

MATCHED FILTER

EE161 S'12

2/14/12

Matched filter (p. 398 of textbook)

A filter whose impulse response is given by

$$h(t) = s(T-t),$$

→ where $s(t)$ is confined to the interval $(0, T)$
 (assumed to be) ← ??
 is called the matched filter to the signal $s(t)$.

Response of the MF to $s(t)$:

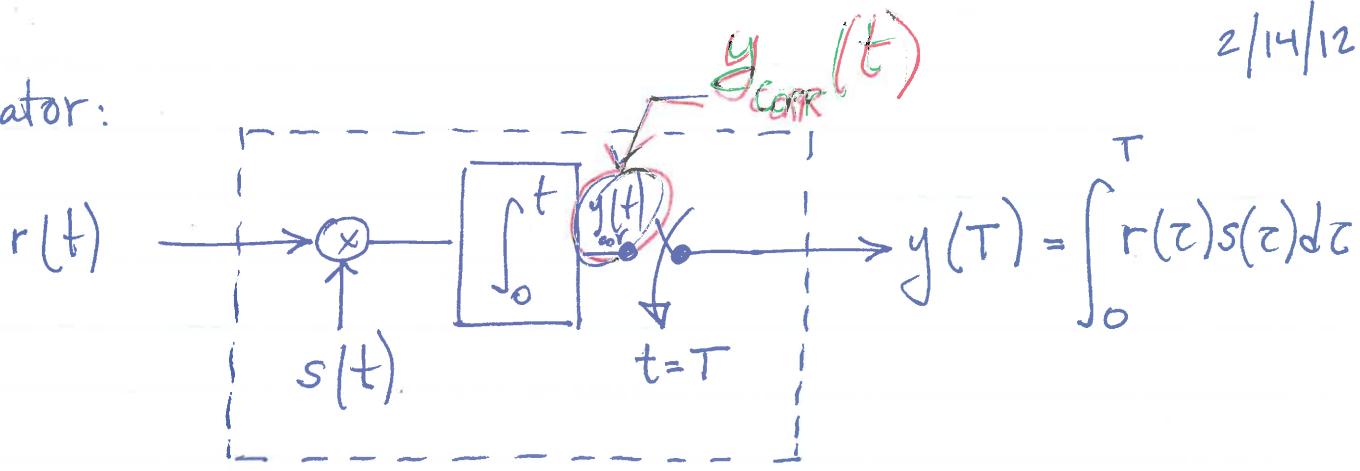
$$\begin{aligned} y(t) &= \int_0^t s(\tau) h(t-\tau) d\tau \quad (= s(t) * h(t)) \\ &= \int_0^t s(\tau) s(T-(t-\tau)) d\tau \end{aligned}$$

at $t=T$:

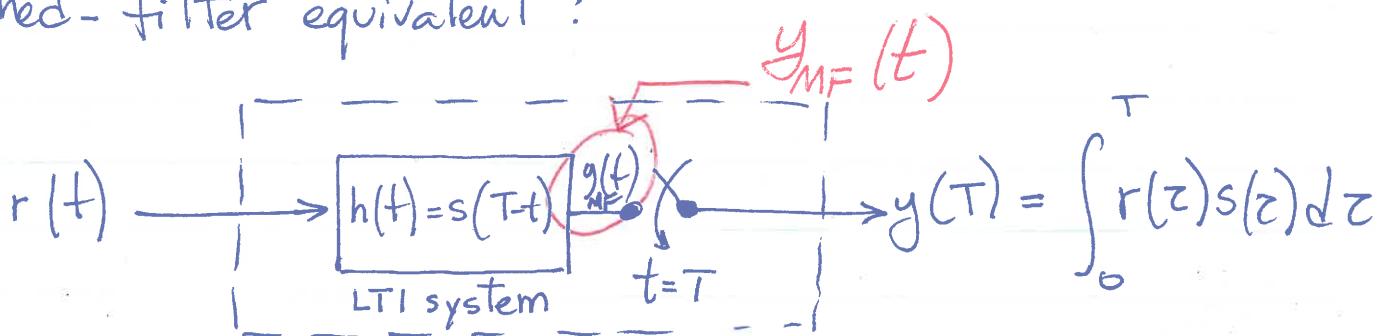
$$y(T) = \underbrace{\int_0^T s^2(\tau) d\tau}_{E_S} \text{ the autocorrelation (energy) of } s(t).$$

Same output as a correlator.

Correlator:

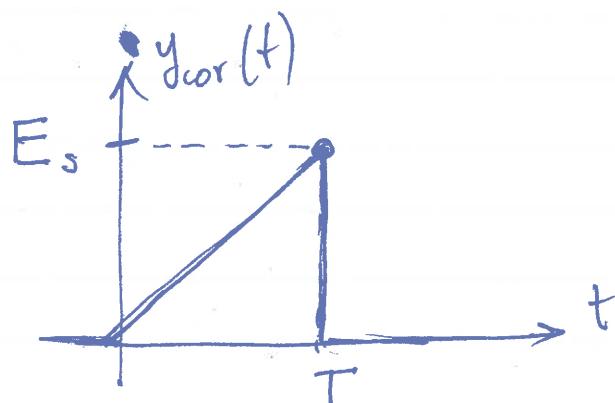


Matched-filter equivalent:

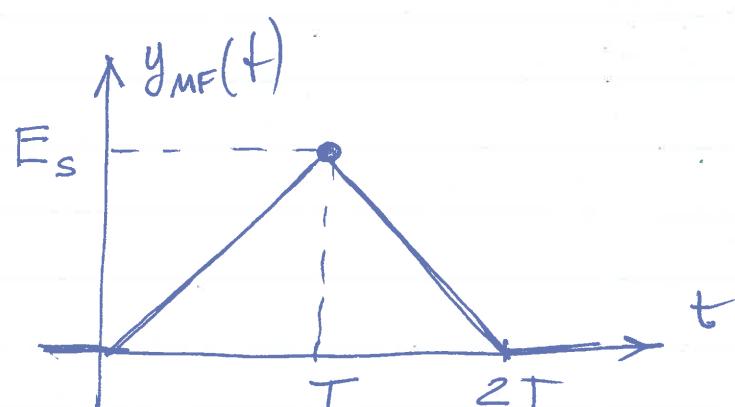


The result at $t=T$ is the same, even though responses $y(t)$ are different.

Example 1: NRZ pulse. (Input r same as reference s .)



correlator

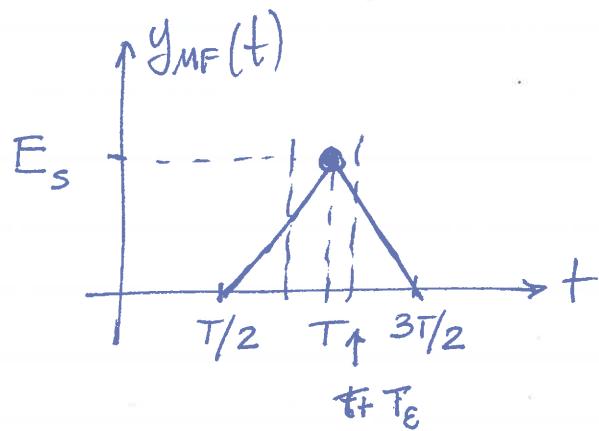
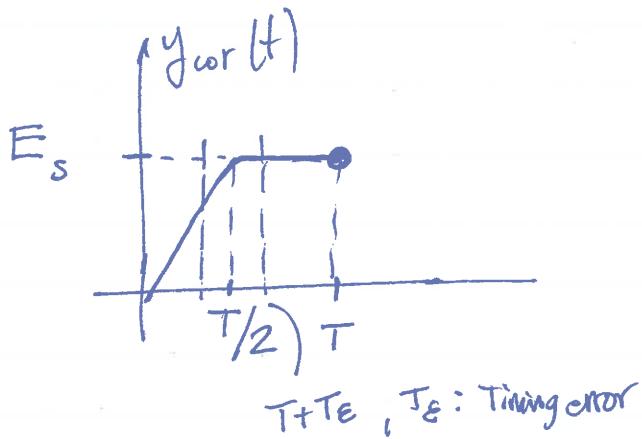


Matched filter

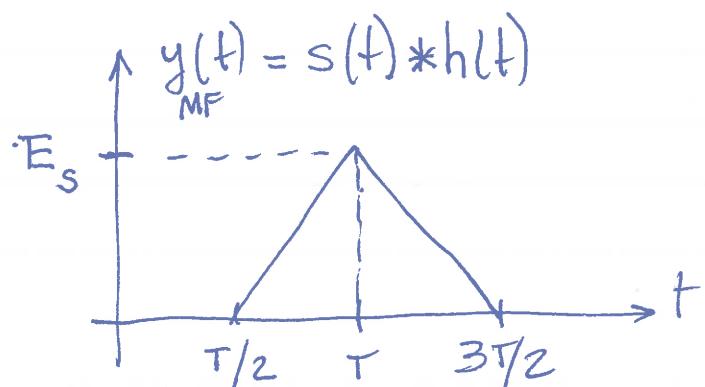
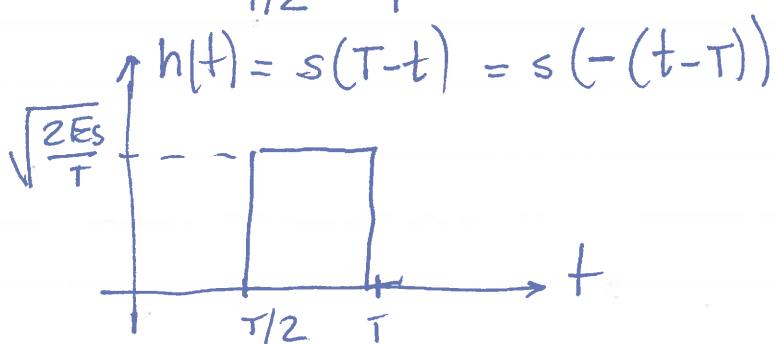
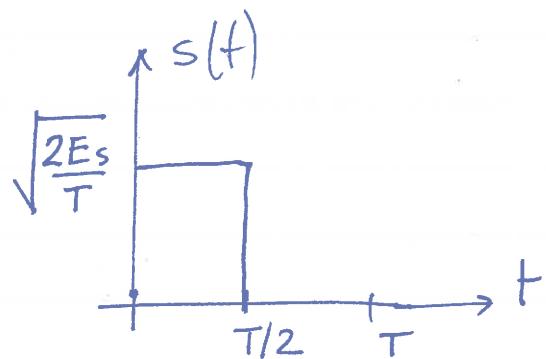
Generally:

MF is less sensitive to timing errors.

Example 2: RZ pulse



Note:



Properties of the matched filter:

(1) Energy detector

$$\boxed{y(T) = [s(t) * h(t)]_{t=T} = E_s}$$

where $E_s = \int_0^T s^2(\tau) d\tau$, is the energy of $s(t)$.

(2) Maximizes the $\frac{\text{output}}{\text{signal-to-noise ratio}}$ (SNR).

$$\boxed{\left(\frac{s}{n}\right)_o = \frac{2E_s}{N_o}}$$

Maximum output SNR
of an MF.

where $\frac{N_o}{2} = \sigma^2$ is the variance of ^{the} AWGN
sample.

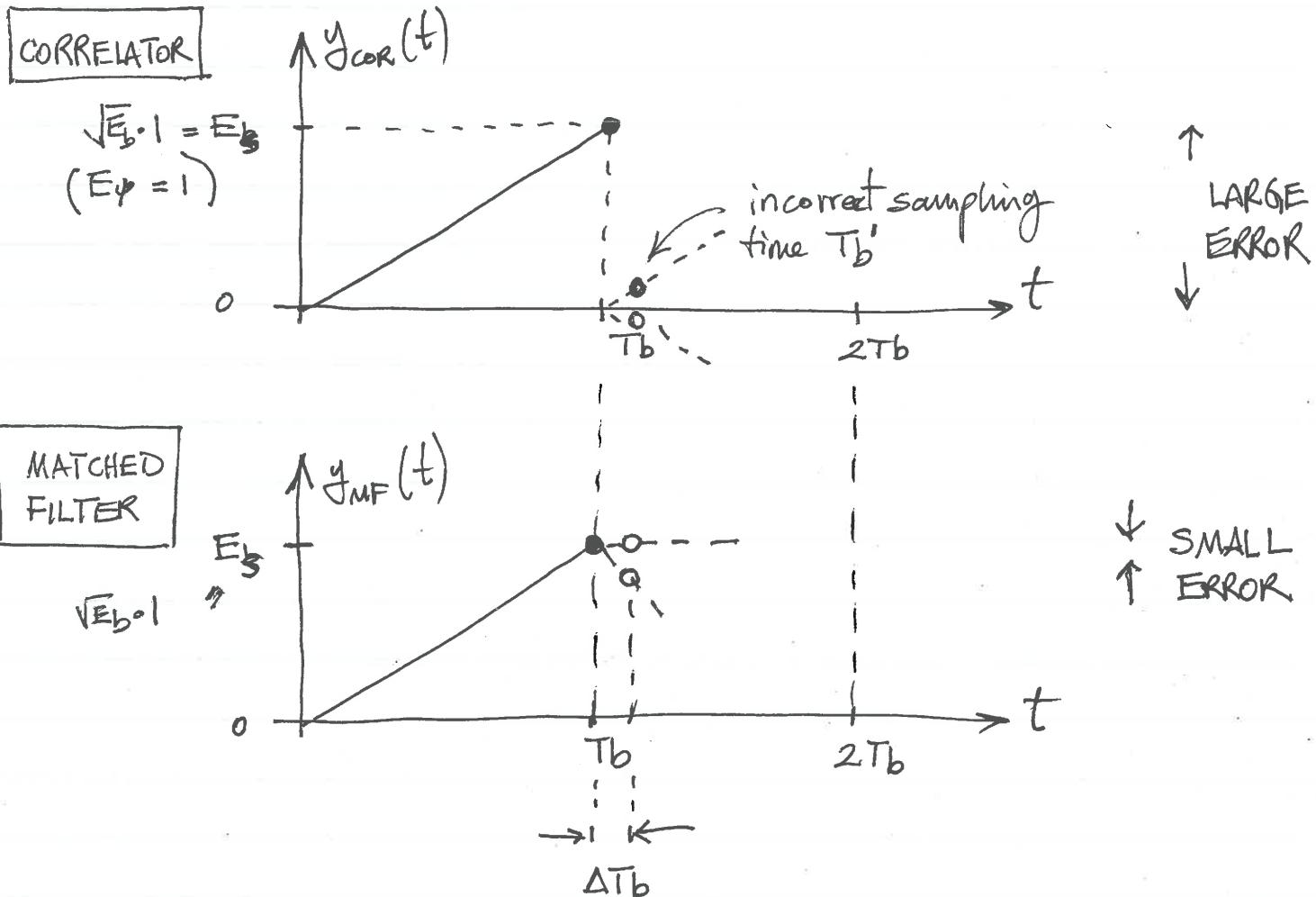
* Correlator : Only works for finite-duration pulses

MF : Works for any energy-type signal !!

2/18/14
2/2

Matched filter implementation advantage

Robust against timing errors. For example, one bit sent by NRZ pulse (polar mapping)



$$T_b' = T_b + \Delta T_b \quad \text{sampling time at } \underline{\text{receiver}}$$

ΔT_b : Timing error due to different clocks
(one at transmitter and one at receiver)