# **Embedded Rust**

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Rust Zürichsee Meetup



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#### **Outline**

1. Embedded Programming

2. State of Embedded in 2020

3. probe-rs

4. probe\_rs.await?;



# **Embedded Programming**



## What is an Embedded System?

A combination of computer hardware and software, and perhaps additional mechanical or other parts, designed to perform a dedicated function.

Michael Barr. "Embedded Systems Glossary" 1

<sup>1</sup> https://barrgroup.com/Embedded-Systems/Glossary-E#embedded\_system

## What is embedded programming?

- Dedicated, not general purpose, μC system
- Baremetal
- Low-Level

## What is embedded programming?

- Dedicated, not general purpose, μC system
- Baremetal
- Low-Level
- For this talk: Bare metal on Cortex-M MCUs

## Why do they say it's hard?

- Harsh environment (No OS which protects you)
- Resource constrained (Remember dedicated?)
- Non-standard, Non-OSS toolchain
- Hard realtime requirements
- ...

#### What does it mean for Rust?



### Why is Rust awesome for it?

- Zero cost abstractions!
- Provides safety at compiler level, not OS
- Expressive type system to encode constraints

# State of Embedded in 2020

#### The compiler

- const fn
- core::future::Future
- alloc crate is stable
- MaybeUninit<T>: Fixes undefined behavior

## The compiler



## async / await of course

The .await is over, async fns are here

 $\rightarrow$  We'll get to it

### State of Embedded in 2020

const fn

#### **Constant Fun!**



- Stabilized at the end of 2018
- Tons of functions got const during 2019
- More functions from libcore
- More features (destructuring, bindings, assignment, ...)

### **Constant Fun Example**

An example from the lin-bus crate<sup>2</sup>

```
/// Calculate the PID from an ID.
/// P0 = ID0 ^ ID1 ^ ID2 ^ ID4
/// P1 = ¬(ID1 ^ ID3 ^ ID4 ^ ID5)
const fn from_id_const(id: u8) -> PID {
      // count parity bits and check if they are even / odd
      let p0 = (id & Ob1_O111).count_ones() as u8 & Ob1;
      let p1 = ((id & Ob11_1010).count_ones() as u8 + 1) & Ob1;
      PID(id | (p0 << 6u8) | (p1 << 7u8))
}</pre>
```

<sup>&</sup>lt;sup>2</sup>https://github.com/Sensirion/lin-bus-rs/blob/ e89739e326daf091803373419a4d60d0888422fc/src/frame.rs

## **Less Constant Fun Example**

Saw the problem?

#### **Less Constant Fun Example**

#### Saw the problem?

```
pub fn from_id(id: u8) -> PID {
    assert!(id < 64, "ID must be less than 64");
    PID::from_id_const(id)
}</pre>
```

### **Less Constant Fun Example**

#### Saw the problem?

```
pub fn from_id(id: u8) -> PID {
    assert!(id < 64, "ID must be less than 64");
    PID::from_id_const(id)
}</pre>
```

#### Workaround

```
// check that id < 64. Compile error during const evaluation 
// and panic on debug build 
let \_: u8 = id + 192;
```

#### **Constant Future**

What is missing?

- Panicking in constants<sup>3</sup>
- Const generics<sup>4</sup>

<sup>3</sup>https://github.com/rust-lang/rust/issues/51999

<sup>4</sup>https://github.com/rust-lang/rust/issues/44580

## State of Embedded in 2020

**Other News** 

### **New Platform Support**

- AVR basic support got merged<sup>5</sup>
- New ARM targets: thumbv7neon-linux-{androideabi,gnueabihf}, armv{6/7}-unknown-freebsd-gnueabihf, aarch64-unknown-none-\*
- New RISC-V targets: riscv64imac-unknown-none-elf, riscv64gc-unknown-none-elf, riscv32i-unknown-none-elf
- Sony PSP support<sup>7</sup>

<sup>&</sup>lt;sup>5</sup>https://github.com/rust-lang/rust/pull/69478

<sup>&</sup>lt;sup>6</sup>https://github.com/rust-lang/rust/issues/44052

<sup>&</sup>lt;sup>7</sup>https://github.com/rust-lang/rust/pull/72062

#### $\mathsf{RTFM} \to \mathsf{RTIC}$

- RTFM got renamed → RTIC<sup>8</sup>
- Examples: https://github.com/coredump-ch/nixiecounter/tree/master/firmware/

<sup>8</sup>https://rtic.rs/0.5/book/en/migration\_rtic.html

## State of Embedded in 2020

**Embedded HAL** 

#### What is the Embedded HAL?

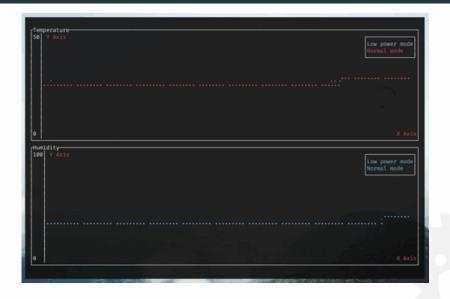
- Unified interface to the same HW functionality which has different interfaces
- Higher level crates (drivers) are write once use always
- Nice examples: shtc3 driver<sup>9</sup> developed and debugged on a Raspberry Pi and used with an STM32

<sup>9</sup>https://github.com/dbrgn/shtcx-rs

## **SHTC3** Driver as Example



# SHTC3 Driver as Example



### **Embedded HAL** — Challanges / Future

- It's hard to define traits which work everywhere
- How to define async traits?
- Ecosystem needs to move as a whole on breaking changes
- 1.0 Release planed<sup>10</sup>

 $<sup>^{10} \</sup>verb|https://github.com/rust-embedded/embedded-hal/issues/177|$ 

# State of Embedded in 2020

async on embedded

#### async — Some Background

- async/await landed in stable Rust 1.39<sup>11</sup>
- In February 2020 Ferrous Systems started blogging about bringing it to embedded<sup>12 13</sup>
- Since Rust 1.44 usable on no\_std <sup>14</sup>

<sup>11</sup>https://blog.rust-lang.org/2019/11/07/Async-await-stable.html

<sup>12</sup>https://ferrous-systems.com/blog/embedded-async-await/

<sup>13</sup>https://ferrous-systems.com/blog/async-on-embedded/

<sup>14</sup>https://ferrous-systems.com/blog/stable-async-on-embedded/

#### async — What is it Even?

- Mostly syntactic suger for a state machine
- Useful for concurrent waiting

## async — State Machine

```
async fn foo() -> u8 {
async fn bar(a: u8) -> u8 {
    a + 2
async fn f() \rightarrow u8 {
    let a = foo().await;
    bar(a).await
```

#### async — State Machine

```
async fn foo() -> u8 {
                                          enum Future {
                                              Ready(u8),
                                              Pending,
async fn bar(a: u8) -> u8 {
    a + 2
                                          enum State {
async fn f() \rightarrow u8  {
                                              Foo,
    let a = foo().await;
                                              Bar(u8),
    bar(a).await
                                              Done(u8),
```

#### async — State Machine

```
fn f desugared(state: State) -> State {
    match state {
        State::Foo => match foo () {
            Future::Ready(a) => State::Bar(a),
            Future::Pending => State::Foo,
        },
        State::Bar(a) => match bar (a) {
            Future::Ready(b) => State::Done(b),
            Future::Pending => State::Bar(a),
        State::Done(b) => State::Done(b)
```

## async — Why on Embedded?

- Most embedded systems are event driven → Most code is awaiting events.
- lacktriangle Embedded systems may want to save power ightarrow Sleep whenever possible.
- We often need to wait for peripherals / IO

## async — A blocking blinky

```
fn main() -> ! {
    let mut led = Led::new();
    let mut timer = Timer::new();
    loop {
        led.on();
        timer.delay_ms(1_000);
        led.off();
        timer.delay_ms(1_000);
```

#### async — A async blinky

```
fn main() -> ! {
    let mut led = Led::new();
    let mut timer = Timer::new();
    // `block_on` runs the future (`async` block) to completion
    task::block_on(async {
        loop {
            led.on():
            timer.wait(Duration::from_secs(1)).await;
            // ^ suspends the task for one second
            led.off();
            timer.wait(Duration::from_secs(1)).await;
    })
```

# async — embrio-rs<sup>17</sup>

- Playground for async on no\_std
- Provides a custom async desugaring via a proc macro
- Not actively developed anymore according to author<sup>15</sup>
- Works very nice on the NRF51
- Used in the Polymer mechanical keyboard firmware<sup>16</sup>

<sup>15</sup>https://www.reddit.com/r/rust/comments/f0ckiv/bringing\_asyncawait\_to\_
embedded\_rust/fgwh6ij/

<sup>16</sup>https://josh.robsonchase.com/rest-of-the-keyboard/

<sup>17</sup>https://github.com/Nemo157/embrio-rs

## async — The Future

- Reusable executors?
- Thread safety with interrupts?

#### async — The Future

- Reusable executors?
- Thread safety with interrupts?
- RTIC may provide a solution for that ©

#### More Resources

- The Rust Embedded WG Blog<sup>18</sup>
- The Rust Embedded Book<sup>19</sup>
- The Discovery book<sup>20</sup>
- Awesome Embedded Rust<sup>21</sup>

<sup>18</sup>https://rust-embedded.github.io/blog/

<sup>19</sup>https://docs.rust-embedded.org/book/

<sup>20</sup>https://docs.rust-embedded.org/discovery/index.html

<sup>21</sup>https://github.com/rust-embedded/awesome-embedded-rust

# probe-rs



#### **Embedded Development**

- Software is written on a host instead of the target.
- The microchip has no direct feedback.
- A middleman is needed (soft- & hardware).
- probe-rs



#### probe-rs!

- Rust Library
- Easy to use
- Unified interface
- Developed on Github
- Talks to ARM and RISC-V cores (for now)
- Supports CMSIS-DAP, ST-Link, J-Link

#### **Current State**

- Memory Access (read, write)
- CPU Manipulation (run, halt, step, reset, etc.)
- Breakpoints (set, reset)
- Flashing (ELF, BIN, HEX)

## **Memory Access**

```
use probe_rs::Session;
use probe_rs::MemoryInterface;

let mut session = Session::auto_attach("nrf52")?;
let mut core = session.core(0)?;

// Read a single 32 bit word.
let word = core.read_word_32(0x2000_0000)?;
```

#### **CPU Control**

```
use probe_rs::Session;
use probe_rs::MemoryInterface;

let mut session = Session::auto_attach("nrf52")?;
let mut core = session.core(0)?;

// Reset the CPU.
core.reset()?;
```

#### **Breakpoint Manipulation**

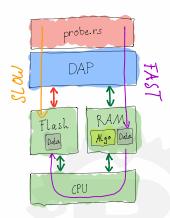
```
use probe_rs::Session;
use probe_rs::MemoryInterface;

let mut session = Session::auto_attach("nrf52")?;
let mut core = session.core(0)?;

// Set a breakpoint.
core.set_hw_breakpoint(0x1500_2000)?;
```

#### Flash Algorithms

- Used for fast flashing
- Used to circumvent slow flash access
- Small program loaded into RAM
- Copies data from RAM to Flash
- CMSIS-Packs
  - ARM standard
  - thousands of available targets



# cargo flash

- slim cargo plugin
- for flashing targets
- to jumpstart in a project
- https://github.com/probe-rs/cargo-flash
- cargo install cargo-flash

#### cargo embed

- fat client embedded toolkit
- flashing
- RTT
- GDB
- more?
- highly configurable
- https://github.com/probe-rs/cargo-embed
- cargo install cargo-embed

# probe\_rs.await?;

#### **VSCode**

- VSCode plugin
- Microsoft DAP
- no GDB required
- Modern, extensive API (JSON)
- async
- working, with limitations
- https://github.com/probe-rs/vscode

#### ITM

- powerful data streaming from the target
- ISR events
- memory access events
- custom binary data
- working, not on master yet
- https://github.com/probe-rs/probe-rs/pull/145

#### **Custom Hooks**

- use CMSIS-Pack hooks
- unlocking, special bytes, etc.
- uses custom WASM format
- poc, no PR yet

## rs-probe

- open source probe
- pure rust firmware
- extremely fast (500 Mbit/s)
- uses standard ARM API
- can stream DAP, ITM and UART data
- https://github.com/korken89/hs-probe



#### Contribute

- https://probe.rs
- https://github.com/probe-rs/probe-rs
- #probe-rs:matrix.org on Matrix
- Questions & Bugreports very welcome
- PRs very welcome

# Thank you!

https://coredump.ch

https://technokrat.ch/

Slides: https://github.com/rust-zurichsee/meetups/



# **Appendix**



# 5. Appendix



# **Appendix**

Alloc crate

#### alloc crate

- alloc allows you to use a subset of std (e.g. Vec, Box, Arc) in #! [no\_std] environments if the environment has access to heap memory allocation.<sup>22</sup>
- You need to define a #[global\_allocator]<sup>23</sup>
- Check out https://crates.io/crates/alloc-cortex-m

<sup>&</sup>lt;sup>22</sup>https://github.com/rust-lang/rfcs/blob/master/text/2480-liballoc.md

<sup>&</sup>lt;sup>23</sup>https://doc.rust-lang.org/stable/std/alloc/#the-global\_allocator-attribute

# **Appendix**

svd2rust

#### svd2rust

- Every Cortex-M C vendor must provide an SVD (System View Descriptions) file
- SVD is an XML standard to describe peripheral registers
- svd2rust<sup>24</sup>: Generate Rust register maps (structs) from SVD files

<sup>24</sup>https://github.com/rust-embedded/svd2rust