# **VauLSMorg**

06 PT - Processes & Threads Aneka Soal Ujian Sistem Operasi A. Wibisono (AW), C. BinKadal (CB) H. Kurniawan (HK)

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#### 1. **2016-1**

```
001 /* FORK
002 * (c) 2015-2016 M. Anwar Ma'sum and Rahmat M. Samik-Ibrahim
003 * This is a free software ----- Rev. 06 - 01-Apr-2016
004 */
005
006 #include <stdio.h>
007 #include <sys/types.h>
008 #include <unistd.h>
009
010 void main(void) {
011
      pid_t pid1, pid2, pid3;
012
013
      pid1 = pid2 = pid3 = getpid();
      printf(" 2016  2015  Lainnya--\n=======\n");
014
      printf("[%4d][%4d] \n", pid1, pid2, pid3);
015
016
      fork();
017
      pid1 = getpid();
018
      wait(NULL);
019
      pid2 = getpid();
      if(!fork()) {
020
         pid2 = getpid();
021
022
          fork();
023
      }
024
      pid3 = getpid();
025
      wait(NULL);
026
      printf("[%4d][%4d]\n", pid1, pid2, pid3);
027 }
```

- (a) (KOLOM) Lingkari tahun angkatan anda berikut ini: (A) 2016 (B) 2015 (C) lainnya.
- (b) (BARIS) Lingkari sesuai angka terakhir (paling kanan) dari NPM anda: 0 1 2 3 4 5 6
- (c) Harap mengisi (KOLOM:BARIS) dengan 1000
- (d) Harap mengisi kolom dan baris lainnya sesuai dengan keluaran program di atas!

NPM		2016		2015		Lainnya	
0	[		] [		] [		]
1	[		] [		] [		]
2	[		] [		] [		]
3	[		] [		] [		]
4	[		] [		] [		]
5	[		] [		] [		]
6	[		] [		] [		]

### 2. **2016-2**

```
001 /*
002 * (c) 2016 Rahmat M. Samik-Ibrahim -- This is free software
003 * REV02 Tue Apr 11 19:09:21 WIB 2017
004 * START Sun Dec 04 00:00:00 WIB 2016
005 * wait()
                  = suspends until its child terminates.
006 * fflush()
                  = flushes the user-space buffers.
    * getppid() = get parent PID
007
    * ASSUME first pid > 2000; first ppid < 1000
800
009
    */
010
011 #include <stdio.h>
012 #include <sys/types.h>
013 #include <unistd.h>
014 #include <sys/wait.h>
015 #define NN 2
016
017 void main (void) {
       int id1000=getpid()-1000;
018
       for (int ii=1; ii<=NN; ii++) {</pre>
019
020
          fork();
021
          wait(NULL);
022
          int rPID = getpid()-id1000; // "relative"
          int rPPID=getppid()-id1000; // "relative"
023
024
          if (rPPID < 1) rPPID=999;
          printf("Loop [%d] - rPID[%d] - rPPID[%4.4d]\n", ii, rPID, rPPID);
025
026
          fflush(NULL);
       }
027
028 }
```

## Fill the following blanks (program output):

Loop [	] - rPID[	] - rPPID[	]
Loop [	] - rPID[	] - rPPID[	]
Loop [	] - rPID[	] - rPPID[	]
Loop [	] - rPID[	] - rPPID[	]
Loop [	] - rPID[	] - rPPID[	]
Loop [	] - rPID[	] - rPPID[	]

## 3. **2017-1**

```
Program Code of Processes and Threads
001 /*
                                                       019 #include <sys/wait.h>
                                                       020 #include <stdlib.h>
002 * (c) 2005-2017 Rahmat M. Samik-Ibrahim
003 * This is free software. Feel free to copy and/or
                                                       021
004 * modify and/or distribute it, provided this
                                                       022 void main(void) {
005 * notice, and the copyright notice, are preserved.
                                                              int firstPID = (int) getpid();
006 * REV02 Wed May 17 16:52:02 WIB 2017
                                                       024
                                                              int RelPID;
007 * REV00 Wed May 3 17:07:09 WIB 2017
                                                       025
* 800
                                                       026
                                                              fork();
009 * fflush(NULL): flushes all open output streams
                                                       027
                                                              wait(NULL);
                                                       028
010 * fork(): creates a new process by cloning
                                                              fork();
011 * getpid(): get PID (Process ID)
                                                       029
                                                              wait(NULL);
012 * wait(NULL): wait until the child is terminated
                                                       030
                                                              fork();
                                                       031
013 *
                                                              wait(NULL);
014 */
                                                       032
015
                                                       033
                                                              RelPID=(int)getpid()-firstPID+1000;
016 #include <stdio.h>
                                                       034
                                                              printf("RelPID: %d\n", RelPID);
017 #include <unistd.h>
                                                       035
                                                              fflush(NULL);
018 #include <sys/types.h>
                                                       036 }
```

```
        Real P I D :
```

#### 4. **2017-2**

The Program Code						
001 /* 002 * (c) 2017 Rahmat M. Samik-Ibrahim 003 * http://rahmatm.samik-ibrahim.vlsm.org/ 004 * This is free software. 005 * REV02 Mon Dec 11 17:46:01 WIB 2017 006 * START Sun Dec 3 18:00:08 WIB 2017 007 */ 008 009 #include <stdio.h> 010 #include <unistd.h> 011 #include <sys types.h=""> 012 #include <sys wait.h=""> 013 014 #define LOOP 3 015 #define OFFSET 1000</sys></sys></unistd.h></stdio.h>	<pre>017 void main(void) { 018    int basePID = getpid() - OFFSET; 019 020    for (int ii=0; ii &lt; LOOP; ii++) { 021        if(!fork()) { 022            printf("PID[%d]-PPID[%d]\n",</pre>					

Program Output (line 22 of every process):						

### 5. **2018-1**

```
01 /*
                                               053 void init(void) {
   Copyright 2018 Rahmat M. Samik-Ibrahim
                                               054
                                                       product = mmap(NULL, sizeof(int),
   You are free to SHARE (copy and
                                               055
                                                                       PROT, VISIBLE, 0, 0);
   redistribute the material in any medium
                                                       *product = 0;
                                               056
05
   or format) and to ADAPT (remix,
                                               057
                                                       ctr_prod = sem_open(SEM_COUNT1,
   transform, and build upon the material
06
                                               058
                                                                  O_CREAT, 0600, BUFSIZE);
   for any purpose, even commercially).
                                               059
                                                       ctr_cons = sem_open(SEM_COUNT2,
80
   This program is distributed in the hope
                                               060
                                                                  O_{CREAT}, 0600, 0);
   that it will be useful, but WITHOUT ANY
                                               061
                                                       mutex
                                                                = sem_open(SEM_MUTEX,
10
   WARRANTY; without even the implied
                                               062
                                                                  O_CREAT, 0600, 1);
   warranty of MERCHANTABILITY or FITNESS
                                                                = sem_open(SEM_SYNC,
                                               063
                                                       ssync
   FOR A PARTICULAR PURPOSE.
12
                                               064
                                                                  O_{CREAT}, 0600, 0);
13
                                               065 }
   * REV02 Wed May 2 11:30:19 WIB 2018
                                               066
   * START Wed Apr 18 19:50:01 WIB 2018
15
                                               067 void producer (void) {
16
   */
                                               068
                                                       sem_wait(ssync);
17
                                                       flushprintf("PRODUCER PID",getpid());
                                               069
18 // DO NOT USE THE SAME SEMAPHORE NAME!!!!
                                                070
                                                       for (int loop=0; loop<LOOP; loop++) {</pre>
19 // Replace "demo" with your own SSO name.
                                               071
                                                          sem_wait(ctr_prod);
20 #define SEM_COUNT1
                            "/count-1-demo"
                                                072
                                                          sem_wait(mutex);
21 #define SEM_COUNT2
                            "/count-2-demo"
                                               073
                                                          flushprintf("PRODUCT
22 #define SEM_MUTEX
                            "/mutex-demo"
                                                                                ++(*product));
23 #define SEM_SYNC
                            "/sync-demo"
                                               074
                                                          sem_post(mutex);
24
                                               075
                                                          sem_post(ctr_cons);
25 #include <fcntl.h>
                                               076
                                                       }
26 #include <stdio.h>
                                               077
                                                       wait(NULL);
27 #include <stdlib.h>
                                               078 }
28 #include <unistd.h>
                                               080 void consumer (void) {
29 #include <semaphore.h>
                                                       flushprintf("CONSUMER PID",getpid());
                                               081
30 #include <sys/mman.h>
                                               082
                                                       sem_post(ssync);
31 #include <sys/types.h>
                                               083
                                                       for (int loop=0; loop<LOOP; loop++) {</pre>
32 #include <sys/wait.h>
                                               084
                                                          sem_wait(ctr_cons);
33
                                                          sem_wait(mutex);
                                               085
34 // Shared Memory: R/W with no name.
                                                086
                                                          flushprintf("CONSUME ", *product);
                                  |PROT_WRITE)
35 #define PROT
                   (PROT_READ
                                                087
                                                          sem_post(mutex);
36 #define VISIBLE (MAP_ANONYMOUS|MAP_SHARED)
                                                880
                                                          sem_post(ctr_prod);
37
                                                089
                                                       }
38 #define LOOP
                                               090 }
39 #define BUFSIZE 1
                                               092 // WARNING: NO ERROR CHECK! ////////
40
                                               093 void main(void) {
41 sem_t*
          ctr_prod;
                                               094
                                                       flushprintf("STARTING PID",getpid());
42 sem_t*
          ctr_cons;
                                               095
                                                       init();
43 sem_t*
           mutex;
                                               096
                                                            (fork()) producer();
                                                       if
                                                                                   //
                                                                                       Parent
44 sem_t*
           ssync;
                                               097
                                                       else
                                                                     consumer();
                                                                                  // Child
45 int*
           product;
                                               098
                                                       sem_unlink(SEM_COUNT1);
46
                                               099
                                                       sem_unlink(SEM_COUNT2);
47 // WARNING: NO ERROR CHECK! ////////
                                                100
                                                       sem_unlink(SEM_SYNC);
48 void flushprintf(char* str, int ii) {
                                               101
                                                       sem_unlink(SEM_MUTEX);
49
      printf("%s [%d]\n", str, ii);
                                               102
                                                       flushprintf("STOP HERE PID", getpid());
      fflush(NULL);
50
                                               103 }
51 }
```

## 6. **2018-1** (continued)...

- (a) Assume the Parent PID is 1000 and the Child PID is 1001. What is the output of the program above?
- (b) Name all four (4) semaphore!
- (c) What is the purpose of line 68?
- (d) What is the purpose of line 71?

#### 7. 2018-2

```
005 // REV04 Sun Dec 16 11:15:54 WIB 2018
006 // START Wed Nov 14 20:30:05 WIB 2018
008 #include <fcntl.h>
009 #include <stdio.h>
010 #include <stdlib.h>
011 #include <string.h>
012 #include <semaphore.h>
013 #include <unistd.h>
014 #include <sys/mman.h>
015 #include <sys/types.h>
016 #include <sys/stat.h>
017 #include <sys/wait.h>
019 #define MYFLAGS
                        O_CREAT | O_RDWR
020 #define MYPROTECT PROT_READ | PROT_WRITE
021 #define MYVISIBILITY
                                   MAP_SHARED
022 #define SFILE
                              "demo-file.bin"
024 typedef
             struct {
025
       sem_t sync[3];
026
              share;
       int
027
              loop;
       int
028
      pid_t relative;
029 } myshare;
031 myshare* mymap;
033 void flushprintf(char* tag1, char* tag2){
      printf("%s[%s] loop%d relative(%d)\n",
034
035
          tag1, tag2, mymap->loop,
          getpid() + mymap->relative);
036
037
       fflush(NULL);
038 }
```

- (e) What is the purpose of line 77?
- (f) What is the purpose of line 84?
- (g) How many Critical Section(s) is/are there in the program above? Where/which lines are the Critical Section(s)?
- (h) Explain briefly the purpose of function fflush(NULL) in line 50!
- (i) What is the purpose of lines 98 101?

```
040 #define MAIN "30:ADDSUB"
041 #define ADD1 "
                     31:ADD1"
042 #define SUB1 "
                     32:SUB1"
044 void main(void) {
                =open(SFILE,MYFLAGS,S_IRWXU);
045
       int fd
046
       int ssize=sizeof(myshare);
       truncate(SFILE, ssize);
047
       mymap=mmap(NULL, ssize, MYPROTECT,
048
                  MYVISIBILITY, fd, 0);
049
050
       mymap->share
                        = 0;
051
       mymap->loop
                        = 3;
       mymap->relative = 1000 - getpid();
052
       sem_init (&(mymap->sync[0]), 1, 0);
053
054
       sem_init (&(mymap->sync[1]), 1, 0);
055
       sem_init (&(mymap->sync[2]), 1, 0);
       flushprintf(MAIN, "EXEC");
056
057
       if (!fork())
058
          execlp("./31-add1", ADD1, NULL);
059
       if (!fork())
          execlp("./32-sub1", SUB1, NULL);
060
061
       do {
          sleep(1);
062
063
          flushprintf(MAIN, "LOOP");
       } while (--mymap->loop);
064
       sem_wait (&(mymap->sync[0]));
065
066
       sem_wait (&(mymap->sync[0]));
       flushprintf(MAIN, "WAIT");
067
068
                (mymap->share > 1500)
       if
          flushprintf("SHARE +/-", "2000");
069
       else if (mymap->share > 500)
070
          flushprintf("SHARE +/-", "1000");
071
072
       else
          flushprintf("SHARE +/-", "0");
073
074
       wait(NULL);
075
       wait(NULL);
076
       flushprintf(MAIN, "EXIT");
077
       close(fd);
078 }
```

```
080 // FILE: 31-add1.c =======
                                                 105 // FILE: 32-sub1.c ======
081 // SEE ALSO: 30-add1sub1.c =======
                                                 106 // SEE ALSO: 30-add1sub1.c ======
082
                                                 107
083 void main(int argc, char* argv[]) {
                                                 108 void main(int argc, char* argv[]) {
       int fd =open(SFILE, MYFLAGS, S_IRWXU);
                                                         int fd =open(SFILE, MYFLAGS, S_IRWXU);
084
                                                 109
085
       int ssize=sizeof(myshare);
                                                         int ssize=sizeof(myshare);
                                                 110
086
       mymap=mmap(NULL, ssize, MYPROTECT,
                                                 111
                                                         mymap=mmap(NULL, ssize, MYPROTECT,
                  MYVISIBILITY, fd, 0);
                                                                    MYVISIBILITY, fd, 0);
087
                                                 112
880
       sem_post (&(mymap->sync[2]));
                                                         sem_post (&(mymap->sync[1]));
                                                 113
089
       sem_wait (&(mymap->sync[1]));
                                                 114
                                                         sem_wait (&(mymap->sync[2]));
090
       sem_wait (&(mymap->sync[1]));
091
       mymap->share=1000;
                                                 115
                                                         mymap->share=2000;
092
       flushprintf(argv[0], "PASS");
                                                         flushprintf(argv[0], "PASS");
                                                 116
                                                 117
                                                         sem_post (&(mymap->sync[1]));
093
       while (mymap->loop) {
                                                 118
                                                         while (mymap->loop) {
094
          for(int ii=0; ii<1000000; ii++);
                                                            for(int ii=0; ii<1000000; ii++);
                                                 119
095
          mymap->share++;
                                                 120
                                                            mymap->share--;
096
       }
                                                         }
                                                 121
097
       sem_post (&(mymap->sync[2]));
                                                 122
                                                         sem_post (&(mymap->sync[1]));
098
       sem_wait (&(mymap->sync[1]));
                                                 123
                                                         sem_wait (&(mymap->sync[2]));
                                                 124
                                                         sem_wait (&(mymap->sync[2]));
099
       flushprintf(argv[0], "EXIT");
                                                 125
                                                         flushprintf(argv[0], "EXIT");
100
       sem_post (&(mymap->sync[2]));
101
       sem_post (&(mymap->sync[0]));
                                                 126
                                                         sem_post (&(mymap->sync[0]));
102
       close(fd);
                                                 127
                                                         close(fd);
103 }
                                                 128 }
```

- (a) What is the purpose of line 37?
- (b) Write the output of running program "30-add1sub1" (fill the blanks):

```
] loop
relative(
                                )
)
       ] loop
                relative(
] loop
                relative(
                                )
relative(
                                )
       ] loop
Γ
                                )
       ] loop
                relative(
] loop
                relative(
                                )
] loop
                relative(
                                )
] loop
                                )
                relative(
Γ
       ] loop
                                )
                relative(
)
       ] loop
                relative(
Γ
       ] loop
                relative(
                                )
```

### 8. 2019-1 (83.3%)

```
057 #define NDRIVERS SIZEofD/SIZEofD0
001 // (c) 2019 This is Free Software R03
                                                 058 typedef struct {
002 // Rahmat M. Samik-Ibrahim 20190508-0906
                                                 059
                                                       sem_t
                                                                mutex;
004 // WARNING: NO ERROR CHECK! ////////
                                                 060
                                                       sem_t
                                                                 turns[TURNS];
005 // exit(STATUS)
                       == exit with STATUS
                                                 061
                                                       pid_t
                                                                relPID;
006 // memcpy(*d,*s,n) == copy n from s to d
                                                 062
                                                       volatile int rTime;
007 // mmap()
               == creates a new memory map
                                                 063
                                                       drivers D[NDRIVERS];
008 // usleep(DELAY1MS)== sleep 1 MS
                                                 064 } shareMem;
010 #define TURNS
                     15
                                                 065 #define MSIZE (int) sizeof(shareMem)
011 #define LAP
                     25
                                                 066 #define MAXSEM
                                                                       2
012 #define DELAY1MS 901
                                                 067 #define MUTEX
                                                                       1
013 #define DELAY
                     DELAY1MS*20
                                                 068 #define PROTECT PROT_READ | PROT_WRITE
016 typedef struct {
                                                 069 #define VISIBLE MAP_SHARED|MAP_ANONYMOUS
017
       char motoGP[35];
                                                 071 shareMem* mymap;
018
       int countLap;
                                                 072 // ========
019 } drivers;
                                                 073 void init(void) {
020 drivers D[]={
                                                 074
                                                        printf("[1000] INIT: %d %d %d %d\n",
                            - Honda ", 0}
021
        {"(93) M Marquez
                                                 075
                                                           SIZEofD, SIZEofDO, NDRIVERS, MSIZE);
022
       ,{"(42) A Rins
                            - Suzuki ", 0}
                                                        mymap=mmap(NULL, MSIZE, PROTECT,
                                                 076
023
       ,{"(04) A Dovizioso
                            - Ducati ", 0}
                                                 077
                                                                    VISIBLE, 0, 0);
                            - Yamaha ", 0}
024
       ,{"(46) V Rossi
                                                 078
                                                        for (int ii=0; ii<TURNS; ii++) {
                            - Ducati ", 0}
025
       ,{"(09) D Petrucci
                                                 079
                                                            sem_init (&(mymap->turns[ii]),
026
       ,{"(12) M Vinales
                            - Yamaha ", 0}
                                                 080
                                                                      1, MAXSEM);
027
       ,{"(43) J Miller
                            - Ducati ", 0}
                                                 081
                                                        }
028
       ,{"(30) T Nakagami
                            - Honda ", 0}
                                                 082
                                                        sem_init (&(mymap->mutex),1,MUTEX);
029
       ,{"(35) C Crutchlow - Honda ", 0}
                                                 083
                                                        mymap->rTime=0;
030
       ,{"(21) F Morbidelli - Yamaha ", 0}
                                                        mymap->relPID=getpid() - 1000;
                                                 084
031
       ,{"(44) P Espargaro
                            - KTM
                                      ", 0}
                                                        memcpy(mymap->D, D, sizeof(D));
                                                 085
       ,{"(41) A Espargaro
                            - Aprilia", 0}
032
                                                        printf("[1000] INIT: END\n");
                                                 086
033
       ,{"(21) F Quartararo - Yamaha ", 0}
                                                 087 }
       ,{"(99) J Lorenzo
034
                            - Honda ", 0}
                                                 088 // =========
035
       ,{"(63) F Bagnaia
                            - Ducati ", 0}
                                                 089 void motoGP(int number) {
036
       ,{"(36) J Mir
                            - Suzuki ", 0}
                                                 090
                                                        pid_t relPID=getpid()-mymap->relPID;
                                      ", 0}
037
       ,{"(88) M Oliveira
                            - KTM
                                                        while(mymap->D[number].countLap<LAP){
                                                 091
       ,{"(05) J Zarco
038
                            - KTM
                                      ", 0}
                                                           for (int ii=0; ii<TURNS; ii++) {</pre>
                                                 092
039
                            - Honda ", 0}
       ,{"(06) S Bradl
                                                 093
                                                               usleep(DELAY);
040
       ,{"(29) A Iannone
                            - Aprilia", 0}
                                                 094
                                                               sem_wait (&(mymap->turns[ii]));
041
       ,{"(53) T Rabat
                            - Ducati ", 0}
                                                 095
                                                               sem_post (&(mymap->turns[ii]));
042
       ,{"(17) K Abraham
                            - Ducati ", 0}
                                                 096
                                                           }
                                      ", 0}
043
       ,{"(55) H Syahrin
                            - KTM
                                                 097
                                                           mymap->rTime++;
044
       ,{"(38) B Smith
                            - Aprilia", 0}
                                                 098
                                                           mymap->D[number].countLap++;
045 };
                                                        }
                                                 099
047 #include <semaphore.h>
                                                        sem_wait (&(mymap->mutex));
                                                 100
048 #include <stdio.h>
                                                        printf("[%d] %s Lap %2d rTime %3d\n",
                                                 101
049 #include <stdlib.h>
                                                           relPID, mymap->D[number].motoGP,
                                                 102
050 #include <string.h>
                                                 103
                                                           mymap->D[number].countLap,
051 #include <sys/mman.h>
                                                           mymap->rTime++);
                                                 104
052 #include <sys/types.h>
                                                 105
                                                        fflush(NULL);
053 #include <sys/wait.h>
                                                 106
                                                        sem_post (&(mymap->mutex));
054 #include <unistd.h>
                                                 107
                                                        exit (0);
055 #define SIZEofD (int) sizeof(D)
                                                 108 } // (continued to the next page !!) //
056 #define SIZEofDO (int) sizeof(D[0])
```

```
110 void main(void) {
111
      init();
      printf("[1000] motoGP:START\n");
112
      for (int ii=0; ii<NDRIVERS; ii++) {</pre>
113
114
         if(!fork()) motoGP(ii);
115
         usleep(DELAY1MS);
116
      }
      printf("[1000] motoGP:RACING\n");
117
      for (int ii=0; ii<NDRIVERS; ii++)</pre>
118
119
         wait(NULL);
120
      printf("[1000] motoGP:FINISH\n");
121
      exit (0);
122 }
(a) (Line 055) (90%) SIZEofD = \_
(b) (Line 056) (89%) SIZEofD0 = \_
```

- (c) (Line 057) (91%) NDRIVERS = \_\_\_\_\_
- (d) (Line 065) (88%) MSIZE = \_\_\_\_\_
- (e) What is the relative PID of the rider "(41) A Espargaro" (94%)?
- (f) Explain why the rider "(93) M Marquez" has the best chance to win! (86%)
- (g) Why is (Line 120) only executed by one process (i.e. rPID 1000) (54%)?

```
Program Output:
```

```
[1000] INIT: 960 40 24 1480
[1000] INIT: END
[1000] motoGP:START
[1000] motoGP:RACING
[1004] (46) V Rossi
                        - Yamaha Lap 25 rTime 575
[1002] (42) A Rins
                        - Suzuki Lap 25 rTime 577
[1001] (93) M Marquez
                        - Honda
                                  Lap 25 rTime 579
[1003] (04) A Dovizioso - Ducati Lap 25 rTime 581
[1006] (12) M Vinales
                        - Yamaha Lap 25 rTime 583
[1007] (43) J Miller
                        - Ducati Lap 25 rTime 586
[1005] (09) D Petrucci
                        - Ducati Lap 25 rTime 587
[1011] (44) P Espargaro - KTM
                                  Lap 25 rTime 589
[1009] (35) C Crutchlow - Honda
                                  Lap 25 rTime 593
[1010] (21) F Morbidelli - Yamaha Lap 25 rTime 594
[1008] (30) T Nakagami
                        - Honda
                                  Lap 25 rTime 595
[1015] (63) F Bagnaia
                        - Ducati Lap 25 rTime 597
[1013] (21) F Quartararo - Yamaha Lap 25 rTime 601
[1012] (41) A Espargaro - Aprilia Lap 25 rTime 602
[1014] (99) J Lorenzo
                        - Honda
                                  Lap 25 rTime 603
                        - KTM
                                  Lap 25 rTime 605
[1018] (05) J Zarco
[1017] (88) M Oliveira
                        - KTM
                                  Lap 25 rTime 607
[1016] (36) J Mir
                        - Suzuki Lap 25 rTime 609
                        - Honda
                                  Lap 25 rTime 612
[1019] (06) S Bradl
[1020] (29) A Iannone
                        - Aprilia Lap 25 rTime 613
[1023] (55) H Syahrin
                        - KTM
                                  Lap 25 rTime 615
                        - Ducati Lap 25 rTime 617
[1022] (17) K Abraham
[1021] (53) T Rabat
                        - Ducati Lap 25 rTime 619
                        - Aprilia Lap 25 rTime 621
[1024] (38) B Smith
[1000] motoGP:FINISH
```

#### 9. **2019-2**

```
001 // (c) 2019 This is Free Software R01
002 // Rahmat M. Samik-Ibrahim 20191209-1628
003 // R01 1215 1505
005 // File Name: 55-192a.c
006 // To run: ./55-192a
007
008 #include <fcntl.h>
009 #include <stdio.h>
010 #include <stdlib.h>
011 #include <string.h>
012 #include <semaphore.h>
013 #include <unistd.h>
014 #include <sys/mman.h>
015 #include <sys/types.h>
016 #include <sys/stat.h>
017 #include <sys/wait.h>
```

```
019 #define MYFLAGS
                        O_CREAT | O_RDWR
020 #define MYPROTECT PROT_READ | PROT_WRITE
021 #define MYVISIBILITY
                                  MAP_SHARED
022 #define SFILE
                              "demo-file.bin"
023
024 typedef struct {
025
       sem_t sync1;
026
       sem_t sync2;
027
       pid_t relative;
028 } myshare;
029
030 myshare* mymap;
031
032 void flushprintf(char* tag){
       printf("PIDr[%d] %s\n",
033
034
          getpid() + mymap->relative, tag);
035
       fflush(NULL);
036 }
```

```
038 void main(void) {
                                                  059 void main(int argc, char* argv[]) {
039
       int fd
                =open(SFILE,MYFLAGS,S_IRWXU);
                                                         int fd
                                                                  =open(SFILE,MYFLAGS,S_IRWXU);
                                                  060
040
       int ssize=sizeof(myshare);
                                                  061
                                                         int ssize=sizeof(myshare);
       truncate(SFILE, ssize);
041
                                                  062
                                                         mymap=mmap(NULL, ssize, MYPROTECT,
042
      mymap=mmap(NULL, ssize, MYPROTECT,
                                                                    MYVISIBILITY, fd, 0);
                                                  063
043
                  MYVISIBILITY, fd, 0);
                                                  064
                                                         flushprintf("START");
044
      mymap->relative = 1000 - getpid();
                                                  065
                                                         if(argc == 1) {
045
       sem_init (&(mymap->sync1), 1, 0);
                                                  066
                                                            if (!fork()) {
046
       sem_init (&(mymap->sync2), 1, 0);
                                                  067
                                                               sem_post (&(mymap->sync1));
047
       flushprintf("START");
                                                  068
                                                               sem_wait (&(mymap->sync2));
048
       if (!fork())
                                                  069
                                                               flushprintf("FORK CHILD");
049
         execlp("./56-192b","./56-192b",NULL);
                                                  070
                                                            } else {
050
       wait(NULL);
                                                  071
                                                               sem_wait (&(mymap->sync1));
051
       flushprintf("EXIT");
                                                  072
                                                               flushprintf("FORK PARENT");
052 }
                                                  073
                                                               sem_post (&(mymap->sync2));
053
                                                            }
                                                  074
054 // File Name: 56-192b.c
                                                            execlp(argv[0],argv[0],"XYZZY",NULL);
                                                  075
055 // To run: ./56-192b
                                                  076
056 // [line 1-37] see file 55-192a.c
                                                  077
                                                         wait(NULL);
                                                  078
                                                         flushprintf("EXIT");
                                                  079 }
```

OUTPUT of program "55-192a" (47.9%):