
RECYCLINGPLANT SHARED RESOURCE

CADT Recycling_Plant

OPERATIONS

ACTION Notify_weight: $\mathbb{N} [i]$

ACTION Increment_weight: $\mathbb{N} [i]$

ACTION Notify_Drop: *Void*

ACTION Prepare_Replacement:

ACTION Notify_Replacement: $\mathbb{N} [i]$

PROTOCOLS: *Crane* : *Notify_Weight*; *Increment_Weight*; *Notify_Drop*
Container : *Prepare_Replacement*; *Notify_Replacement*

CONCURRENCY: *Crane* | *Container*

SEMANTICS

DOMAIN:

TYPE: *Recycling_Plant* = (*weight* : $\mathbb{N} \times$ *state* : *State* \times *accessing* : \mathbb{N})

State = *READY* | *TO_REPLACE* | *REPLACING*

INITIAL: *self.weight* = 0 \wedge *self.state* = *READY* \wedge *self.accessing* = 0

INVARIANT: $\forall r \in \text{Recycling_Plant} \bullet r.\text{weight} \leq \text{MAX_W_CONTAINER} \wedge$
 $r.\text{accessing} \leq \text{MAX_CRANES} \wedge \text{MAX_W_CONTAINER} > 0$

CPRE: *self.state* \neq *REPLACING*

Notify_weight(w)

POST: *self*ⁱⁿ.*weight* + *w* > *MAX_W_CONTAINER* \rightarrow *self*^{out}.*state* =
TO_REPLACE \wedge *self*ⁱⁿ.*weight* + *p* \leq *MAX_W_CONTAINER* \rightarrow *self*^{out}.*state* =
READY

CPRE: *self.weight* + *w* \leq *MAX_W_CONTAINER* \wedge *self.state* \neq *REPLACING*

Increment_Weight(w)

POST: *self*^{out}.*accessing* = *self*ⁱⁿ.*accessing* + 1 \wedge *self*^{out}.*weight* = *self*ⁱⁿ.*weight* +
w

PRE: *accessing* > 0

CPRE: True

Notify_Drop

POST: *self*^{out}.*accessing* = *self*ⁱⁿ.*accessing* - 1

CPRE: *self.state* = *TO_REPLACE* \wedge *self.accessing* = 0

Prepare_Replacement

POST: *self*^{out}.*state* = *REPLACING*

PRE: *self.state* = *REPLACING* \wedge *self.accessing* = 0 \wedge *m* > 0

CPRE: True

Notify_Replacement(m)

POST: *self*^{out}.*state* = *READY* \wedge *self*^{out}.*weight* = 0 \wedge *MAX_W_CONTAINER* =

m