# Iterative Learning Control of a Pneumatically Driven Robot Joint

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Abstract—In this contribution the concept of *Iterative Learning Control (ILC)* is introduced and applied to a pneumatically driven joint build-in a pneumatic cobot. Iterative Learning Control is highly suitable to repeatable control tasks as they appear typically in robot applications [6].

Index Terms—model-based control, robot control

#### I. Introduction

Robot control tasks often follows a repeating trajectory. For this kind of application the concept of learning from the error of the previous control run lies on the hand. That's why in the field of robot control the concept of ILC is often used [1]. In [2] the concept for

#### II. CONTROL TASK

As a drafted version the paper of Steinboeck can be used [7]

## A. Model of the Pneumatic Robot Joint

In this research a single joint (cf. Fig. 2) of a pneumatic robot (cf. Fig. 1) is considered. In this pneumatically driven revolute joint, the two pressure chambers are separated by a swivel wing of area  $A_{\rm eff}$  and an effective radius  $R_{\rm eff}$ , which is semi-rotatable to  $\pm 135^{\circ}$ . The pressure difference between the two chambers 1 and 2 of the joint generates a driving torque

$$\tau(p_1, p_2) = A_{\text{eff}} R_{\text{eff}} (p_1 - P_2). \tag{1}$$

The pressure in each chamber is set individually by a massflow  $\dot{m}_{1,2}$  into or out of the chamber with a pneumatic valve, not considered in detail here. A more detailed overview of the pneumatic model can be found in [3].

The governing equations of the rotary joint model are:

$$\ddot{q} = \frac{A_{\rm eff}R_{\rm eff}(p_1 - p_2)}{J}, \qquad (2a)$$

$$\dot{p}_2 = \frac{nRT}{V_{\rm dead,2} + A_{\rm eff}R_{\rm eff}(|q_{\rm max} - q)}\dot{m}_2 - \frac{np_2A_{\rm eff}R_{\rm eff}\dot{q}}{V_{\rm dead,2} + A_{\rm eff}R_{\rm eff}(|q_{\rm max} - q)}, \qquad (2b)$$

$$\dot{p}_1 = \frac{nRT}{V_{\rm dead,1} + A_{\rm eff}R_{\rm eff}(|q_{\rm min} + q)}\dot{m}_1 + \frac{nP_1A_{\rm eff}R_{\rm eff}\dot{q}}{V_{\rm dead,1} + A_{\rm eff}R_{\rm eff}(|q_{\rm min} + q)}, \qquad (2c)$$

where the  $A_{\text{eff}}$ See also [5], and [4].



Fig. 1. Pneumatic Cobot from Festo (2020)

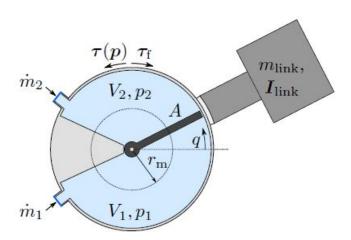


Fig. 2. Schematics of a pneumatic rotary joint [5].

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Define abbreviations and acronyms the first time they are used in the text, even after they have been defined in the abstract. Abbreviations such as IEEE, SI, MKS, CGS, ac, dc, and rms do not have to be defined. Do not use abbreviations in the title or heads unless they are unavoidable.

#### B. Iterative Learning Control

Rather following the approach from [2].

- Use either SI (MKS) or CGS as primary units. (SI units are encouraged.) English units may be used as secondary units (in parentheses). An exception would be the use of English units as identifiers in trade, such as "3.5-inch disk drive".
- Avoid combining SI and CGS units, such as current in amperes and magnetic field in oersteds. This often leads to confusion because equations do not balance dimensionally. If you must use mixed units, clearly state the units for each quantity that you use in an equation.
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Number equations consecutively. To make your equations more compact, you may use the solidus ( / ), the exp function, or appropriate exponents. Italicize Roman symbols for quantities and variables, but not Greek symbols. Use a long dash rather than a hyphen for a minus sign. Punctuate equations with commas or periods when they are part of a sentence, as in:

$$a + b = \gamma \tag{3}$$

Be sure that the symbols in your equation have been defined before or immediately following the equation. Use "(3)", not "Eq. (3)" or "equation (3)", except at the beginning of a sentence: "Equation (3) is . . ."

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#### E. Some Common Mistakes

- The word "data" is plural, not singular.
- The subscript for the permeability of vacuum  $\mu_0$ , and other common scientific constants, is zero with subscript formatting, not a lowercase letter "o".
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  word alternatively is preferred to the word "alternately"
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- Do not use the word "essentially" to mean "approximately" or "effectively".
- In your paper title, if the words "that uses" can accurately replace the word "using", capitalize the "u"; if not, keep using lower-cased.
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- Do not confuse "imply" and "infer".
- The prefix "non" is not a word; it should be joined to the word it modifies, usually without a hyphen.
- There is no period after the "et" in the Latin abbreviation "et al.".
- The abbreviation "i.e." means "that is", and the abbreviation "e.g." means "for example".

An excellent style manual for science writers is [2].

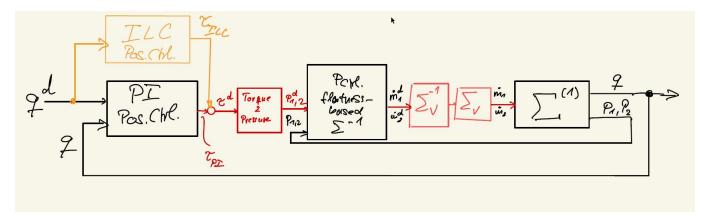


Fig. 3. Control Structure

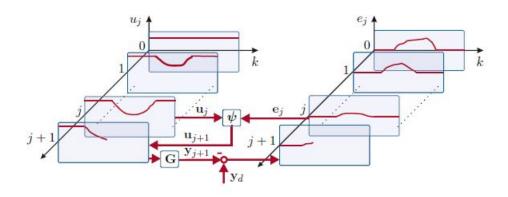


Fig. 4. Illustration of the ILC concept [2]

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Head	Table column subhead	Subhead	Subhead
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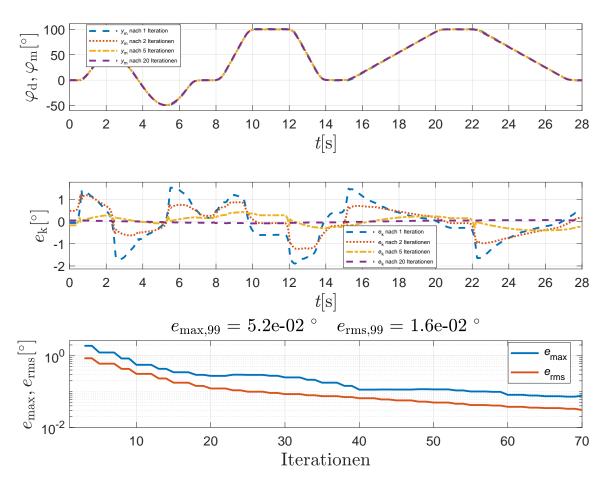


Fig. 5. Measurement resutls for a robot joint

Figure Labels: Use 8 point Times New Roman for Figure labels. Use words rather than symbols or abbreviations when writing Figure axis labels to avoid confusing the reader. As an example, write the quantity "Magnetization", or "Magnetization, M", not just "M". If including units in the label, present them within parentheses. Do not label axes only with units. In the example, write "Magnetization  $\{A[m(1)]\}$ ", not just "A/m". Do not label axes with a ratio of quantities and units. For example, write "Temperature (K)", not "Temperature/K".

## ACKNOWLEDGMENT

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#### REFERENCES

#### REFERENCES

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