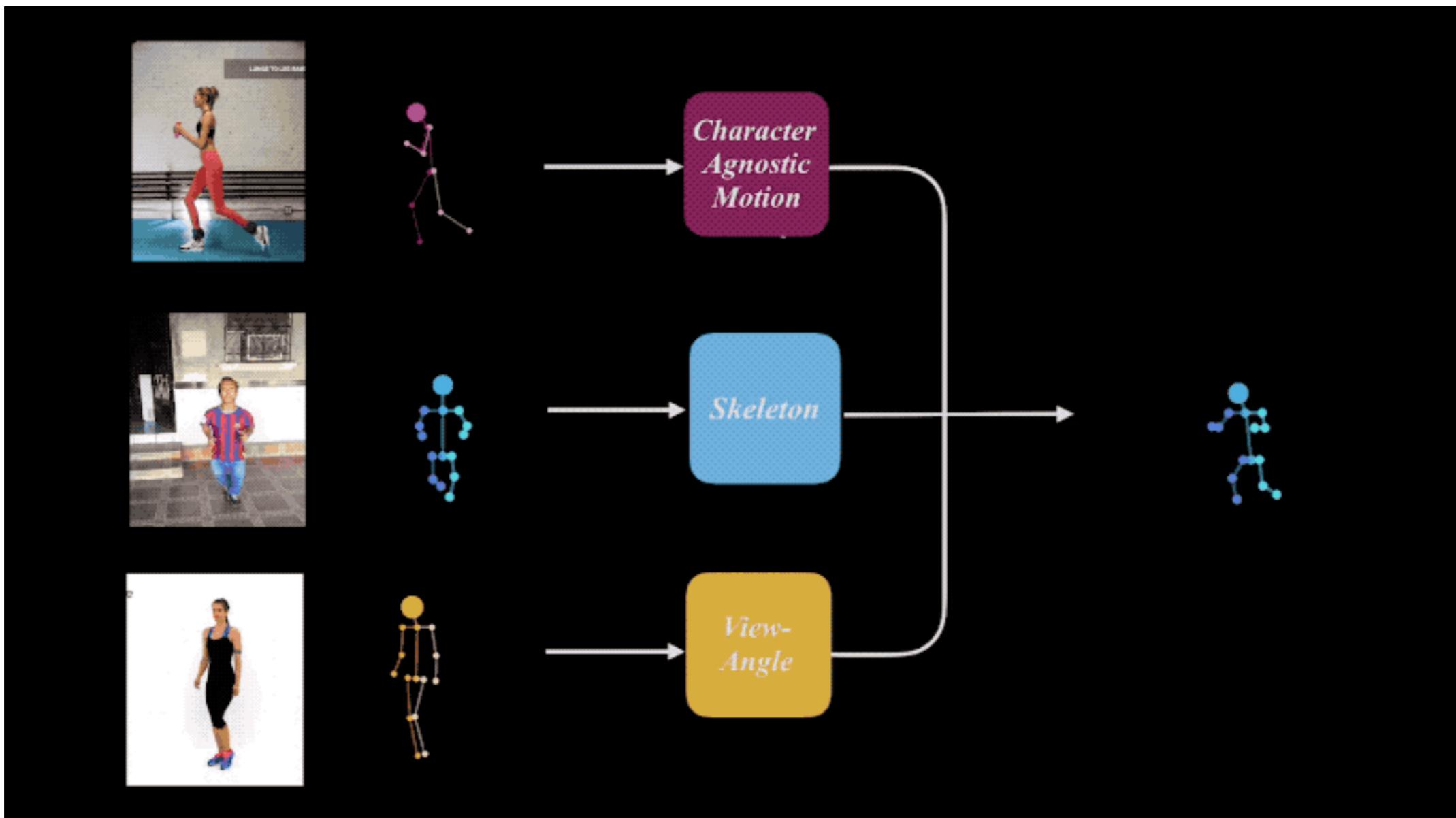
**Unsupervised**

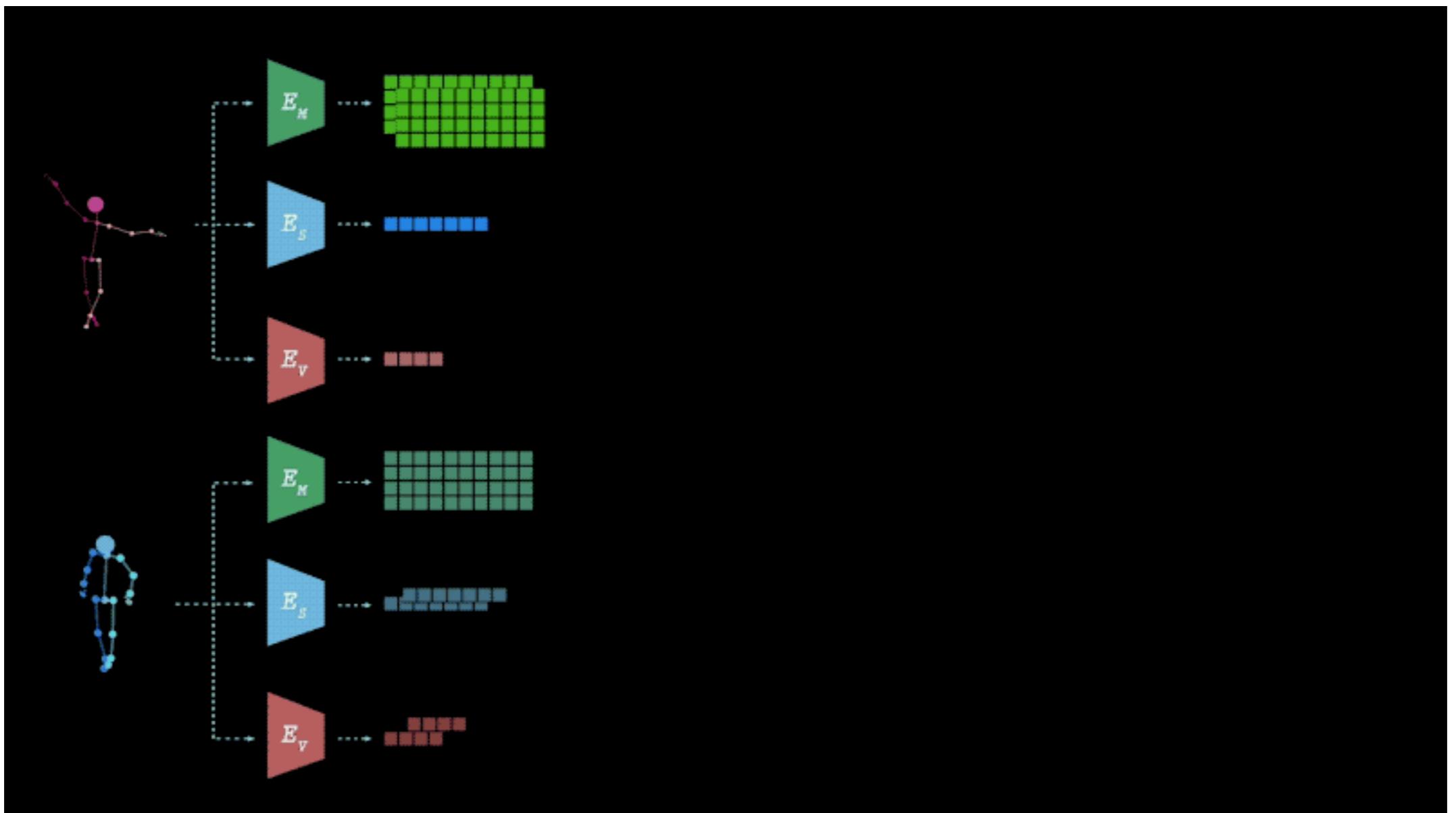
**Fully-  
Supervised**

# Learning Character-Agnostic Motion for Motion Retargeting in 2D

Kfir Aberman, Rundi Wu, Dani Lischinski, Baoquan Chen, Daniel Cohen-Or

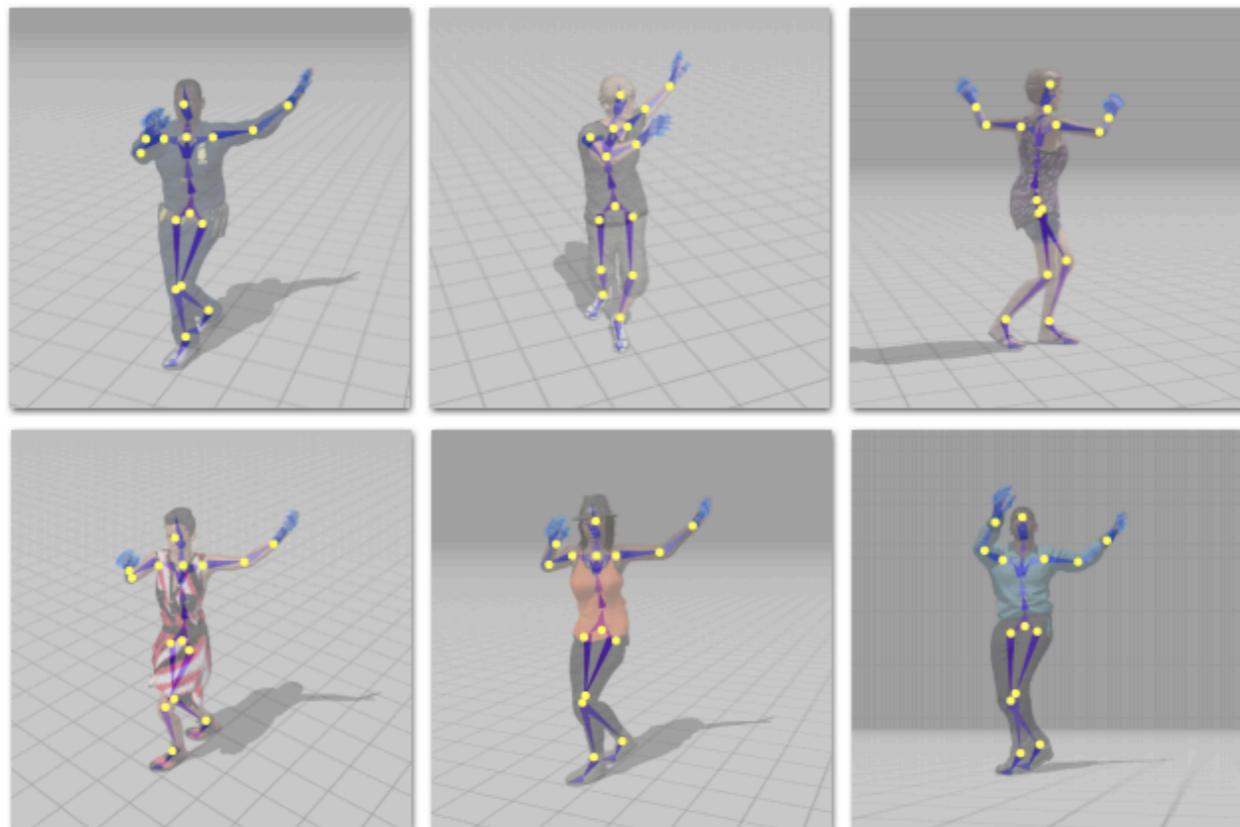






# Synthetic dataset

Multiple samples of each motion, as performed by the different characters, and these motions can be projected to 2D, from arbitrary view angles.



# Fully-Supervised

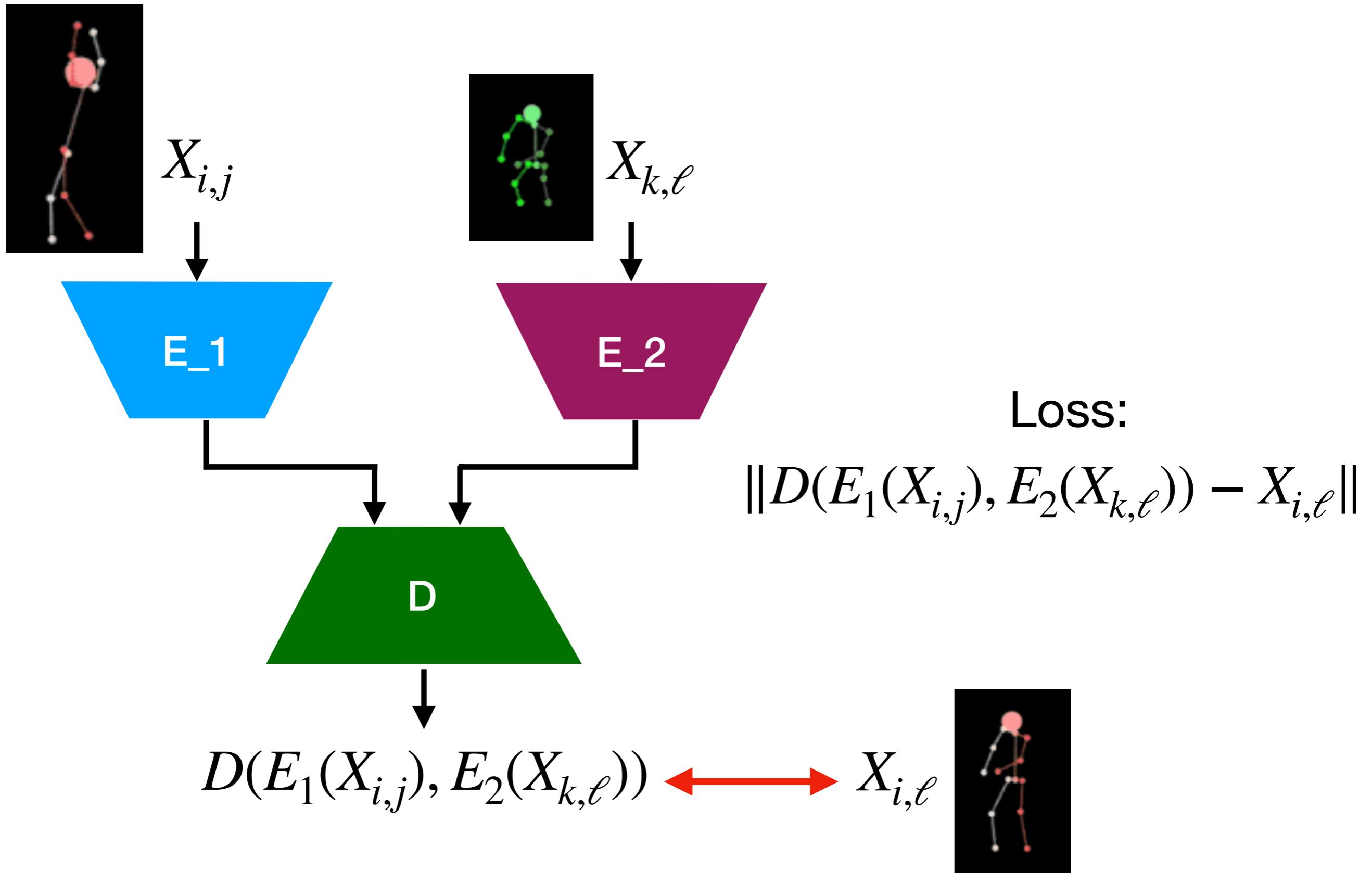
Example:  $\{X_{a,b}\}_{a \in A, b \in B}$

Let A and B be two independent factors of variation, then the dataset contains triplets:

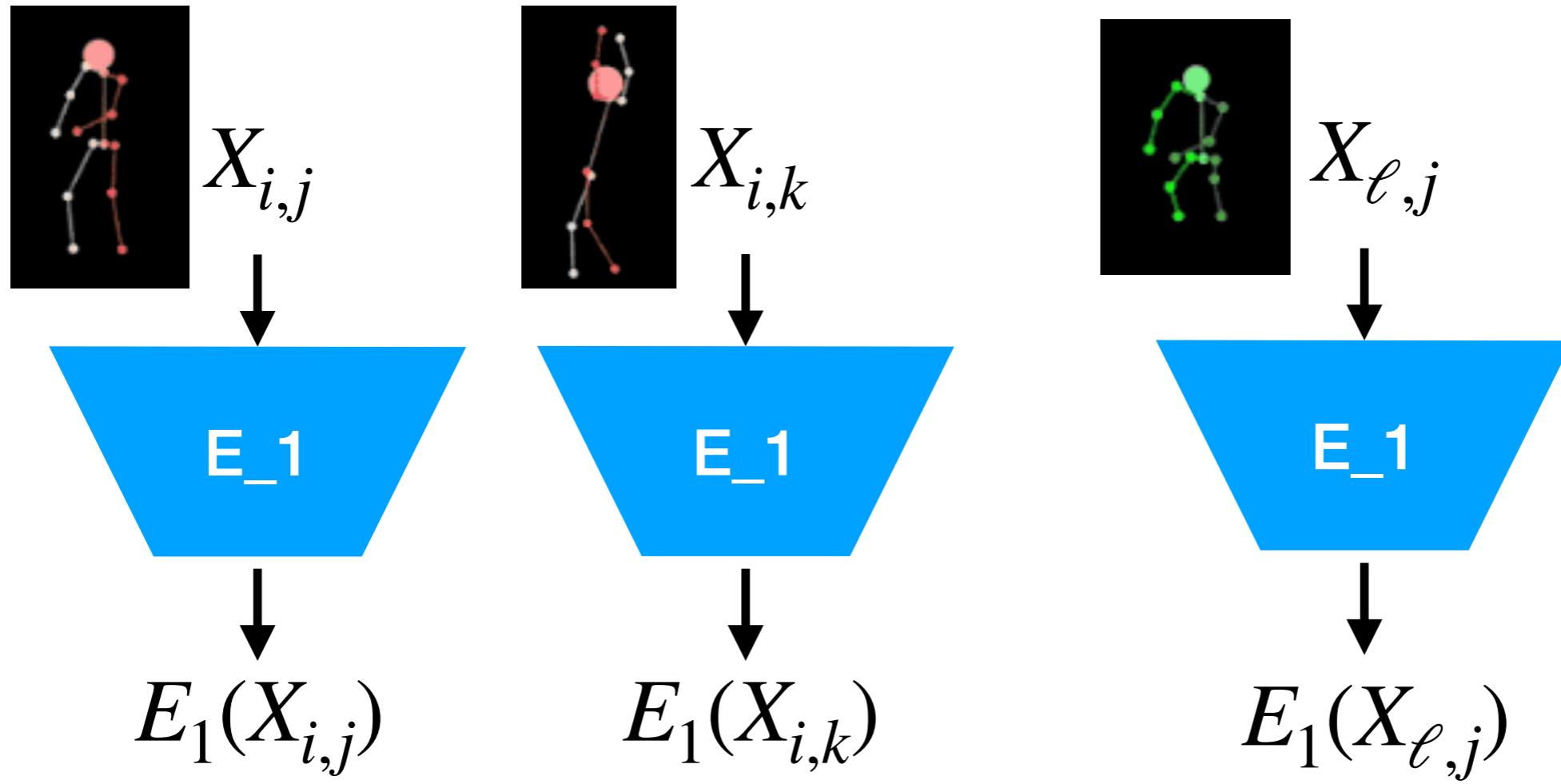
$$(X_{i,j}, X_{i,k}, X_{\ell,j})$$



# Cross Loss



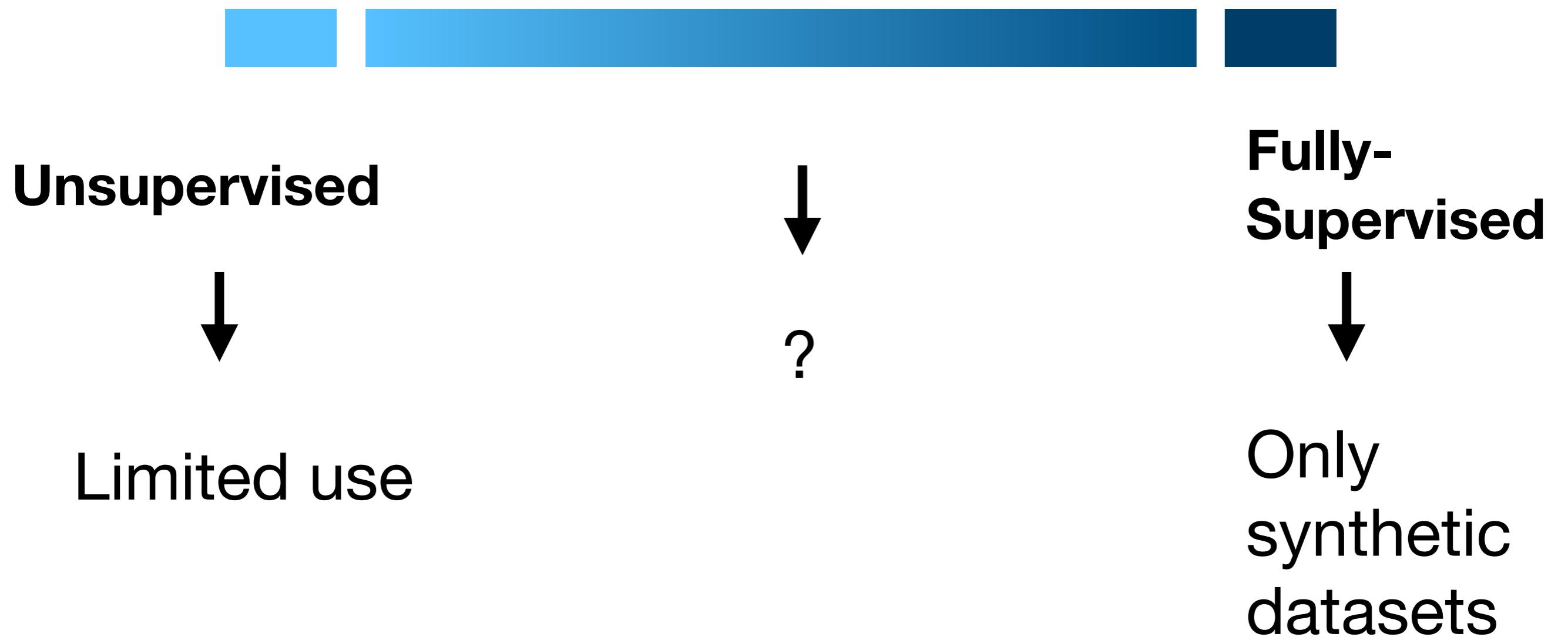
# Triplet Loss



Loss:

$$\max (\|E_1(X_{i,j}) - E_1(X_{i,k})\| - \|E_1(X_{i,j}) - E_1(X_{\ell,j})\| + \varepsilon, 0)$$

# Supervision

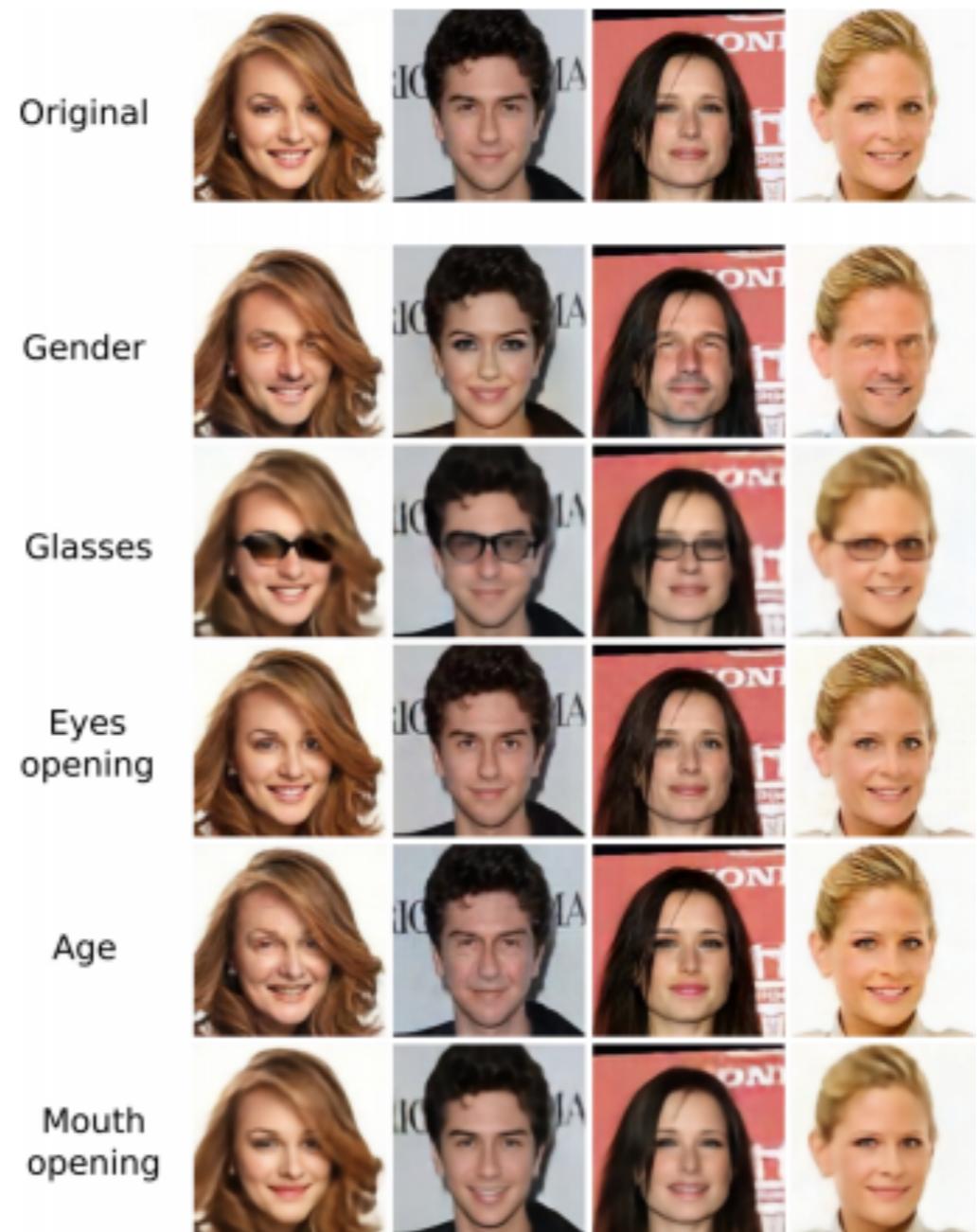


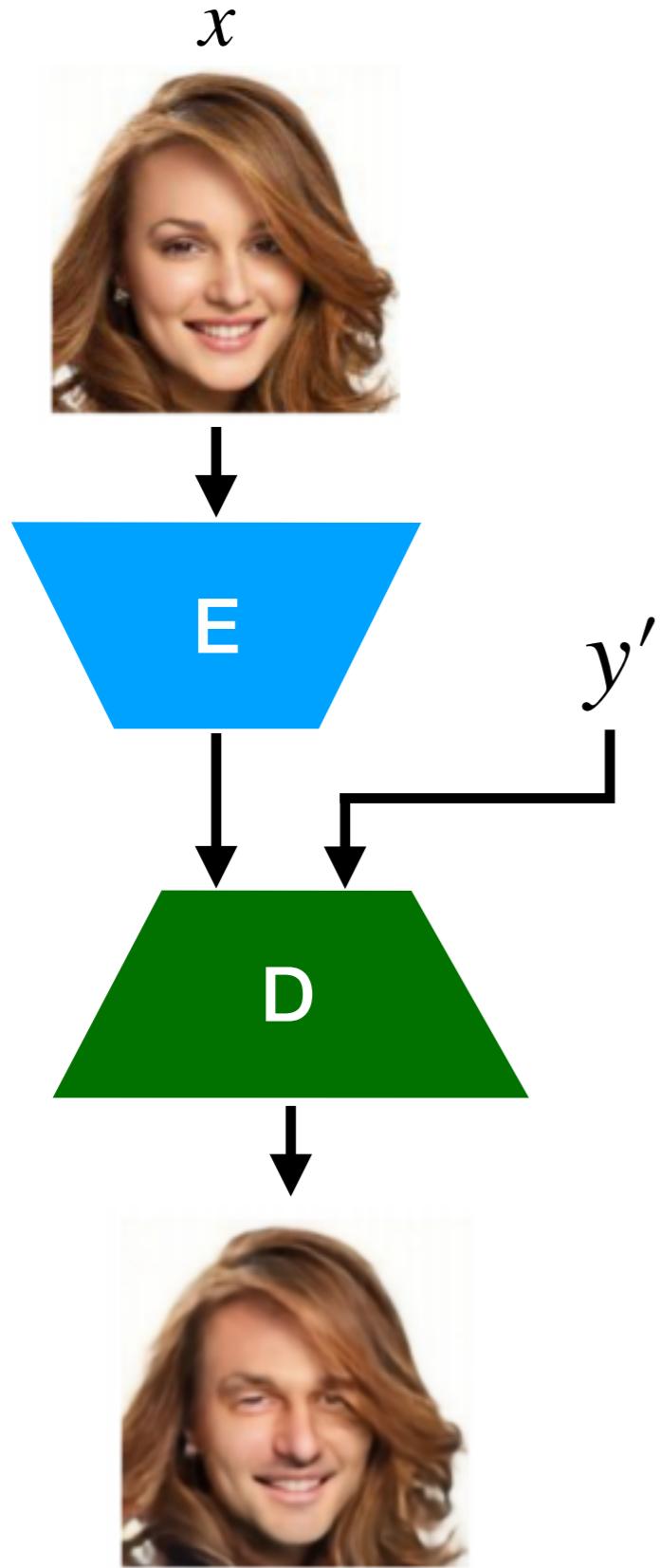
# Fader Networks: Manipulating Images by Sliding Attributes

Guillaume Lample, Neil Zeghidour, Nicolas Usunier, Antoine Bordes, Ludovic Denoyer,  
Marc'Aurelio Ranzato

Set of images and several attributes for each image.

$$\{(x, y)\}_{x \in X, y \in \{0,1\}^k}$$

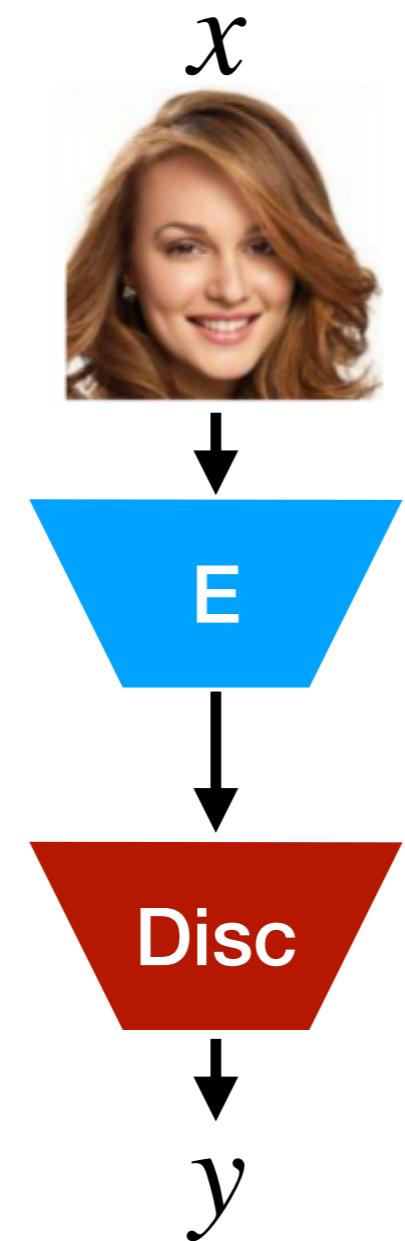




We would like to find representation of the images which is invariant to the image attributes.

# Adversarial Loss

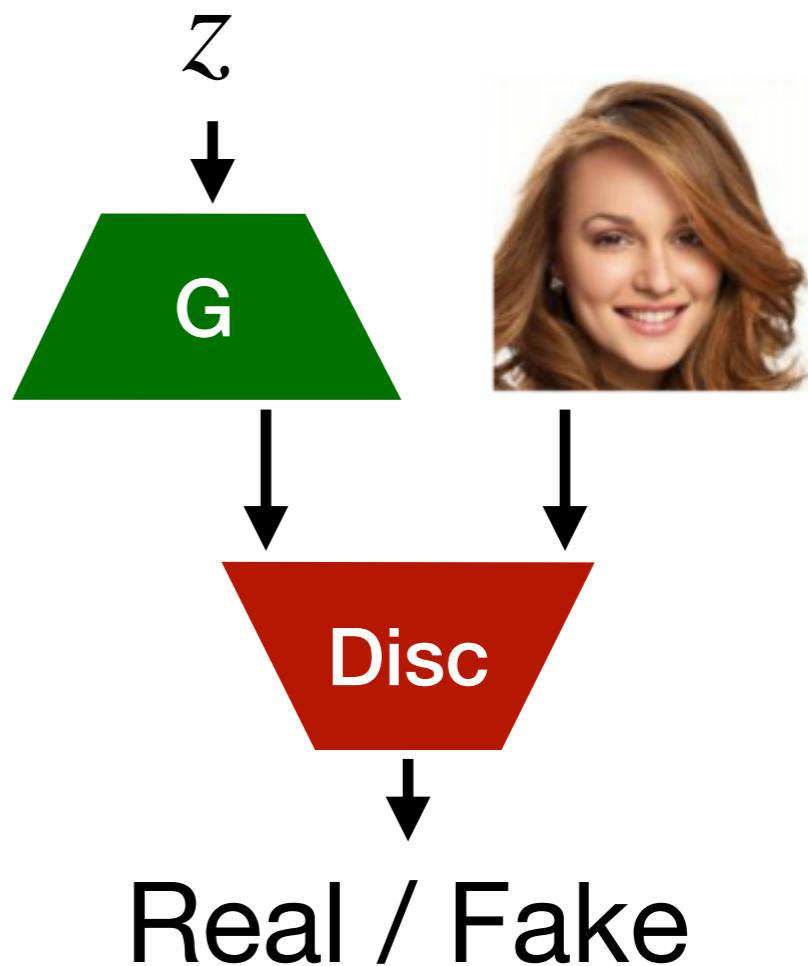
FaderNet:



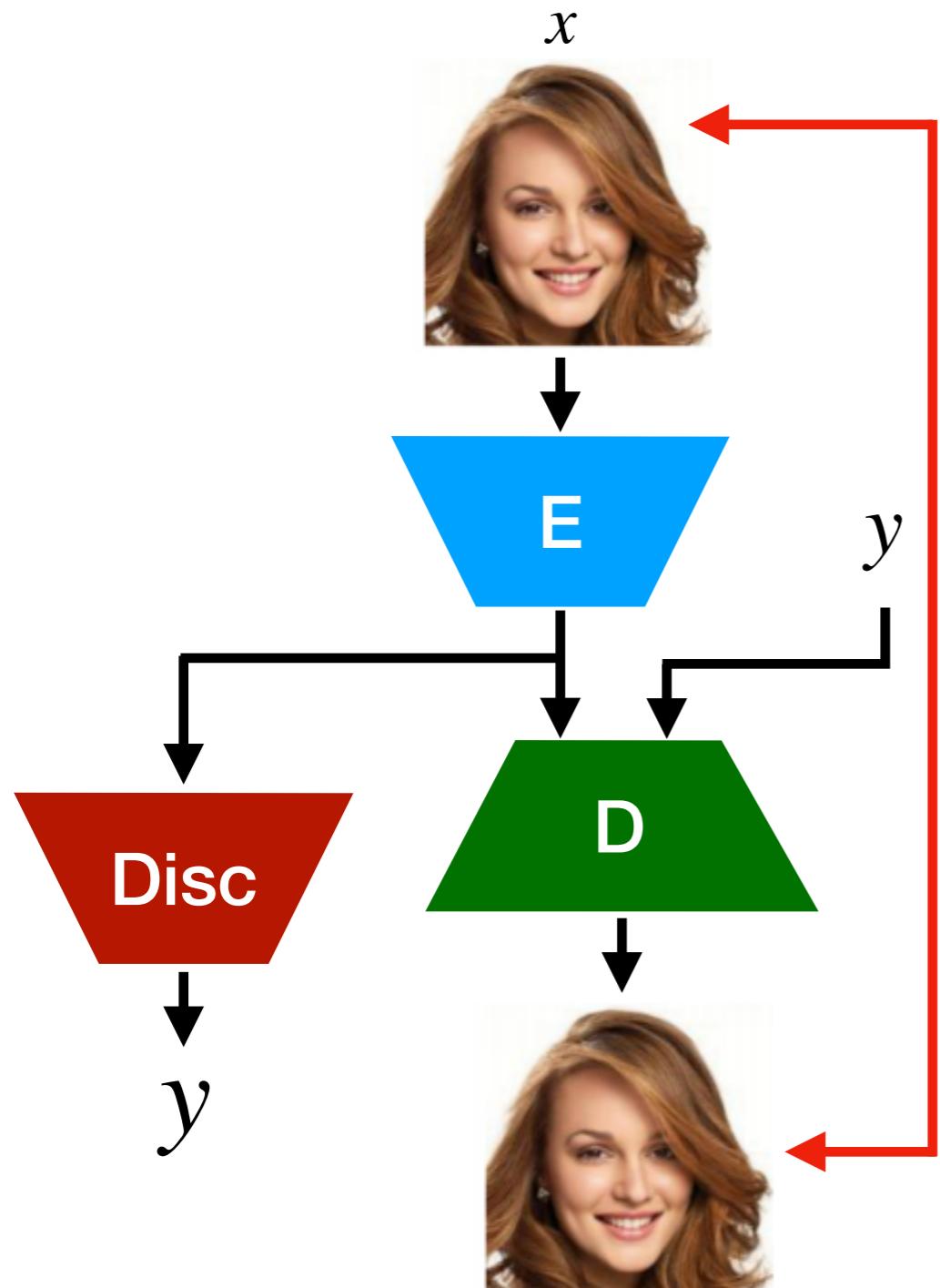
Encoder try to fool  
the discriminator.

Discriminator  
try to predict  $y$ .

GAN:



# Loss Function



## 1. Adversarial loss:

Discriminator try to predict  $y$ .  
Encoder try to fool the discriminator.

## 2. Reconstruction loss:

$$\mathcal{L}_R = \|D(E(x), y) - x\|$$

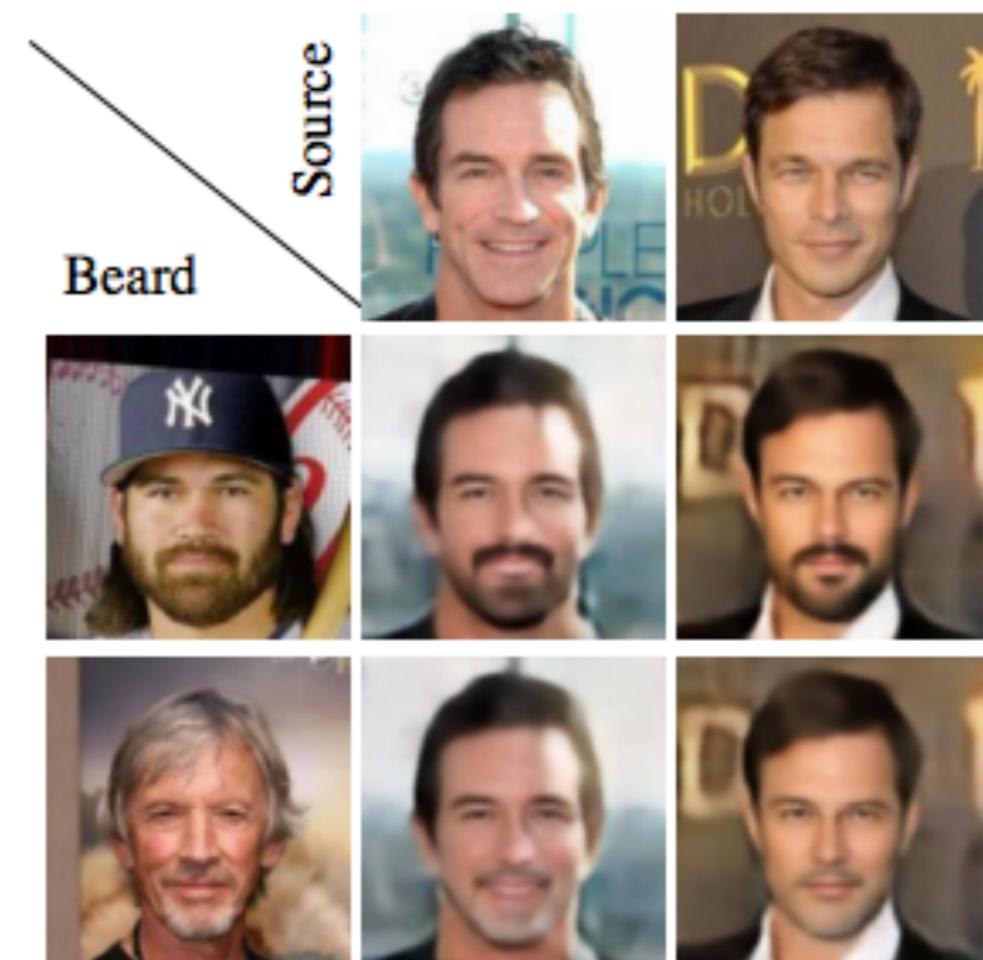
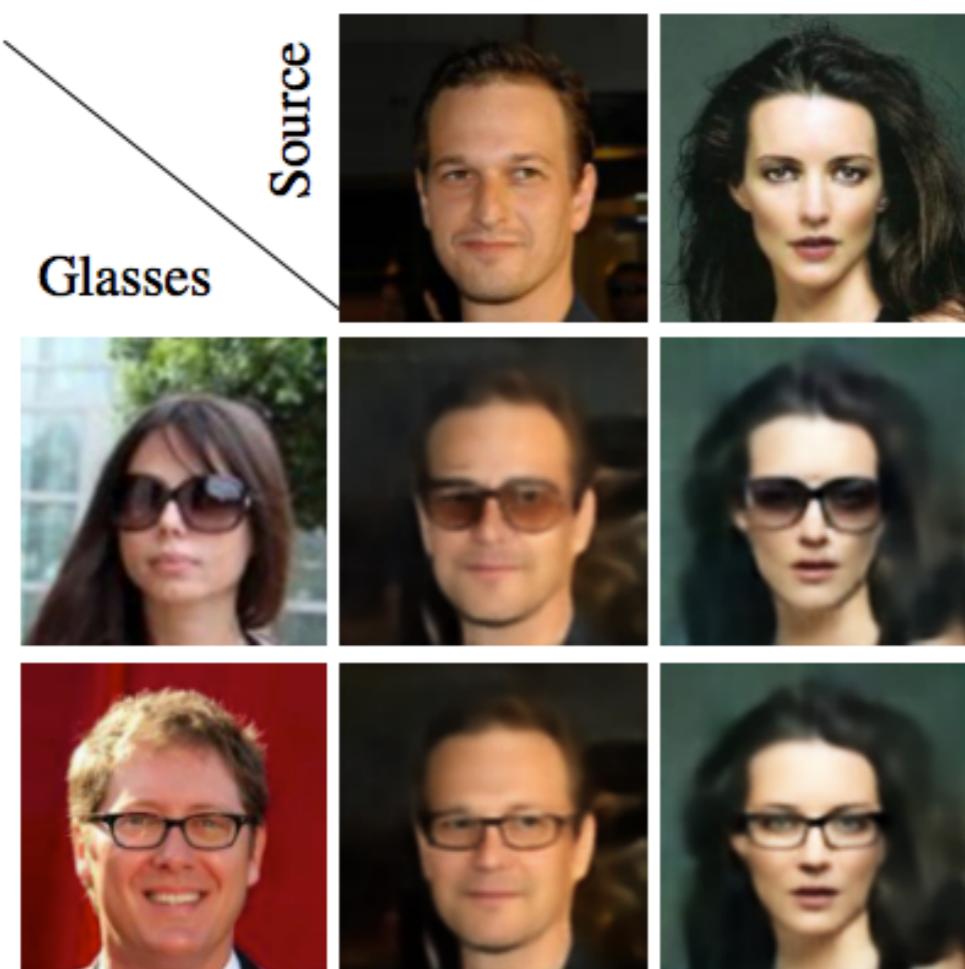
# Sliding



# EMERGING DISENTANGLEMENT IN AUTO-ENCODER BASED UNSUPERVISED IMAGE CONTENT TRANSFER

Ori Press, Tomer Galanti, Sagie Benaim, Lior Wolf

Content transfer:



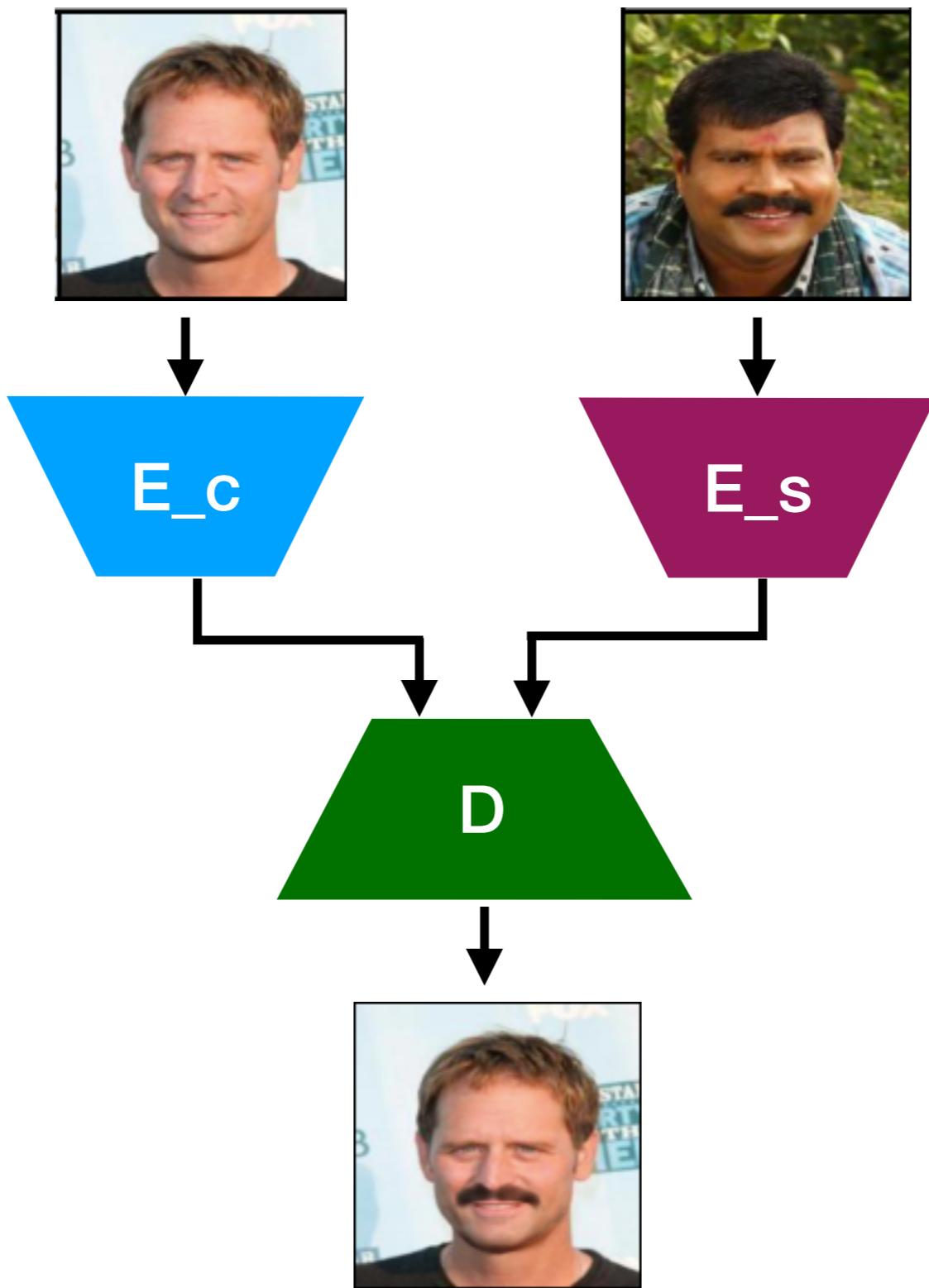
# Unsupervised Content Transfer

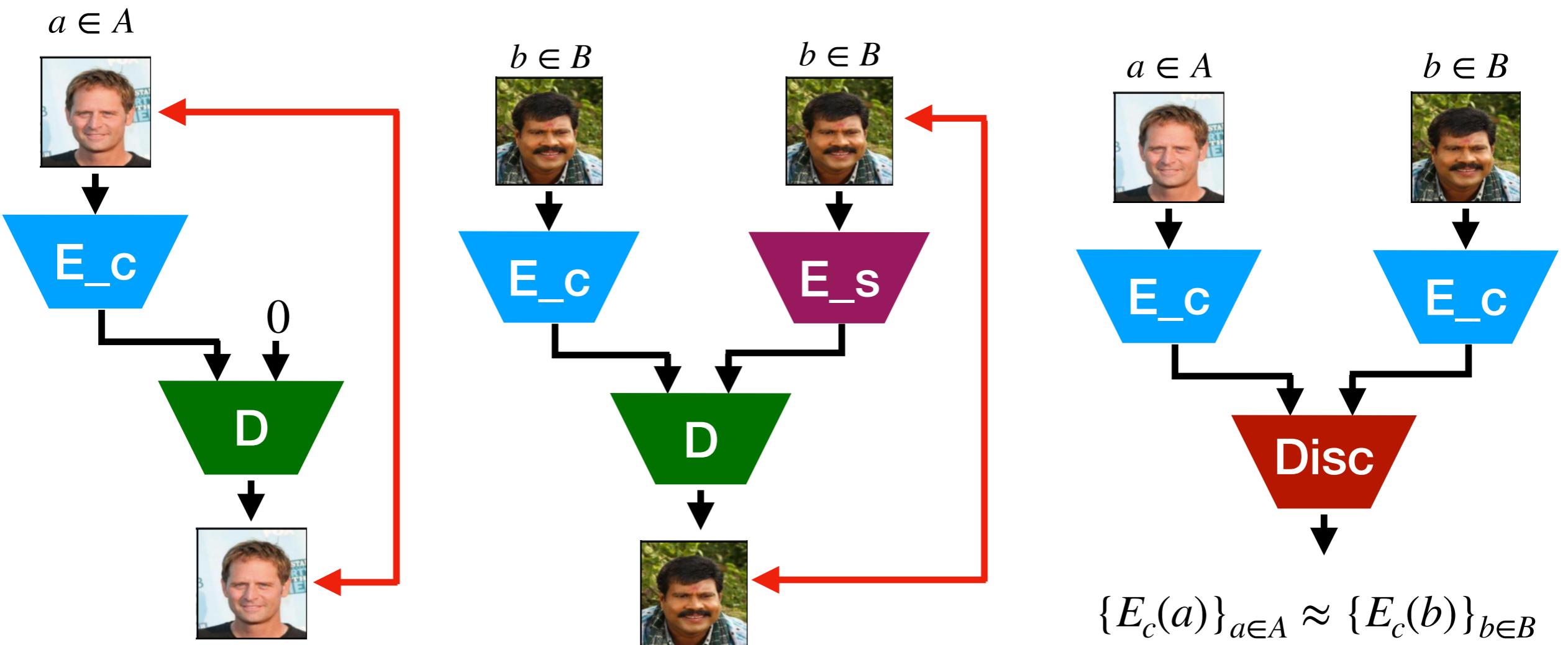


Domain A contains  
common content



Domain B contains  
common and  
separate content





# Domain Confusion

$$a \in A$$

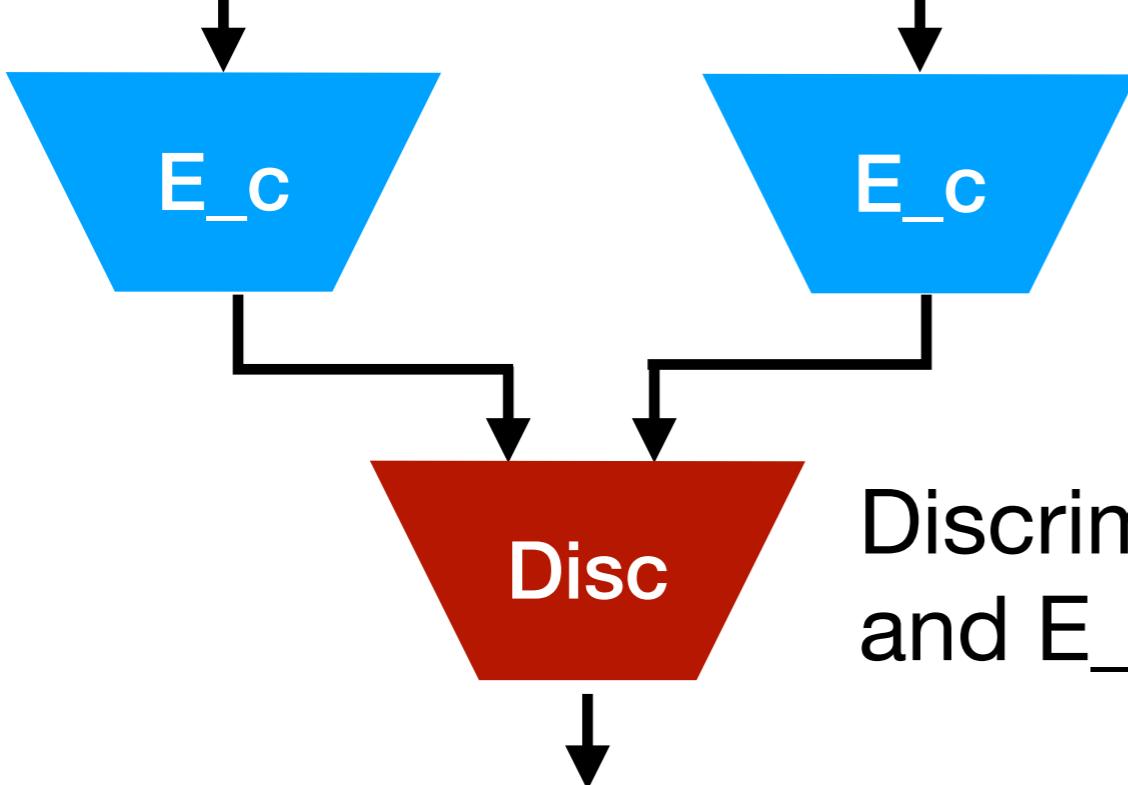


$$b \in B$$



Goal:

$$\{E_c(a)\}_{a \in A} \approx \{E_c(b)\}_{b \in B}$$

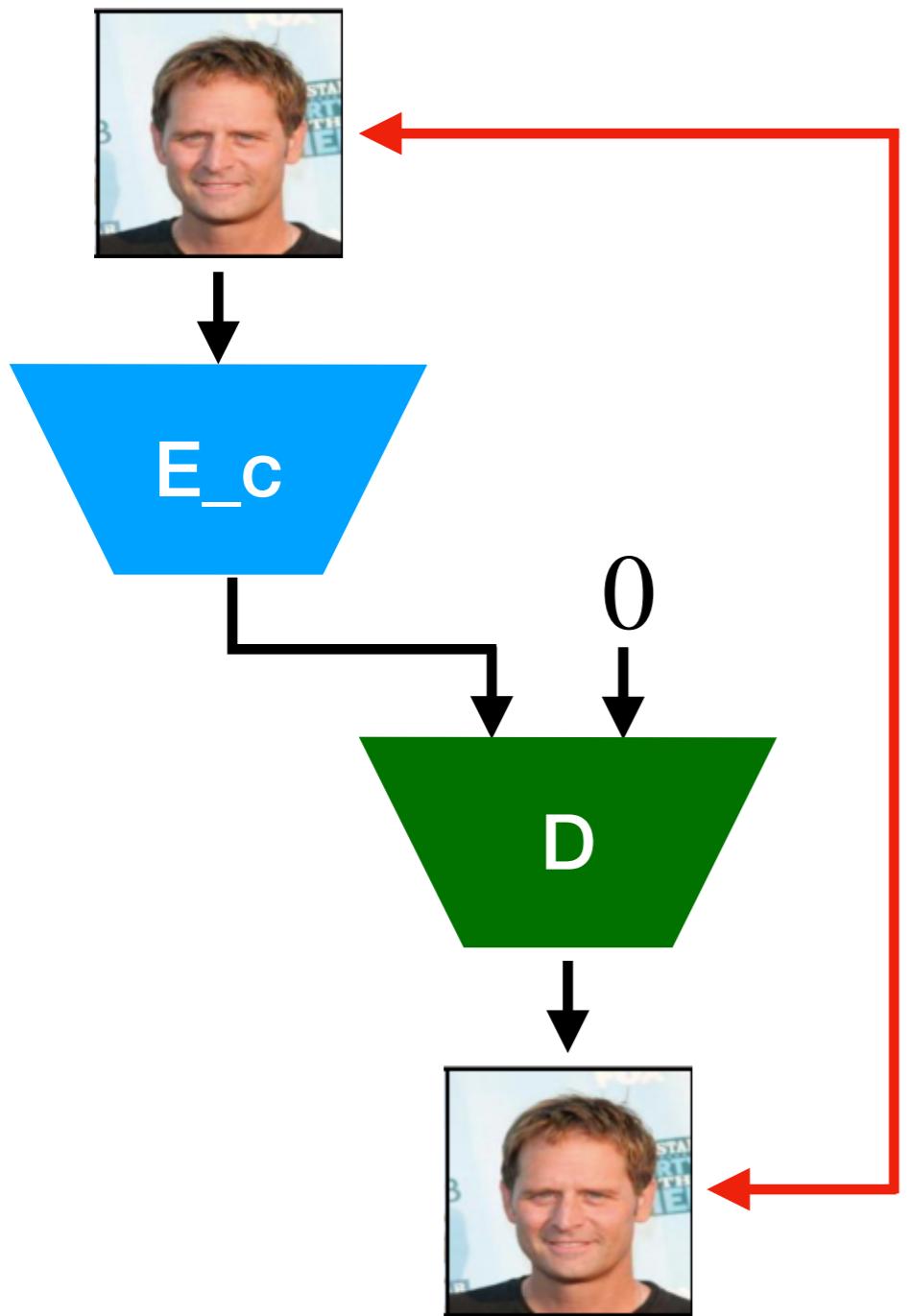


Encoder try to fool the discriminator

Discriminator try to distinguish  $E_c(a)$  and  $E_c(b)$

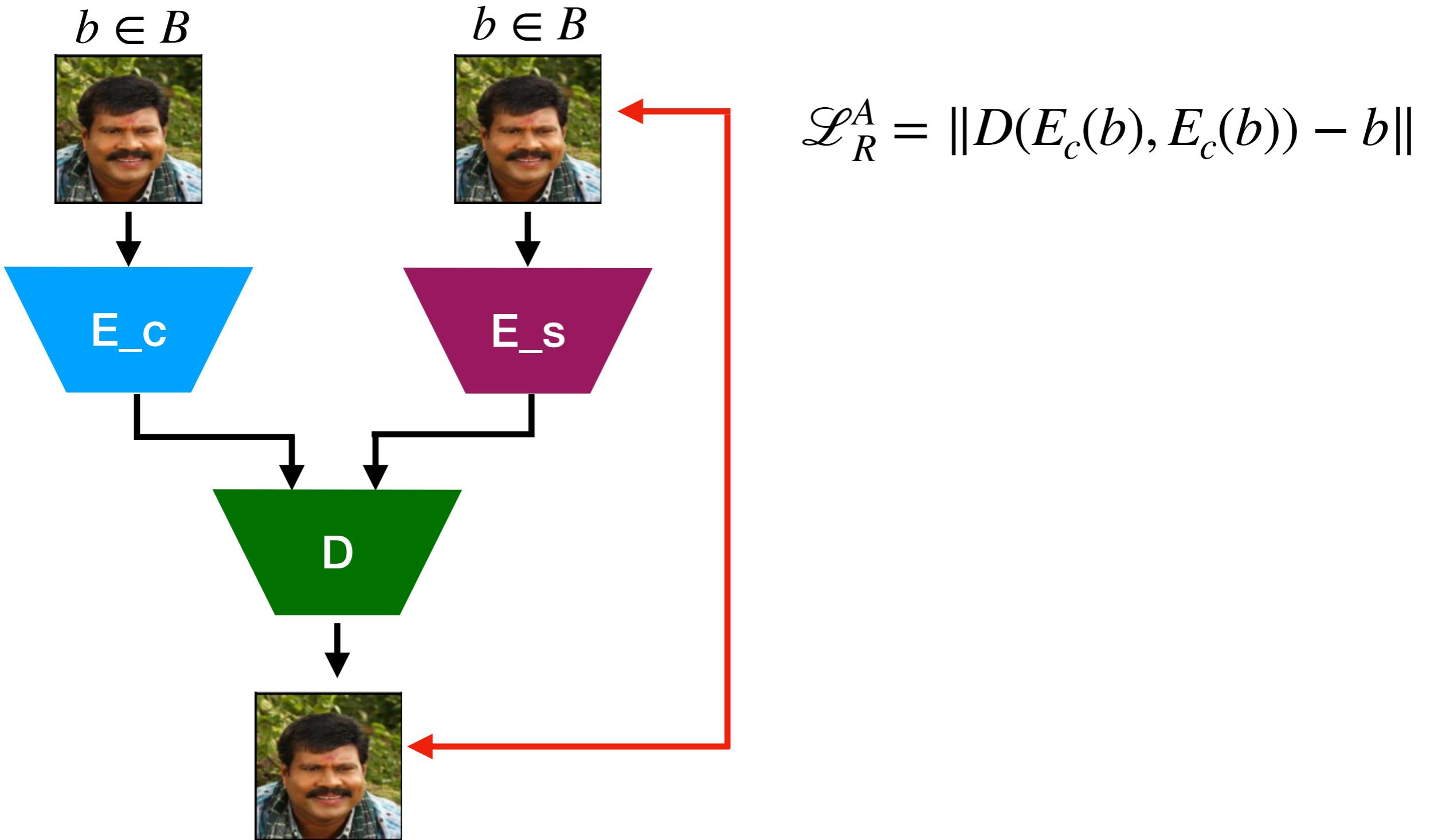
# Reconstruction

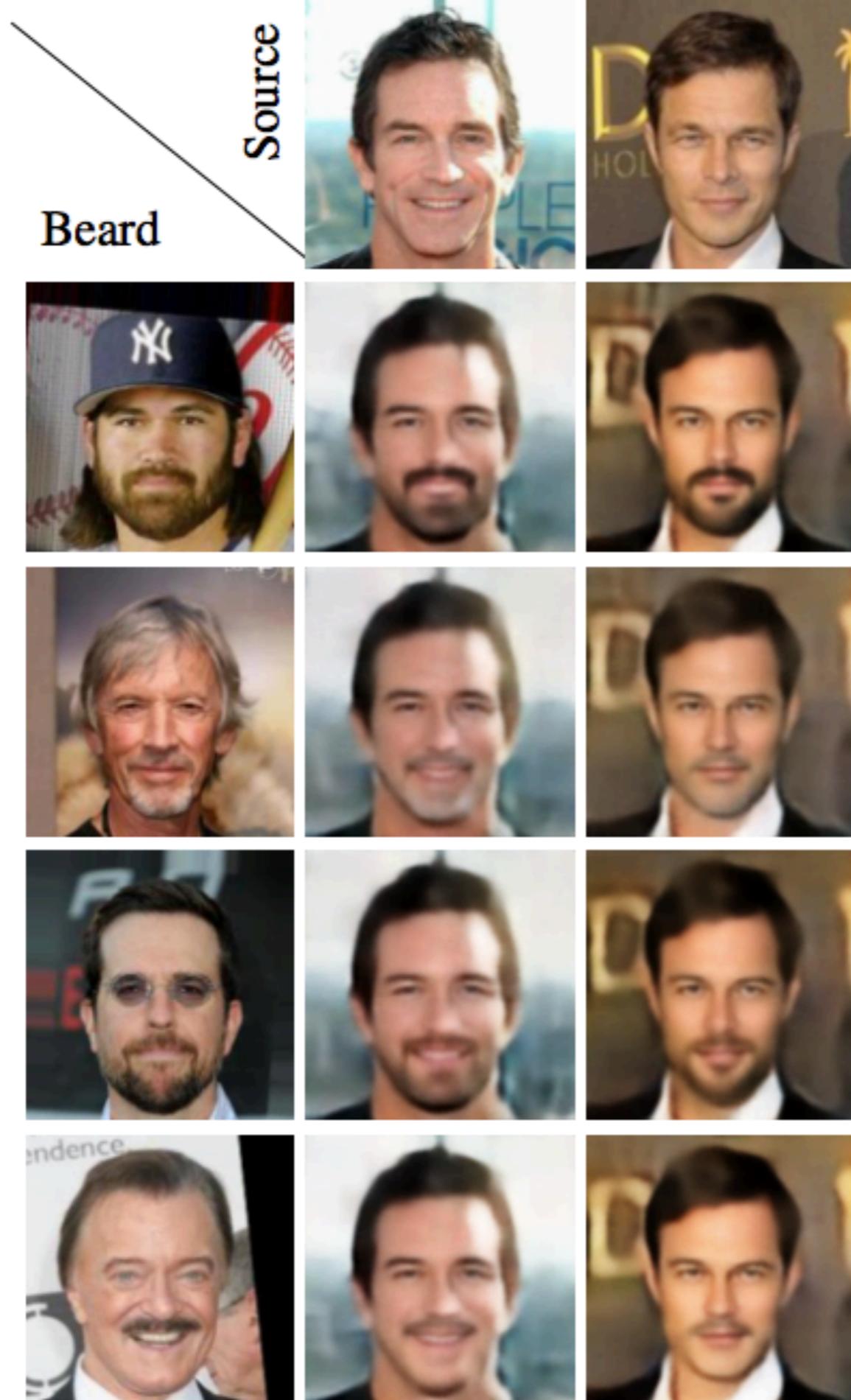
$a \in A$



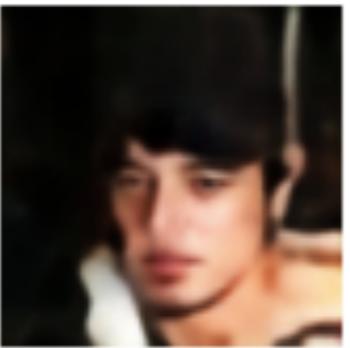
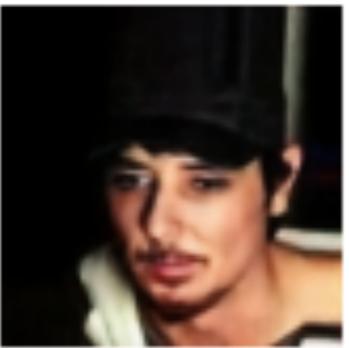
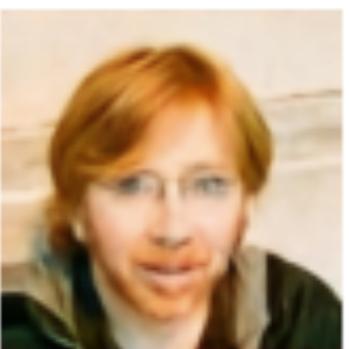
$$\mathcal{L}_R^A = \|D(E_c(a), 0) - a\|$$

# Reconstruction 2





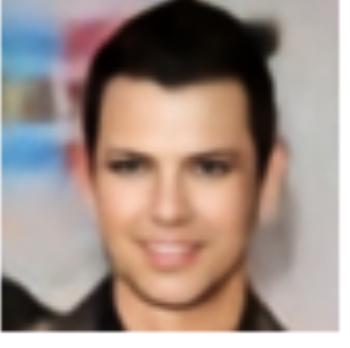
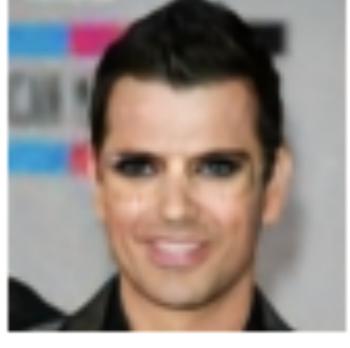
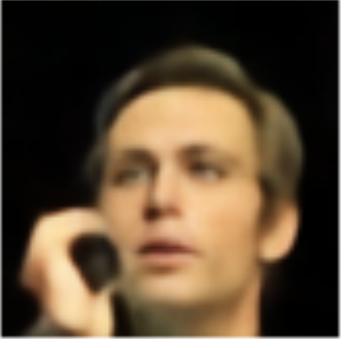




Original

Fader

Our



Original

Fader

Our

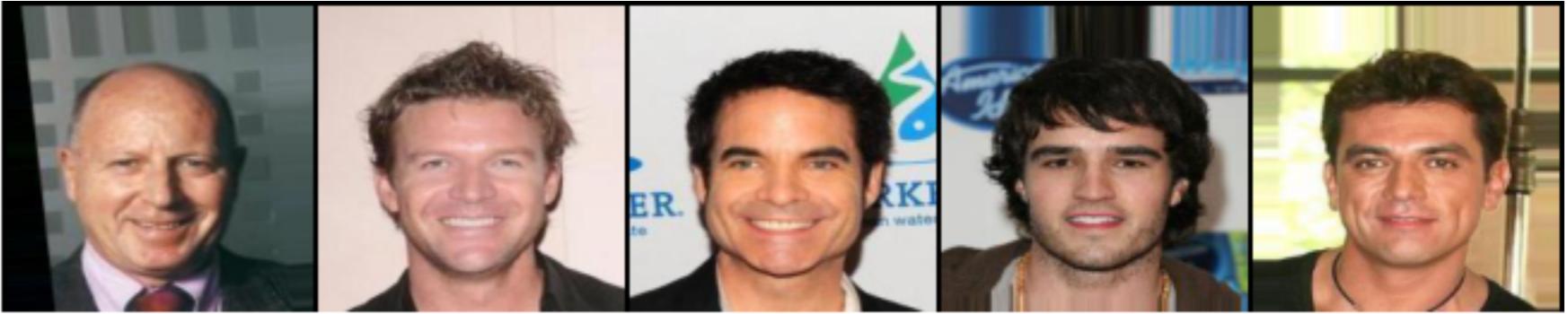
# MASK BASED UNSUPERVISED CONTENT TRANSFER

Ron Mokady, Sagie Benaim, Lior Wolf, Amit Bermano

- Transfer content using a mask for state-of-the-art quality.
- Use the mask as a weakly-supervised semantic segmentation.

# Comparison





# Using a mask

$$a \in A$$



$$b \in B$$



$$a \in A$$



$$E_c$$

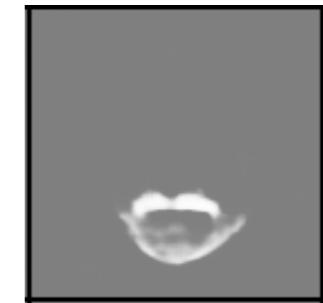
$$E_c(a)$$

$$E_s$$

$$E_s(b)$$

$$E_c(a) \ E_s(b)$$

$$D_2$$



$$z(a, a, b) = m \odot z^{\text{raw}} + (1 - m) \odot a$$

$$m, z^{\text{raw}} = D_2(E_c(a), E_s(b))$$

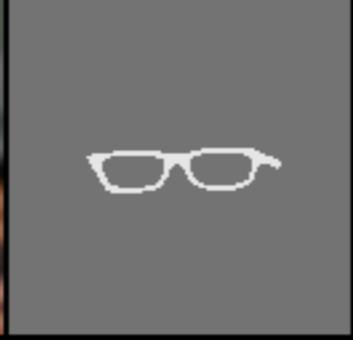
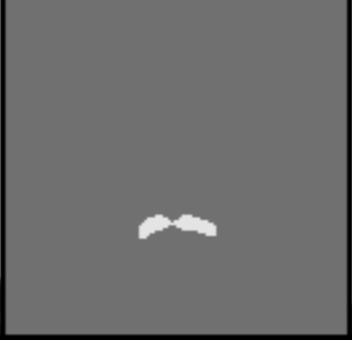
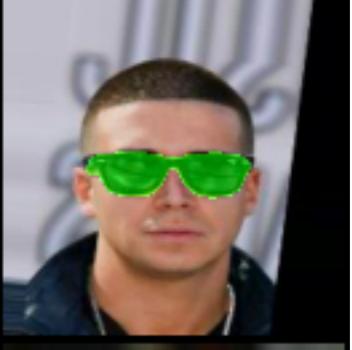
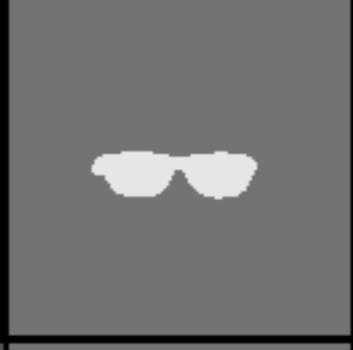
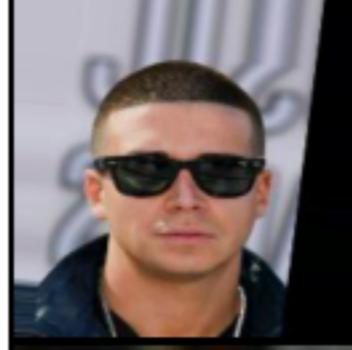
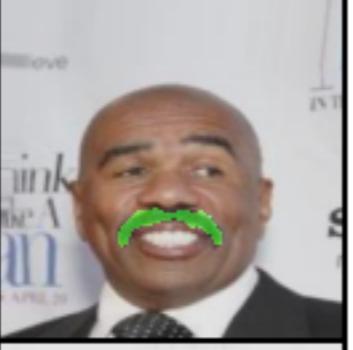
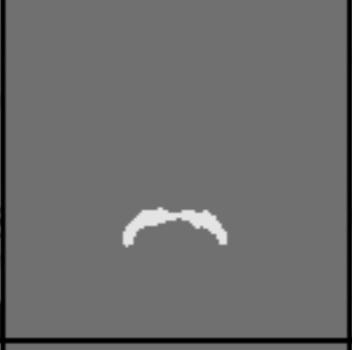
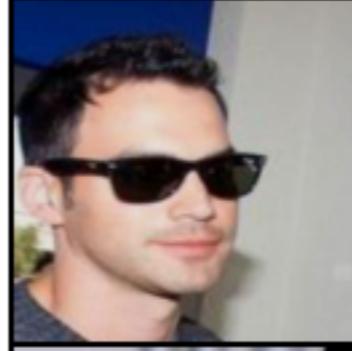
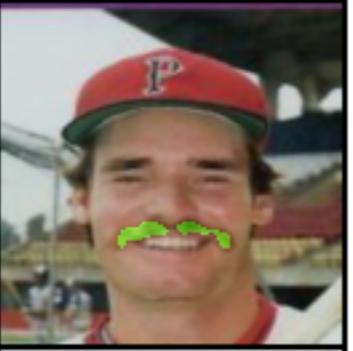
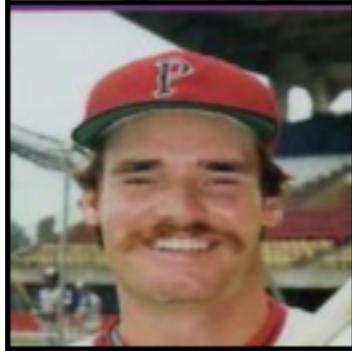


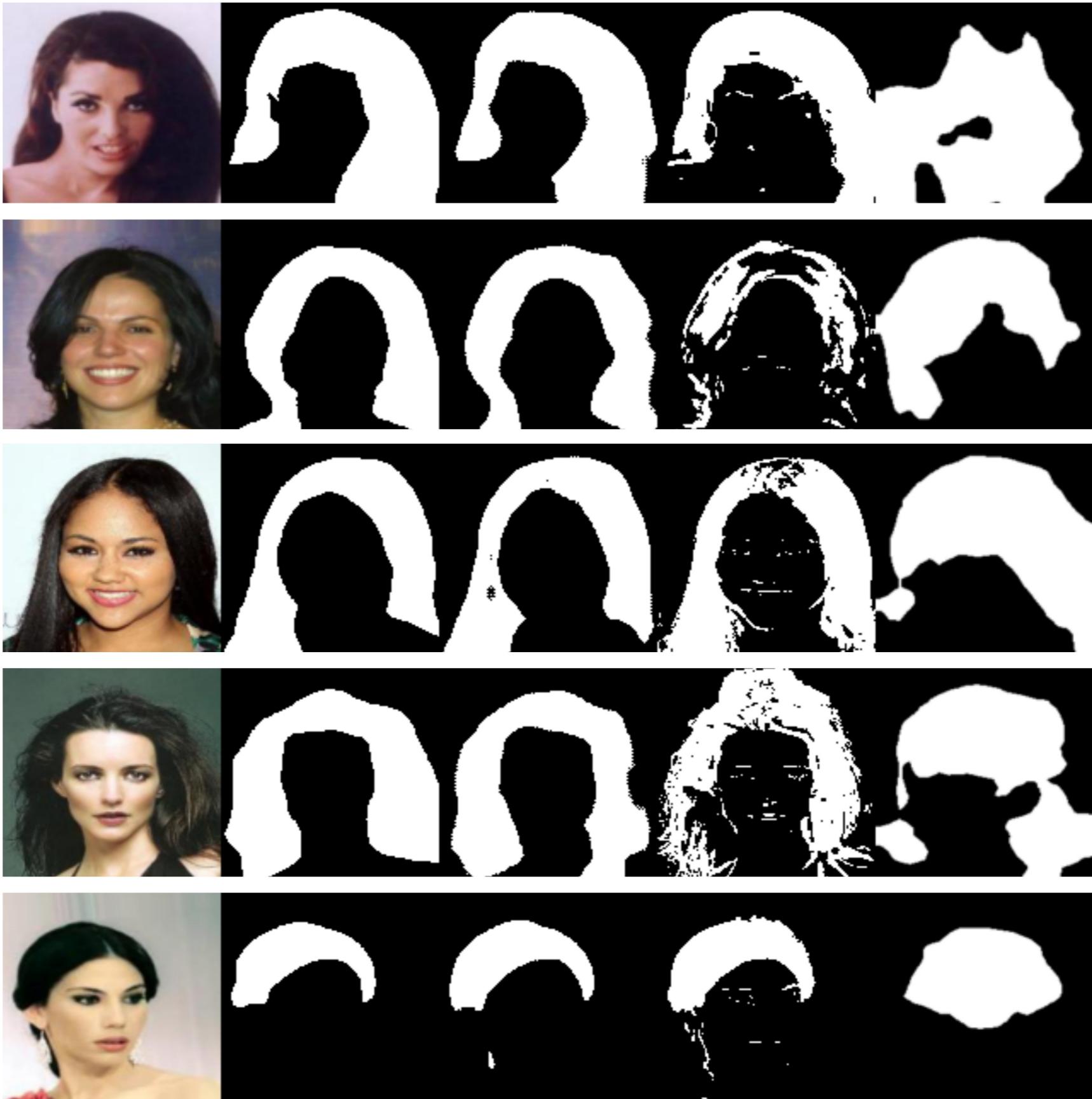
$$z(a, a, b)$$



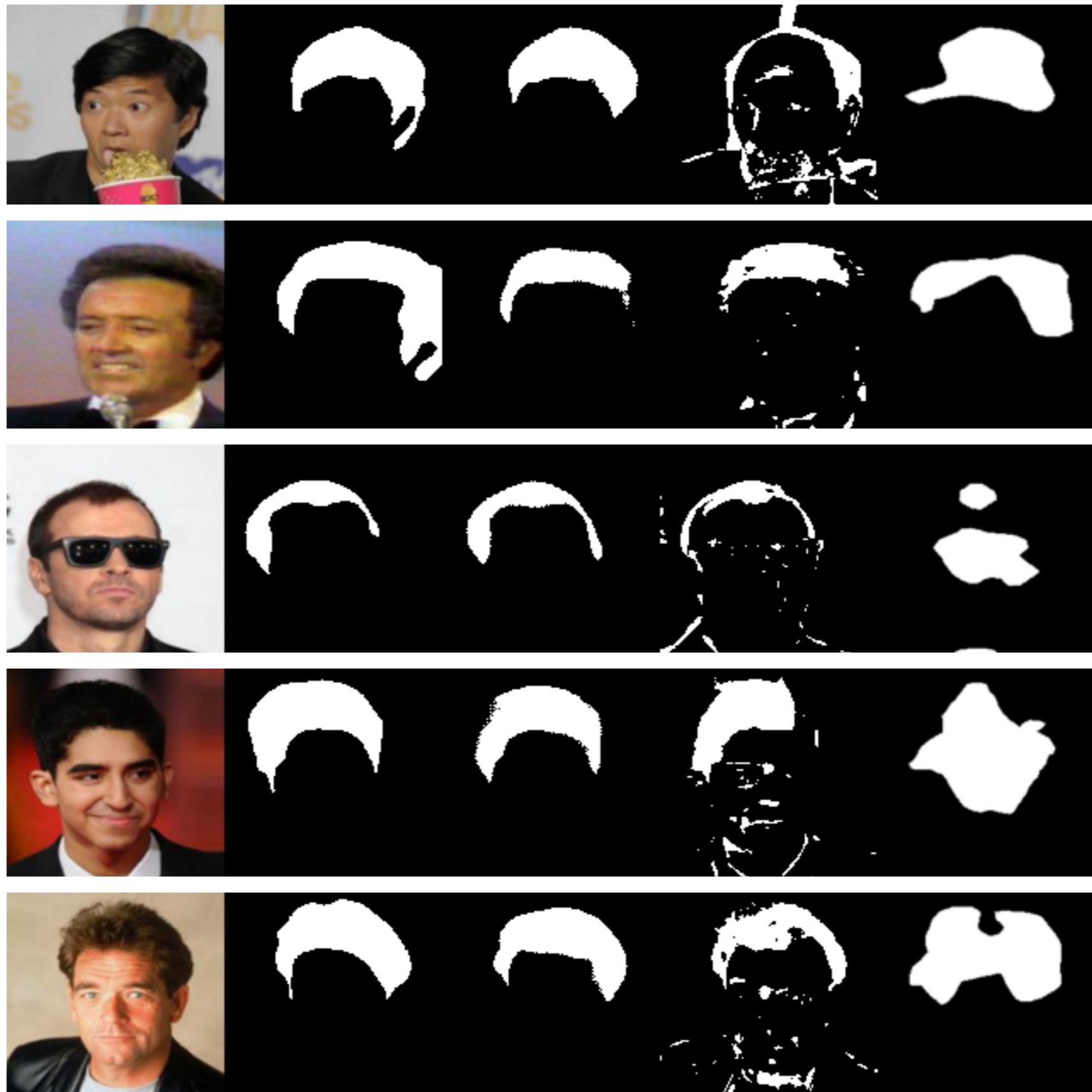








**GT      Ours      Press et al.      Ahn et al.**

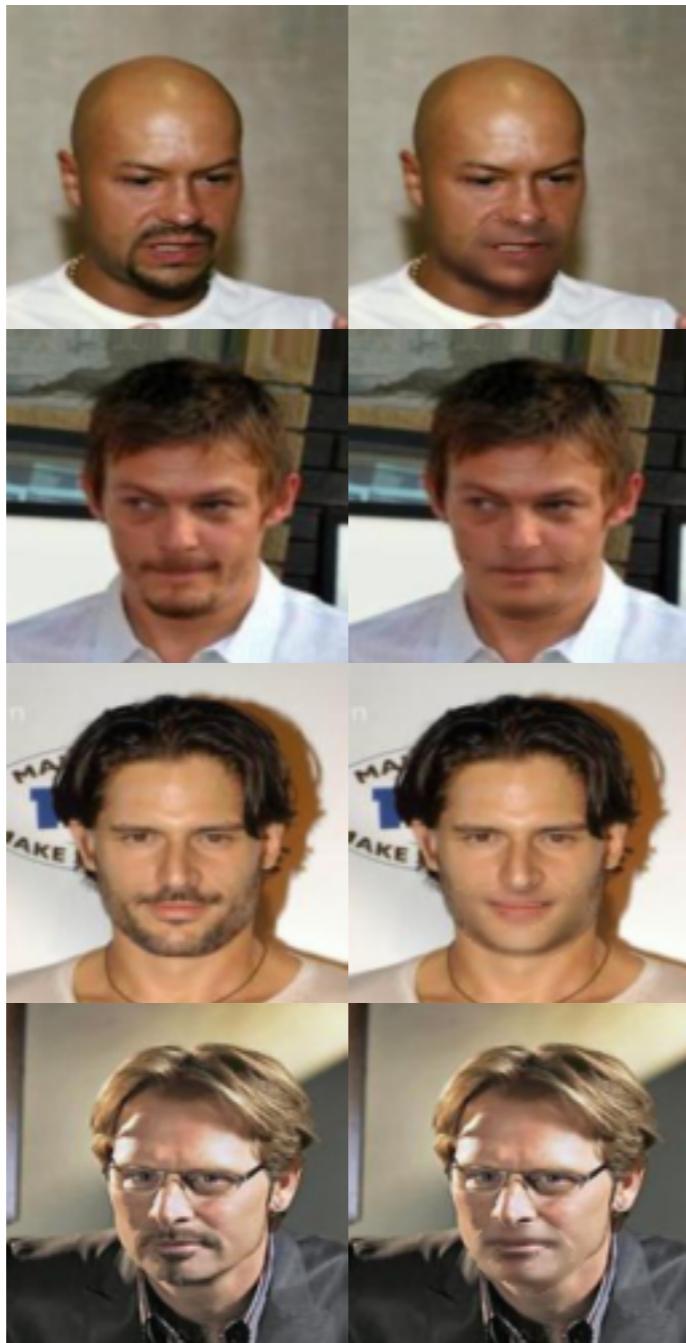


GT

Ours

Press et al. Ahn et al.

# Removal



# Generate Unseen Images



Domain A: glasses  
without mustache.



Domain B: mustache  
without glasses.

**Can we generate face with both mustche and glasses? Or one without mustache and glasses?**

# Domain Intersection and Domain Difference

Sagie Benaim, Michael Khaitov , Tomer Galanti, Lior Wolf

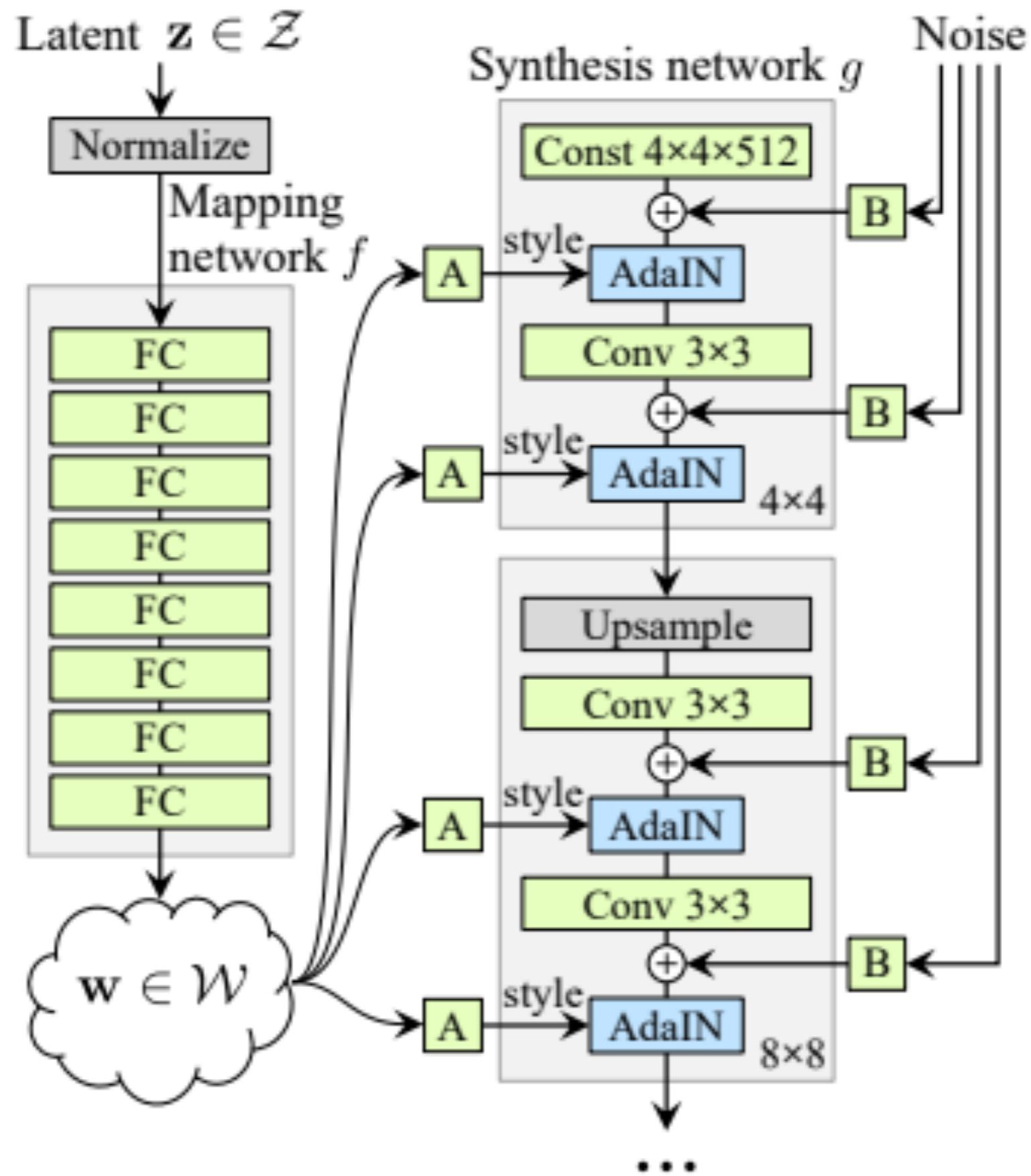
Three encoders, one for the common and two for the attributes.

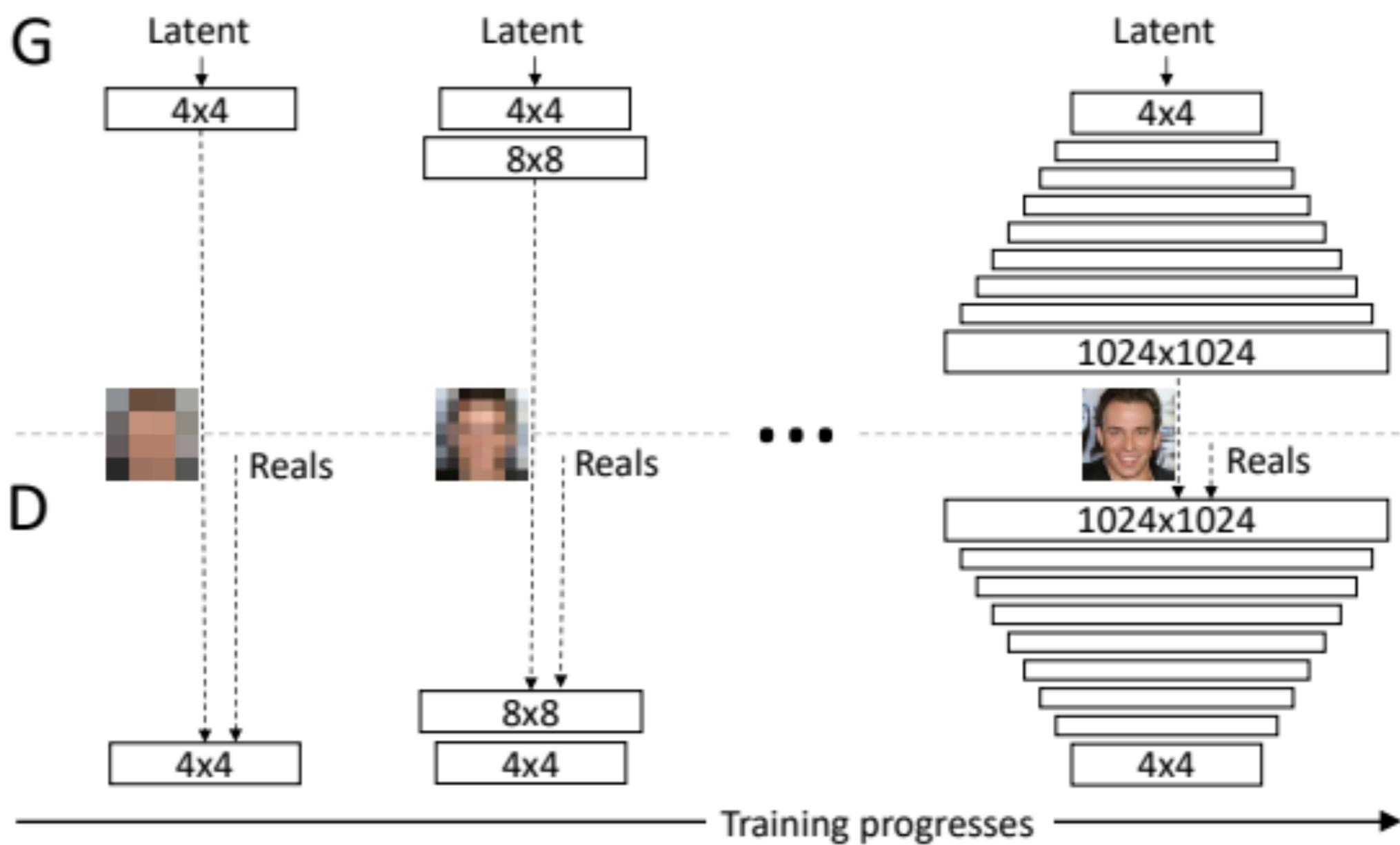
Same Reconstruction and Domain-Confusion loss as Press et el. with Additional zero loss.

# A Style-Based Generator Architecture for Generative Adversarial Networks

Tero Karras, Samuli Laine, Timo Aila







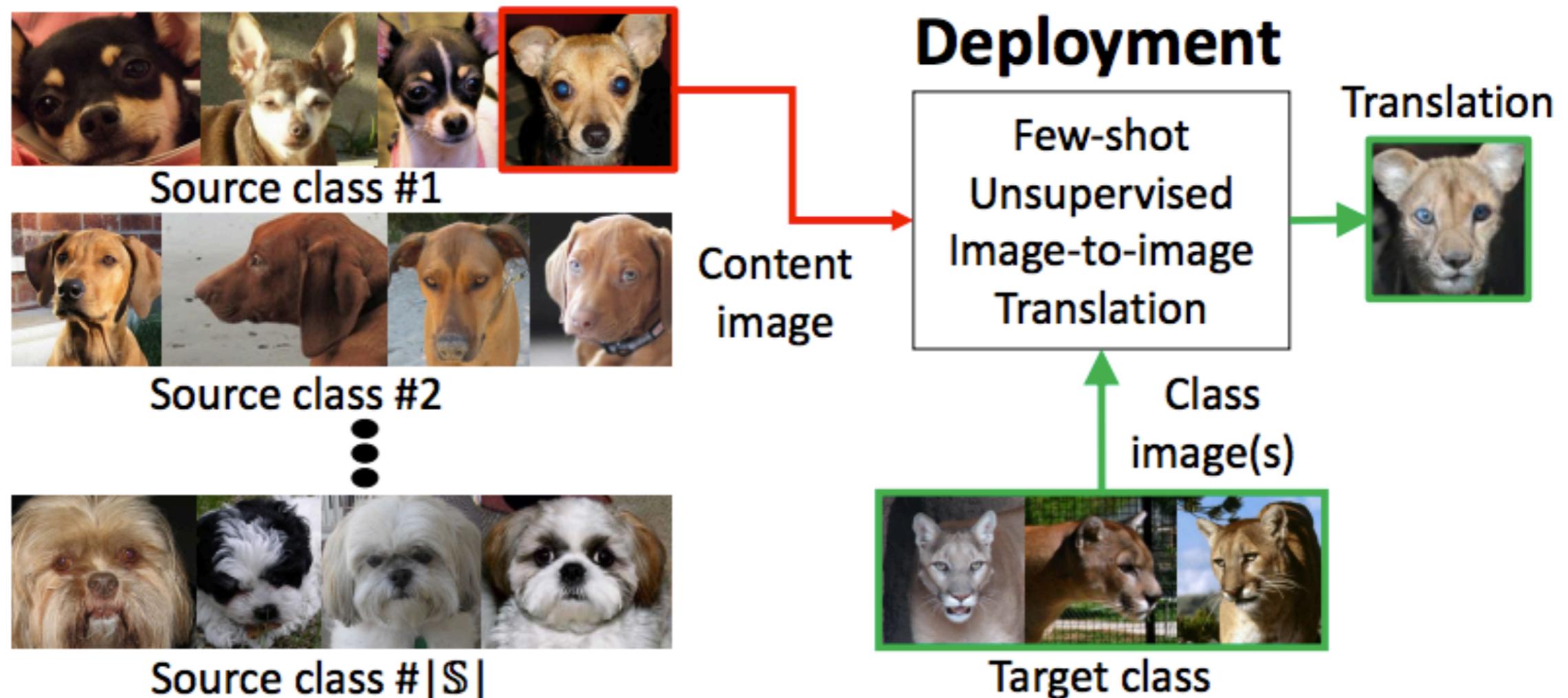
# A Style-Based Generator Architecture for Generative Adversarial Networks

Tero Karras, Samuli Laine, Timo Aila



# Few-Shot Unsupervised Image-to-Image Translation

Ming-Yu Liu, Xun Huang, Arun Mallya, Tero Karras, Timo Aila, Jaakko Lehtinen, Jan Kautz



Source



Target



$E_p$

$E_s$

D



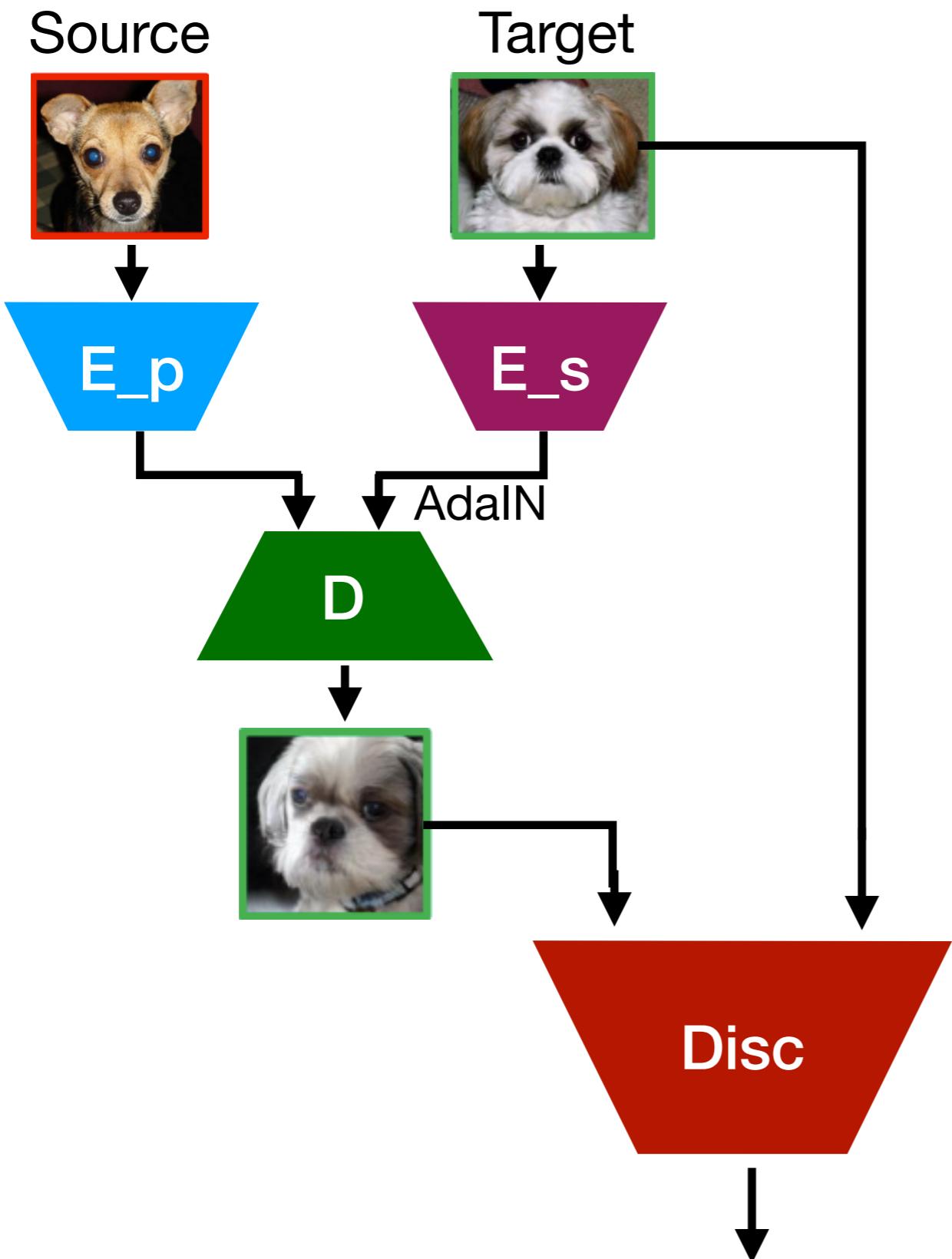
# Style Encoder

Map each image to latent space then computes the mean.

# Decoder

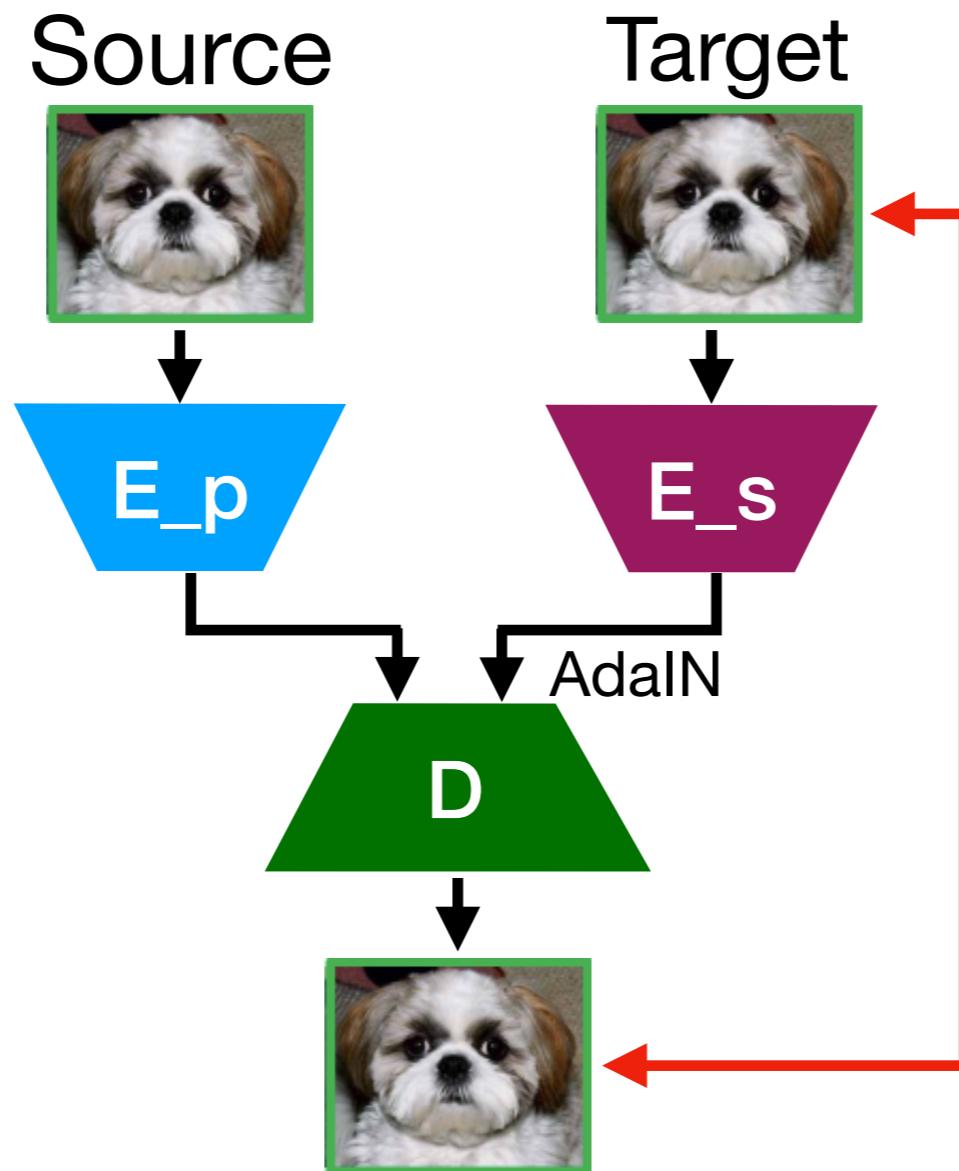
Since target domain used only for style, we feed the target encoding (style encoding) to the decoder via the AdaIN layers. We let the target images control the global look (e.g., object appearance), while the content image determines the local structure.

# GAN Loss

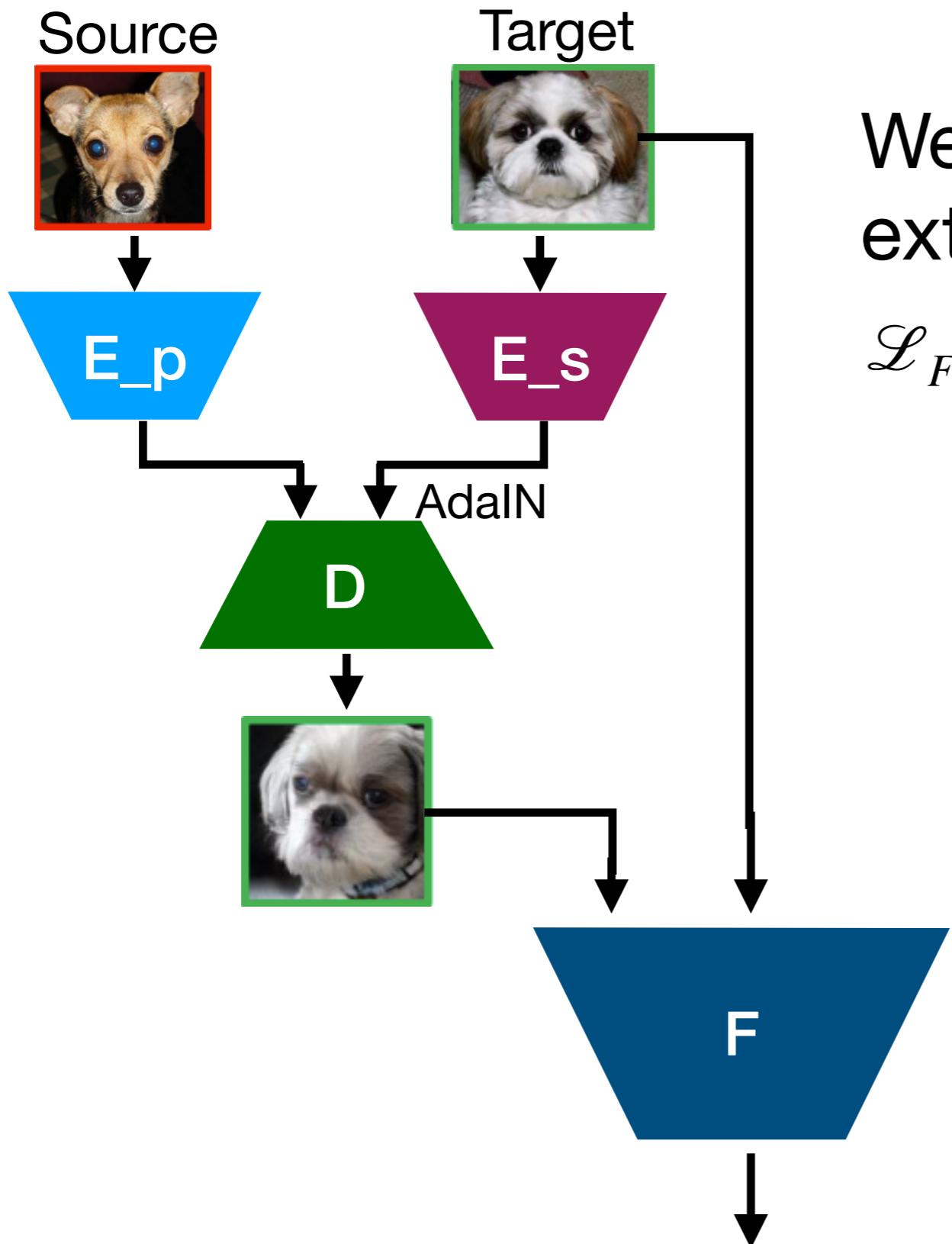


Discriminator output  
Real / Fake per class.

# Reconstruction



# Feature Matching Loss



We use feature extractor  $F$ .

$$\mathcal{L}_F = \|F(D(E_c(x), E_s(y))) - F(y)\|$$

# Disentanglement?

Network architecture. Style encoding can't change the local structure.



$y_1$

$y_2$

$x$

$\bar{x}$

# Conclusions

- Transfer some factors from image to image (content, style, rotation, etc.).
- Easier to work over latent space (e.g. adversarial loss).
- Enables to generate out-of-domain images.

# Questions?