

CS 473: Algorithms

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Polynomials, Convolutions and FFT

Lecture 2

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Outline

Discrete Fourier Transform (DFT) and Fast Fourier Transform (FFT) have many applications and are connected to important mathematics.

“One of top 10 Algorithms of 20th Century” according to IEEE.
Gilbert Strang: “The most important numerical algorithm of our lifetime”.

Our goal:

- Multiplication of two degree n polynomials in $O(n \log n)$ time. Surprising and non-obvious.
- Algorithmic ideas
 - change in representation
 - mathematical properties of polynomials
 - divide and conquer

Part I

Polynomials, Convolutions and FFT

Polynomials

Definition

A **polynomial** is a function of one variable built from additions, subtractions and multiplications (but no divisions).

$$p(x) = \sum_{j=0}^{n-1} a_j x^j$$

The numbers a_0, a_1, \dots, a_n are the **coefficients** of the polynomial. The **degree** is the highest power of x with a non-zero coefficient.

Example

$$p(x) = 3 - 4x + 5x^3$$

$a_0 = 3, a_1 = -4, a_2 = 0, a_3 = 5$ and $\deg(p) = 3$

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Coefficient Representation

Polynomials represented by vector $a = (a_0, a_1, \dots, a_{n-1})$ of coefficients.

Operations on Polynomials

- Evaluate** Given a polynomial p and a value α , compute $p(\alpha)$
- Add** Given (representations of) polynomials p, q , compute (representation of) polynomial $p + q$
- Multiply** Given (representation of) polynomials p, q , compute (representation of) polynomial $p \cdot q$.
- Roots** Given p find all *roots* of p .

Evaluation

Compute value of polynomial $a = (a_0, a_1, \dots, a_{n-1})$ at α

```
power = 1
value = 0
for  $j = 0$  to  $n - 1$ 
    // invariant:  $\text{power} = \alpha^j$ 
    value = value +  $a_j \cdot \text{power}$ 
    power = power  $\cdot \alpha$ 
end for
return value
```

Uses $2n$ multiplication and n additions

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Uses $2n$ multiplication and n additions

Horner's rule can be used to cut the multiplications in half

$$a(x) = a_0 + x(a_1 + x(a_2 + \dots + xa_{n-1}))$$

Evaluation: Numerical Issues

Question

How long does evaluation really take? $O(n)$ time?

Bits to represent α^n is $n \log \alpha$ while bits to represent α is only $\log \alpha$. Thus, need to pay attention to size of numbers and multiplication complexity.

Ignore this issue for now. Can get around it for applications of interest where one typically wants to compute $p(\alpha) \bmod m$ for some number m .

Addition

Compute the sum of polynomials

$a = (a_0, a_1, \dots, a_{n-1})$ and $b = (b_0, b_1, \dots, b_{n-1})$

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$a = (a_0, a_1, \dots, a_{n-1})$ and $b = (b_0, b_1, \dots, b_{n-1})$

$a + b = (a_0 + b_0, a_1 + b_1, \dots, a_{n-1} + b_{n-1})$. Takes $O(n)$ time.

Multiplication

Compute the product of polynomials

$a = (a_0, a_1, \dots, a_n)$ and $b = (b_0, b_1, \dots, b_m)$

Recall $a \cdot b = (c_0, c_1, \dots, c_{n+m})$ where

$$c_k = \sum_{i,j: i+j=k} a_i \cdot b_j$$

Takes $\Theta(nm)$ time; $\Theta(n^2)$ when $n = m$.

$$(5 + 3x + 10x^3) \times (1 + 3x^2)$$

Multiplication

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We will give a better algorithm!

Convolutions

Definition

The **convolution** of vectors $\mathbf{a} = (a_0, a_1, \dots, a_n)$ and $\mathbf{b} = (b_0, b_1, \dots, b_m)$ is the vector $\mathbf{c} = (c_0, c_1, \dots, c_{n+m})$ where

$$c_k = \sum_{i,j: i+j=k} a_i \cdot b_j$$

Convolution of vectors \mathbf{a} and \mathbf{b} is denoted by $\mathbf{a} * \mathbf{b}$. In other words, the convolution is the coefficients of the product of the two polynomials.

Revisiting Polynomial Representations

Representation

Polynomials represented by vector $\mathbf{a} = (a_0, a_1, \dots, a_{n-1})$ of coefficients.

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Question

Are there other useful ways to represent polynomials?

Representing Polynomials by Roots

Root of a polynomial $p(x)$: r such that $p(r) = 0$. If

r_1, r_2, \dots, r_{n-1} are roots then

$$p(x) = a_{n-1}(x - r_1)(x - r_2) \dots (x - r_{n-1}).$$

Valid representation because of:

Theorem (Fundamental Theorem of Algebra)

*Every polynomial $p(x)$ of degree d has exactly d roots r_1, r_2, \dots, r_d where the roots can be **complex numbers** and can be repeated.*

Representing Polynomials by Roots

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Polynomials represented by vector scale factor a_{n-1} and roots r_1, r_2, \dots, r_{n-1} .

Representing Polynomials by Roots

Representation

Polynomials represented by vector scale factor a_{n-1} and roots r_1, r_2, \dots, r_{n-1} .

- Evaluating p at a given x is easy. Why?
- Multiplication: given p, q with roots r_1, \dots, r_{n-1} and s_1, \dots, s_{m-1} the product $p \cdot q$ has roots $r_1, \dots, r_{n-1}, s_1, \dots, s_{m-1}$. Easy! $O(n + m)$ time.
- Addition: requires $\Omega(nm)$ time?
- Given coefficient representation, how do we go to root representation? No finite algorithm because of potential for irrational roots.

Representing Polynomials by Samples

Let p be a polynomial of degree $n - 1$.

Pick n *distinct samples* $x_0, x_1, x_2, \dots, x_{n-1}$

Let $y_0 = p(x_0), y_1 = p(x_1), \dots, y_{n-1} = p(x_{n-1})$.

Representation

Polynomials represented by $(x_0, y_0), (x_1, y_1), \dots, (x_{n-1}, y_{n-1})$.

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Representation

Polynomials represented by $(x_0, y_0), (x_1, y_1), \dots, (x_{n-1}, y_{n-1})$.

Is the above a valid representation? Why do we use $2n$ numbers instead of n numbers for coefficient and root representation?

Sample Representation

Theorem

Given a list $\{(x_0, y_0), (x_1, y_1), \dots (x_{n-1}, y_{n-1})\}$ there is exactly one polynomial p of degree $n - 1$ such that $p(x_j) = y_j$ for $j = 0, 1, \dots, n - 1$.

Sample Representation

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So representation is valid.

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So representation is valid.

Can use same x_0, x_1, \dots, x_{n-1} for all polynomials of degree $n - 1$.

No need to store them explicitly and hence need only n numbers y_0, y_1, \dots, y_{n-1} .

Lagrange Interpolation

Given $(x_0, y_0), \dots, (x_{n-1}, y_{n-1})$ the following polynomial p satisfies the property that $p(x_j) = y_j$ for $j = 0, 1, 2, \dots, n-1$.

$$p(x) = \sum_{j=0}^{n-1} \left(\frac{y_j}{\prod_{k \neq j} (x_j - x_k)} \prod_{k \neq j} (x - x_k) \right)$$

For $n = 3$, $p(x) =$

$$y_0 \frac{(x - x_1)(x - x_2)}{(x_0 - x_1)(x_0 - x_2)} + y_1 \frac{(x - x_0)(x - x_2)}{(x_1 - x_0)(x_1 - x_2)} + y_2 \frac{(x - x_0)(x - x_1)}{(x_2 - x_0)(x_2 - x_1)}$$

Easy to verify that $p(x_j) = y_j$! Thus there exists one polynomial of degree $n-1$ that interpolates the values $(x_0, y_0), \dots, (x_{n-1}, y_{n-1})$.

Lagrange Interpolation

Given $(x_0, y_0), \dots, (x_{n-1}, y_{n-1})$ there is a polynomial $p(x)$ such that $p(x_i) = y_i$ for $0 \leq i < n$. Can there be two distinct polynomials?

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No! Use Fundamental Theorem of Algebra to prove it — exercise.

Addition and Multiplication with Sample Representation

- Let $\{(x_0, y_0), (x_1, y_1), \dots, (x_{n-1}, y_{n-1})\}$ and $\{(x_0, y'_0), (x_1, y'_1), \dots, (x_{n-1}, y'_{n-1})\}$ be representations of two polynomials of degree $n - 1$

Addition and Multiplication with Sample Representation

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- $a + b$ can be represented by $\{(x_0, (y_0 + y'_0)), (x_1, (y_1 + y'_1)), \dots, (x_{n-1}, (y_{n-1} + y'_{n-1}))\}$
 - Thus, can be computed in $O(n)$ time

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 - Thus, can be computed in $O(n)$ time
- $a \cdot b$ can be evaluated at n samples $\{(x_0, (y_0 \cdot y'_0)), (x_1, (y_1 \cdot y'_1)), \dots, (x_{n-1}, (y_{n-1} \cdot y'_{n-1}))\}$
 - Can be computed in $O(n)$ time.

Addition and Multiplication with Sample Representation

- Let $\{(x_0, y_0), (x_1, y_1), \dots, (x_{n-1}, y_{n-1})\}$ and $\{(x_0, y'_0), (x_1, y'_1), \dots, (x_{n-1}, y'_{n-1})\}$ be representations of two polynomials of degree $n - 1$
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But what if p, q are given in coefficient form? Convolution requires p, q to be in coefficient form.

Coefficient representation to Sample representation

Given \mathbf{p} as $(a_0, a_1, \dots, a_{n-1})$ can we obtain a sample representation $(x_0, y_0), \dots, (x_{n-1}, y_{n-1})$ quickly? Also can we *invert* the representation quickly?

Coefficient representation to Sample representation

Given p as $(a_0, a_1, \dots, a_{n-1})$ can we obtain a sample representation $(x_0, y_0), \dots, (x_{n-1}, y_{n-1})$ quickly? Also can we *invert* the representation quickly?

- Suppose we choose x_0, x_1, \dots, x_{n-1} arbitrarily.
- Take $O(n)$ time to evaluate $y_j = p(x_j)$ given (a_0, \dots, a_{n-1}) .
- Total time is $\Omega(n^2)$
- Inversion via Lagrange interpolation also $\Omega(n^2)$

Key Idea

Can choose x_0, x_1, \dots, x_{n-1} carefully!

Total time to evaluate $p(x_0), p(x_1), \dots, p(x_{n-1})$ should be better than evaluating each separately.

Key Idea

Can choose x_0, x_1, \dots, x_{n-1} carefully!

Total time to evaluate $p(x_0), p(x_1), \dots, p(x_{n-1})$ should be better than evaluating each separately.

How do we choose x_0, x_1, \dots, x_{n-1} to save work?

A Simple Start

$$a(x) = a_0 + a_1x + a_2x^2 + a_3x^3 + \dots + a_{n-1}x^{n-1}$$

Assume n is a power of 2 for rest of the discussion.

Observation: $(-x)^{2j} = x^{2j}$. Can we exploit this?

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Example

$$3+4x+6x^2+2x^3+x^4+10x^5 = (3+6x^2+x^4)+x(4+2x^2+10x^4)$$

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Example

$$3+4x+6x^2+2x^3+x^4+10x^5 = (3+6x^2+x^4)+x(4+2x^2+10x^4)$$

If we have $a(x)$ then easy to also compute $a(-x)$

Odd and Even Decomposition

- Let $a = (a_0, a_1, \dots, a_{n-1})$ be a polynomial.
- Let $a_{\text{odd}} = (a_1, a_3, a_5, \dots)$ be the $n/2$ degree polynomial defined by the odd coefficients; so

$$a_{\text{odd}}(x) = a_1 + a_3x + a_5x^2 + \dots$$

- Let $a_{\text{even}} = (a_0, a_2, a_4, \dots)$ be the $n/2$ degree polynomial defined by the even coefficients.
- Observe

$$a(x) = a_{\text{even}}(x^2) + xa_{\text{odd}}(x^2)$$

- Thus, evaluating a at x can be reduced to evaluating lower degree polynomials plus constantly many arithmetic operations.

Exploiting Odd-Even Decomposition

$$a(x) = a_{\text{even}}(x^2) + xa_{\text{odd}}(x^2)$$

- Choose n samples

$$x_0, x_1, x_2, \dots, x_{n/2-1}, -x_0, -x_1, \dots, -x_{n/2-1}$$

Exploiting Odd-Even Decomposition

$$a(x) = a_{\text{even}}(x^2) + xa_{\text{odd}}(x^2)$$

- Choose n samples
 $x_0, x_1, x_2, \dots, x_{n/2-1}, -x_0, -x_1, \dots, -x_{n/2-1}$
- Sufficient to evaluate a_{even} and a_{odd} at $x_0^2, x_1^2, x_2^2, \dots, x_{n/2-1}^2$.
Plus $O(n)$ work gives $a(x)$ for all n samples

Exploiting Odd-Even Decomposition

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- Sufficient to evaluate a_{even} and a_{odd} at $x_0^2, x_1^2, x_2^2, \dots, x_{n/2-1}^2$.
Plus $O(n)$ work gives $a(x)$ for all n samples
- Suppose we can make this work recursively. Then

$$T(n) = 2T(n/2) + O(n) \text{ which implies } T(n) = O(n \log n)$$

Collapsible sets

Definition

Given a set X of numbers $\text{square}(X)$ (for square of X) is the set $\{x^2 \mid x \in X\}$.

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A set X of n numbers is *collapsible* if $\text{square}(X) \subset X$ and $|\text{square}(X)| = n/2$.

$$\{1, -1, i, -i\}$$

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Definition

A set X of n numbers (for n a power of 2) is *recursively collapsible* if $n = 1$ or if X is collapsible and $\text{square}(X)$ is recursively collapsible.

Divide and Conquer assuming collapsible set

Assume we have a collapsible set X of size n and a polynomial p of degree n . We can compute a sample representation of a for numbers in X as follows:

SampleRepresentation(a , X , n)

If $n = 1$ return $a(x_0)$ where $X = \{x_0\}$

Compute $\text{square}(X)$ in $O(n)$ time

$\{y_0, y_1, \dots, y_{n/2-1}\} = \text{SampleRepresentation}(a_{\text{odd}}, \text{square}(X), n/2)$

$\{y'_0, y'_1, \dots, y'_{n/2-1}\} = \text{SampleRepresentation}(a_{\text{even}}, \text{square}(X), n/2)$

For each $x_i \in X$ compute

$$z_i = a_{\text{even}}(x_i^2) + x_i a_{\text{odd}}(x_i^2)$$

Return $\{z_0, z_1, \dots, z_{n-1}\}$

Exercise: show that algorithm runs in $O(n \log n)$ time

$$a(x) = a_{\text{even}}(x^2) + x \cdot a_{\text{odd}}(x^2)$$

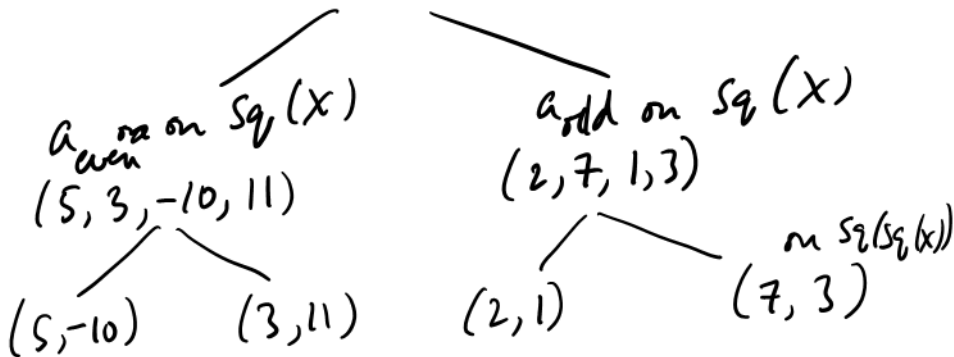
$$5 + 2x + 3x^2 + 7x^3 - 10x^4 + x^5 + 11x^6 + 3x^7$$

$$= (5 + 3x^2 - 10x^4 + 11x^6) + x(2 + 7x^2 + x^4 + 3x^6)$$

Evaluate on $X = \{x_0, x_1, \dots, x_7\}$

Square $(X) = \{x_0, x_1, x_2, x_3\}$ wlog

a on X (5, 2, 3, 7, -10, 1, 11, 3)



Are there collapsible sets?

- n samples $x_0, x_1, x_2, \dots, x_{n/2-1}, -x_0, -x_1, \dots, -x_{n/2-1}$
- Next step in recursion $x_0^2, x_1^2, \dots, x_{n/2-1}^2$

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- To continue recursion, we need

$$\{x_0^2, x_1^2, \dots, x_{\frac{n}{2}-1}^2\} = \{z_0, z_1, \dots, z_{\frac{n}{4}-1}, -z_0, -z_1, \dots, -z_{\frac{n}{4}-1}\}$$

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- If $z_0 = x_0^2$ and say $-z_0 = x_j^2$ then $x_0 = \sqrt{-1}x_j$ That is $x_0 = ix_j$ where i is the imaginary number.
- Can continue recursion but need to go to *complex* numbers.

Complex Numbers

Notation

For the rest of lecture, i stands for $\sqrt{-1}$

Definition

Complex numbers are points lying in the complex plane represented as

Cartesian $a + ib = \sqrt{a^2 + b^2} e^{(\arctan(b/a))i}$

Polar $re^{\theta i} = r(\cos \theta + i \sin \theta)$

Thus, $e^{\pi i} = -1$ and $e^{2\pi i} = 1$.

Power Series for Functions

What is e^z when z is a real number? When z is a complex number?

$$e^z = 1 + z/1! + z^2/2! + \dots + z^j/j! + \dots$$

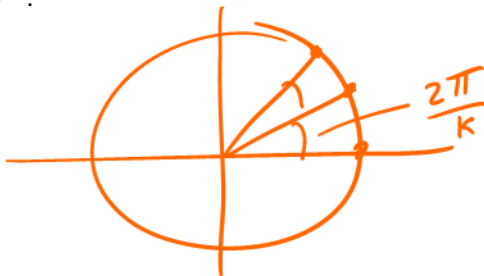
Therefore

$$\begin{aligned} e^{i\theta} &= 1 + i\theta/1! + (i\theta)^2/2! + (i\theta)^3/3! + \dots \\ &= (1 - \theta^2/2! + \theta^4/4! - \dots +) + i(\theta - \theta^3/3! + \dots +) \\ &= \cos \theta + i \sin \theta \end{aligned}$$

Complex Roots of Unity

What are the roots of the polynomial $x^k - 1$?

- Clearly **1** is a root.
- Suppose $re^{\theta i}$ is a root then $r^k e^{k\theta i} = 1$ which implies that $r = 1$ and $k\theta = 2\pi$ since $e^{k\theta i} = \cos(k\theta) + i \sin(k\theta) = 1$
- Let $\omega_k = e^{2\pi i/k}$. The roots are $1 = \omega_k^0, \omega_k^1, \dots, \omega_k^{k-1}$ where $\omega_k^j = e^{2\pi j i/k}$.



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- Let $\omega_k = e^{2\pi i/k}$. The roots are $1 = \omega_k^0, \omega_k^2, \dots, \omega_k^{k-1}$ where $\omega_k^j = e^{2\pi ji/k}$.

Proposition

Let ω_k be $e^{2\pi i/k}$. The equation $x^k = 1$ has k distinct complex roots given by $\omega_k^j = e^{2\pi ji/k}$ for $j = 0, 1, \dots, k-1$

Proof.

$$(\omega_k^j)^k = (e^{2\pi ji/k})^k = e^{2\pi ji} = (e^{2\pi i})^j = (1)^j = 1$$



More on the Roots of Unity

Observations

- $\omega_k^j = \omega_k^{j \bmod k}$
- $\omega_k = \omega_{jk}^j$; thus, every k th root is also a jk th root.
- $\sum_{s=0}^{k-1} (\omega_k^j)^s = (1 + \omega_k^j + \omega_k^{2j} + \dots + \omega_k^{j(k-1)}) = 0$ for $j \neq 0$

More on the Roots of Unity

Observations

- $\omega_k^j = \omega_k^{j \bmod k}$
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- $\sum_{s=0}^{k-1} (\omega_k^j)^s = (1 + \omega_k^j + \omega_k^{2j} + \dots + \omega_k^{j(k-1)}) = 0$ for $j \neq 0$
 - ω_k^j is root of $x^k - 1 = (x - 1)(x^{k-1} + x^{k-2} + \dots + 1)$
 - Thus, ω_k^j is root of $(x^{k-1} + x^{k-2} + \dots + 1)$

Roots of unity form a collapsible set

Lemma

Assume n is a power of 2. The n 'th roots of unity are a recursively collapsible set.

Proof.

Let $X_n = \{1, \omega_n, \omega_n^2, \dots, \omega_n^{n-1}\}$. Verify that $\text{square}(X_n)$ is the set of $n/2$ powers of unity. □

- $X_1 = \{1\}, X_2 = \{1, -1\}$
- $X_4 = \{1, -1, i, -i\}$
- $X_8 = \{1, -1, i, -i, \frac{1}{\sqrt{2}}(\pm 1 \pm i)\}$

$$\{1, \omega_n, \omega_n^2, \dots, \omega_n^{n-1}\} = X$$

$$e^{\frac{2\pi}{n} \cdot 0}, e^{\frac{2\pi}{n} \cdot 1}, \dots, e^{\frac{2\pi}{n} \cdot (n-1)}$$

$$\text{Square}(X) =$$

$$\left\{ e^{\frac{2\pi}{n} \cdot 2 \times 0}, e^{\frac{2\pi}{n} \cdot 2 \times 1}, \dots, e^{\frac{2\pi}{n} \cdot 2 \times (\frac{n}{2} - 1)}, \dots \right\}$$

$$= \left\{ e^{\frac{2\pi}{n/2} \cdot 0}, e^{\frac{2\pi}{n/2} \cdot 1}, \dots, e^{\frac{2\pi}{n/2} \cdot (\frac{n}{2} - 1)}, \dots \right\}$$

$$e^{\frac{2\pi}{n} \cdot 2 \times (\frac{n}{2} + 0)}, e^{\frac{2\pi}{n} \cdot 2 \times (\frac{n}{2} + 1)}, \dots, e^{\frac{2\pi}{n} \cdot 2 \times (\frac{n}{2} + \frac{n}{2} - 1)}$$

$$e^{2\pi} \left[e^{\frac{2\pi}{n} \cdot 0}, e^{\frac{2\pi}{n} \cdot 1}, e^{\frac{2\pi}{n} \cdot 2}, \dots, e^{\frac{2\pi}{n} (\frac{n}{2} - 1)} \right]$$

Discrete Fourier Transform

Definition

Given vector $\mathbf{a} = (a_0, a_1, \dots, a_{n-1})$ the *Discrete Fourier Transform* (DFT) of \mathbf{a} is the vector $\mathbf{a}' = (a'_0, a'_1, \dots, a'_{n-1})$ where $a'_j = a(\omega_n^j)$ for $0 \leq j < n$.

\mathbf{a}' is a sample representation of polynomial with coefficient representation \mathbf{a} at n 'th roots of unity.

We have shown that \mathbf{a}' can be computed from \mathbf{a} in $O(n \log n)$ time. This divide and conquer *algorithm* is called the *Fast Fourier Transform* (FFT).

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Back to Convolutions and Polynomial Multiplication

Convolutions

Compute convolution $c = (c_0, c_1, \dots, c_{2n-2})$ of $a = (a_0, a_1, \dots, a_{n-1})$ and $b = (b_0, b_1, \dots, b_{n-1})$

- 1 Compute values of a and b at some n sample points.
- 2 Compute sample representation of product. That is $c' = (a'_0 b'_0, a'_1 b'_1, \dots, a'_{n-1} b'_{n-1})$.
- 3 Compute coefficients of unique polynomial associated with sample representation of product. That is compute c from c' .

Back to Convolutions and Polynomial Multiplication

Convolutions

Compute convolution $c = (c_0, c_1, \dots, c_{2n-2})$ of $a = (a_0, a_1, \dots, a_{n-1})$ and $b = (b_0, b_1, \dots, b_{n-1})$

- 1 Compute values of a and b at the n th roots of unity.
- 2 Compute sample representation of product. That is $c' = (a'_0 b'_0, a'_1 b'_1, \dots, a'_{n-1} b'_{n-1})$.
- 3 Compute coefficients of unique polynomial associated with sample representation of product. That is compute c from c' .

How can we compute c from c' ? We only have n sample points and c' has $2n - 1$ coefficients!

Convolutions and Polynomial Multiplication

Convolutions

Compute convolution $c = (c_0, c_1, \dots, c_{2n-2})$ of $a = (a_0, a_1, \dots, a_{n-1})$ and $b = (b_0, b_1, \dots, b_{n-1})$

- 1 Pad a with n zeroes to make it a $(2n - 1)$ degree polynomial $a = (a_0, a_1, \dots, a_{n-1}, a_n, a_{n+1}, \dots, a_{2n-1})$. Similarly for b .
- 2 Compute values of a and b at the $2n$ th roots of unity.
- 3 Compute sample representation of product. That is $c' = (a'_0 b'_0, a'_1 b'_1, \dots, a'_{n-1} b'_{n-1}, \dots, a'_{2n-1} b'_{2n-1})$.
- 4 Compute coefficients of unique polynomial associated with sample representation of product. That is compute c from c' .

- Step 2 takes $O(n \log n)$ using divide and conquer algorithm
- Step 3 takes $O(n)$ time
- Step 4?

Part II

Inverse Fourier Transform

Inverse Fourier Transform

Input Given the evaluation of a $n - 1$ -degree polynomial a on the n th roots of unity (specified by vector a')

Goal Compute the coefficients of a

We saw that a' can be computed from a in $O(n \log n)$ time. Can we compute a from a' in $O(n \log n)$ time?

A Matrix Point of View

$a'_0 = a(x_0), a'_1 = a(x_1), \dots, a'_{n-1} = a(x_{n-1})$ where $x_j = \omega_n^j$.

Let $\omega_n^1 = e^{2\pi/n} = \omega$.

$$\begin{bmatrix} 1 & x_0 & x_0^2 & \dots & x_0^{n-1} \\ 1 & x_1 & x_1^2 & \dots & x_1^{n-1} \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 1 & x_j & x_j^2 & \dots & x_j^{n-1} \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 1 & x_{n-1} & x_{n-1}^2 & \dots & x_{n-1}^{n-1} \end{bmatrix} \begin{bmatrix} a_0 \\ a_1 \\ \vdots \\ a_j \\ \vdots \\ a_{n-1} \end{bmatrix} = \begin{bmatrix} a'_0 \\ a'_1 \\ \vdots \\ a'_j \\ \vdots \\ a'_{n-1} \end{bmatrix}$$

A Matrix Point of View

$a'_0 = a(x_0), a'_1 = a(x_1), \dots, a'_{n-1} = a(x_{n-1})$ where $x_j = \omega_n^j$.

Let $\omega_n^1 = e^{2\pi/n} = \omega$.

$$\begin{bmatrix} 1 & 1 & 1 & \dots & 1 \\ 1 & \omega & \omega^2 & \dots & \omega^{n-1} \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 1 & \omega^j & \omega^{2j} & \dots & \omega^{j(n-1)} \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 1 & \omega^{n-1} & \omega^{2(n-1)} & \dots & \omega^{(n-1)(n-1)} \end{bmatrix} \begin{bmatrix} a_0 \\ a_1 \\ \vdots \\ a_j \\ \vdots \\ a_{n-1} \end{bmatrix} = \begin{bmatrix} a'_0 \\ a'_1 \\ \vdots \\ a'_j \\ \vdots \\ a'_{n-1} \end{bmatrix}$$

Handwritten orange annotations showing a simplified version of the matrix equation. The matrix is written as $\begin{bmatrix} 1 & \omega^1 & \omega^2 & \dots & \omega^{n-1} \end{bmatrix}$ and the vector as $\begin{bmatrix} a_0 \\ a_1 \\ \vdots \\ a_{n-1} \end{bmatrix}$. The result vector is $\begin{bmatrix} a'_0 \\ a'_1 \\ \vdots \\ a'_{n-1} \end{bmatrix}$.

Inverting the Matrix

$$\begin{bmatrix} a_0 \\ a_1 \\ \vdots \\ a_j \\ \vdots \\ a_{n-1} \end{bmatrix} = \begin{bmatrix} 1 & 1 & 1 & \dots & 1 \\ 1 & \omega & \omega^2 & \dots & \omega^{n-1} \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 1 & \omega^j & \omega^{2j} & \dots & \omega^{j(n-1)} \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 1 & \omega^{n-1} & \omega^{2(n-1)} & \dots & \omega^{(n-1)(n-1)} \end{bmatrix}^{-1} \begin{bmatrix} a'_0 \\ a'_1 \\ \vdots \\ a'_j \\ \vdots \\ a'_{n-1} \end{bmatrix}$$

Inverting the Matrix

$$\begin{bmatrix} 1 & 1 & 1 & \dots & 1 \\ 1 & \omega & \omega^2 & \dots & \omega^{n-1} \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 1 & \omega^j & \omega^{2j} & \dots & \omega^{j(n-1)} \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 1 & \omega^{n-1} & \omega^{2(n-1)} & \dots & \omega^{(n-1)(n-1)} \end{bmatrix}^{-1} = \frac{1}{n} \begin{bmatrix} 1 & 1 & 1 & \dots & 1 \\ 1 & \omega^{-1} & \omega^{-2} & \dots & \omega^{-(n-1)} \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 1 & \omega^{-j} & \omega^{-2j} & \dots & \omega^{-j(n-1)} \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 1 & \omega^{-(n-1)} & \omega^{-2(n-1)} & \dots & \omega^{-(n-1)(n-1)} \end{bmatrix}$$

Replace ω by ω^{-1} which is also a root of unity!

$$\omega^{-j} = e^{-j2\pi/n} = \omega^{(n-j)2\pi/n}.$$

Inverse matrix is simply a permutation of the original matrix modulo scale factor $1/n$.

Why does it work?

Can check using simple algebra $\mathbf{V}\mathbf{V}^{-1} = \mathbf{I}$ where \mathbf{V} is the original matrix and \mathbf{I} is the $n \times n$ identity matrix.

$$(1, \omega^j, \omega^{2j}, \dots, \omega^{j(n-1)}) \cdot (1, \omega^{-k}, \omega^{-2k}, \dots, \omega^{-k(n-1)}) = \sum_{s=0}^{n-1} \omega^{(j-k)s}$$

Note that ω^{j-k} is a n 'th root of unity. If $j = k$ then sum is n , otherwise by previous observation sum is 0 .

Rows of matrix \mathbf{V} (and hence also those of \mathbf{V}^{-1}) are *orthogonal*. Thus $\mathbf{a}' = \mathbf{V}\mathbf{a}$ can be thought of a transforming the vector \mathbf{a} into a new Fourier basis with basis vectors corresponding to rows of \mathbf{V} .

Inverse Fourier Transform

Input Given the evaluation of a $n - 1$ -degree polynomial a on the n th roots of unity (specified by vector a')

Goal Compute the coefficients of a

We saw that a' can be computed from a in $O(n \log n)$ time. Can we compute a from a' in $O(n \log n)$ time?

Yes! $a = V^{-1}a'$ which is simply a permuted and scaled version of DFT. Hence can be computed in $O(n \log n)$ time.

Convolutions Once More

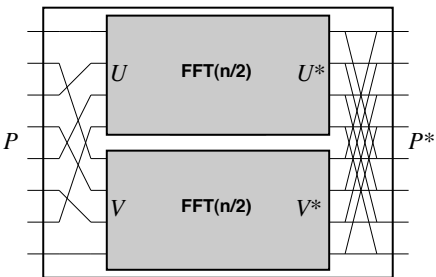
Convolutions

Compute convolution of $a = (a_0, a_1, \dots, a_{n-1})$ and $b = (b_0, b_1, \dots, b_{n-1})$

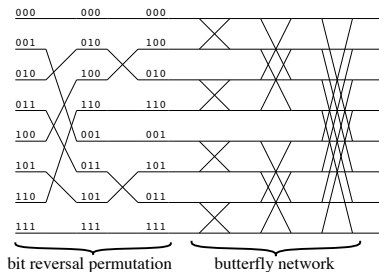
- 1 Compute values of a and b at the $2n$ th roots of unity
- 2 Compute sample representation c' of product $c = a \cdot b$
- 3 Compute c from c' using inverse Fourier transform.

- Step 1 takes $O(n \log n)$ using two FFTs
- Step 2 takes $O(n)$ time
- Step 3 takes $O(n \log n)$ using one FFT

FFT Circuit



The recursive structure of the FFT algorithm.



Numerical Issues

- As noted earlier evaluating a polynomial p at a point x makes numbers big
- Are we cheating when we say $O(n \log n)$ algorithm for convolution?
- Can get around numerical issues — work in finite fields and avoid numbers growing too big.
- Outside the scope of lecture
- We will assume for reductions that convolution can be done in $O(n \log n)$ time.

Part III

Application to String Matching

Basic string matching problem:

Input Given a pattern string P on length m and a text string T of length n over a fixed alphabet Σ

Goal Does P occur as a substring of T ? Find all “matches” of P in T .



Basic string matching problem:

Input Given a pattern string P on length m and a text string T of length n over a fixed alphabet Σ

Goal Does P occur as a substring of T ? Find all “matches” of P in T .

Several generalizations. Matching with don't cares.

Input Given a pattern string P on length m over $\Sigma \cup \{*\}$ ($*$ denotes don't care) and a text string T of length n over Σ

Goal Find all “matches” of P in T . $*$ matches with any character of Σ

Example: $P = a * *$, $T = aardvark$

Shifted products via Convolution

Given two arrays A and B with say with $A[0..m-1]$ and $B[0..n-1]$

Input Two arrays: $A[0..(m-1)]$ and $B[0..(n-1)]$ with $m \leq n$

Goal Compute all shifted products in array $C[0..(n-m-1)]$ where $C[i] = \sum_{j=0}^{m-1} A[j]B[i+j]$.

Example: $A = [0, 1, 1, 0]$, $B = [0, 0, 1, 1, 1, 0, 1]$

$$C = [1, 2, 0 \cdot x^0 + 1 \cdot x^1 + 1 \cdot x^2 + 0 \cdot x^3]$$

$$A \quad \begin{array}{cccc} & 0 & 1 & 1 & 0 \end{array}$$

$$B \quad \begin{array}{ccccccc} & 0 & 0 & 1 & 1 & 1 & 0 & 1 \\ & 0 \cdot x^6 & 0 \cdot x^5 & 1 \cdot x^4 & \dots & 1 \cdot x^0 \end{array}$$

Shifted products via Convolution

Given two arrays A and B with say with $A[0..m-1]$ and $B[0..n-1]$

Input Two arrays: $A[0..(m-1)]$ and $B[0..(n-1)]$ with $m \leq n$

Goal Compute all shifted products in array $C[0..(n-m-1)]$ where $C[i] = \sum_{j=0}^{m-1} A[j]B[i+j]$.

Example: $A = [0, 1, 1, 0]$, $B = [0, 0, 1, 1, 1, 0, 1]$
 $C =$

Lemma

C is the convolution of the vectors A and reverse of B .

Proof.

Exercise.



Reduction of pattern matching to shifted products

Assume first that $\Sigma = \{0, 1\}$

- Convert $P = a_0 a_1 \dots a_{m-1}$ to binary array A of m numbers.
- Convert $T = b_0 b_1 \dots b_{n-1}$ to binary array B of n numbers.
- Use shifted product C of A and B such that:
 - $C[i]$ counts number of “Type 1” mismatches when P is aligned with T at $T[i]$: $P[j] = 0$ and $T[i+j] = 1$
 - $C[i]$ counts number of “Type 2” mismatches when P is aligned with T at $T[i]$: $P[j] = 1$ and $T[i+j] = 0$.

There is a match at position i of T iff both types of mismatches are 0.

0 1 1 0
0 0 1 1 1 0 1

Finding mismatches

Finding Type 1 mismatches:

- If $P[j] = 0$ set $A[j] = 1$, if $P[j] = 1$ or $*$ set $A[j] = 0$.
- $B[j] = T[j]$

Finding mismatches

Finding Type 1 mismatches:

- If $P[j] = 0$ set $A[j] = 1$, if $P[j] = 1$ or * set $A[j] = 0$.
- $B[j] = T[j]$

Finding Type 2 mismatches:

- If $P[j] = 0$ or * set $A[j] = 0$, if $P[j] = 1$ set $A[j] = 1$.
- ~~$B[j] = T[j]$~~ ($B[j] = 1 - T[j]$)

Running time analysis

- Reducing to shift product is $O(n)$.
- Need to compute two convolutions with polynomials of size n and m . Total run time is $O(n \log n)$ (here we assume $m \leq n$).
- Can reduce to $O(n \log m)$ as follows. Break text T into $O(n/m)$ overlapping substrings of length $2m$ each and compute matches of P with these substrings. Total time is $O(n \log m)$.
Exercise: work out the details of this improvement.

General Alphabet

If Σ is not binary replace each character $\alpha \in \Sigma$ by its binary representation. Need $s = \lceil \log |\Sigma| \rceil$ bits. Running time increases to $O(n \log m \log s)$.

Can remove dependence on s and obtain $O(n \log m)$ time where $m = |P|$ using more advanced ideas and/or randomization.

$$\frac{n}{m} \times m \log m = n \log m$$