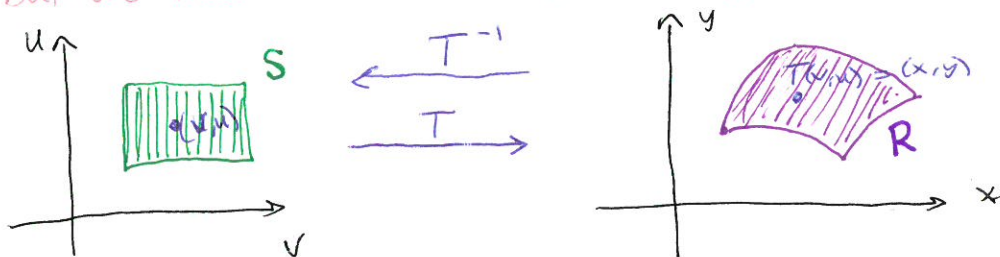


Section 15.10 - Change of variables

Vector Calc

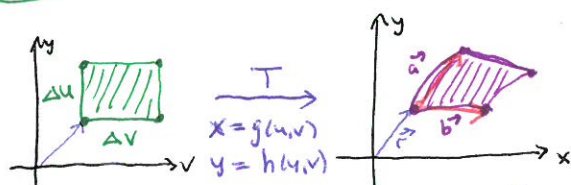
★ Can be useful to create your own coordinate system
But we need an easier way to change between the two.



$$x = g(u,v) \quad u = k(x,y) \\ y = h(u,v) \quad v = l(x,y)$$

- T is called a Transformation :
- point (u,v) maps to (x,y) , (x,y) is the image of (u,v)
- If no two points have the same image then T is One-to-One
- If T is One-to-One then T has an inverse T^{-1}

How This affects a double Integral :



Goal approx. area of purple shape with parallelogram

$$\vec{r}(u,v) = g(u,v)\vec{i} + h(u,v)\vec{j} \\ |\vec{a} \times \vec{b}| = |\vec{r}_u \Delta u \times \vec{r}_v \Delta v| = |\vec{r}_u \times \vec{r}_v| \Delta u \Delta v \quad |\vec{r}_u \times \vec{r}_v| = \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ \frac{\partial x}{\partial u} & \frac{\partial y}{\partial u} & 0 \\ \frac{\partial x}{\partial v} & \frac{\partial y}{\partial v} & 0 \end{vmatrix} = \begin{vmatrix} \frac{\partial x}{\partial u} & \frac{\partial y}{\partial u} \\ \frac{\partial x}{\partial v} & \frac{\partial y}{\partial v} \end{vmatrix} k$$

The Jacobian of the transformation T given by $x = g(u,v)$ and $y = h(u,v)$ is

$$\frac{\partial(x,y)}{\partial(u,v)} = \begin{vmatrix} \frac{\partial x}{\partial u} & \frac{\partial y}{\partial u} \\ \frac{\partial x}{\partial v} & \frac{\partial y}{\partial v} \end{vmatrix} = \frac{\partial x}{\partial u} \frac{\partial y}{\partial v} - \frac{\partial x}{\partial v} \frac{\partial y}{\partial u} \quad dA = \left| \frac{\partial(x,y)}{\partial(u,v)} \right| du dv$$

Change of variables : T a transformation with continuous first-order partials, whose Jacobian is non-zero, who maps region $S(u,v)$ onto a region $R(x,y)$. f continuous on R and T one-to-one, except on the boundary of S then

$$\iint_R f(x,y) dA = \iint_S f(x(u,v), y(u,v)) \left| \frac{\partial(x,y)}{\partial(u,v)} \right| du dv$$

Polar: $x = r \cos \theta$ $y = r \sin \theta$ $\frac{\partial(x,y)}{\partial(r,\theta)} = \begin{vmatrix} \cos \theta & -r \sin \theta \\ \sin \theta & r \cos \theta \end{vmatrix} = r \cos^2 \theta + r \sin^2 \theta = r > 0$

So $\iint_R f(x,y) dA = \iint_S f(r \cos \theta, r \sin \theta) r dr d\theta$

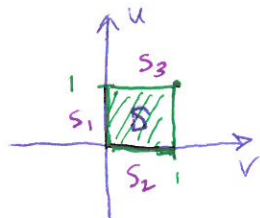
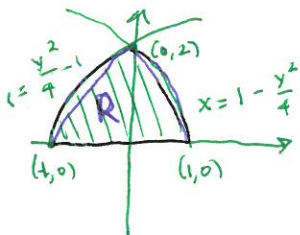
Section 15.10 - Change of Variables

Vector Calc

Ex 2 Use the change of variables $x = u^2 - v^2$, $y = 2uv$ to evaluate

$\iint_R y \, dA$ where R is bounded by the x -axis, and parabolas $y^2 = 4 - 4x$

and $y^2 = 4 + 4x$, $y \geq 0$.



$$y = 0 \Rightarrow u \text{ or } v = 0$$

$$-1 \leq x \leq 0 \Rightarrow u = 0 \quad S_1$$

$$0 \leq x \leq 1 \Rightarrow v = 0 \quad S_2$$

$$y^2 = 4 - 4x \quad 0 \leq x \leq 1 \Rightarrow 4u^2v^2 = 4 - 4u^2 + 4v^2$$

$$y^2 = 4 + 4x \quad -1 \leq x \leq 0 \Rightarrow 4u^2(v^2 + 1) = 4(v^2 + 1)$$

$$\Rightarrow 4u^2v^2 = 4 + 4u^2 - 4v^2 \quad u^2 = 1 \quad S_3$$

$$4v^2(u^2 + 1) = 4(u^2 + 1)$$

$$v^2 = 1 \quad S_4$$

$$\left| \frac{\partial(x,y)}{\partial(u,v)} \right| = \begin{vmatrix} 2u & 2v \\ -2v & 2u \end{vmatrix} = 4u^2 + 4v^2 > 0$$

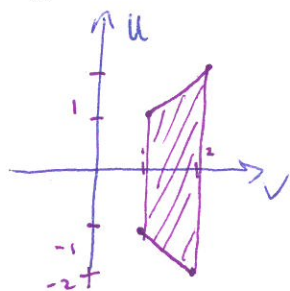
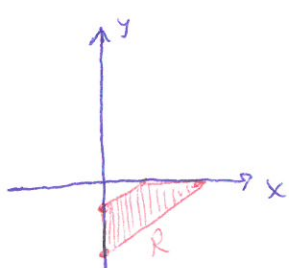
$$\iint_R y \, dA = \int_0^1 \int_0^1 2uv \left| \frac{\partial(x,y)}{\partial(u,v)} \right| du dv$$

$$= \int_0^1 \int_0^1 2uv(4u^2 + 4v^2) du dv$$

$$= 8 \int_0^1 \left[\frac{u^4}{4} v + \frac{u^2}{2} v^3 \right]_0^1 dv$$

$$= 8 \int_0^1 \left[\frac{1}{4} v + \frac{1}{2} v^3 \right] dv = 8 \left[\frac{1}{8} v^2 + \frac{1}{8} v^4 \right]_0^1 = \boxed{2}$$

Ex 3 Evaluate $\iint_R e^{\frac{x+y}{x-y}} \, dA$ where R is the trapezoid region with vertices $(0, -1)$, $(0, -2)$, $(2, 0)$, $(1, 0)$



$u = x + y$ $v = x - y$ Since $e^{\frac{u}{v}}$ easy to integrate

$$x = \frac{1}{2}(u+v) \quad y = \frac{1}{2}(u-v)$$

$$x = 0 \quad -2 \leq y \leq -1 \Rightarrow u = -v$$

$$y = 0 \quad 1 \leq x \leq 2 \Rightarrow u = v$$

$$y = x - 1 \quad 0 \leq x \leq 1 \Rightarrow v = 1$$

$$y = x - 2 \quad 0 \leq x \leq 2 \Rightarrow v = 2$$

$$\iint_R e^{\frac{x+y}{x-y}} \, dA = \iint_S e^{\frac{u}{v}} \left| \frac{\partial(x,y)}{\partial(u,v)} \right| du dv$$

$$\left| \frac{\partial(x,y)}{\partial(u,v)} \right| = \left| \begin{vmatrix} \frac{1}{2} & \frac{1}{2} \\ \frac{1}{2} & -\frac{1}{2} \end{vmatrix} \right| = \frac{1}{2}$$

$$= \frac{1}{2} \int_1^2 \int_{-v}^v e^{\frac{u}{v}} du dv = \frac{1}{2} \int_1^2 (e^{\frac{v}{v}} - e^{-\frac{v}{v}}) dv = \frac{1}{2} (e^1 - e^{-1}) \left(\frac{2-1}{2} \right) = \frac{3}{4} (e - e^{-1})$$

2