

MATCHED FILTER

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Matched filter (p. 398 of textbook)

A filter whose impulse response is given by

$$h(t) = s(T-t)$$

→ where $s(t)$ is confined to the interval $(0, T)$
(assumed to be) ← ??

is called the matched filter to the signal $s(t)$.

Response of the MF to $s(t)$:

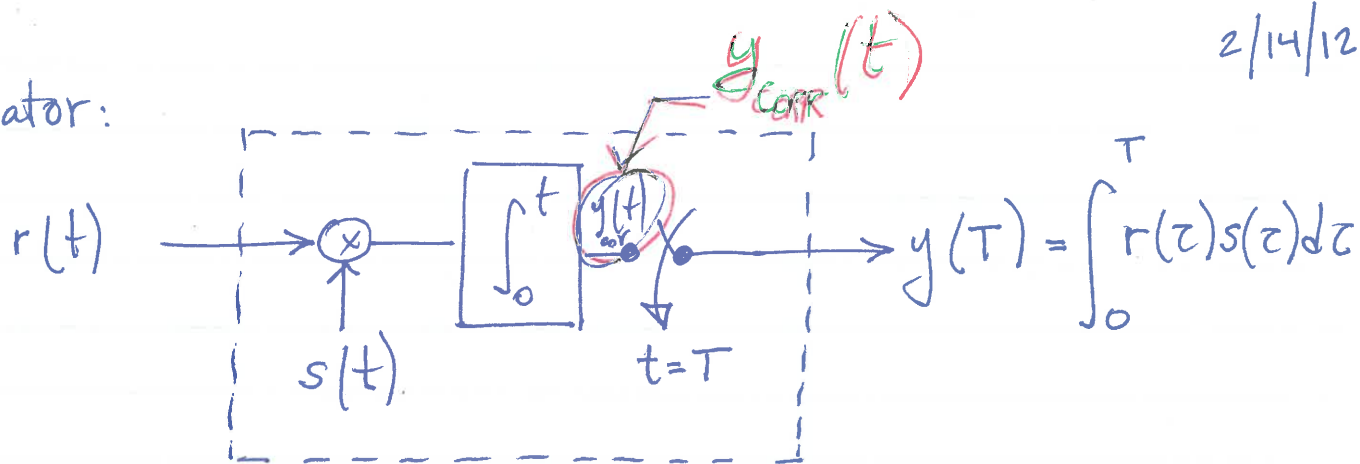
$$\begin{aligned} y(t) &= \int_0^t s(\tau) h(t-\tau) d\tau \quad (= s(t) * h(t)) \\ &= \int_0^t s(\tau) s(T-(t-\tau)) d\tau \end{aligned}$$

at $t=T$:

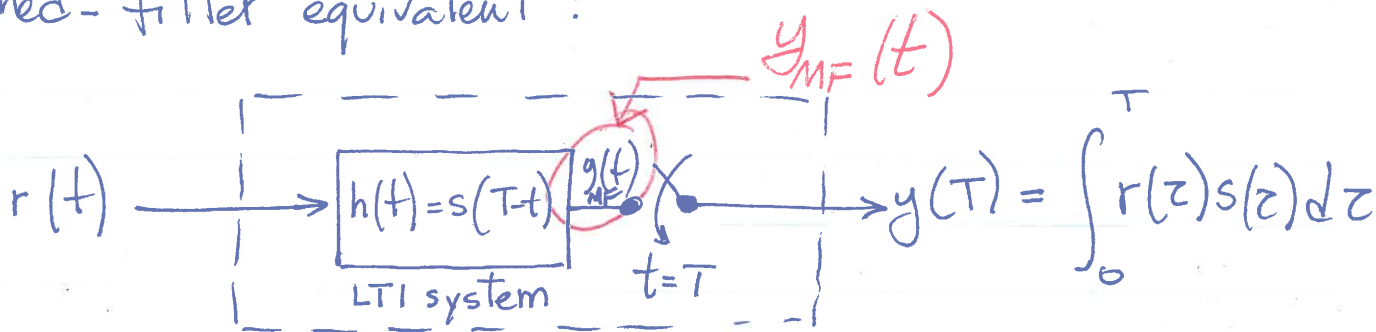
$$\underline{\underline{y(T) = \int_0^T s^2(\tau) d\tau = E_s}} \quad \text{the autocorrelation (energy) of } s(t).$$

Same output as a correlator.

Correlator:

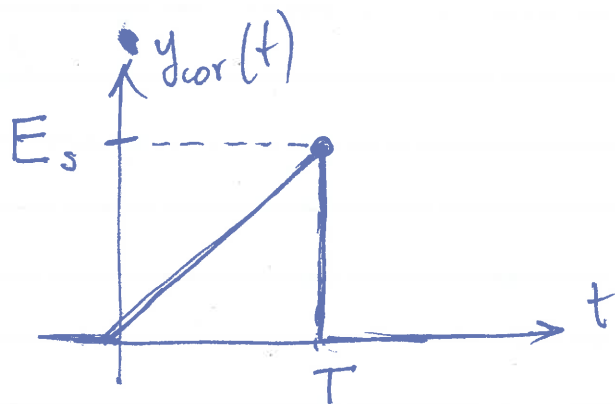


Matched-filter equivalent:

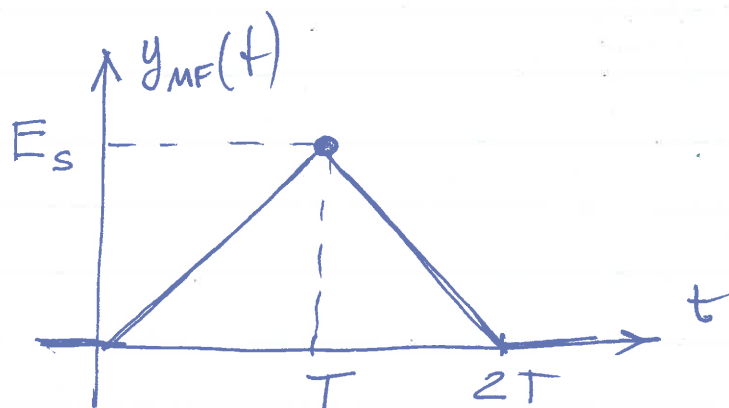


The result at $t=T$ is the same, even though responses $y(t)$ are different.

Example 1: NRZ pulse. (Input r same as reference r .)



correlator



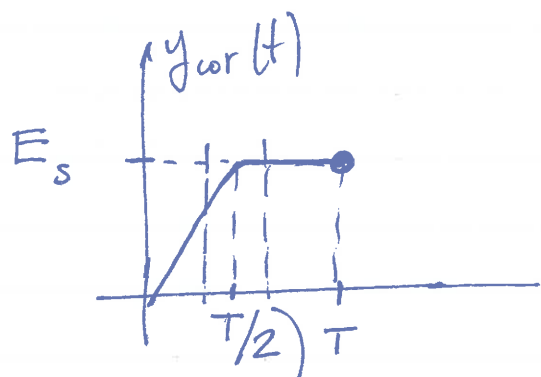
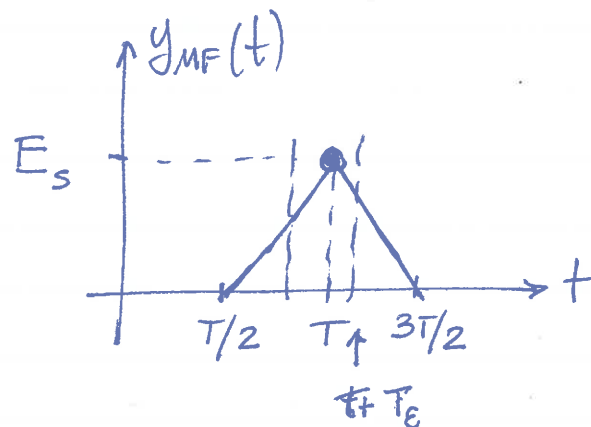
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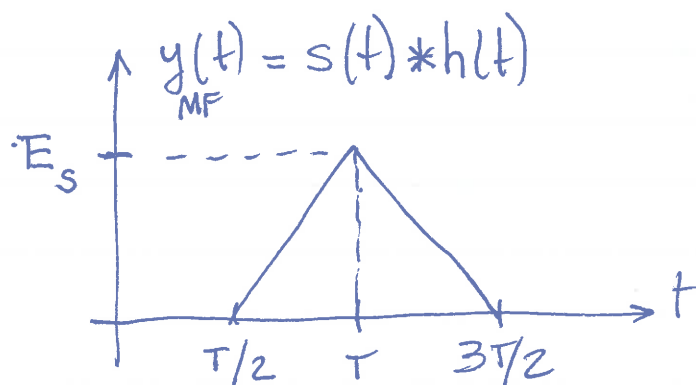
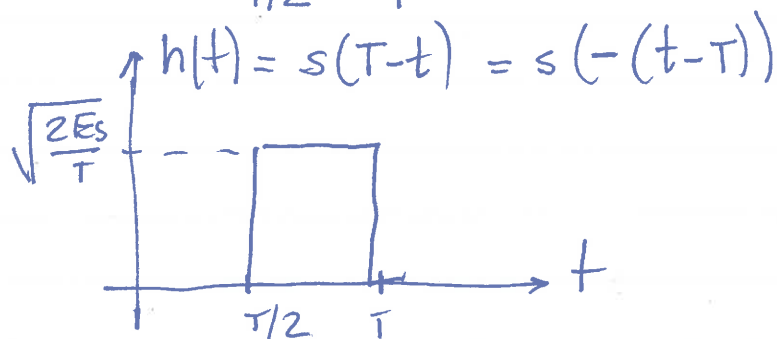
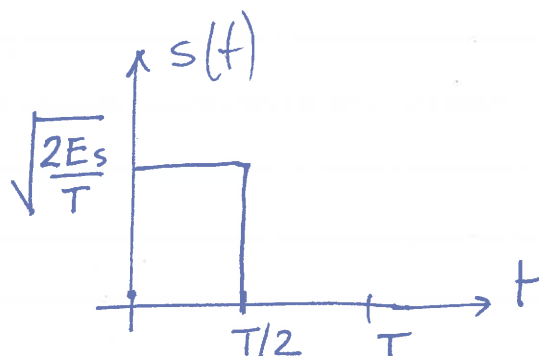
Generally:

MF is less sensitive to timing errors.

Example 2: RZ pulse

 $T+T_E$, T_E : Timing error

Note:



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Properties of the matched filter:

(1) Energy detector

$$y(T) = [s(t) * h(t)]_{t=T} = E_s$$

where $E_s = \int_0^T s^2(\tau) d\tau$, is the energy of $s(t)$.

(2) Maximizes the ^{output} signal-to-noise ratio (SNR).

$$\left(\frac{S}{N}\right)_0 = \frac{2E_s}{N_0}$$

Maximum output SNR of an MF.

where $\frac{N_0}{2} = \sigma^2$ is the variance of ^{the} AWGN sample.

Correlator : Only works for finite-duration pulses

MF : Works for any energy-type signal!!!

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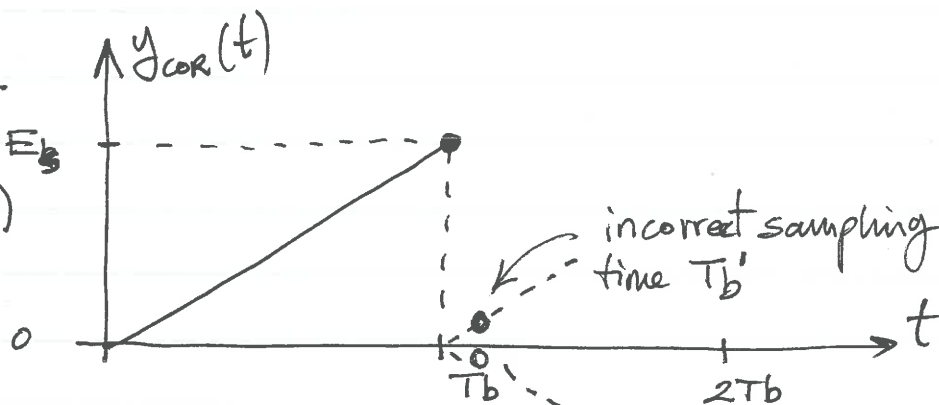
Matched filter implementation advantage

Robust against timing errors. For example, one bit sent by NRZ false: (polar mapping)

CORRELATOR

$$\sqrt{E_b} \cdot 1 = E_b$$

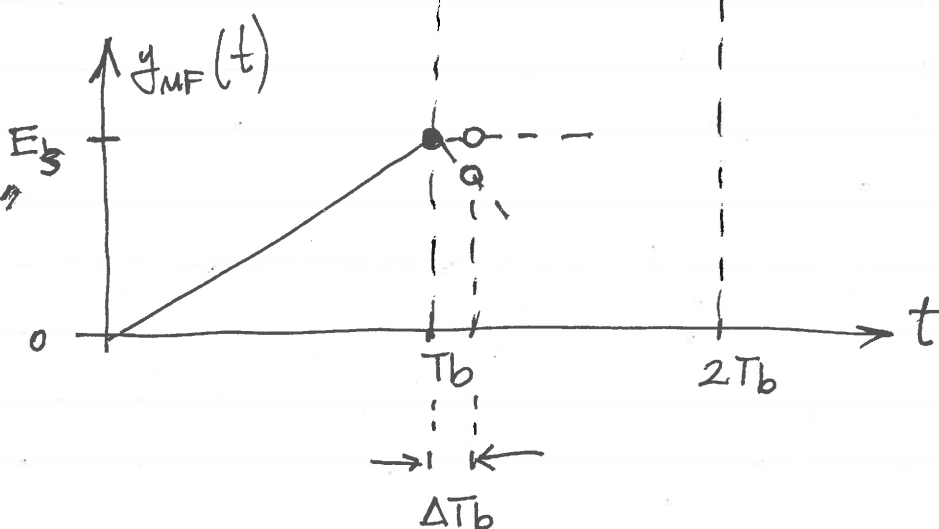
($E_b = 1$)



↑
LARGE
ERROR
↓

MATCHED
FILTER

$$\sqrt{E_b} \cdot 1$$



↓
SMALL
ERROR
↑

$T_b' = T_b + \Delta T_b$ sampling time at receiver.

ΔT_b : Timing error due to different clocks
(one at transmitter and one at receiver)