Physical Applications: Computing Mass, electric charge, Center of mass, inertia

fare = Area(R) Sf(x,y) dA Already Seen: Average value of a function

Consider a thin plate (called a lamina) with variable density occupying a region D in the xy-plane:

- · Goals: Given a density function P(x,y) for a Lamina find:
 - 1 total mass of lamina
 - 2 Moments of the Camina
 - 3 Center of mass
 - 1 Moments of Irertia
- · Total mass of lumina: Sum masses over DA

In general density = mass but for thin plate clensity = mass

 $\Delta M = \int (x,y) \Delta A$

m= Sipexity dA

Moments of Lumina: product of mass and its directed distance from an axis. (measures the tendency for the plate to rotate about the ax

About x-axis: Amx = Am.y = y. gary AA

Mx = Syp(x,y)dA Tendency to rotate
about x-axis

Tendency to cotate About y-axis: Lmy = Am-x = X·f(x,y) DA

My = Mx f(x,y)dA / wont y-axis

Center of mass: point where plate balances hir: tontally

* Point may not be an plate Ex. A , Horse shoe Point (x,j) such that mx=My, my=Mx

 $\overline{X} = \frac{M_y}{M} = \frac{1}{m} \iint \times \mathcal{S}(x,y) dA \left[\overline{y} = \frac{M_x}{m} = \frac{1}{m} \right] \left[y \mathcal{S}(x,y) dA \right]$

A See movents demo on website / Paper plate demo

· Moments of Inertia:

* Muss determines force needed for an acceleration

A So Inertia determines torque needed for an angular acceleration

About x-axis: DIx = Dm.y2 = y2 p(x,y) AA

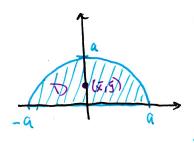
About y-axis: DIy = Am·x2 = x2 p(x,y) AA

About origin: $\Delta I_o = \Delta m (x^2 + y^2) \frac{x^2 f(x, y) dA}{g(x^2 + y^2) f(x, y) \Delta A}$

$$I_0 = \iint_D (x^2 + y^2) f(x, y) dA$$

Example

The Density at any point on a semicircular lamina is proportional to the distance from the center of the circle. Find the center of mass.



$$D = \{(r, \theta) \mid 0 \le r \le \alpha, 0 \le \theta \le \pi\} \quad f(x, y) = K \sqrt{x^2 + y^2}, K \text{ Constant of } propertionality}$$

$$M = \iint r dA = \int_0^{\pi} \int_0^{x} kr^2 dr d\theta = \frac{k\pi a^3}{3}$$

$$y = \frac{3}{k\pi a^3} \int_0^{\pi} \int_0^{\alpha} k_r^2 (r\sin \theta) dr d\theta = \frac{3}{k\pi a^3} (\frac{ka^4}{4})^{(2)} = \frac{3a}{2\pi}$$

Center of mass:
$$(\bar{x},\bar{g}) = (0,\frac{3a}{2\pi})$$

[Example] find the moment of inertia Io of a homogeneous D with density of center (0,0) and radius a. Use Io to determine Ix, Iy,

$$T_0 = \int_0^{2\pi} \int_0^a r^2 \rho \, r dr d\theta = 2\pi \rho \frac{a^4}{4}$$

$$I_{x} = I_{y} = \pi \beta \frac{qq}{q}$$

Section 15.5 - Applications of Double Integrals

MVC

- · Extra Examples
- # 11. A lumina occupies the first quadrant of x2+y2=1. Find its center of mass if the densits at any point is proportional to its distance from the x-axis.

$$D = \{(r,\theta) \mid 0 \le \theta = \sqrt{r}/2, \quad 0 \le r \le 1\} \quad f(x,y) = ky \quad f(r,\theta) = kr \le 10\theta$$

$$M = \int_{0}^{\sqrt{r}/2} \int_{0}^{1} kr^{2} \sin \theta \, dr \, d\theta = \frac{k}{3}$$

$$\bar{x} = \frac{3}{K} \int_{0}^{\sqrt{r}/2} \int_{0}^{1} r \cos \theta \cdot kr \sin \theta \cdot r \, dr \, d\theta = \frac{3}{K} \frac{K}{4} \frac{1}{2} = \frac{3}{8}$$

$$\bar{y} = \frac{3}{K} \int_{0}^{\sqrt{r}/2} \int_{0}^{1} r \cos \theta \cdot kr \sin \theta \cdot r \, dr \, d\theta = \frac{3}{4K} \int_{0}^{\sqrt{r}/2} 1 - \frac{\cos(2\theta)}{2} \, d\theta$$

$$= \frac{3}{8} \left(\theta - \sin(2\theta)\right) \Big|_{0}^{\sqrt{r}/2} = \frac{3\pi}{16}$$

$$\left(\bar{x}, \bar{y}\right) = \left(\frac{3}{8}, \frac{3\pi}{16}\right)$$

#12. Lamina from #11 but the density at any point is proportional to the Square of its distance from the origin.

$$\int (x_1 y) = (x^2 + y^2) K \int (r_1 \theta) = (r^3) K$$

$$M = \int_0^{17/2} \int_0^1 K r^3 dr d\theta = \frac{K}{4}$$

$$\bar{X} = \frac{4}{K} \int_0^{17/2} \int_0^1 r \omega s \theta \cdot K r^3 dr d\theta = \frac{4}{5}$$

$$\bar{Y} = \frac{4}{K} \int_0^{17/2} \int_0^1 r \sin \theta \cdot K r^3 dr d\theta = \frac{4}{5}$$

$$(\bar{x}_1 \bar{y}) = (\frac{4}{5}, \frac{4}{5})$$

\$ 18. Find To, Ix, Iy for the Lamina in #12.

$$\begin{split} I_{x} &= \int_{0}^{\pi/2} \int_{0}^{1} r^{2} \cos^{2}\theta \, r^{2} \cdot k \cdot r \, dr \, d\theta = \frac{K}{6} \int_{0}^{\pi/2} \left(1 + \frac{\cos(2\theta)}{2} \right) \, d\theta \\ &= \frac{K}{6} \cdot \frac{1}{2} \left(\theta + \frac{\sin(2\theta)}{2} \right) \Big|_{0}^{\pi/2} = \frac{K}{24} \\ I_{y} &= \int_{0}^{\pi/2} \int_{0}^{1} r^{2} \sin^{2}\theta \, r^{2} \cdot k r \, dr \, d\theta = \frac{K}{6} \int_{0}^{\pi/2} \left(1 - \frac{\cos(2\theta)}{2} \right) = \frac{K}{24} \\ I_{0} &= I_{x} + I_{y} = \frac{K}{12} \end{split}$$