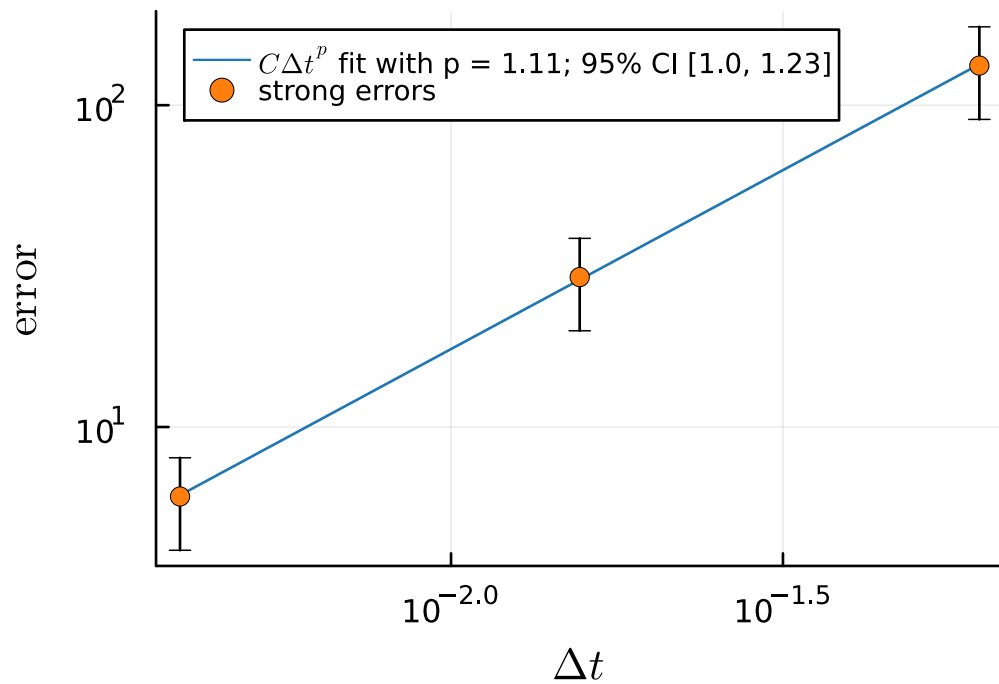
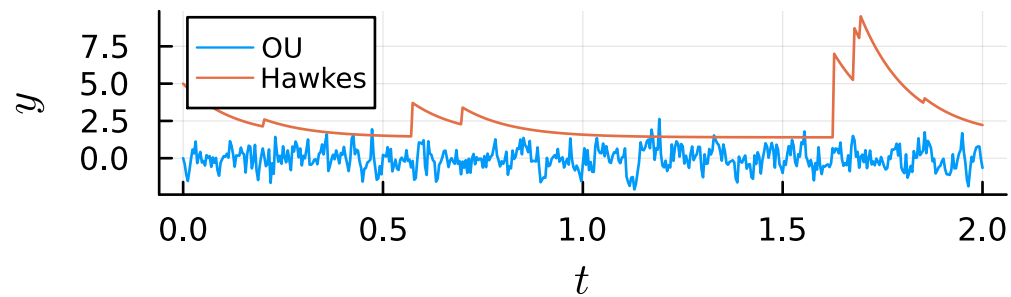


(a) Fisher-KPP model



(b) noise parts



(c) noise sample path

