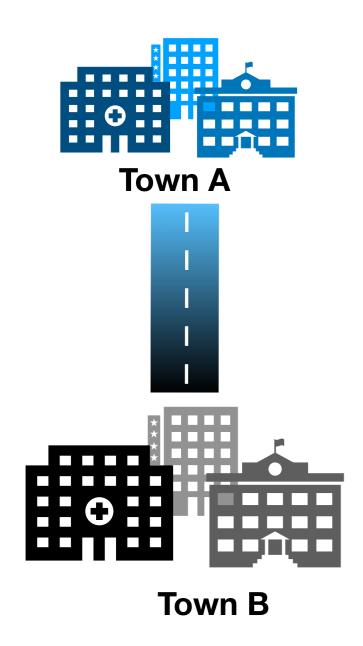
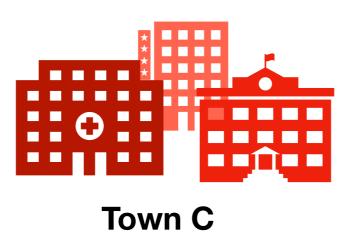
### CS 61BL Lab 21

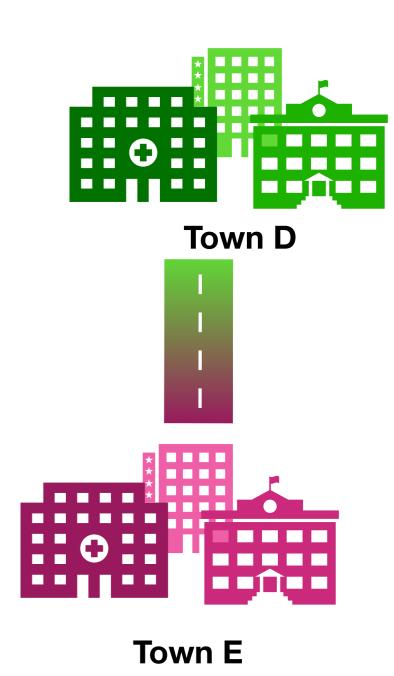
Ryan Purpura

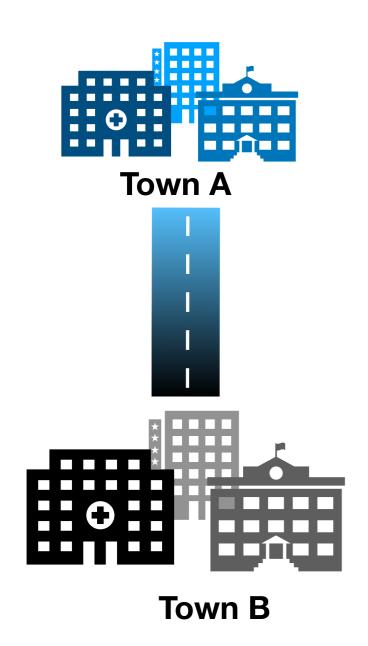
#### Announcements

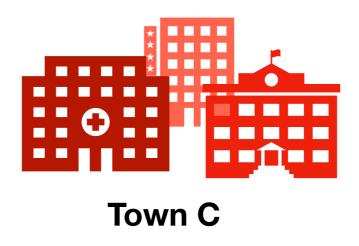
- It is the final week!
- Final on Thursday!

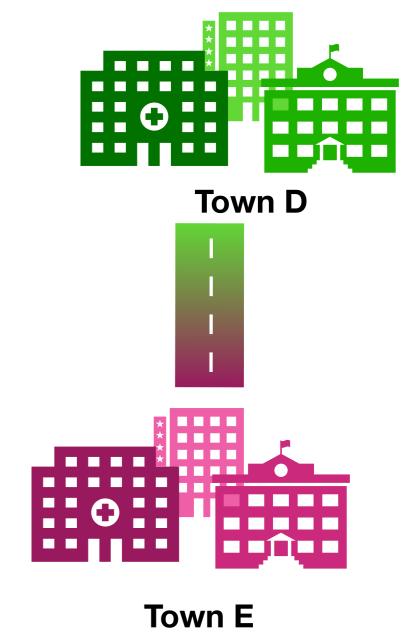




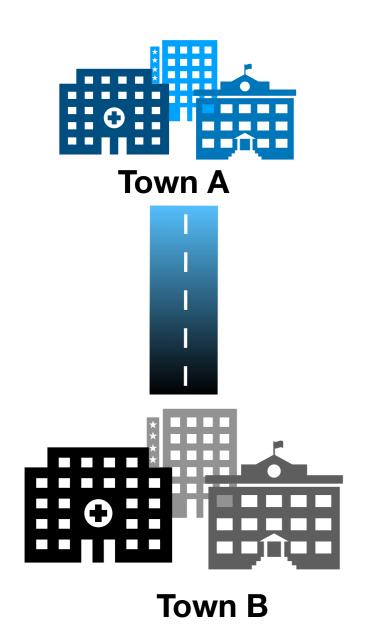


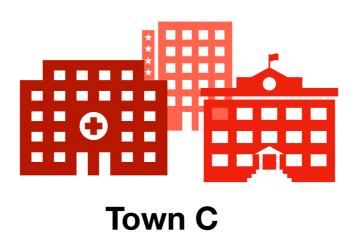


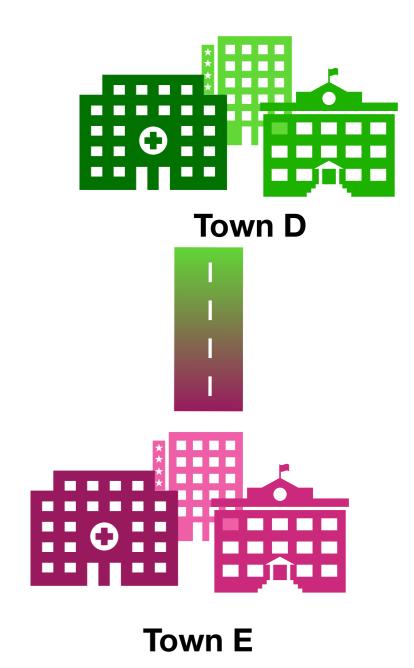




A connected to B?
A connected to C?
A connected to D?
A connected to E?

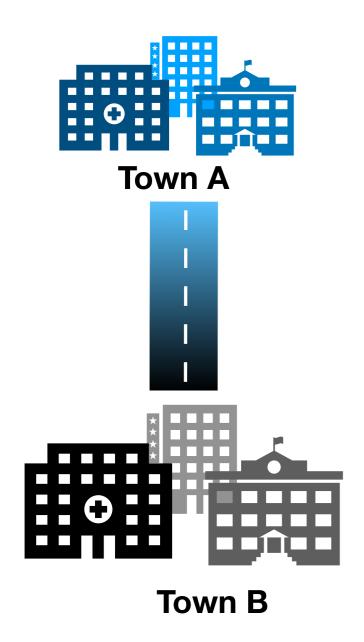


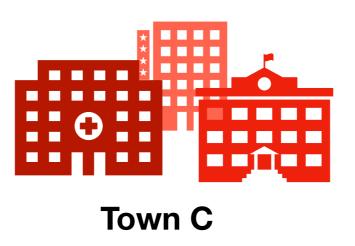


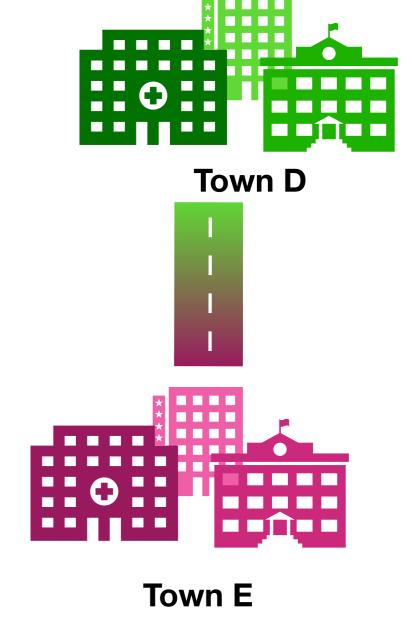


A connected to B? yes A connected to C? A connected to D?

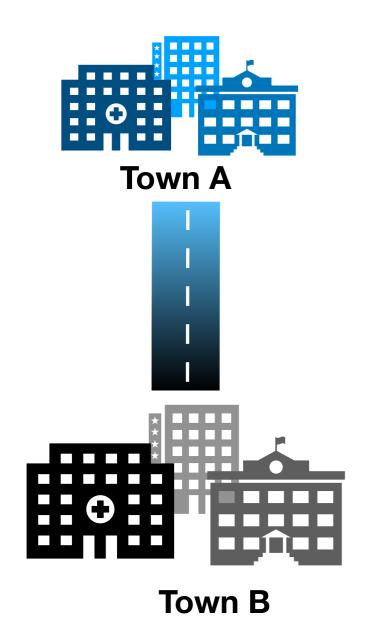
A connected to E?

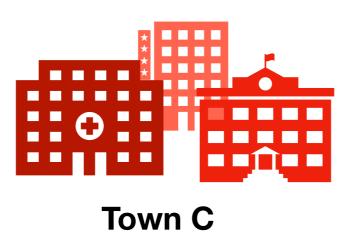


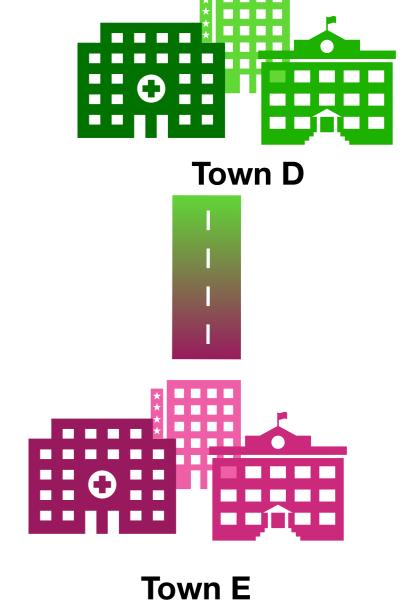




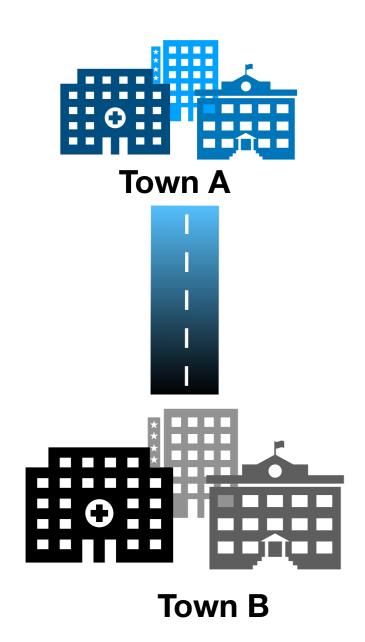
A connected to B? yes
A connected to C? no
A connected to D?
A connected to E?

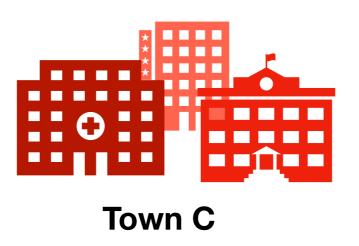


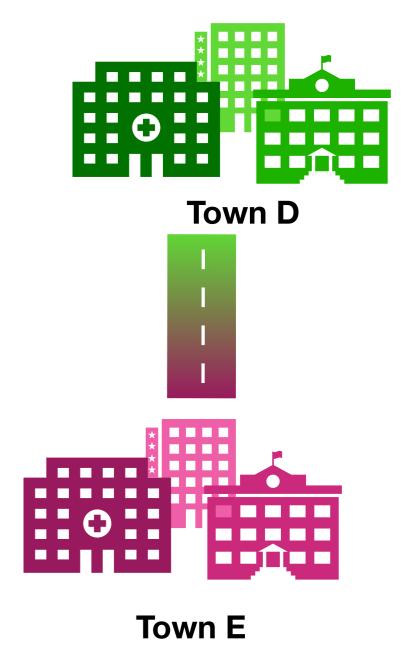




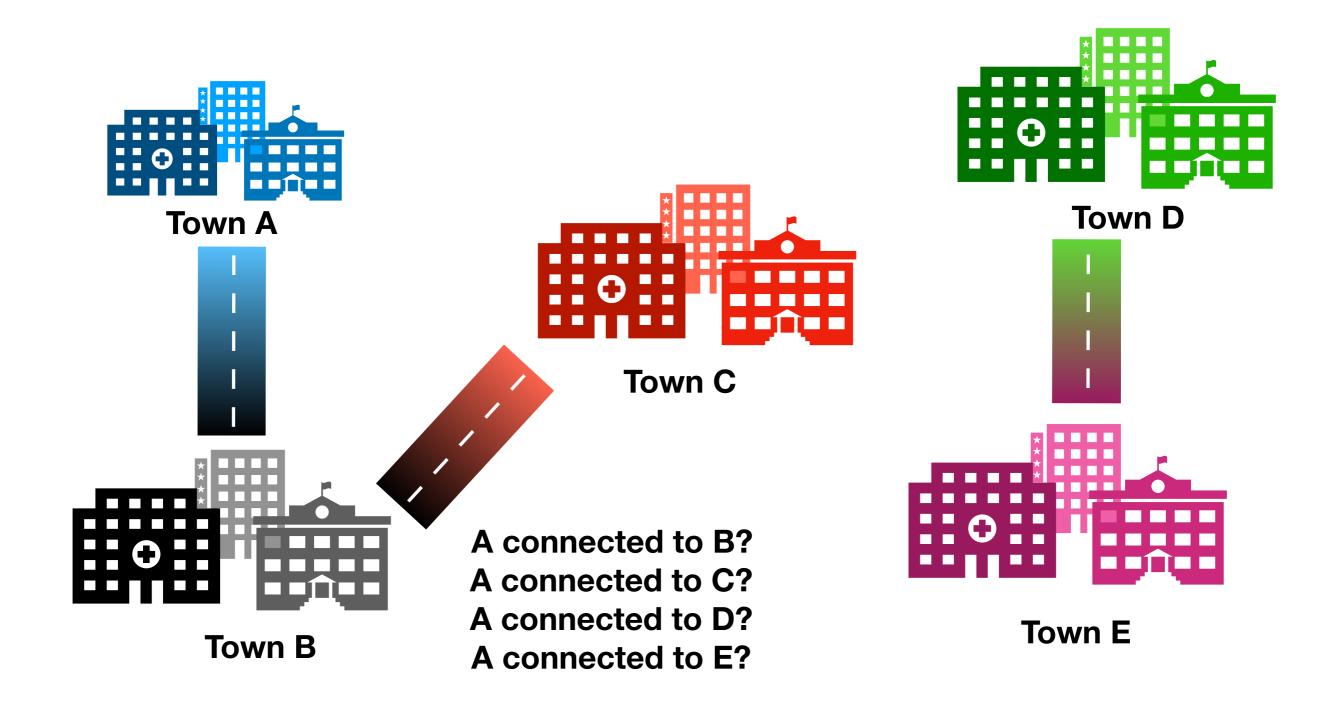
A connected to B? yes
A connected to C? no
A connected to D? no
A connected to E?

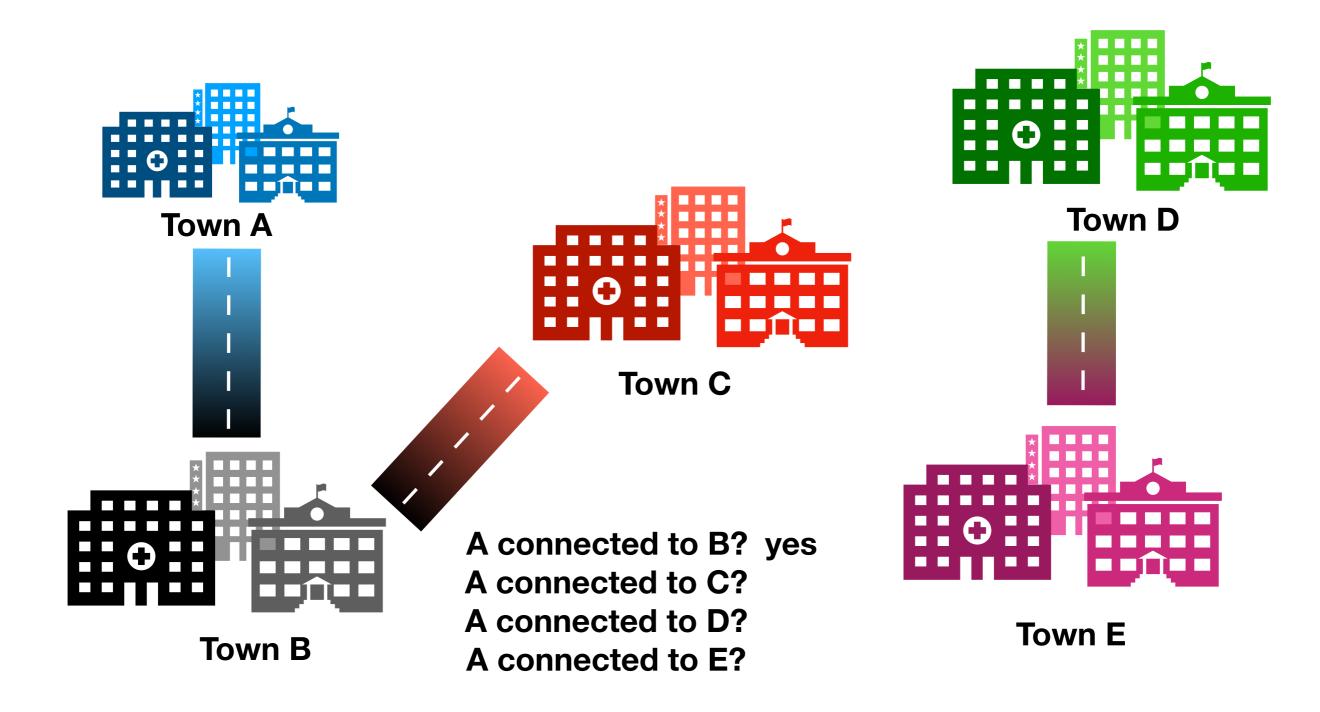


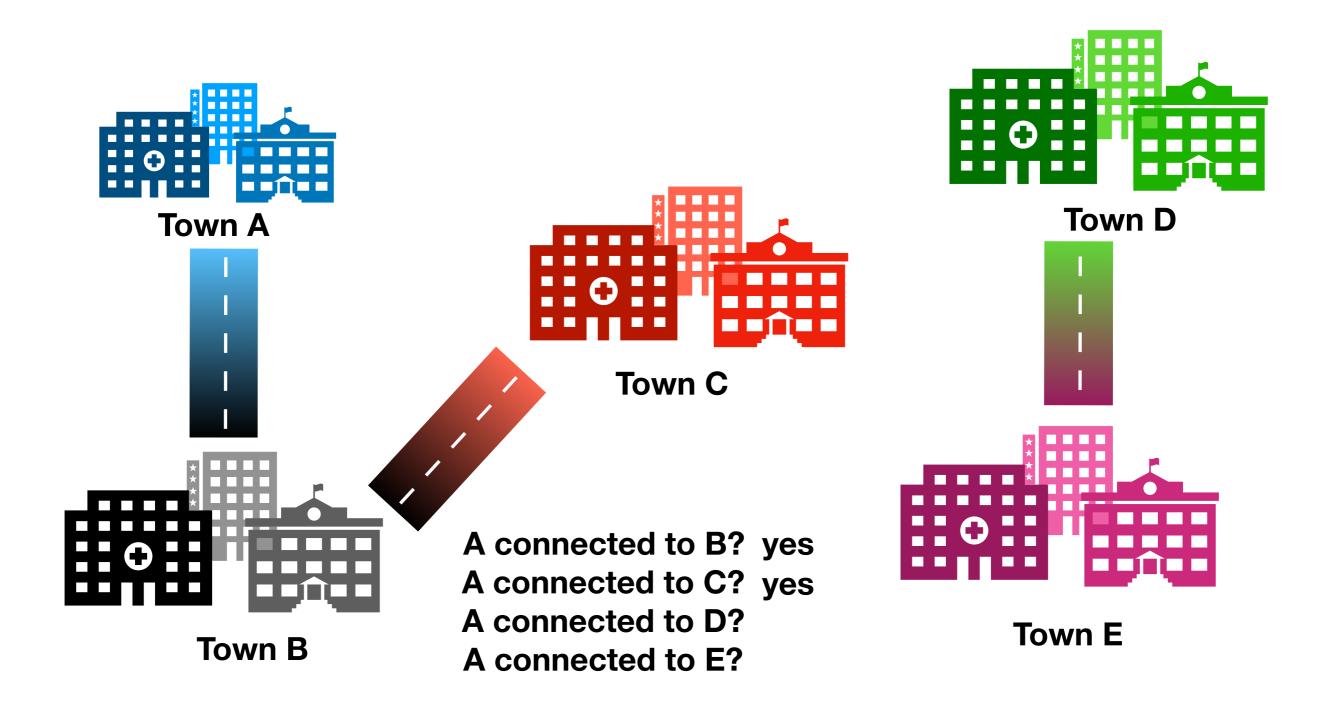


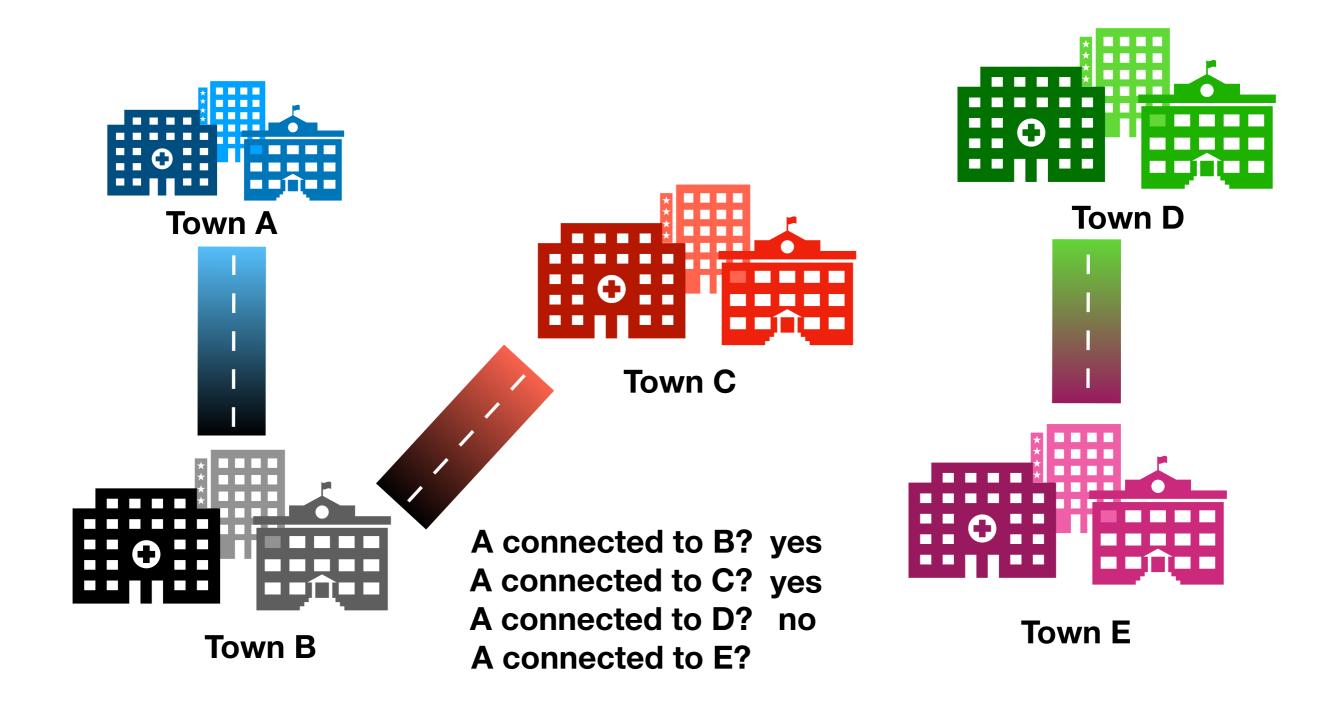


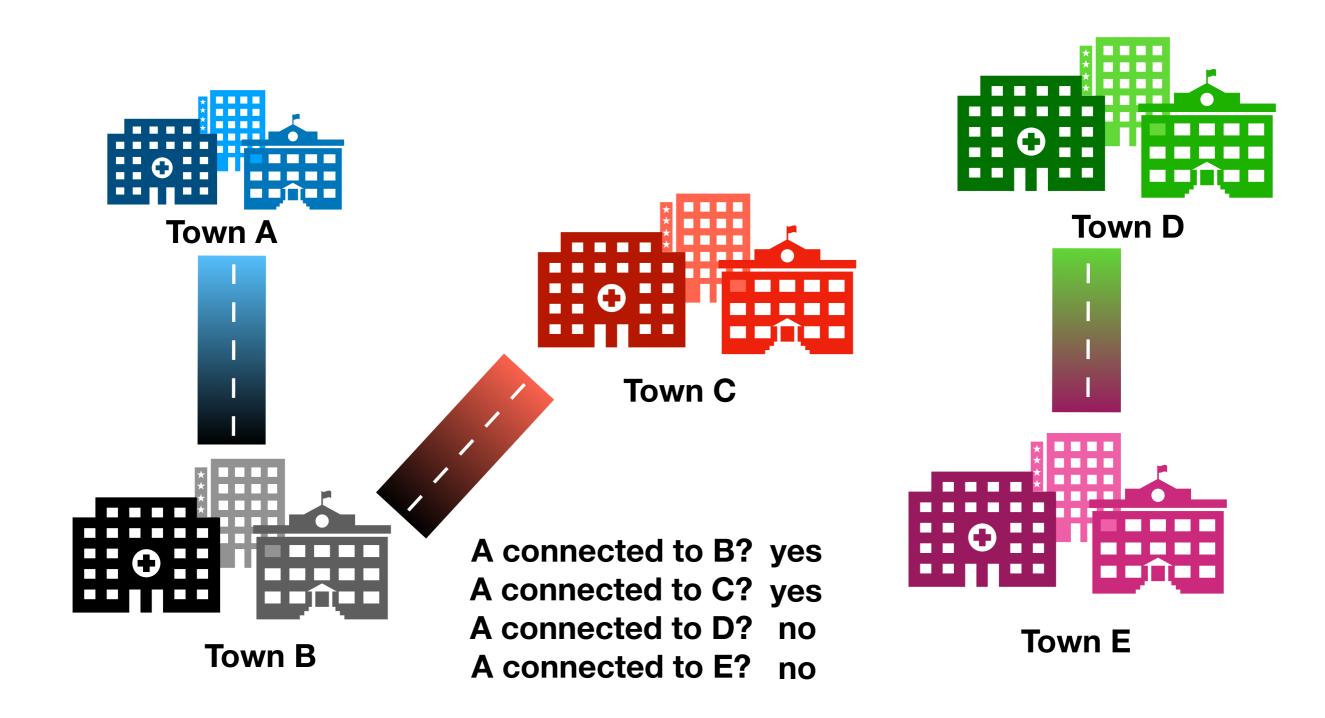
A connected to B? yes
A connected to C? no
A connected to D? no
A connected to E? no

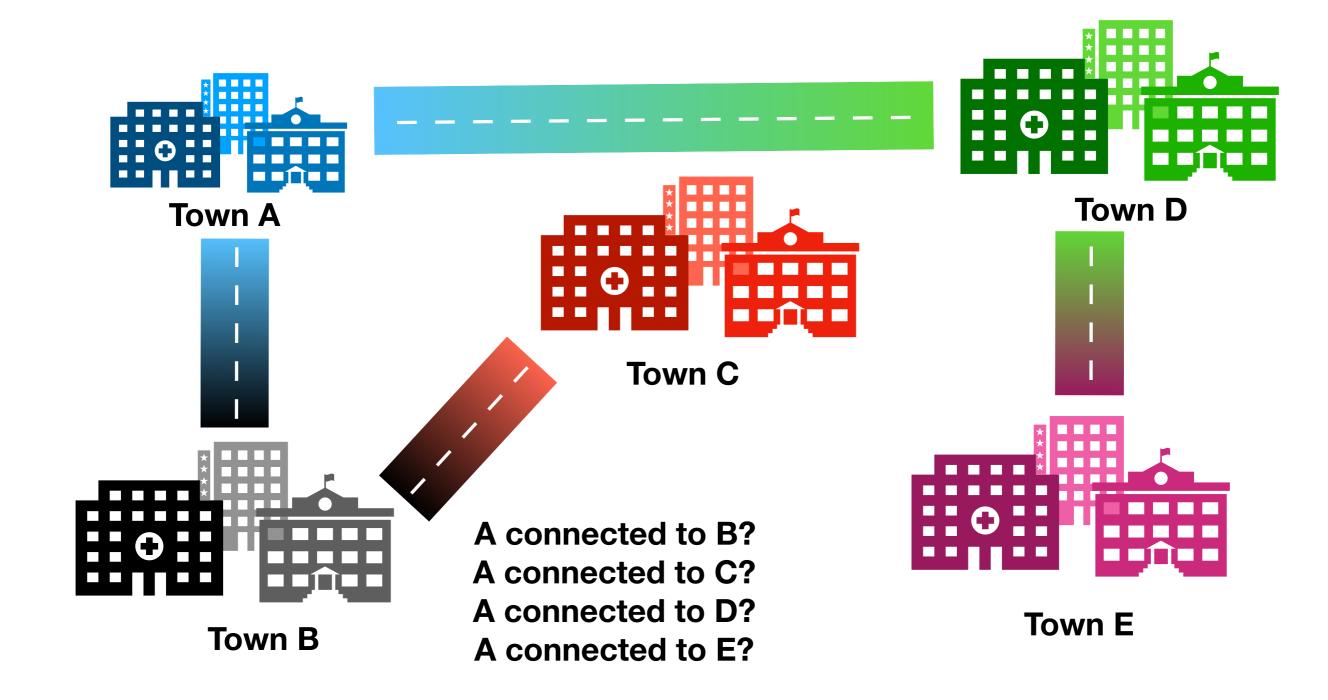


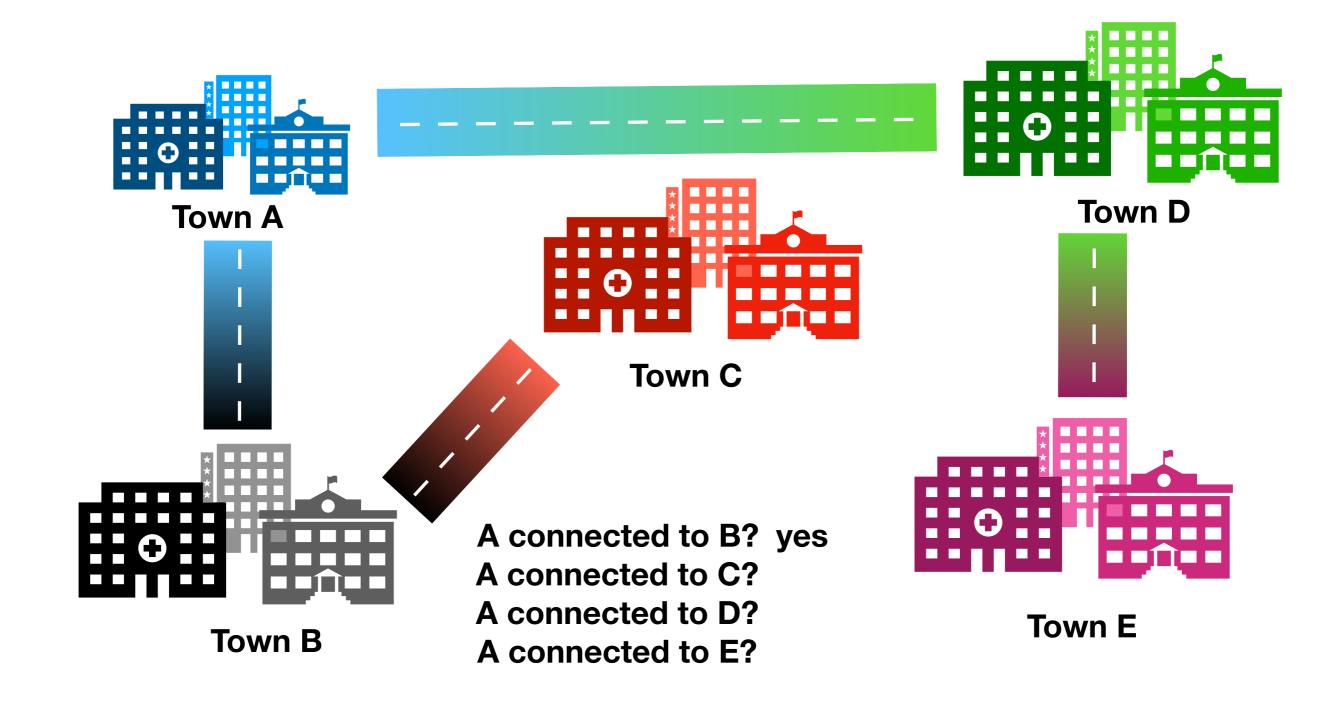


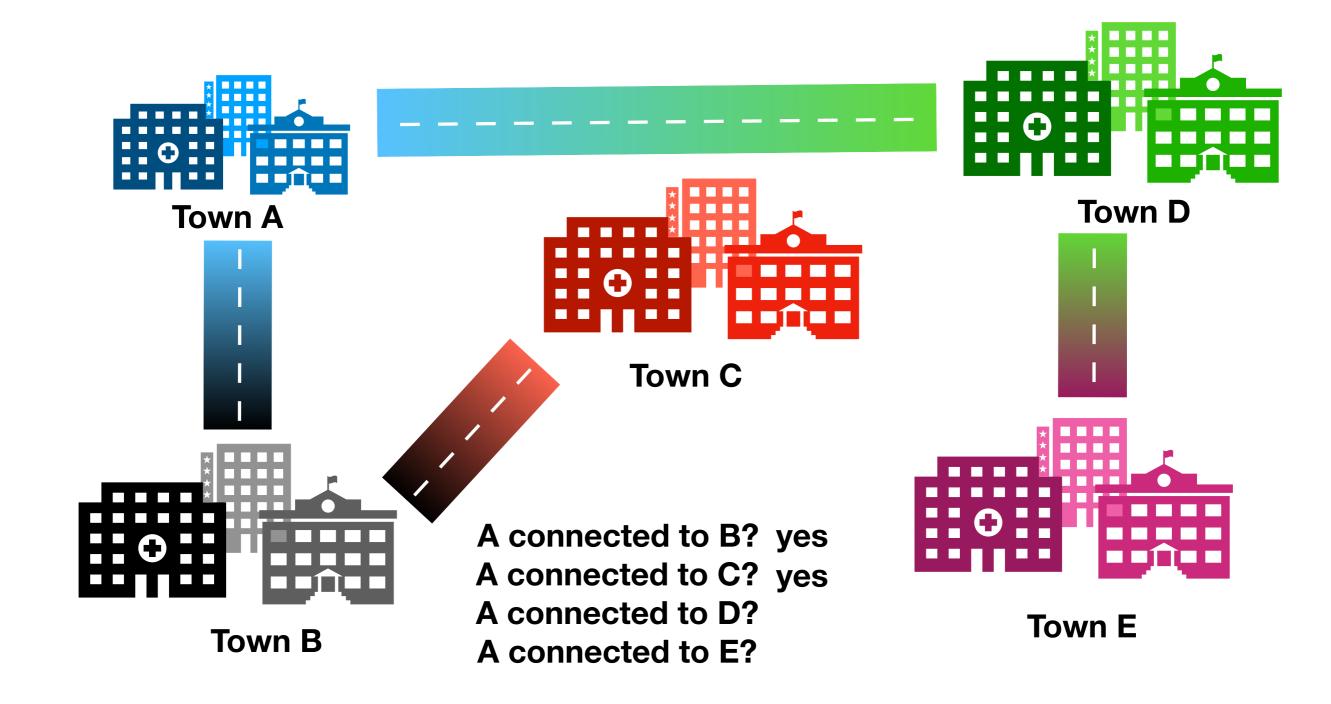


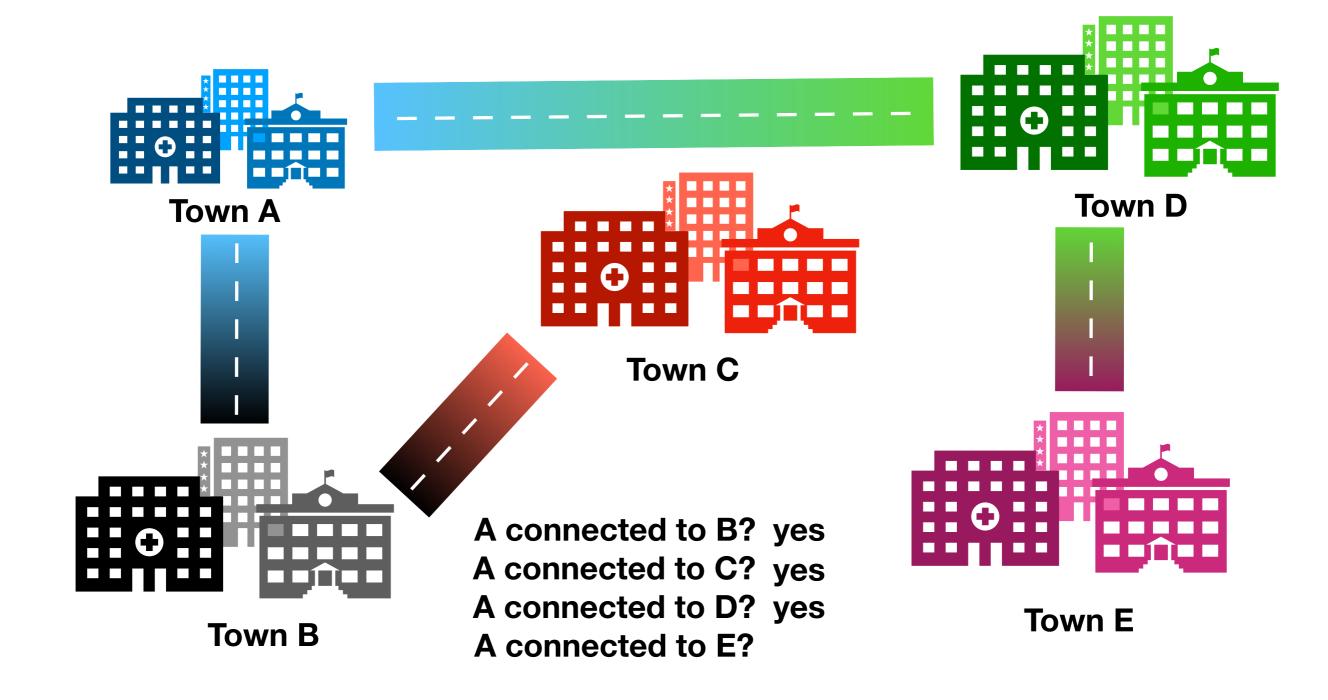


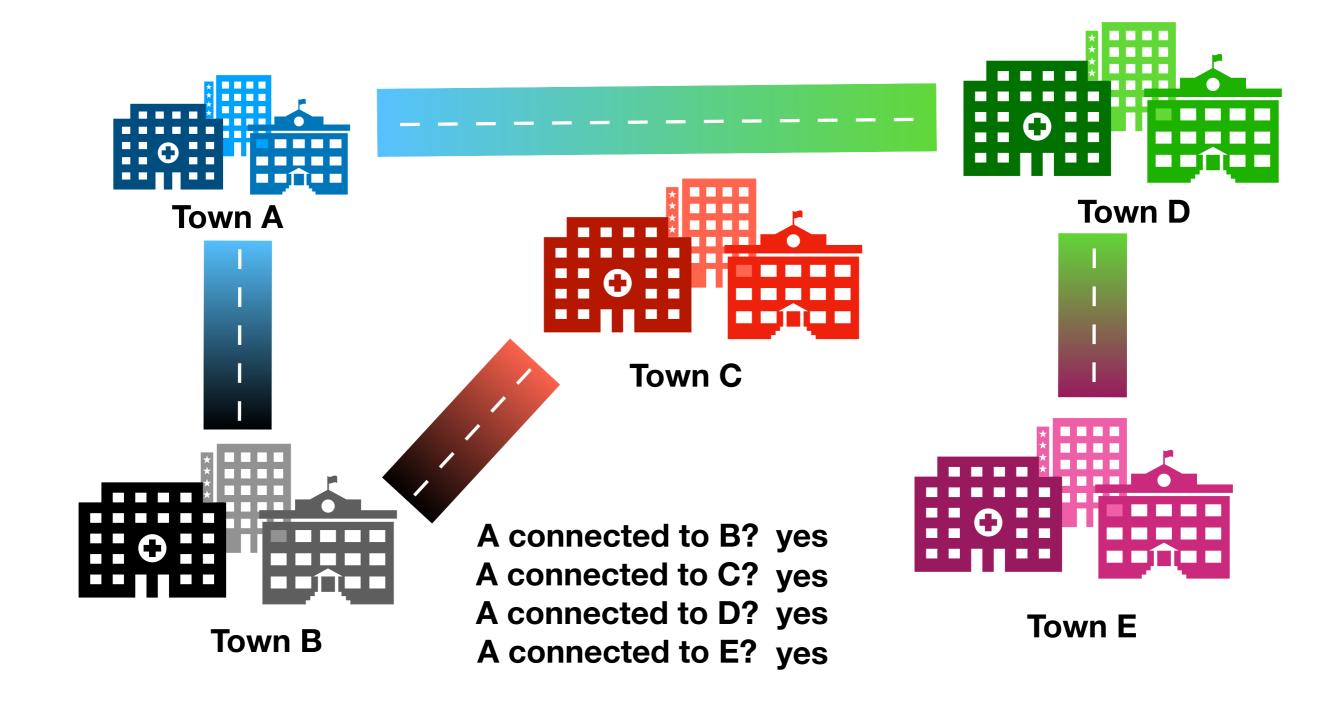










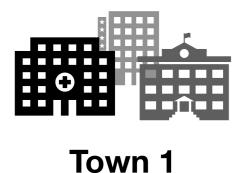


- Given a collection of elements:
  - Join two elements ("union")
  - See which set an element belongs to ("find")
- How to do both efficiently?



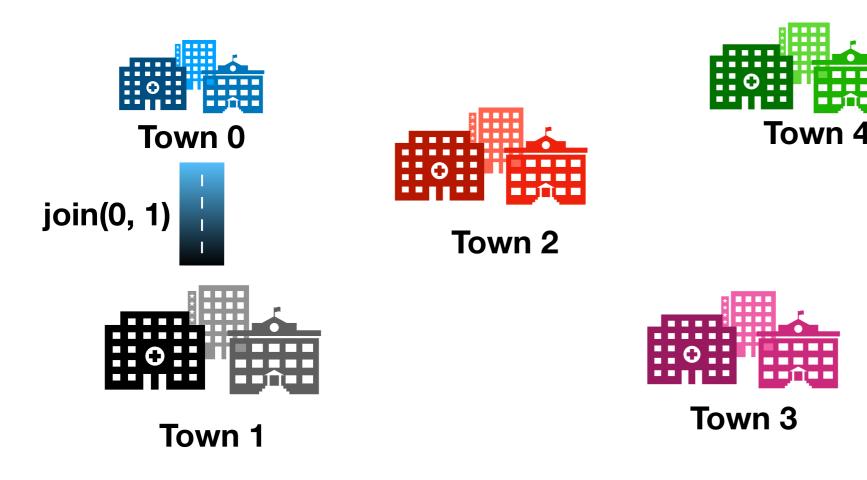




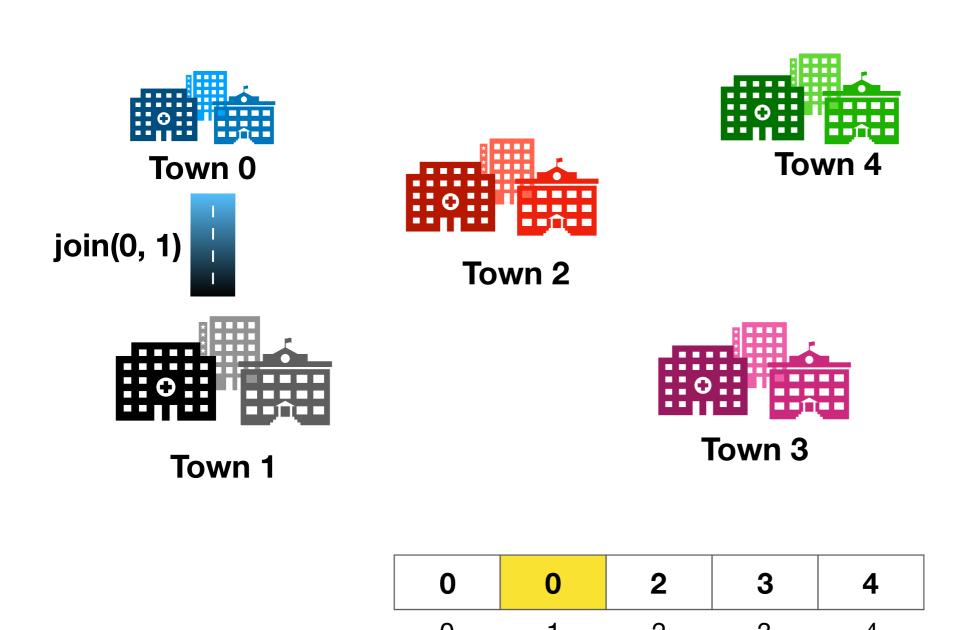


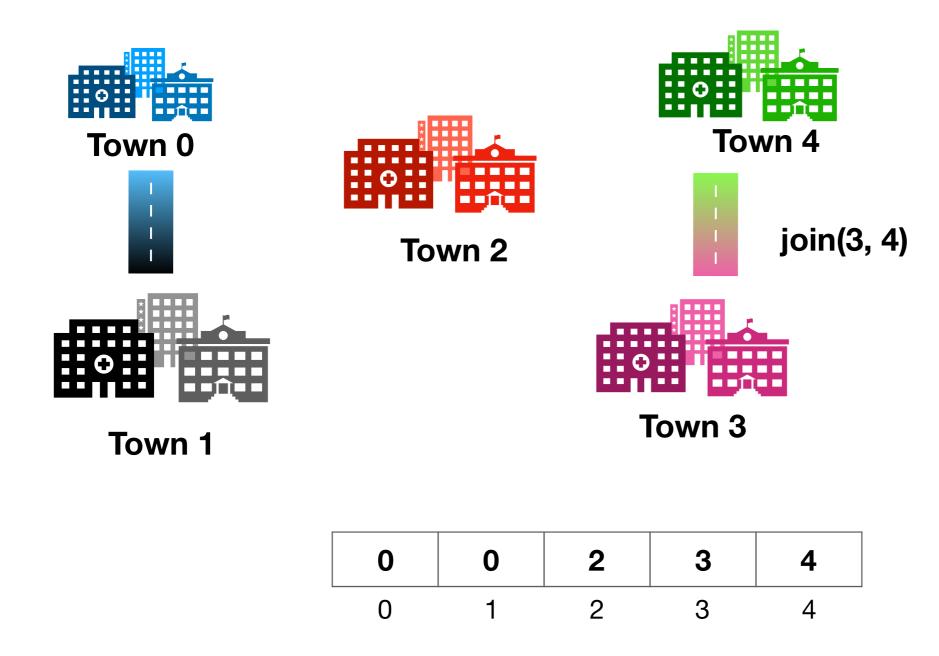


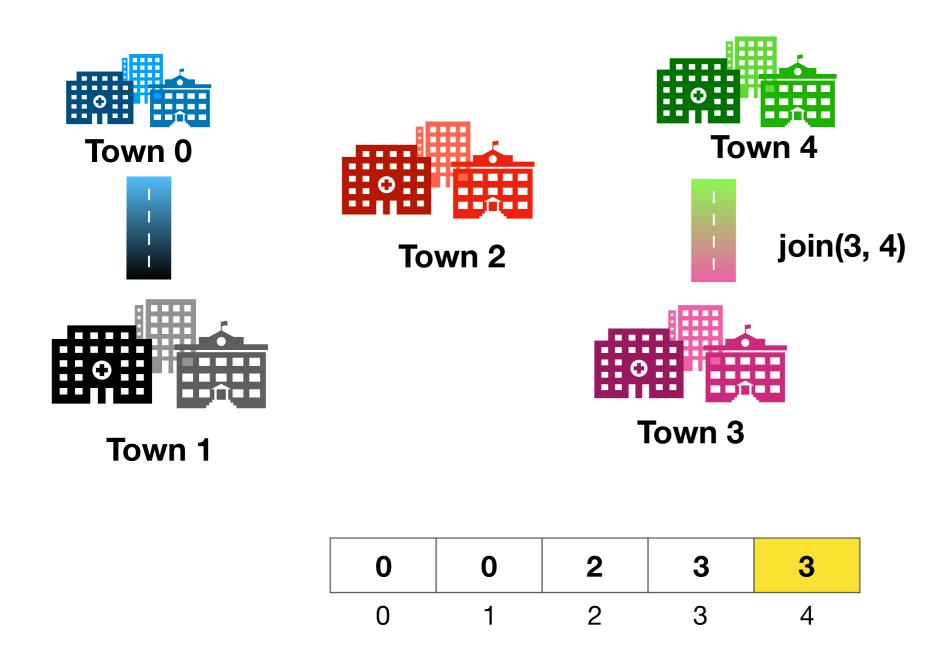
0	1	2	3	4
0	1	2	3	4

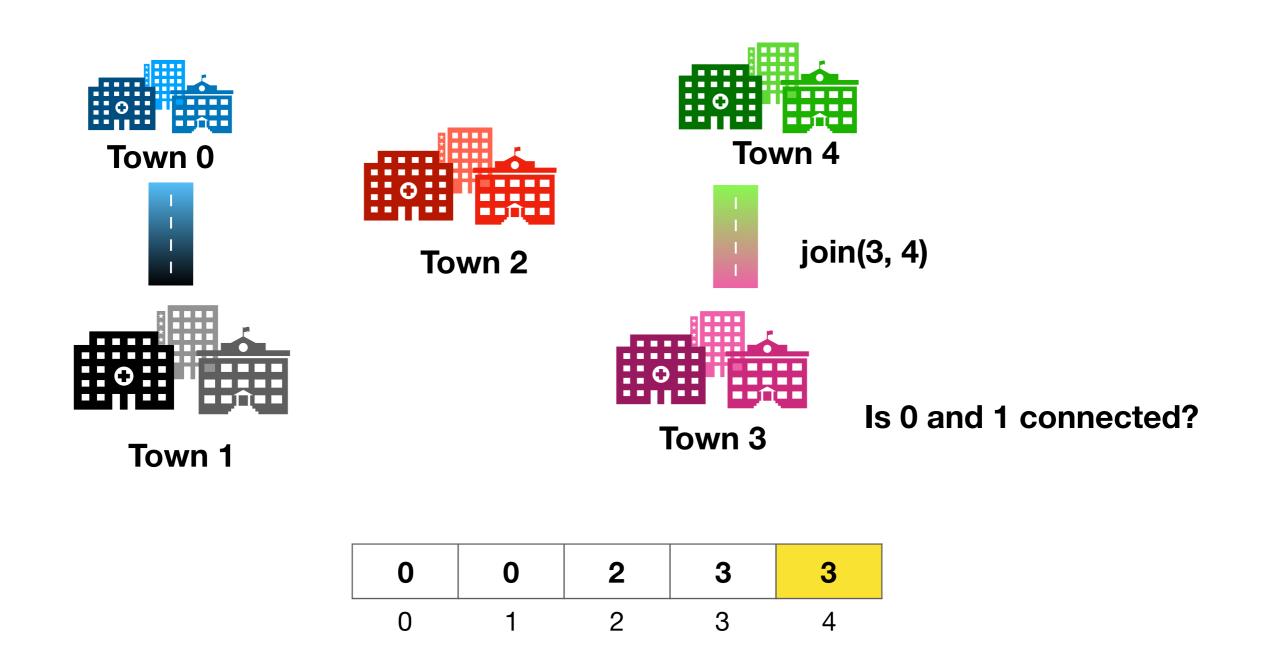


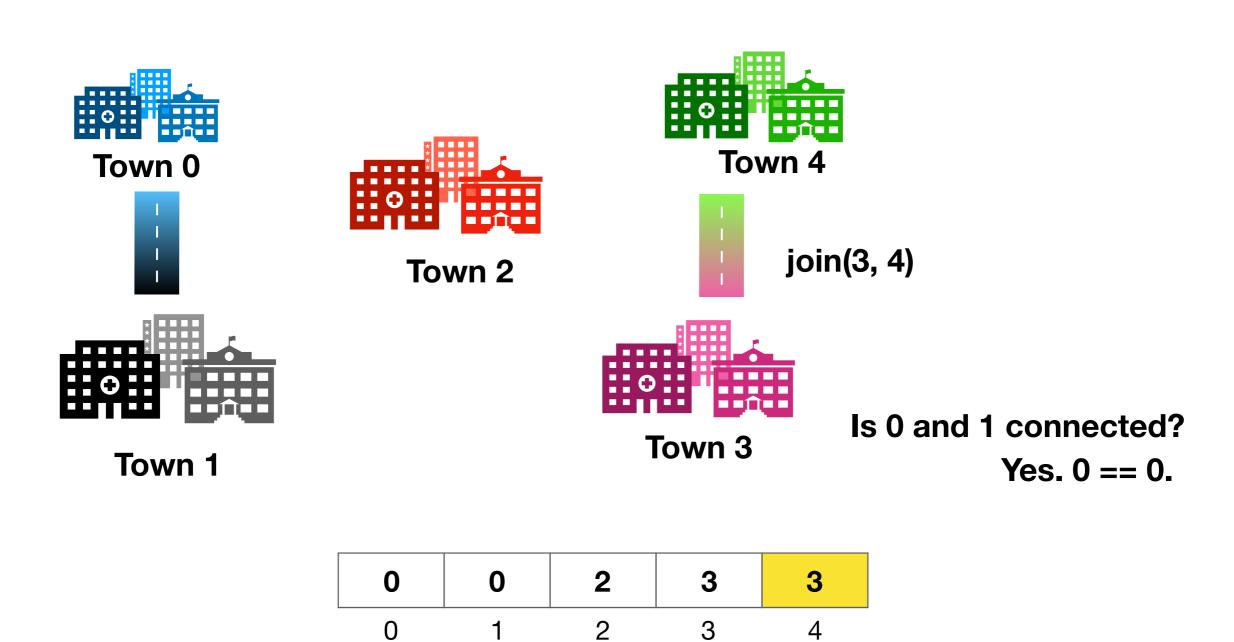




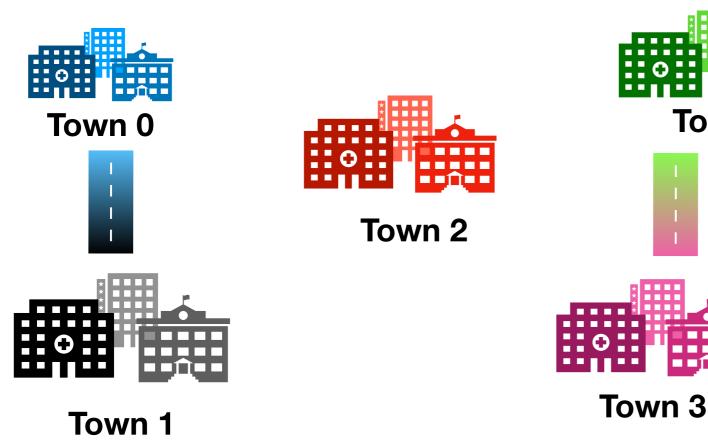


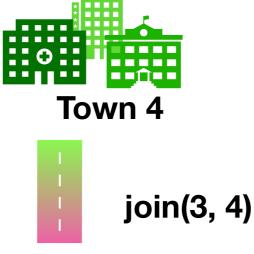






Assign each connected set a number. When unioning two sets, set all elements in those two sets to the same group number.



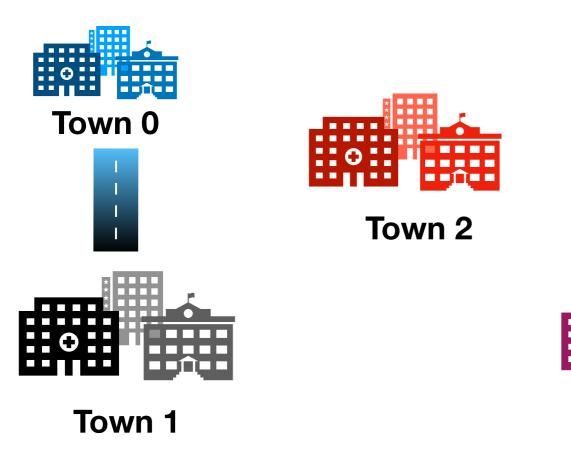


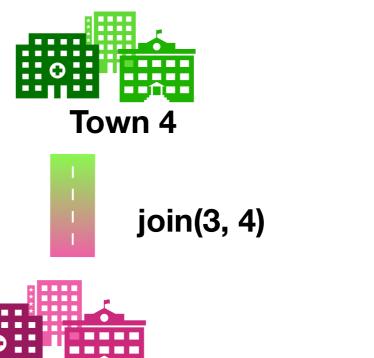
Is 0 and 1 connected? Yes. 0 == 0.

Is 0 and 4 connected?

0	0	2	3	3
0	1	2	3	4

Assign each connected set a number. When unioning two sets, set all elements in those two sets to the same group number.



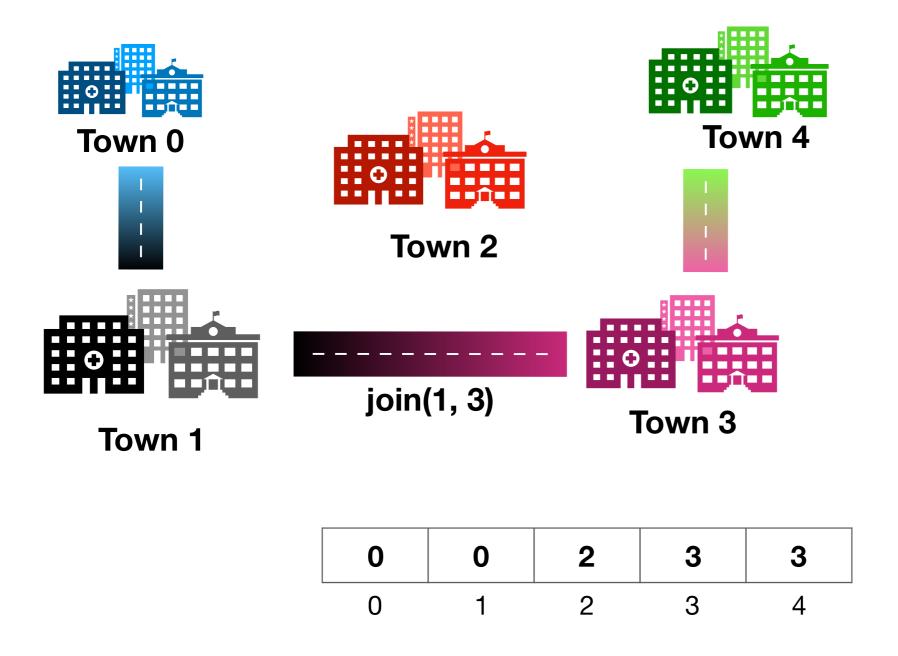


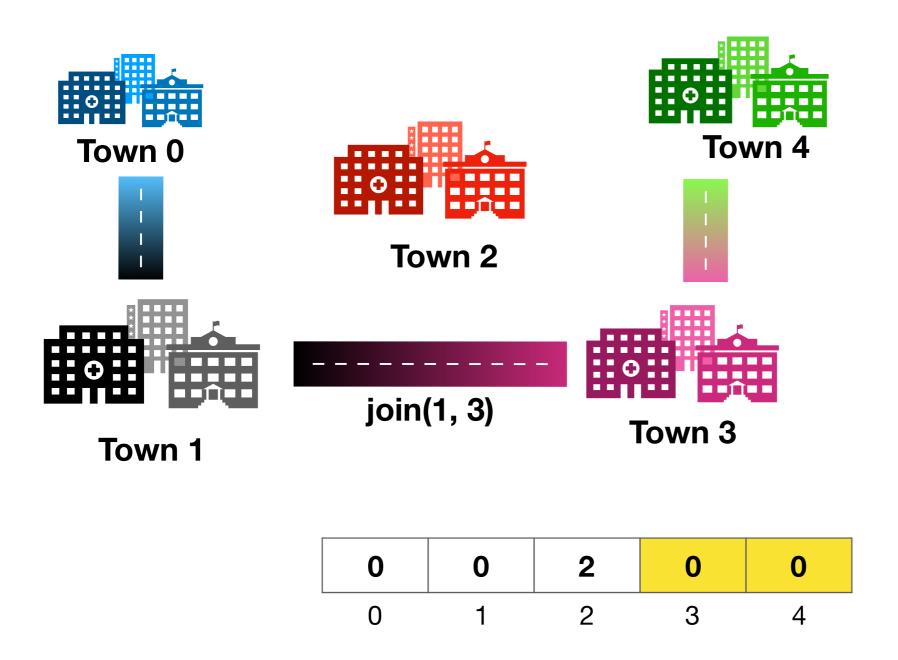


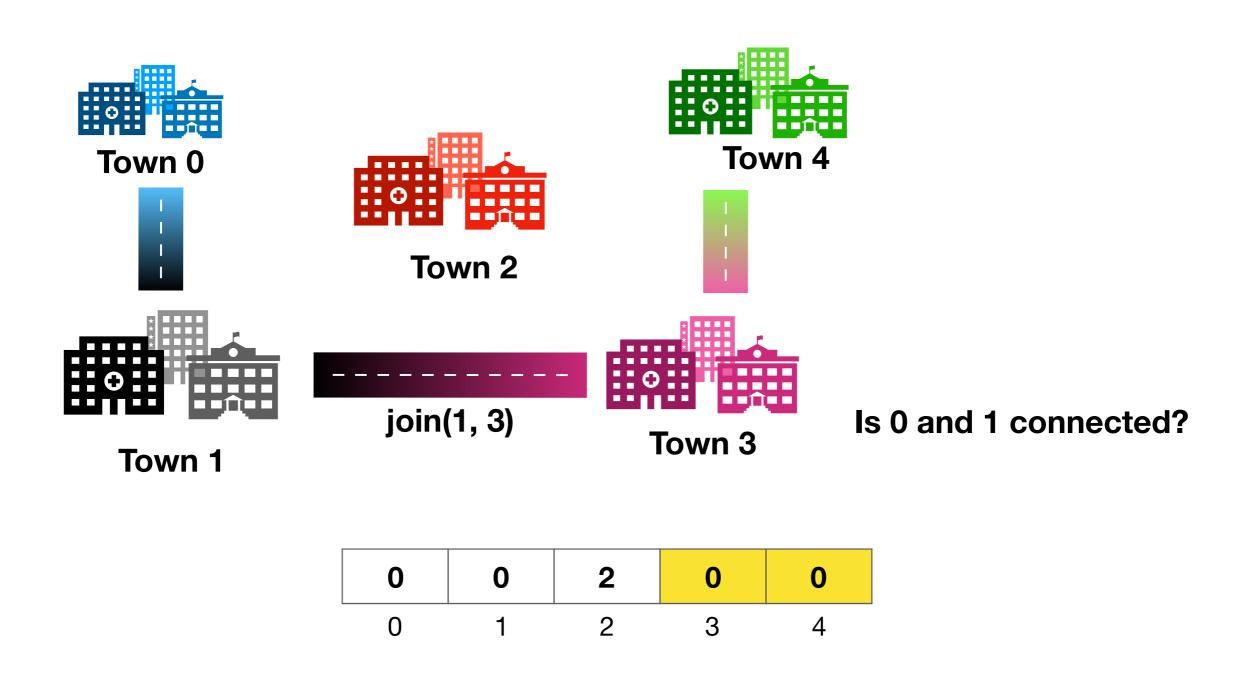
Is 0 and 1 connected? Yes. 0 == 0.

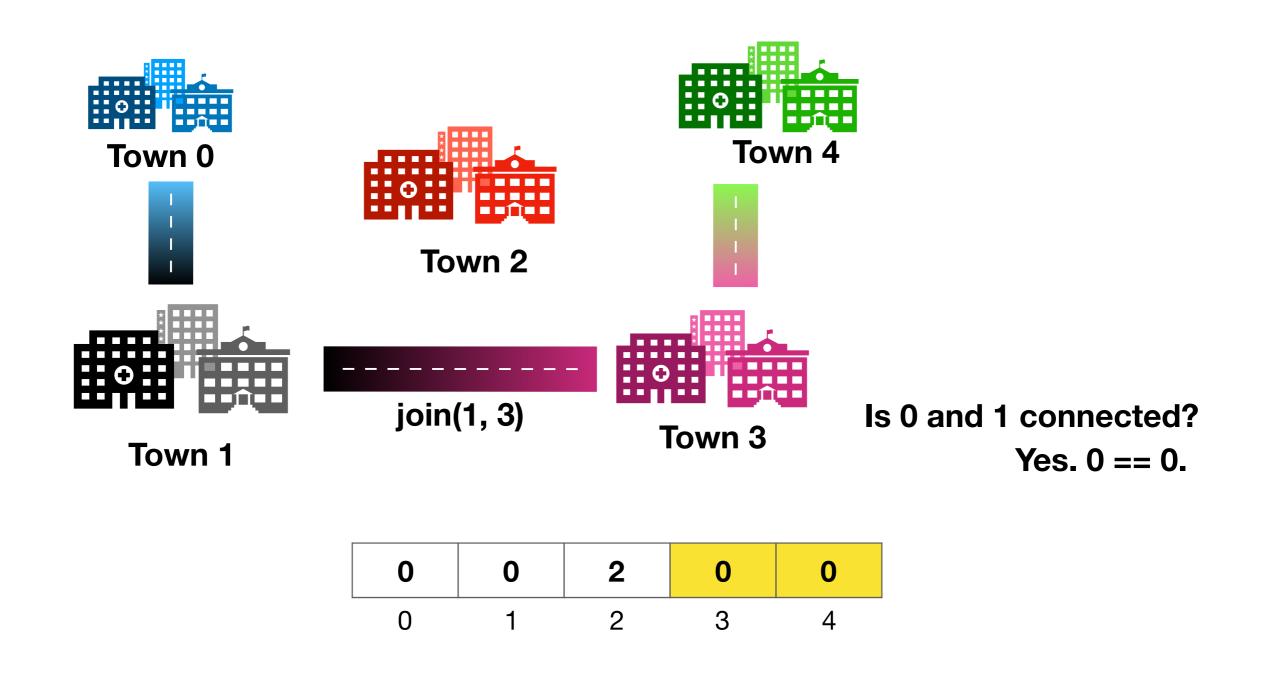
Is 0 and 4 connected?
No. 0 != 3

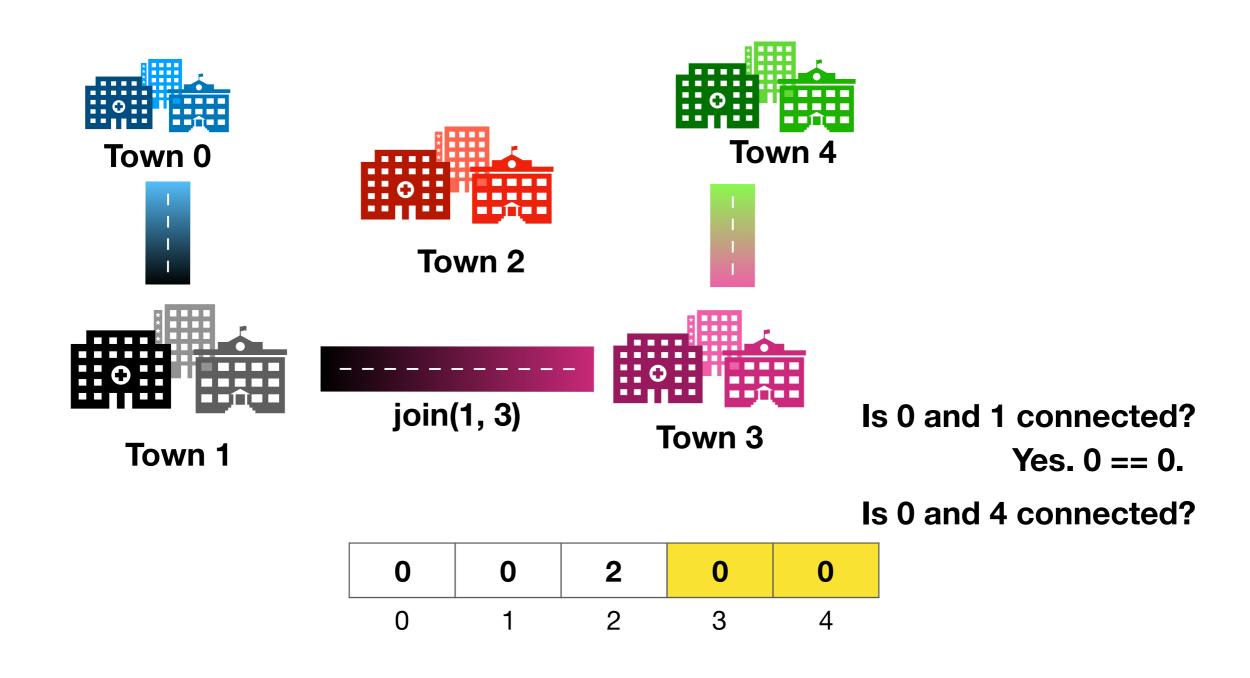
0	0	2	3	3
0	1	2	3	4

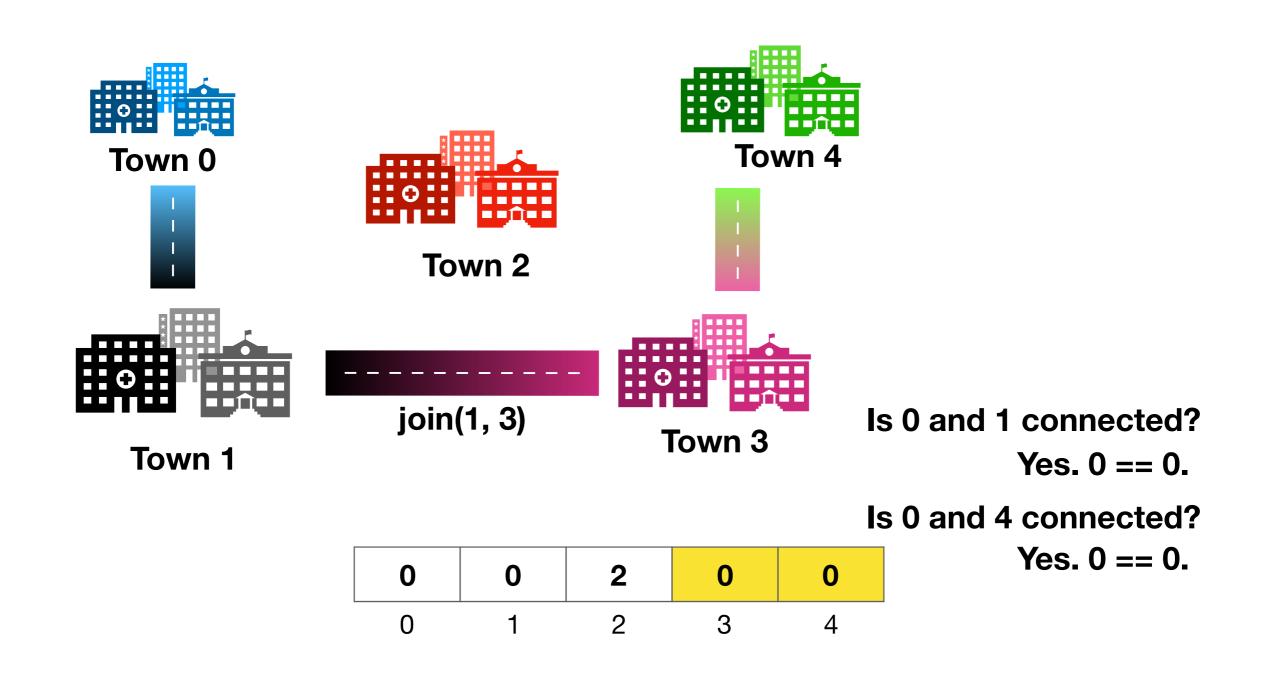












### QuickFind Pseudocode

```
class QuickFindDS:
  int[] id
  QuickFindDS(N):
    id = new int[N]
    for i in 0...N:
      id[i] = i
  find(a):
                                 Runtime?
    return id[a]
  union(a, b):
    let aId = id[a]
    let bId = id[b]
                                Runtime?
    for i in 0...N:
      if id[i] == a_id:
        id[i] = b_id
```

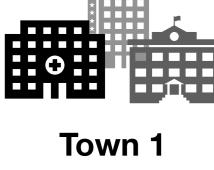
### QuickFind Pseudocode

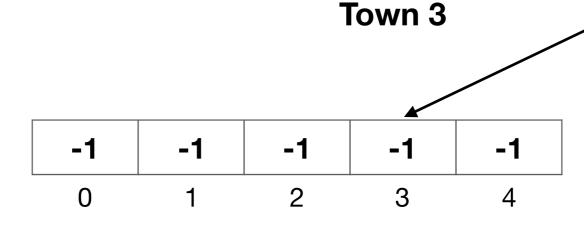
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class QuickFindDS:
  int[] id
  QuickFindDS(N):
    id = new int[N]
    for i in 0...N:
      id[i] = i
  find(a):
                                 Runtime?
                                               \Theta(1)
    return id[a]
  union(a, b):
    let aId = id[a]
    let bId = id[b]
                                 Runtime?
    for i in 0...N:
      if id[i] == a_id:
        id[i] = b_id
```

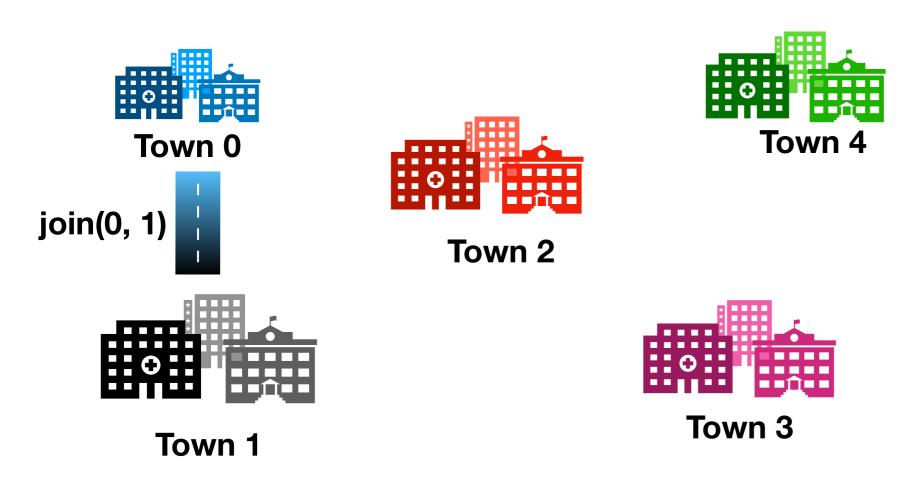
## QuickFind Pseudocode

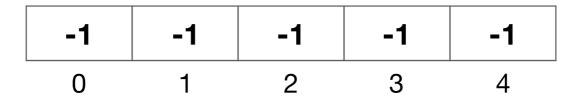
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      id[i] = i
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                                  Runtime?
                                                \Theta(1)
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    let aId = id[a]
    let bId = id[b]
                                  Runtime?
                                               \Theta(N)
    for i in 0...N:
      if id[i] == a_id:
        id[i] = b_id
```

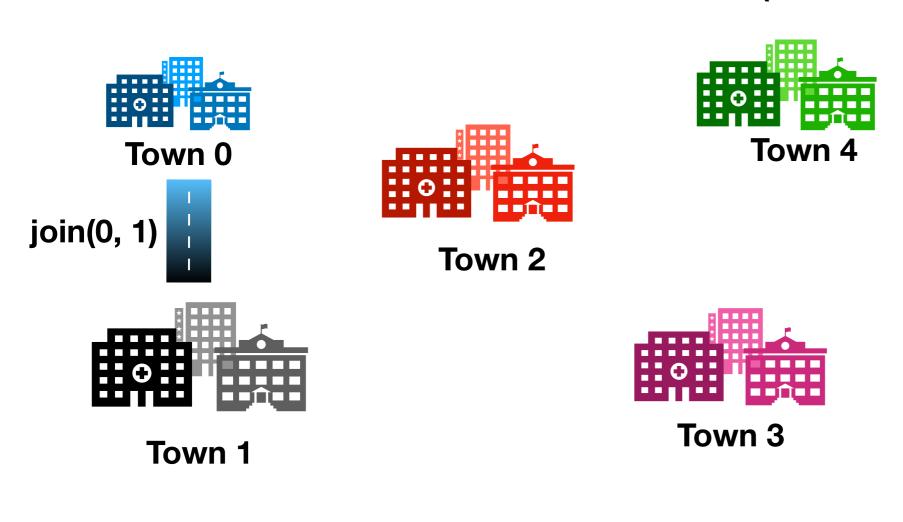


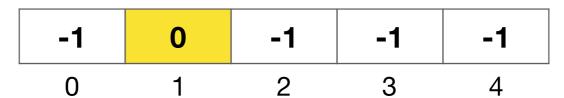


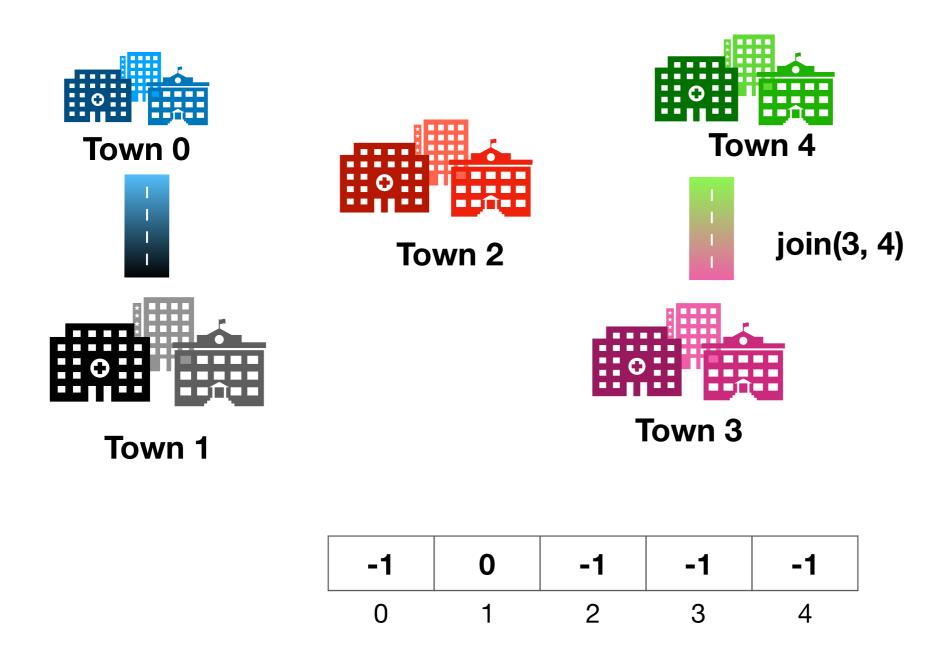


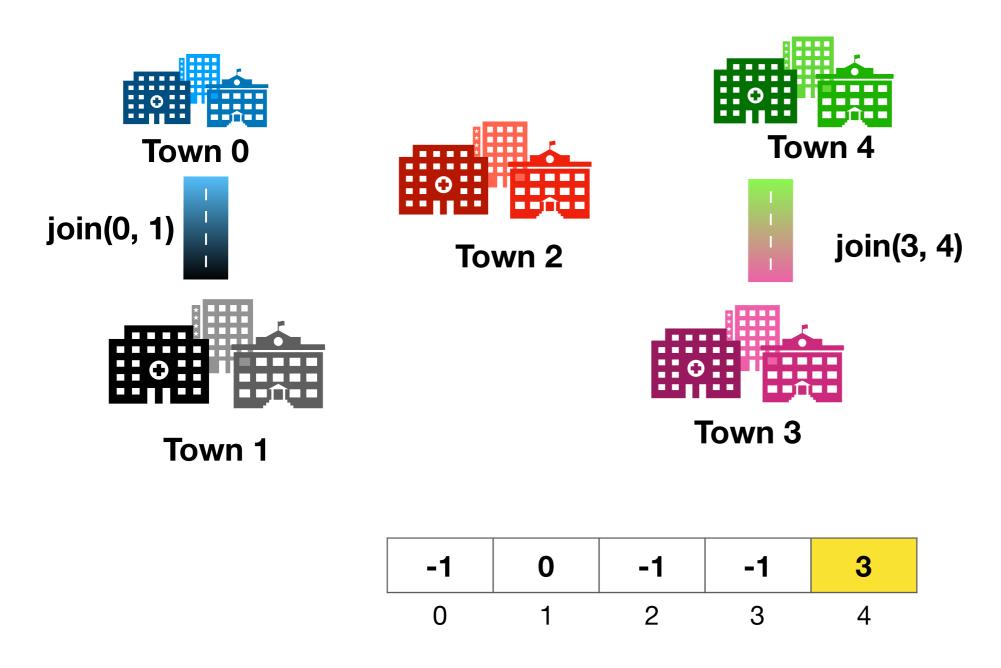


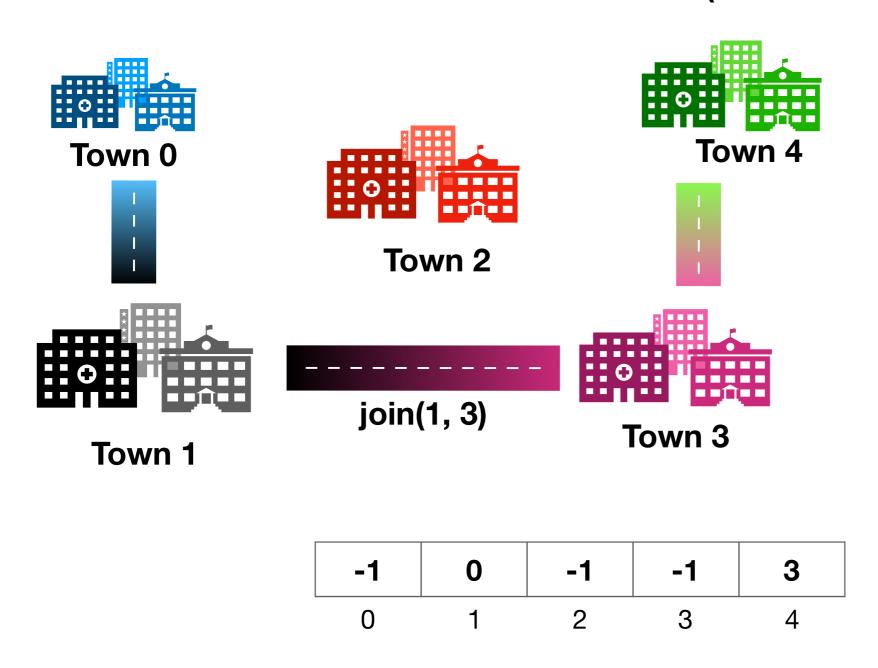


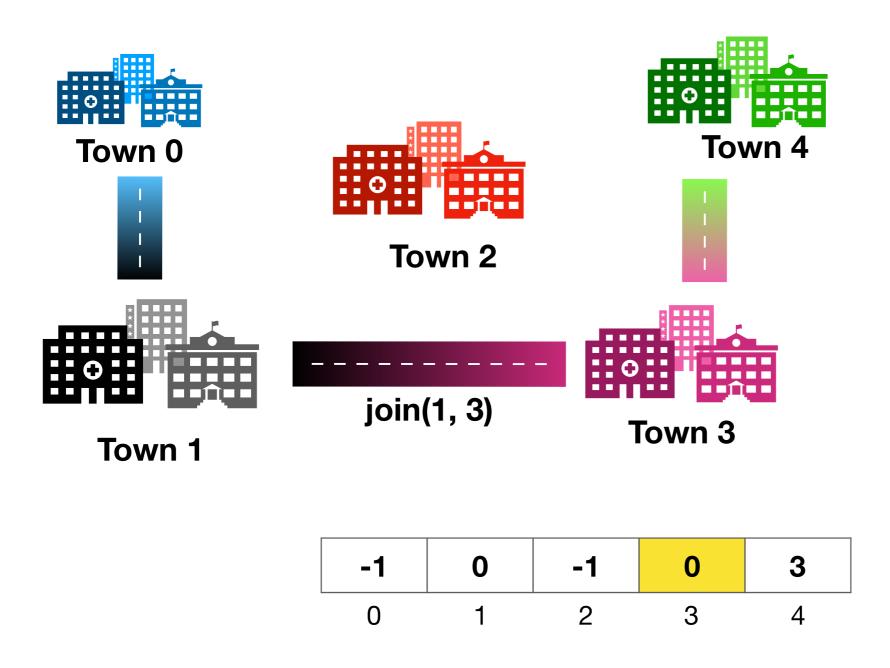


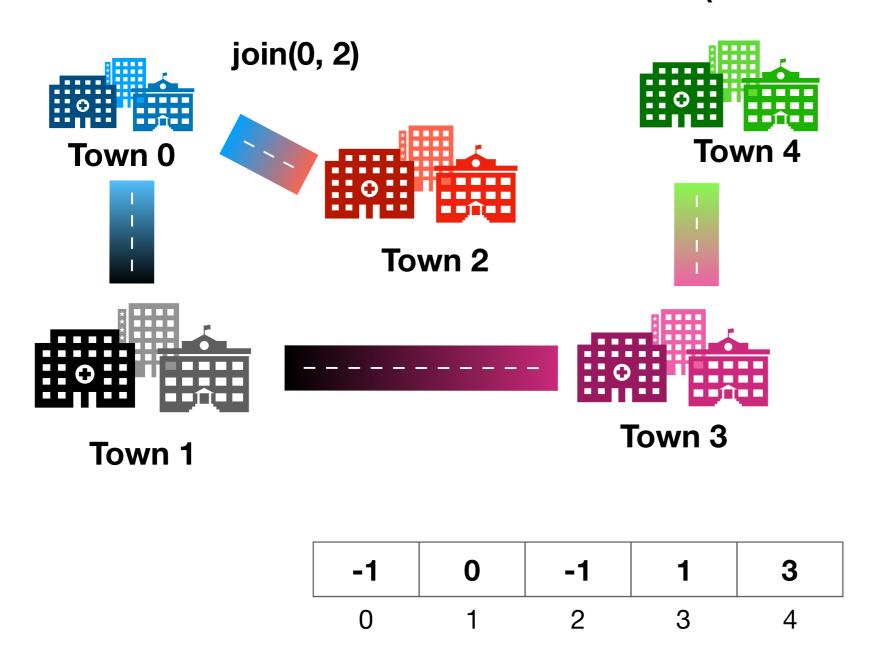


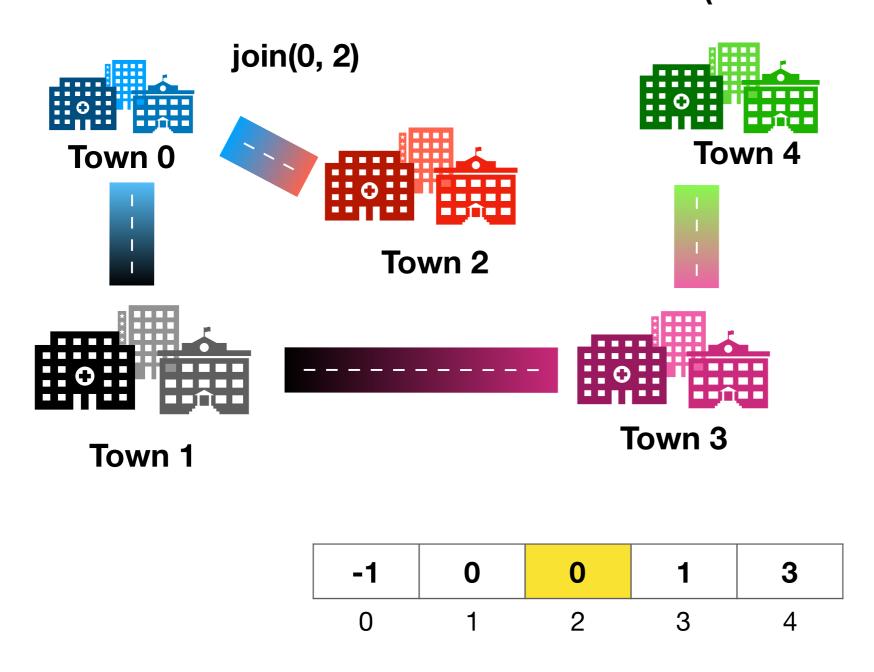










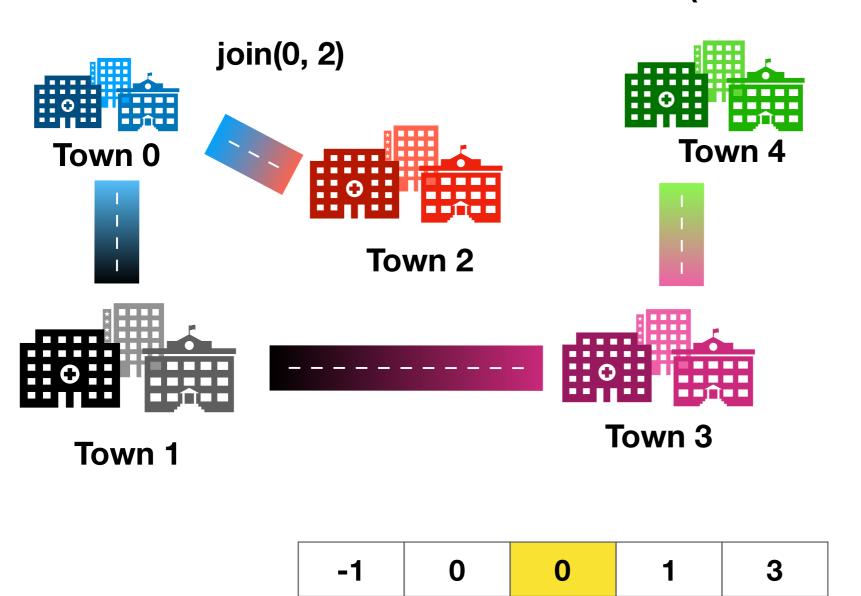


We will represent the sets using a tree structure.

When you join a and b, set the root of a to be the parent of the root of b.

The set # is the oldest ancestor (i.e. the root).

3



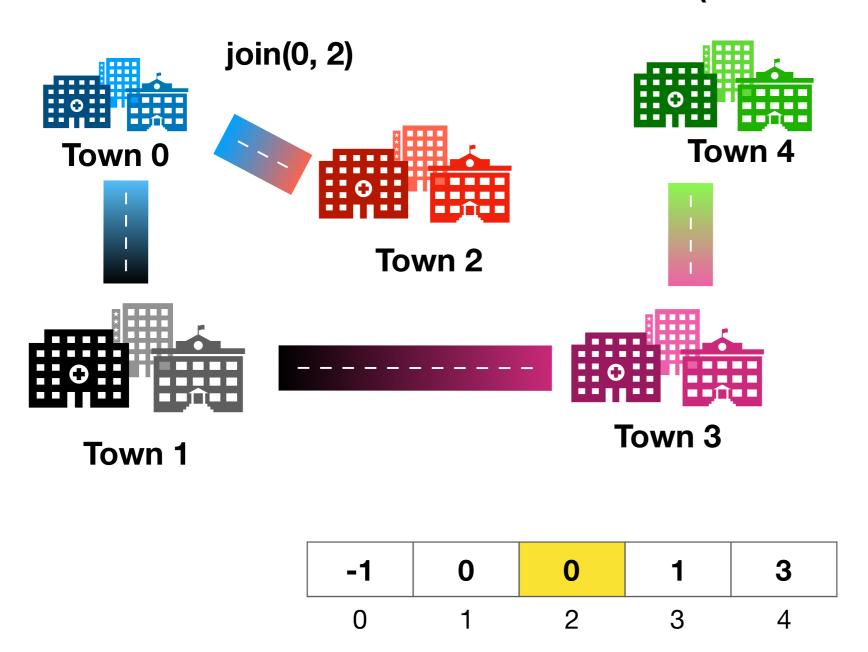
0

Is 2 and 4 connected?

We will represent the sets using a tree structure.

When you join a and b, set the root of a to be the parent of the root of b.

The set # is the oldest ancestor (i.e. the root).



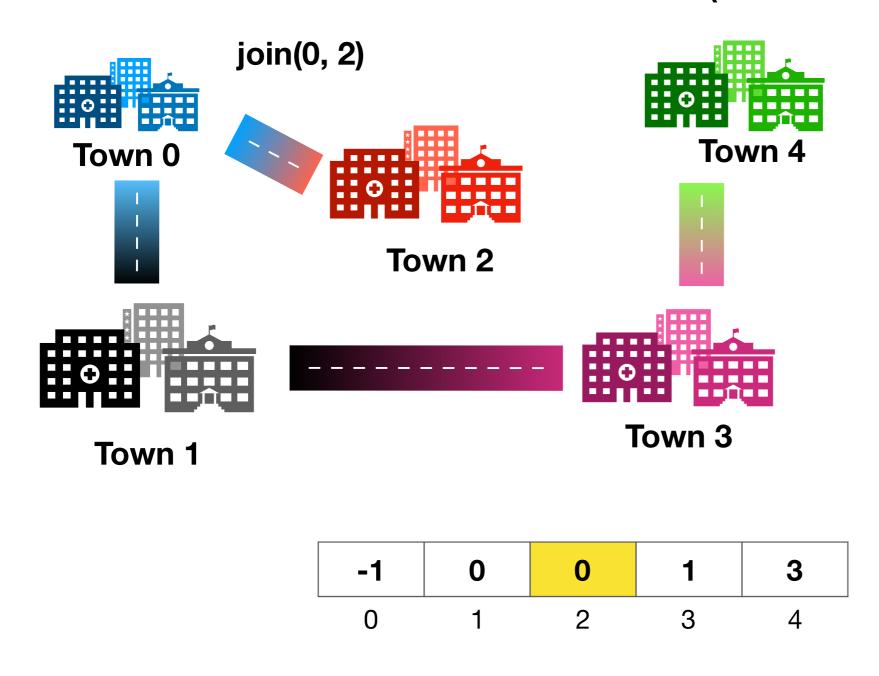
Is 2 and 4 connected?

See if find() returns the same thing.

We will represent the sets using a tree structure.

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Is 2 and 4 connected?

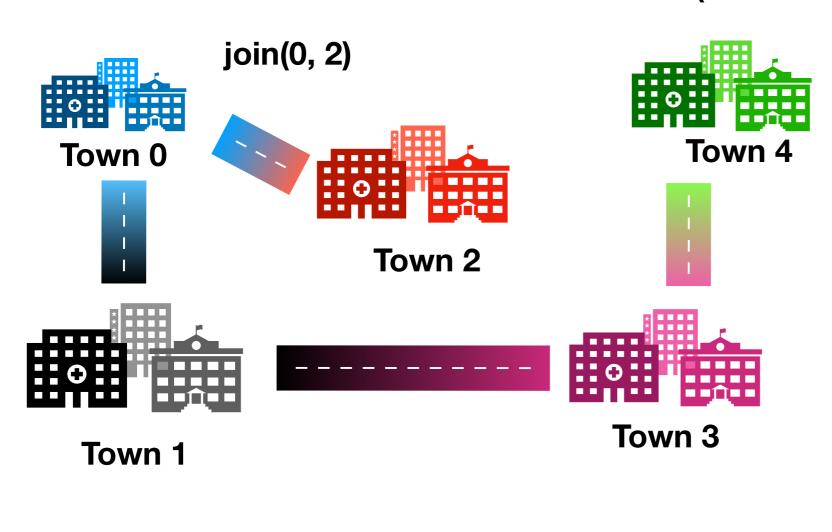
See if find() returns the same thing.

$$2 -> 0$$

We will represent the sets using a tree structure.

When you join a and b, set the root of a to be the parent of the root of b.

The set # is the oldest ancestor (i.e. the root).



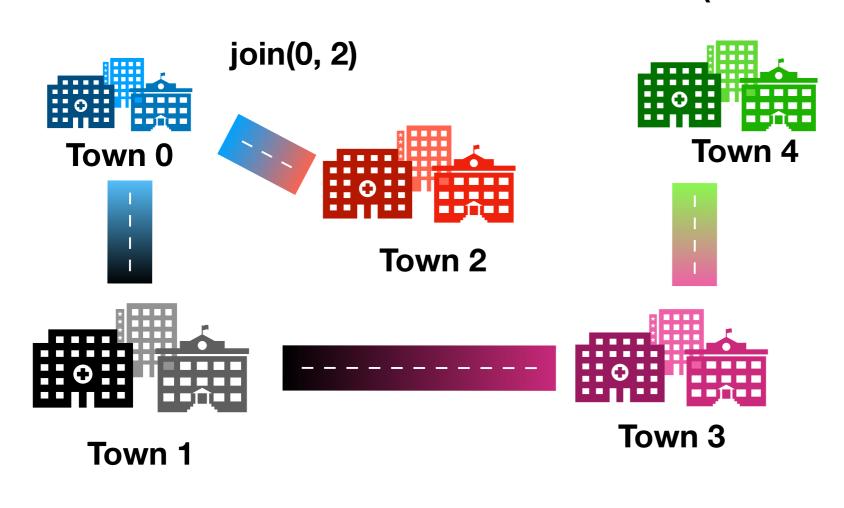
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When you join a and b, set the root of a to be the parent of the root of b.

The set # is the oldest ancestor (i.e. the root).



Is 2 and 4 connected?

See if find() returns the same thing.

Yes.

## QuickUnion Pseudocode

```
class QuickUnionDS:
  int[] parent
                                           Problem: we're forming a tree
                                           structure and it's possible the
  QuickUnionDS(N):
                                                 tree is spindly!
    parent = new int[N]
    for i in 0...N:
      id[i] = -1
  find(a):
    let curr = a
    while parent[curr] != -1:
                                         Runtime?
      curr = parent[curr]
    return curr
  union(a, b):
                                         Runtime?
    parent[find(b)] = find(a)
```

## QuickUnion Pseudocode

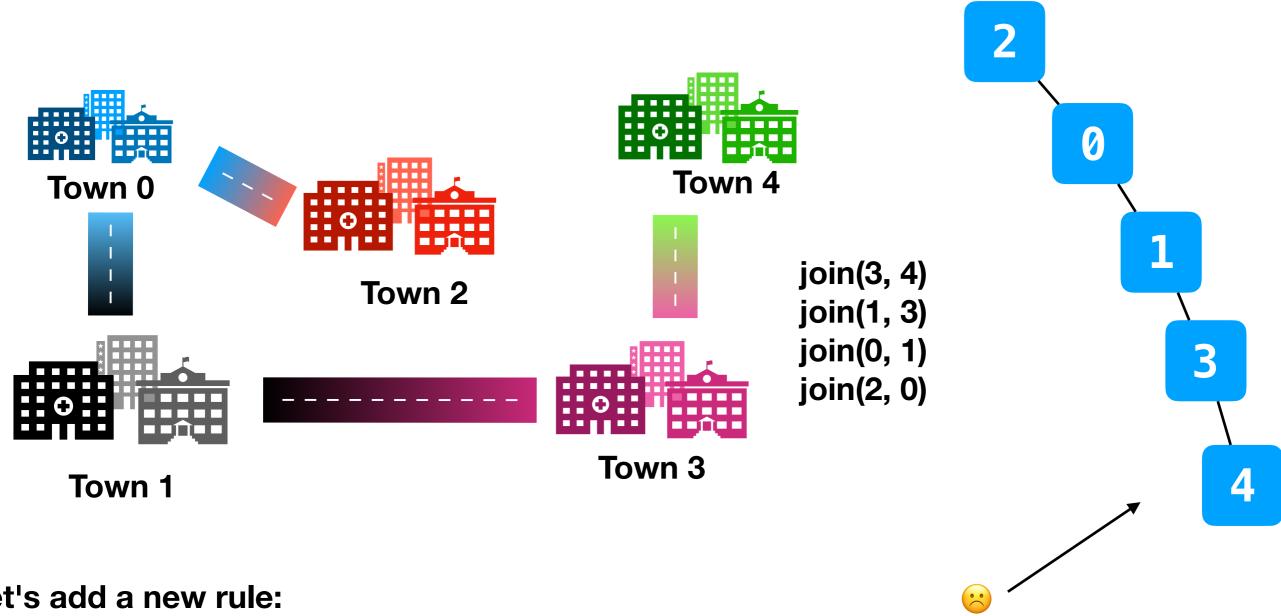
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  find(a):
    let curr = a
    while parent[curr] != -1:
                                         Runtime? O(N)
      curr = parent[curr]
    return curr
  union(a, b):
                                         Runtime?
    parent[find(b)] = find(a)
```

## QuickUnion Pseudocode

```
class QuickUnionDS:
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                                          Problem: we're forming a tree
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      curr = parent[curr]
    return curr
  union(a, b):
                                         Runtime? O(N)
    parent[find(b)] = find(a)
```

## Problem with QuickUnion

Easy to get spindly tree depending on insertion order.



Let's add a new rule:

Let's add a new rule:

1. Always join the smaller tree to the larger tree



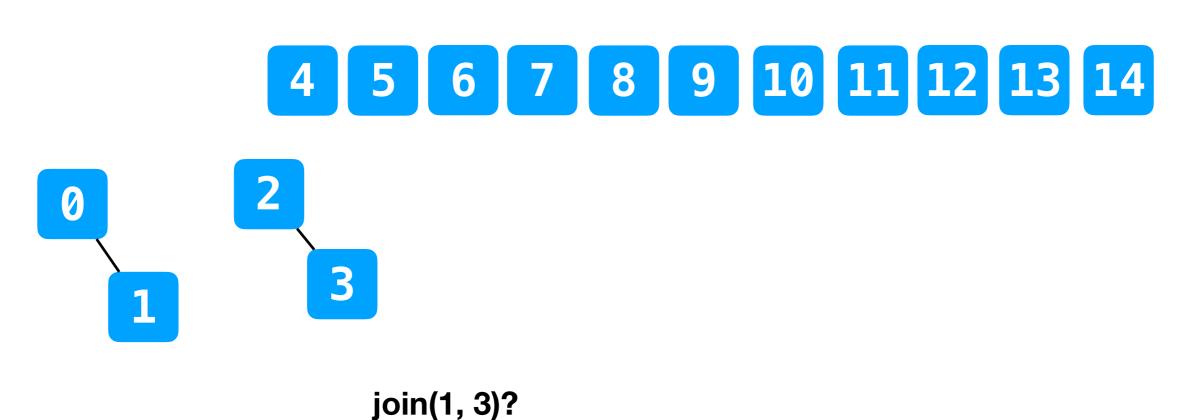
join(0, 1)?

#### Let's add a new rule:



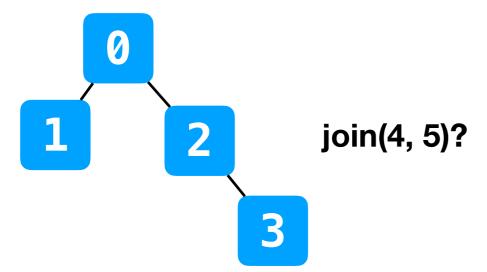


#### Let's add a new rule:

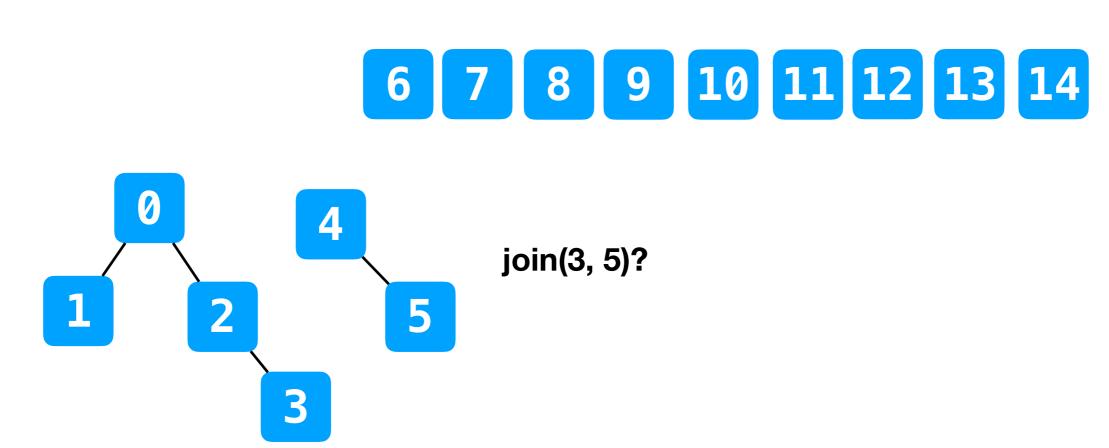


#### Let's add a new rule:

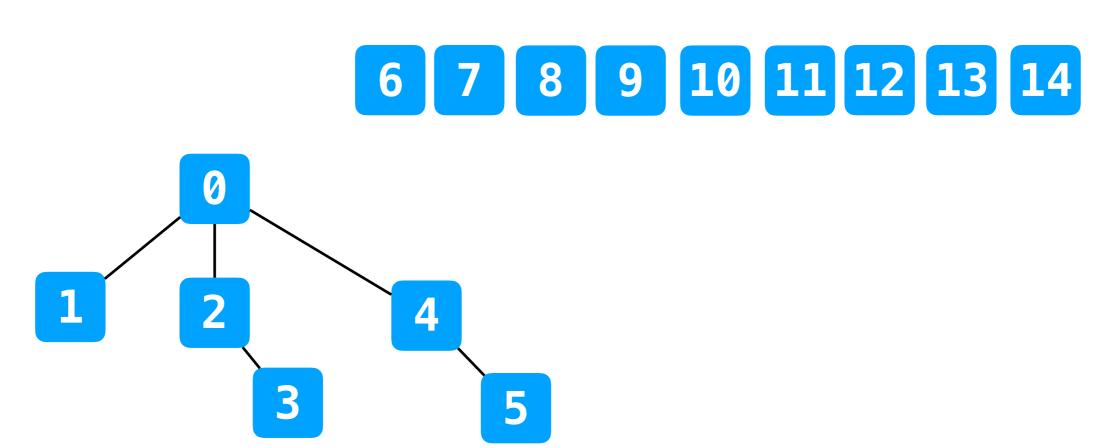




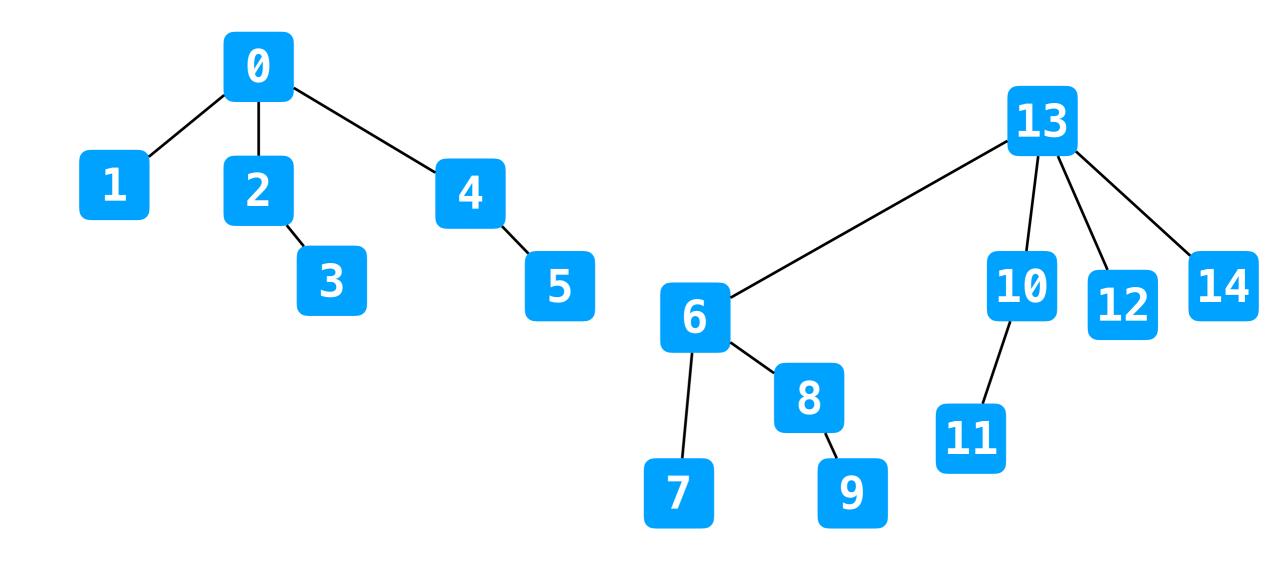
#### Let's add a new rule:



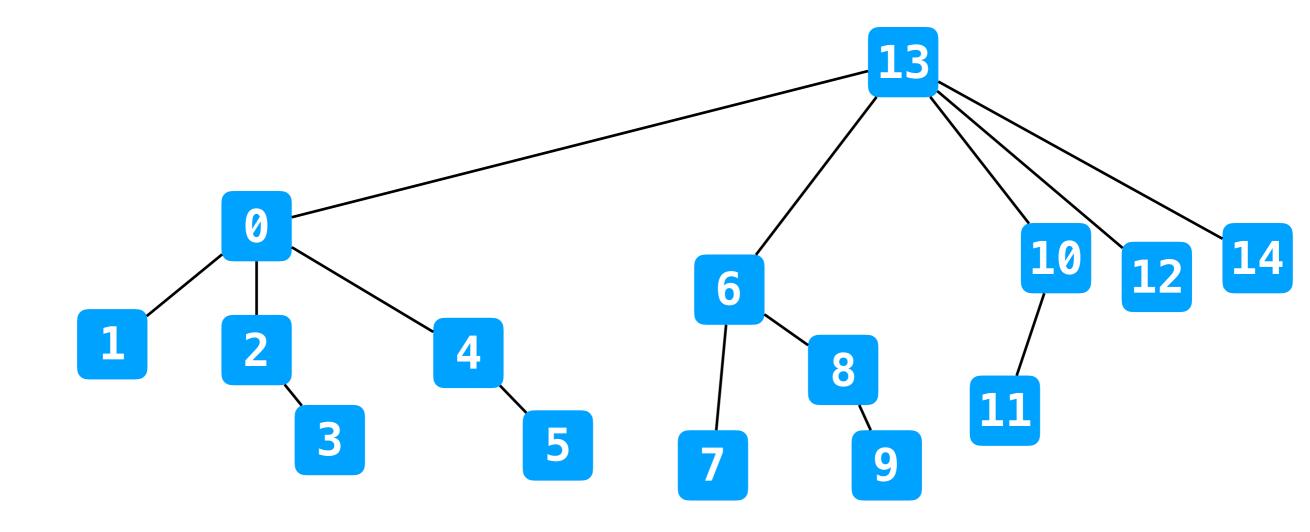
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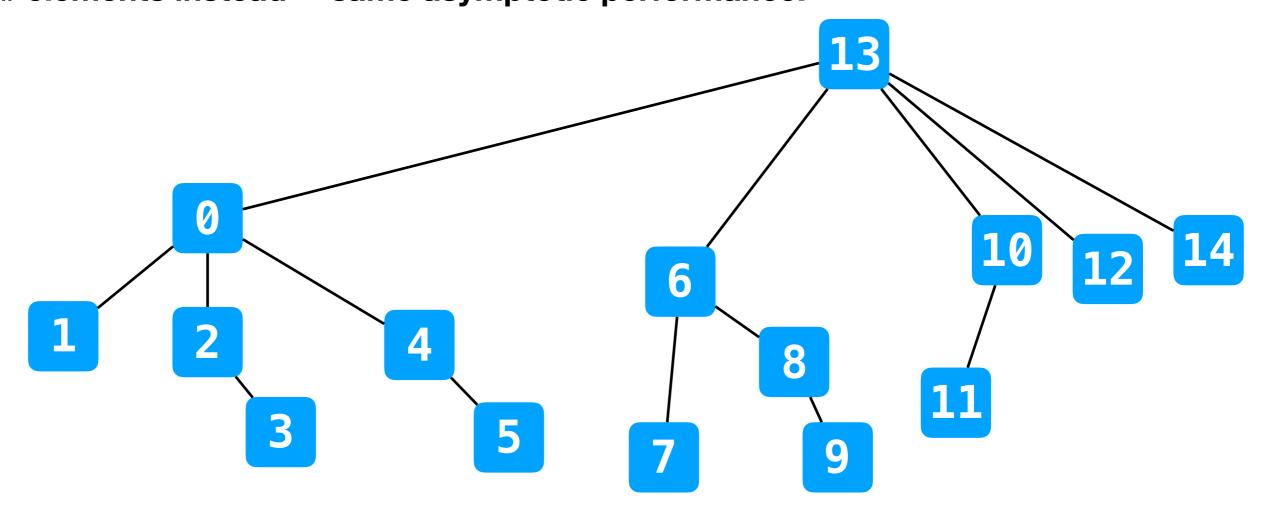
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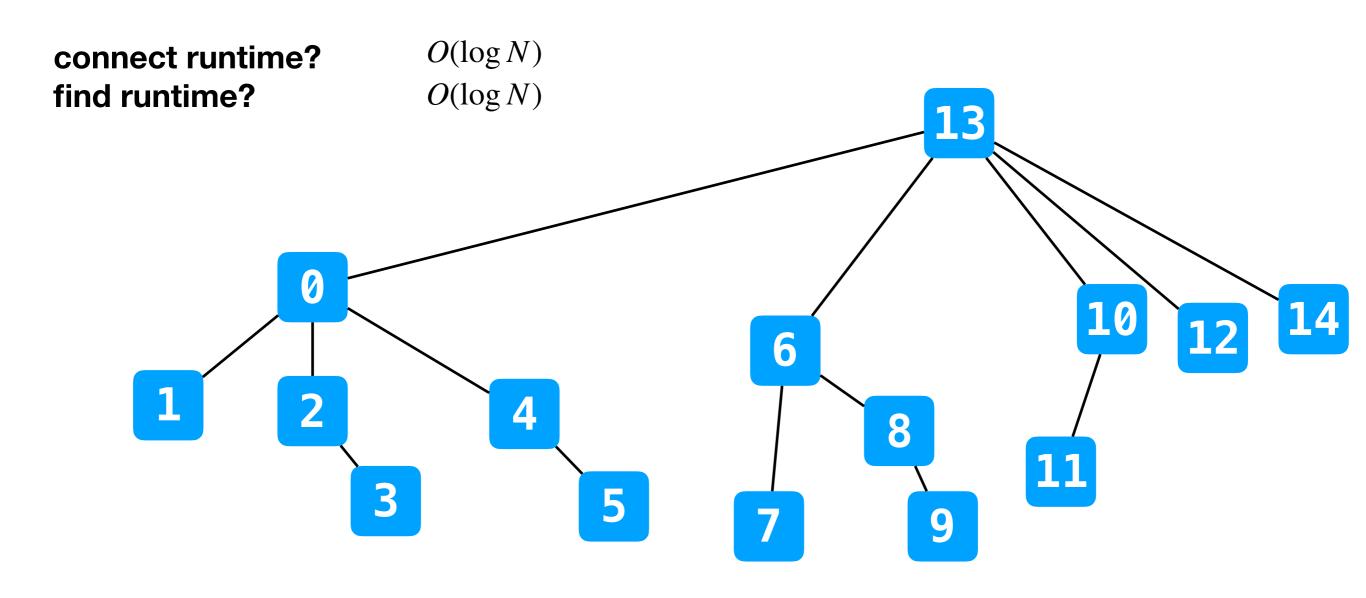
#### Let's add a new rule:

1. Always join the smaller tree to the larger tree

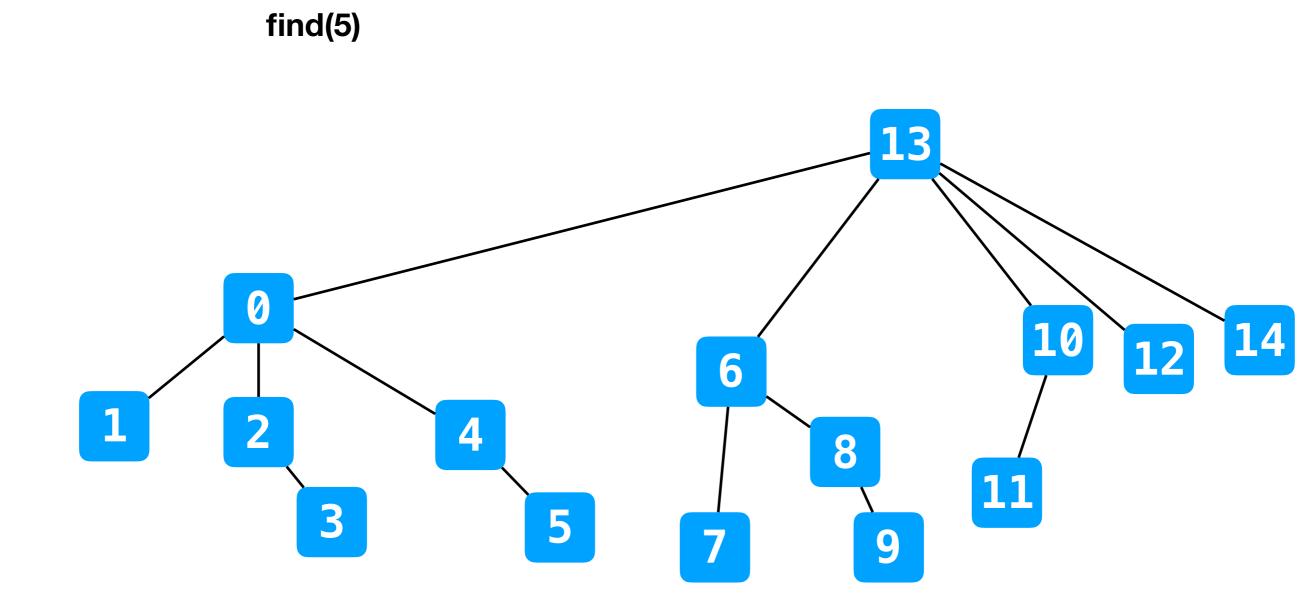
What constitutes "larger"?
Height seems most intuitive but is more annoying to calculate.
Use # elements instead -- same asymptotic performance.



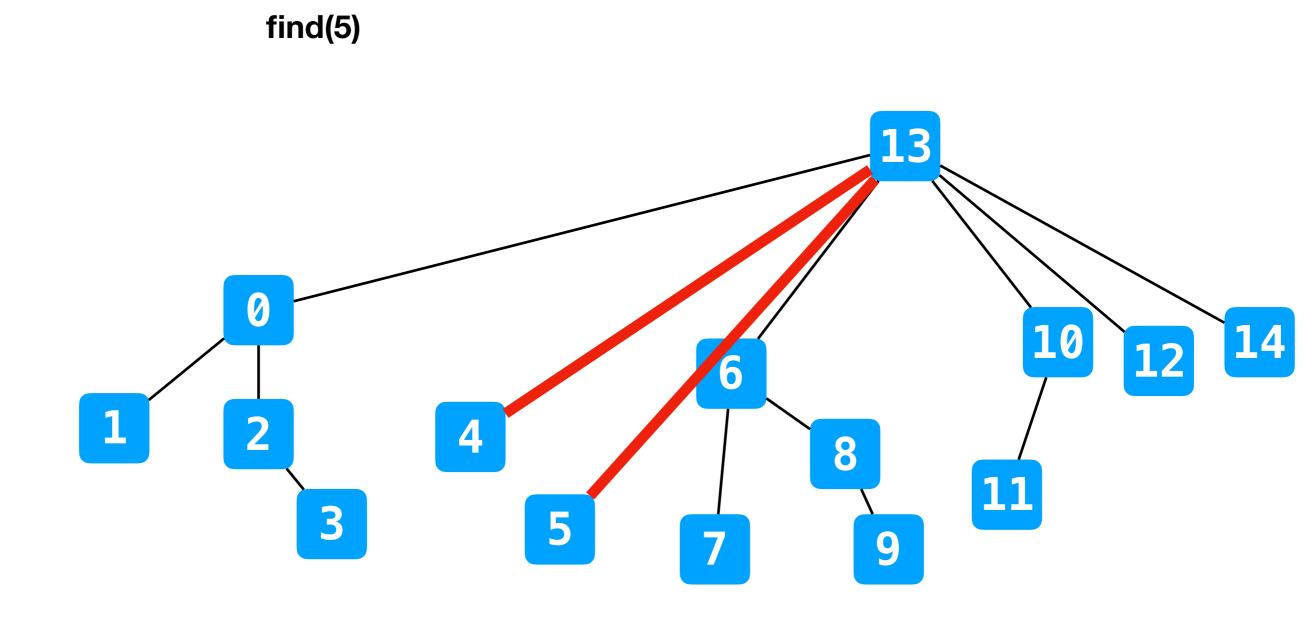
#### Let's add a new rule:



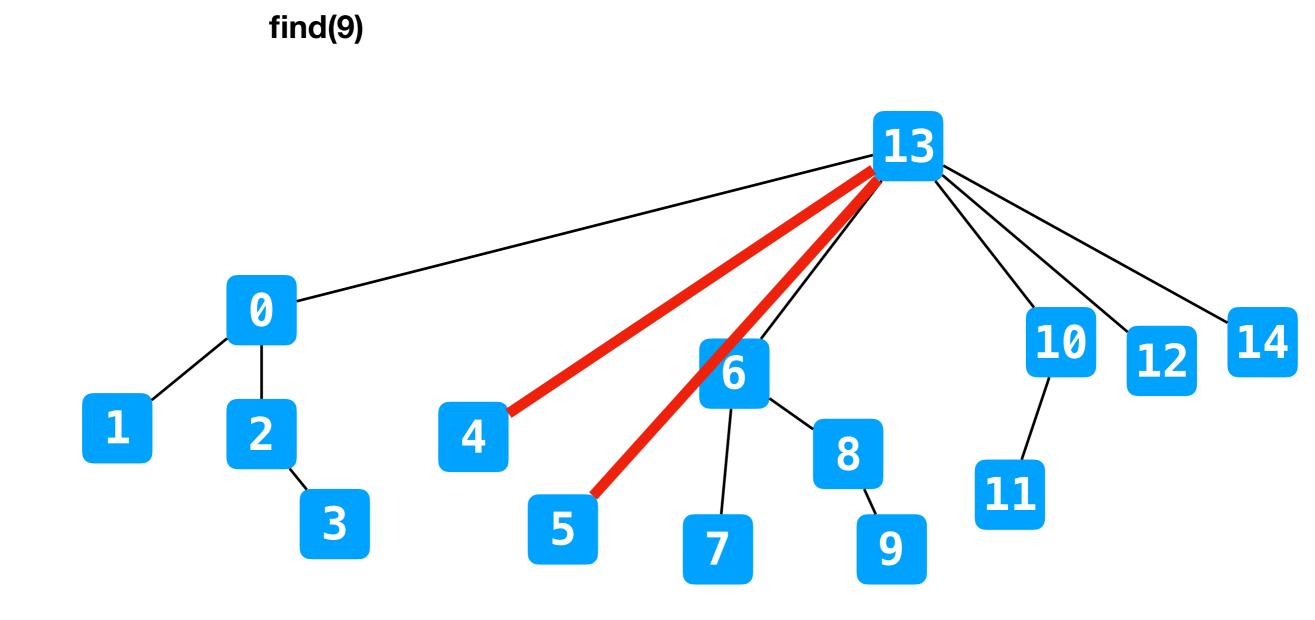
Whenever you run find, tie nodes along the way back to the root.



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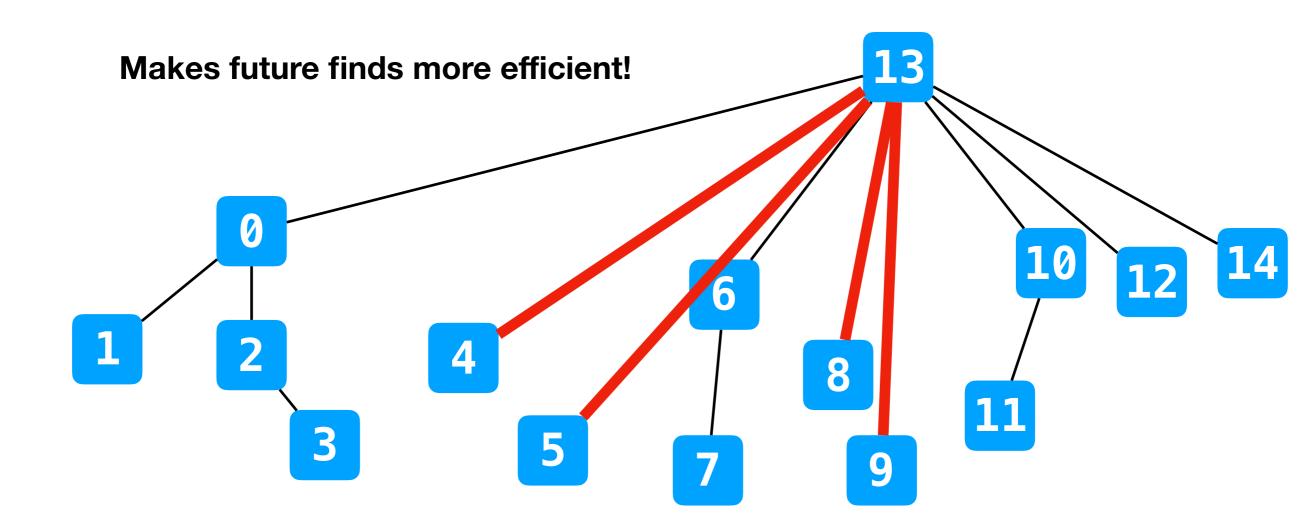


Whenever you run find, tie nodes along the way back to the root.



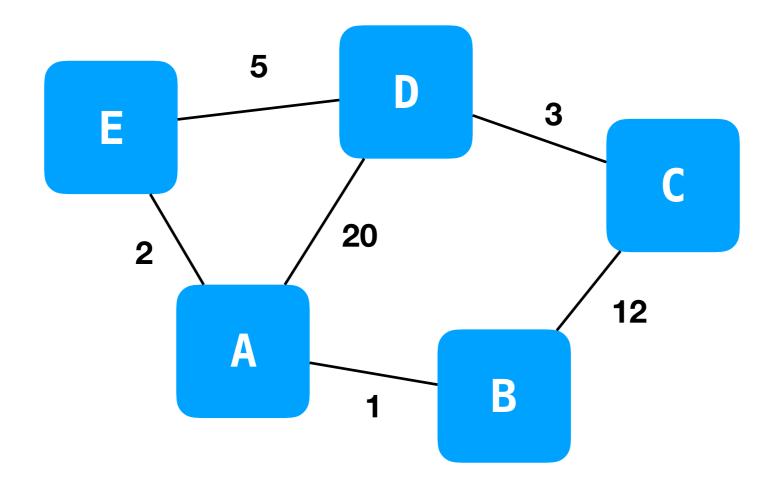
Whenever you run find, tie nodes along the way back to the root.

#### find(9)



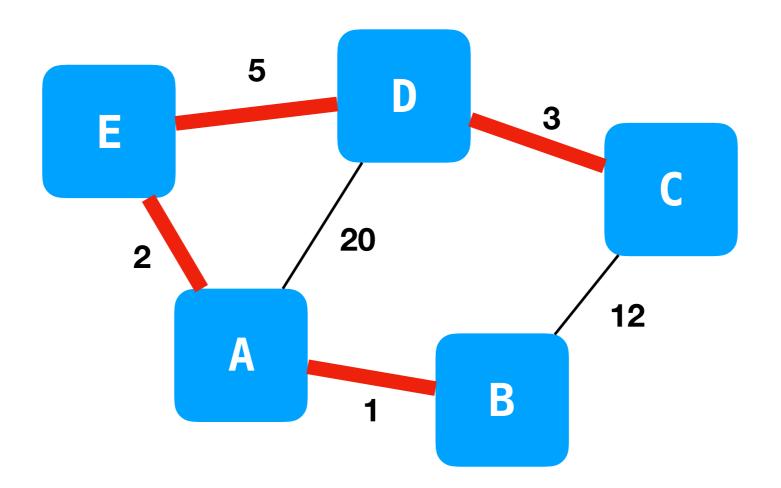
## Minimum Spanning Tree

• The MST of a graph is a tree consisting of all of the vertices of the graph but whose total edge weights are minimized.



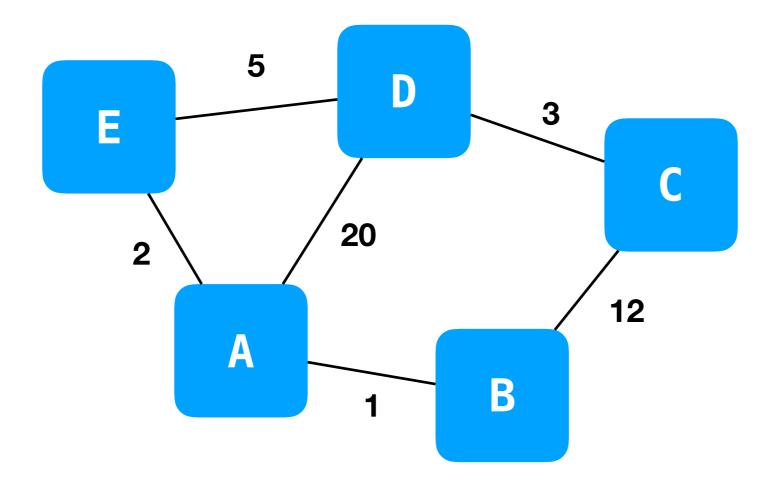
## Minimum Spanning Tree

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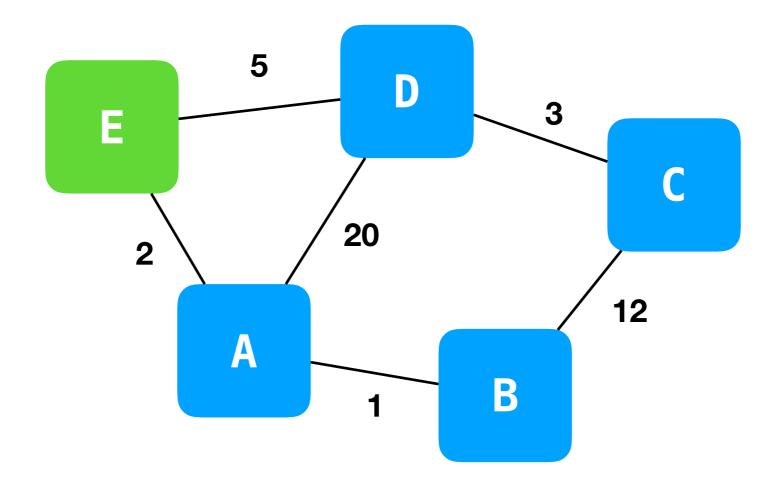


## Prim's Algorithm

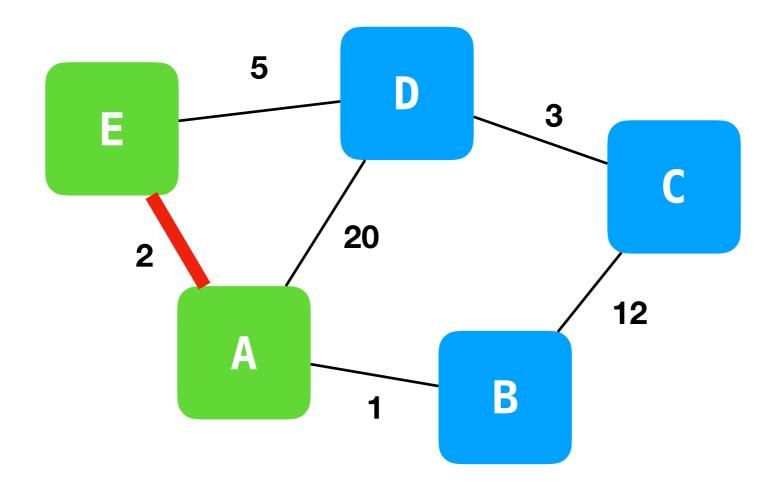
- Start at an arbitrary node, add to MST.
- Find the closest node to the in-progress MST and add it to the MST.
- Repeat until V 1 edges.



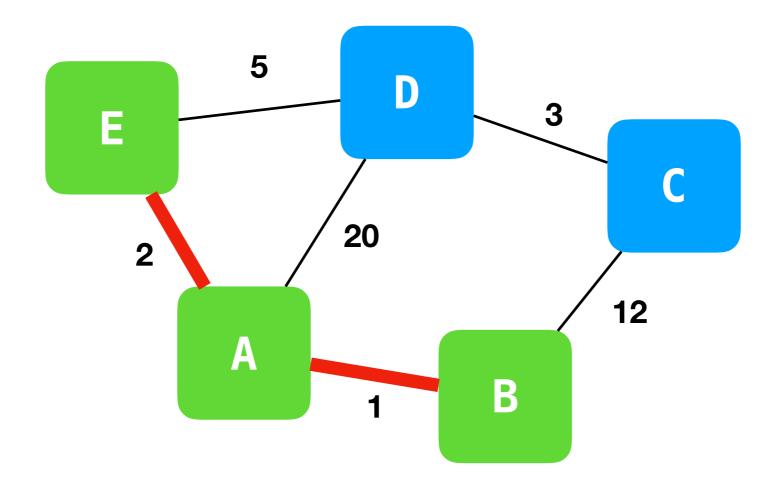
- Start at an arbitrary node, add to MST.
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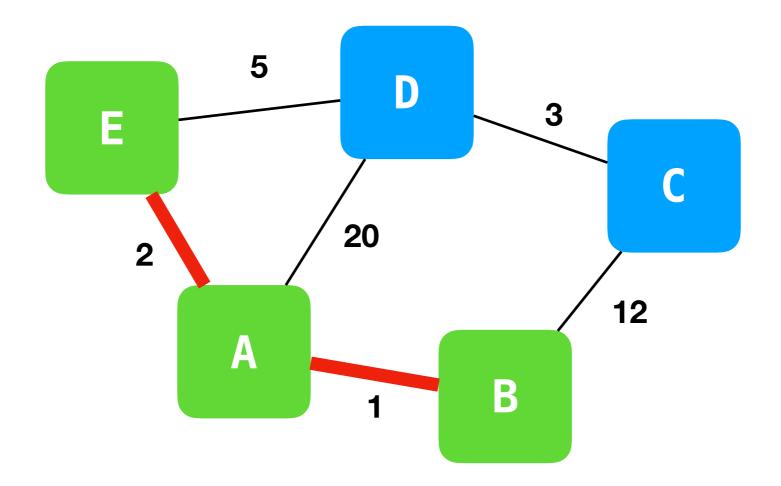
- Start at an arbitrary node, add to MST.
- Find the closest node to the in-progress MST and add it to the MST.
- Repeat until V 1 edges.



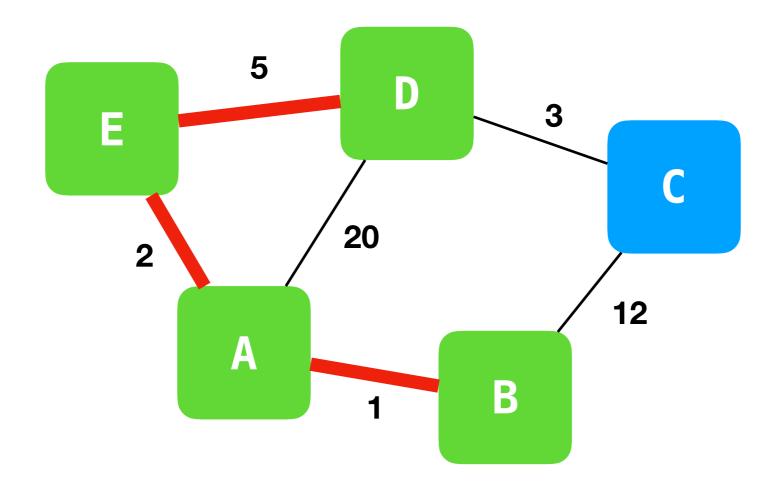
- Start at an arbitrary node, add to MST.
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- Repeat until V 1 edges.



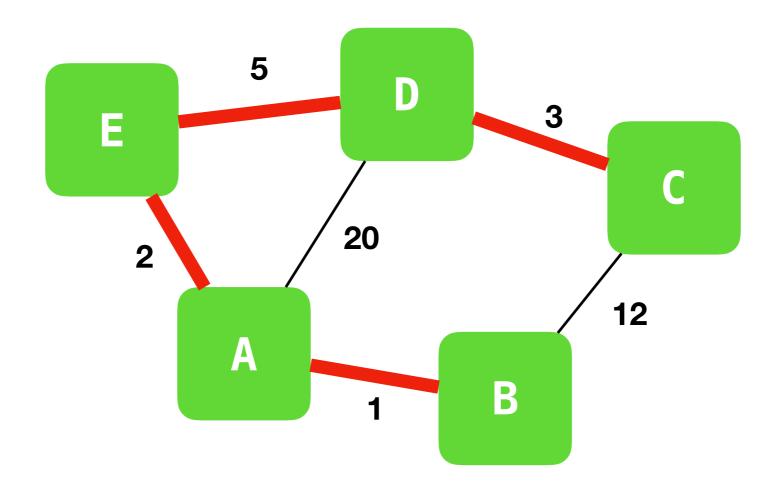
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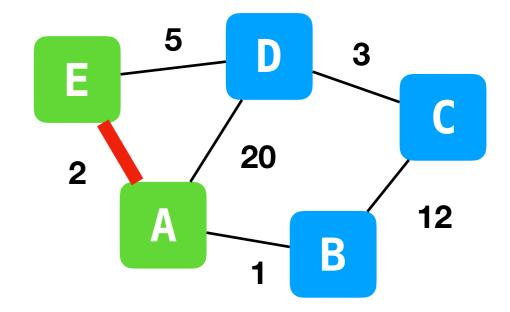
#### Prim's Algorithm Runtime

- We'll use a priority queue of vertices to determine which node is closest to the in-progress MST.
- Cost of inserting/updating a priority queue?  $\log V$ .
- ullet How many insertions/updates are we doing? However many edges we have. E.
- In total, worst-case runtime is  $\Theta(E \log V)$ .

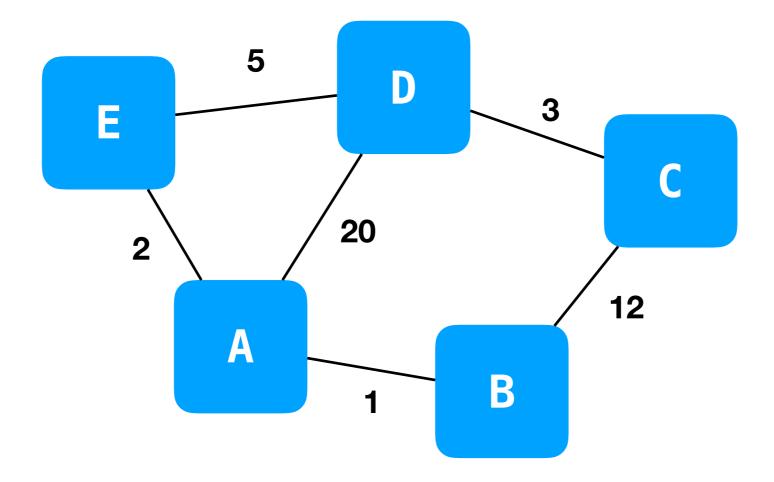
Start at an arbitrary node, add to MST.

Find the closest node to the inprogress MST and add it to the MST.

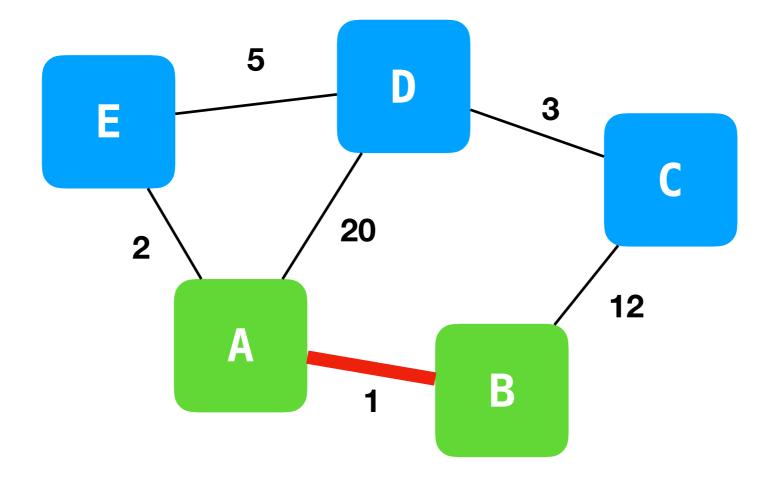
Repeat until V - 1 edges.



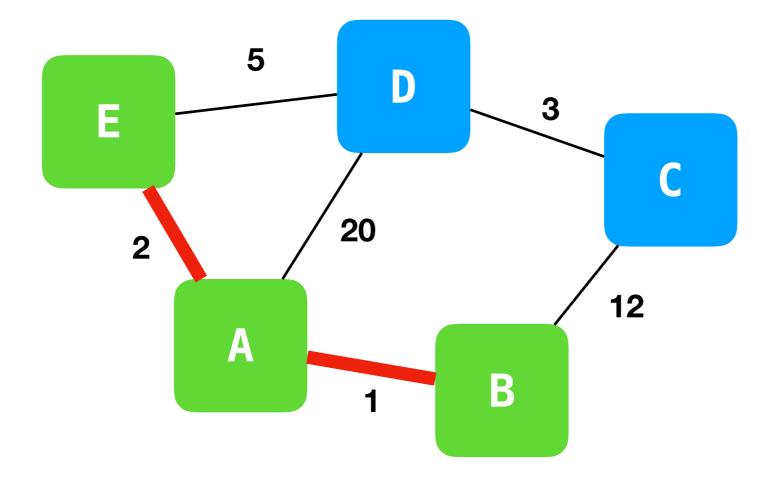
- Consider edges in order of weight, smallest first.
- Add edge to MST unless creates a cycle.
- Repeat until V 1 edges.



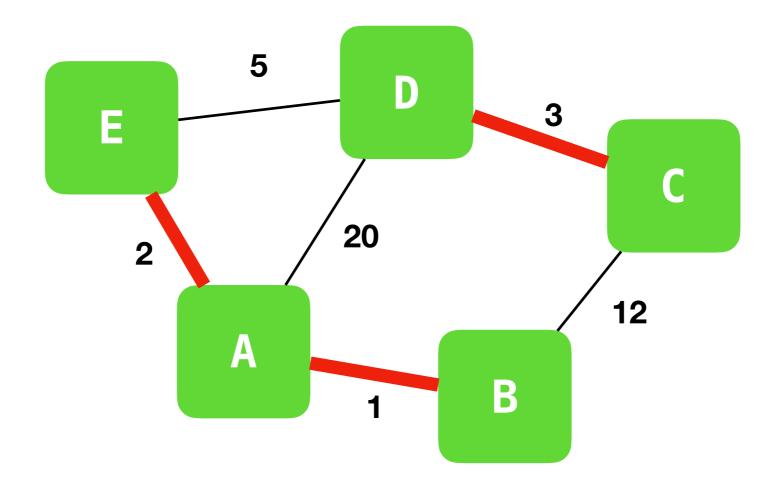
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- Repeat until V 1 edges.



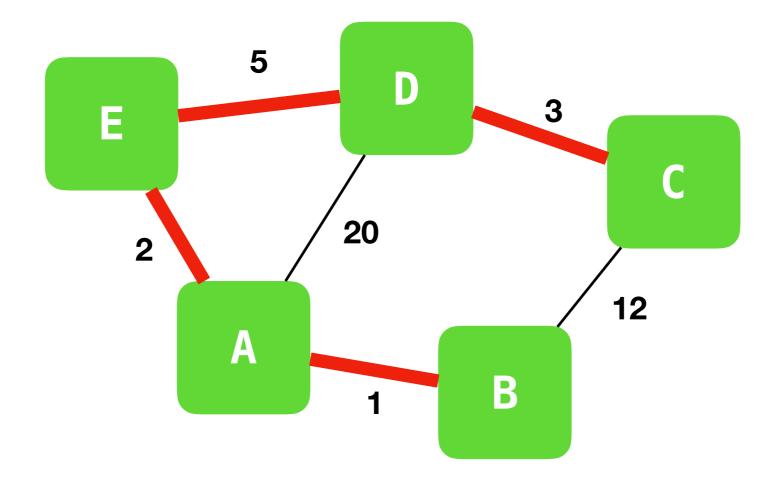
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- Consider edges in order of weight, smallest first.
- Add edge to MST unless creates a cycle.
- Repeat until V 1 edges.



### Kruskal's Algorithm Runtime

- Cost of sorting edges?  $E \log E$
- Cost of cycle detection? We need to check if the two nodes joined by the edge are already connected by the in-progress MST.
  - We can use a weighted quick union to see if the two nodes are connected already! Cost:  $E \log V$  since we do  $\sim V$  unions and at worst  $\sim E$  finds (if we detect a lot of cycles)
- E > V assuming graph is connected so worst-case runtime is  $E \log E$ .

Consider edges in order of weight, smallest first.

Add edge to MST unless creates a cycle.

Repeat until V - 1 edges.

