# **Exercise cpc-08: Example 5: Configuration of track indicators**

#### **Exercise-08b: Configuration of track indicators**

This exercise is an alternative to 08a!
You need not implement both, but only one ...

Model the track indication problem from **example** 5 in cpc-examples.pdf in MiniZinc.

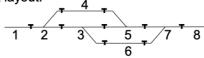
Required result: PDF file named surname(s)-08b.pdf containing the contents of following files

- · tracks.mzn: generic program
- \*.dzn: various examples

Be prepared to run your MiniZinc program during your presentation!

Based on a (much more complicated) example from the railroad domain:

· Example track layout:



- T-separators divide tracks into sections (e.g. 1-8)
- · Each section is monitored by a track indicator
- Each track indicator has a type (A, B, C, D)
- Neighboring indicators are subject to restrictions:
  - · A allows only B as neighbors
  - · B allows only A or C as neighbors
  - · C allows only B or D as neighbors
  - · D allows only C as neighbors

#### Additional questions for discussion in the lesson:

· Differences of solving times for different layouts

#### Tasks

- Model specific for the example track layout, e.g. single mzn file with variables, domains, constraints, test with all solutions
- Generic model for arbitrary track layouts,
   e.g. array of variables for sections in an mzn file,
   table for neighborship in a dzn file (for each layout)
- Test with various layouts and compare solving times e.g. duplicate example layout (and optionally connect the two)
- Define an unsatisfiable layout
- Implement optimization alternatives:
  - Minimize cost: A=1, B=2, C=3, D=4
  - Ensure equal distribution: All 4 types shall be selected as equally as possible
  - Pareto front of both alternatives (criteria)

#### Generic model (tracks.mzn):

```
enum Type = {A, B, C, D};
array[Type,Type] of 0..1: allows = [|
% A, B, C, D
0, 1, 0, 0 | % A
1, 0, 1, 0 | % B
0, 1, 0, 1 | % C
0, 0, 1, 0 % D
|];
int: NrSections;
set of int: Sections = 1..NrSections;
array[Sections,Sections] of 0..1: neighborship;
array[Sections] of var Type: indicators;
constraint forall (i, j in Sections where i<j)
    (neighborship[i, j]==1 -> allows[indicators[i],indicators[j]] == 1);
solve satisfy;
```

## Original Example (8 sections):

```
NrSections = 8;
% only upper half is used because of i<j constraint
neighborship = [|
% 1, 2, 3, 4, 5, 6, 7, 8
    0, 1, 0, 0, 0, 0, 0, 0 | %1
    0, 0, 1, 1, 0, 0, 0, 0 | %2
    0, 0, 0, 1, 1, 0, 0 | %3
    0, 0, 0, 0, 1, 0, 0, 0 | %4
    0, 0, 0, 0, 0, 1, 0 | %5
    0, 0, 0, 0, 0, 1, 0 | %5
    0, 0, 0, 0, 0, 0, 1, 0 | %6
    0, 0, 0, 0, 0, 0, 0, 1 | %7
    0, 0, 0, 0, 0, 0, 0, 0 %8
]];</pre>
```

## **Output Sample:**

```
Running tracks.mzn, sample8_1.dzn
indicators = [A, B, A, A, B, B, A, B];
% time elapsed: 169msec
-----
%%mzn-stat: failures=0
%%mzn-stat: initTime=0.00036
%%mzn-stat: nodes=5
%%mzn-stat: peakDepth=4
%%mzn-stat: propagations=40
%%mzn-stat: propagators=9
%%mzn-stat: restarts=0
%%mzn-stat: solutions=1
%%mzn-stat: solveTime=9.3e-05
%%mzn-stat: variables=8
%%mzn-stat-end
Finished in 169msec.
```

169msec

#### Unsatisfiable Example:

```
NrSections = 8;
% only upper half is used because of i<j constraint
neighborship = [|
% 1, 2, 3, 4, 5, 6, 7, 8
    0, 1, 0, 0, 0, 0, 0, 0 | %1
    0, 0, 1, 1, 0, 0, 0, 1 | %2
    0, 0, 0, 0, 1, 1, 0, 0 | %3
    0, 0, 0, 0, 1, 0, 0, 0 | %4
    0, 0, 0, 0, 0, 1, 0 | %5
    0, 0, 0, 0, 0, 0, 1, 0 | %6
    0, 0, 0, 0, 0, 0, 0, 1 | %7
    0, 0, 0, 0, 0, 0, 0, 0 %8
];</pre>
```

## **Output Sample:**

Running tracks.mzn, sample8\_1\_unsatisfiable.dzn

190msec

```
=====UNSATISFIABLE=====
%%mzn-stat: failures=4
%%mzn-stat: initTime=0.000384
%%mzn-stat: nodes=7
%%mzn-stat: propagations=124
%%mzn-stat: propagations=124
%%mzn-stat: restarts=0
%%mzn-stat: restarts=0
%%mzn-stat: solutions=0
%%mzn-stat: solveTime=0.000129
%%mzn-stat: variables=8
%%mzn-stat-end
Finished in 190msec.
```

#### Double-sized Example:

NrSections = 16;

```
% only upper half is used because of i<j constraint
neighborship = [|
% 1, 2, 3, 4, 5, 6, 7, 8, 9, 10 11 12 13 14 15 16
 0, 1, 0, 0, 0, 0, 0, 0, 1, 0, 0, 0, 0, 0, 0 | \%1
 0, 0, 1, 1, 0, 0, 0, 0, 0, 0, 1, 1, 0, 0, 0, 0 | %2
0, 0, 0, 0, 1, 1, 0, 0, 0, 0, 0, 0, 1, 1, 0, 0 | %3
 0, 0, 0, 0, 1, 0, 0, 0, 0, 0, 0, 0, 1, 0, 0, 0
 0, 0, 0, 0, 0, 0, 1, 0, 0, 0, 0, 0, 0, 0, 1, 0
0, 0, 0, 0, 0, 0, 1, 0, 0, 0, 0, 0, 0, 0, 1, 0
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 0, 0, 0, 0, 0, 0, 0, 1, 0, 0, 0, 0, 0, 0, 0, 1
                                   %7
 0, 0, 0, 0, 0, 0, 0, 1, 0, 0, 0, 0, 0, 0
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 %12
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```

#### **Output Sample:**

11:

193msec

#### Larger Example (32 sections):

```
NrSections = 32;
```

```
% only upper half is used because of i<j constraint
neighborship = [|
 1, 2, 3, 4,
                   7, 8, 9, 10 11 12 13 14 15 16 17 18 19 20 21 22 23 24 25 26 27 28 29 30 31 32
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|];
```

#### **Output Sample:**

```
Running tracks.mzn, sample8_1_16t copy.dzn
                                                                           197msec
B, B, A, B];
% time elapsed: 166msec
%%mzn-stat: failures=0
%%mzn-stat: initTime=0.00052
%%%mzn-stat: nodes=16
%%mzn-stat: peakDepth=15
%%mzn-stat: propagations=179
%%mzn-stat: propagators=39
%%mzn-stat: restarts=0
%%mzn-stat: solutions=1
%%mzn-stat: solveTime=0.000133
%%mzn-stat: variables=32
%%mzn-stat-end
Finished in 197msec.
```

#### Solver Performance Comparison:

Size	Average solveTime	Avg. overall time
8	0.000093	169ms
16	0.000130	161ms
32	0.000133	166ms