

# Rémy Leroy

Computer Vision Researcher

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## Research Interests

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Signal  
Processing

Computer  
Vision

Machine Learning

Computational  
Imaging

Co-Design

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## Education

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**Ph.D. in Signal and Images Processing** - 11/2019 - 03/2023

*Université Paris-Saclay, France*

Thesis: *Deep Learning methods for monocular 3D vision systems*

Development of a **deep learning** algorithm using **optimal transport** for **monocular 3D point cloud estimation** on outdoor scenes.

Development of a lightweight neural network model for **Depth from Defocus** using soft-assignment encoding.

Simulations for **co-design** of an **unconventional optical system** and image processing neural networks for **monocular depth estimation** and **extended depth of field**.

**Master of Engineering & MSc in Signal, Image, Systems and Automation** - 09/2015 - 09/2019

*IMT Atlantique, France - GPA 3.7*

Applied Mathematics, Machine learning, Signal Processing

Electronics, Computer Science

Introductory courses to research

**Exchange semester** - 03/2017 - 06/2017

*Seoul National University, South Korea*

Statistics, Machine Learning, Linear Algebra, CPU and computer architecture

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## Publications

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### Journal Articles

*Learning local depth regression from defocus blur by soft-assignment encoding.*

R. Leroy, P. Trouvé-Peloux, B. Le Saux, B. Buat et F. Champagnat.

Applied Optics, vol.61, n°29, p.8843--8849. **2022**

## Conference Articles

*Multitask deep co-design for extended depth of field and depth from defocus.*

M. Dufraisie, R. Leroy, P. Trouvé-Peloux, F. Champagnat, J.-B. Volatier.

SPIE. Apr **2024**

*Régression locale de la profondeur grâce au flou de défocalisation et à un réseau de neurones entraîné par soft-assignment.*

R. Leroy, P. Trouvé-Peloux, B. Le Saux, B. Buat et F. Champagnat.

GRETSI #28. Sep **2022**

*Pix2Point: Learning Outdoor 3D Using Sparse Point Clouds and Optimal Transport.*

R. Leroy, P. Trouvé-Peloux, F. Champagnat, B. Le Saux et M. Carvlho.

Int. Conf. on Machine Vision and Applications (MVA), Oct **2021**

*Pix2Point: prédiction monoculaire de scènes 3D par réseaux de neurones hybrides et transport optimal.*

R. Leroy, B. Le Saux, M. Pinheiro Carvalho, P. Trouvé-Peloux et F. Champagnat.

RFIAP, Oct **2020**

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## Work Experience

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### Postdoctoral Researcher - 05/2023 – Present

Development of a coordinate-based algorithm using Multiplicative Filter Networks for signal compression, applied to conventional and lightfield images

Investigating methods for generalizing Implicit Neural Representation to multiple signals

### Internship ONERA - 03/2019 – 09/2019

Deep neural networks for Monocular Depth Estimation using 3D Point cloud modality

### Internship CEA - 09/2017 – 03/2018

Iterative regularization of the Kaiser-Squires transformation for dark matter mass mapping

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## Certificates

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Principles of Data Networks - Mines-Telecom Institute (2015)

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## General Skills

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Machine Learning

Object Oriented Programming

Photography

Window/Gnu Linux

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## Languages

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**French**  
Native

**English**  
Fluent

**Korean**  
Novice

**Japanese**  
Novice

**German**  
Intermediate